```
smacc::SmaccClientBehavior
 + stateMachine
 + currentState
 + currentOrthogonal
 + SmaccClientBehavior()
 + ~SmaccClientBehavior()
 + getName()
 + onEntry()
 + onExit()
 + postEvent()
+ postEvent()
+ requiresClient()
+ requiresComponent()
configureEventSourceTypes()
sm dance bot::move
base z client::CbNavigate
        GlobalPosition
+ initialPoint
+ initialYaw

    moveBaseClient

+ CbNavigateGlobalPosition()
+ CbNavigateGlobalPosition()
+ onEntry()
```

+ goToRadialStart() + readStartPoseFromParameter Server() + onExit()