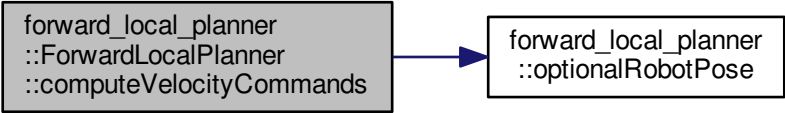


```
forward_local_planner  
::ForwardLocalPlanner  
::computeVelocityCommands
```



```
graph LR; A[forward_local_planner  
::ForwardLocalPlanner  
::computeVelocityCommands] --> B[forward_local_planner  
::optionalRobotPose]
```

A diagram showing a function call. On the left, a gray box contains the text 'forward\_local\_planner', '::ForwardLocalPlanner', and '::computeVelocityCommands'. A blue arrow points from this box to a white box on the right. The white box contains the text 'forward\_local\_planner' and '::optionalRobotPose'.

```
forward_local_planner  
::optionalRobotPose
```