

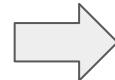
UrbanMandscape: Bridging the Subjective and Objective Perception in Proximate Sensing

Keywords: Urban Perception; Semantic Segmentation; Street View Images; Convolutional Neural Network (CNN); Deep Learning

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BACKGROUND

Street View
Images(SVI) have
been a valuable
resource in
different contexts.



Urban Analysis of the Built Environment

Infrastructure Management

Environmental Monitoring

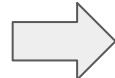
Real Estate and Property Management

Public Safety and Security

Social and Economic Research

BACKGROUND

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Urban Analysis of the Built Environment

Create visual representations of human perceptions and the physical characteristics of urban environments by leveraging deep learning techniques.

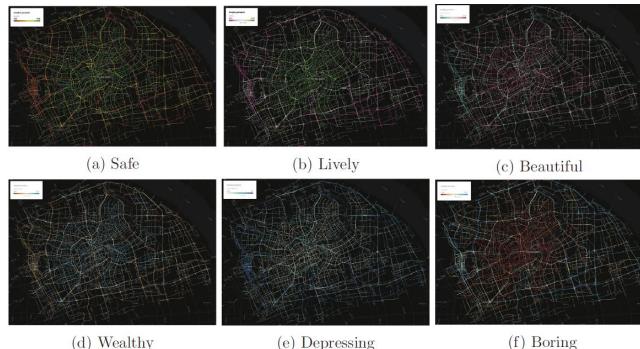
Objective

Subjective

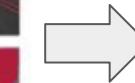
A comprehensive understanding
of urban spaces

Background

Subjective



Objective



Urban
Perception

Human Perception Score

Proximate Sensing

Background

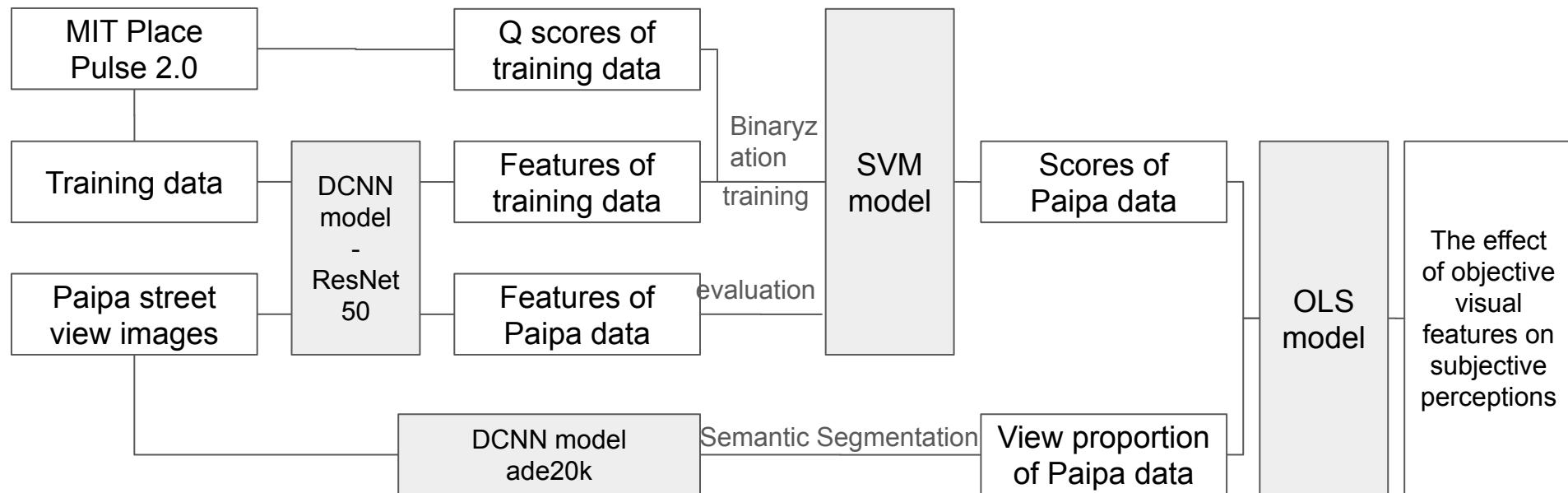
MIT Place Pulse 2.0

| Continent | #Cities | #Images |
|---------------|---------|---------|
| Asia | 7 | 11,342 |
| Africa | 3 | 5,069 |
| Australia | 2 | 6,082 |
| Europe | 22 | 38,636 |
| North America | 15 | 33,691 |
| South America | 7 | 16,168 |
| Total | 56 | 110,988 |

The user interface of the MIT Place Pulse data collection platform. Participants are asked to choose one of the two images in response to one of the six questions. Millions of human perception responses for the images have been collected.



