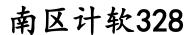


计算机视觉





群聊: 计算机视觉2024—2025 第一学期



该二维码7天内(9月9日前)有效,重新进入将更新

课程助教:

李沣凯: 876030122@qq.com

深圳大学 计算机与软件学院





实验内容

序号	实验主题	实验内容	实验要求	实验时数	每组人数	实验 类型
1	图像处理应用 实验	1. 熟悉图像的表示及基本元素、通道操作; 2. 掌握基本图像增强方法; 3. 掌握OpenCV计算机视觉库;	必做	6	1	讲授 + 实验
2	图像特征提取 及综合应用实 践	 熟悉图像处理基本操作; 掌握图像边缘检测原理; 掌握图像基本特征抽取方法及应用; 	必做	6	1	讲授 + 实验
3	计算机视觉系 统实践	 熟悉计算机视觉分类任务; 掌握数据集的准备及模型训练过程; 培养应用计算机视觉解决问题的能力; 	必做	6	1	讲授 + 实验

涉及学科

- ●数字图像处理
- ●计算机视觉
- ●模式识别
- ●程序设计





实验考察形式

- 三次实验报告
- 平时编程练习及表现
- 实验汇报

序号	实验主题	实验内容	实验要求	实验时数	每组人数	实验时间
1	图像处理应用实验	1. 熟悉图像的表示及基本元素、通道操作; 2. 掌握基本图像增强方法; 3. 掌握OpenCV计算机视觉库;	必做	6	1	2024年9月2日- 2024年10月13日
2	图像特征提取及综合应用实践	 熟悉图像处理基本操作; 掌握图像边缘检测原理; 掌握图像基本特征抽取方法及应用; 	必做	6	1	2024年10月14日- 2024年11月18日
3	计算机视觉系统实 践	 熟悉计算机视觉分类任务; 掌握数据集的准备及模型训练过程; 培养应用计算机视觉解决问题的能力; 	必做	6	1	2024年11月19日- 2024年12月30日

实验考察内容

- 计算机视觉与模式识别基础知识掌握能力
- 算法设计能力
- 编程及系统架构能力
- 论文写作及表达能力



● 计算机视觉应用简介

图像处理应用



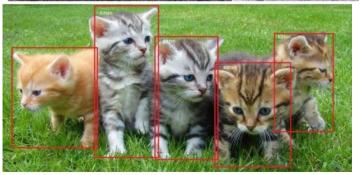






















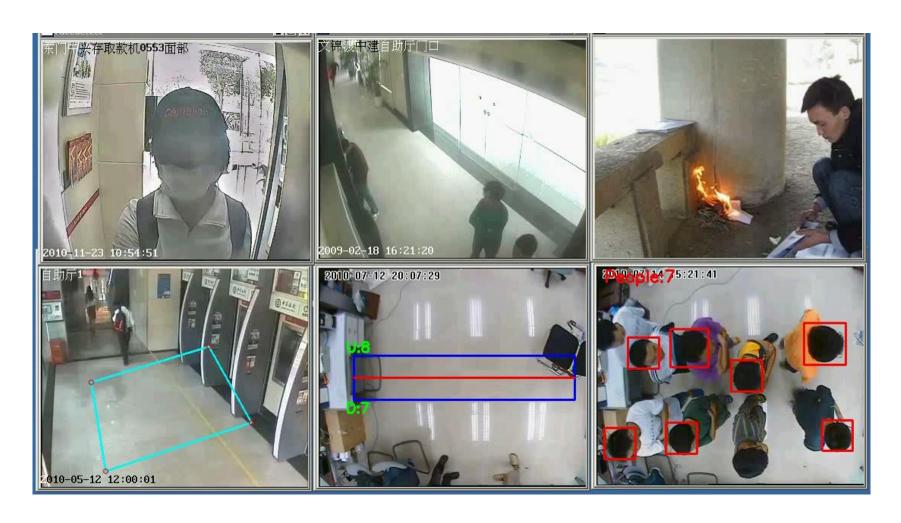








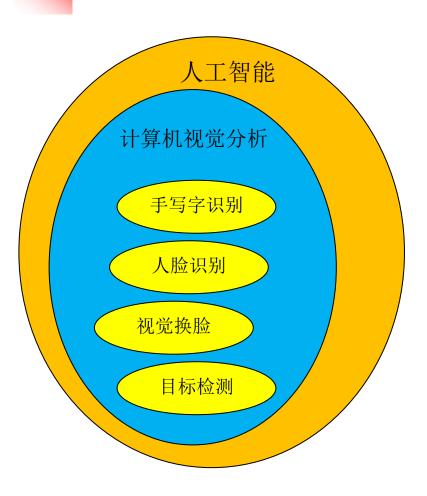
深圳大学 SHENZHEN UNIVERSITY







● 计算机视觉应用简介



1)视觉分析难点

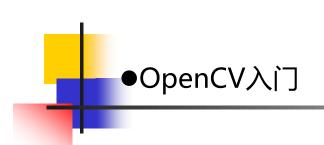
- ●姿态变化;
- ●光线干扰:
- ●成像噪声影响(模糊、抖动、点噪声)等。

2) 视觉分析关键问题

如何在这些复杂环境下进行有效的特征提取和目标表示是视觉分析的关键问题。

3) 视觉分析研究目的

设计有效的方法对目标进行有效的特征提取, 把一系列初级特征转化为具有综合语义的高 级特征,实现视觉任务的模式检测、识别等 问题。





OpenCV (Open Source Computer Vision Library)是一个基于BSD许可(开源)发行的跨平台计算机视觉库,允许学术和商业的自由使用,它拥有C++、Python和Java接口并可以运行在Windows、Linux、Mac OS操作系统和Android上。OpenCV专注于各种计算机视觉问题的高效计算和实时应用,是经优化过的C/C++代码编写而成,实现了图像处理和计算机视觉方面的很多通用算法。





●OpenCV入门-参考资料

图像处理

● Rafael C. Gonzalez, Richard E. Woods著,阮秋琦, 阮宇智译,数字图像处理(第三版), 电子工业出版社, 2011.6.

