nav_core::BaseLocalPlanner
<u> </u>
backward_local_planner ::BackwardLocalPlanner
- paramServer
+ BackwardLocalPlanner() + ~BackwardLocalPlanner() + computeVelocityCommands() + isGoalReached() + setPlan() + initialize() + initialize() + initialize() - reconfigCB() - createCarrotGoal() - pureSpinningCmd() - defaultBackwardCmd() - publishGoalMarker()