

# HIGHER DIPLOMA IN SOFTWARE ENGINEERING COURSEWORK

## Robotic Application Development

### DIY Fire Fighting Robot

<b>Module Name:</b>	Robotic Application Development
<b>Name of Lecturer:</b>	MR SUPUN
<b>Department:</b>	School of Computing
<b>Submission Due on:</b>	13 May 2024
<b>Type of Coursework:</b>	Group 15
<b>Title of the Coursework:</b>	DIY Fire Fighting Robot

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## DECLARATION

This project includes our course work of Robotic Application Development which is a module to higher diploma in software engineering course of NIBM and in this project we are going to design prototype DIY Fire Fighting Robot. This is the procedure of the course work that will be launched under Mr. Supun

## SUMMERY

This project centers on building a basic, functional fire-fighting robot accessible to DIY enthusiasts. Using a Raspberry Pi and LiDAR sensor, the robot will detect where the fire is and put it out. The goal is to emphasize learning and create a clear guide for others with an interest in robotics.

## CONTENT

- Introduction/ Nature of the project

The project aims to construct a basic firefighting robot. By utilizing accessible components such as L298 Motor driver and Flame sensors, we intend to demonstrate how simple, and effective firefighting solution can be created at home.

- **Technology**
  - Motors and Wheels: To make the robot move.
  - Simple Fire Fighting Mechanism: A water tank and pipes in a small container
  - Programming Language: C++ and java

## **Use Components**

- Arduion UNO
- Flame sensors
- hardboard sheets
- BO motors
- L298 Motor driver
- Solder-less Breadboard
- Mini servo
- 5-9v Water pump+pipe
- Water tank/bottle
- 3.7V batteries
- Jumper wires
- TIP-122 Transistor
- 104 uf capacitor
- 1K Resistor

## **Expected outcomes of the project**

Our primary result is that the robot detects the road, avoids the obstacles and puts out the fire.

## Budget of the project

<i>Item</i>	<i>Prices</i>
1. Arduion UNO	RS.8000
2. Flame sensors 3	RS.600
3. Hardboard sheets	RS.670
4. BO motors	RS.1290
5. L298 Motor driver	RS.670
6. Solder-less Breadboard	RS.230
7. Mini servo	RS.670
8. 5-9v Water pump+pipe	RS.1290
9. Jumper wires	RS.300
10. TIP-122 Transistor	RS.70
11. 104 uf capacitor	RS.4
12. 1K Resistor	RS.50
<b>Total</b>	<b>13,844</b>

## Duration of the Project

