

BaseGlobalPlanner

```
classDiagram
    class BaseGlobalPlanner {
    }
    class forward_global_planner_FwdGlobalPlanner {
        -nh_
        -planPub_
        -costmap_ros_
        -skip_straight_motion_distance_
        -puresSpinningRadStep_
        +ForwardGlobalPlanner()
        +makePlan()
        +makePlan()
        +initialize()
    }
    BaseGlobalPlanner <|-- forward_global_planner_FwdGlobalPlanner
```

forward_global_planner
::ForwardGlobalPlanner

- nh_
- planPub_
- costmap_ros_
- skip_straight_motion_distance_
- puresSpinningRadStep_

- + ForwardGlobalPlanner()
- + makePlan()
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