Chipsee

Industrial PC

Linux Qt 5.5 OS on iMX6Q User Manual

For iMX6Q Products

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Linux Qt 5.5 OS

Chipsee Linux Qt 5.5 OS User Manual

This manual provides users with a fast guide of Chipsee Industrial Computer (Abbreviate as IPC) about Linux Qt 5.5 OS development. Through this manual, users can quickly understand the hardware resources; users can build a complete compilation of Linux development environment; users can debug Linux Qt 5.5 OS via serial and Internet.

Revision	Date	Author	Description
V1.1	2021-12-30	Randy	Revised
V1.0	2018-05-14	Madi	Initial Version

SUPPORTED BOARDS:

> *CS10600F070 CS10768F097 CS12800F101 CS10768F121 CS10768F121-U CS10768F150 CS12102F170 CS14900F190 CS19108F215*

PREBUILT FILES PACKAGE:

Prebuilt files for the various industrial PCs can be found in the OS Downloads.
Below are the links to the prebuilt files for each industrial PC model.

- CS10600F070
- CS10768F097
- CS12800F101
- CS10768F121
- CS10768F121-U

- CS10768F150
- CS12102F170
- CS14900F190
- CS19108F215

System Features

Feature	Comment
Kernel	Kernel 3.14.52
Bootloader	Uboot 2015.04
System	Linux Qt 5.5
Python	Python 2.7.9
Qt	Qt 5.5.1
Desktop	matchbox
user/password	[root/root]

Preparation

You will need to prepare the following items before you can start using the Prebuilt Files Package to re-flash the system.

Power Supply Unit (PSU) with the appropriate voltages, as follows:

- These products: CS10768F121, CS10768F121-U, CS10768F150, CS12102F170, CS14900F190, and CS19108F215 requires a 15V to 36V power adapter.
- These products: CS10768F097 and CS12800F101 product needs a 12V to 36V power adapter.
- The CS10600F070 product needs a 6V to 36V power adapter.

You need to prepare the Power Adapter by yourself

Hardware Requirements

- Chipsee Industrial PC
- PSU according to the instructions above
- USB-to-serial or other serial cable for debugging
- USB A-A cable (used only if the hardware configured as OTG)
- Windows 7 PC
- Mini-B USB OTG Cable

- TF Card (at least 4GB) and card reader

Software Requirements

- Linux Qt 5.5 OS Prebuilt Files Package (from the link above)
- Xshell or other terminal emulation software
- VNC-Viewer
- Cross-toolchain
- MFGTools
- Useful tools for Qt development

> **Note**
>
> - If you want to re-flash the system, you need the Prebuilt image package.
> - You can use MFGTools on the Windows PC to download system images to the IPC.
> - You can use Xshell or other terminal emulation software to debug Chipsee Industrial PC products in Windows.
> - You can use VNC-Viewer to to remote control Chipsee Industrial PC over Ethernet.
> - The cross-toolchain can compile a program for Chipsee Industrial PC.

> **Note**
>
> In this documentation, all the commands are executed with `root` user privileges.

Debug

In this document, we use Xshell to debug the Chipsee Industrial Computer. You can also use other tools such as Putty, Minicom, SecureCRT or any terminal emulation software.

Serial Debug

You can refer to the RS232/RS485/CAN Connector section under the EPC/PPC-A9-070-C manual to understand the serial ports of the IPC. The debug serial port of Chipsee Industrial Computer is the first RS232 port. You can use it to debug directly, and the default user and password is [root/root]. You can use RS232_1_TXD, RS232_1_RXD, GND.

Follow these steps to perform serial debugging:

- Connect your Windows PC to the Chipsee IPC over a serial cable. Please reference the `How To Connect Board By Serial` manual to connect your PC and Chipsee Industrial Computer over a serial cable.
- **Open XShell and use the session properties as shown on the figure below.**

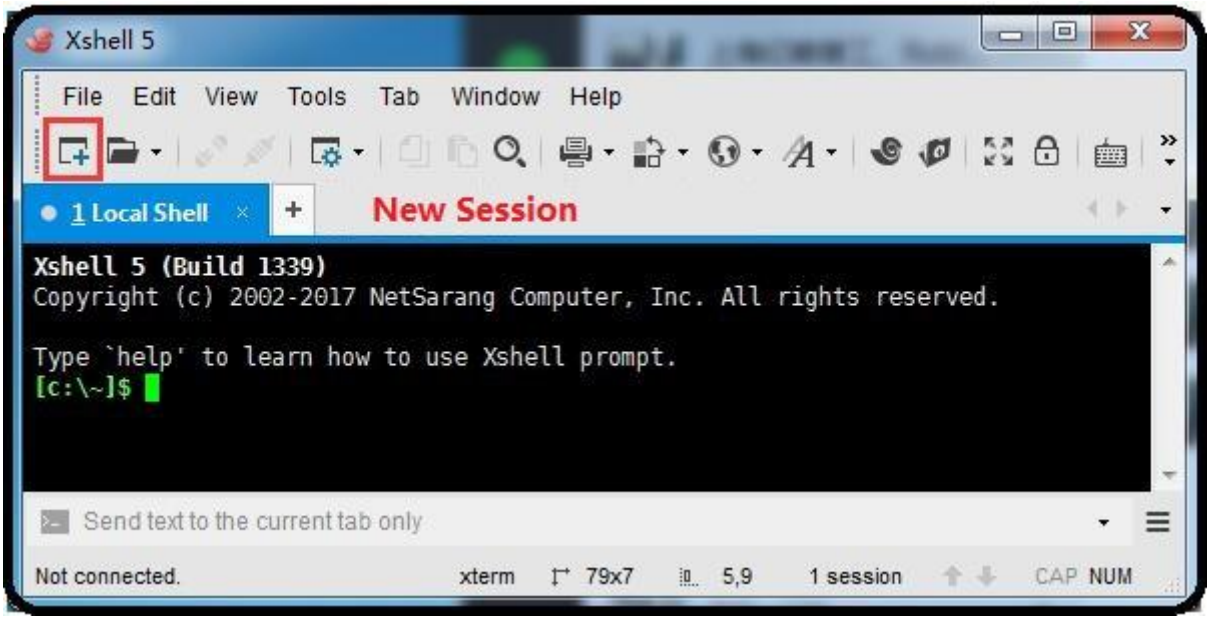


Figure 214: *Add Session*

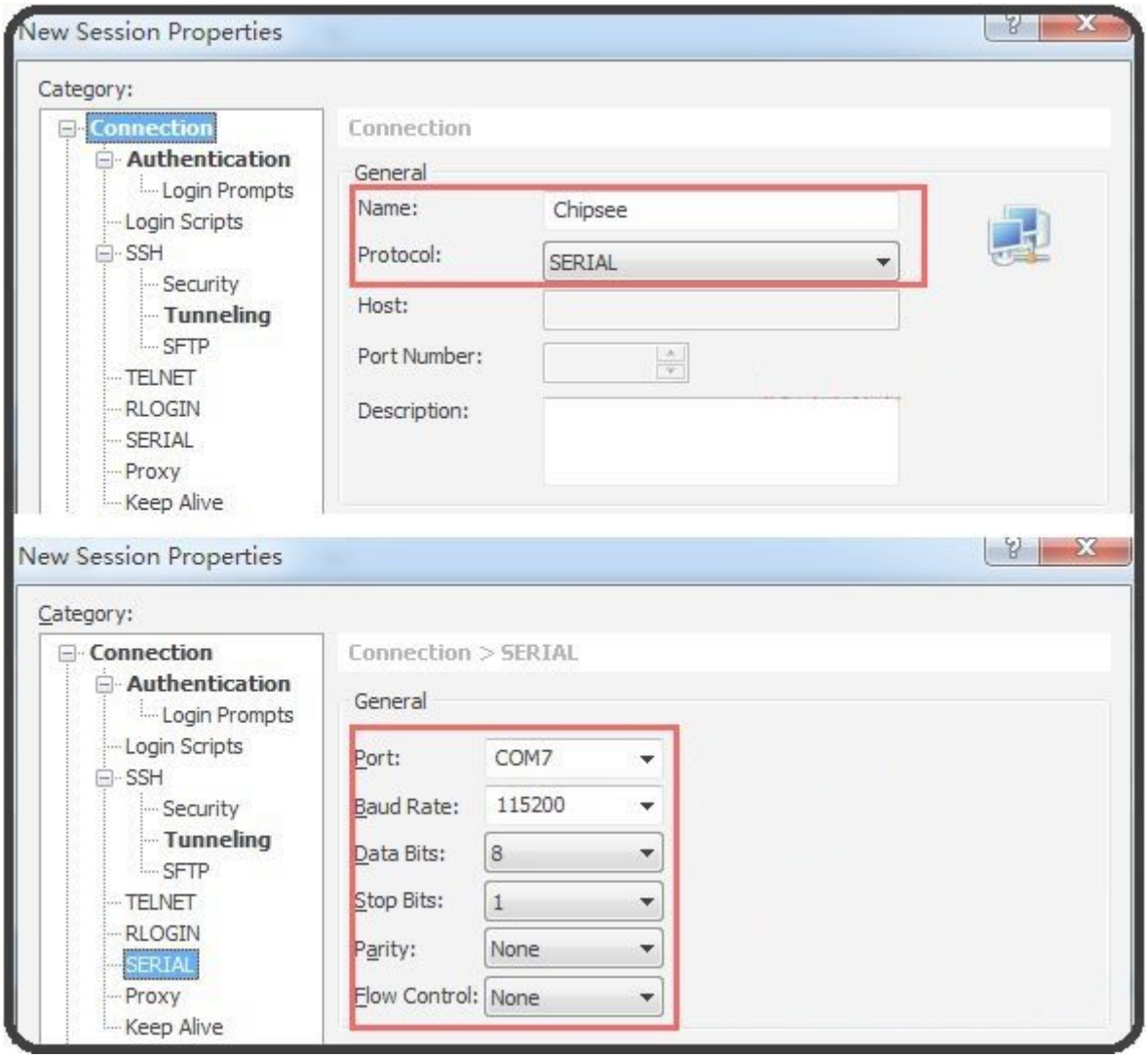


Figure 215: *Session Properties*

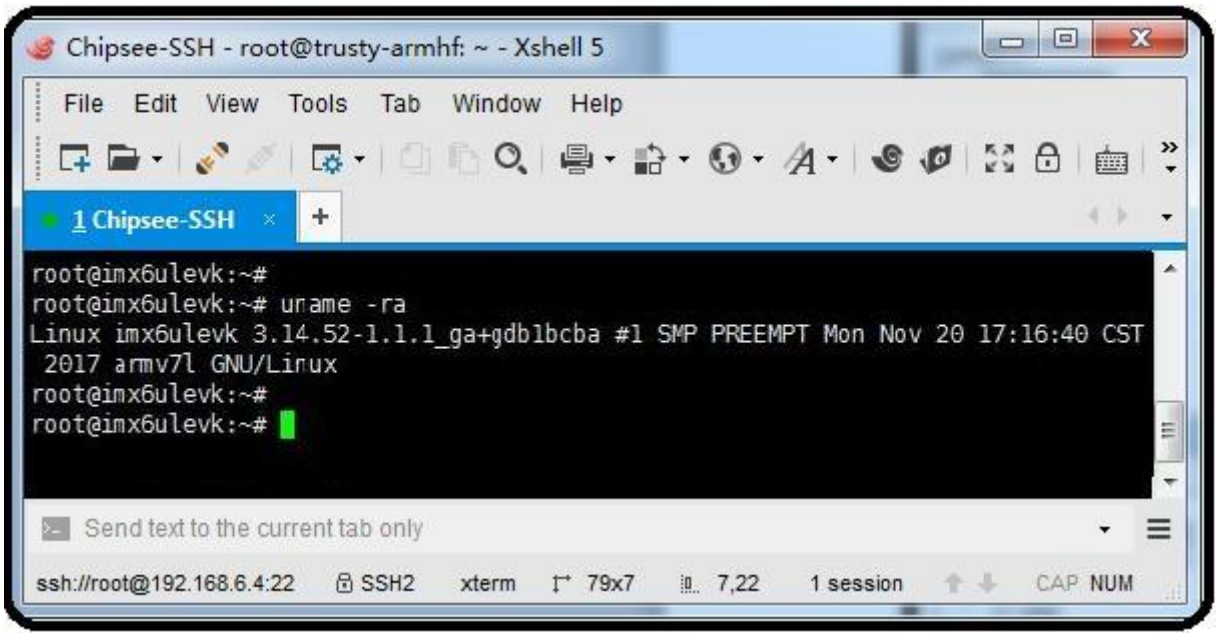


Figure 216: *Serial Debug*

SSH Debug

To perform SSH debugging on the Chipsee IPC, you must first connect the product to the Internet.

Continue the debugging by follow these steps:

- Get the IP address of the Chipsee IPC product.
- You can configure XShell or you can directly use the SSH tool in Linux OS. In this tutorial, we will use the XShell tool to perform SSH debugging.
- **Open XShell and add a new session and set it as shown on the figure below.**

