Chipsee

Industrial PC

Raspberry Pi OS on CM4 User Manual

For CM4 Products

Content can change at anytime, check our website for latest information of this product.
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Raspberry Pi OS

Raspberry Pi OS User Manual

This manual provides users with a quick start guide of Chipsee Raspberry Pi Computer (Abbreviated as RPC) running a Raspberry Pi OS (raspios-debian-buster, raspios-debian-bullseye). Through this manual, users can quickly understand the hardware resources; users can debug Raspberry Pi OS via serial, SSH, and VNC.

Revision	Date	Author	Description
V2.1	2021-04-28	Chipsee	Revision
V2.2	2023-11-09	Chipsee	Update Supported Boards

SUPPORTED BOARDS:

- CS10600RA070
- CS12800RA101
- CS12720RA4050
- CS10600RA4070
- CS10600RA4070P-D
- CS12800RA4101A
- CS12800RA4101P
- CS10768RA4121
- CS19108RA4133
- CS10768RA4150
- CS19108RA4156

> - CS12102RA4170
> - CS12102RA4190
> - CS19108RA4215
> - CS19108RA4236
> - CSRA4BOX

PREBUILT IMAGES PACKAGE:

Below are the links to the prebuilt images for the Raspbian operating system on the various industrial Pi PC's.

- `Latest system image for Chipsee Industrial Pi products`

System Features

> **Note**
>
> Chipsee uses the Raspberry official OS on the product.
> We add Chipsee hardware drivers to the Raspberry official system.
> For more information, please refer to Industrial Pi.

Preparation

You will need to prepare the following items before you can start using the Prebuilt Images Package to re-flash the system.

Power Supply Unit (PSU) with the appropriate voltages, as follows:

- These products: CS12720RA4050, CS10600RA070, CS10600RA4070, CS10600RA4070P-D, CSRA4BOX and CS12800RA101 requires a 6V to 36V power adapter. You must provide the power adapter since Chipsee does not ship these products with a power adapter.
- The CS12800RA4101A RPC needs a 12V power adapter. Chipsee provides the power adapter.
- The CS12800RA4101P, CS10768RA4121, CS19108RA4133, CS10768RA4150, CS19108RA4156, CS19108RA4215, CS19108RA4236 RPC need 12V to 36V power adapter.

Hardware Requirements

- Chipsee Raspberry Pi®
- PSU according to the instructions above
- Mini-B USB OTG and MicroB USB Cable to download system images to CM3/CM3+/CM4 based IPC's.
- USB to RS232 serial cable for serial debugging the Chipsee Raspberry Pi® product.
- TF Card (SD Card) to create a bootable storage for re-flashing the system. Use the prebuilt files link above to re-flash the system.
- If you use CM3 Lite/CM3 Lite+/CM4 Lite, you also need one SD card, 16GB at least.

Software Requirements

- Raspberry Pi OS Prebuilt Images Package (from the link above)
- 7zip
- XShell or other terminal emulation software
- VNC Viewer
- BalenaEtcher
- `Rpiboot`

> **Note**
>
> - If you want to change the system, you need 7zip, a Prebuilt image, balenaEtcher, and rpiboot.

- You can use Xshell or other terminal emulation software to debug Chipsee Raspberry Pi products in Windows.
- You can use VNC-Viewer to control Chipsee Raspberry Pi products over Ethernet.

Note

In this documentation, all the commands are executed with `root` user privileges.

Debug

In this document, we use Xshell to debug the Chipsee Raspberry Pi products. You can also use other tools such as Putty or another terminal emulation software.

Serial Debug

The RS232_0 is configured as debug console by default on all Chipsee Raspberry Pi products. You can use it to debug directly, and the default user and password is [pi / raspberry]. Use the session properties as shown on the figure below.

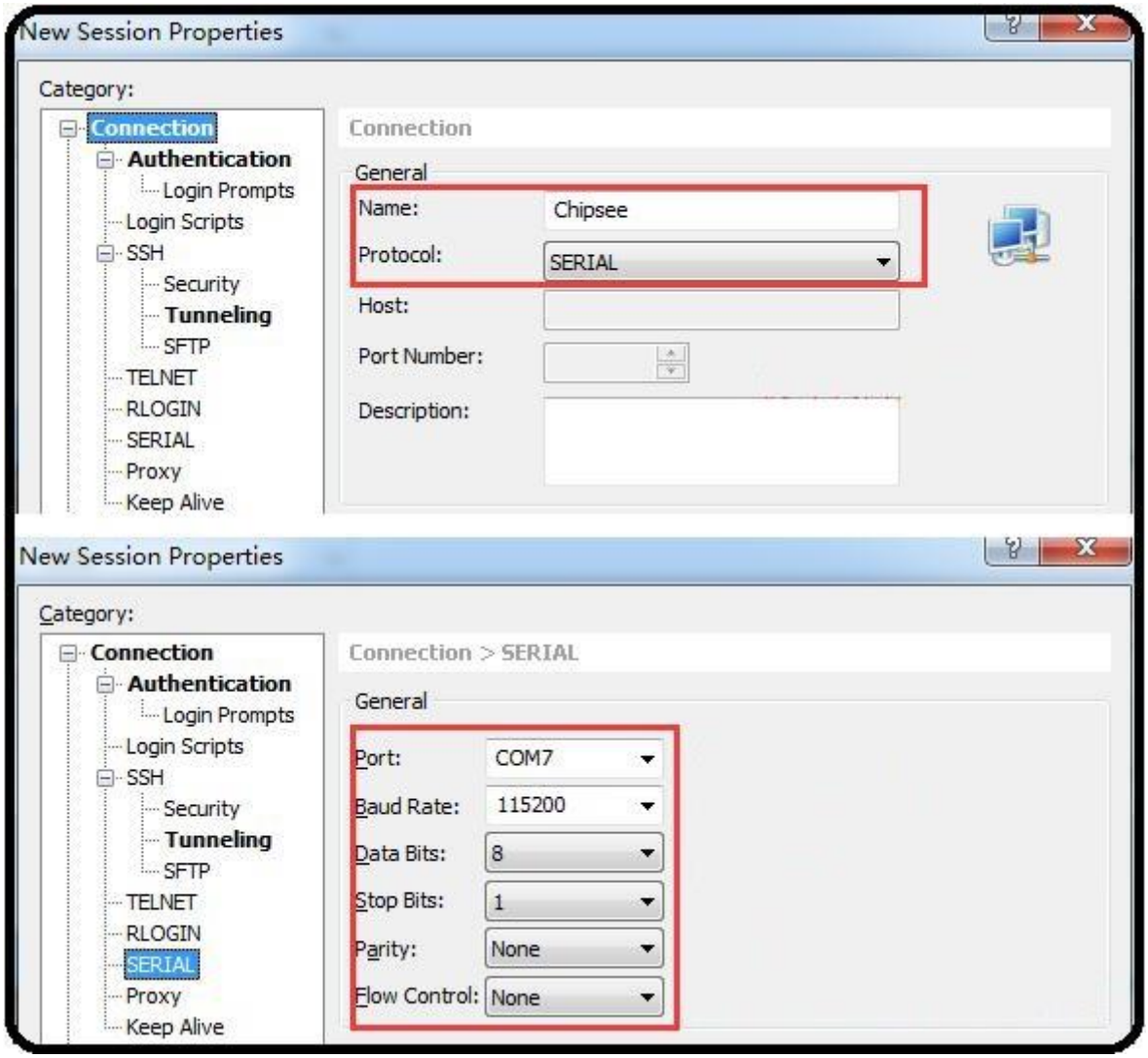


Figure 1055: Session Properties

If you need to change the debug serial to normal serial, follow these steps:

- Open and edit */boot/cmdline.txt* file.
- In the file, remove the line *console=ttyAMA0, 115200* . Save and close file.
- Reboot the RPC.