Methods



Experiment

Study Area:

Train: MIT Place Pulse 2.0 dataset

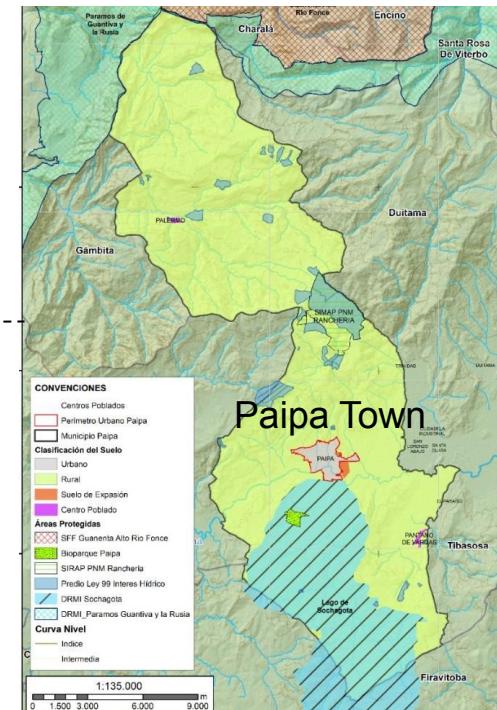
Test: Paipa Town, Colombia

Dataset:

MIT Place Pulse 2.0 street view images across the world

MIT Place Pulse 2.0 Q scores of SVI in six human perceptions

Paipa street view images(10m distance)

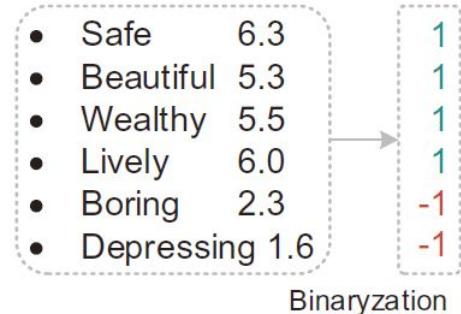


Experiment

To avoid introducing noise and error as much as possible, I followed the paper reference here and selected representative positive/negative samples from the whole dataset to use for the training task.

Zhang, F., Zhou, B., Liu, L., Liu, Y., Fung, H.H., Lin, H., Ratti, C., 2018. Measuring human perceptions of a large-scale urban region using machine learning. *Landscape and Urban Planning* 180, 148–160. <https://doi.org/10.1016/j.landurbplan.2018.08.020>

$$y_i^v = \begin{cases} -1 & \text{if } Q_i^v < \mu_v - \delta\sigma_v \\ 1 & \text{if } Q_i^v > \mu_v + \delta\sigma_v \end{cases}$$



| | location_id | Q | trueSkill.stds.-1 | study_question | image_id | features | Q_label |
|-------|--------------------------|-----------|-------------------|----------------|--------------------------|---|---------|
| 0 | 513e6df2fdc9f0358700c383 | 20.592330 | 3.056702 | safer | 513e6df2fdc9f0358700c383 | [0.22940833866596222, 1.0244624614715576, 0.01... | -1.0 |
| 4 | 5140cc3efdc9f04926002d59 | 28.707450 | 2.886764 | safer | 5140cc3efdc9f04926002d59 | [0.12468238919973373, 0.5190224647521973, 0.04... | 1.0 |
| 5 | 50f5ec0dfdc9f065f0008640 | 20.298309 | 4.895043 | safer | 50f5ec0dfdc9f065f0008640 | [0.06582643836736679, 0.41787010431289673, 0.0... | -1.0 |
| 6 | 50f60121beb2fed6f80001b8 | 18.482701 | 4.151866 | safer | 50f60121beb2fed6f80001b8 | [0.34781795740127563, 0.6622889041900635, 0.12... | -1.0 |
| 8 | 5142183ffdc9f04926008100 | 27.814428 | 5.197565 | safer | 5142183ffdc9f04926008100 | [0.12155959755182266, 0.771874725818634, 0.020... | 1.0 |
| ... | ... | ... | ... | ... | ... | ... | ... |
| 19993 | 50f5e70dfdc9f065f0007031 | 28.091575 | 3.007945 | safer | 50f5e70dfdc9f065f0007031 | [0.4073934257030487, 0.5427781343460083, 0.159... | 1.0 |
| 19995 | 50f439edfdc9f065f0002d42 | 16.917069 | 2.759283 | safer | 50f439edfdc9f065f0002d42 | [0.2706283926963806, 0.8877367377281189, 0.329... | -1.0 |
| 19996 | 50f42eabfdc9f065f00022d3 | 33.181343 | 2.884191 | safer | 50f42eabfdc9f065f00022d3 | [0.21051648259162903, 1.1483752727508545, 0.06... | 1.0 |
| 19997 | 5140cc37fdc9f04926002d47 | 20.803571 | 2.217072 | safer | 5140cc37fdc9f04926002d47 | [0.057956207543611526, 0.8228529095649719, 0.0... | -1.0 |
| 19999 | 513d5787fdc9f0358700319e | 20.646238 | 2.397467 | safer | 513d5787fdc9f0358700319e | [0.3766400218009949, 1.0521074533462524, 0.068... | -1.0 |

