# **Question 2**

# **Data Description**

The following problem is intended to illustrate alterations in performance and shape of distributions brought about by variations in covariance matrices.

- **Training data**: 'P2\_train.csv' consisting of 310 instances, 2 attributes +1 class label.
- Test data: 'P2\_train.csv' consisting of 90 instances, 2 attributes +1 class label.

Learn a binary classifier for the given data taking class conditional densities as normal density. Estimate the misclassification rates of both classes, plot the discriminant function and iso-probability contours for the following cases:

- a) Equal Diagonal  $\Sigma_s$  of equal variances along both dimensions,  $\Sigma_0=\Sigma_1=\begin{bmatrix}a&0\\0&a\end{bmatrix}$
- b) Equal Diagonal  $\Sigma_s$  of unequal variances along different dimensions,

$$\Sigma_0 = \Sigma_1 = \left[egin{array}{cc} a & 0 \ 0 & b \end{array}
ight]$$

- c) Arbitrary  $\Sigma_s$  but shared by both classes,  $\Sigma_0=\Sigma_1=egin{bmatrix} a & b \\ c & d \end{bmatrix}$
- d) Different arbitrary  $\Sigma_s$  for 2 classes

# **Importing Libraries**

```
In [ ]: import numpy as np
import matplotlib.pyplot as plt
```

# **Training**

Procedure will be the same as question 1.

## Importing data

P2\_train has 3 columns

first 2 are features and the last column is class label [ $y_i \in \{0,1\}, orall i$ ]

```
In [ ]: filename = 'P2_train.csv'
    data= np.loadtxt(filename, delimiter=',')
    print(data.shape)

    (310, 3)

In [ ]: X_train = data[:,0:2]
    y_train = data[:,-1]
    print(X_train.shape,y_train.shape)

    (310, 2) (310,)
```

### **Grouping feature vectors**

```
In [ ]: X_train_0 = X_train[y_train == 0.0]
    X_train_1 = X_train[y_train == 1.0]
```

## **Estimating mean**

Mean of the class labels (0 and 1) for both features are

```
In []: # ML mean is just sample mean
mu_0 = np.array([X_train_0[:,0].mean(),X_train_0[:,1].mean()])
mu_1 = np.array([X_train_1[:,0].mean(),X_train_1[:,1].mean()])
print(f"{mu_0 = }\n{mu_1 = }")

mu_0 = array([-2.48646619,  0.23701453])
mu_1 = array([ 1.056773 , -1.2525509])
```

## **Defining covariance**

In this block we will define the 4 different covariance matrices that meet the conditions of the above question.

```
In []: Sig_0_a, Sig_1_a = np.array([[1,0],[0,1]]), np.array([[1,0],[0,1]])
    Sig_0_b, Sig_1_b = np.array([[0.5,0],[0,1]]), np.array([[0.5,0],[0,1]])
    Sig_0_c, Sig_1_c = np.array([[10,0.2],[4,1]]), np.array([[10,0.2],[4,1]])
    Sig_0_d, Sig_1_d = np.array([[4,1],[0.2,10]]), np.array([[10,0.2],[4,1]])
```

### **Defining Prior Probabilities**

```
In [ ]: p_0 = X_train_0.size/X_train.size
p_1 = 1- p_0
print(p_0,p_1)
```

0.4838709677419355 0.5161290322580645

# **Testing**

## **Importing Data**

P2\_test has 3 columns

first 2 are features and the last column is class label [ $y_i \in \{0,1\}, \forall i$ ]

```
In []: filename = 'P2_test.csv'
    test_data = np.loadtxt(filename, delimiter=',')
    print(test_data.shape)

(90, 3)
In []: X_test = test_data[:,0:2]
    y_test = test_data[:,-1]
    print(X_test.shape,y_test.shape)

(90, 2) (90,)
```