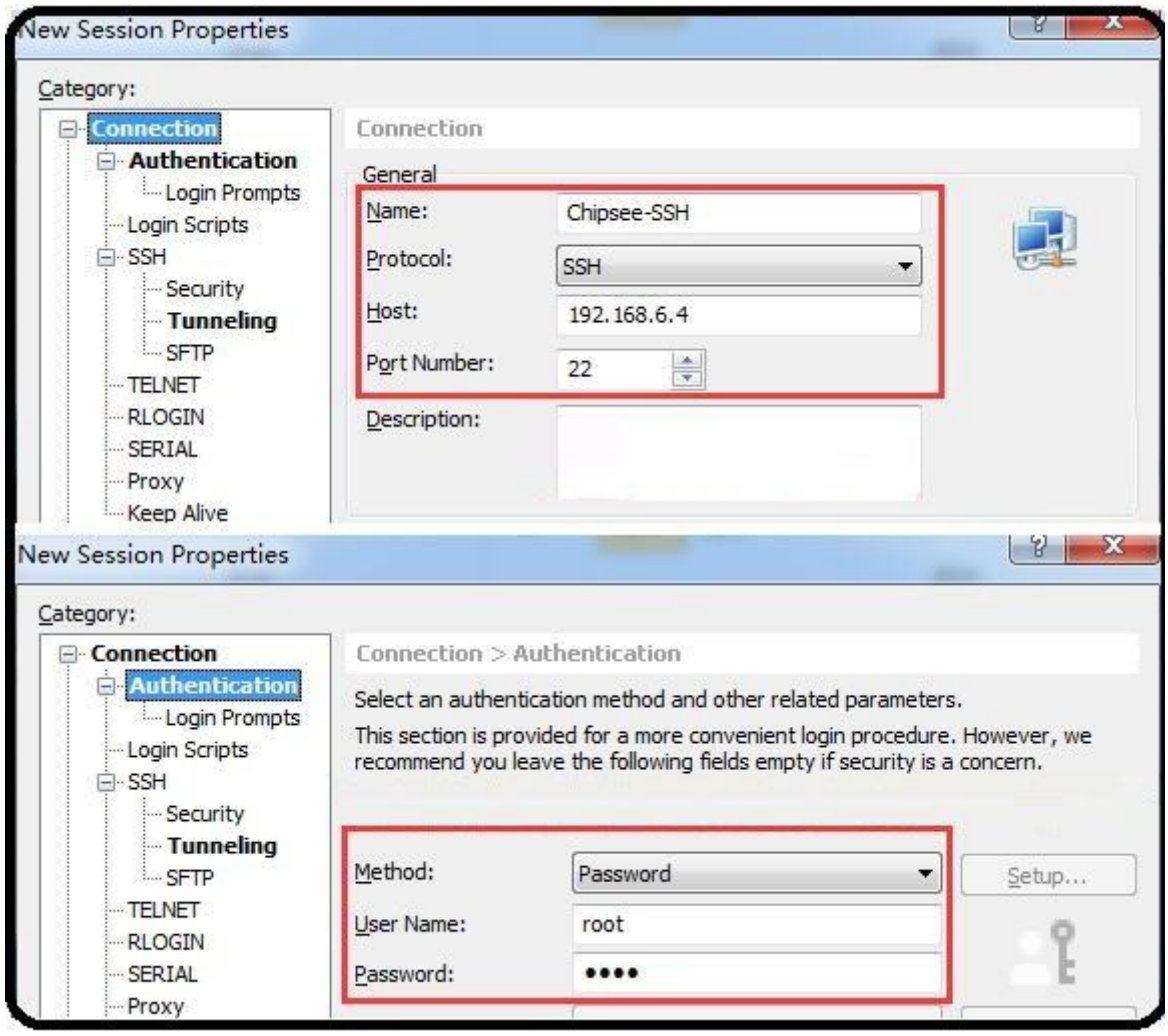


Figure 217: *SSH Setting*

- **Now we can perform SSH debugging using XShell.**

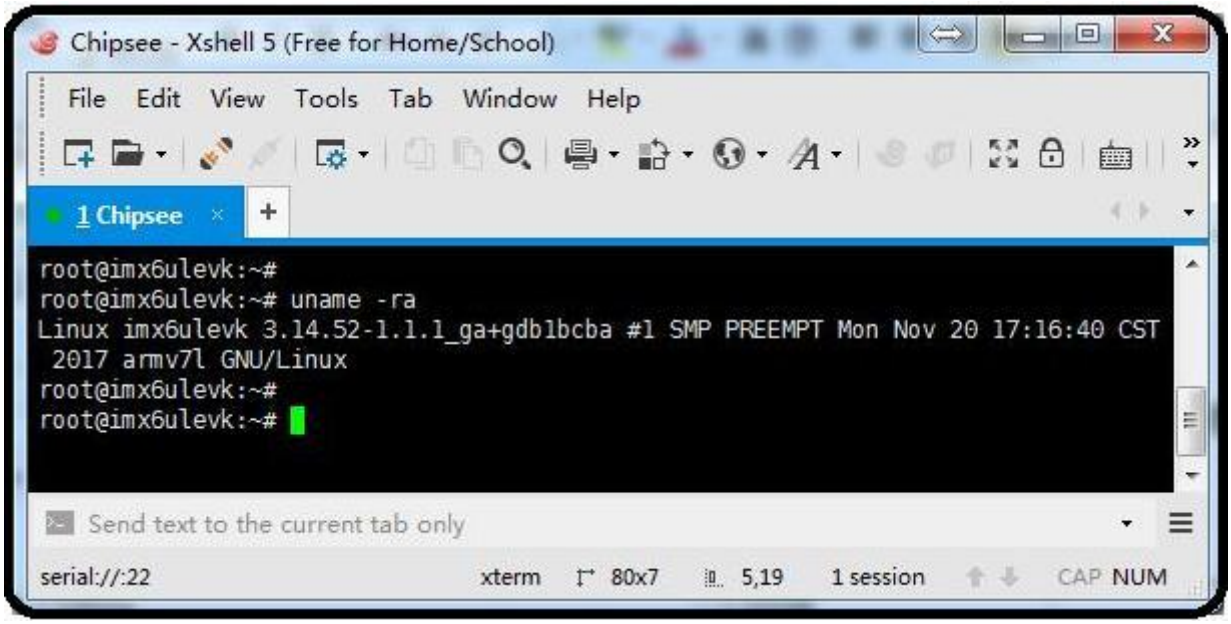


Figure 218: *SSH Debug*

VNC Debug

You can use the VNC-Viewer software in Windows to control Chipsee IPC over Ethernet.

- **Open the VNC-Viewer software as shown on the figure below.**

Figure 219: *VNC Desktop*

- **Click on the X11VNC icon to enable the X11VNC.**

Figure 220: *X11VNC Enable*

- **Use VNC-Viewer in Windows to control it over Ethernet, as shown on the figure below.**

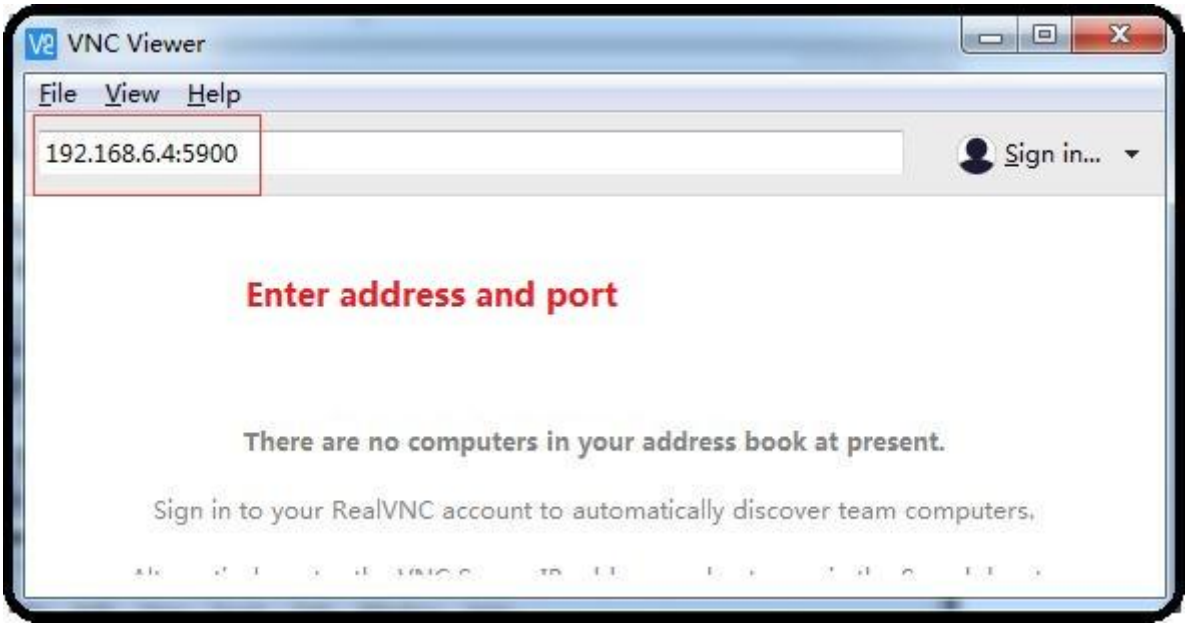


Figure 221: *VNC-Viewer Connect*

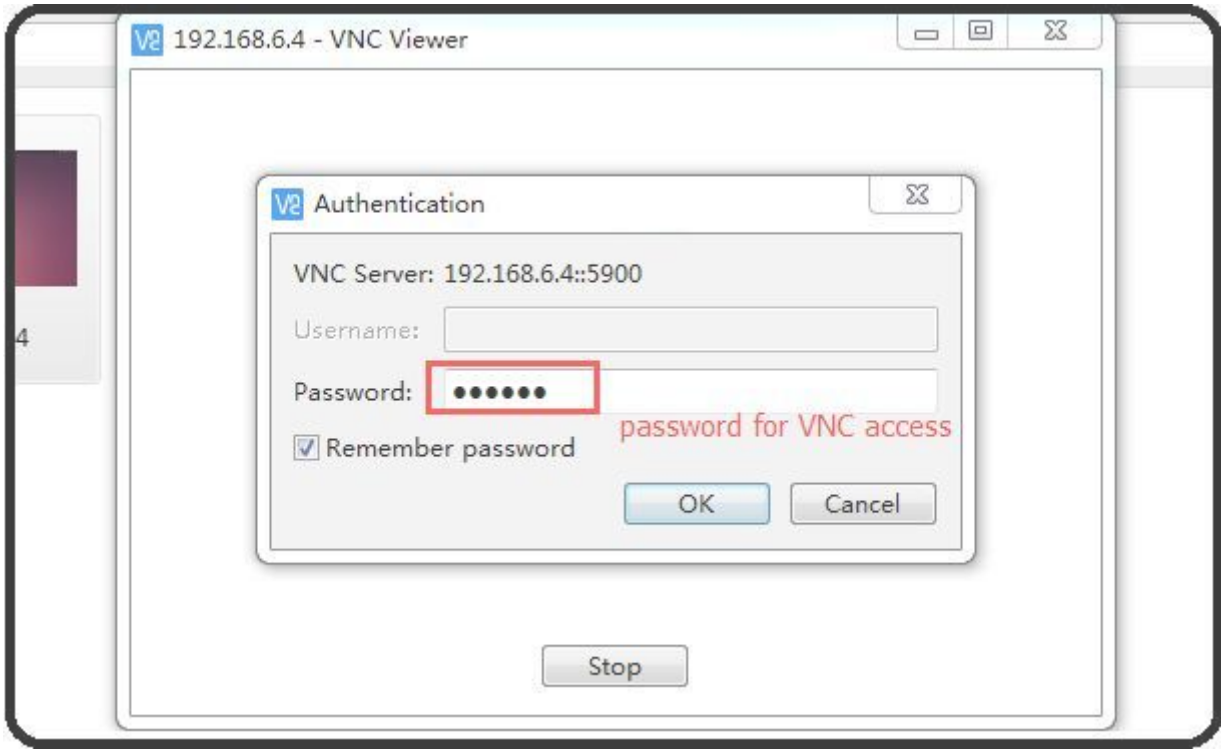


Figure 222: *Authentications*

Downloading images

Boot Switch Configuration

CS-IMX6 has a boot configuration select switch, as shown on the figure below. You can use the boot select switch to change between three modes, namely

- TF Card

- eMMC Boot
- Download

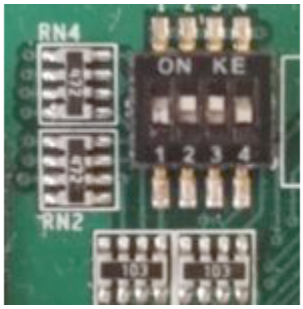


Figure 223: Boot Mode Setup

SW Mode	1	2	3	4
TF Card	1	0	0	0
eMMC	1	1	0	1
Download	0	1	1	0

Table 49 Boot Configuration Selection

Note

The user can use both the pre-built Linux Qt 5.5 image files and the MFGTools software to download new images to the system, boot system and perform necessary software and hardware test.

Prebuilt Files Package

You can get the Prebuilt Files Package for each model from links mentioned at the beginning of this documentation. You can also get the Prebuilt Files Package from the DVD in /Linux Qt 5.5/Prebuilds folder. However, it may be outdated so always compare the versions (the last number in the filename is the release date).

The prebuilt package has the following content:

Contents	Comment
boot/imx6q-eisd.dtb	TF Card boot dtb file
boot/u-boot-sd.imx	TF Card boot bootloader
boot/zImage	TF Card boot kernel file
boot/logo.bmp	TF Card boot logo file
filesystem/rootfs-emmc-flasher.tar.bz2	TF Card boot rootFS
mksdcard.sh	Shell tools to make bootable TF Card
README	Simple guidelines

Contents	Comment
S1.jpg	Boot Switch Config Figure
emmc-flash/emmc/rootfs.tar.bz2	RootFS in target eMMC
emmc-flash/emmc/u-boot-emmc.imx	Bootloader in target eMMC
emmc-flash/emmc/zImage	Kernel file in target eMMC
emmc-flash/emmc/zImage_framebuffer	Kernel file with frame-buffer
emmc-flash/emmc/imx6q-eisd.dtb	Dtb file in target eMMC
emmc-flash/emmc/imx6q-eisd.dtb_framebuffer	Dtb file with frame-buffer
emmc-flash/emmc/logo.bmp	Logo file in eMMC
emmc-flash/mkemmc.sh	Shell tool to download images to eMMC

Table 50 Prebuilt Files Package

Note

- The default `zImage` and `imx6q-sabresd.dtb` files support *'keep the logo from uboot to kernel'* but don't support framebuffer.
- We also provide `zImage_framebuffer` and `imx6q-eisd.dtb_framebuffer` file versions that support the framebuffer function but do not support the *'keep the logo from uboot kernel'* feature. If you need the framebufer, just rename these two files to `zImage` and `imx6q-eisd.dtb`.

Downloading Images by using MFGTool

The MFGTools can be used to download images into a target device. It is a quick and easy tool for downloading images.

Note

The operator should use the prebuilt file we provided in the CD to test the hardware before re-flashing the system.

Before downloading images with the MFGTools, set the boot switch to download mode. (refer to Boot Switch Configuration above)

Configuring MFGTool

To configure MFGTool, follow these steps:

- Untar `Mfgtools-K31452-Vx.x.tar.gz` file.
- Open the extracted folder `Mfgtools-K31452-Vx.x` and edit `cfg.ini` file.
- In the `cfg.ini` file, ensure the `name` and `display` variables are set to `eMMC-Linux` and `1024600` respectively, as shown on the figure below.

Figure 224: *Cfg.ini file*

Note

You can get the supported display from *Mfgtools-K31452-V1.0\Profiles\Linux\OS Firmware\firmware* directory. Modify config `UICfg.ini` file. This file has only one line: `PortMgrDlg=1` that indicates you can download the images to one board at the same time. The max value is 4.

COPY IMAGE TO ANDROID DIRECTORY

Follow these steps to copy image to Linux directory:

- Copy the images from *prebuilt-xxx/emmc-flash/emmc/* to *Mfgtools-K31452-V1.0\Profiles\Linux\OS Firmware\files\linux* directory.