10922 rows × 7 columns

| Background | Method | Result: Human Perception - Semantic Segmentation | Conclusion |
|------------|--------|--|------------|
|------------|--------|--|------------|

Street Perception Analysis: Subjective Perceptions

Which place looks safer ?

Which place looks **safer**?

Which place looks **livelier**?

Which place looks **more boring**?

Which place looks **wealthier**?

Which place looks **more depressing**?

Which place looks **more beautiful**?



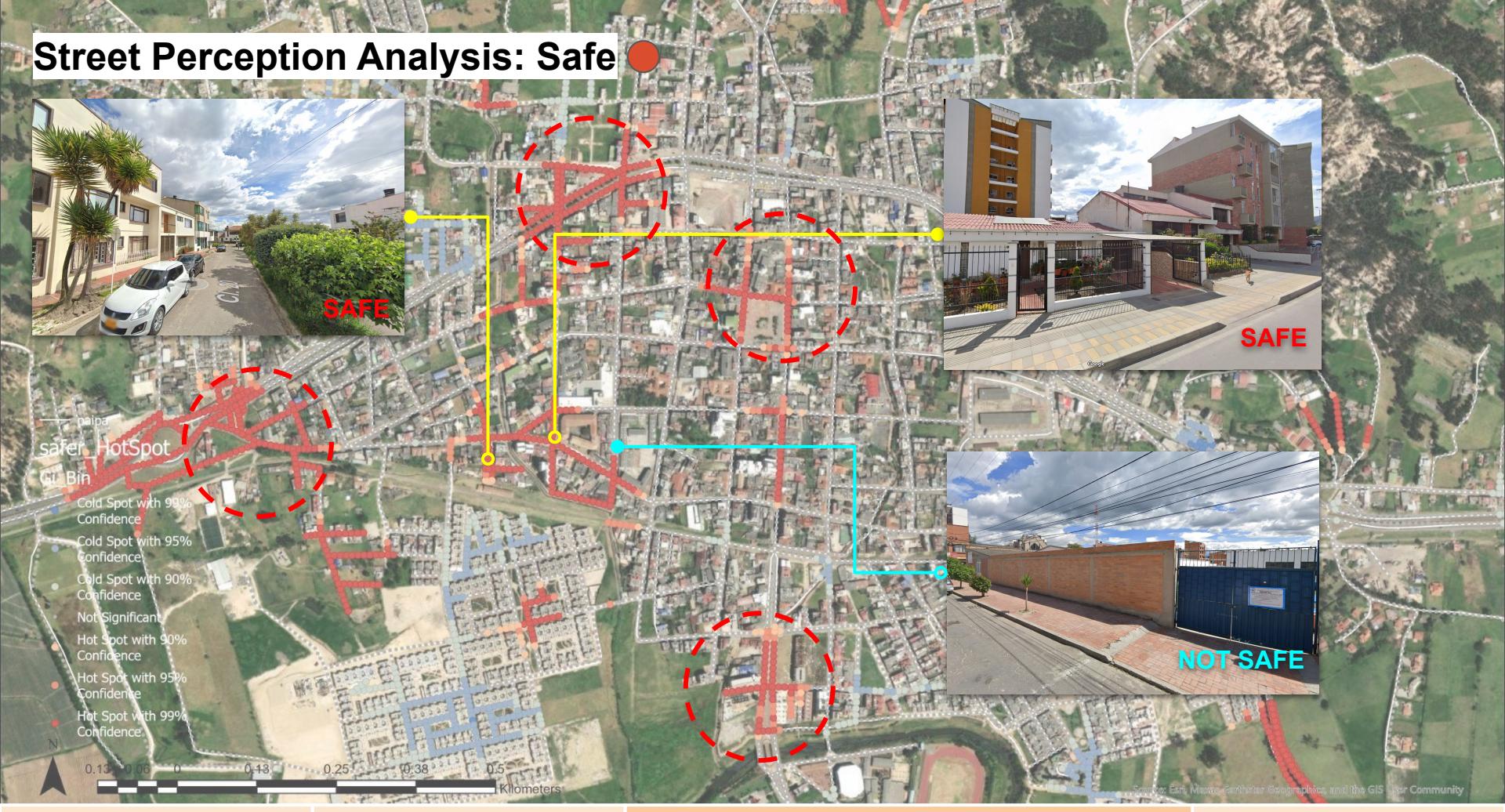
Training data: 110,988 samples from 56 cities