## **Defining normal distribution**

```
In [ ]: def Gaussian(x,mu,Sigma): #3rd argument should be SD and not var if 1Dimensional
             if (isinstance(mu,int) or mu.size ==1): #univariate gaussian
                  return (1/(Sigma*np.sqrt(2*np.pi)))*(np.exp(-1*(x - mu)**2 / (2*Sigma**2)
             n = mu.size
             Sig_det = np.linalg.det(Sigma)
             C = ((2*np.pi)**n)
             Mlbns_dist = Mahalanobis_distance(x,mu,Sigma)
             y = (np.exp(-1*Mlbns dist/2)/
                  np.sqrt(C*Sig_det))
             return y
        def Mahalanobis_distance(x,mu,Sigma):
             n = mu.size
             mu = np.array(mu)
             Sigma = np.array(Sigma)
             x_hat = x_mu
             try:
                  Mlbns_dist = x_hat@Sigma@x_hat.T #Mahalanobis distance squared
             except:
                  print("dimensions dont match")
             else:
                  Mlbns_dist = x_hat.T@Sigma@x_hat #Mahalanobis distance squared
             return Mlbns_dist
```

### Confusion matrix definition

```
In [ ]: def Confusion_Matrix(pred,test,label_a,label_b):
    pred = np.array(pred)
    test = np.array(test)
    assert pred.size == test.size ,'Size of the predicted and test samples don\'t n
    a00, a01, a10, a11 = 0, 0, 0, 0
    for i in range(pred.size):
        if (test[i] == label_a and pred[i] == label_a):
            a00 = a00 + 1
        elif (test[i] == label_a and pred[i] == label_b):
            a01 = a01 + 1
        elif (test[i] == label_b and pred[i] == label_a):
            a10 = a10 + 1
        else:
            a11 = a11 + 1
        return (1/pred.size)*np.array([[a00,a01],[a10,a11]])
```

### Misclassification rates

#### Case 1:

#### Classification

```
In [ ]: no_of_samples = int(X_test.size/2)

y_pred_1 = np.zeros([no_of_samples,1])
for i in range(no_of_samples):
    f_0 = Gaussian(X_test[i,:],mu_0,Sig_0_a)
```

```
f_1 = Gaussian(X_test[i,:],mu_1,Sig_1_a)
if(p_0*f_0 > p_1*f_1):
    y_pred_1[i]=0
else:
    y_pred_1[i]=1
```

#### Confusion matrix and Misclassification rate

#### Case 2:

#### Classification

```
In []: no_of_samples = int(X_test.size/2)

y_pred_2 = np.zeros([no_of_samples,1])
for i in range(no_of_samples):
    f_0 = Gaussian(X_test[i,:],mu_0,Sig_0_b)
    f_1 = Gaussian(X_test[i,:],mu_1,Sig_1_b)
    if(p_0*f_0 > p_1*f_1):
        y_pred_2[i]=0
    else:
        y_pred_2[i]=1
```

#### Confusion matrix and Misclassification rate

```
In [ ]: CM_2 = Confusion_Matrix(y_pred_2,y_test,0,1)
    print(f'Confusion Matrix for Case 2 is \n{CM_2}')
    error_2 = (CM_2[0,1]+CM_2[1,0])
    print(f'\n\nAccuracy Score for Case 2 is \n{1- error_2}')

Confusion Matrix for Case 2 is
    [[0.48888889     0.06666667]
        [0.01111111     0.43333333]]

Accuracy Score for Case 2 is
    0.9222222222222222
```

### Case 3:

#### Classification

```
In [ ]: no_of_samples = int(X_test.size/2)
```

```
y_pred_3 = np.zeros([no_of_samples,1])
for i in range(no_of_samples):
    f_0 = Gaussian(X_test[i,:],mu_0,Sig_0_c)
    f_1 = Gaussian(X_test[i,:],mu_1,Sig_1_c)
    if(p_0*f_0 > p_1*f_1):
        y_pred_3[i]=0
    else:
        y_pred_3[i]=1
```