SSH Debug

To perform SSH debugging on the Chipsee Raspberry Pi® product, you must first connect the product to the Internet.

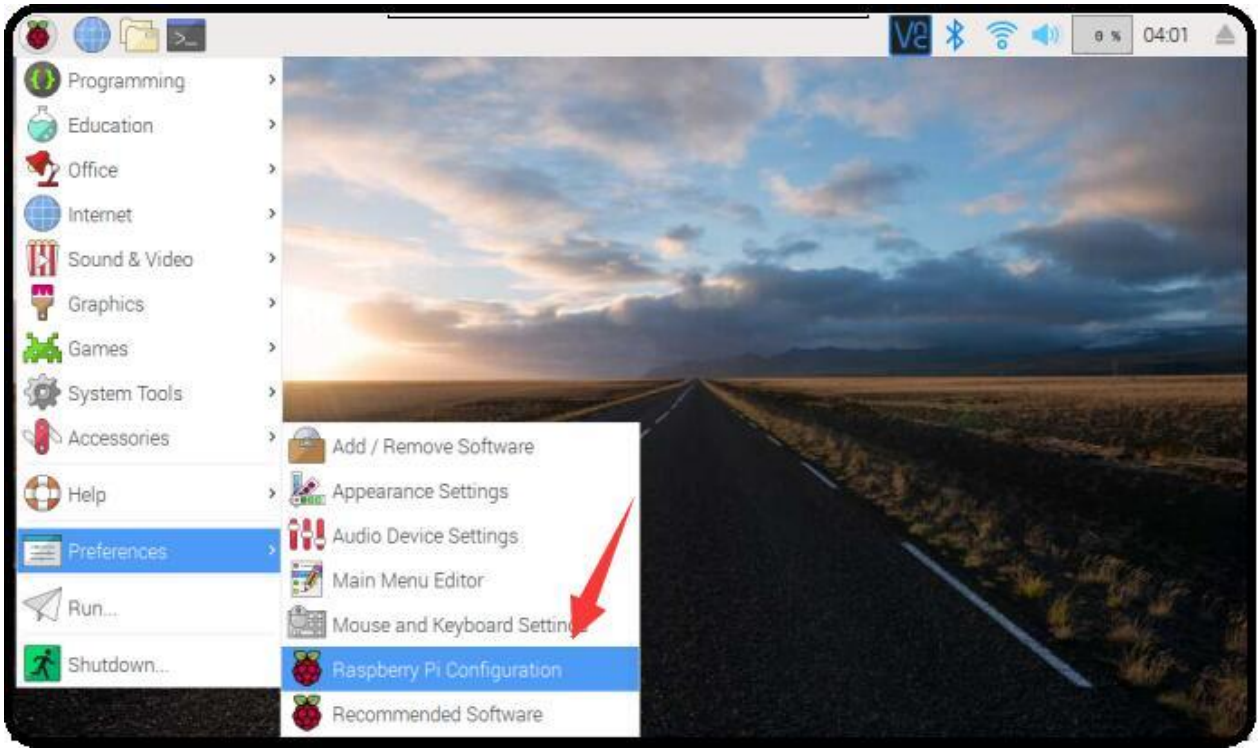
Continue the debugging by follow these steps:

- Get the IP address of the Chipsee Raspberry Pi® product.
- **Enable the SSH feature in the Chipsee Raspberry Pi® product by running the following command in debug console:**

```
$ sudo raspi-config

Interfacing Options -> SSH -> Yes
```

- **If you don't have a debug console, you can also use the GUI feature to enable SSH.**



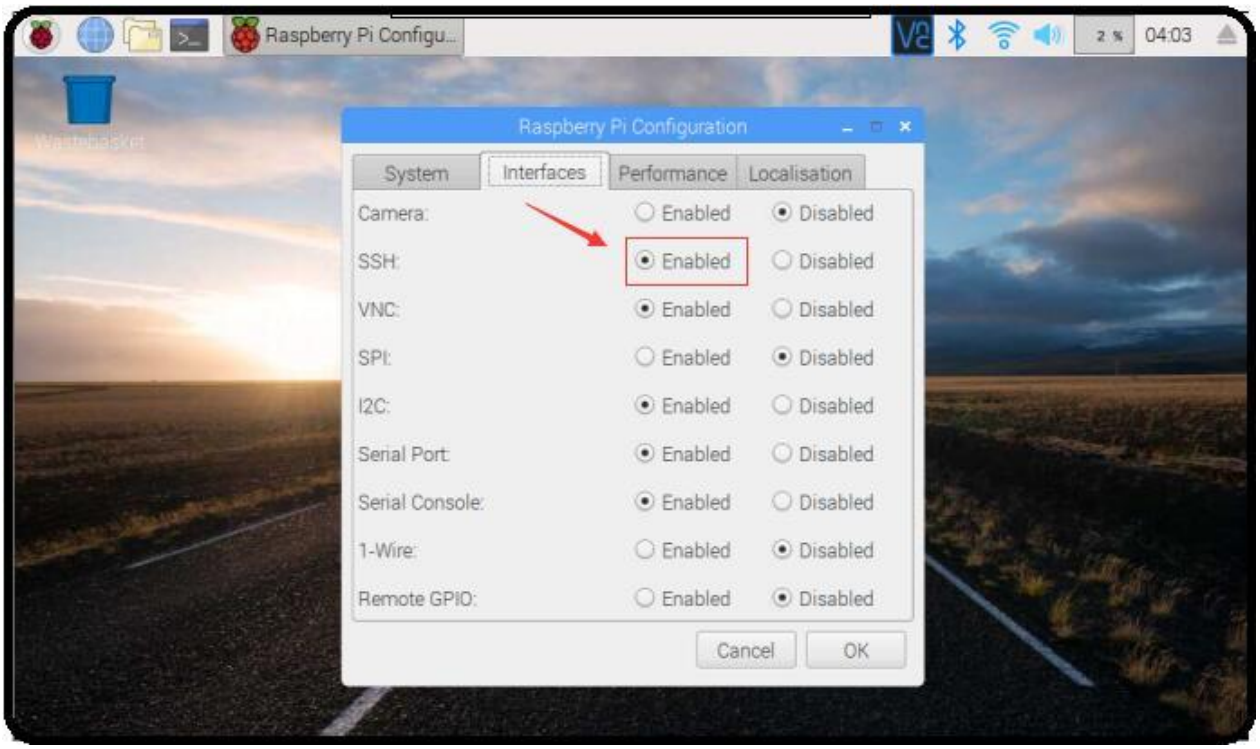


Figure 1056: Enabling SSH (GUI)

