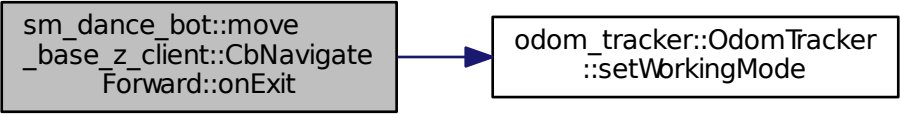


sm\_dance\_bot::move  
\_base\_z\_client::CbNavigate  
Forward::onExit



```
graph LR; A["sm_dance_bot::move  
_base_z_client::CbNavigate  
Forward::onExit"] --> B["odom_tracker::OdomTracker  
::setWorkingMode"]
```

A diagram showing a call from a source node to a target node. The source node is a gray rectangle on the left containing the text 'sm\_dance\_bot::move', '\_base\_z\_client::CbNavigate', and 'Forward::onExit'. A blue arrow points from the right side of this rectangle to the left side of a white rectangle on the right. The white rectangle contains the text 'odom\_tracker::OdomTracker' and '::setWorkingMode'.

odom\_tracker::OdomTracker  
::setWorkingMode