



# **REDESIGNED SSES IN THE ADVANCED CLEAR-SKY PROCESSOR FOR OCEANS**

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# Objectives

- The SSES algorithm in ACSPO v.2.40 was redesigned, with the specific objective to improve assimilation of ACSPO L2/L3U products in the “foundation” L4 analyses.
- The new SSES is expected to satisfy the following requirements
  1. Applying SSES biases to ACSPO SST should minimize the need for bias correction during the L4 analyses (*tested by improving the consistency with in situ SST*)
  2. SSES SDs should characterize the precision of ACSPO SST under variable conditions. This should allow optimal weighting of ACSPO SSTs with other data in the L4 analyses (*not tested yet*)
- This presentation evaluates the performance of the new SSES bias correction against *in situ* and L4 SST.
- The ultimate test of the new ACSPO SSES will be its using in the L4 analyses

# Baseline regression SST in ACSPO (BSST)

The ACSPO adopts regression SST equations by OSI-SAF (*Lavanant et al., 2012*)

Day:  $T_s = a_0 + (a_1 + a_2 S_{\vartheta}) T_{11} + [a_3 + a_4 T_s^0 + a_5 S_{\vartheta}] (T_{11} - T_{12}) + a_6 S_{\vartheta}$

Night:  $T_s = b_0 + (b_1 + b_2 S_{\vartheta}) T_{3.7} + (b_3 + b_4 S_{\vartheta}) (T_{11} - T_{12}) + b_5 S_{\vartheta}$

$T_{11}, T_{12}, T_{3.7}$  observed BTs in bands 11, 12 and 3.7  $\mu\text{m}$

$S_{\vartheta} = 1/\cos(\vartheta)$   $\vartheta$  is VZA

$T_s^0$  first guess SST (in  $^{\circ}\text{C}$ )

$a$ 's and  $b$ 's regression coefficients trained on global datasets of matchups (MDS)

- These equations are used globally, each with a single set of coefficients
- Retrieval errors essentially vary across the global SST domain
- SSES should be estimated independently for separate segments of the SST domain uniform in terms of retrieval errors
- The question is: How to define the “segments with uniform errors”?

# The segmentation concept

- Customarily, SST retrieval errors are parameterized with certain physical variables (such as TPW, VZA, latitude, wind speed, aerosol, etc) (e.g., *Castro et al., 2008; Minnett, 2014; Petrenko et al., 2014*)
- This approach was initially used in ACSPO (Petrenko and Ignatov, 2014)
- However, it remains unclear if it is possible to account for all essential physical effects (e.g., underscreened clouds)
- In the redesigned ACSPO v2.40:
  - ✓ SSES are considered in the space of regressors (terms of the SST equation, excluding the offset). This way, the effects of all physical variables are aggregated in a limited number of arguments.
  - ✓ The “segmentation parameter” is then derived from the statistics of regressors within the training dataset of matchups (MDS); as a result, it is directly linked to the SD of retrieval error

# Segmentation parameter

- SSES are parameterized with Fisher distance in the space of regressors:

$$\rho = [(\mathbf{R} - \langle \mathbf{R} \rangle)^T \mathbf{D}^{-1} (\mathbf{R} - \langle \mathbf{R} \rangle)]^{0.5},$$

$\mathbf{R}$  is a vector of regressors  
 $\langle \mathbf{R} \rangle$  is a mean  $\mathbf{R}$  over the MDS  
 $\mathbf{D}$  is a covariance matrix of  $\mathbf{R}$  within the MDS

- SD of the retrieval error is shown to be a monotonic function of  $\rho$
- The dependencies of the retrieval errors on  $\rho$  are different along different directions in the space of regressors To account for such anisotropy:
  - An orthogonal basis is introduced in the space of regressors, with the origin at  $\langle \mathbf{R} \rangle$
  - Segmentation is performed independently in each orthant of this basis

# Generation of SSES LUTs and Processing satellite data

## Generation of LUT:

- The segmentation criteria are derived from the global MDS
- The global MDS is subdivided into subsets of matchups belonging to specific segments
- For each segment, SSES SDs and local regression coefficients are calculated and stored in the LUT

## L2 processing:

- The SST pixels are ascribed to segments (using regressors' values)
- Corresponding SSES SDs and local coefficients are obtained from LUT
- An auxiliary product - **Piecewise Regression (PWR) SST** - is produced with local coefficients
- **SSES biases** are calculated as **differences between the Baseline SSTs and PWR SSTs**

• **Correction of SSES biases transforms BSST back into PWR SST**  
**PWR SST = De-biased ACSPO SST**

# The statistics of fitting *in situ* SST with Baseline and De-biased SST

(Dependent) MDS from 15 May 2013 – 8 Aug 2014

SST	Statistics	S-NPP VIIRS	Aqua MODIS	NOAA19 AVHRR	MetOp-A AVHRR	MetOp-B AVHRR	Terra MODIS
		Day, afternoon sensors			Day, morning sensors		
Baseline	Bias	0	0	0	0	0	0
	SD	0.41	0.45	0.50	0.43	0.44	0.46
De-biased	Bias	0	0	0	0	0	0
	SD	0.31	0.33	0.34	0.31	0.30	0.32

		Night, afternoon sensors			Night, morning sensors		
Baseline	Bias	0	0	0	0	0	0
	SD	0.33	0.35	0.46	0.38	0.36	0.35
De-biased	Bias	0	0	0	0	0	0
	SD	0.25	0.26	0.29	0.27	0.26	0.26