- Open and configure XShell or use ssh tool in the PC directly
- **In XShell, add a new session and set it as shown on the figure below.**

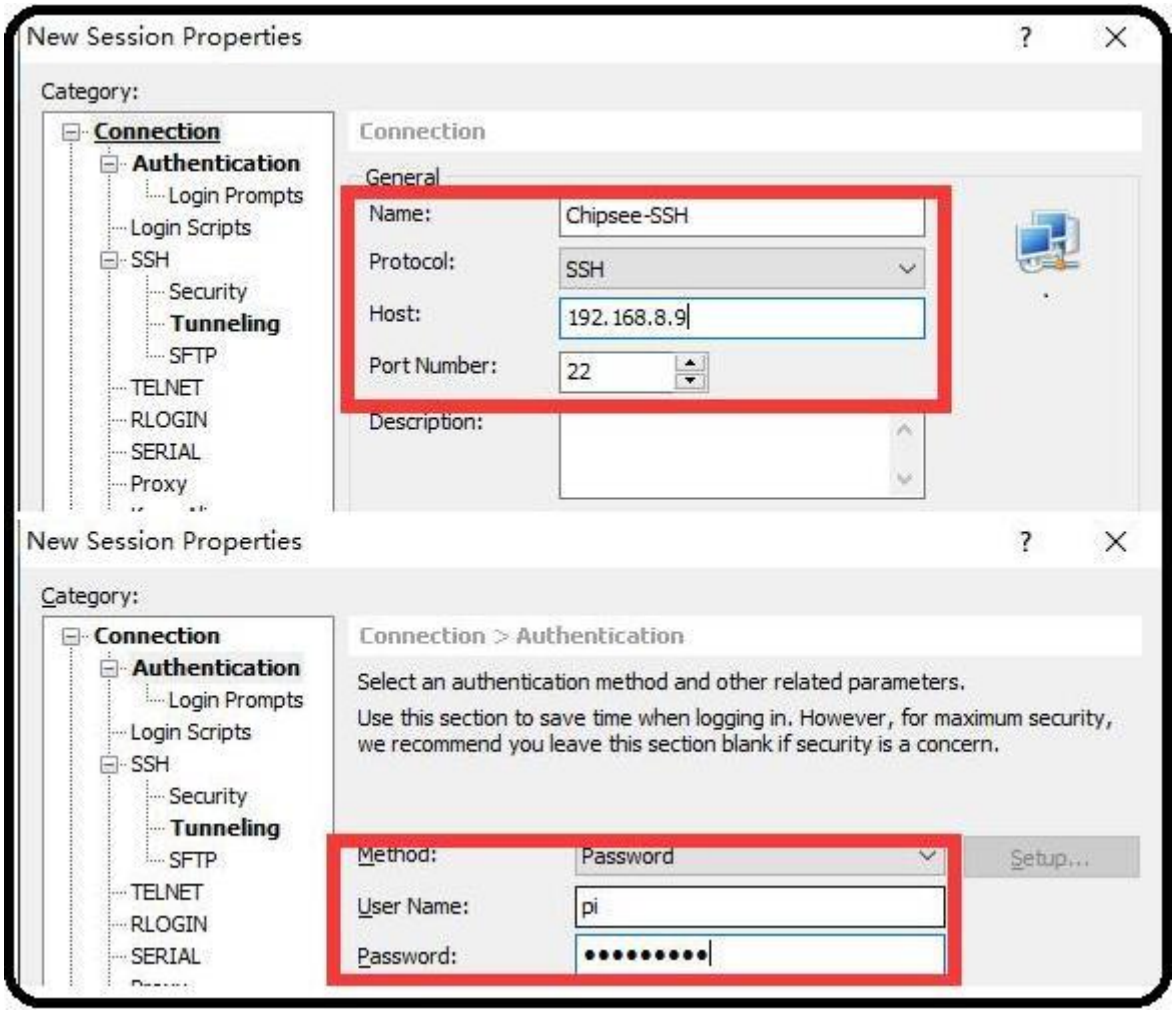


Figure 1057: SSH Setting on Xshell

- **Now we can perform SSH debugging using XShell**

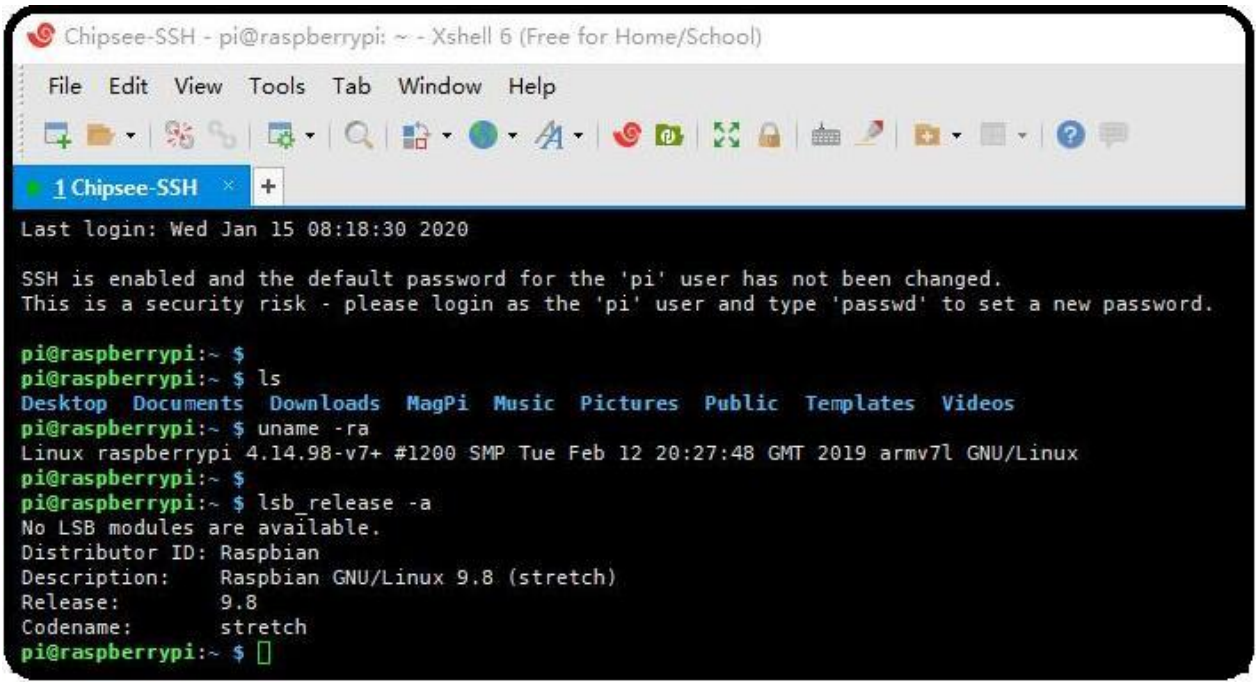


Figure 1058: SSH Debug

VNC Debug

You can use VNC-Viewer in Windows to control Chipsee Raspberry Pi product over Ethernet.