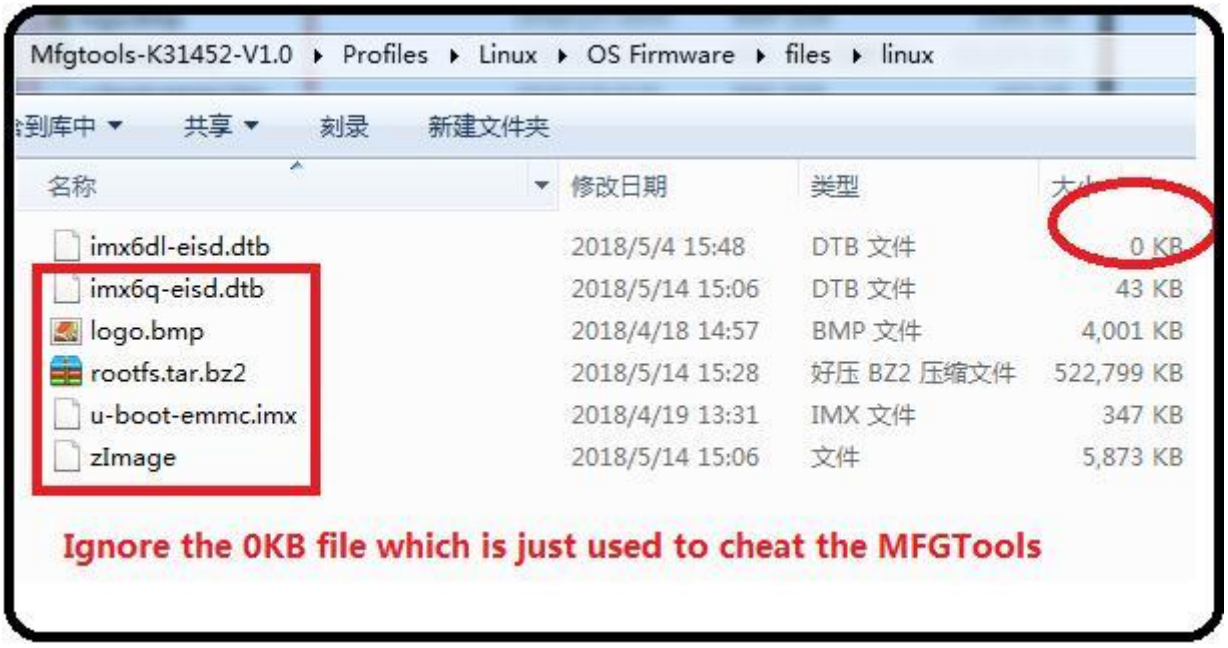


Figure 225: *Prepare Images*

USING MFGTOOL

1. Connect a USB OTG cable from a Windows PC to the USB OTG port on the IPC.
2. **Change the boot select configuration to 0 1 1 0, as shown on the figure below.**

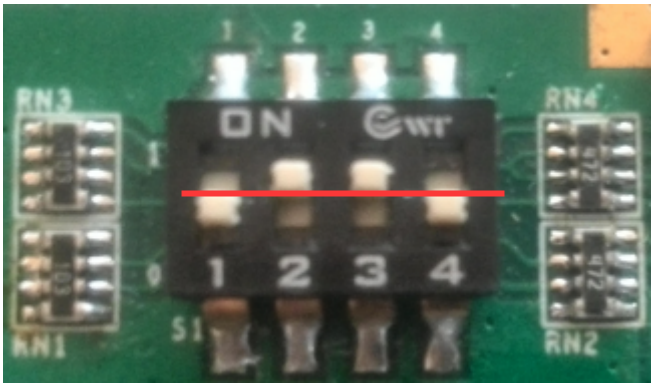


Figure 226: *Boot Switch Config*

3. Connect a 12V-2A power adapter to the IPC and power ON.
4. **On your Windows PC, open the `Mfgtools-Rel-XXX_XXXXXX_MX6Q_UPDATER_VXX` directory and run the `MfgTool2.exe` file, as shown on the figure below.**

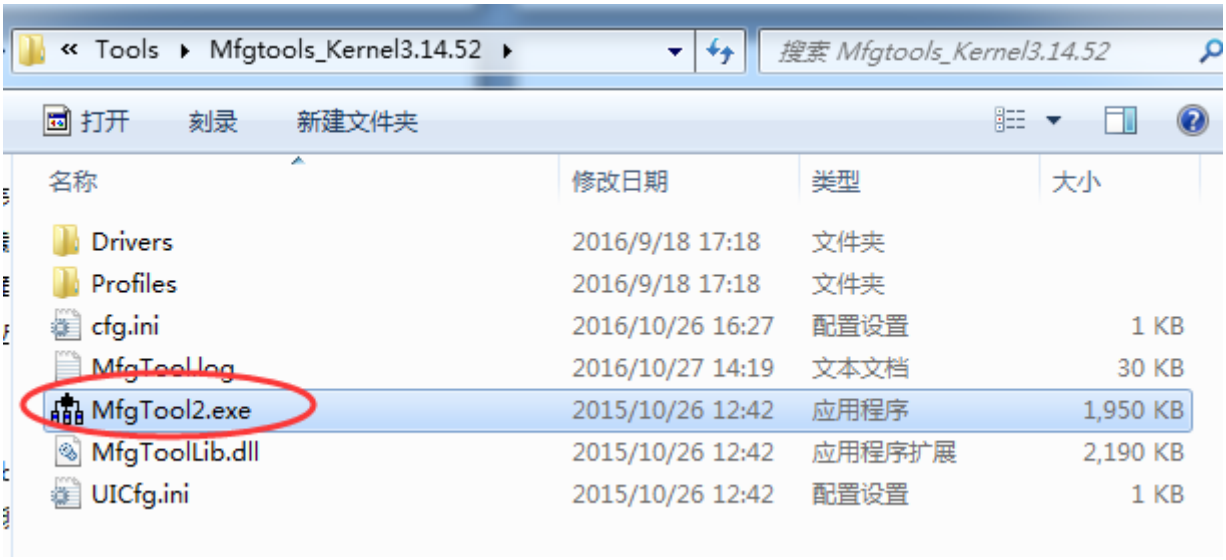


Figure 227: *Run* **MfgTools2.exe** *file*

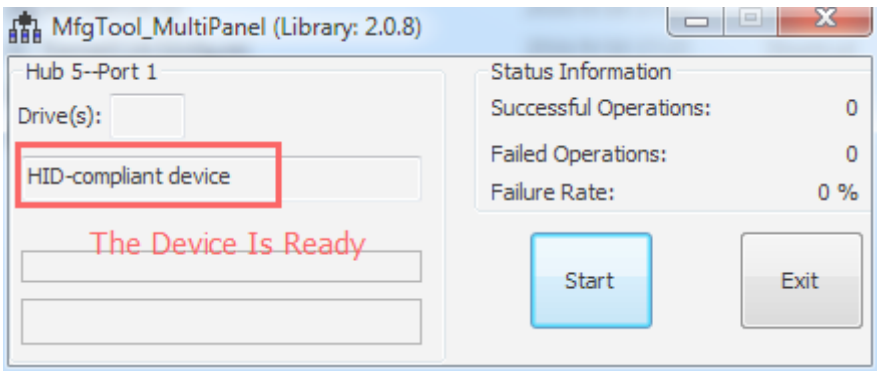


Figure 228: *Prepare to start*

Note

If you get a message saying *No Device Connected*, check the USB-OTG cable to ensure it is ready.

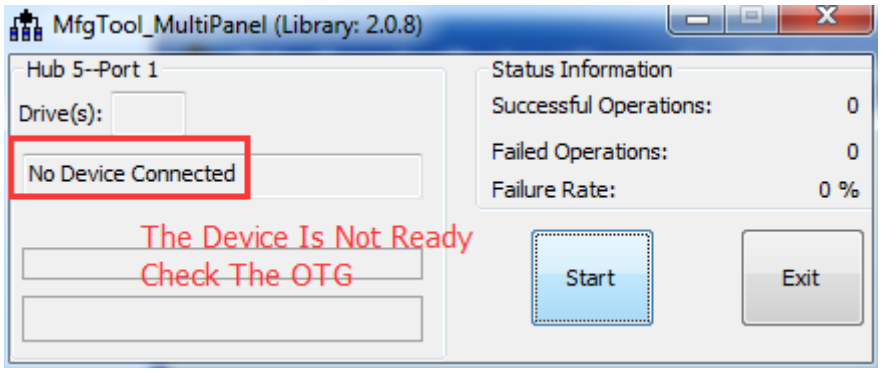


Figure 229: *The USB-OTG cable is not connected correctly.*

5. **Click on Start button to download the Image.**

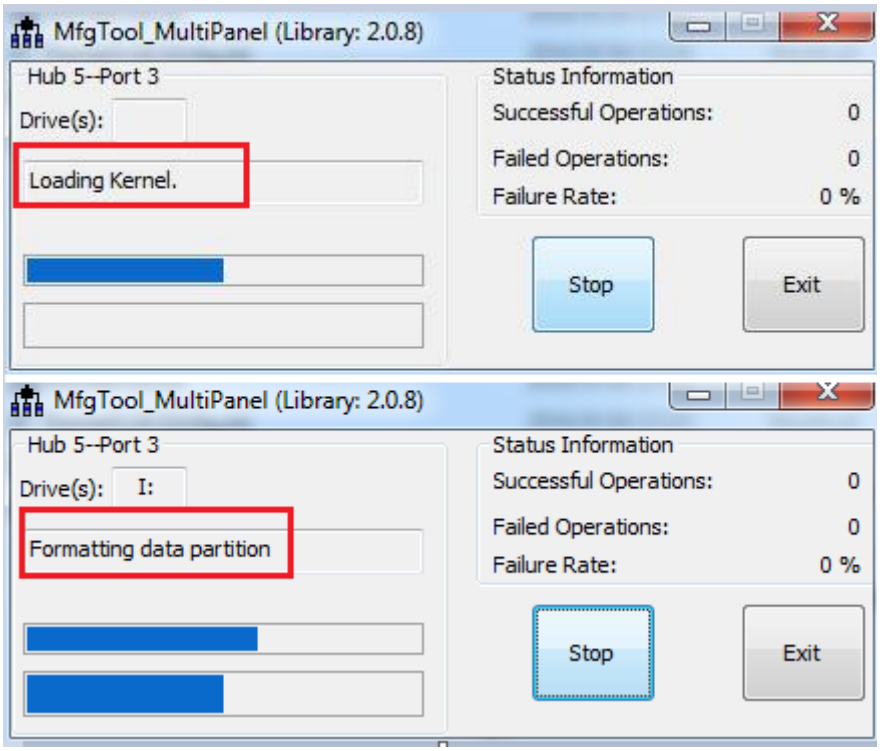


Figure 230: *Downloading Images*

Note

If you are using a Window 7 PC, you will receive a prompt that asks you to format the disk. Please ignore or cancel it.

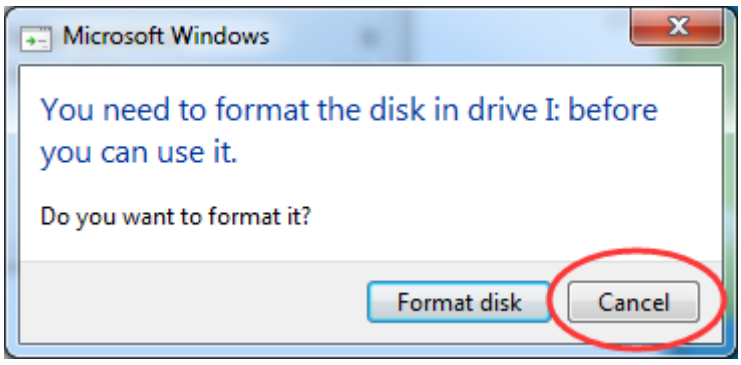


Figure 231: *Cancel format disk*

6. **When the process is complete, you click the Stop button to stop downloading Image and exit.**

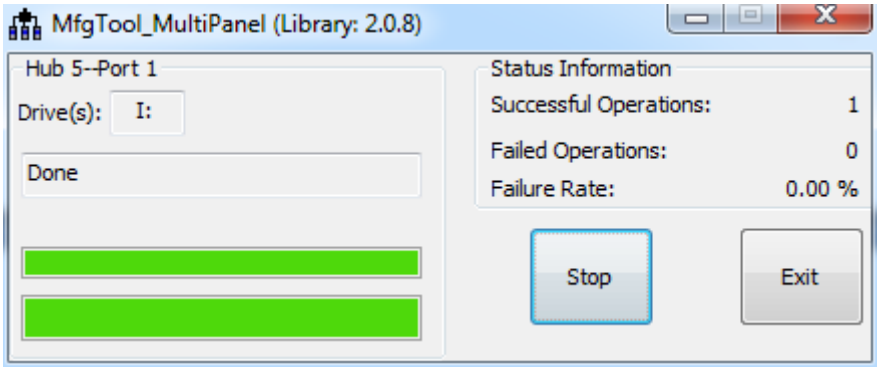


Figure 232: *Download Image is finished*

Downloading Images by using the TF card

Follow the steps below to download images onto the eMMC by using the TF Card:

1. Copy the Prebuilt Files Package to a Linux environment (such as Ubuntu 14.04).
2. Insert the SD card into your computer. If you are using virtual machines, please ensure the SD card is mounted to the Linux operating system.
3. **Confirm the SD card mount point, `/dev/sdX` (e.g., `/dev/sdc` or `/dev/sdb`, be sure to use the right one). In a Linux system, you can use the command below to find out what *X* is.**

```
$ sudo fdisk –l
```

4. Copy the `prebuilt-imxv1-csXXXXXfXXXvX-android6-emmc-YYYYMMDD.tar.gz` to somewhere(such as $HOME) on the Ubuntu PC.
5. **Extract the `prebuilt-imxv1-csXXXXXfXXXvX-android6-emmc-YYYYMMDD.tar.gz`**

```
$ tar -xzvf prebuilt-imxv1-csXXXXXfXXXvX-android6-emmc-YYYYMMDD.tar.gz
```

6. **Go to the folder**

```
$ cd prebuilt-imxv1-csXXXXXfXXXvX-android6-emmc-YYYYMMDD
```

7. **Use the following command to flash the Linux Qt 5.5 OS to the SD card**

```
$ sudo ./mksdcard.sh --device /dev/sd<?>
```

> **Note**
>
> • sd<?> means the SD card mount point, (e.g., `/dev/sdc` or `/dev/sdb`) in Ubuntu system.
>
> • The recommended SD card should be Sandisk Class4 level SD card or above.

8. The bootable SD Card is now ready. Power OFF the industrial PC and insert the SD Card.
9. Set the switch S1 to TF card boot mode. (refer to Boot Switch Configuration above)
10. Connect the industrial PC to PC via COM1. Power ON the IPC.
11. After 20 minutes, if the LED on industrial PC stays lit, flashing is completed. Using COM1, you can also find this message **>>>>>>> eMMC Flashing Completed <<<<<<<** which indicates that the system image was downloaded correctly to the eMMC.
12. Power OFF and set the switch S1 to eMMC boot mode. (refer to Boot Switch Configuration above)

System Resource

TF Card/USB/SATA Disk

The TF Card and USB Storage supports hot-plug but the SATA Disk does not support hot-plug. These devices will be automatically mounted on */run/media/mmcblk0P** , as shown in the figure.

