smacc::ISmaccClient

stateMachine_

+ ISmaccClient()
+ ~ISmaccClient()
+ initialize()
+ setStateMachine()
+ getName()
+ postEvent()
+ postEvent()
- assignToOrthogonal()

ros_timer_client::SmaccTimerClient

+ onTimerTick
+ c_
# nh_
# timer
# duration
# oneshot

+ SmaccTimerClient()
+ ~SmaccTimerClient()
+ initialize()
# timerCallback()