Applying SSES biases reduces daytime SDs from 0.41-0.50 K to 0.30-0.34 K and nighttime SDs from 0.33-0.46 K to 0.25-0.29 K

# The statistics of fitting *in situ* SST with De-biased SST and CMC

- (Dependent) MDS from 15 May 2013 – 8 Aug 2014
- CMC is Canadian Met Center L4 SST

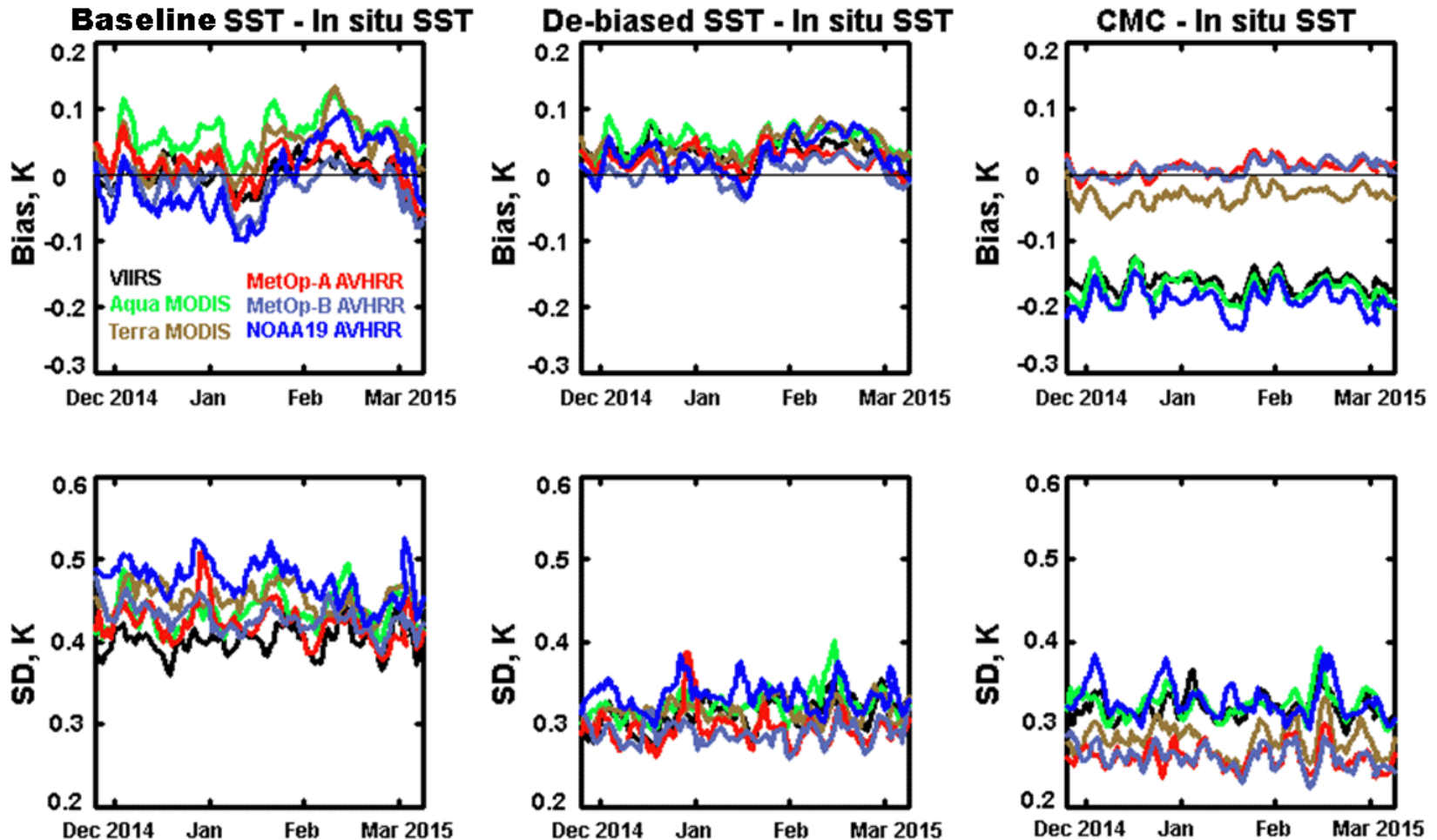
SST	Statistics	S-NPP VIIRS	Aqua MODIS	NOAA19 AVHRR	MetOp-A AVHRR	MetOp-B AVHRR	Terra MODIS
		Day, afternoon sensors			Day, morning sensors		
De-biased	Bias	0	0	0	0	0	0
	SD	0.31	0.33	0.34	0.31	0.30	0.32
CMC	Bias	-0.19	-0.20	-0.21	-0.01	-0.01	-0.06
	SD	0.34	0.34	0.35	0.30	0.30	0.31

		Night, afternoon sensors			Night, morning sensors		
De-biased	Bias	0	0	0	0	0	0
	SD	0.25	0.26	0.29	0.27	0.26	0.26
CMC	Bias	0.01	0.02	0.02	-0.07	-0.07	-0.04
	SD	0.27	0.28	0.29	0.31	0.29	0.29

- SDs for De-biased SST are close to CMC SST
- CMC SST is biased cold wrt daytime matchups for afternoon platforms (S-NPP, Aqua, NOAA19) and wrt nighttime matchups for the morning platforms (Terra, MetOp-A, MetOp-B)
- The De-biased ACSPO SST does not have such biases



