```
smacc::SmaccClientBehavior
 + stateMachine
 + currentState
 + currentOrthogonal
 + SmaccClientBehavior()
 + ~SmaccClientBehavior()
 + getName()
 + onEntry()
 + onExit()
 + postEvent()
 + postEvent()
 + requiresClient()
 + requiresComponent()
 configureEventSourceTypes()
ros publisher client
::CbPublishOnce < RosMsgType >
+ onEntry()
```