Continue the debugging by follow these steps:

- **Enable the VNC feature in the Chipsee Raspberry Pi® product by running the following command in debug console:**

```
$ sudo raspi-config

Interfacing Options -> VNC -> Yes
```

- **If you don’t have a debug console, you can also use the GUI feature to enable VNC.**

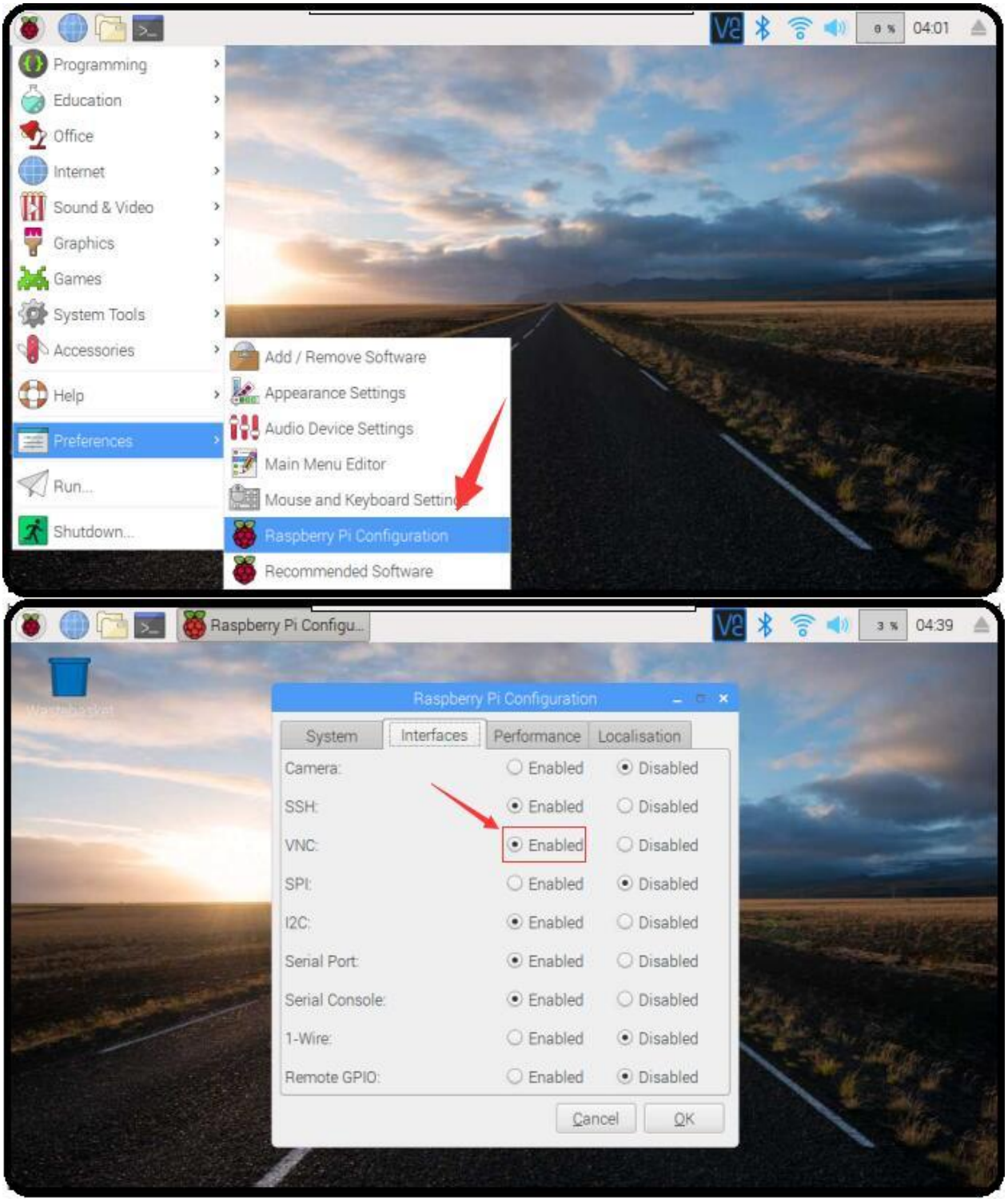


Figure 1059: Enabling VNC (GUI)

- **Use VNC-Viewer in Windows to control it over Ethernet, as shown in the figures below.**