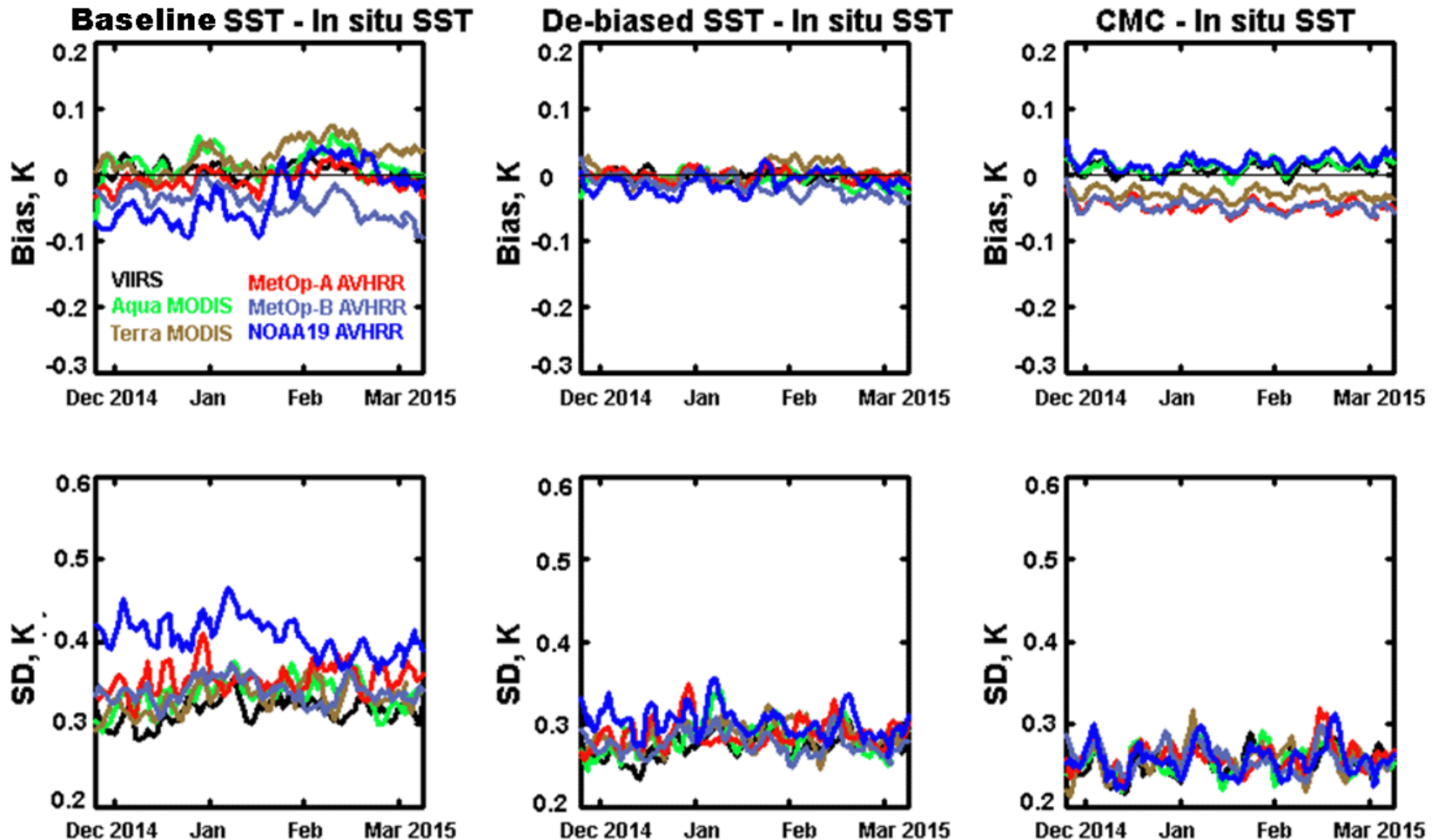
# Time series of daily **daytime** Bias and SD wrt *in situ* SST, 24 November 2014 – 10 March 2015 (independent MDS)



- De-biased ACSPO SST:

- improves cross-platform consistency of biases and reduces SDs to the CMC level
- unlike CMC, does not produce daytime biases for the afternoon platforms

