move\_base\_z\_client
::backward\_global\_planner
::BackwardGlobalPlanner
::makePlan

move\_base\_z\_client
::backward\_global\_planner
::BackwardGlobalPlanner
::makePlan

move\_base\_z\_client ::backward\_global\_planner ::BackwardGlobalPlanner ::createDefaultBackwardPath

move\_base\_z\_client ::backward\_global\_planner ::BackwardGlobalPlanner

::publishGoalMarker