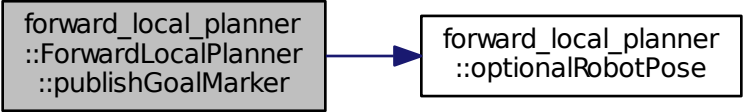


forward_local_planner
::ForwardLocalPlanner
::publishGoalMarker



```
graph LR; A["forward_local_planner  
::ForwardLocalPlanner  
::publishGoalMarker"] --> B["forward_local_planner  
::optionalRobotPose"]
```

A diagram showing a call to the `publishGoalMarker` method of the `ForwardLocalPlanner` class. The call is represented by a box with a gray background and a black border. A blue arrow points from this box to another box on the right, which represents the target of the call, `optionalRobotPose`.

forward_local_planner
::optionalRobotPose