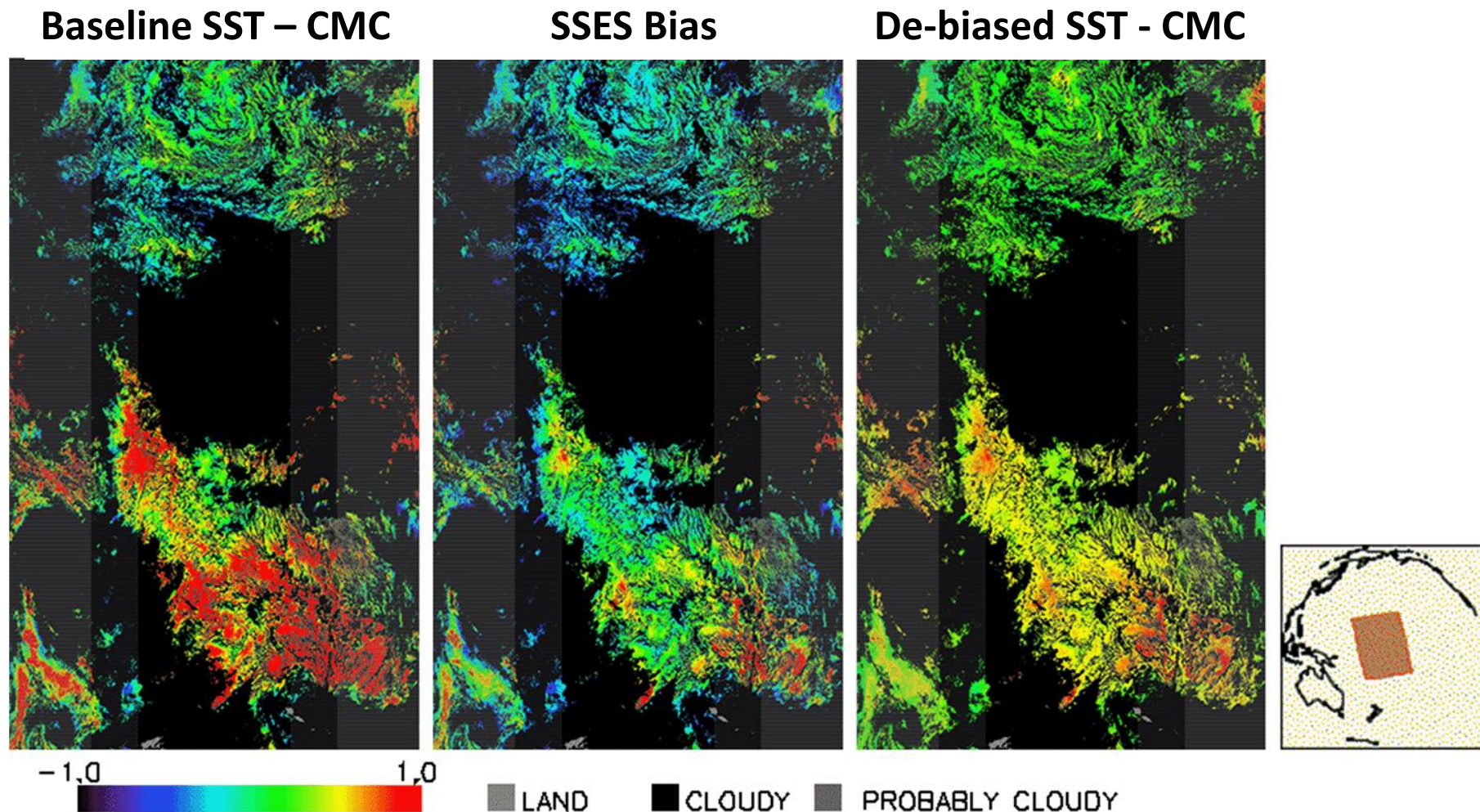
# Time series of daily **nighttime** Bias and SD wrt *in situ* SST, 24 November 2014 – 10 March 2015 (independent MDS)



- De-biased ACSPO SST:

- improves cross-platform consistency of biases and reduces SDs to the CMC level
- unlike CMC, does not produce nighttime biases for the morning platforms