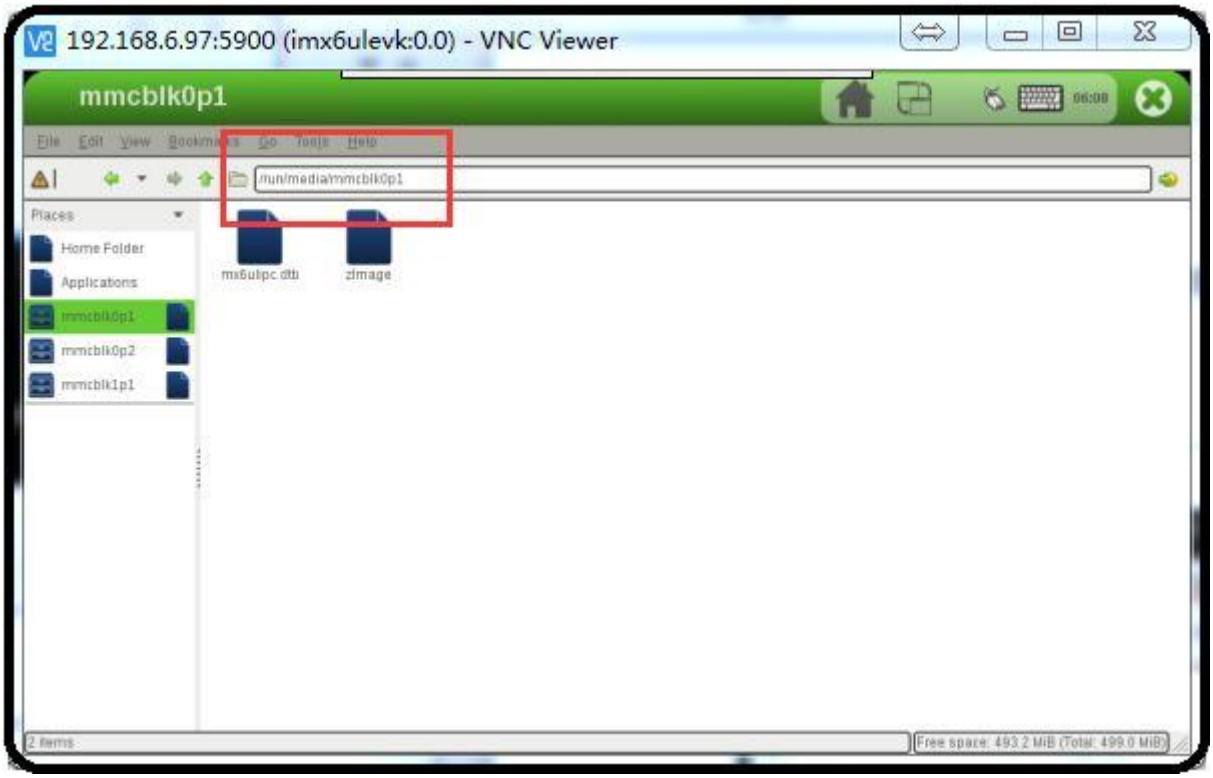


Figure 233: *TF Card*

> **Note**
>
> The TF card and USB Storage do not support NTFS format. Please format it to FAT32 first before plugging into IPC.

Network

This system uses a networking service to control Ethernet and uses `wpa_supplicant` to control the WIFI network.

Wired Ethernet

You can get the IP address from the following application, as shown on the figure below.

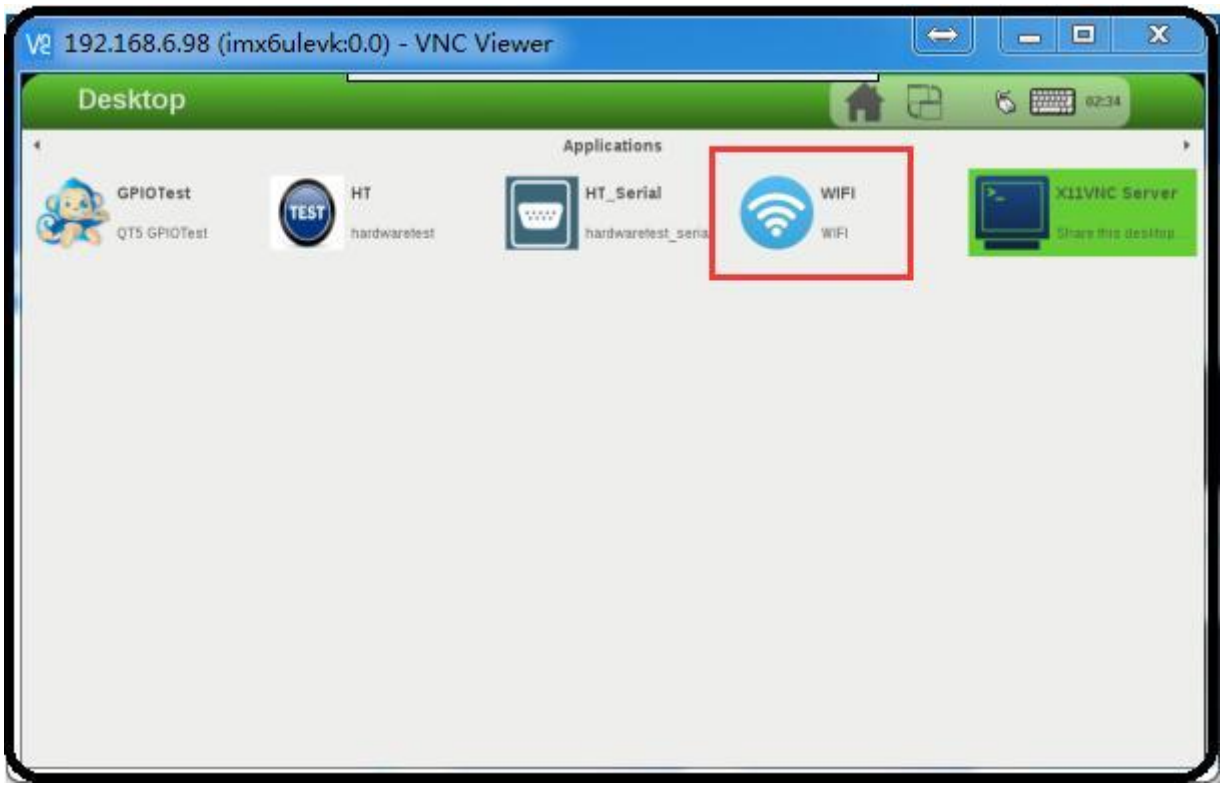


Figure 234: *Wired Connection*

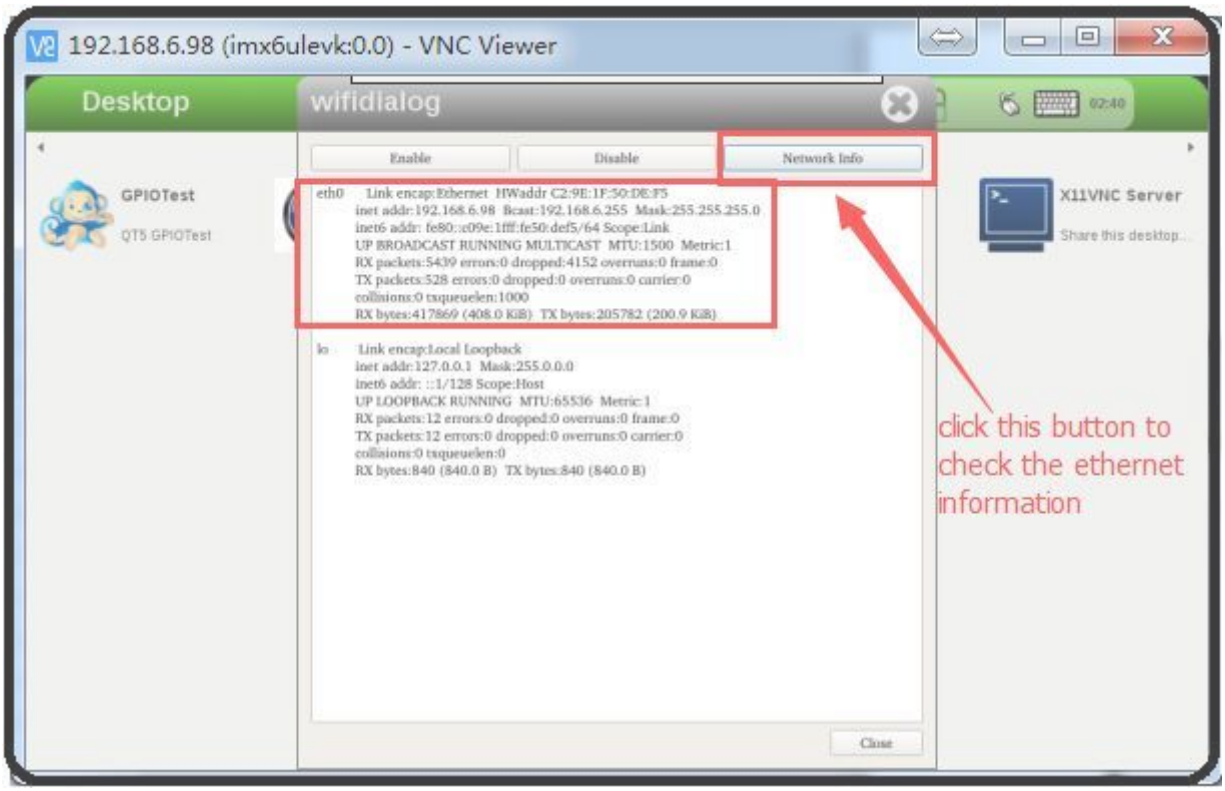


Figure 235: *Ethernet Information*

Wi-Fi

You can configure the Wi-Fi using these methods:

- Config Wi-Fi by GUI
- Config Wi-Fi by Command

Config Wi-Fi by GUI

- Click the **terminal** on the desktop
- Use the following command to generate network config information.

```
# wpa_passphrase "Chipsee" "1chipsee234567890"
```

- Replace the information in */etc/wpa_supplicant.conf* by setting the `ssid=Chipsee` and `psk=1chipsee234567890`, as shown on the figure below.

Figure 236: *Wi-Fi Config File*

- Open the **Wi-Fi** icon on the desktop, then click the **Enable** button. Wait for some time to get the Wi-Fi working. The Wi-Fi is working when the network tab displays the *WIFI Enabled!* message, as shown on the figure below.

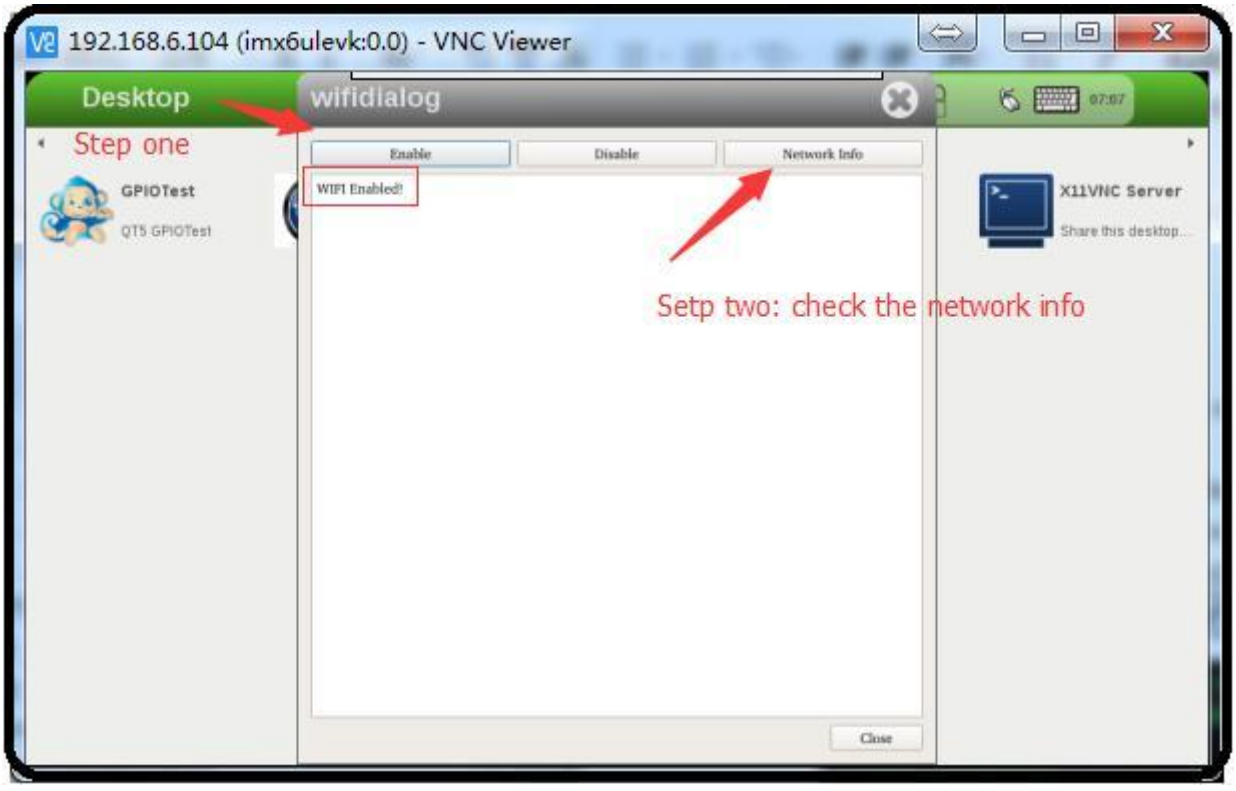


Figure 237: *Wi-Fi Enable*

Config Wi-Fi by Command

- Use the command below to enable Wi-Fi.

```
# wifienable.sh
```

- List available network and remove default if exist using these commands

```
# wpa_cli list_network
# wpa_cli remove_network
# wpa_cli scan
# wpa_cli scan_result // get latest scan results
# wpa_cli ap_scan 1
```

- Add a new network and list added network using these commands

```
# wpa_cli add_network
# wpa_cli list_network
```

- Set SSID, Password, and key management using these commands

```
# wpa_cli set_network 0 ssid "Chipsee"
# wpa_cli set_network 0 key_mgmt WPA-PSK
# wpa_cli set_network 0 psk "1chipsee234567890"
```

- Enable the `network 0` with this command

```
# wpa_cli select_network 0
```

- Save config

```
# wpa_cli save_config
```

- Re-enable Wi-Fi

```
# wifienable.sh
```

Multimedia

This system supports NXP Gstreamer-imx Multimedia library and its various plugins.

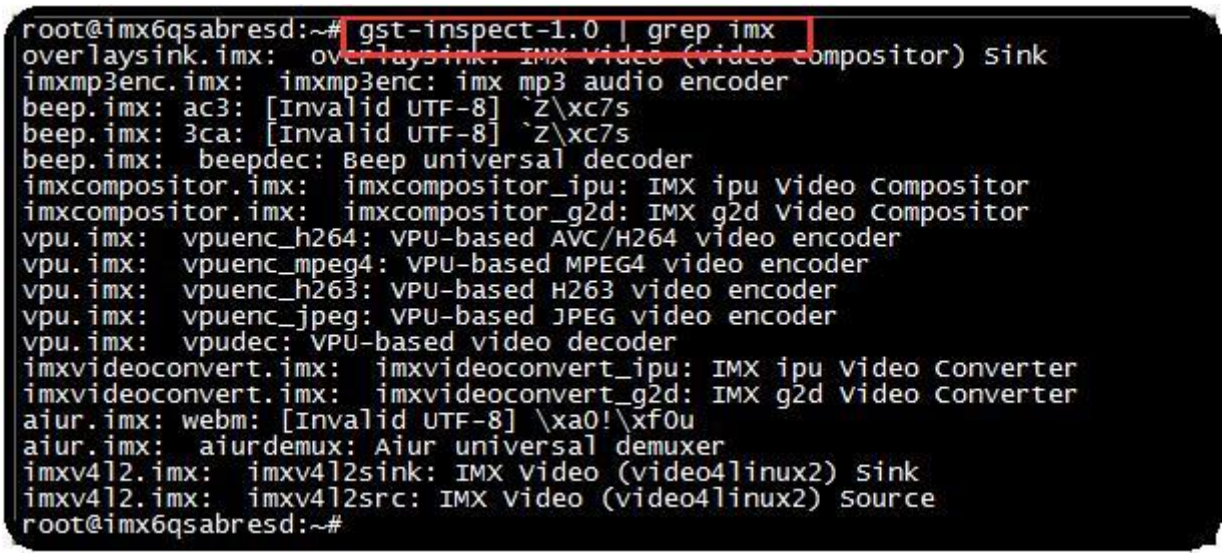


Figure 238: *GStreamer Plugins*

Audio Test

You can use the command below to record music. The `-d` parameter means *interrupt after # seconds*. In this example, `-d` is equal to 18 seconds.

```
$ sudo arecord -N -M -r 44100 -f S16_LE -c 2 -d 18 test.wav
```

You can use the command below to playback the recorded sound above.

```
$ sudo aplay -N -M test.wav
```

You can also use the **QT Test Application** to record and playback audio.

