

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/orthogonals/obstacle\_perception  
\_orthogonal.h



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\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/sm\_dance\_bot.h



smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/src/sm\_dance\_bot.cpp