# The effect of the **daytime** SSES bias correction (VIIRS, 19 December 2014)



**Correction of SSES biases reduces the effects of cloud leakages and diurnal warming**

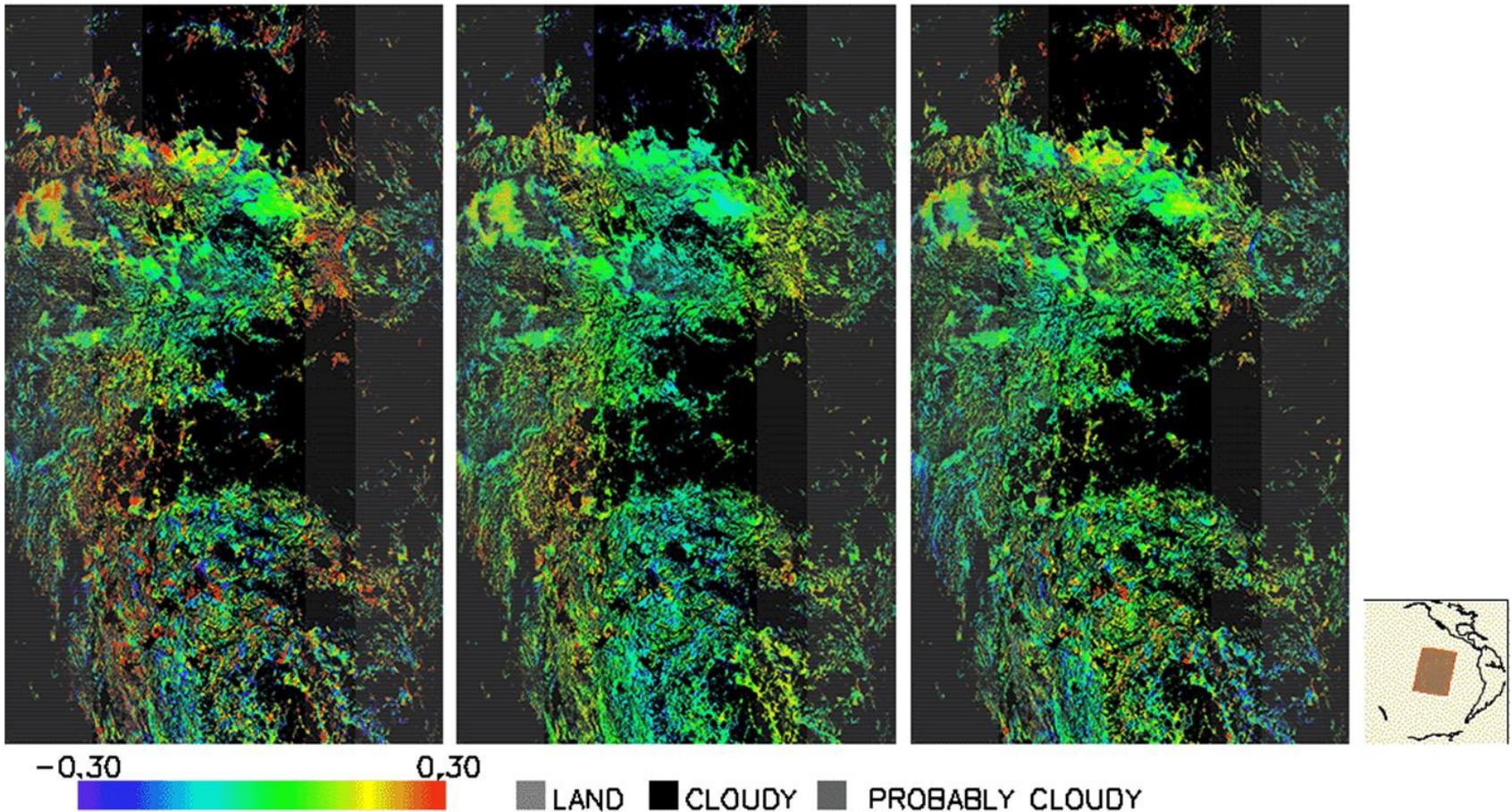


# The effect of the **nighttime** SSES bias correction (VIIRS, 19 December 2014)

Baseline SST – CMC

SSES Bias

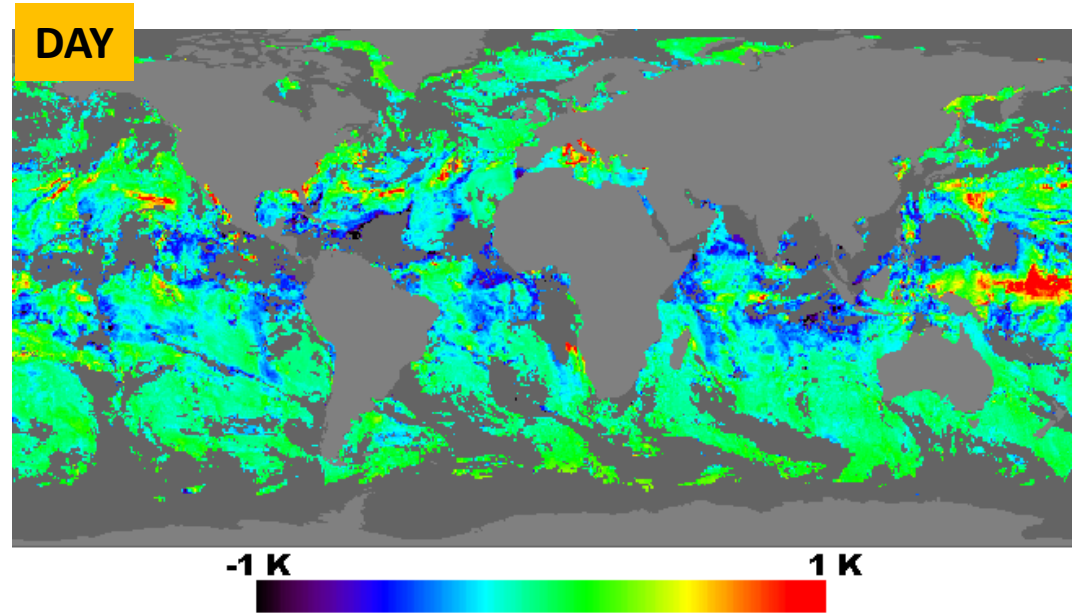
De-biased SST - CMC



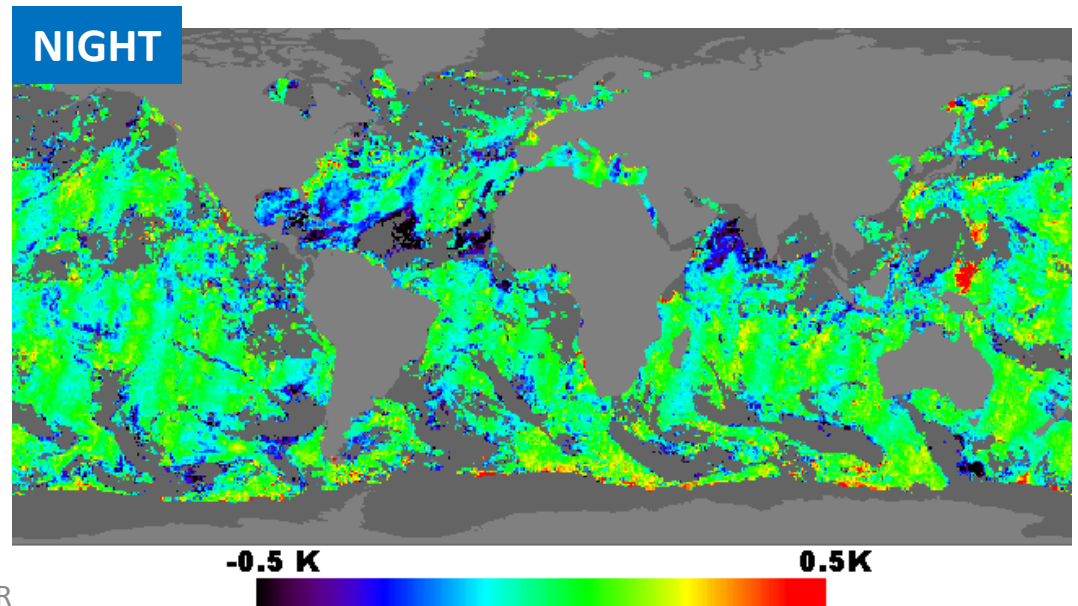
**Correction of SSES biases reduces the effects of VZA and cloud leakages**

