

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/clients/move_base_z_client  
/client_behaviors/cb_rotate.h"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/sm_dance_bot.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
/src/sm_dance_bot.cpp"];
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/clients/move\_base\_z\_client  
/client\_behaviors/cb\_rotate.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/sm\_dance\_bot.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/src/sm\_dance\_bot.cpp