On the **QT Test Application** desktop, click on the **HT** button to perform a hardware test, as shown on the figure below.

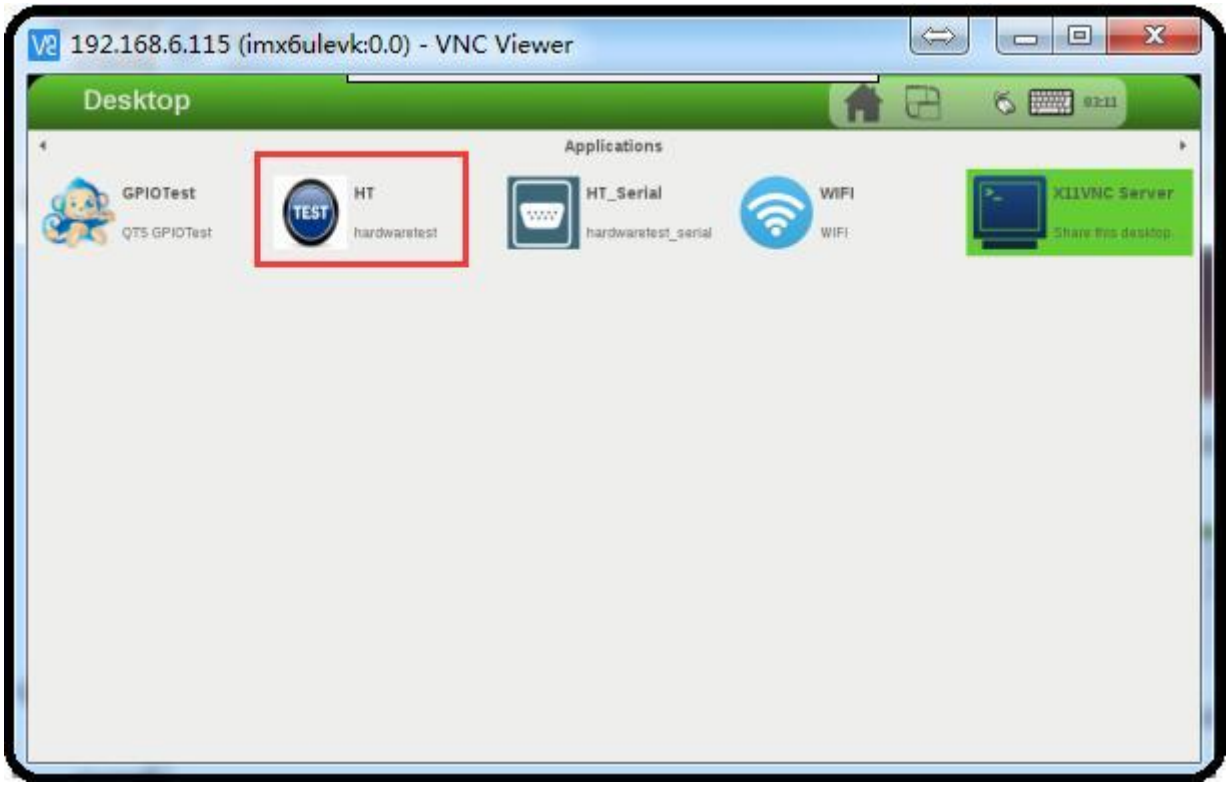


Figure 239: *Hardware Test*

You can click the **Audio** button to playback audio. You can also click the **Record** button to record 18 seconds of audio then the application will playback the audio automatically.

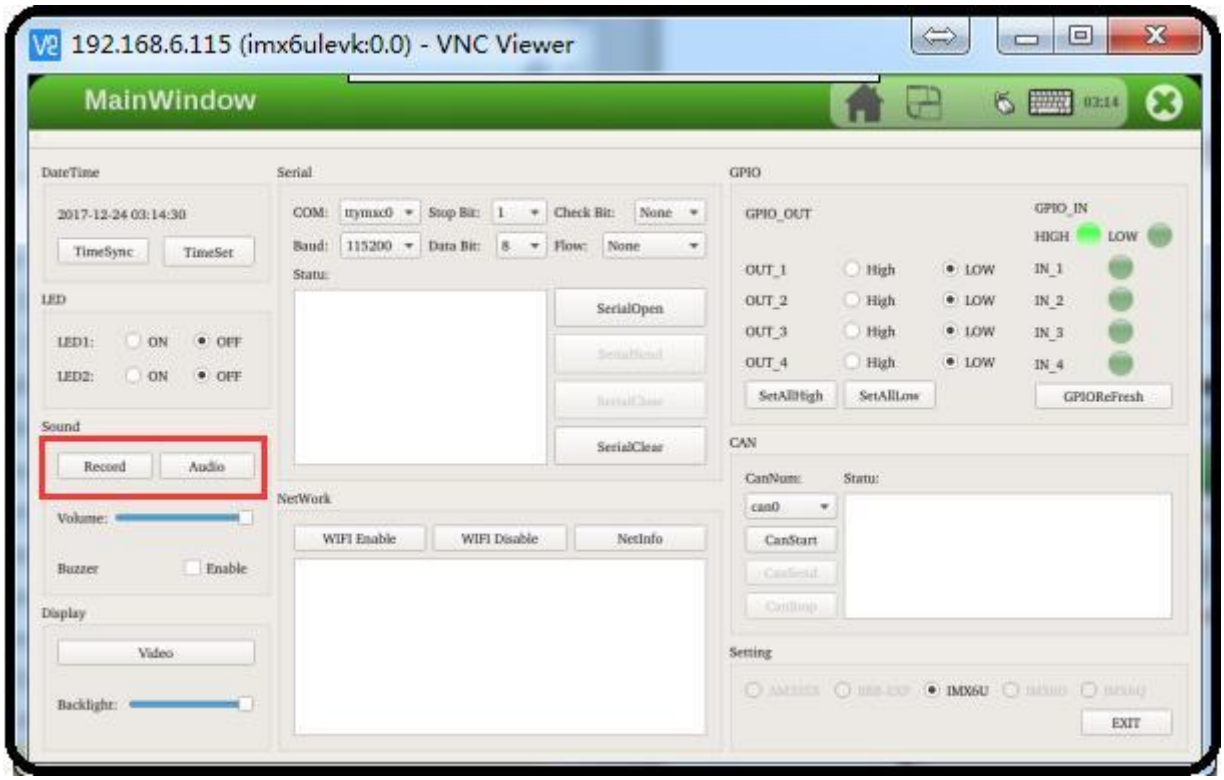


Figure 240: *Audio Test*

HDMI

You can follow the steps below to display the IPC output onto an external display via HDMI.

- Power OFF IPC. Connect the external display to the IPC using an HDMI cable.
- Refer to the Serial Debug section to set serial debug.
- **Power ON IPC. In XShell, hit any key to stop auto boot and input the uboot command mode, as shown on the figure below.**

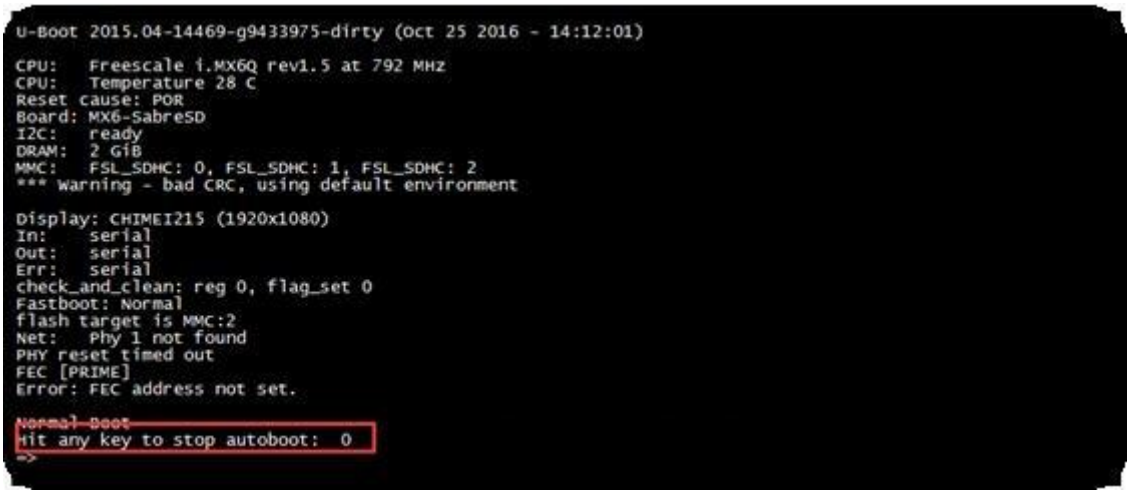


Figure 241: *Uboot*

> **Note**
>
> HDMI does not support hot-plug. The sound comes from the HDMI monitor, neither the speaker nor the headset on board.

- **Use the following command to set different resolution**
  - **For 1080p**

```
=> setenv displayargs video=mxcfb0:dev=hdmi,1920x1080M@60
video=mxcfb1:dev=off video=mxcfb2:off
=> saveenv
=> boot
```

  - **For 720p**

```
=> setenv displayargs video=mxcfb0:dev=hdmi,1280x720M@60
video=mxcfb1:dev=off video=mxcfb2:off
=> saveenv
=> boot
```

  - **For 480p**

```
=> setenv displayargs video=mxcfb0:dev=hdmi,800x480M@60
video=mxcfb1:dev=off video=mxcfb2:off
=> saveenv
=> boot
```

Figure 242: *HDMI Output Setting*

- Reboot the IPC.
- **Use the following command to reset the output from LDB.**

```
=> setenv displayargs video=mxcfb0:dev=ldb video=mxcfb1:dev=off
video=mxcfb2:off
=> saveenv
=> boot
```

Serial Port

There are five serial ports on the Chipsee IPC: 2 x RS232 and 3 x RS485 (can be customised). Refer to the table below for the available serial device nodes.

The default serial port configuration is 2 x RS232, 2 x RS485, 1 x RS485 which is shared with Bluetooth.
Contact us if you need help with changing the default serial port configuration

Ports	Device Node
COM1(RS232, Debug)	/dev/ttymxc0
COM2(RS485)	/dev/ttymxc1
COM3(RS232)	/dev/ttymxc2
COM4(RS485)	/dev/ttymxc3
COM5(RS485)	/dev/ttymxc4

Table 51 Serial Ports Nodes on the System

> **Note**
>
> If you use COM2(RS485), you can't use Bluetooth because COM2(RS485) share pin with Bluetooth.

You can test the serial port by using the **HT_Serial Application** in the desktop, as shown on the figure below.