# SSES Biases (VIIRS, 7 July 2015)

- Daytime SSES biases respond to diurnal surface warming, residual cloud, and VZA



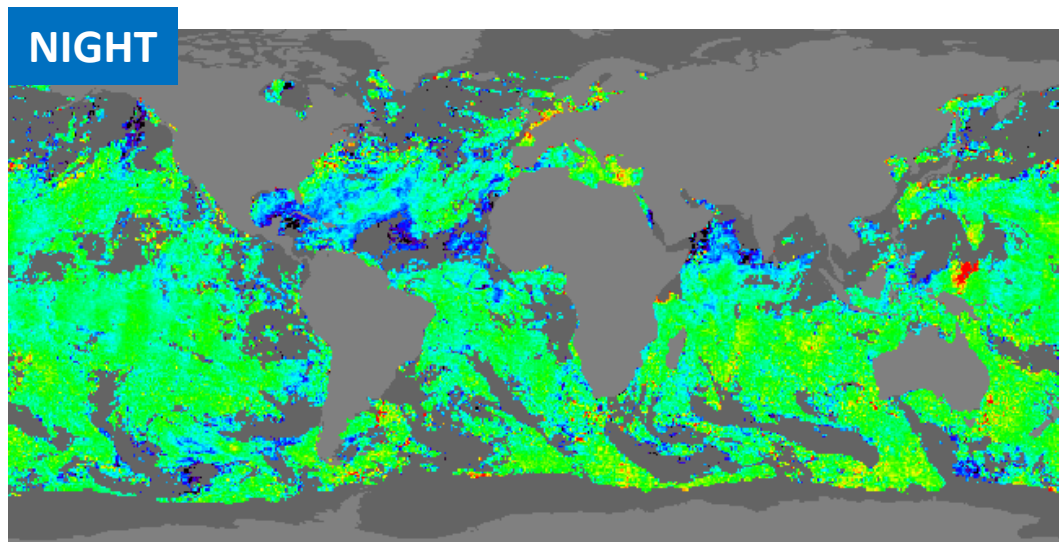
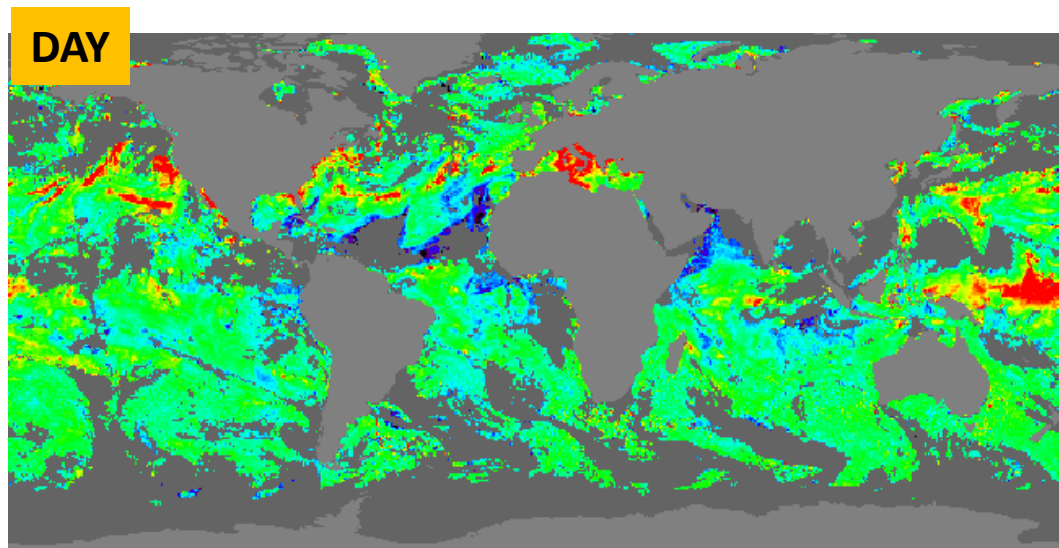
- Nighttime SSES biases mostly reflect the dependence on VZA and cloud leakages





