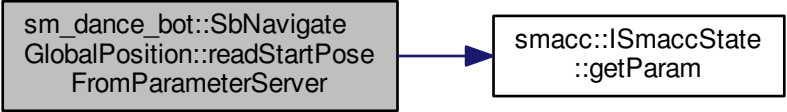


sm_dance_bot::SbNavigate
GlobalPosition::readStartPose
FromParameterServer



```
graph LR; A["sm_dance_bot::SbNavigate  
GlobalPosition::readStartPose  
FromParameterServer"] --> B["smacc::ISmaccState  
::getParam"]
```

A diagram showing a call from a function in the `sm_dance_bot` namespace to a function in the `smacc` namespace. The call is represented by a blue arrow pointing from the left box to the right box.

smacc::ISmaccState
::getParam