OpenCV3 教程

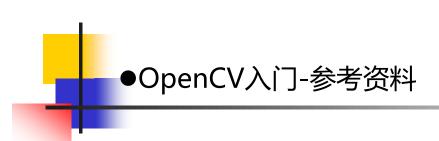
- Adrian Kaehler, Gary Bradski, Learning OpenCV 3 Computer Vision in C++ with the OpenCV Library, O'Reilly, 2016.12
- Gary Bradski, Adrian Kaehler著, 于仕供译,学习OpenCV(中文版), 清华大学出版社, 2009.10

OpenCV 官网

https://opencv.org/

* OpenCV - 4.10.0

2024-06-03





机器学习教程

● 周志华, 机器学习, 清华大学出版社, 2016.01.

深度学习教程

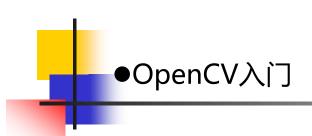
● Ian Goodfellow, Yoshua Bengio, Aaron Courville著, 赵申剑等译, 深度学习, 人民邮电出版社, 2017.8.

Python教程

https://www.liaoxuefeng.com/wiki/1016959663602400

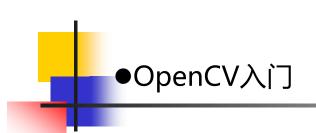
深度学习平台教程

PyCharm教程 https://www.yiibai.com/pycharm





- OpenCV在Python语言环境下的配置
- OpenCV在C++语言环境下的配置





- Python+Anaconda+OpenCV
- ➤ Python+Pycharm+OpenCV (参考计算机视觉环境配置相关文档,在Blackboard下载)





所需安装工具:

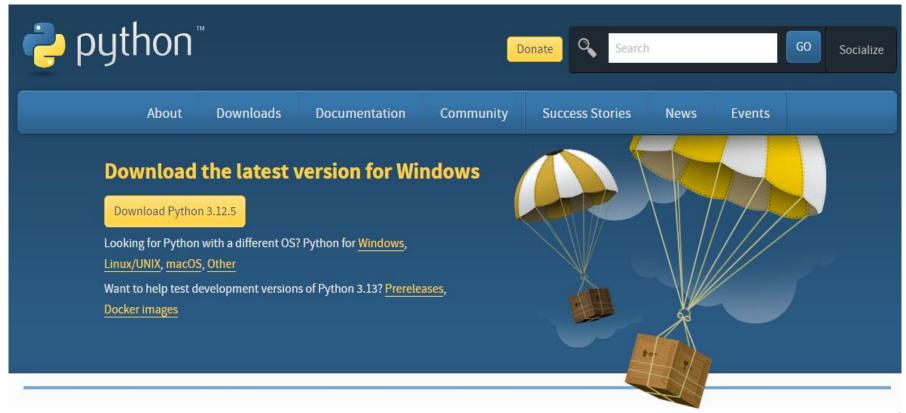
- ① Python
- 2 Anaconda
- ③ OpenCV





Python的安装

Python官网https://www.python.org/downloads/下载Windows版本的Python







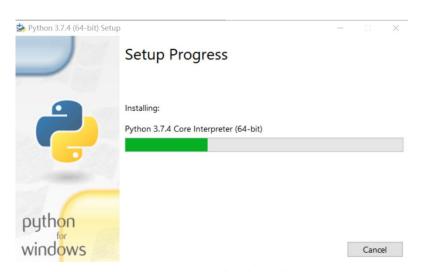
Files					
Version	Operating System	Description	MD5 Sum	File Size	G
Gzipped source tarball	Source release		68111671e5b2db4aef7b9ab01bf0f9be	23017663	S
XZ compressed source tarball	Source release		d33e4aae66097051c2eca45ee3604803	17131432	s
macOS 64-bit/32-bit installer	Mac OS X	for Mac OS X 10.6 and later	6428b4fa7583daff1a442cba8cee08e6	34898416	s
macOS 64-bit installer	Mac OS X	for OS X 10.9 and later	5dd605c38217a45773bf5e4a936b241f	28082845	S
Windows help file	Windows		d63999573a2c06b2ac56cade6b4f7cd2	8131761	S
Windows x86-64 embeddable zip file	Windows	for AMD64/EM64T/x64	9b00c8cf6d9ec0b9abe83184a40729a2	7504391	S
Windows x86-64 executable installer	Windows	for AMD64/EM64T/x64	a702b4b0ad76debdb3043a583e563400	26680368	S
Windows x86-64 web-based installer	Windows	for AMD64/EM64T/x64	28cb1c608bbd73ae8e53a3bd351b4bd2	1362904	S
Windows x86 embeddable zip file	Windows		9fab3b81f8841879fda94133574139d8	6741626	S
Windows x86 executable installer	Windows		33cc602942a54446a3d6451476394789	25663848	S
Windows x86 web-based installer	Windows		1b670cfa5d317df82c30983ea371d87c	1324608	S