Dubey, A., Naik, N., Parikh, D., Raskar, R., & Hidalgo, C. A. (2016). Deep learning the city: Quantifying urban perception at a global scale. European conference on computer vision (pp. 196–212). Springer.

Testing data: 15,000 samples in Paipa

This model answers question:
**Is this place safe/ lively/ beautiful/
wealthy/ boring/ depressing?**

Street Perception Analysis: Safe



Background

Method

Result: Human Perception - Semantic Segmentation

Conclusion

Street Perception Analysis: Wealthy



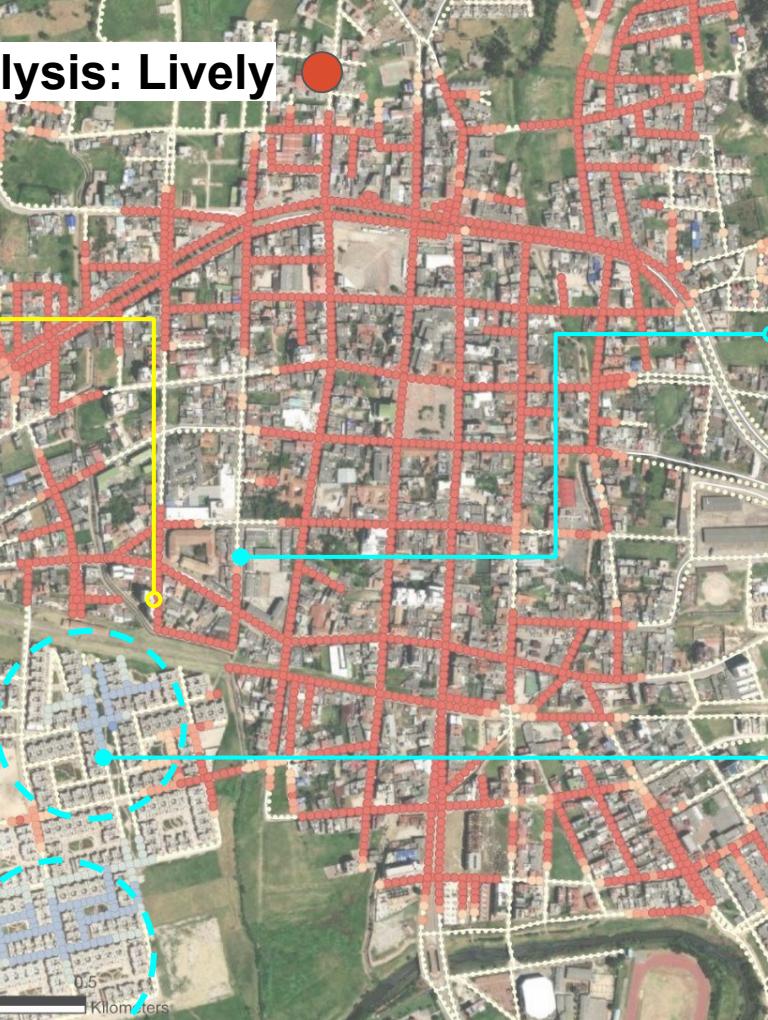
Background

Method