#### Confusion matrix and Misclassification rate

```
In [ ]: CM_3 = Confusion_Matrix(y_pred_3,y_test,0,1)
    print(f'Confusion Matrix for Case 3 is \n{CM_3}')
    error_3 = (CM_3[0,1]+CM_3[1,0])
    print(f'\n\nAccuracy Score for Case 3 is \n{1- error_3}')

Confusion Matrix for Case 3 is
    [[0.555555556 0.     ]
    [0.04444444 0.4   ]]

Accuracy Score for Case 3 is
    0.955555555555556
```

#### Case 4:

#### Classification

```
In [ ]: no_of_samples = int(X_test.size/2)

y_pred_4 = np.zeros([no_of_samples,1])
for i in range(no_of_samples):
    f_0 = Gaussian(X_test[i,:],mu_0,Sig_0_d)
    f_1 = Gaussian(X_test[i,:],mu_1,Sig_1_d)
    if(p_0*f_0 > p_1*f_1):
        y_pred_4[i]=0
    else:
        y_pred_4[i]=1
```

#### Confusion matrix and Misclassification rate

## Plotting Discriminant function and Iso-probabilistic contours

### **Bayes Classifier in Discriminant form**

As discussed in class, Bayes classifer can be easily reskinned into Discriminant(quadratic specifically) form.

$$h_B=0$$
 if  $X^T(\Sigma_1^{-1}-\Sigma_0^{-1})X+2X^T(\Sigma_0^{-1}\mu_0-\Sigma_1^{-1}\mu_1)+(\mu_1^T\Sigma_1^{-1}\mu_1-\mu_0^T\Sigma_0^{-1}\mu_0)+2ln(rac{p_0L(1,0)}{p_1L(0,1)})+lr$ 

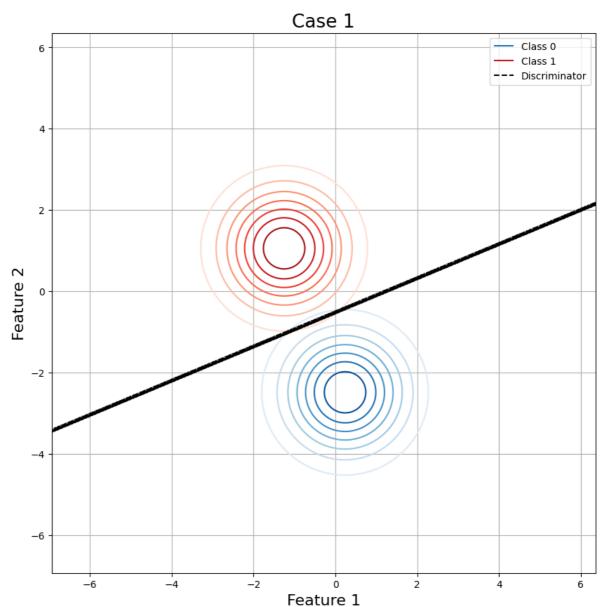
We have assumed a 0-1 Loss function, and the remaining values have been calculated except ofcourse X, with which we will plot the Discriminant function.

```
In [ ]: def Bayes_Discriminator(X,mu0,mu1,Sigma0,Sigma1,p0,p1,L10,L01):
            X = np.array(X)
            mu0 = np.array(mu0)
            mu1 = np.array(mu1)
            Sigma0 = np.array(Sigma0)
            Sigma1 = np.array(Sigma1)
            Sigma0_inv = np.linalg.inv(Sigma0)
            Sigma1_inv = np.linalg.inv(Sigma1)
            trv:
                Quad = X.T@(Sigma1_inv - Sigma0_inv)@X
                print("Either dimensions of X and Sigma or dimensions of Sigma0 and Sigma1
                Quad = X@(Sigma1 inv - Sigma0 inv)@X.T
                Lin = 2*X.T@(Sigma0_inv@mu0 - Sigma1_inv@mu1)
                print("Dimensions of x mu and Sigma dont match")
            else:
                Lin = 2*X@(Sigma0_inv@mu0 - Sigma1_inv@mu1).T
                Const1 = (mu1.T@Sigma1_inv@mu1) - (mu0.T@Sigma0_inv@mu0)
                print("Dimensions of Sigma and mu dont match")
            else:
                Const1 = mu1@Sigma1_inv@mu1.T - mu0@Sigma0_inv@mu0.T
            Const2 = 2*np.log(p0*L10/
                            p1*L01)
            #-----
            Const3 = np.log(np.linalg.det(Sigma1)/
                            np.linalg.det(Sigma0))
            return Quad + Lin + Const1 + Const2 + Const3
```

