nav_core::BaseGlobalPlanner
Δ
backward_global_planner
::BackwardGlobalPlanner
- nh forwardPathSub planPub markersPub lastForwardPathMsg costmap_ros cmd_server skip_straight_motion _distance puresSpinningRadStep_
+ BackwardGlobalPlanner() + ~BackwardGlobalPlanner() + makePlan() + makePlan() + createDefaultBackwardPath() + createPureSpiningAndStragiht LineBackwardPath() + initialize() - onForwardTrailMsg() - publishGoalMarker() - commandServiceCall()