```
smacc::SmaccClientBehavior
   + stateMachine
   + currentState
   + currentOrthogonal
   + SmaccClientBehavior()
   + ~SmaccClientBehavior()
   + getName()
   + onEntry()
   + onExit()
   + postEvent()
   + requiresClient()
   + requiresComponent()
   - assignToOrthogonal()
                  smacc::SensorTopic
                         < ClientType >
                  + sensor
                  + c1
                  + c2
                  + c3
                  + deferedEventPropagation
                  + SensorTopic()
                  + assignToOrthogonal()
                  + onEntry()
                  + onExit()
                  + onMessageCallback()
                  + getEventLabel()
                        < LaserSensor >
 smacc::SensorTopic
      < LaserSensor >
 + sensor
 + c1
 + c2
 + c3
 + deferedEventPropagation
 + SensorTopic()
 + assignToOrthogonal()
 + onEntry()
 + onExit()
 + onMessageCallback()
 + getEventLabel()
sm dance bot::CbLidarSensor
+ CbLidarSensor()
+ onEntry()
+ onMessageCallback()
```