```
# stateMachine
     # components
     + ISmaccClient()
     + ~ISmaccClient()
     + initialize()
     + setStateMachine()
     + getName()
     + postEvent()
     + postEvent()
     + getComponent()
     + createComponent()
     configureEventSourceTypes()
                    smacc::client_bases
                    ::SmaccSubscriberClient
                           < MessageType >
                    + topicName
                    + queueSize
                    + onFirstMessageReceived
                    + onMessageReceived
                    + postMessageEvent
                    + postInitialMessageEvent
                    # nh_
                    - sub
                    firstMessage_
                    - initialized
                    + SmaccSubscriberClient()
                    + ~SmaccSubscriberClient()
                    + configureEventSourceTypes()
                    + initialize()
                    messageCallback()
                    < sensor_msgs::LaserScan >
smacc::client_bases
::SmaccSubscriberClient
 < sensor_msgs::LaserScan >
                                     smacc::SensorClient
+ topicName
                                           < MessageType >
+ queueSize
+ onFirstMessageReceived
                                     + onMessageTimeout
+ onMessageReceived
                                     + postTimeoutMessageEvent
+ postMessageEvent
                                     + timeout
+ postInitialMessageEvent

    timeoutTimer_

# nh_
                                     - initialized
- sub
firstMessage_
                                     + SensorClient()
- initialized
                                     + configureEventSourceTypes()
                                     + initialize()
+ SmaccSubscriberClient()
                                     timeoutCallback()
+ ~SmaccSubscriberClient()
+ configureEventSourceTypes()
+ initialize()
messageCallback()
                                     < sensor_msgs::LaserScan >
          smacc::SensorClient
            < sensor msgs::LaserScan >
           + onMessageTimeout
          + postTimeoutMessageEvent
          + timeout
           timeoutTimer_
          - initialized
           + SensorClient()
                            SourceTypes()
           + initialize()
          timeoutCallback()
               sm_dance_bot::cl lidar
                  ::ClLaserSensor
               + ClLaserSensor()
```

smacc::ISmaccClient