

```
graph BT; A["smacc_sm_reference_library/sm_dance_bot  
/include/sm_dance_bot  
/states/s_pattern/ssr_spattern  
_rotate_3.h"] --> B["smacc_sm_reference_library/sm_dance_bot  
/include/sm_dance_bot  
/superstates/ss_s_pattern_1.h"]; B --> C["smacc_sm_reference_library/sm_dance_bot  
/include/sm_dance_bot  
/sm_dance_bot.h"]; C --> D["smacc_sm_reference_library/sm_dance_bot  
/src/sm_dance_bot.cpp"];
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/states/s\_pattern/ssr\_spattern  
\_rotate\_3.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/superstates/ss\_s\_pattern\_1.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/sm\_dance\_bot.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/src/sm\_dance\_bot.cpp