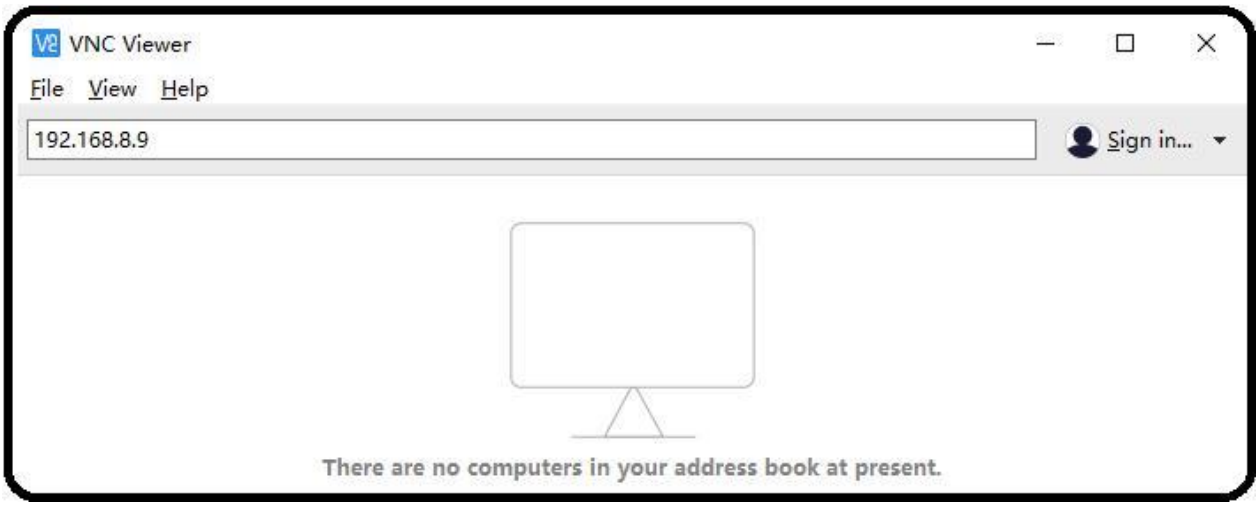


Figure 1060: Vnc-Viewer Connect

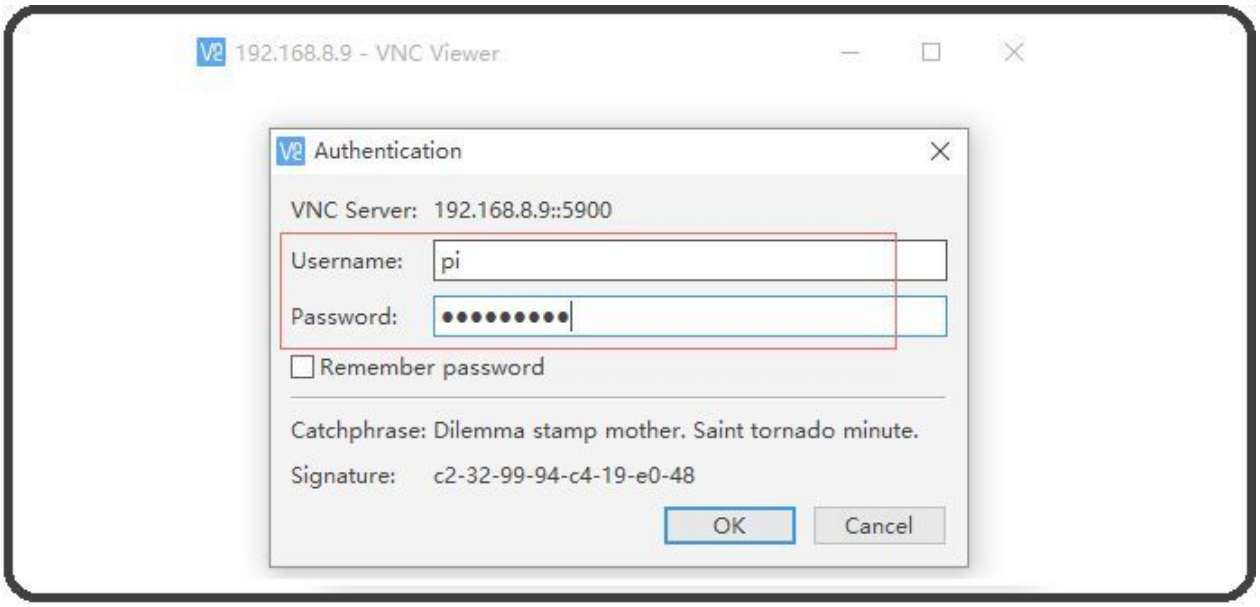


Figure 1061: Authentications

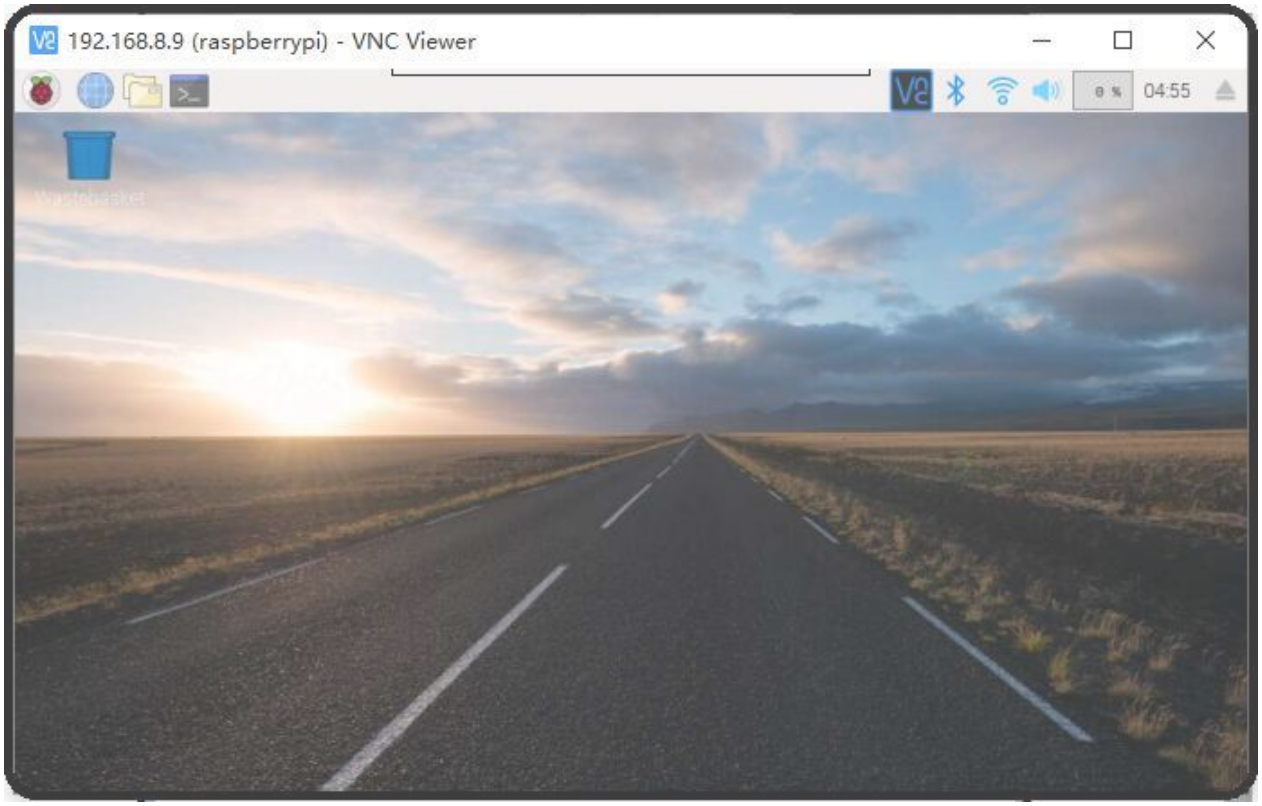


Figure 1062: VNC Desktop

Downloading images

Boot Switch Configuration

Chipsee RPC supports booting from an integrated eMMC or an external TF Card (also known as the micro SD card).

> **Note**
>
> CS12800RA4101A and CS12800RA4101P only supports eMMC boot

The Compute Module (CM) version will determine the boot modes your product supports. If you use CM with eMMC, you can only use eMMC boot. If you use CM Lite which has no eMMC, you can only use SD boot.
To boot from the SD Card, you must place the SD Card in **SD0** slot. You can use the **SD1** slot as external storage.

