

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
_client_behaviors/navigation  
_client_behaviors/cb_navigate  
_global_position.h"] <-- B["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/sm_dance_bot.h"]; B <-- C["smacc_sm_reference  
_library/sm_dance_bot  
/src/sm_dance_bot.cpp"]
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
\_client\_behaviors/navigation  
\_client\_behaviors/cb\_navigate  
\_global\_position.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/sm\_dance\_bot.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/src/sm\_dance\_bot.cpp