#### Case 1:

```
In [ ]: N = 1000
    x0 = np.linspace(np.min([X_train_0.min(),X_train_1.min()]),np.max([X_train_0.max(),x1 = np.linspace(np.min([X_train_0.min(),X_train_1.min()]),np.max([X_train_0.max(),x1] = np.meshgrid(x0,x1)
```

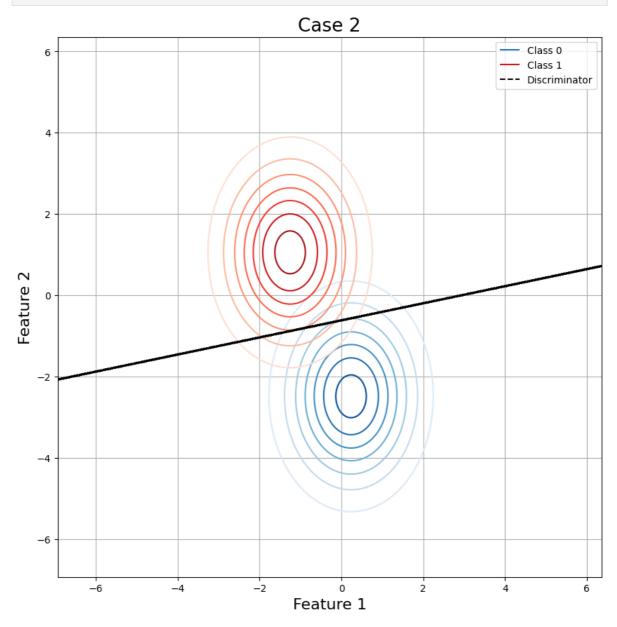
```
In [ ]: #Function for Contour and Discriminant
        #Computationally slightly heavy (about 2m)
        Y0 1 = np.zeros([N,N])
        Y1_1 = np.zeros([N,N])
        Z = np.zeros([N,N])
        for i in range(N):
            for j in range(N):
                Y0_1[i,j] = Gaussian([x0[i],x1[j]],mu_0,Sig_0_a)
                Y1_1[i,j] = Gaussian([x0[i],x1[j]],mu_1,Sig_1_a)
                tmp = Bayes_Discriminator([x0[i],x1[j]],mu_0,mu_1,Sig_0_a,Sig_1_a,p_0,p_1,1
                if(tmp<0.3 and tmp>-0.3):
                    Z[i,j]=tmp
        Z[Z==0] = np.nan #when value is nan, matplotlib does not plot the corresponding val
In [ ]: fig, ax = plt.subplots(1, 1, figsize=(10, 10))
        c1 = ax.contour(X0,X1,Y0_1,cmap='Blues')
        c2 = ax.contour(X0,X1,Y1 1,cmap='Reds')
        1 = ax.contour(X0,X1,Z,colors='black')
        ax.set xlabel('Feature 1',fontsize='16')
        ax.set_ylabel('Feature 2',fontsize='16')
        ax.set_title('Case 1',fontsize='19')
        #ax.set_xlim(-6,3)
        #ax.set_ylim(-6.5,6.5)
        ax.grid('on')
        h1,l1 = c1.legend_elements()
        h2,l1 = c2.legend_elements()
        h3,l1 = l.legend_elements()
        plt.legend([h1[-3], h2[-3], h3[0]], ['Class 0', 'Class 1', 'Discriminator'])
        plt.show()
```



