

```
graph BT; A["smacc_sm_reference_library/sm_dance_bot/include/sm_dance_bot/obstacle_perception_orthogonal.h"] <-- B["smacc_sm_reference_library/sm_dance_bot/include/sm_dance_bot/sm_dance_bot.h"]; B <-- C["smacc_sm_reference_library/sm_dance_bot/src/sm_dance_bot.cpp"]
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/orthogonals/obstacle\_perception  
\_orthogonal.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/sm\_dance\_bot.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/src/sm\_dance\_bot.cpp