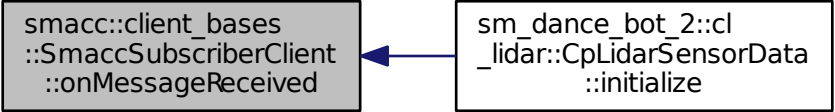


```
smacc::client_bases  
::SmaccSubscriberClient  
::onMessageReceived
```



A diagram showing a call from a client to a base class. A blue arrow points from the right box to the left box. The left box is shaded gray and contains the text 'smacc::client\_bases', '::SmaccSubscriberClient', and '::onMessageReceived'. The right box is white and contains the text 'sm\_dance\_bot\_2::cl', '\_lidar::CpLidarSensorData', and '::initialize'.

```
sm_dance_bot_2::cl  
_lidar::CpLidarSensorData  
::initialize
```