```
smacc::SmaccSubStateBehavior
+ stateMachine
+ currentState
+ SmaccSubStateBehavior()
+ ~SmaccSubStateBehavior()
+ postEvent()
+ requiresComponent()
+ getName()
+ onEntry()
+ onExit()
   SbNavigateGlobalPosition
+ initialPoint
+ initialYaw

    moveBaseClient

- odomTracker
- plannerSwitcher
+ SbNavigateGlobalPosition()
+ SbNavigateGlobalPosition()
+ onEntry()
+ goToRadialStart()
+ readStartPoseFromParameter
Server()
```

+ onExit()