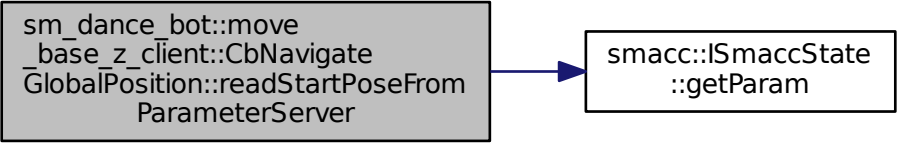


sm_dance_bot::move
_base_z_client::CbNavigate
GlobalPosition::readStartPoseFrom
ParameterServer



```
graph LR; A["sm_dance_bot::move  
_base_z_client::CbNavigate  
GlobalPosition::readStartPoseFrom  
ParameterServer"] --> B["smacc::ISmaccState  
::getParam"]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and a black border, containing four lines of text. The right box has a white background and a black border, containing two lines of text.

smacc::ISmaccState
::getParam