

smacc\_sm\_examples/sm  
\_dance\_bot/include/sm  
\_dance\_bot/superstates  
/ss\_radial\_pattern\_1.h

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graph TD; A["smacc_sm_examples/sm_dance_bot/include/sm_dance_bot/superstates/ss_radial_pattern_1.h"] --> B["sm_dance_bot/superstate_routines/radial_motion/ssr_radial_end_point.h"]; A --> C["sm_dance_bot/superstate_routines/radial_motion/ssr_radial_return.h"]; A --> D["sm_dance_bot/superstate_routines/radial_motion/ssr_radial_rotate.h"];
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sm\_dance\_bot/superstate  
\_routines/radial\_motion  
/ssr\_radial\_end\_point.h

sm\_dance\_bot/superstate  
\_routines/radial\_motion  
/ssr\_radial\_return.h

sm\_dance\_bot/superstate  
\_routines/radial\_motion  
/ssr\_radial\_rotate.h