确定版本号



进入Python安装界面

选择合适的安装文件



Python安装过程

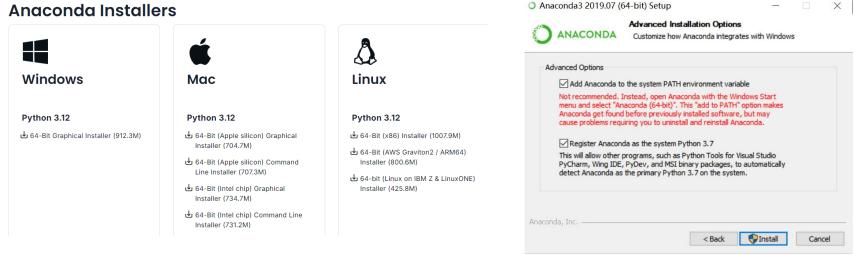




Anaconda的配置

在Anaconda官网https://www.anaconda.com/download下载Anaconda(根据Python的版本选择安装) (例如安装目录为: C:\ProgramData\Anaconda3

Anaconda Installers



选择合适的版本

执行安装



存在问题

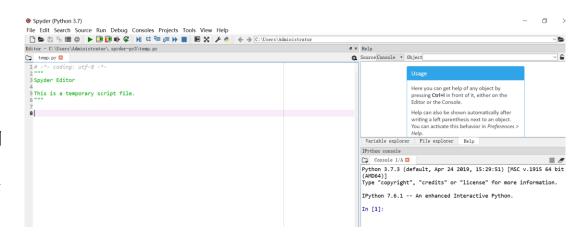




打开Spyder失败!

解决方案

- 直接在ANACONDA Prompt命令窗口, 运行pip uninstall numpy,卸载存在问 题的numpy库;
- 然后安装pip install numpy。问题解决



成功打开Spyder!



OpenCV的安装

- ① 从网站 https://www.lfd.uci.edu/~gohlke/pythonlibs/#opencv 上下载(选择合适的版本)
 - (https://pypi.org/project/opencv-python/#files) opencv_python-4.1.1+contrib-cp37-cp37-win_amd64.whl
- ② 把该文件并放入安装目录C:\ProgramData\Anaconda3\Lib\site-packages下
- ③ 在Anaconda Prompt命令窗口转到目录 C:\ProgramData\Anaconda3\Lib\site-packages,并输入命令: pip install opencv_python-4.1.1+contrib-cp37-cp37mwin amd64.whl
- ④ 安装完后在Spyder窗口输入import cv2,如没有报错,表示安装成功.

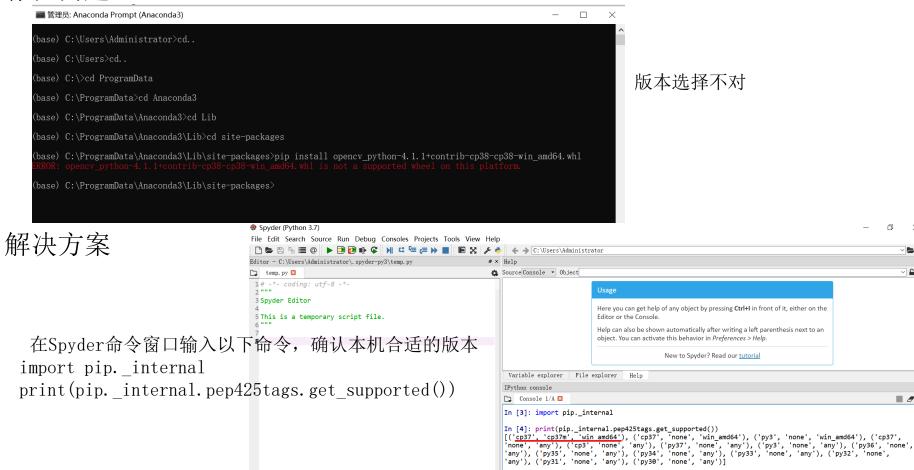


```
https://www.lfd.uci.edu/~gohlke/pvthonlibs/#opency
OpenCV, a real time computer vision library
  opencv_python-2.4.13.7-cp27-cp27m-win32.whl
  opency python-2.4.13.7-cp27-cp27m-win amd64.whl
  opency_python-3.4.7+contrib-cp35-cp35m-win32.whl
  opency python-3.4.7+contrib-cp35-cp35m-win amd64.whl
  opency_python-3.4.7+contrib-cp36-cp36m-win32.whl
  opency python-3.4.7+contrib-cp36-cp36m-win amd64.whl
  opency_python-3.4.7+contrib-cp37-cp37m-win32.whl
  opency python-3.4.7+contrib-cp37-cp37m-win amd64.whl
  opency_python-3.4.7+contrib-cp38-cp38-win32.whl
  opencv python-3.4.7+contrib-cp38-cp38-win amd64.whl
  opency_python-3.4.7-cp35-cp35m-win32.whl
  opency python-3.4.7-cp35-cp35m-win amd64.whl
  opencv_python-3.4.7-cp36-cp36m-win32.whl
  opencv python-3.4.7-cp36-cp36m-win amd64.whl
  opency_python-3.4.7-cp37-cp37m-win32.whl
  opency python-3.4.7-cp37-cp37m-win amd64.whl
  opencv_python-3.4.7-cp38-cp38-win32.whl
  opency_python-3.4.7-cp38-cp38-win_amd64.whl
  opency python-4.1.1+contrib-cp35-cp35m-win32.whl
  opency python-4.1.1+contrib-cp35-cp35m-win amd64.whl
  opency_python-4.1.1+contrib-cp36-cp36m-win32.whl
  opencv_python-4.1.1+contrib-cp36-cp36m-win_amd64.whl
  opencv_python-4.1.1+contrib-cp37-cp37m-win32.whl
  opency python-4.1.1+contrib-cp37-cp37m-win amd64.whl
  opency_python-4.1.1+contrib-cp38-cp38-win32.whl
  opencv_python-4.1.1+contrib-cp38-cp38-win_amd64.whl
```