### Case 2:

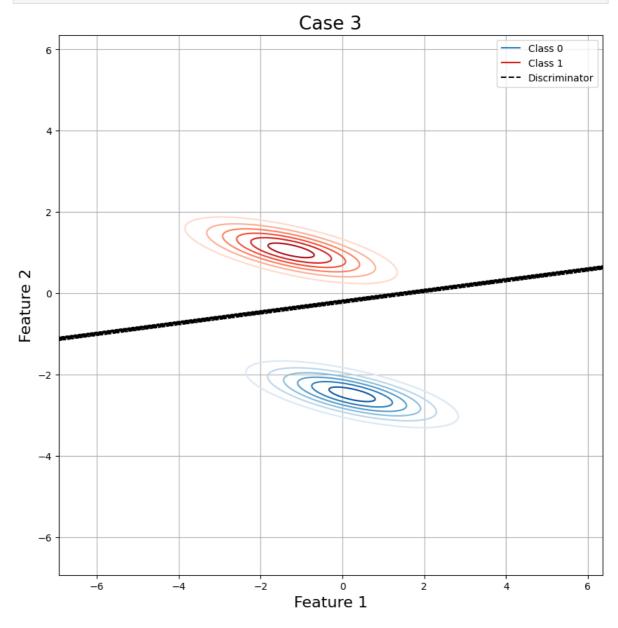
```
In [ ]: #Function for Contour and Discriminant
        #Computationally slightly heavy (about 2m)
        Y0_2 = np.zeros([N,N])
        Y1 2 = np.zeros([N,N])
        Z2 = np.zeros([N,N])
        for i in range(N):
            for j in range(N):
                Y0_2[i,j] = Gaussian([x0[i],x1[j]],mu_0,Sig_0_b)
                Y1_2[i,j] = Gaussian([x0[i],x1[j]],mu_1,Sig_1_b)
                tmp = Bayes_Discriminator([x0[i],x1[j]],mu_0,mu_1,Sig_0_b,Sig_1_b,p_0,p_1,1
                if(tmp<0.3 and tmp>-0.3):
                    Z2[i,j]=tmp
        Z2[Z2==0] = np.nan#when value is nan, matplotlib does not plot the corresponding va
In [ ]: fig, ax = plt.subplots(1, 1,figsize=(10,10))
        c1 = ax.contour(X0,X1,Y0_2,cmap='Blues')
        c2 = ax.contour(X0,X1,Y1_2,cmap='Reds')
        1 = ax.contour(X0,X1,Z2,colors='black')
        ax.set_xlabel('Feature 1',fontsize='16')
        ax.set_ylabel('Feature 2',fontsize='16')
        ax.set_title('Case 2',fontsize='19')
```

```
#ax.set_xlim(-6,5)
ax.grid('on')
h1,l1 = c1.legend_elements()
h2,l1 = c2.legend_elements()
h3,l1 = l.legend_elements()
plt.legend([h1[-3], h2[-3], h3[0]], ['Class 0', 'Class 1', 'Discriminator'])
plt.show()
```



#### Case 3:

```
In []: fig, ax = plt.subplots(1, 1,figsize=(10,10))
    c1 = ax.contour(X0,X1,Y0_3,cmap='Blues')
    c2 = ax.contour(X0,X1,Y1_3,cmap='Reds')
    l = ax.contour(X1,X0,Z3,colors='black')
    ax.set_xlabel('Feature 1',fontsize='16')
    ax.set_ylabel('Feature 2',fontsize='16')
    ax.set_title('Case 3',fontsize='19')
    #ax.set_xlim(-6,5)
    #ax.set_ylim(-3.2,2.5)
    ax.grid('on')
    h1,l1 = c1.legend_elements()
    h2,l1 = c2.legend_elements()
    h3,l1 = l.legend_elements()
    plt.legend([h1[-3], h2[-3], h3[0]], ['Class 0', 'Class 1', 'Discriminator'])
    plt.show()
```

