Lab Assignment #2

EE-126/COMP-46: Computer Engineering w/lab
Professor: Joel Grodstein **TA:** Dave Werner
Tufts University, Fall 2017

Due as per the class calendar, via 'provide'

The ultimate goal of this project is to design a pipelined version of a MIPS processor that can detect control and data hazards. The functionality of the processor and its components should match the descriptions in the textbook unless otherwise noted. All work must be your own; copying of code will result in a zero for the project and a report to the administration.

List of assignments

- Lab 1: Basic Processor Components and Testbenches
- **Lab 2: Remaining Processor Components including ALU, Memories, and control logic**
- Lab 3: Single Cycle MIPS-32 processor implementation
- Lab 4: Pipelined processor with no hardware hazard detection
- Lab 5: Overcoming data-hazards using forwaring and stalling
- Lab 6: Overcoming control hazards by resolving branches/jumps in ID and using flushing
- Lab 7: Advanced Topics: open-ended team project (groups up to 2 people)

Lab Submission

Please submit your VHDL files *and* a PDF report via 'provide' command on the EE/CS machines. The easiest way to do this is via the web interface, which you can find from the course home page.

VHDL Files: Submit the VHDL source files **(*.vhd)**[1] and any dependencies thereof. Use the entity descriptions provided at the end of this document.[2] These descriptions can also be found in assignment2.zip.

Report: Submit your report as a PDF**(*.pdf)**. Demonstrate the functionality of your code by providing waveforms as detailed in the Deliverables Section. Label/annotate important signals and events in your waveforms and then provide a brief description of what is happening.

Lab2 Objectives

- Understand the functionality of the provided DMEM (dmem.vhd) component
- Write a testbench for DMEM
- Implement ADD, ALU Control, ALU, CPU Control, Instruction Memory, Registers in VHDL
  - *HINT*: Use dmem.vhd as a starting point for IMEM and Registers
- Verify functionality of each component via simulation in Modelsim

[1] Do NOT submit your entire Modelsim project (including but not limited to ***.mpf** and files in **work/**)

[2] Submissions that fail to to follow any of these directions may be penalized at the discretion of the grader. If you have questions, contact the TA (Dave Werner: David.Werner@tufts.edu).

