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move_base_z_client  
::WaypointNavigator  
::loadWayPointsFromFile
```

```
sm_dance_bot::StNavigate  
ToWaypointsX::loadWaypointsFirstTime
```

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sm_dance_bot::StNavigate  
ToWaypointsX::onInitialize
```

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graph RL; A[sm_dance_bot::StNavigate ToWaypointsX::onInitialize] --> B[sm_dance_bot::StNavigate ToWaypointsX::loadWaypointsFirstTime]; B --> C[move_base_z_client::WaypointNavigator::loadWayPointsFromFile];
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