```
smacc::ISmaccComponent
    # stateMachine
    + ISmaccComponent()
    + ~ISmaccComponent()
    + initialize()
    + setStateMachine()
    + getName()
    + postEvent()
smacc_odom tracker
          ::OdomTracker
# robotBasePathPub
# odomSub
# minPointDistanceForwardThresh
# minPointDistanceBackward
Thresh
# minPointAngularDistanceForward
Thresh
# minPointAngularDistanceBackward
Thresh
# publishMessages
# baseTrajectory
# workingMode
# pathStack
# subscribeToOdometryTopic
# m mutex
+ OdomTracker()
+ initialize()
+ processOdometryMessage()
+ setWorkingMode()
+ setPublishMessages()
+ pushPath()
+ popPath()
+ clearPath()
+ setStartPoint()
+ getPath()
# rtPublishPaths()
# updateForward()
# updateBackward()
```