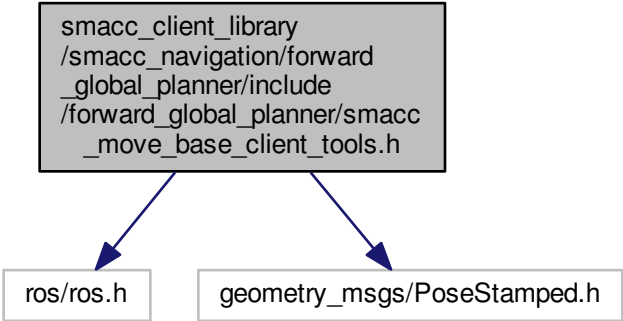


smacc_client_library
/smacc_navigation/forward
_global_planner/include
/forward_global_planner/smacc
_move_base_client_tools.h



```
graph TD; A["smacc_client_library  
/smacc_navigation/forward  
_global_planner/include  
/forward_global_planner/smacc  
_move_base_client_tools.h"] --> B["ros/ros.h"]; A --> C["geometry_msgs/PoseStamped.h"]
```

ros/ros.h

geometry_msgs/PoseStamped.h