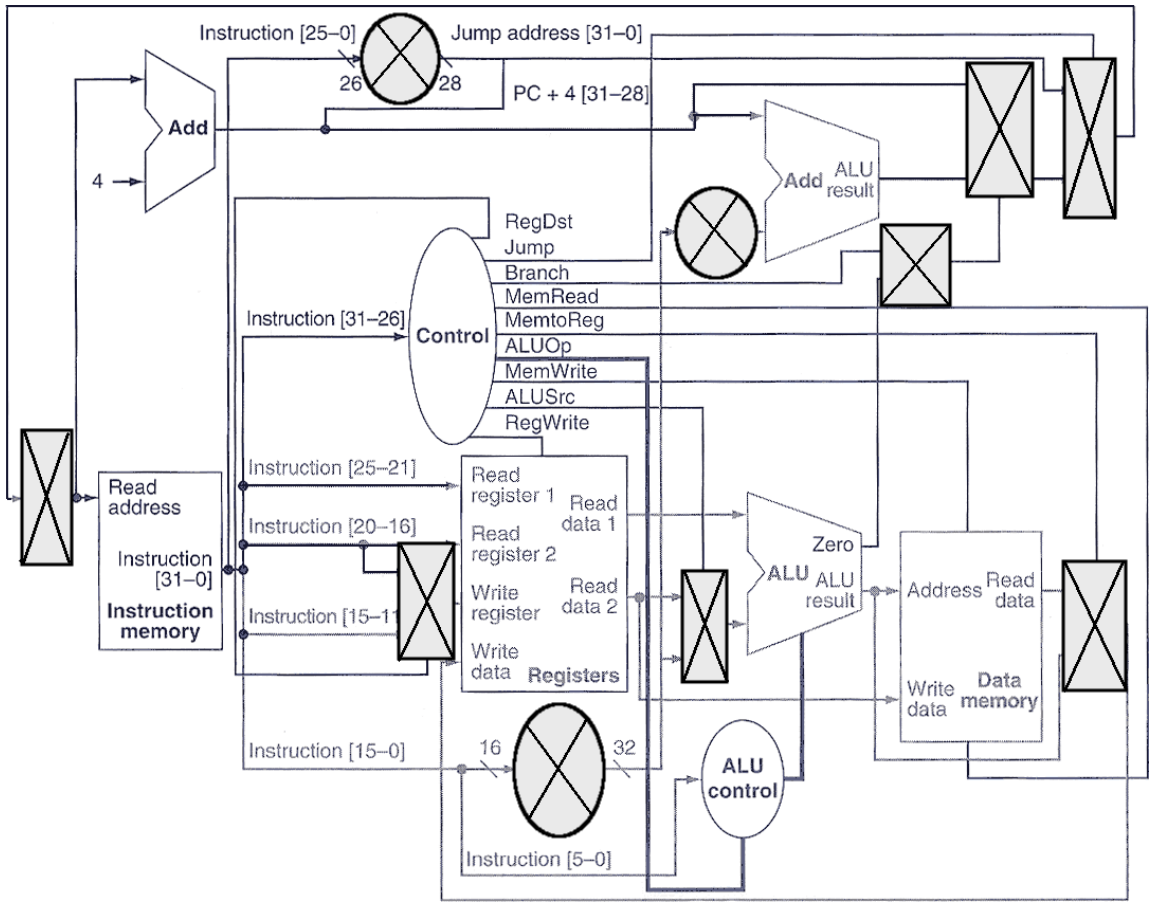

Figure 1: **Components of MIPS processor for Lab 2.** NOTE: The components completed already are greyed out. The remaining components will be implemented in this lab. The DMEM component will be given to you, but you must submit a testbench for it. This is Figure 4.24 in the textbook.

Deliverables

VHDL Files:

1. ADD, ALU Control, ALU, CPU Control, Instruction Memory, Registers.[3] See Figure 1.
2. A testbench for DMEM that writes to multiple adresses and then reads out the stored data.

Report:
Include brief descriptions and annotated waveforms that demonstrate the functionality of the following:

- ALU
  - 'and' and 'or' operations (display values in binary)
  - 'add' and 'subtract' operations (display values in decimal or hex)
  - functionality of 'zero' and 'overflow' output flags (show at least one case where each is '1')
- Registers
  - Initialize $t0=0 $t1=1 $t2=2 $t3=4 $s0=8 $s1=16 $s2=32 $s3=64
    - *Hint*: look at the *if(first)* code block from dmem.vhd for an example of initialization
    - *Hint*: DEBUG_TMP_REGS should be 0x00000000-00000001-00000002-00000004
  - Write to and read from some of the registers. Label where reads/writes occur!
  - Attempt to write register 0($zero) and show that such writes fail ($zero is always 0)
- DMEM (using your testbench)
  - Include annotations and a brief description of each read/write event

[3] You do *not* need to submit your testbenches for these components, but making them is *highly* recommended to facilitate simulation, debugging, and waveform generation.

Entity Descriptions **(provided in assignment2.zip)**

Note that some of these entities have output signals beginning with "DEBUG". These signals will be used for testing purposes and do not impact the functionality of the components, but they need to be hooked up properly or the tests will fail. The comments around the DEBUG signals will tell you how they should be connected. In these comments, the '&' character means concatenation and is also the concatenation operator in VHDL. The provided dmem.vhd file shows an example of properly connecting internal signals to the DEBUG ports.

