



Tokyo Tech

Outdoor mmWave band Tx Localization using scattering path under Spectrum Sharing scenario

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Background

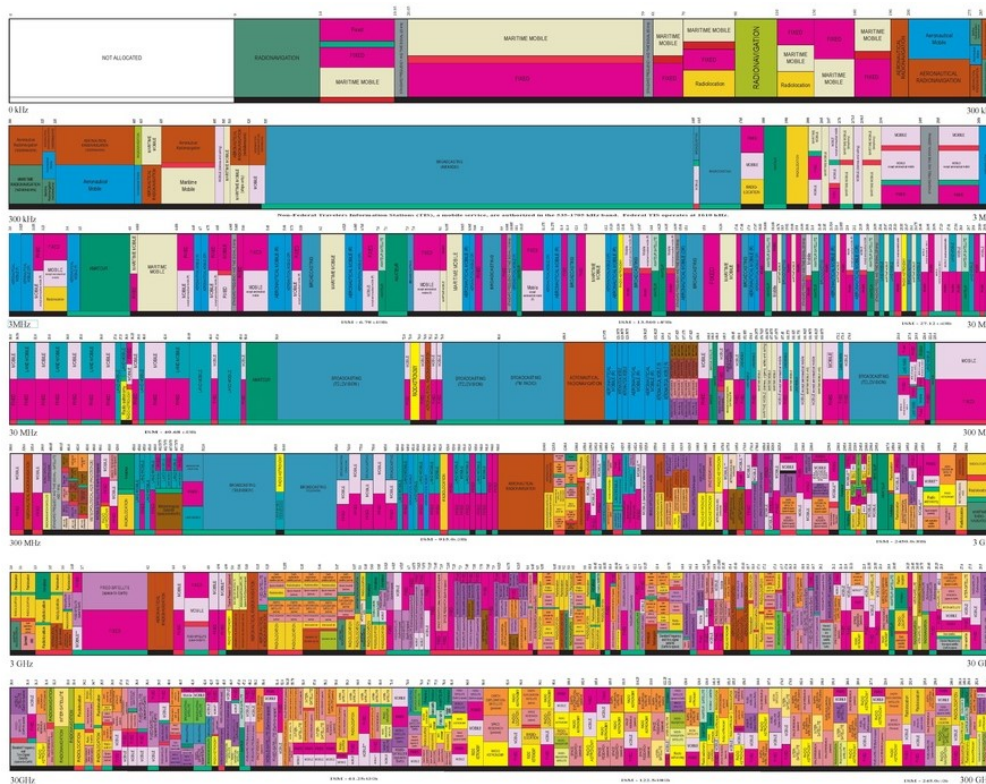


Fig.1 Spectrum allocation in USA

Taken from:United_States_Frequency_Allocations_Chart_The_Radio_Spectrum.

The spectrum resources are artificially scarce because the static legacy regulatory prevents the spectrum to be shared more intensively.

Spectrum

Spectrum resources is a key point for future development of International Mobile Telecommunication (IMT).

According to WRC 19 conclusions, **24.25-27.5GHz** frequency band is identified to IMT.

Existing Problem

However, as you can see in Fig.1. The different color means different radio services. 0kHz to 300GHz is divided in every 10GHz.