选择合适的版本

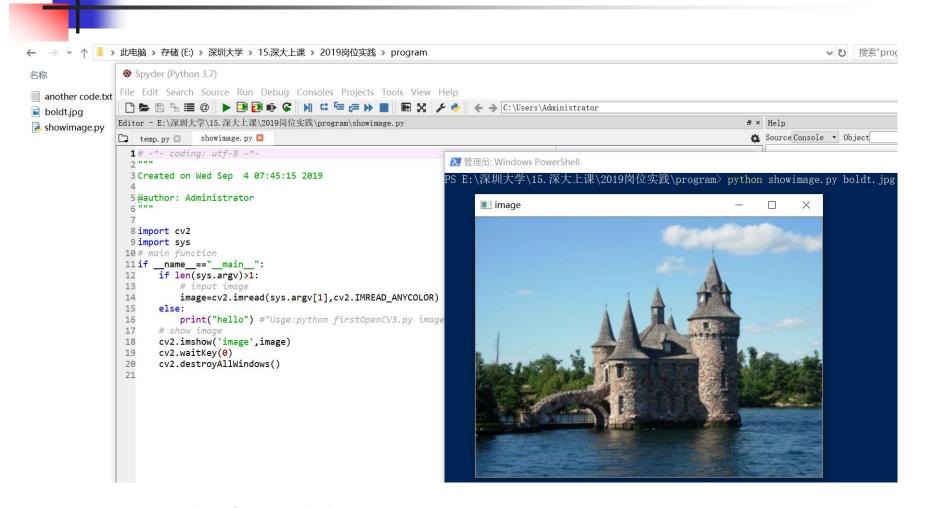


存在问题



In [5]:





执行一个Python程序



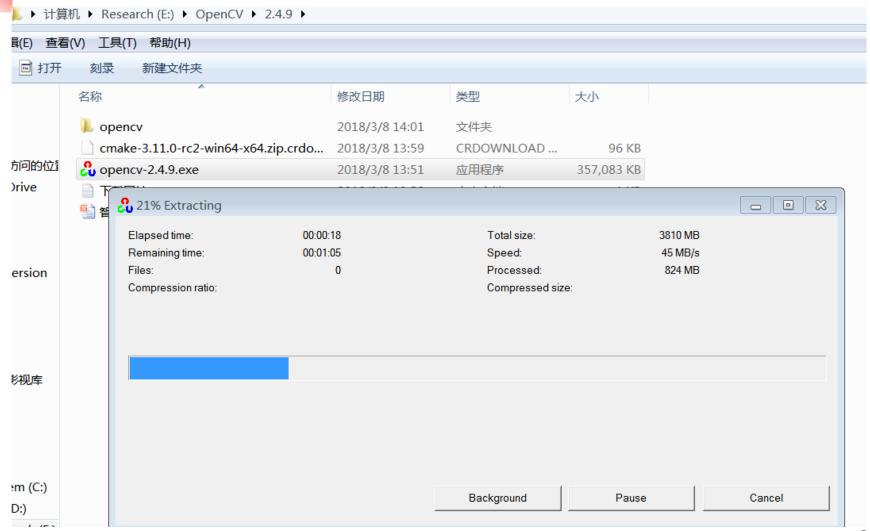


OpenCV的安装

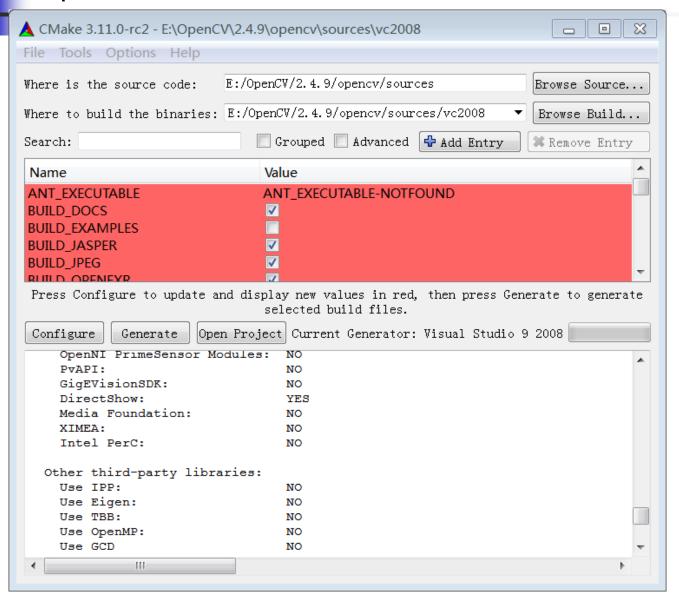
- 准备Win7操作系统、VS2015、OpenCV 3.4.2函数库、Cmake编译器;
- 用Cmake编译对OpenCV 3.4.2进行编译;
- 用VS2015对编译出来的OpenCV.sln进行编译,生成库文件和包含文件;
- 根据库文件和包含文件的对系统进行配置。

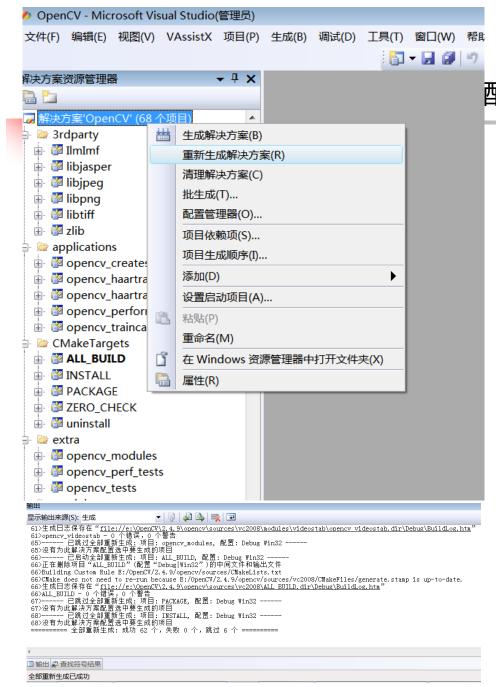
详细的安装步骤参考以下文档 Installation method of OpenCV2.4.9+VS2012.docx



