

Classical Mechanics

PH2213

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Spring 2021

Contents

1 Assignment 1

1.1 Solution 1

- **Virtual Displacement** is a infinitesimal small displacement consistant with the constraint relations at any given instant(i.e At frozen time.)
- With virtual displacement, we can account for the constraint relations as the work done by constraint forces is zero

Applying Newton's 2nd Law on system of particles(EQ 1):

$$\sum_i (\vec{F}_i - \dot{\vec{p}}) = 0$$

Where,

$$\vec{F}_i = F_i^{(a)} + \vec{f}_i$$

On solving EQ 1 and putting $\sum_i \vec{f}_i \cdot \delta \vec{r}_i = 0$,
We get **D' Alembert's** principle,

$$\sum_i (F_i^{(a)} - \dot{p}_i) \cdot \delta \vec{r}_i = 0$$

Which is independent of constraint forces hence its easier to work with this equation. Furthermore, we can derive **Lagrange equation** using the D' Alembert's relation.

Example 1.1. For a simple pendulum with variable length $l(t)$. The displacement of the pendulum and the tension are not perpendicular. For a virtual displacement δr consistant with $l(t)$ at time t . If time is frozen the virtual displacement is perpendicular to the string direction hence work done is 0.

1.2 Solution 2

No

Internal Forces don't do work.

- Since internal forces cause no displacement.
- Even if we consider above statement to be false, For rigid bodies,

$$\text{mod } (r_a - r_b) = \text{constant}$$

$$\text{mod } (r_a - r_b)^2 = \text{constant}$$

$$(r_a - r_b) \cdot \Delta(r_a - r_b) = 0$$

Using Newton's 3rd Law

$$F_{ab} = -F_{ba}$$

$$F_{ab} \cdot \Delta r_a = -F_{ba} \cdot \Delta r_b$$

$$\Delta W = \sum_{a,b,a \neq b} F_{ab} \cdot \Delta r_a = \sum_{a,b,b > a} (F_{ab} \cdot \Delta r_a + F_{ba} \cdot \Delta r_b) = \sum_{a,b,b > a} F_{ab} \cdot \Delta(r_a - r_b)$$

$$F_{ab} = C_{ab}(r_a - r_b)$$

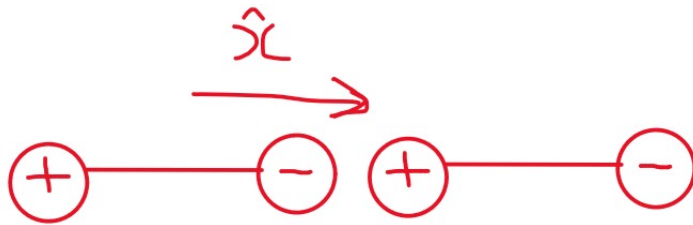
$$\Delta W = \sum_{a,b,b > a} C_{ab}(r_a - r_b) \cdot \Delta(r_a - r_b)$$

Thus Work done is 0.

1.3 Solution 3

- Newtonian Laws are only applicable for inertial frames of reference whereas Lagrange formalism is applicable to all frames.
- Newtonian Laws only work for Cartesian Coordinates whereas Lagrange equation can take any type of Coordinates.
- Its much easier to work with scalar quantities in Lagrange equation rather than vector quantities in Newtonian equations.
- In Newtonian formalism knowledge of all forces acting on the body is required whereas in Lagrangian formalism in Kinetic and potential Energy is required.
- It can be difficult to deal with constraints in Newton formalism.
- In newton formalism the quantity $p_1 + p_2 = m_1 v_1 + m_2 v_2$ is not a constant of motion for mutually attracting particles. In Lagrange formalism the definition of canonical momentum solves this.

1.4 Solution 4



Van der Waals force is a electrostatic dipole induced dipole force such that both dipoles have their axis aligned. According to Couloumb's Law all electrostatic forces are radial.

Using the approximation as in the figure above, all the forces are along the x direction therefore

$$\begin{aligned}\vec{F} &= k.\hat{x} \\ \tau &= \vec{r} \times \vec{F} \\ \tau &= (r.\hat{x}) \times (k.\hat{x}) \\ \tau &= 0\end{aligned}$$

Since torque is 0 it is a central force.