

```
graph BT; A["smacc_sm_reference_library/sm_dance_bot  
/include/sm_dance_bot  
/states/s_pattern/ssr_spattern  
_rotate_2.h"] --> B["smacc_sm_reference_library/sm_dance_bot  
/include/sm_dance_bot  
/superstates/ss_s_pattern_1.h"]; B --> C["smacc_sm_reference_library/sm_dance_bot  
/include/sm_dance_bot  
/sm_dance_bot.h"]; C --> D["smacc_sm_reference_library/sm_dance_bot  
/src/sm_dance_bot.cpp"]
```

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/states/s_pattern/ssr_spattern
_rotate_2.h

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/superstates/ss_s_pattern_1.h

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/sm_dance_bot.h

smacc_sm_reference
_library/sm_dance_bot
/src/sm_dance_bot.cpp