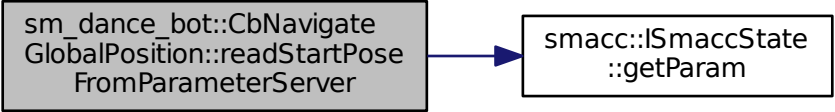


sm_dance_bot::CbNavigate
GlobalPosition::readStartPose
FromParameterServer



```
graph LR; A["sm_dance_bot::CbNavigate  
GlobalPosition::readStartPose  
FromParameterServer"] --> B["smacc::ISmaccState  
::getParam"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains three lines of text: 'sm_dance_bot::CbNavigate', 'GlobalPosition::readStartPose', and 'FromParameterServer'. The right box is white with a black border and contains two lines of text: 'smacc::ISmaccState' and '::getParam'. A blue arrow points from the right side of the gray box to the left side of the white box.

smacc::ISmaccState
::getParam