Result: Human Perception - Semantic Segmentation

Conclusion

Street Perception Analysis: Lively



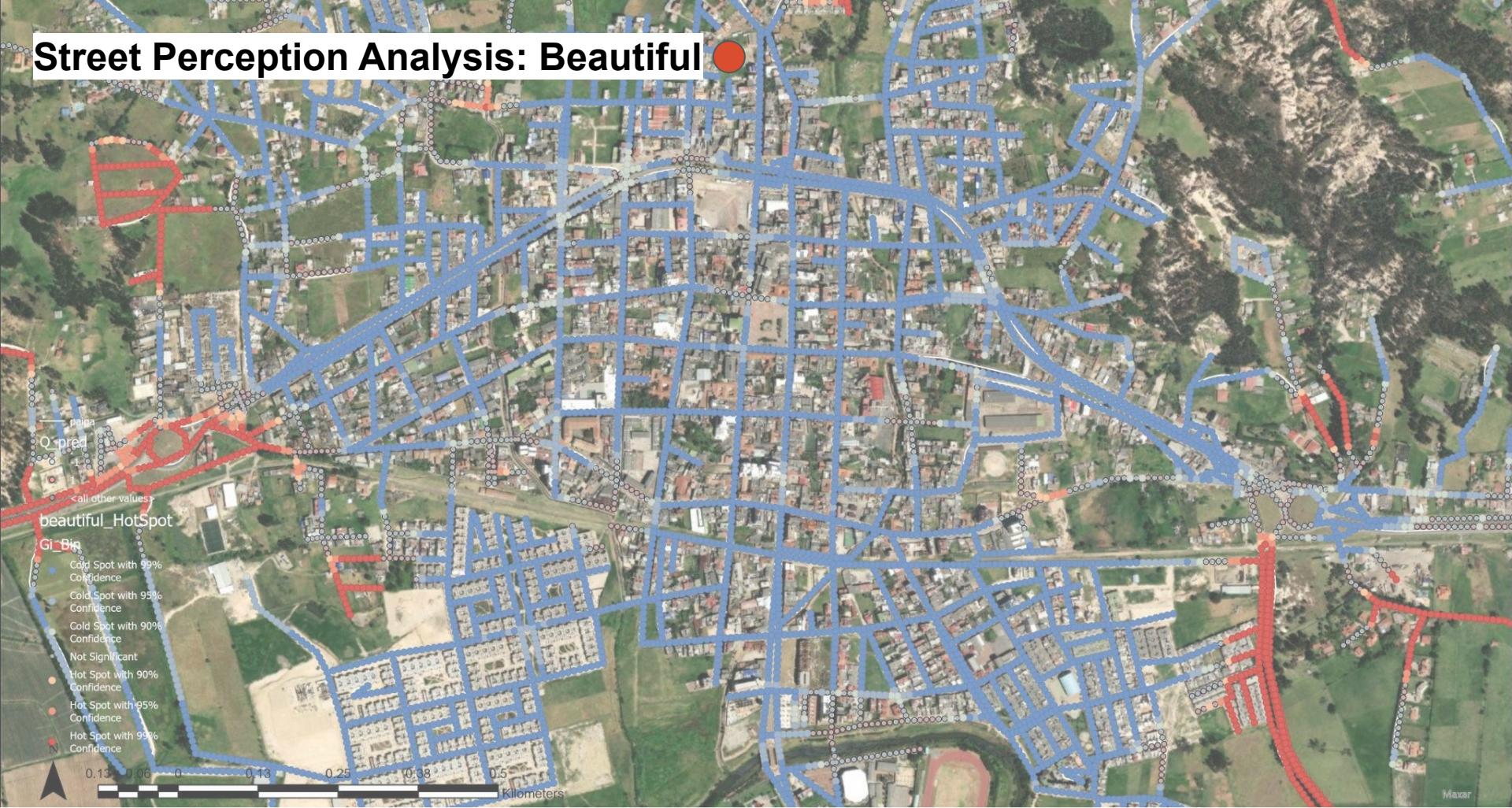
Background

Method

Result: Human Perception - Semantic Segmentation

Conclusion

Street Perception Analysis: Beautiful



Background

Method

Result: Human Perception - Semantic Segmentation

Conclusion

Street Perception Analysis: Boring



Summer East, Miami, Earthstar Geographics, and the GIS for Community

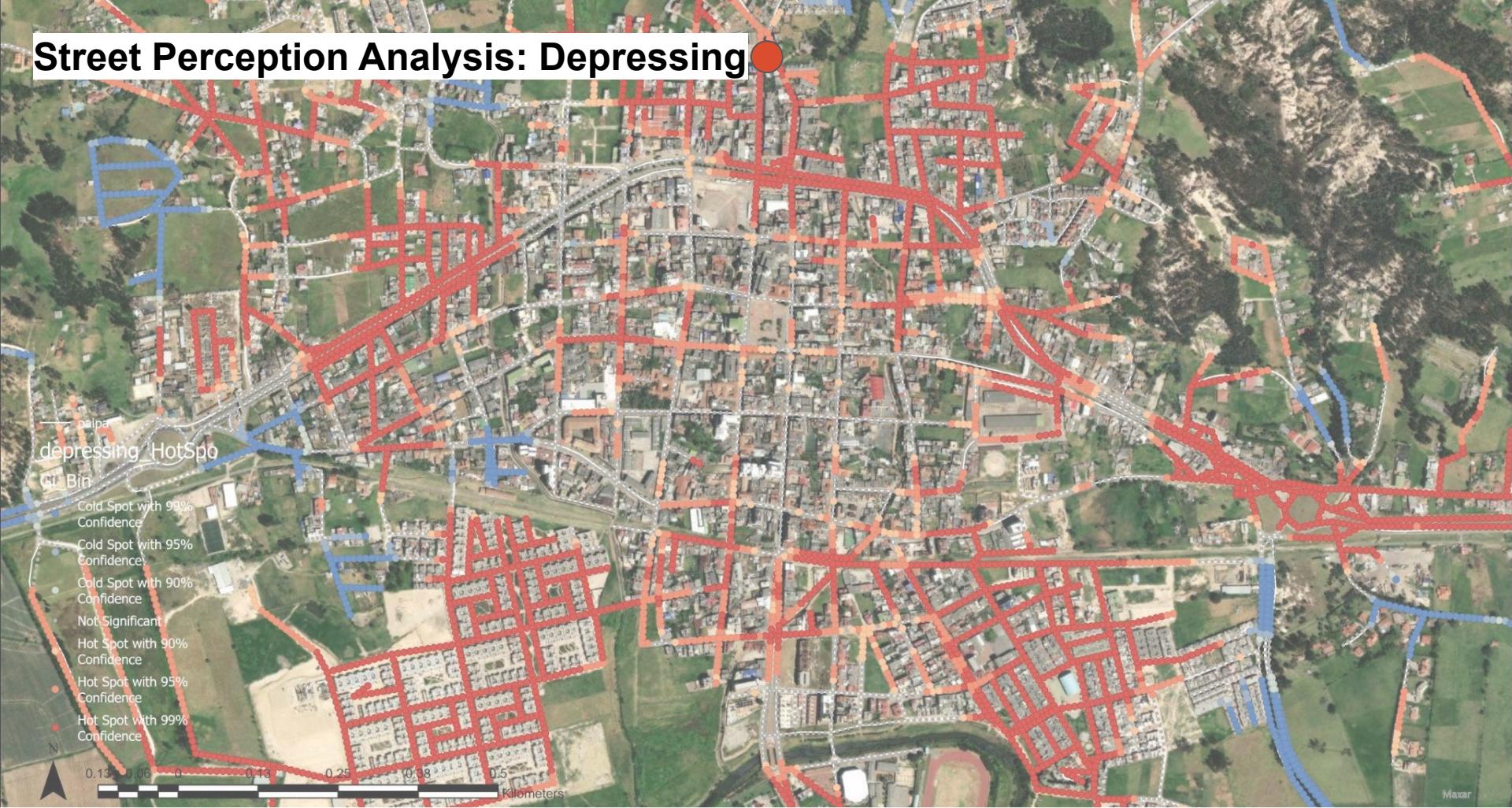
Background

Method

Result: Human Perception - Semantic Segmentation

