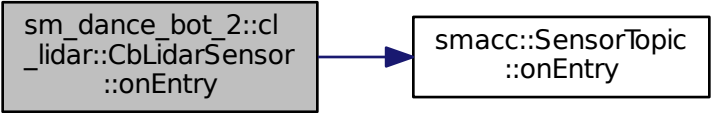


sm_dance_bot_2::cl
_lidar::CbLidarSensor
::onEntry



```
graph LR; A["sm_dance_bot_2::cl_lidar::CbLidarSensor::onEntry"] --> B["smacc::SensorTopic::onEntry"]
```

smacc::SensorTopic
::onEntry