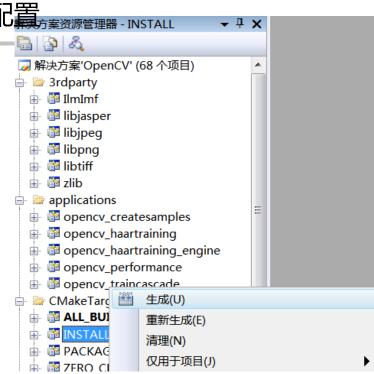




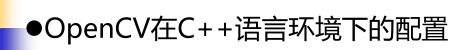


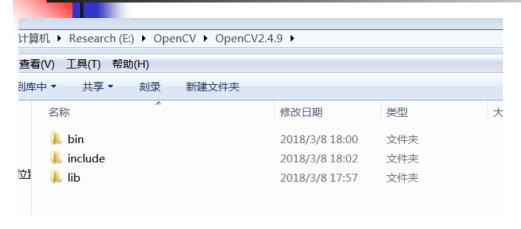












64位系统+VC2008

include:

C:\OpenCV\OpenCV2.4.7\include

 $C: \verb|OpenCV| A.7 \le e^- C. A.7 \le e^- C.7 \le e^- C.7 \le e^- C. A.7 \le e^- C.7 \le e^- C. A.7 \le e^- C.$

C:\OpenCV\OpenCV2.4.7\include\opencv2

lib:

C:\OpenCV\OpenCV2.4.7\lib

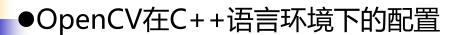
bin:

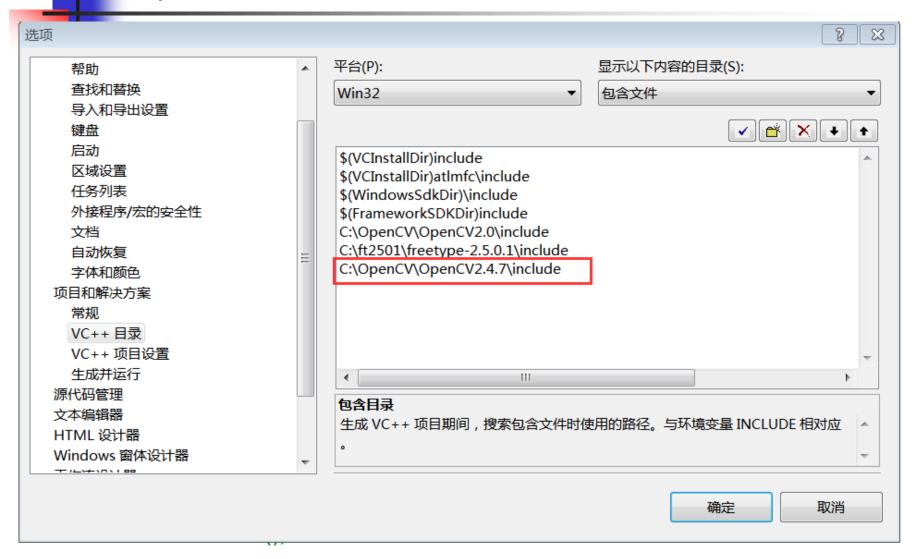
C:\OpenCV\OpenCV2.4.7\bin

Debug配置增加 [附加依赖项 Additional Dependencies]:

opencv_highgui247d.lib;opencv_imgproc247d.lib;opencv_core247d.lib;opencv_features2d247d.lib;opencv_video247d.lib;opencv_video247d.lib;opencv_contrib247d.lib;opencv_contrib247d.lib;opencv_flann247d.lib;opencv_gpu247d.lib;opencv_haartraining_engined.lib;opencv_legacy247d.lib;opencv_nonfree247d.lib;opencv_ocl247d.lib;opencv_photo247d.lib;opencv_stitching247d.lib;opencv_superres247d.lib;opencv_ts247d.lib