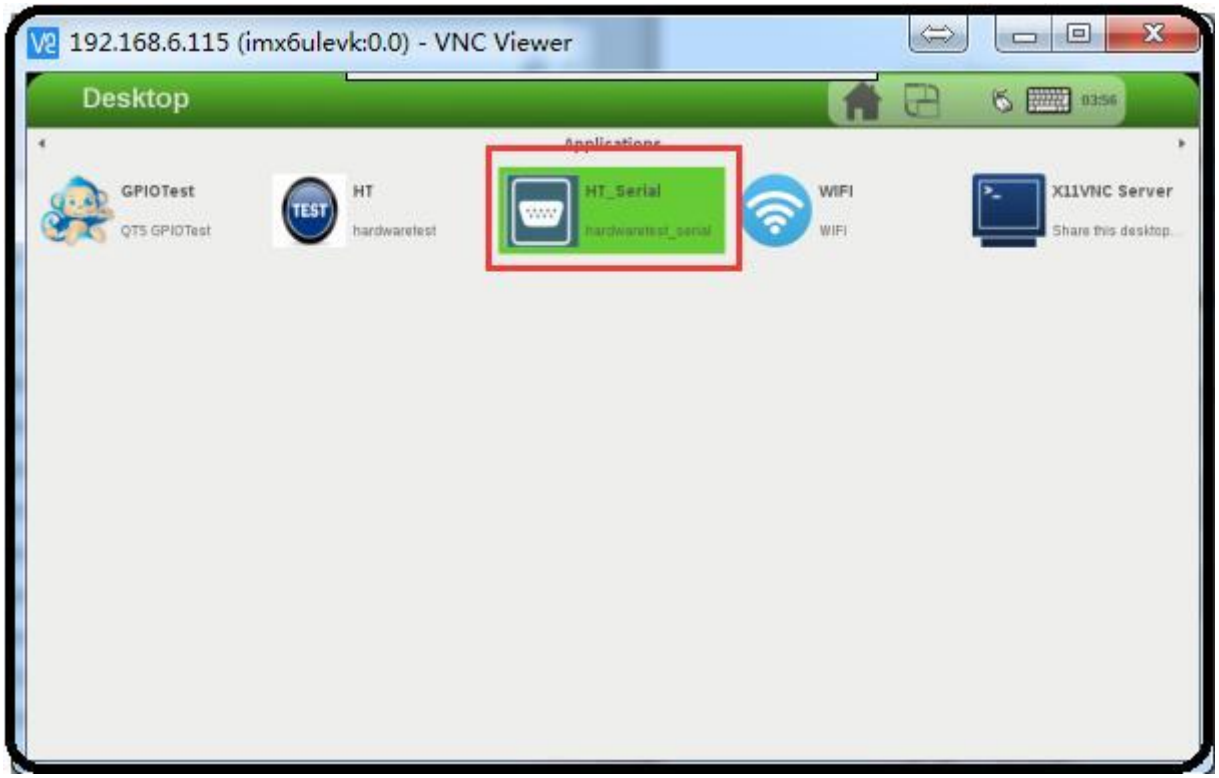


Figure 243: *HT_Serial Test*

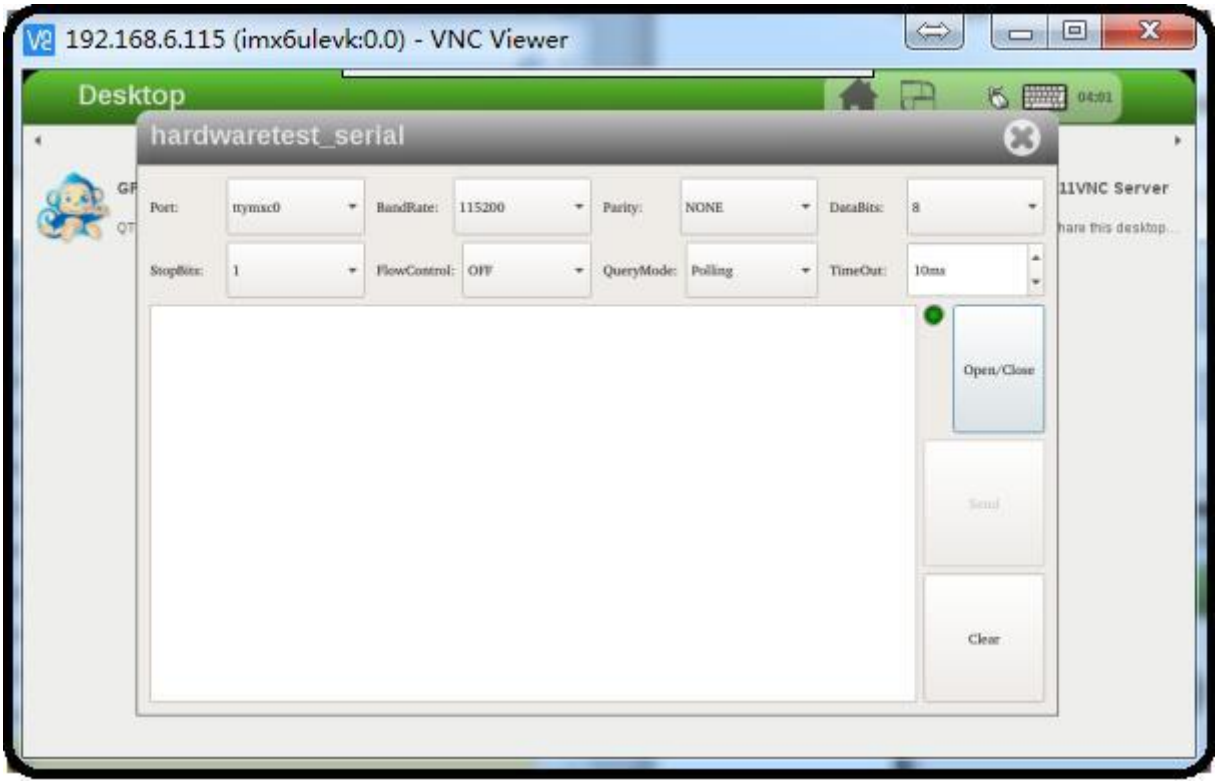


Figure 244: *HT_Serial Test*

CAN Bus

Chipsee Industrial PC is equipped with two CAN busses (CAN1 and CAN2). Two devices can be interconnected. You can test the CAN buses by using the **HT application** but you must add one 120Ω resistor between CAN_H and CAN_L on one of the two Boards, as shown on the figure below.

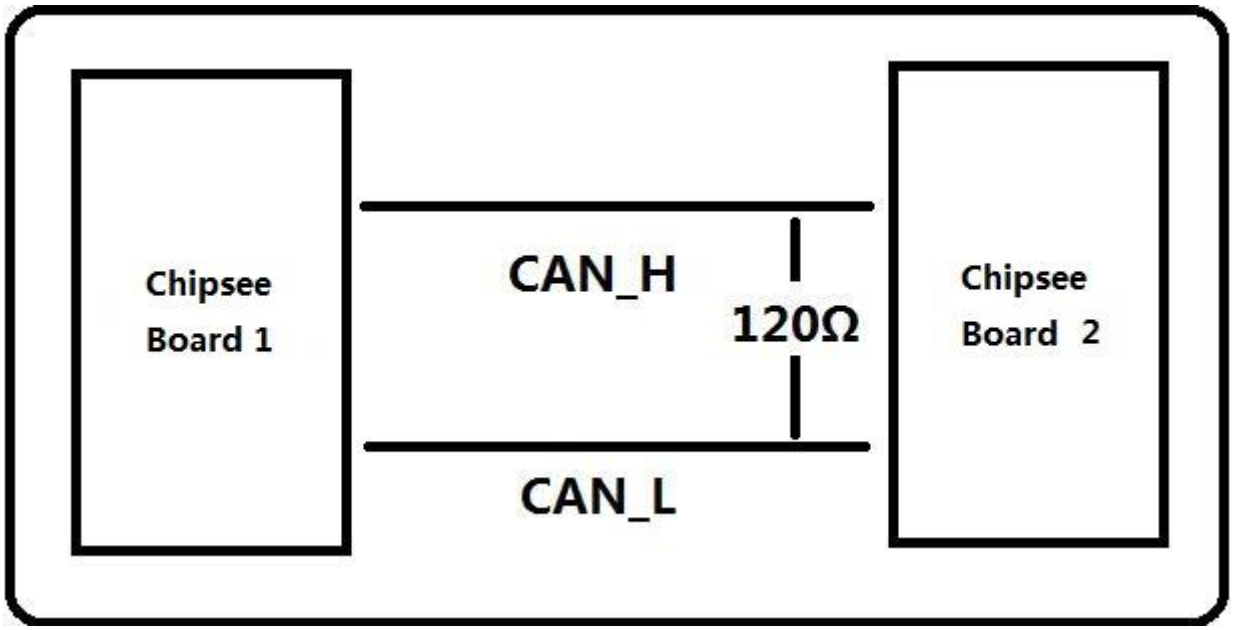


Figure 245: *CAN Connect*

Note

> The Chipsee IPC does not mount the 120Ω matched resistor on all CAN signals by default.

Here are a few examples to test CAN by using CAN units

- **Install** *can-utils*

```
$ sudo apt install can-utils
```

- **Set the bit-rate to 50Kbits/sec with triple sampling using the following command (use ROOT user):**

```
$ sudo ip link set can0 type can bitrate 50000 triple-sampling on
```

- **Bring up the device using the command:**

```
$ sudo ip link set can0 up
```

- **Transfer packets**
  - Transmit 8 bytes with standard packet id number as 0x10

```
$ sudo cansend can0 -i 0x10 0x11 0x22 0x33 0x44 0x55 0x66 0x77 0x88
```

  - Transmit 8 bytes with extended packet id number as 0x800

```
$ sudo cansend can0 -i 0x800 0x11 0x22 0x33 0x44 0x55 0x66 0x77 0x88 - e
```

  - Transmit 20 8 bytes with extended packet id number as 0xFFFFF

```
$ sudo cansend can0 -i 0xFFFFF 0x11 0x22 0x33 0x44 0x55 0x66 0x77 0x88 -e
--loop=20
```

- **Receive data from CAN bus**

```
$ sudo candump can0
```

- **Bring down the device**

```
$ sudo ip link set can0 down
```

You can use the **HT application** to test CAN. To perform the CAN test, you need two Chipsee IPC boards to perform the test.
Follow these steps to perform the CAN test:

- Connect the two IPC boards and select the CAN port `can0` or `can1` simultaneously on both IPC boards.
- Click on the **CanStart** button simultaneously on both IPC boards.

Refer to the figure below for the CAN part in the HT application.

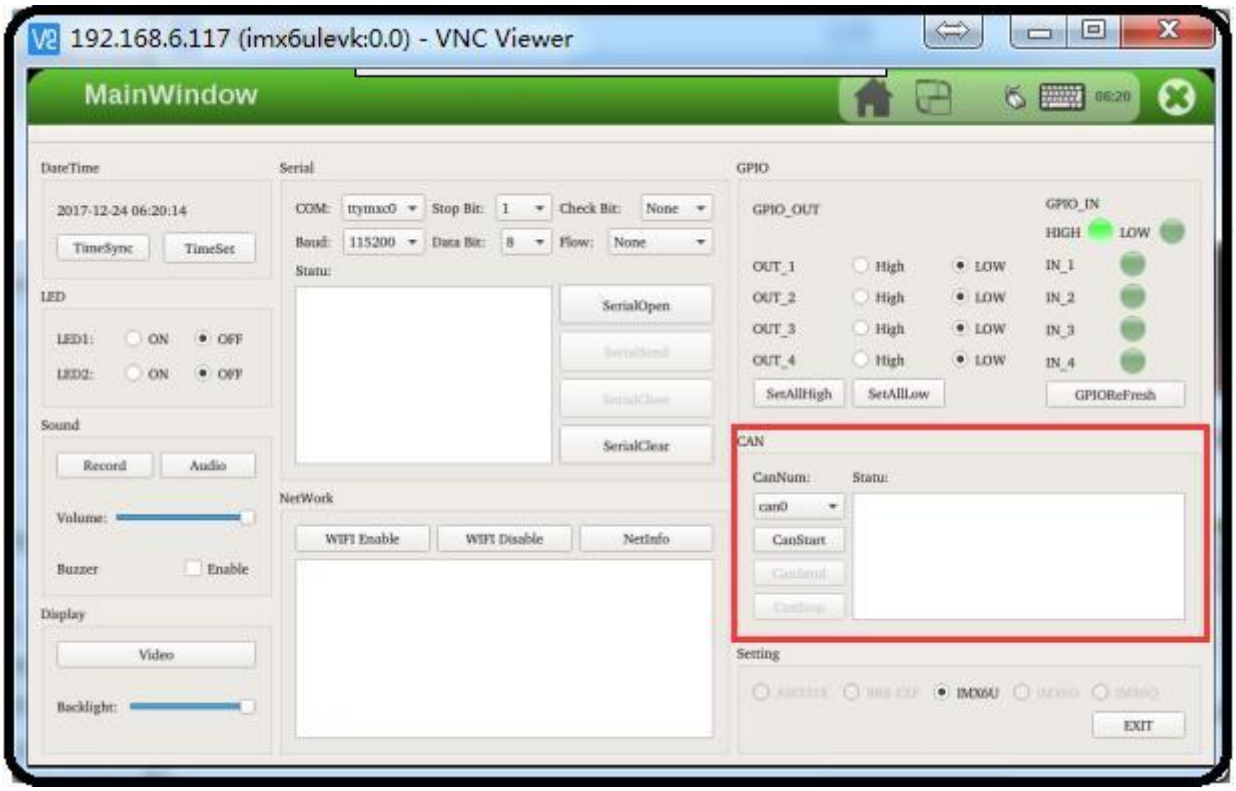


Figure 246: *CAN*

GPIO

There are 8 GPIOs, 4 Output, and 4 Input, they are all isolated. You can control the output or input pin voltage by feeding the VDD_ISO suite voltage. The pin voltage should be from 5V to 24V. Refer to the tables below for a detailed port definition:

Pin Number	GPIO Number
11	205
12	106
13	29
14	30
15	28
16	204

Pin Number	GPIO Number
17	94
18	95

Table 52 CS80480F070 – V1.0 P11 Port

Pin Number	GPIO Number
21	106
22	29
23	30
24	28
27	95
28	94
29	87
30	130

Table 53 CS10600F070 – V1.0 P21 Port

Pin Number	GPIO Number
21	29
22	106
23	28
24	30
27	130
28	87
29	94
30	95

Table 54 CS10600F070 – V2.0 P21 Port

Pin Number	GPIO Number
3	106
4	30
6	95
7	87
8	29
9	28

Pin Number	GPIO Number
11	94
12	130

Table 55 CS12800F010 – V1.0 P28 Port

Note

You need `ROOT` permissions to control GPIO.

Set *gpio106 Output* to high or low using this command

```
# echo  106  > /sys/class/gpio/export                //export gpio106
# echo  out  > /sys/class/gpio/gpio106/direction     //set gpio106 Output
# echo  1  > /sys/class/gpio/gpio106/value           //Set gpio106 high
# echo  0  > /sys/class/gpio/gpio106/value           //Set gpio106 low
```

Set *gpio30 Input* using this command

```
# echo  30  > /sys/class/gpio/export                  //export  gpio30
# echo  in  > /sys/class/gpio/gpio30/direction        //Set  gpio30 input
```

Un-export *gpio30* using this command

```
# echo  30  > /sys/class/gpio/unexport                 //un-export  gpio30
```

You can use the **HT application** to test GPIO.
Follow these steps to perform the GPIO test:

- Before you test, you need to connect the output gpio and input gpio, like *out 1 — in 1* / *out 2 — in 2* / *out 3 — in 3* / *out 4 — out 4* .
- Click on the **SetAllHigh** or **SetAllLow** button to check the right light status.
- Also, you can set the *output gpio* to high or low respectively. Then check the right *input gpio* status, as shown on the figure below.

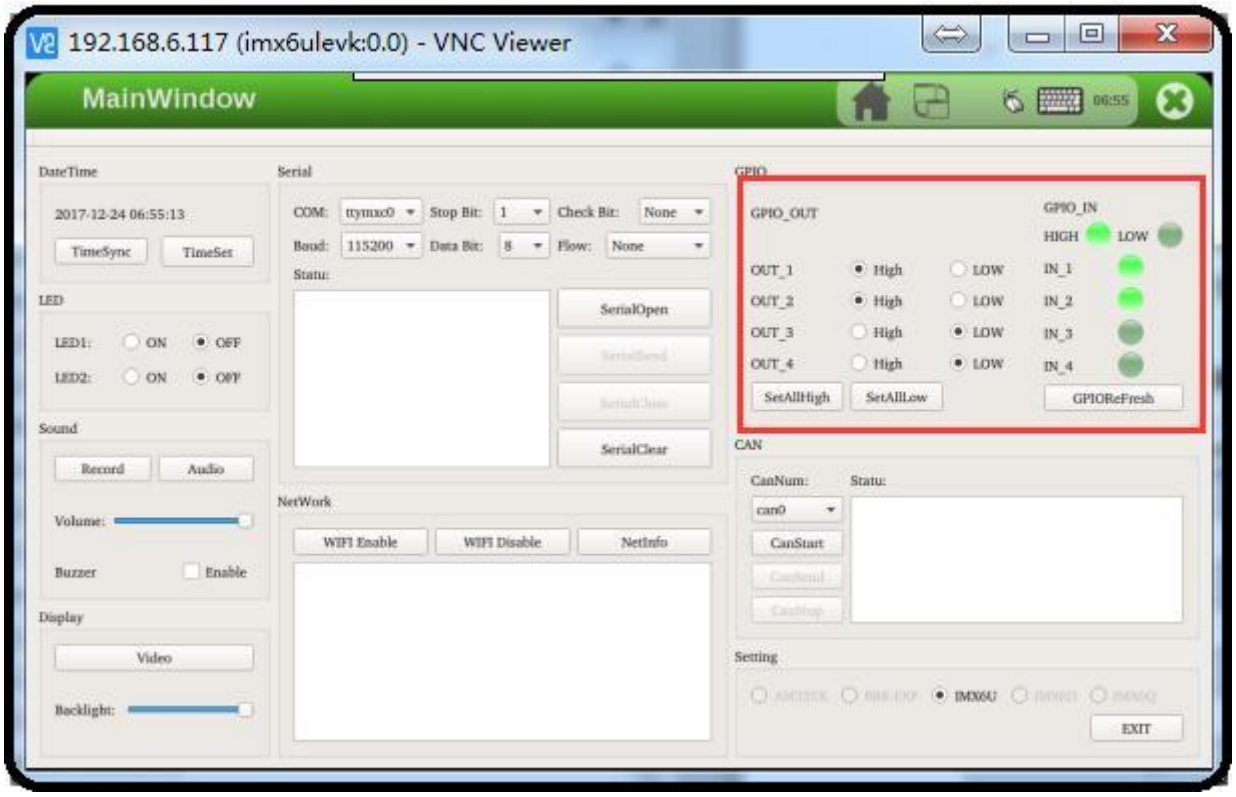


Figure 247: *GPIO Test*

> **Note**
>
> The default gpio has 4 Outputs and 4 Inputs. If you want a custom solution, please check the */etc/init.d/chipsee-init* file for details.