Conclusion

Street Perception Analysis: Depressing



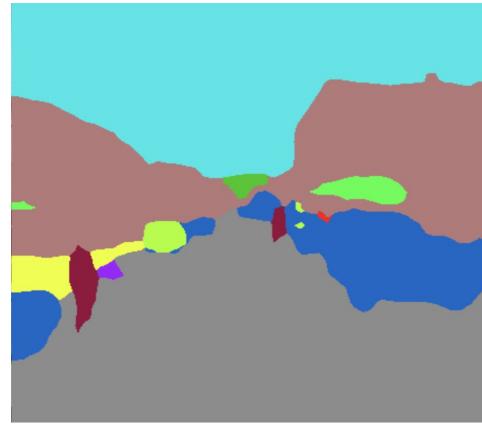
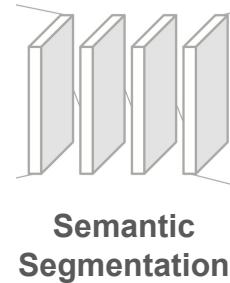
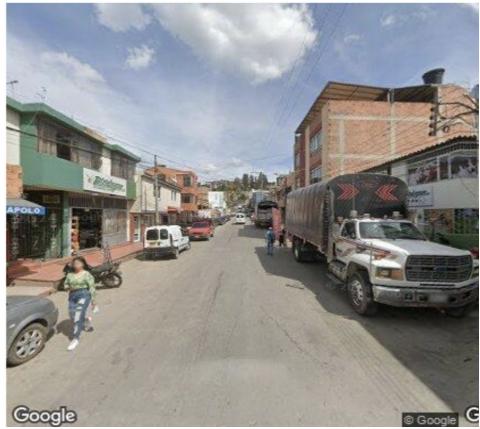
Background

Method

Result: Human Perception - Semantic Segmentation

Conclusion

Street Perception Analysis: Objective Perception



- wall 0.0013
- building 0.1071
- sky 0.1700
- tree 0.2843
- road 0.2251
- grass 0.1020
- sidewalk 0.0033
- plant 0.0001
- car 0.0973
- sign 0.0035
- stairs 0.0002
- van 0.0058



What percentage of the vision is building/car/tree/sky/road...?