# Baseline SST – CMC SST (VIIRS, 7 July 2015)

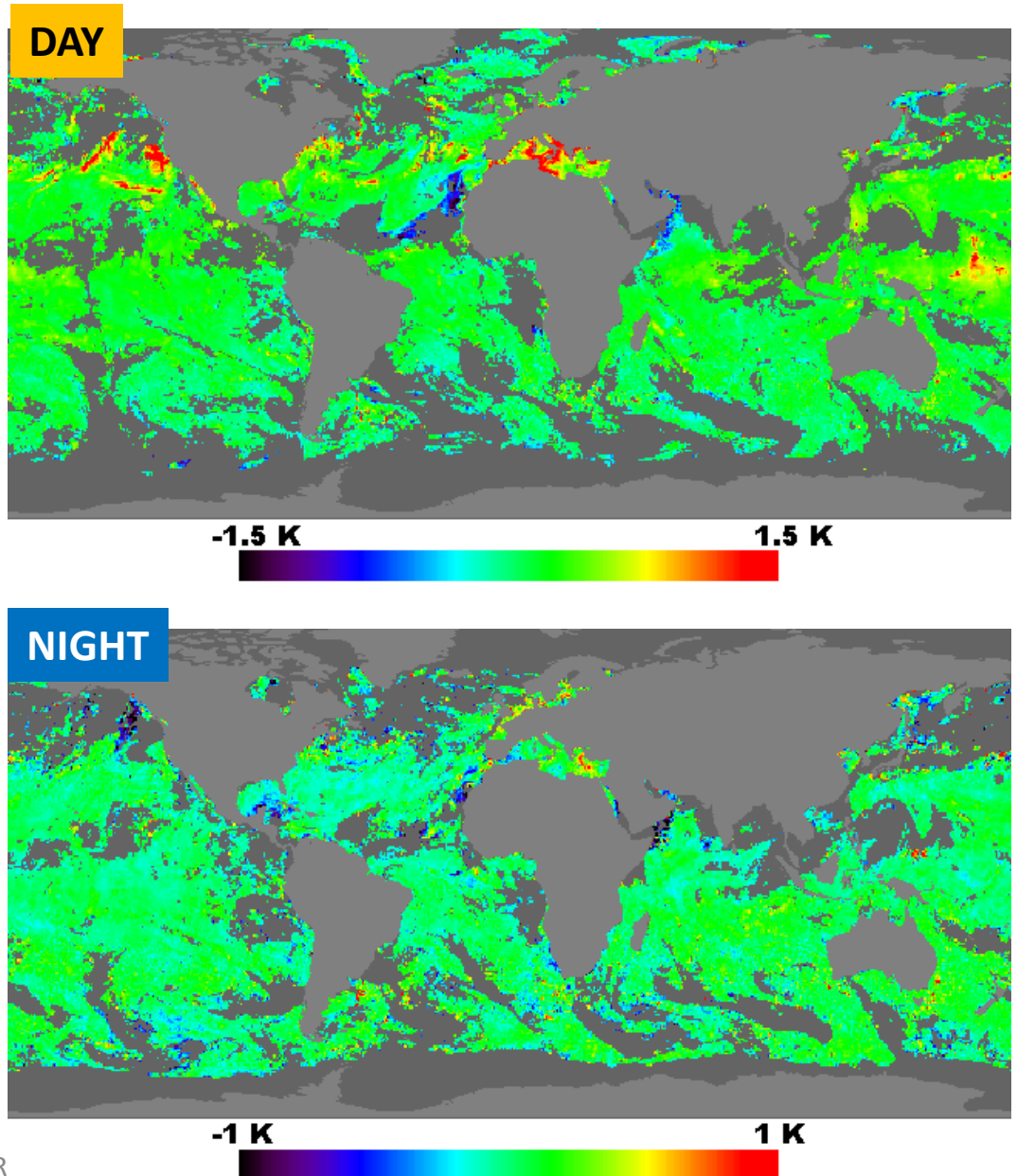
Deviations of Baseline SST from CMC are consistent with SSES biases



# De-biased SST – CMC SST (VIIRS, 7 July 2015)

SST	Bias	SD
Day		
Baseline	0.24 K	0.60 K
De-biased	0.24 K	0.42 K
Night		
Baseline	0.04 K	0.37 K
De-biased	0.24 K	0.30 K