Buzzer

The buzzer is one GPIO, which has the GPIO Number as 80.

You can test the buzzer with the following commands.

```
# echo  80  > /sys/class/gpio/export                 //export gpio80
# echo  out  > /sys/class/gpio/gpio80/direction     //set gpio80 output
# echo  1  > /sys/class/gpio/gpio80/value           //Open Buzzer
# echo  0  > /sys/class/gpio/gpio80/value           //Close Buzzer
```

You also can use the HT application to test the buzzer.

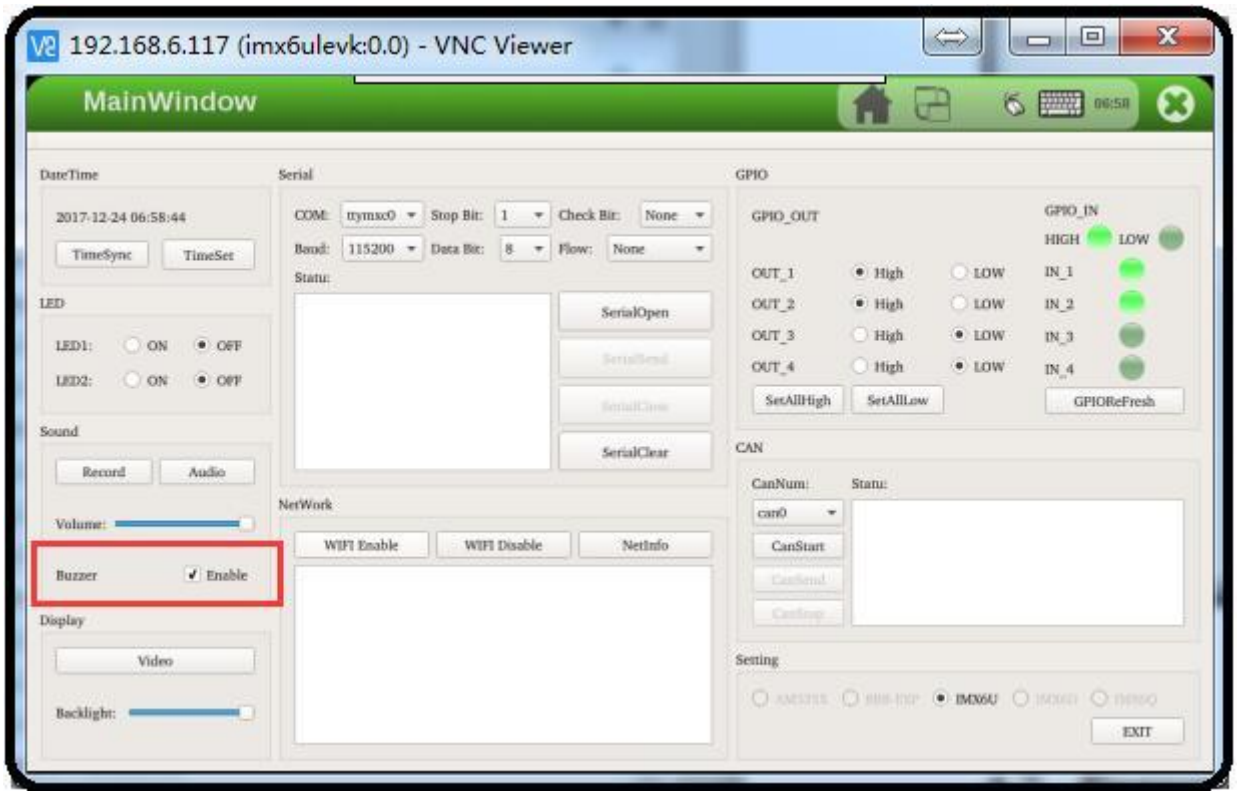


Figure 248: *Buzzer*

Modify Logo

This system supports changing the logo by yourself. There are two ways:

- Replace the logo file in prebuilt images packages, and download images.
- Change the logo without downloading images.

> **Note**
>
> Logo file is one 32bpp, format is bmp.

Method 1 - Downloading images

Replace the *prebuilt-xxx/emmc-flash/emmc/logo.bmp* and reference Downloading Images by using MFGTool to flash the image.

Method 2 - Don't Download Images

We will use **MFGTools** and the **Logoflasher** apps to change the logo.

Use MFGTools to Change LOGO

- Replace the `logo.bmp` file in *Mfgtools-K31452-V1.0\Profiles\Linux\OS Firmware\files\ubuntu* with your customised logo file.

- **Open and edit the** *Mfgtools-K31452-V1.0\cfg.ini* **file and set the** `name` **variable to** `eMMC-Linux-Logo` **as shown below.**

Figure 249: *Change name*

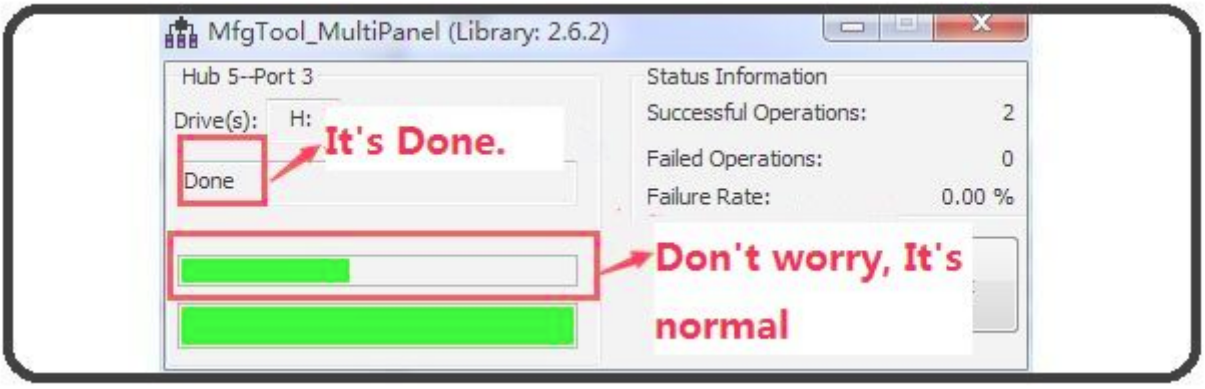


Figure 250: *Logo Modify with MFGTool*

Use Logoflasher to Change Logo

You can get the Logoflasher file and use this tool to make one bootable TF card.
Follow the steps below to change logo

- **Use the following commands to make bootable TF card.**

```
$ sudo  tar  zxvf  prebuilt-imx6qdl-bootfile-update-xxx.tar.gz
$ sudo  cd  prebuilt-imx6qdl-bootfile-update-xxx
$ sudo  ./mksdcard.sh  --device  /dev/sdX --display 1024600     //
resolution
```

- Put your custom logo file in the first partition `boot-flash` directory on the TF Card.
- Set boot mode to **TF card**. You can reference Boot Switch Configuration.

- Power ON the IPC. If you see this message, **>>>>>>> eMMC Flashing Completed <<<<<<<**, you are done:

Development

In this chapter, you will learn how to set up the QT development environment, and develop the first QT application on Chipsee IPC boards.

Host system requirements

1. Ubuntu 14.04 LTS 64bit system should be installed on the host machine.
2. Qtcreator is optional to develop application, you can download QT5.5.1 which will install Qtcreator. Other Qt version should ok as we only need Qtcreator.

Preparation

1. Download QT5.5.1 and install it on the system. Other Qt version should ok as we only need Qtcreator. Install it in the */home/<user>/program* directory.
2. **Install SDK. Get the SDK and install it using this command:**

```
# chmod +x fsl-imx-x11-glibc-x86_64-meta-toolchain-qt5-cortexa9hf-vfp-neon-toolchain-3.14.52-1.1.1.sh
# ./ fsl-imx-x11-glibc-x86_64-meta-toolchain-qt5-cortexa9hf-vfp-neon-toolchain-3.14.52-1.1.1.sh
```

   The default install directory is */opt/fsl-imx-x11/3.14.52-1.1.1* . You can install it in this directory or you can also use another directory.

3. **Use the following command to test SDK:**

```
# source /opt/fsl-imx-x11/3.14.52-1.1.1/ environment-setup-cortexa7hf-vfp-neon-poky-linux-gnueabi
# echo ${CC}
```

4. **Setting Qtcreator. If you installed `qt-opensource-linux-x64-5.5.1.run`, the Qtcreator will be installed automatically.**

   - **Before you open QtCreator, you need to add the following code-block in the first line of */home/<user>/program/Qt5.5.1/Tools/QtCreator/bin/qtcreator.sh* , as shown on the figure below.**

```
$ source /opt/fsl-imx-x11/3.14.52-1.1.1/ environment-setup-cortexa7hf-vfp-neon-poky-linux-gnueabi
```

Figure 251: *Setting QtCreator*

5. **Use the following command to open Qtcreator.**

```
# /home/program/Qt5.5.1/Tools/QtCreator/bin/qtcreator.sh
```

6. **Open the QtCreator Options, then click on Tools->Options->Build & Run. Set the Debuggers/Compilers/Qt Versions/Kits as shown on the figures below.**