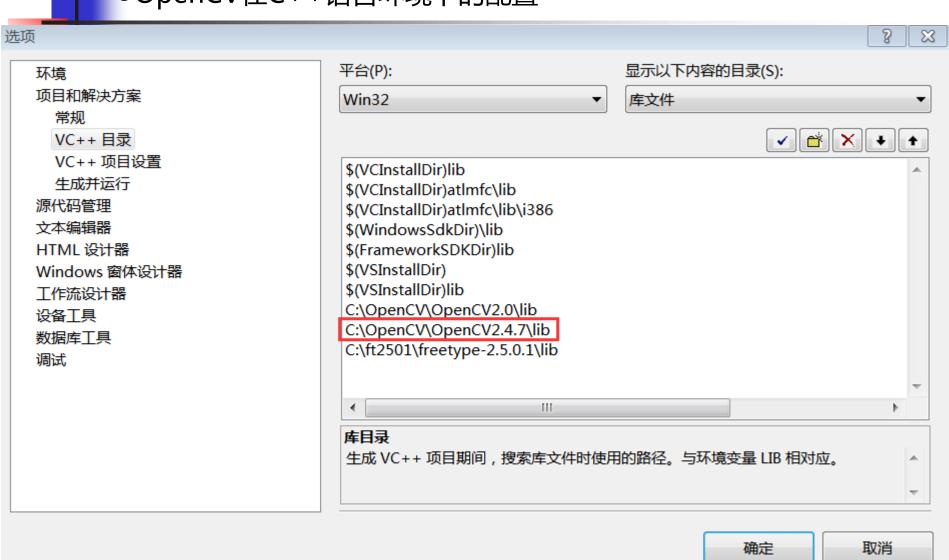




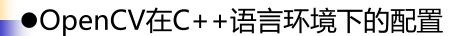


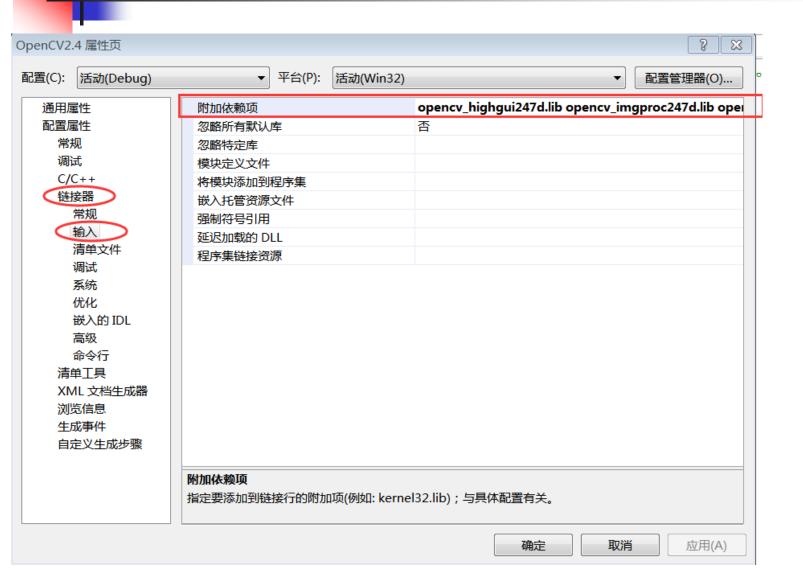




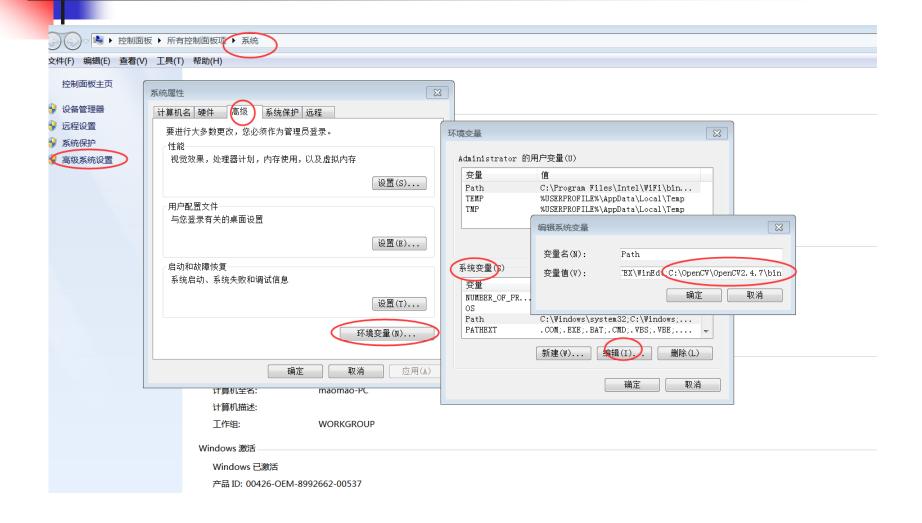








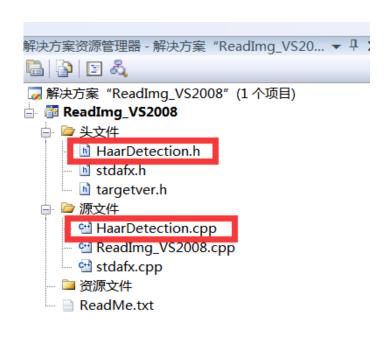






编程要求:

- ① 建立C++类;
- ② 把变量和方法写入C++类;
- ③ 通过声明类对象方式调用方法。



(1) 建立.h和.cpp文件

```
HaarDetection.h
CHaarDetection
 ##ifndef HAARDETECTION H
  #define HAARDETECTION H
  //opency obligatect24/g.lip
  #include <vector>
  #include <opencv2/opencv.hpp>
  using namespace std;
  using namespace cv;
public:
    CascadeClassifier cascade_faceDetector;
  public:
    CHaarDetection(void);
    ~CHaarDetection(void);
    //最多返回10个人脸
    //在图像中的局部区域LocalArea进行Adaboost,
    void FaceDetection(Mat image,Rect LocalArea,vecto
    void DrawOnImg(Mat &image,vector<Rect>Faces);
    void TestOnImgDemo();
    void TestOnVideoDemo();
  #endif
```



编程要求:

```
▼ CHaarDetection()
CHaarDetection

≡#include "stdafx h"

 #include "HaarDetection.h"
 ☐ CHaarDetection::CHaarDetection(void)
     //预定义分类器路径
     string cascade path1="haarcascade frontalface alt.xml";
     string cascade path2="C:\\haarcascade frontalface alt.xml";
     if(cascade faceDetector.empty()==true)
       cascade faceDetector.load(cascade path1);
       //cascade faceDetector.load(cascade path2);
     if(cascade faceDetector.empty()==true)
       printf("没有找到分类器文件\n");
 □ CHaarDetection::~CHaarDetection(void)
 void CHaarDetection::FaceDetection(Mat image,Rect LocalArea,vector<Rect>&FaceVector,vector
     Mat ImgROI=image (Rect(LocalArea.x,LocalArea.y,LocalArea.width,LocalArea.height));//直
    int flags = CASCADE FIND BIGGEST OBJECT/CASCADE DO ROUGH SEARCH; //
    //int flags = CASCADE SCALE IMAGE; //检测多个人
     Size minFeatureSize(10, 10);
     float searchScaleFactor = 1.1f;
```

```
ReadImg_VS2008.cpp*
 □// ReadImg VS2008.cpp: 定义控制台应用程序的入口
  #include "stdafx.h"
  //#include <opencv2/opencv.hpp>
  //using namespace std:
  //using namespace cv;
  #include "HaarDetection h"
  //void Read Show():
  //void Read Video FromCam();
  //void Read Video();
 ☐ int _tmain(int argc, _TCHAR* argv[])
    //Read Show();
    //Read Video FromCam();
    //Read Video();
    CHaarDetection Obj;
    Obi.TestOnImaDemo():
    //Obj.TestOnVideoDemo();
    return 0;
```