ADD

```
entity ADD is
-- Adds two signed 32-bit inputs
-- output = in1 + in2
port(
     in0    : in  STD_LOGIC_VECTOR(31 downto 0);
     in1    : in  STD_LOGIC_VECTOR(31 downto 0);
     output : out STD_LOGIC_VECTOR(31 downto 0)
);
end ADD;
```

ALU Control

```
entity ALUControl is
-- Functionality should match truth table shown in Figure 4.13 in the textbook.
-- You only need to consider the cases where ALUOp = "00", "01", and "10". ALUOp = "11" is not
--    a valid input and need not be considered; its output can be anything, including "0110",
--    "0010", "XXXX", etc.
-- To ensure proper functionality, you must implement the "don't-care" values in the funct field,
-- for example when ALUOp = '00", Operation must be "0010" regardless of what Funct is.
port(
     ALUOp     : in  STD_LOGIC_VECTOR(1 downto 0);
     Funct     : in  STD_LOGIC_VECTOR(5 downto 0);
     Operation : out STD_LOGIC_VECTOR(3 downto 0)
);
end ALUControl;
```

ALU

```
entity ALU is
-- Implement: AND, OR, ADD (signed), SUBTRACT (signed)
--    as described in Section 4.4 in the textbook.
-- The functionality of each instruction can be found on the 'MIPS Reference Data' sheet at the
--    front of the textbook.
port(
     a         : in     STD_LOGIC_VECTOR(31 downto 0);
     b         : in     STD_LOGIC_VECTOR(31 downto 0);
     operation : in     STD_LOGIC_VECTOR(3 downto 0);
     result    : buffer STD_LOGIC_VECTOR(31 downto 0);
     zero      : buffer STD_LOGIC;
     overflow  : buffer STD_LOGIC
);
end ALU;
```

CPU Control

```
entity CPUControl is
-- Functionality should match the truth table shown in Figure 4.22 of the textbook, inlcuding the
--    output 'X' values.
-- The truth table in Figure 4.22 omits the jump instruction:
--    Jump = '1'
--    MemWrite = RegWrite = '0'
--    all other outputs = 'X'
port(Opcode   : in  STD_LOGIC_VECTOR(5 downto 0);
     RegDst   : out STD_LOGIC;
     Branch   : out STD_LOGIC;
     MemRead  : out STD_LOGIC;
     MemtoReg : out STD_LOGIC;
     MemWrite : out STD_LOGIC;
     ALUSrc   : out STD_LOGIC;
     RegWrite : out STD_LOGIC;
     Jump     : out STD_LOGIC;
     ALUOp    : out STD_LOGIC_VECTOR(1 downto 0)
);
end CPUControl;
```

Instruction Memory (read only)

```
entity IMEM is
-- The instruction memory is a byte addressable, big-endian, read-only memory
-- Reads occur continuously
-- HINT: Use the provided dmem.vhd as a starting point
generic(NUM_BYTES : integer := 128);
-- NUM_BYTES is the number of bytes in the memory (small to save computation resources)
port(
     Address  : in  STD_LOGIC_VECTOR(31 downto 0); -- Address to read from
     ReadData : out STD_LOGIC_VECTOR(31 downto 0)
);
end IMEM;
```

Registers

```
entity registers is
-- This component is described in the textbook, starting on page 2.52
-- The indices of each of the registers can be found on the MIPS reference page at the front of the
--    textbook
-- Keep in mind that register 0(zero) has a constant value of 0 and cannot be overwritten

-- This should only write on the negative edge of Clock when RegWrite is asserted.
-- Reads should be purely combinatorial, i.e. they don't depend on Clock
-- HINT: Use the provided dmem.vhd as a starting point
port(RR1      : in  STD_LOGIC_VECTOR (4 downto 0);
     RR2      : in  STD_LOGIC_VECTOR (4 downto 0);
     WR       : in  STD_LOGIC_VECTOR (4 downto 0);
     WD       : in  STD_LOGIC_VECTOR (31 downto 0);
     RegWrite : in  STD_LOGIC;
     Clock    : in  STD_LOGIC;
     RD1      : out STD_LOGIC_VECTOR (31 downto 0);
     RD2      : out STD_LOGIC_VECTOR (31 downto 0);
     --Probe ports used for testing
     -- $t0 & $t1 & t2 & t3
     DEBUG_TMP_REGS : out STD_LOGIC_VECTOR(32*4 - 1 downto 0);
     -- $s0 & $s1 & s2 & s3
     DEBUG_SAVED_REGS : out STD_LOGIC_VECTOR(32*4 - 1 downto 0)
);
end registers;
```

Data Memory Implementation (provided in assignment2.zip)

