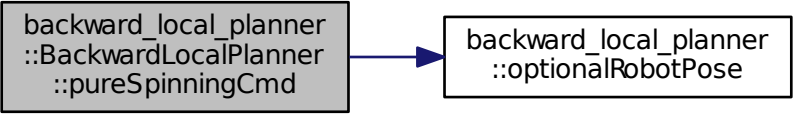


```
backward_local_planner  
::BackwardLocalPlanner  
::pureSpinningCmd
```



A diagram illustrating a return type transformation. A grey rectangular box on the left contains the text 'backward_local_planner :: BackwardLocalPlanner :: pureSpinningCmd'. A blue arrow points from this box to a white rectangular box on the right. The white box contains the text 'backward_local_planner :: optionalRobotPose'.

```
backward_local_planner  
::optionalRobotPose
```