For **CS10600RA070**, **CS12800RA101**, and **CS10600RA4070** products, you can download a new system to eMMC by: configuring the boot switch to USB position, inserting Mini-B USB cable, and then power the board. This will enable eMMC to work as a USB storage.
After the eMMC flash, you need to configure the boot switch to the eMMC position again.
If you need to use SD boot, you should configure the boot switch to the eMMC position.

For the **CS12800RA4101A** product, you can download a new system to eMMC by: inserting a Micro-B USB cable, pressing the VOL+ button, and then power the board to enable eMMC to work as a USB storage. If you use C111 Version, you should press Boot Mode button.

For the **CS12800RA4101P** product, you can download a new system to eMMC by: inserting a Micro-B USB cable, pressing the Boot DIP button, and then power the board to enable eMMC to work as a USB storage.

The next sections explain in detail the steps in downloading a new system to eMMC.

Prebuilt image

Chipsee Raspberry Pi products use the Raspberry Pi official system as a base and add some modules and drivers. You can get the driver and latest image by referring to https://github.com/Chipsee/industrial-pi#latest-system-images.
If you're not using balenaEtcher, you'll need to unzip the *.img.xz* file and get the image file *(.img)* to write to your SD card.

Writing images to the SD Card

Before you start, don't forget to check your SD card size (at least 16GB).
You will need to use an image writing tool to install the downloaded image on your SD card.

Using balenaEtcher Tool

balenaEtcher is a graphical SD card writing tool that works on Mac OS, Linux and Windows, and is the easiest option for most users. balenaEtcher also supports writing images directly from the .img.xz file, without any unzipping required.
To write your image with balenaEtcher, follow these steps:

- Download and install the latest version of balenaEtcher.
- Connect an SD card reader with the SD card inside.
- Open balenaEtcher and select from your hard drive the Raspberry Pi® .img.xz file you want to write to the SD card.
- Select the SD card you want to write your image to.
- Review your selections and click 'Flash!' to begin writing data to the SD card.

> **Note**
>
> For Linux users, **zenity** might need to be installed on your machine for balenaEtcher to be able to write the image on your SD card.

> **Note**
>
> The image supports Chipsee all Industrial-Pi products but AIO-CM4-156, you should refer to the guide for your product. You should wait 2 ~ 5 minutes after flashed system as it needs time to detect the product to complete initial work. If a sound is heard, don't worry, just wait it to boot.

Writing images to the eMMC

Before you start, don't forget to check your eMMC size, and select one image. You also need to install `rpiboot` to enable eMMC to work as one USB storage in your PC.

Under Windows, an installer is available to install the required drivers and boot tool automatically.

For those who just want to enable the Compute Module eMMC as a mass storage device under Windows, the stand-alone installer is the recommended option.

The write images to the eMMC, follow these steps:

- Download and run the Windows installer **rpitools** to install the drivers and boot tool.

- For **CS10600RA070**, **CS12800RA101**, and **CS10600RA4070** products, plug your host PC Mini-B USB into the USB Downloader port, making sure the boot switch is set to the USB position.
- For **CS12800RA4101A** product, plug your host PC Micro-B USB into the USB Slave port (can be also called USB Download Port), press and hold the VOL+ button, if you use C111 Version, press Boot Mode button.
- For **CS12800RA4101P** product, plug your host PC Micro-B USB into the USB Slave port (can be also called USB Download Port), press and hold the Boot DIP button.
- Power ON the board. Windows should now find the hardware and install the driver. For CS12800RA4101A and CS12800RA4101P, you can release the button now.
- **Once the driver installation is complete, run the RPiBoot.exe tool that was previously installed. You can run RPiBoot.exe in Windows PowerShell, as shown on the figure below.**

Figure 1063: RPIboot tool

- After a few seconds, the Compute Module eMMC will pop up under Windows as a disk (USB mass storage device).
- Refer to Writing images to the SD Card to flash system to eMMC (like the SD card in Windows).
- If process completes, power OFF the board and ensure the boot switch is set to eMMC position. Power ON to use the new system.
  For **CS12800RA4101A**, ignore repositioning the boot switch, a reboot will be ok.
  To learn more, visit the following link: https://www.raspberrypi.org/documentation/hardware/computemodule/cm-emmc-flashing.md

Note

The image supports Chipsee all Industrial-Pi products but AIO-CM4-156, you should refer to the guide for your product. You should wait 2 ~ 5 minutes after flashed system as it needs time to detect the product to complete initial work. If a sound is heard, don't worry, just wait it to boot.

System Resource

SD Card/USB

SD Card is for external storage and needs to be placed in the **SD1** port. The **SD0** port is used by boot.

SD Card and USB Storage support hot plug. They will be automatically mounted on */media/pi/* . For **CS12800RA4101A** and **CS12800RA4101P**, there is only one SD slot.

Serial Port

Chipsee Raspberry Pi® boards support RS232 and RS485. Check the table below to know more about the serial port on different boards.

Ports	Name	Node	Protocol
1	RS232_0	/dev/ttyAMA0	RS232
2	RS232_1/RS485_1	/dev/S0	RS232/RS485

Table 475 CS10600RA070-C111

> **Note**
>
> RS232_1/RS485_1 uses the same UART pins from the CPU, so they use the same device node. You can only use one at a time. RS485 signal has been mounted on the 120Ω Matched Resistor.

There is one GPIO that is used by RS485. You can control it to enable and disable RS485 to send and receive. Check the tables below.

GPIO	Initial	Control	Function
GPIO34	*$ echo 34 > /sys/class/gpio/export* *$ echo out > /sys/class/gpio/gpio34/direction*	*$ echo 1 > /dev/rs485con*	Enable send
			Disable receive
	$ ln -s /sys/class/gpio/gpio34/value /dev/rs485con	*$ echo 0 > /dev/rs485con*	Enable receive
			Disable send

Table 476 RS485 control GPIO

Ports	Name	Node	Protocol
1	CPU_RS232_0	/dev/ttyAMA0	RS232
2	CPU_RS232_1	/dev/ttyS0	RS232
3	RS232_1	/dev/ttyUSB0	RS232
4	RS232_2	/dev/ttyUSB1	RS232
5	RS485_3	/dev/ttyUSB2	RS485
6	RS485_4	/dev/ttyUSB3	RS485

Table 477 CS12800RA101

Ports	Name	Node	Protocol
1	RS232_0	/dev/ttyAMA0	RS232
2	RS232_2	/dev/ttyAMA1	RS232
3	RS232_3	/dev/ttyAMA2	1
4	RS485_3	/dev/ttyAMA2	RS485
5	RS232_5	/dev/ttyAMA3	1
6	RS485_5	/dev/ttyAMA3	RS485

Table 478 CS10600RA4070-C111/CS10600RA4070P-D/CSRA4BOX

1(1,2) This channel does not output data by default. You can customize the channel to RS232 with port 4 and port 6 disabled.