Note: You should *not* modify this file except for the initialization of **dmemBytes** inside the *if(first)* block.

```
library IEEE;
use IEEE.STD_LOGIC_1164.ALL; -- STD_LOGIC and STD_LOGIC_VECTOR
use IEEE.numeric_std.ALL; -- to_integer and unsigned

entity DMEM is
-- The data memory is a byte addressble, big-endian, read/write memory with a single address port
-- It may not read and write at the same time
generic(NUM_BYTES : integer := 32);
-- NUM_BYTES is the number of bytes in the memory (small to save computation resources)
port(
     WriteData          : in  STD_LOGIC_VECTOR(31 downto 0); -- Input data
     Address            : in  STD_LOGIC_VECTOR(31 downto 0); -- Read/Write address
     MemRead            : in  STD_LOGIC; -- Indicates a read operation
     MemWrite           : in  STD_LOGIC; -- Indicates a write operation
     Clock              : in  STD_LOGIC; -- Writes are triggered by a rising edge
     ReadData           : out STD_LOGIC_VECTOR(31 downto 0); -- Output data
     --Probe ports used for testing
     -- Four 32-bit words: DMEM(0) & DMEM(4) & DMEM(8) & DMEM(12)
     DEBUG_MEM_CONTENTS : out STD_LOGIC_VECTOR(32*4 - 1 downto 0)
);
end DMEM;

architecture behavioral of DMEM is
type ByteArray is array (0 to NUM_BYTES) of STD_LOGIC_VECTOR(7 downto 0);
signal dmemBytes:ByteArray;
begin
   process(Clock,MemRead,MemWrite,WriteData,Address) -- Run when any of these inputs change
   variable addr:integer;
   variable first:boolean := true; -- Used for initialization
   begin
      -- This part of the process initializes the memory and is only here for simulation purposes
      -- It does not correspond with actual hardware!
      if(first) then
         -- Example: MEM(0x4) = 0x11330098 = 0b 0001 0001 0011 0011 0000 0000 1001 1000 = 288555160(decimal)
         dmemBytes(4)  <= "00010001";
         dmemBytes(5)  <= "00110011";
         dmemBytes(6)  <= "00000000";
         dmemBytes(7)  <= "10011000";
         first := false; -- Don't initialize the next time this process runs
      end if;

      -- The 'proper' HDL starts here!
      if Clock = '1' and Clock'event and MemWrite='1' and MemRead='0' then
         -- Write on the rising edge of the clock
         addr:=to_integer(unsigned(Address)); -- Convert the address to an integer
         -- Splice the input data into bytes and assign to the byte array
         dmemBytes(addr)   <= WriteData(31 downto 24);
         dmemBytes(addr+1) <= WriteData(23 downto 16);
         dmemBytes(addr+2) <= WriteData(15 downto 8);
         dmemBytes(addr+3) <= WriteData(7 downto 0);
      elsif MemRead='1' and MemWrite='0' then -- Reads don't need to be edge triggered
         addr:=to_integer(unsigned(Address)); -- Convert the address
         if (addr+3 < NUM_BYTES) then -- Check that the address is within the bounds of the memory
           ReadData <= dmemBytes(addr) & dmemBytes(addr+1) &
               dmemBytes(addr+2) & dmemBytes(addr+3);
         else report "Invalid DMEM addr. Attempted to read 4-bytes starting at address " &
            integer'image(addr) & " but only " & integer'image(NUM_BYTES) & " bytes are available"
            severity error;
         end if;
      end if;
   end process;
   -- Conntect the signals that will be used for testing
   DEBUG_MEM_CONTENTS <=
      dmemBytes( 0) & dmemBytes( 1) & dmemBytes( 2) & dmemBytes( 3) & --DMEM(0)
      dmemBytes( 4) & dmemBytes( 5) & dmemBytes( 6) & dmemBytes( 7) & --DMEM(4)
      dmemBytes( 8) & dmemBytes( 9) & dmemBytes(10) & dmemBytes(11) & --DMEM(8)
      dmemBytes(12) & dmemBytes(13) & dmemBytes(14) & dmemBytes(15);  --DMEM(12)
end behavioral;
```