



-max_angular_z_speed
-xy_goal_tolerance
-yaw_goal_tolerance
-k_beta_
-k_rho_
-carrot_angular
distance
-beta_offset
-alpha_offset
-k_alpha_
-carrot_distance
-
...

-goalMarkerPublisher_

-plan_

-costmapRos_

-currentPoseIndex_

-goalReached_

