smacc::SmaccClientBehavior

+ stateMachine
+ currentState
+ currentOrthogonal

+ SmaccClientBehavior()
+ ~SmaccClientBehavior()
+ getName()
+ onEntry()
+ onExit()
+ postEvent()
+ requiresClient()
+ requiresComponent()
- assignToOrthogonal()

sm_dance_bot::CbNavigate GlobalPosition

+ initialPoint
+ initialYaw
- moveBaseClient_
- odomTracker_

+ CbNavigateGlobalPosition()
+ CbNavigateGlobalPosition()
+ onEntry()
+ goToRadialStart()
+ readStartPoseFromParameter Server()
+ onExit()