(3) 构造函数、析构函数以及方法编写

(4) C++类的声明与调用



● OpenCV图像读取

```
#indef _FORFRESHMEN_H_
#define FORFRESHMEN H

#include <opencv2/opencv.hpp>
//#include <string>

using namespace std;
using namespace cv;

class CForFreshMen
{
public:
    CForFreshMen(void);
    ~CForFreshMen(void);
```

```
□void CForFreshMen::Read_Show()

{
    const char* imagename = "boldt.jpg";
    //从文件中读入图像
    Mat img =imread(imagename);
    //如果读入图像失败
    if(img.empty())
    {
        fprintf(stderr, "Can not load image %s\n", imagename);
        exit(0);
    }
    //显示图像
    namedWindow("image",1);
    cout<<"函数功能:读入并显示和保存一张图像"<<endl;
    imwrite("save.jpg",img);
    imshow("image", img);
    //此函数等待按键,按键盘任意键就返回
    waitKey(0);
}

**CForF***

**CForF***

**CForF***

**CForF**

**Add **CForF**

**Index **Index **CForF**

**Index **Index **CForF**

**Index **I
```







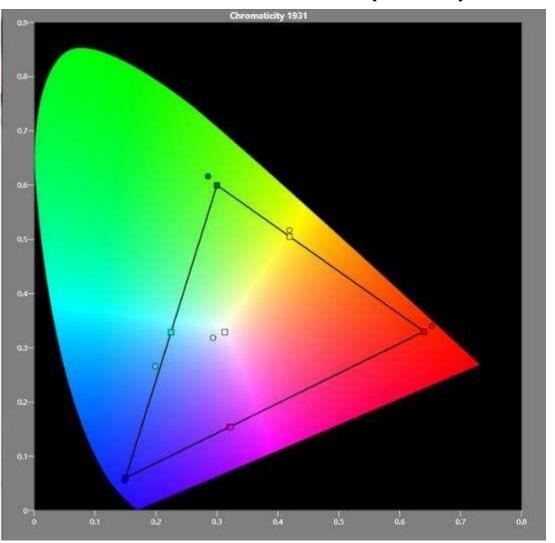
图像矩阵表示

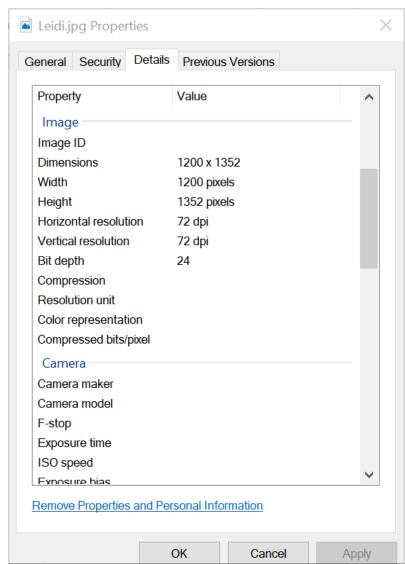


66	59	45	40	34	38	88
76	76	49	40	33	41	59
94	98	73	44	42	41	67
88	99	88	72	71	66	91
59	84	97	83	82	88	81
58	61	79	88	91	87	75
89	59	56	53	60	51	66
114	98	82	65	66	72	86



图像矩阵表示 (RGB)

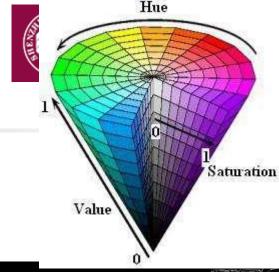








图像矩阵表示 (HSV)









V: 明度

S: 饱和度

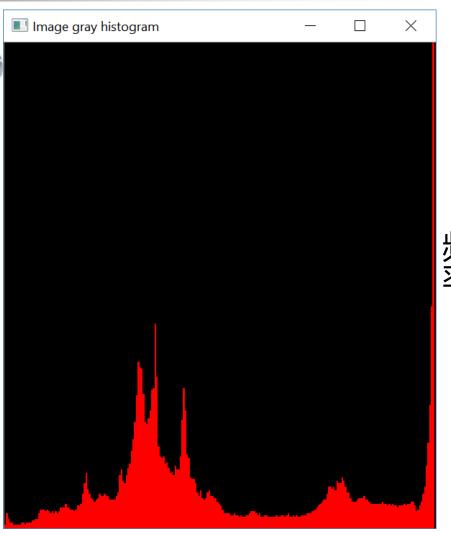
H: 色调

cv::cvtColor(img_work, img_hsv, CV_BGR2HSV);
cv::split(img_hsv, mv);



图像直方图表示





灰度值 (0~255)

