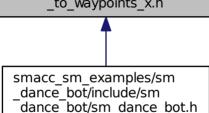```
smacc_sm_examples/sm
_dance_bot/include/sm
_dance_bot/states/st_navigate
_to_waypoints_x.h
```

```
smacc_sm_examples/sm
_dance_bot/include/sm
_dance_bot/sm_dance_bot.h
```

```
smacc_sm_examples/sm
_dance_bot/src/sm_dance
_bot.cpp
```