## **Automated Plant Monitoring System**

**Project Link:** <u>https://www.tinkercad.com/things/ceAi1nKXu0K-automated-plant-monitoring-</u>

system/editel?sharecode=rgwVsS1XrUjyFUtUctixGo42I3wfsaxWC43PrMFEEl4

## Code:

```
#include <LiquidCrystal.h>
const int buzzer = 8;
int echopin = 10;
int trigpin = 9;
int mesafe;
int sure;
const int LM35 = A0;
const int motor = 13;
const int LedRed = 12;
const int LedGreen = 11;
LiquidCrystal lcd(2, 3, 4, 5, 6, 7);
void setup() {
 Serial.begin(9600);
 lcd.begin(16, 2);
```

```
lcd.print("Automated Plant");
 lcd.setCursor(0,1);
 lcd.print("Monitoring System!");
 pinMode(motor, OUTPUT);
 pinMode(LedRed, OUTPUT);
 pinMode(LedGreen, OUTPUT);
 delay(2000);
 lcd.clear();
 lcd.print("Temp= ");
 lcd.setCursor(0,1);
 lcd.print("WaterPump= ");
 pinMode(buzzer, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
void loop() {
 int value = analogRead(LM35);
 float Temperature = value * 500.0 / 1023.0;
 lcd.setCursor(6,0);
 lcd.print(Temperature);
 lcd.setCursor(11,1);
```

```
if (Temperature > 30)
 digitalWrite(motor, HIGH);
 digitalWrite(LedRed, HIGH);
 digitalWrite(LedGreen, LOW);
 lcd.print("ON ");
else {
 digitalWrite(motor, LOW);
 digitalWrite(LedRed, LOW);
 digitalWrite(LedGreen, HIGH);
 lcd.print("OFF");
 delay(1000);
digitalWrite(trigpin,LOW);
delayMicroseconds(2);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
sure = pulseIn(echopin,HIGH);
mesafe = (sure/2)/29.0;
if(mesafe <= 15)
digitalWrite(buzzer,HIGH);
```

```
delay(250);
digitalWrite(buzzer,LOW);
delay(125);
else if(mesafe <= 20)
digitalWrite(buzzer,HIGH);
delay(500);
digitalWrite(buzzer,LOW);
delay(250);
else if(mesafe <= 30)
digitalWrite(buzzer,HIGH);
delay(1000);
digitalWrite(buzzer,LOW);
delay(1000);
}
else
digitalWrite(buzzer,LOW);
delay(500);
```

## Circuit:

