```
smacc::ISmaccClient
   # stateMachine
   # components -
   + ISmaccClient()
   + ~ISmaccClient()
   + initialize()
   + setStateMachine()
   + getName()
   + postEvent()
   + postEvent()
   + getComponent()
   + createComponent()
   configureEventSourceTypes()
                  smacc::SmaccPublisherClient
                        < MessageType >
                  + topicName
                  + queueSize
                  # nh
                  # pub
                  - initialīzed
                  + SmaccPublisherClient()
                  + ~SmaccPublisherClient()
                  + initialize()
                  + publish()
                        < std msgs::String >
smacc::SmaccPublisherClient
   < std msgs::String >
+ topicName
+ queueSize
# nh
# pub
- initialized
+ SmaccPublisherClient()
+ ~SmaccPublisherClient()
+ initialize()
+ publish()
    ros publisher client
      ::ClRosPublisher
    + ClRosPublisher()
```