smacc::ISmaccClient

stateMachine_
components_

+ ISmaccClient()
+ ~ISmaccClient()
+ initialize()
+ setStateMachine()
+ getName()
+ postEvent()
+ postEvent()
+ getComponent()
+ createComponent()
- configureEventSourceTypes()

smacc::SmaccPublisherClient

+ topicName
+ queueSize
# nh_
# pub_
- initialized_

+ SmaccPublisherClient()
+ ~SmaccPublisherClient()
+ configureMessageType()
+ initialize()
+ publish()

ros_publisher_client::ClRosPublisher

+ ClRosPublisher()