Background

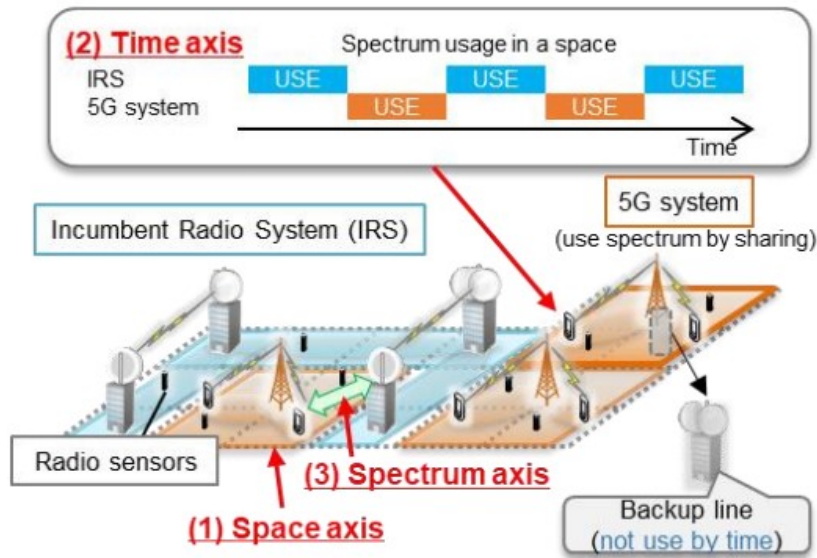


Fig.2 Spectrum Sharing Concept

Taken from: [1] SHINBO, Hiroyuki & YAMAZAKI, Kosuke & KISHI, Yoji. (2021). Research & Development of the advanced dynamic spectrum sharing system between different radio services. IEICE Transactions on Communications. 10.1587/transcom.2020DSI0001.

Fixed Wireless Access

The targeted frequency band is the millimeter wave (mmWave) band of Fixed Wireless Access (FWA) using in Japan.

FWA is a way of providing wireless connectivity through radio links between two **fixed stations**.

Spatial Spectrum Sharing

Spectrum sharing helps to solve the scarce spectrum resources problem.

- Space axis
- Time axis
- Spectrum axis

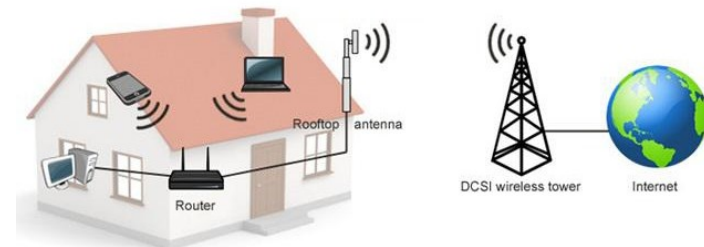


Fig.3 Fixed Wireless Access Concept

Background

Application Background

• Problem 1

Though FWA is fixed, there are also **portable** ones plays as **temporary station**. The operation parameters of portable FWA may **not be registered** in the spectrum sharing database in advance.

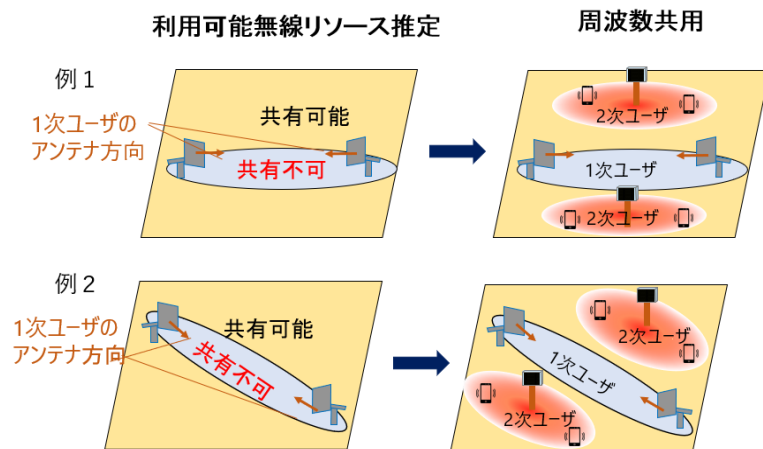


Fig.4 Antenna pattern

Taken from: [2] 異システム間の周波数共用技術の高度化に関する研究開発, Figure 10-7, page 113

• Problem 2

The conventional localization scheme **only estimate the position** of Tx. However, under the spectrum sharing scenario, we need to estimate **more operation parameters**:

1. The antenna pattern of Tx
2. Beamwidth

Theoretical Background

• Problem 3

Localize with LoS can get good accuracy. However, LoS is unlikely guaranteed in urban environment and NLoS path can lower the accuracy. So, the analysis of it is crucial.

