

```
boost::statechart::  
event< EvTimer< TSource > >
```

```
classDiagram
    class boost_statechart_event["boost::statechart::event< EvTimer< TSource > >"]
    class ros_timer_client_ev_timer["ros_timer_client::EvTimer< TSource >"]
    boost_statechart_event <|-- ros_timer_client_ev_timer
```

The diagram illustrates an inheritance relationship. At the top is a white rectangular box representing the base class `boost::statechart::event< EvTimer< TSource > >`. It is divided into three horizontal sections, with the class name in the top section. Below it is a gray rectangular box representing the derived class `ros_timer_client::EvTimer< TSource >`, also divided into three horizontal sections. A blue arrow with an open triangular head points from the top section of the gray box to the bottom section of the white box, indicating that `ros_timer_client::EvTimer` inherits from `boost::statechart::event`.

```
ros_timer_client::EvTimer  
< TSource >
```