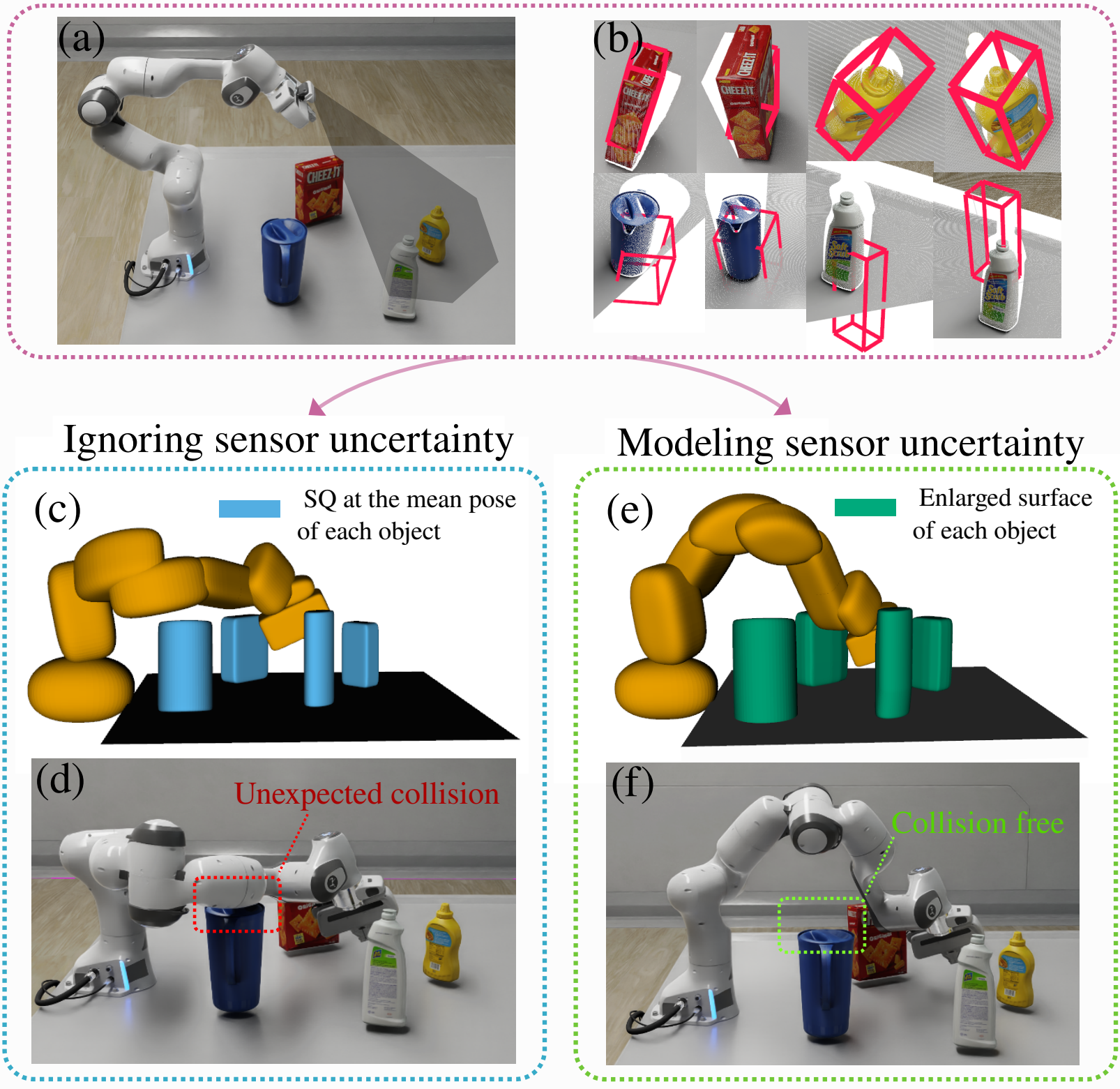
(a)
(b)
Ignoring sensor uncertainty
Modeling sensor uncertainty
(c)
SQ at the mean pose of each object
(e)
Enlarged surface of each object
(d)
Unexpected collision
(f)
Collision free