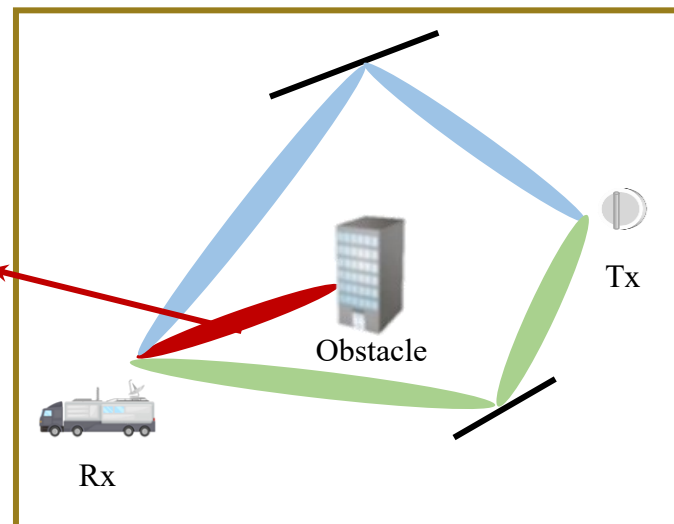


Fig.6 Propagation mechanism in mmWave

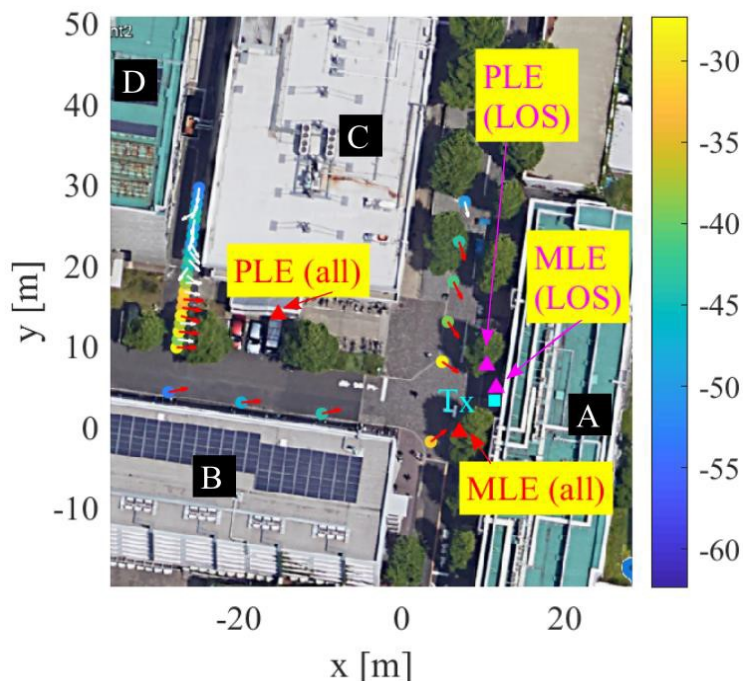


Fig.7 localization results

Distance Error

	PLE	MLE
LOS only	4.5m	1.7m
All points	28.6m	5.7m

Research Content

• Problem 4

mmWave can be easily **blocked** by buildings

- The propagation is very site specific
- Localization with empirical site general model may not be applicable
- Environment map is necessary