Street Perception Analysis: Objective Perception

Classes related to urban space

| Idx | Name |
|-----|--|
| 1 | wall |
| 2 | building;edifice |
| 3 | sky |
| 4 | floor;flooring |
| 5 | tree |
| 7 | road;route |
| 9 | windowpane;window |
| 10 | grass |
| 12 | sidewalk;pavement |
| 13 | person;individual;someone;somebody;mortal;soul |
| 18 | plant;flora;plant;life |
| 21 | car;auto;automobile;machine;motorcar |
| 26 | house |
| 44 | signboard;sign |
| 54 | stairs;steps |
| 103 | van |



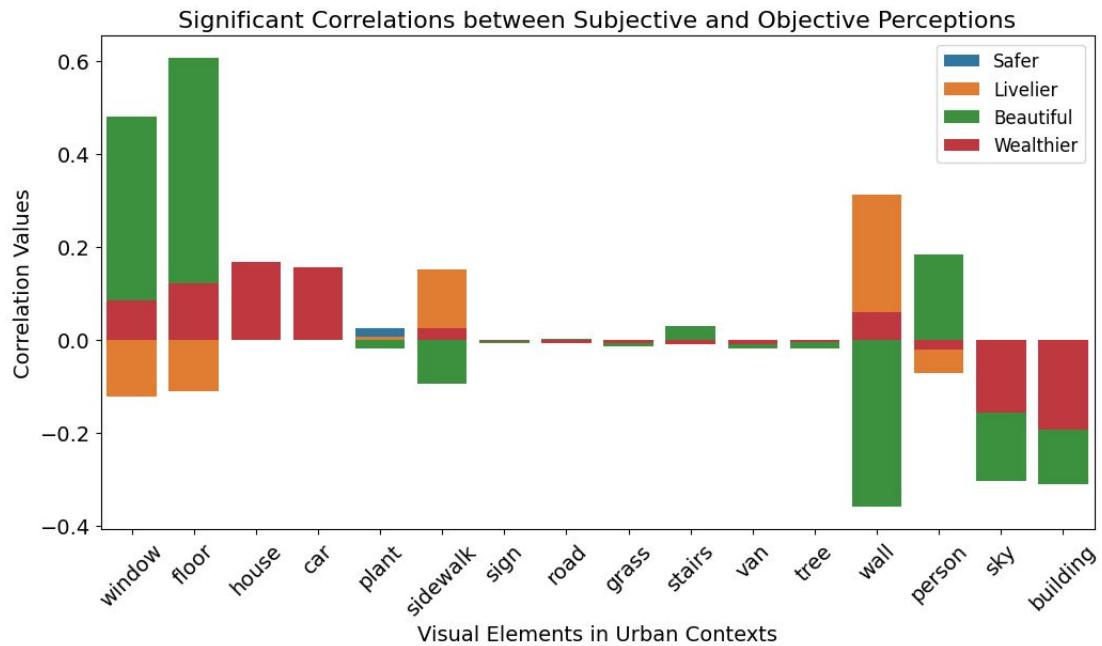
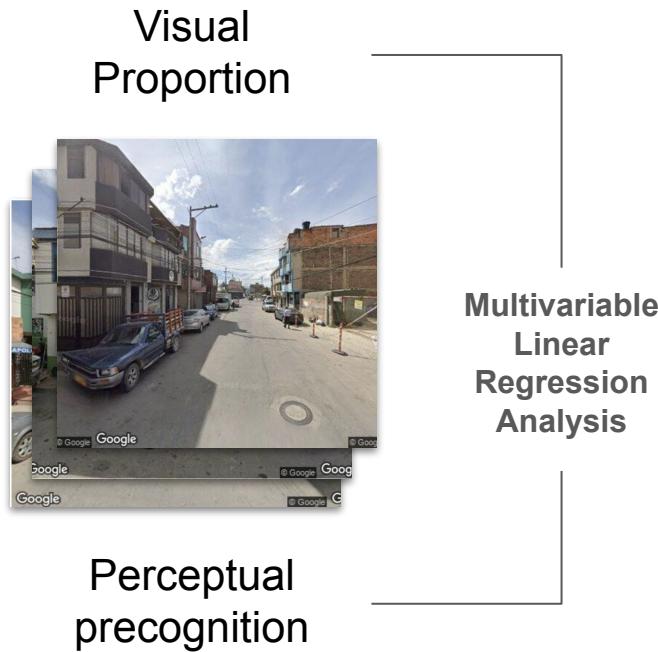
Background