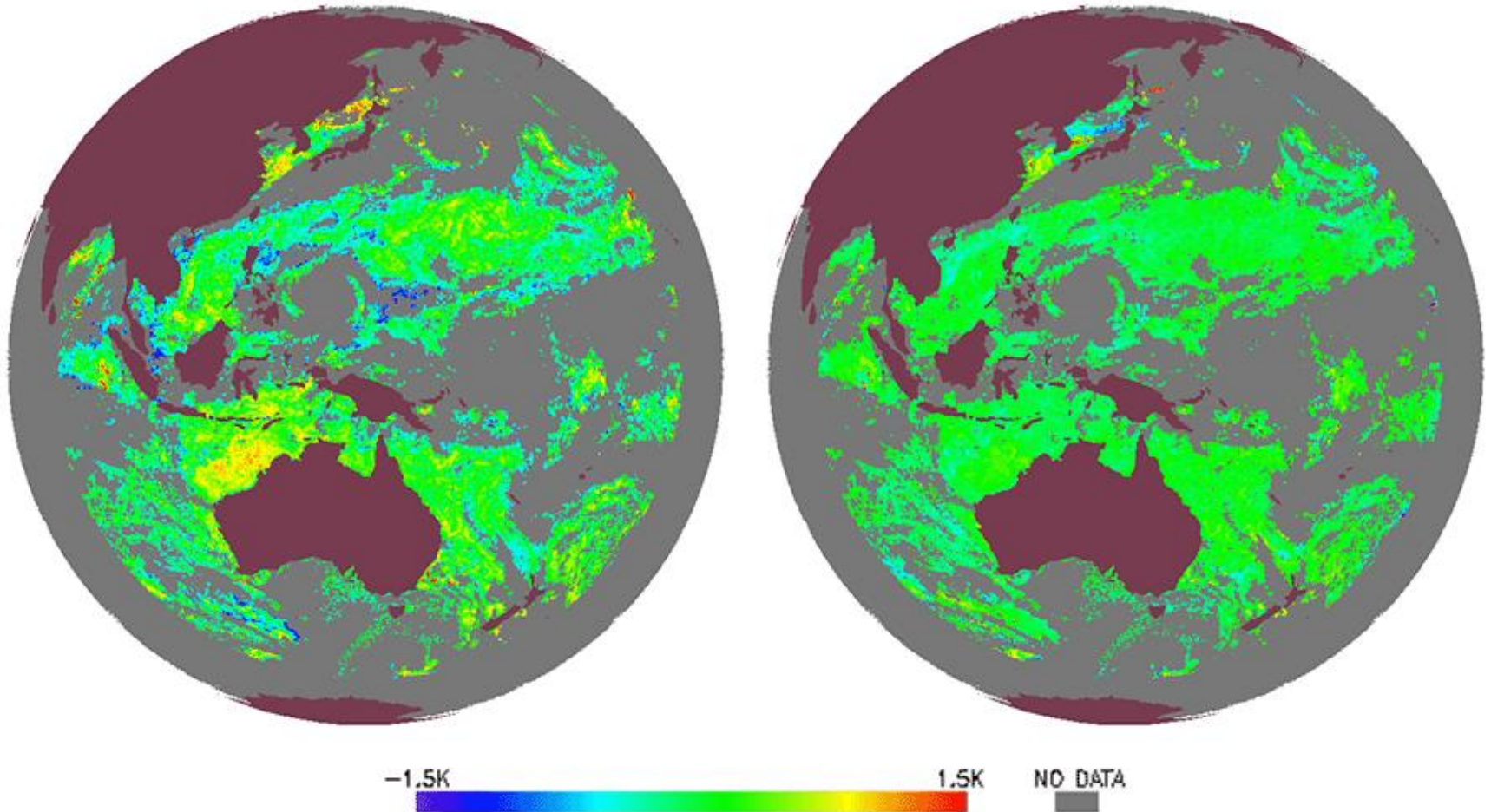
Bias correction improves consistency with CMC



# SST from HIMAWARI (launched on 7 October 2014) (Images for 6 May 2015, 23:20 – 23:30 am)

Baseline SST-CMC: Bias=0.16 K, SD=0.44 K

De-biased SST-CMC: Bias=0.06 K, SD=0.22 K



The statistics are estimated for VZA < 67°



# Comparison of the approaches to coefficients' stratification

The following algorithms are compared here:

ACSPO: Lavanant et al., 2012, Petrenko et al., 2014; Pathfinder: Kilpatrick et al., 2015; LATBAND: Minnett and Evans, 2009

Source	Algorithm	SD wrt <i>in situ</i> SST
Petrenko et al., JGR, 2014	Previous ACSPO*, <i>global coefficients</i>	0.47 K
	Pathfinder*, <i>coefficients depend on <math>T_{11} - T_{12}</math> (proxy of TPW)</i>	0.45 K
	LATBAND*, <i>coefficients depend on latitude</i>	0.45 K
	Current ACSPO**, <i>global coefficients</i>	0.42 K
This study	Current ACSPO**, <i>global coefficients</i>	0.41 K
	ACSPO PWR SST**, <i>coefficients depend on regressors</i>	0.31 K

\* The “classic” NLSST equation (Walton et al., 1998):

$$T_S = a_0 + a_1 T_{11} + a_3 T_S^0 (T_{11} - T_{12}) + a_3 S_{\vartheta} (T_{11} - T_{12})$$

\*\* The current ACSPO equation (proposed by the OSI-SAF):

$$T_S = a_0 + (a_1 + a_2 S_{\vartheta}) T_{11} + [a_3 + a_4 T_S^0 + a_5 S_{\vartheta}] (T_{11} - T_{12}) + a_6 S_{\vartheta}$$

**Stratification of coefficients in the space of regressors is more efficient than stratifications in terms of physical variables**

# Summary

- **The ACSPO v.2.40 offers two SST products:**
  - Baseline ACSPO SST: Sufficiently accurate wrt *in situ* SST & sensitive to SST<sub>skin</sub>
  - The De-biased ACSPO SST is substantially more precise wrt *in situ* SST (closer to SST<sub>depth</sub>)
- **Currently, the De-biased ACSPO SST is not reported as a separate layer in the ACSPO output. It can be obtained as “Baseline SST minus SSES bias”**
- **The SDs wrt *in situ* SST for the de-biased SST are close to CMC L4. However, it does not produce significant global biases.**
- **This suggests the following applications of the de-biased ACSPO SST:**
  - It may simplify the bias correction in the L4 analyses
  - Daytime de-biased ACSPO SSTs can be assimilated in L4 analyses, in addition to nighttime SSTs
  - A specific “daytime” L4 analyses can be produced
- **The ultimate test for the ACSPO SSES will be using it in the L4 analyses. Feedback from the L4 producers is strongly appreciated**

# Thank you