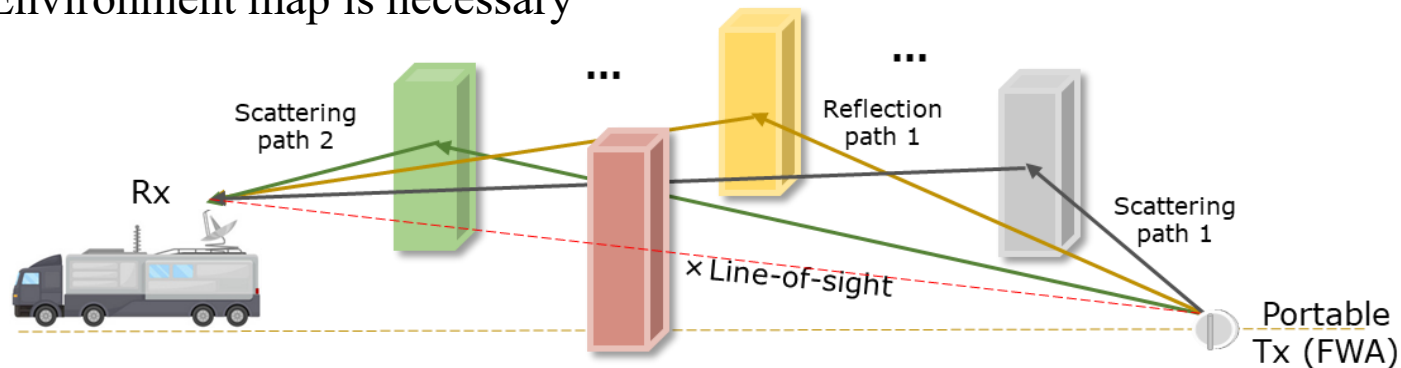
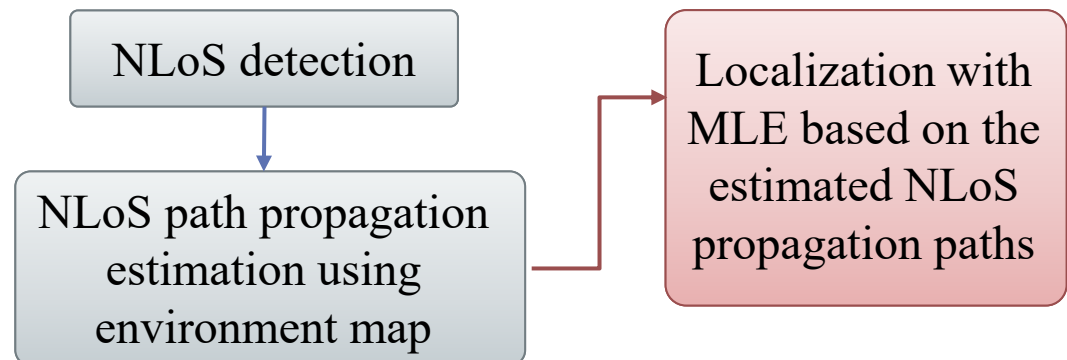


Fig.8 NLOS Localization Concept

Research Objective

Localization of Tx under non-line-of-sight (NLOS) environment at millimeter wave band.

Research Plan



Research Content

NLOS paths Detection

LOS and NLOS path presents the salient difference in many aspects:

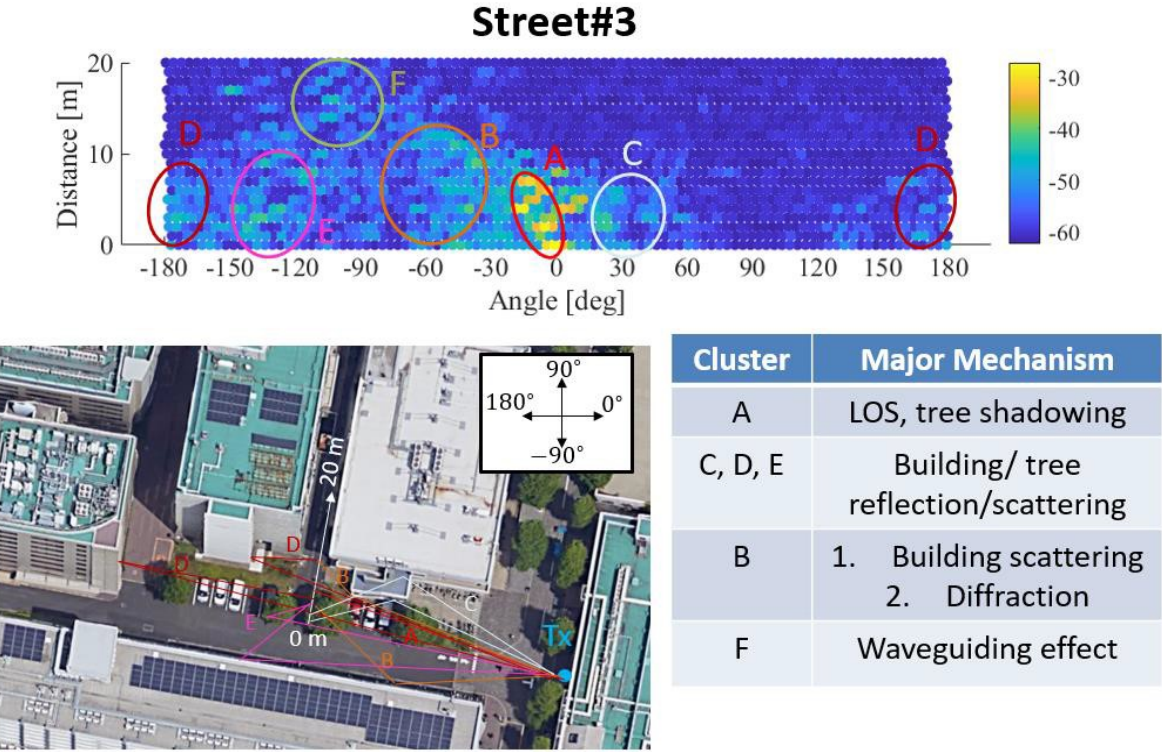


Fig.9 NLOS Localization Concept

Taken from: [2] 異システム間の周波数共用技術の高度化に関する研究開発, Figure 10-8, page 201

- (i) **More attenuation** [3]
due to reflection , and
resulting in relatively **smaller received power.**
- (ii) **Large angular spread** due
to the diffuse scattering paths
and vice versa to the LoS path
due to the direct path.

[3] S. Maran`o, W. M. Gifford, H. Wymeersch, and M. Z. Win, “Nlos identification and mitigation for localization based on uwb experimental data,” IEEE Journal on Selected Areas in Communications, vol. 28, no. 7, pp. 1026–1035, 2010.

Research Content

Overview in Traditional Localization Methods

Maximum Likelihood Estimation (MLE) utilize the angular power spectrum obtained from the spatially separated receiver [4]. However, previous works utilized MLE **only for estimating Tx location** which is not sufficient for spatial spectrum sharing. (**unknown peak direction and beamwidth**)

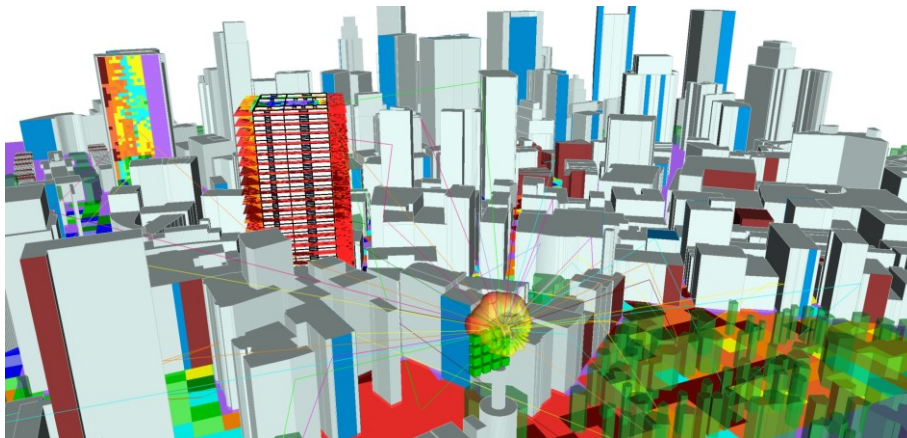


Fig.9 Urban Small-Cell Analysis

Taken from: <https://www.remcom.com/>

Goal: Tx location, peak direction, and beamwidth

Input: Environment model, Rx power.

Output: Estimated location

Before measurement, the test with the RT simulation to validate the estimation methodology is crucial.

References

- [1] SHINBO, Hiroyuki & YAMAZAKI, Kosuke & KISHI, Yoji. (2021). Research & Development of the advanced dynamic spectrum sharing system between different radio services. IEICE Transactions on Communications. 10.1587/transcom.2020DSI0001.

- [2] 異システム間の周波数共用技術の高度化に関する研究開発 (2020)

- [3] S. Marano, W. M. Gifford, H. Wymeersch, and M. Z. Win, “Nlos identification and mitigation for localization based on uwb experimental data,” IEEE Journal on Selected Areas in Communications, vol. 28, no. 7, pp. 1026–1035, 2010.

- [4] K. Dogancay and G. Ibal, “3d passive localization in the presence of large bearing noise,” in 2005 13th European Signal Processing Conference, 2005, pp. 1–4.



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Thank You for your attention

