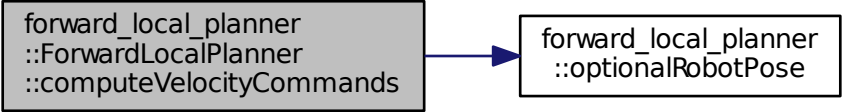


forward\_local\_planner  
::ForwardLocalPlanner  
::computeVelocityCommands



```
graph LR; A["forward_local_planner  
::ForwardLocalPlanner  
::computeVelocityCommands"] --> B["forward_local_planner  
::optionalRobotPose"]
```

A diagram showing a function call. On the left, a gray box contains the text 'forward\_local\_planner', '::ForwardLocalPlanner', and '::computeVelocityCommands'. A blue arrow points from this box to a white box on the right. The white box contains the text 'forward\_local\_planner' and '::optionalRobotPose'.

forward\_local\_planner  
::optionalRobotPose