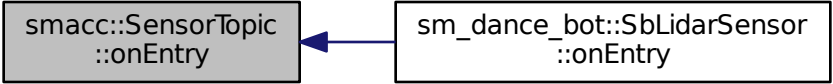


smacc::SensorTopic  
::onEntry



```
graph LR; A[sm_dance_bot::SbLidarSensor::onEntry] --> B[smacc::SensorTopic::onEntry];
```

The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'smacc::SensorTopic' on the top line and '::onEntry' on the bottom line. The box on the right is white and contains the text 'sm\_dance\_bot::SbLidarSensor' on the top line and '::onEntry' on the bottom line. A dark blue arrow points from the right side of the white box to the left side of the gray box.

sm\_dance\_bot::SbLidarSensor  
::onEntry