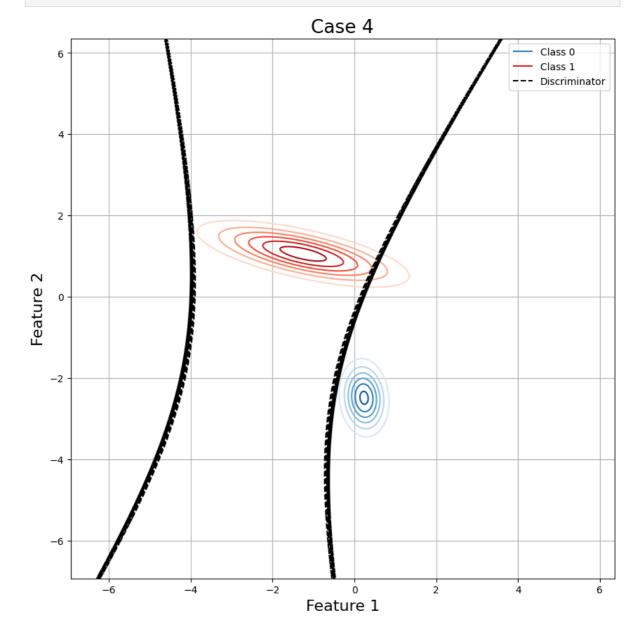


### Case 4:

```
In []: #Function for Contour and Discriminant
    #Computationally slightly heavy (about 2m)
Y0_4 = np.zeros([N,N])
Y1_4 = np.zeros([N,N])
Z4 = np.zeros([N,N])
```

```
for i in range(N):
    for j in range(N):
        Y0_4[i,j] = Gaussian([x0[i],x1[j]],mu_0,Sig_0_d)
        Y1_4[i,j] = Gaussian([x0[i],x1[j]],mu_1,Sig_1_d)
        tmp = Bayes_Discriminator([x0[i],x1[j]],mu_0,mu_1,Sig_0_d,Sig_1_d,p_0,p_1,1
        if(tmp<0.3 and tmp>-0.3):
              Z4[i,j]=tmp
Z4[Z4==0] = np.nan#when value is nan, matplotlib does not plot the corresponding value.
```

```
In [ ]: fig, ax = plt.subplots(1, 1,figsize=(10,10))
    c1 = ax.contour(X0,X1,Y0_4,cmap='Blues')
    c2 = ax.contour(X0,X1,Y1_4,cmap='Reds')
    l = ax.contour(X0,X1,Z4,colors='black')
    ax.set_xlabel('Feature 1',fontsize='16')
    ax.set_ylabel('Feature 2',fontsize='16')
    ax.set_title('Case 4',fontsize='19')
    ax.grid('on')
    h1,l1 = c1.legend_elements()
    h2,l1 = c2.legend_elements()
    h3,l1 = l.legend_elements()
    plt.legend([h1[-3], h2[-3], h3[0]], ['Class 0', 'Class 1', 'Discriminator'])
    plt.show()
```



# **Conclusions**

These were the covariance matrices selected for the question

Case 1:

$$\Sigma_0 = \Sigma_1 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \tag{1}$$

Case 2:

$$\Sigma_0 = \Sigma_1 = \begin{bmatrix} 0.5 & 0 \\ 0 & 1 \end{bmatrix}$$
 (2)

Case 3:

$$\Sigma_0 = \Sigma_1 = \begin{bmatrix} 10 & 0.2 \\ 4 & 1 \end{bmatrix} \tag{3}$$

Case 4:

$$\Sigma_0 = \left[egin{array}{cc} 4 & 1 \ 0.2 & 10 \end{array}
ight], \Sigma_1 = \left[egin{array}{cc} 10 & 0.2 \ 4 & 1 \end{array}
ight]$$

Misclassification Rates and Accuracy score were as follows:

| Case No: | False Positive (0 as 1) | False Negative (1 as 0) | Accuracy Score | | ------ | ------ | ------ | | 1|3.33|0|96.67| | 2|6.67|1.11|92.22| | 3|0|4.44|95.55| | 4|16.67|0|83.33|