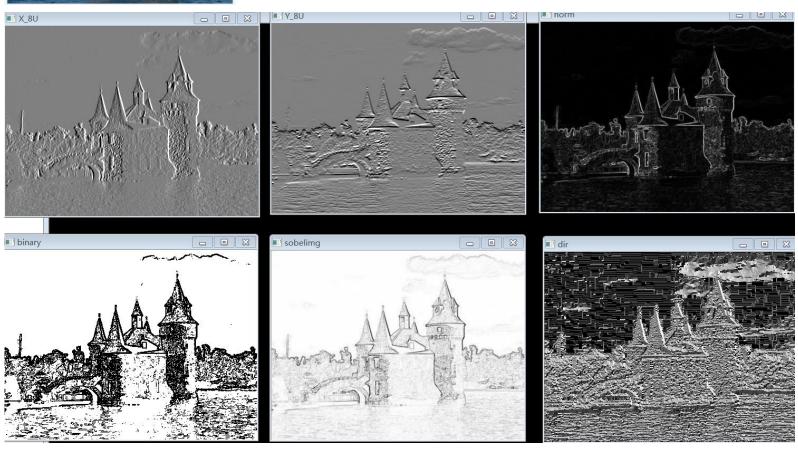


●OpenCV 边缘提取

```
void CForFreshMen::SobelDemo()
              cout << "函数功能: OpenCV中的Sobel函数" << endl;
              Mat image=imread("boldt.jpg",0);//DSC_2038
              //Mat image=imread("new_ac_4_local.bmp",0);//DSC_2038
                                                                                           Mat binaryimg;
              //Mat image=imread("fabric.jpg",0);//DSC 2038
                                                                                           threshold(SobelImg,binaryimg,230,255,THRESH_BINARY);
              Mat SobelX;
                                                                                           imshow("binary",binaryimg);
              Mat SobelY;
              int ksize=3;
              double scale=0.4;//缩放值
                                                                                           Sobel(image,SobelX,CV_32F,1,0);//必须以浮点数格式进行计算
              double delta=128;//偏移量
                                                                                           Sobel(image,SobelY,CV_32F,0,1);
              /*Sobel(image,SobelX,CV_8U,1,0,ksize,1,0);
                                                                                           Mat normimg, dirimg; // 计算L2范式及梯度方向
              Sobel(image, SobelY, CV_8U, 0, 1, ksize, 1, 0);
                                                                                           cartToPolar(SobelX,SobelY,normimg,dirimg,true);//默认:方向的
              imshow("X",SobelX);
                                                                                                                                           //0-2pi 或0
              imshow("Y",SobelY);*/
              Sobel(image, SobelX, CV_8U, 1, 0, ksize, scale, delta);
                                                                                           cout << "norm = " << norming.at < float > (10,10) << endl;
              Sobel(image, SobelY, CV_8U, 0, 1, ksize, scale, delta);
                                                                                           cout << "dirimg=" << dirimg.at < float > (10,10) << endl;
              imshow("X_8U",SobelX);
              imshow("Y_8U",SobelY);
              Sobel(image,SobelX,CV_16S,1,0);
                                                                                           minMaxLoc(normimg,0,&sobmax);
              Sobel(image, SobelY, CV 16S, 0, 1);
                                                                                           normimg.convertTo(normimg,CV_8U,255./sobmax,0);
              Mat SobelImg;
              SobelImg=abs(SobelX)+abs(SobelY);
              double sobmin, sobmax;
              minMaxLoc(SobelImg,&sobmin,&sobmax);
                                                                                           minMaxLoc(dirimg,0,&sobmax);
                                                                                           dirimg.convertTo(dirimg,CV 8U,255./sobmax,0);
              //变为位图像
              //sobelimg=-alpha*sobel+255 //反色
                                                                                           imshow("norm",normimg);
              SobelImg.convertTo(SobelImg,CV_8U,-255./sobmax,255);
                                                                                           imshow("dir",dirimg);
              imshow("sobelimg", SobelImg);
                                                                                           cvWaitKey(0);
```









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OpenCV 锐化图像

```
¬void CForFreshMen::SharpenThreePointMain()
                                                  original
                                                                             23
                                                                                                          0
                                                                                  show
    Mat img=imread("coins.png",1);
   if(img.empty())
      cout<<"找不到图片"<<endl;
      exit(0);
   Mat grayimg, result;
   cout<<"函数功能: 锐化图像-通过三行指
   cvtColor(img,grayimg,CV_RGB2GRAY,0);
    SharpenThreePoint(grayimg,result);
                                                   ivoid CForFreshMen::SharpenThreePoint(const Mat &img,Mat &result)
   namedWindow("original",1);
   imshow("original", grayimg);
                                                     //如有必要则分配图像
   imshow("show",result);
                                                     cout<<"函数功能: 锐化图像-通过三行指针"<<endl;
                                                     result.create(img.size(),img.type());
   cvWaitKey(0);
                                                     for(int j=1;j<img.rows-1;j++)//处理除了第一行和最后一行之外的所有行
                                                       const uchar*previous=img.ptr<const uchar>(j-1);//上一行
                                                       const uchar *current=img.ptr<const uchar>(j);//当前行
                                                       const uchar *next=img.ptr<const uchar>(j+1);//下一行
                                                       uchar *output=result.ptr<uchar>(j);//输出行
                                                       for(int i=1;i<imq.cols-1;i++)
                                                         *output++=saturate cast<uchar>(5*current[i]-current[i-1]-current[i+1]-previous[i]-next[i]);
```

//将未处理的像素设置为0 result.row(0).setTo(Scalar(0));

result.col(0).setTo(Scalar(0));

result.row(result.rows-1).setTo(Scalar(0));

result.col(result.cols-1).setTo(Scalar(0));





上机练习内容:

- 1. OpenCV环境配置;
- 2. 实现对图像的读取;
- 3. 把一副彩色图像的三个通道变成3个单通道图像存储到硬盘 上并显示;
- 4. 计算一幅单通道图像的直方图;
- 5. 编程实现对一幅单通道图像的边缘检测。