```
smacc::SmaccSubStateBehavior

+ stateMachine
+ currentState
+ currentOrthogonal

+ SmaccSubStateBehavior()
+ ~SmaccSubStateBehavior()
+ postEvent()
+ requiresClient()
+ requiresComponent()
+ getName()
+ onEntry()
+ onExit()
```

```
sm_dance_bot::SbNavigate
GlobalPosition
+ initialPoint
```

- + initialYaw
 moveBaseClient_
- odomTracker_
- + SbNavigateGlobalPosition()+ SbNavigateGlobalPosition()+ onEntry()
 - + goToRadialStart()
 - + readStartPoseFromParameter Server()
 - + onExit()