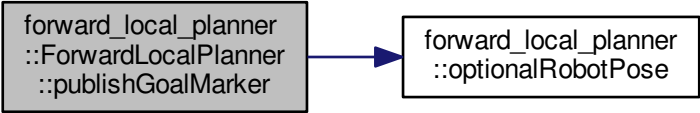


forward_local_planner
::ForwardLocalPlanner
::publishGoalMarker



```
graph LR; A["forward_local_planner  
::ForwardLocalPlanner  
::publishGoalMarker"] --> B["forward_local_planner  
::optionalRobotPose"]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and a black border, containing the text 'forward_local_planner', '::ForwardLocalPlanner', and '::publishGoalMarker' on three lines. The right box has a white background and a black border, containing the text 'forward_local_planner' and '::optionalRobotPose' on two lines.

forward_local_planner
::optionalRobotPose