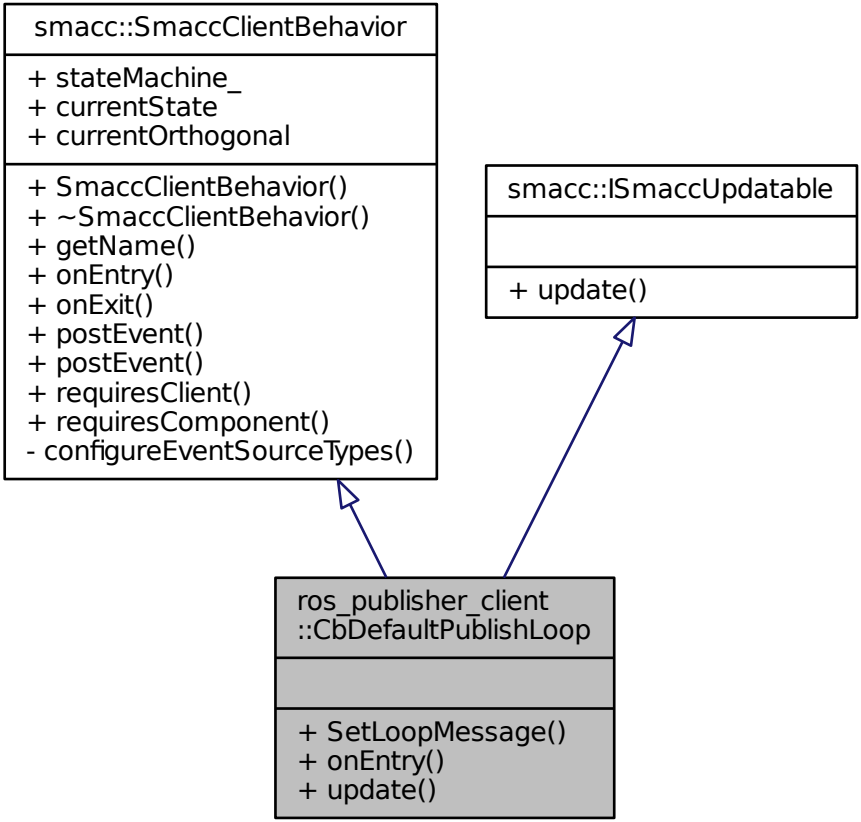
smacc::SmaccClientBehavior
+ stateMachine_
+ currentState
+ currentOrthogonal
+ SmaccClientBehavior()
+ ~SmaccClientBehavior()
+ getName()
+ onEntry()
+ onExit()
+ postEvent()
+ postEvent()
+ requiresClient()
+ requiresComponent()
- configureEventSourceTypes()
smacc::ISmaccUpdatable
+ update()
ros_publisher_client
::CbDefaultPublishLoop
+ SetLoopMessage()
+ onEntry()
+ update()