Ports	Name	Node	Protocol
1	RS232_0	/dev/ttyAMA0	RS232
2	RS232_1	/dev/ttyAMA1	RS232
3	RS485_2	/dev/ttyAMA2	RS485

Table 479 CS12800RA4101A

Ports	Name	Node	Protocol
1	RS232_0	/dev/ttyAMA0	RS232
2	RS232_2	/dev/ttyAMA1	RS232
3	RS232_3	/dev/ttyAMA2	RS485
4	RS232_5	/dev/ttyAMA3	RS485

Table 480 CS12800RA4101P/CS19108RA4133P/CS10768RA4150P/CS19108RA4156P/ CS12102RA4170P/CS12102RA4190P/CS19108RA4215P/CS19108RA4236P

You can install **cutecom** to test the serial port:

```
$ sudo apt-get install cutecom
```

Only root user and use the serial port:

```
$ sudo cutecom
```

GPIO

There are 8 GPIOs, 4 Output, and 4 Input, they are all isolated. You can control the output or input pin voltage by feeding the VDD_ISO suite voltage. The pin voltage should be from 5V to 24V. Refer to the tables below for a detailed port definition:

Function	Device Node	GPIOD line
IN4	/dev/chipsee-gpio8	3
IN3	/dev/chipsee-gpio7	2
IN2	/dev/chipsee-gpio6	1
IN1	/dev/chipsee-gpio5	0
OUT4	/dev/chipsee-gpio4	4
OUT3	/dev/chipsee-gpio3	5
OUT2	/dev/chipsee-gpio2	6
OUT1	/dev/chipsee-gpio1	7
Isolated GND	NC	NC
Isolated VDD(5V-24V)	NC	NC

Table 481 GPIO Device Node

- **Control** *OUT1* **by setting it high or low**

```
$ echo 1 > /dev/chipsee-gpio1    // set OUT1 high

$ echo 0 > /dev/chipsee-gpio1    // set OUT1 low
```

- **Get** *IN1* **value**

```
$ cat /dev/chipsee-gpio5    // value 1 indicate high, value 0 indicate low
```

- **Use libgpiod to control the GPIO**

```
# comment out the following lines in /opt/chipsee/chipsee-init.sh first
## GPIO
#num=1
#for i in $OUT; do
#[ ! -d /sys/class/gpio/gpio$i ] && echo $i > /sys/class/gpio/export
#echo out > /sys/class/gpio/gpio$i/direction
#chmod a+w /sys/class/gpio/gpio$i/value
#ln -sf /sys/class/gpio/gpio$i/value /dev/chipsee-gpio$num
#num=`expr $num + 1`
```

```
#done
#sleep 1
#for i in $IN; do
#[ ! -d /sys/class/gpio/gpio$i ] && echo $i > /sys/class/gpio/export
#echo in > /sys/class/gpio/gpio$i/direction
#chmod a+r /sys/class/gpio/gpio$i/value
#ln -sf /sys/class/gpio/gpio$i/value /dev/chipsee-gpio$num
#num=`expr $num + 1`
#done

# reboot to use libgpiod
$ sudo reboot

# install gpiod
$ sudo apt-get install libgpiod-dev gpiod

# compile test file
$ wget -c https://chipsee-tmp.s3.amazonaws.com/SourcesArchives/
HARDWARETEST/gpiotest.c
$ gcc gpiotest.c -o gpiotest -lgpiod
$ ./gpiotest
```

Relay

There is one Relay on CS12800RA4101A. For a detailed port definition, please refer to the table below.

Ports	Name	Node	Protocol
8	Relay_NO	GPIO17	Normal Open
9	Relay_COM	GPIO17	GND
10	Relay_NC	GPIO17	Normal Close

Table 482 CS12800RA4101A Relay on P10

- **Initialize** *GPIO17* **to output**

```
$ echo 17 > /sys/class/gpio/export

$ echo out > /sys/class/gpio/gpio17/direction
```

- **Enable Relay NO short-circuit Relay COM**

```
$ echo 1 > /sys/class/gpio/gpio17/value
```

- **Enable Relay NC short-circuit Relay COM**

```
$ echo 0 > /sys/class/gpio/gpio17/value
```

BUZZER

The Chipsee Raspberry Pi boards have one buzzer. We have created one symbol link to */dev/buzzer* . You can control it as follows:

```
$ echo 1 > /dev/buzzer    //enable buzzer

$ echo 0 > /dev/buzzer    // disable buzzer
```

Backlight

We use one PWM to control the backlight for Chipsee Raspberry Pi boards, You can use follow commands to control the backlight.

- **Get the supported max brightness:**

```
$ cat  /sys/class/backlight/pwm-backlight/max_brightness
```

- **Set brightness:**

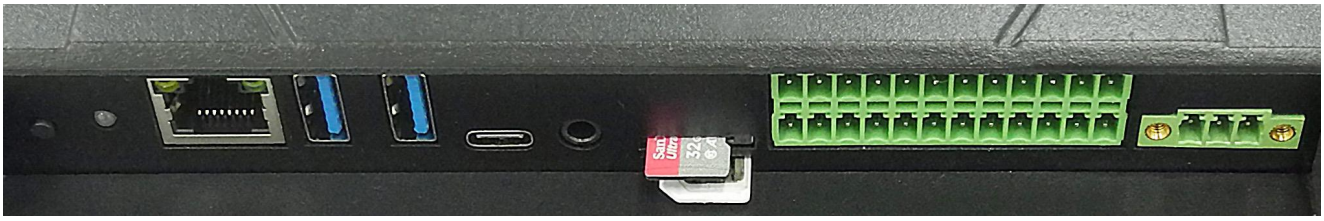
```
$ echo 50 > /sys/class/backlight/pwm-backlight/brightness
```

4G

Note

SIM card does **NOT** support hot plug. **Power off** before inserting/removing SIM card.

SIM Card Direction (7 inch product)



SIM Card Direction (10 inch and above products)

- **You can use 4G on Chipsee Raspberry Pi products. If the 4G module is Quectel EC20, you can use linux-ppp-scripts to connect to internet.**

```
$ sudo apt update
$ sudo apt install ppp
$ sudo ifconfig wwan0 down
$ cd linux-ppp-scripts/
$ sudo ./quectel-pppd.sh <Serial Port> <APN> <username> <password>

For example,
$ sudo ./quectel-pppd.sh /dev/ttyUSB3 3gnet test test

or no username and password
$ sudo ./quectel-pppd.sh /dev/ttyUSB3 3gnet

disconnect 4g
$ cd linux-ppp-scripts/
$ ./quectel-ppp-kill
```

- **If you use EC20 with GPS function, you can enable and get data in the following way.**
  Open one terminal to catch data:

```
cat /dev/ttyUSB1
```

- **Open another terminal to config and enable:**

```
$ microcom –s 9600 /dev/ttyUSB2
AT+QGPSCFG="gpsnmeatype",31 # Turn on all output type, GGA/RMC/GSV/GSA/
VTG, this setting will be saved to NVRAM, persists after reboot
AT+QGPS=1 // enable GPS, wait some minutes, you can get date from fist
terminal.
AT+QGPSEND // disable GPS
```

- Don’t forget to use one GPS ANT.

