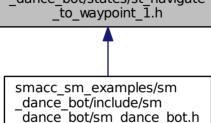
```
smacc_sm_examples/sm
_dance_bot/include/sm
_dance_bot/states/st_navigate
_to_waypoint_1.h
```



smacc_sm_examples/sm _dance_bot/src/sm_dance _bot.cpp