```
smacc::SmaccClientBehavior
    + stateMachine
    + currentState
    + currentOrthogonal
    + SmaccClientBehavior()
    + ~SmaccClientBehavior()
    + getName()
    + onEntry()
    + onExit()
    + postEvent()
    + postEvent()
    + requiresClient()
    + requiresComponent()
    configureEventSourceTypes()
                   smacc::SensorTopic
                           < ClientType >
                   + sensor
                   + c1_
                   + c2_
+ c3_
                   + deferedEventPropagation
                   + SensorTopic()
                   + configureEventSourceTypes()
                   + onEntry()
                   + onExit()
                   + onMessageCallback()
                   + getEventLabel()
                         < ClLaserSensor >
smacc::SensorTopic
     < ClLaserSensor >
+ sensor
+ c1
+ c2
+ c3
+ deferedEventPropagation
+ SensorTopic()
+ configureEventSourceTypes()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
   sm_dance_bot::cl lidar
       ::CbLidarSensor
   + CbLidarSensor()
   + onEntry()
   + onMessageCallback()
```