CAN Bus

There is one channel CAN bus on **CS12800RA101/CS10600RA4070/CS12800RA4101P**. You can install *can-utils* and use them to test CAN. But you must add one 120Ω resistor between CAN_H and CAN_L on one of the two Boards, as shown on the figure below.

> **Note**
>
> The Chipsee IPC does not mount the 120Ω matched resistor on all CAN signals by default.

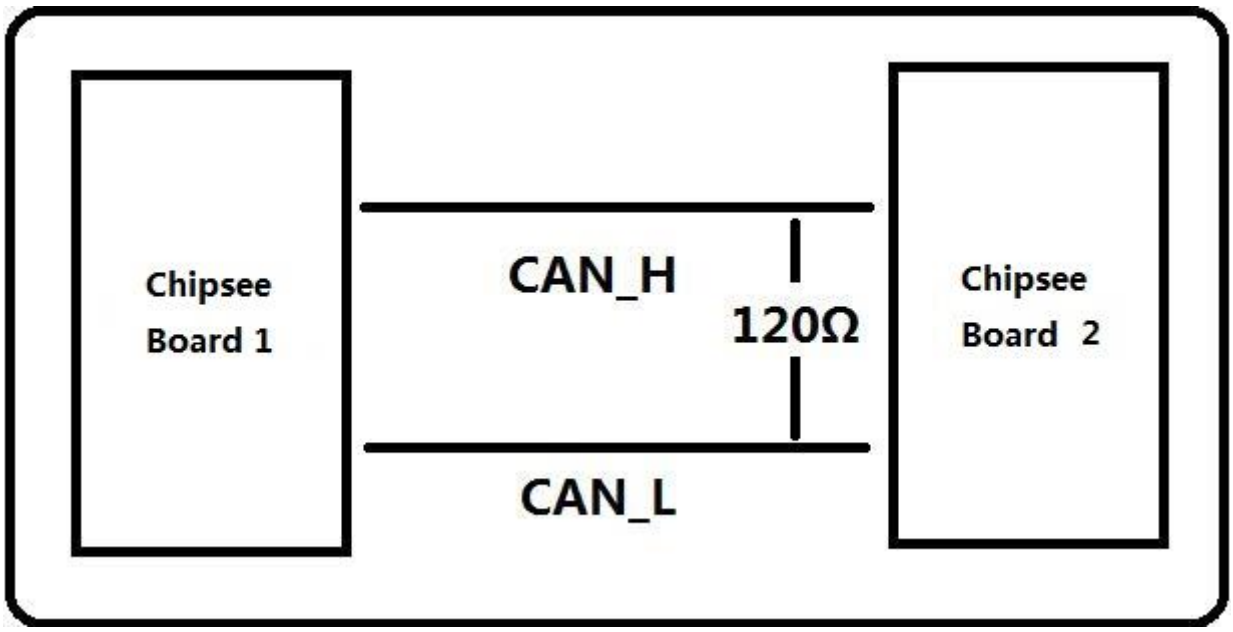


Figure 1064: Connecting CAN

Here are a few examples to test CAN by using CAN units

- **Install** *can-utils*

```
$ sudo apt install can-utils
```

- **Set the bit-rate to 50Kbits/sec with triple sampling using the following command (use ROOT user):**

```
$ sudo ip link set can0 type can bitrate 50000 triple-sampling on
```

- **Bring up the device using the command:**

```
$ sudo ip link set can0 up
```

- **Transfer packets**
  - Transmit 8 bytes with standard packet id number as 0x10

```
$ sudo cansend can0 -i 0x10 0x11 0x22 0x33 0x44 0x55 0x66 0x77 0x88
```

  - Transmit 8 bytes with extended packet id number as 0x800

```
$ sudo cansend can0 -i 0x800 0x11 0x22 0x33 0x44 0x55 0x66 0x77 0x88 - e
```

  - Transmit 20 8 bytes with extended packet id number as 0xFFFFF

```
$ sudo cansend can0 -i 0xFFFFF 0x11 0x22 0x33 0x44 0x55 0x66 0x77 0x88 -e
--loop=20
```

  - For the latest system, we use the following commands

```
$ sudo cansend can0 5A1#11.2233.44556677.88
$ sudo cansend can0 1F334455#1122334455667788
```

- **Receive data from CAN bus**

```
$ sudo candump can0
```

- **Bring down the device**

```
$ sudo ip link set can0 down
```

Wi-Fi

The Chipsee Raspberry Pi boards support *RTL8723BU/RTL8723DU* chip Wi-Fi. The **CS10600RA070/CS12800RA101** have an onboard *RTL8723BU* Wi-Fi chip. The **CS10600RA4070/CS12800RA4101A/CS12800RA4101P** have no onboard Wi-Fi by default so you can use the USB Wi-Fi dongle to enable the Wi-Fi.

Zigbee

The **CS10600RA4070/CS12800RA4101A/CS12800RA4101P** boards have an onboard ZigBee chip *CC2531*. Its device node in the system is */dev/ttyACM0* . We use *zigbee2mqtt* project firmware by default. Check the following link to learn more about this project: Zigbee2mqtt

> **Note**
>
> The Zigbee module is not mounted by default.

Camera

The camera port CAM is compatible with Raspberry pi. Please refer to the following link to learn how to attach a camera: https://www.raspberrypi.org/documentation/hardware/computemodule/cmio-camera.md

Chipsee-init shell

We use one **chipsee-init.sh** as an initial shell which is placed in */opt/chipsee/chipsee-init.sh* .
We initialize the GPIO/Buzzer and other configs in it. If you want to change it, please be careful.
Do a backup first before you modify anything. This script will generaged one log file which located on /var/log/chipsee-init.sh.log. If your device has booting issues, you can send Chipsee® the file to help you find out what happened.

FAQ

How to Rotate the Touch

Display can be rotated from the GUI, but the touch layer needs to be rotated manually.

```
$ sudo vi /usr/share/X11/xorg.conf.d/40-libinput.conf
# inside 40-libinput.conf
# Move to the Section of "Identifier .... touchscreen ...."
# Add this line inside the Section/EndSection:
Option "TransformationMatrix" "0 1 0 -1 0 1 0 0 1"
```

Then the touch will be rotated permanently after reboot. You can also undo this line to rotate it back.

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Technical Support

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