

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/client_behaviors/navigation  
/cb_navigate_global_position.h"] <-- B["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/sm_dance_bot.h"]; B <-- C["smacc_sm_reference  
_library/sm_dance_bot  
/src/sm_dance_bot.cpp"]
```

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/client_behaviors/navigation
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smacc_sm_reference
_library/sm_dance_bot
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