

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
/src/sm_dance_bot.cpp"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/sm_dance_bot.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/mode_states/ms_dance_bot  
_recovery_mode.h"]
```

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/mode_states/ms_dance_bot
_recovery_mode.h

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/sm_dance_bot.h

smacc_sm_reference
_library/sm_dance_bot
/src/sm_dance_bot.cpp