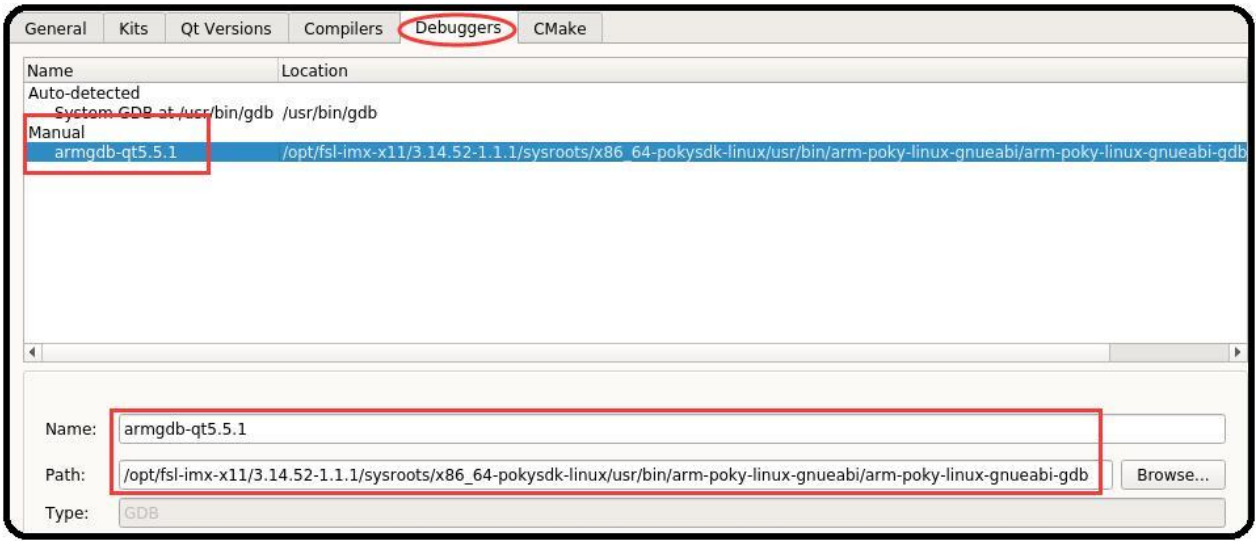


Figure 252: *Debuggers*

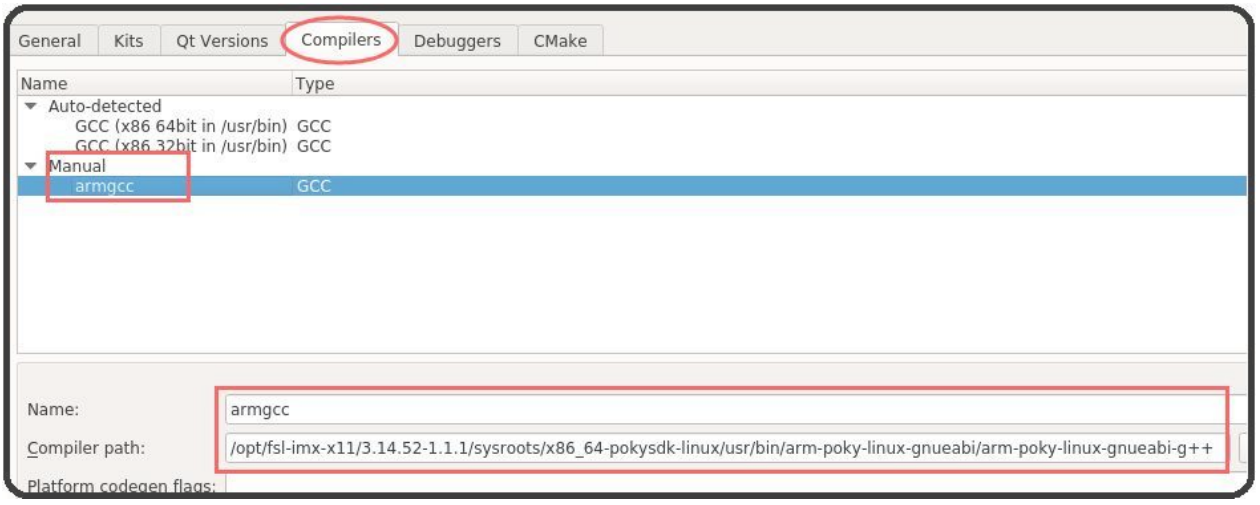


Figure 253: *Compilers*

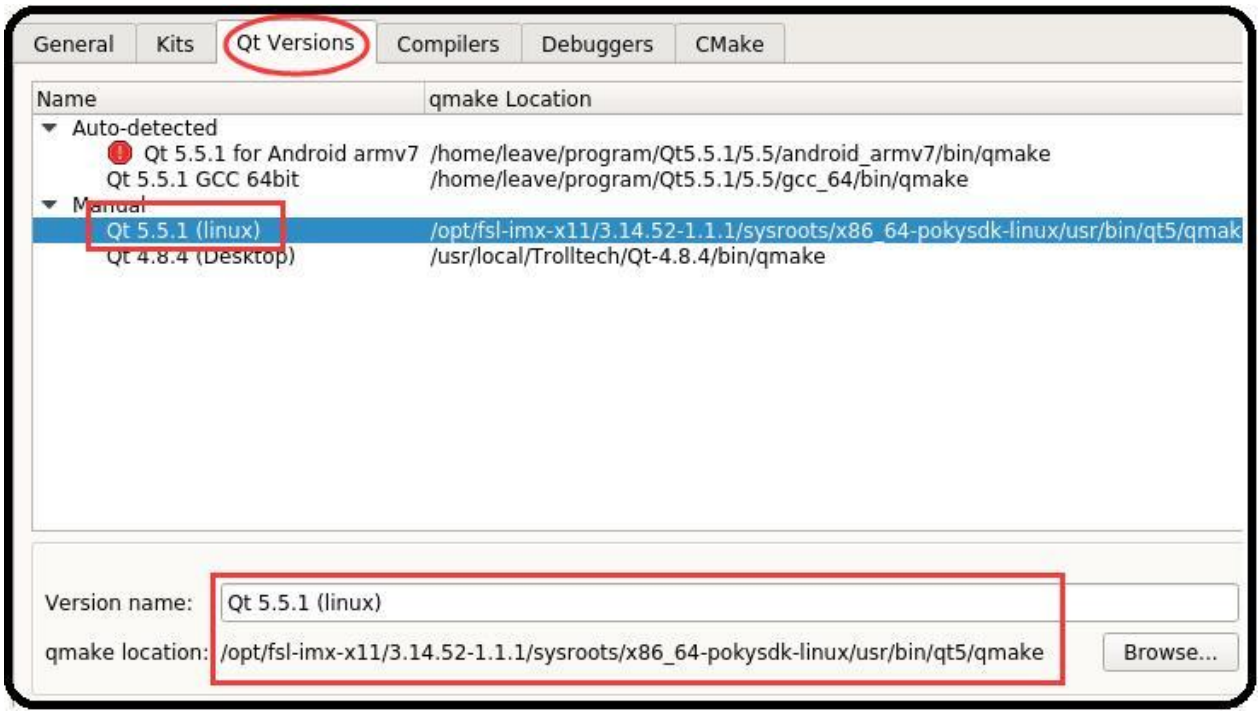


Figure 254: *Qt Versions*

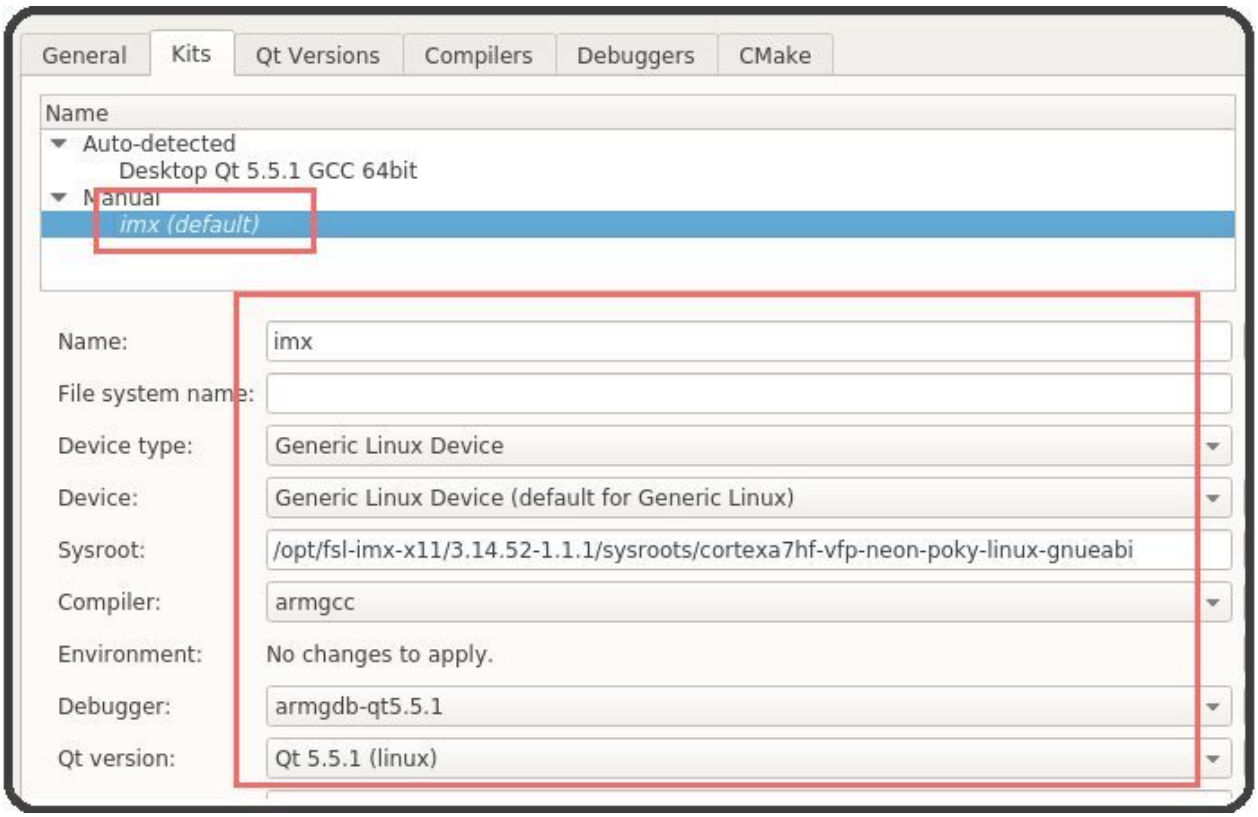


Figure 255: *Kits*

Example — Develop a `HelloWorld` Program

1. **Use QtCreator to create a new Qt Widgets Application, named `HelloWorld`, as shown on the figure below.**

Figure 256: *Qt Widgets Application*

2. **Select IMX kits, as shown on the figure below.**

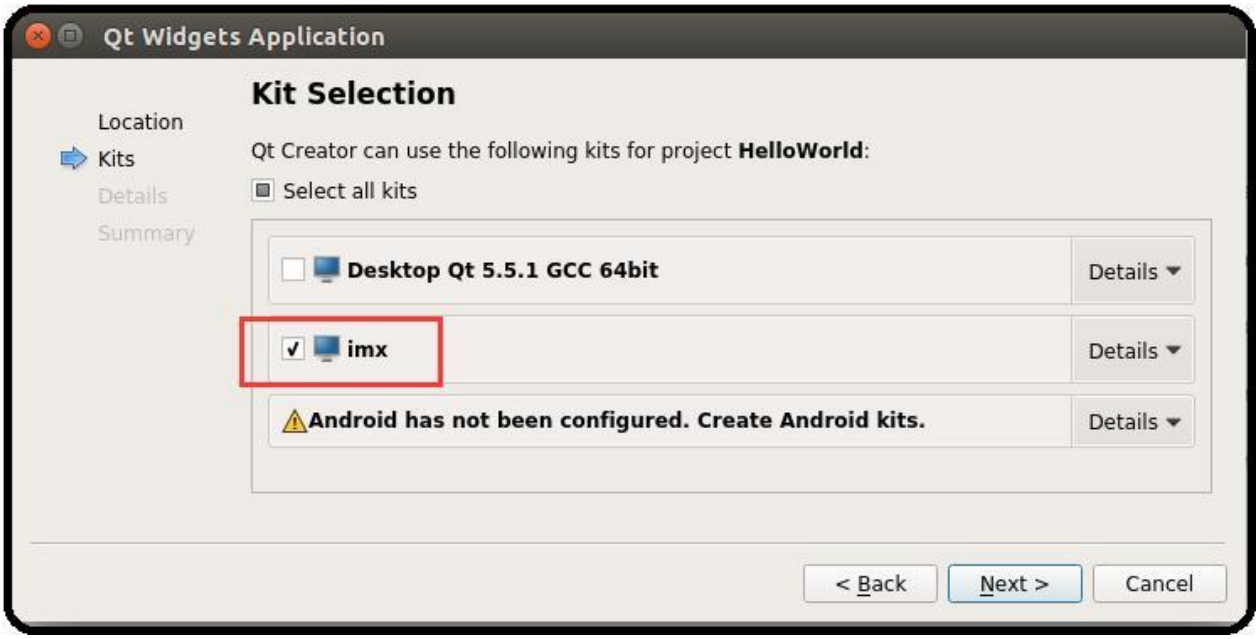


Figure 257: *Kit Selection*

3. **Use QMainWindow as the Base class, as shown on the figure below.**

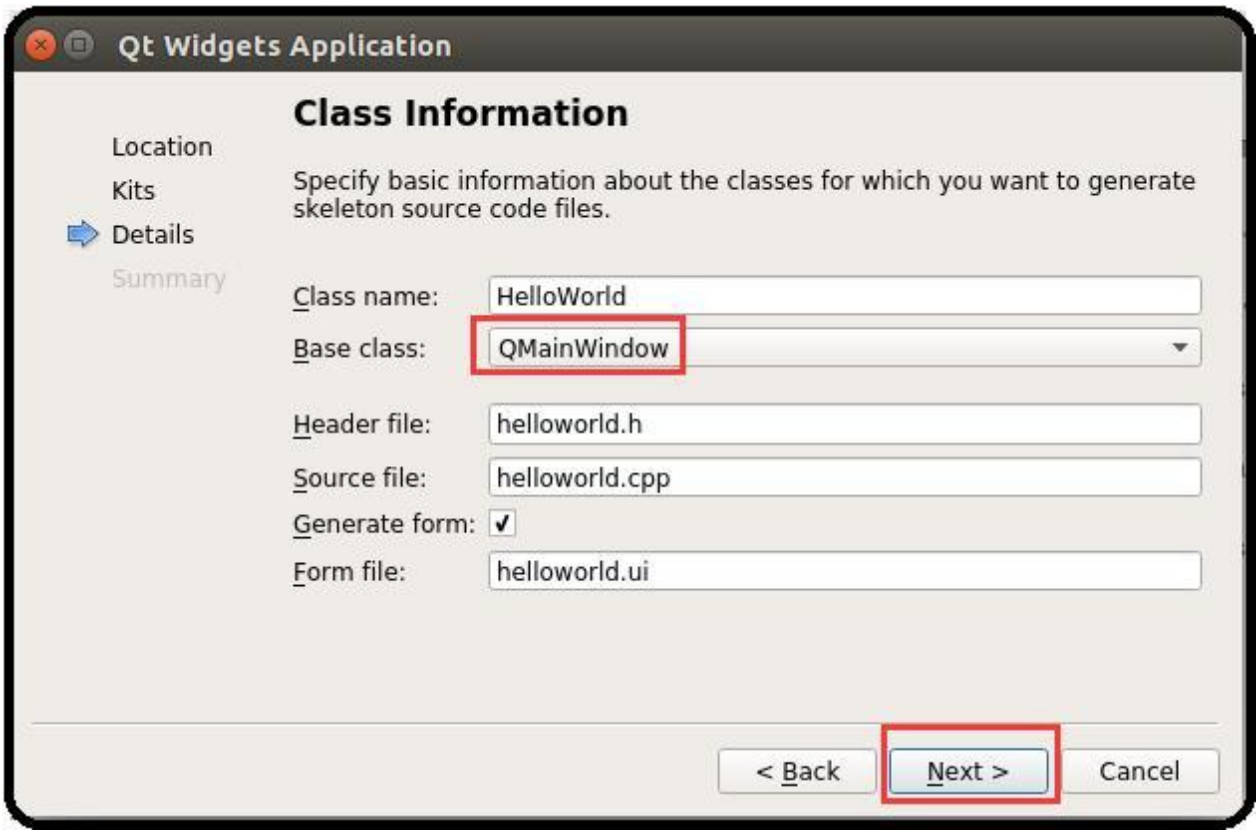


Figure 258: *Base Class*

4. **Click the Design icon to add one label widget, as shown on the figure below.**

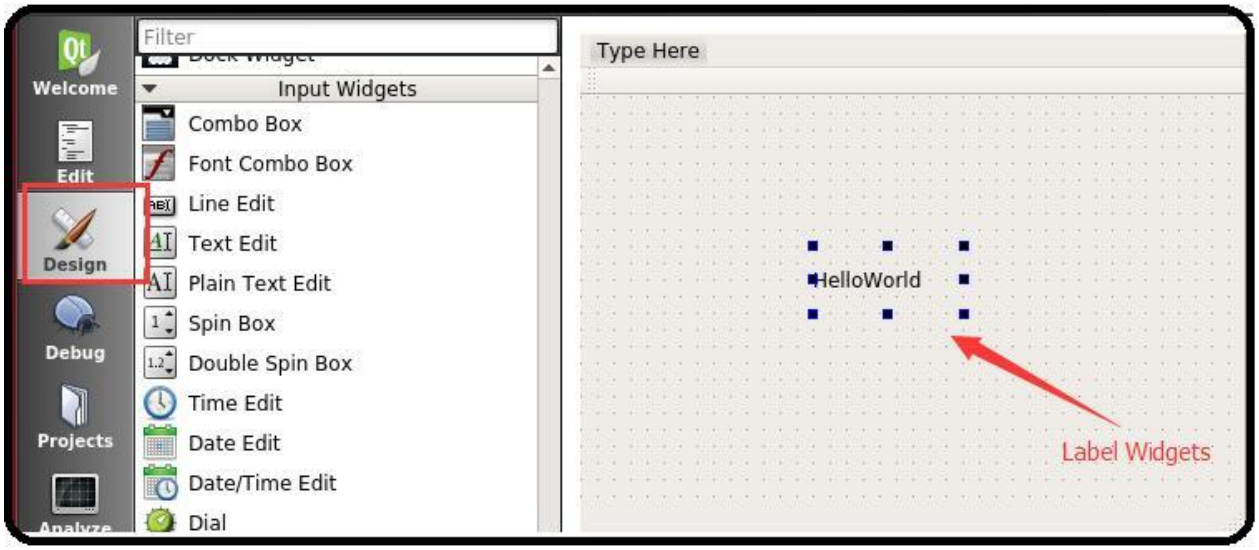


Figure 259: *Add Label Widget*

5. **Click on the Build icon to build app, as shown on the figure below.**

Figure 260: *Build App*

6. **Copy the `Helloworld` app to the IPC board's** */home/root/* **directory and use the following command to run it:**

```
# export DISPLAY=:0.0
# ./HelloWorld
```

You can get the `HelloWorld` app from the */home/leave/build-HelloWorld-imx-Debug* directory, but your directory might not be the same as this one.

Q&A

In this chapter, you can learn how to set up the QT development environment, and develop the first QT application on Chipsee IPC boards.

How to Change psplash's

- **Install IMX SDK and some Packages. Reference the install SDK point under the Preparation section above to install IMX SDK and install some recommends packages using this command:**

```
$ sudo  apt-get  install  autoconf  libgdk-pixbuf2.0-dev
```

- **Generate psplash of your own.**
    - **Get psplash and extract it.**

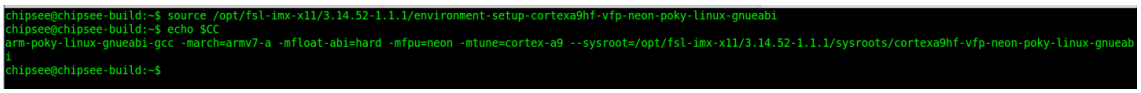
```
$ sudo tar zxvf psplash.tar.gz
```

    - **Prepare a PNG file, such as `chipsee.png`**

```
$ sudo cp chipsee.png psplash/
$ sudo cd psplash
```

- **Setting environment**

```
$ source /opt/fsl-imx-x11/3.14.52-1.1.1/environment-setup-
cortexa9hf-vfp-neon-poky-linux-gnueabi
```



- **Generate header file and modify the psplash.c, then config and make:**

```
$ ./make-image-header.sh chipsee.png POKY  //you will find a new
file named chipsee-img.h
$ vi psplash.c  // replace the header file name (psplash-poky-
img.h) in psplash.c with chipsee-img.h
$ ./autogen.sh
$ make  // you will generate the file psplash
```

- Then you will find the file `psplash`, replace the one in `rootfs` */usr/bin/psplash* . Reboot your IPC board to apply the changes made to the psplash.
- You can remove the */etc/init.d/psplash.sh* file in `rootfs` to disable it.
- **If you want to rotate the psplash screen, just do the following in the system:**

```
# echo 180 > /etc/rotation   // rotate  180  angle
# echo 0 > /etc/rotation         // reset to default.
```

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