Method

Result: Human Perception - Semantic Segmentation

Conclusion

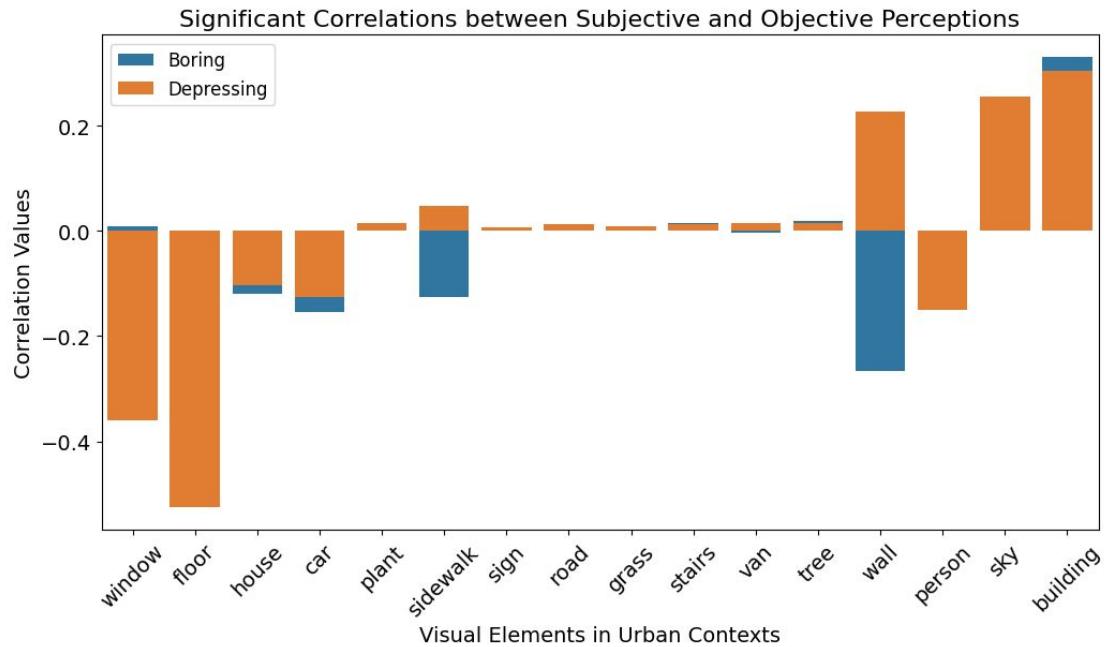
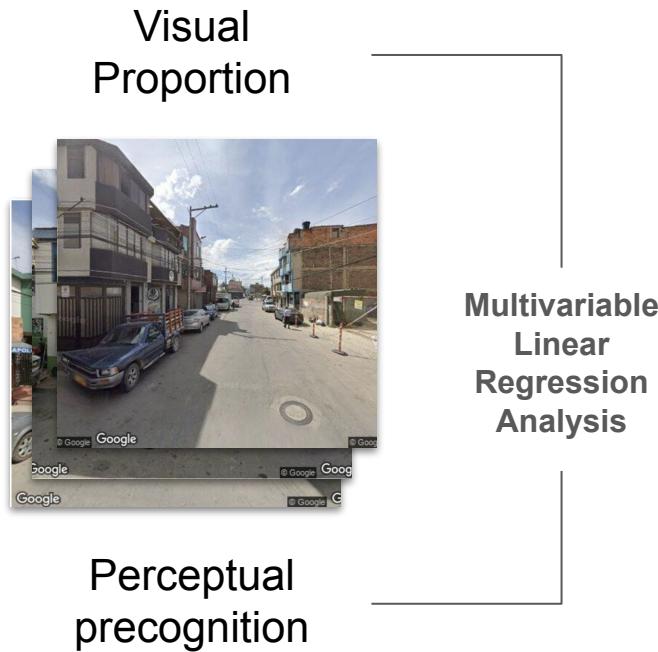
Street Perception Analysis: Objective Perception



How does the proportion of building/car/tree/sky/road affect the feeling of safe/ lively/ beautiful/ wealthy/ boring/ depressing.

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Street Perception Analysis: Objective Perception



How does the proportion of building/car/tree/sky/road affect the feeling of safe/ lively/ beautiful/ wealthy/ boring/ depressing.

Street Perception Analysis: Design Solution Guidelines

Unsafe places

- Enhancing green space
-

Unbeautiful places

- Increasing open public spaces
-

Unlively places

- Building Complete Streets
-

Low-value places

- Promoting quality housing
-

Boring places

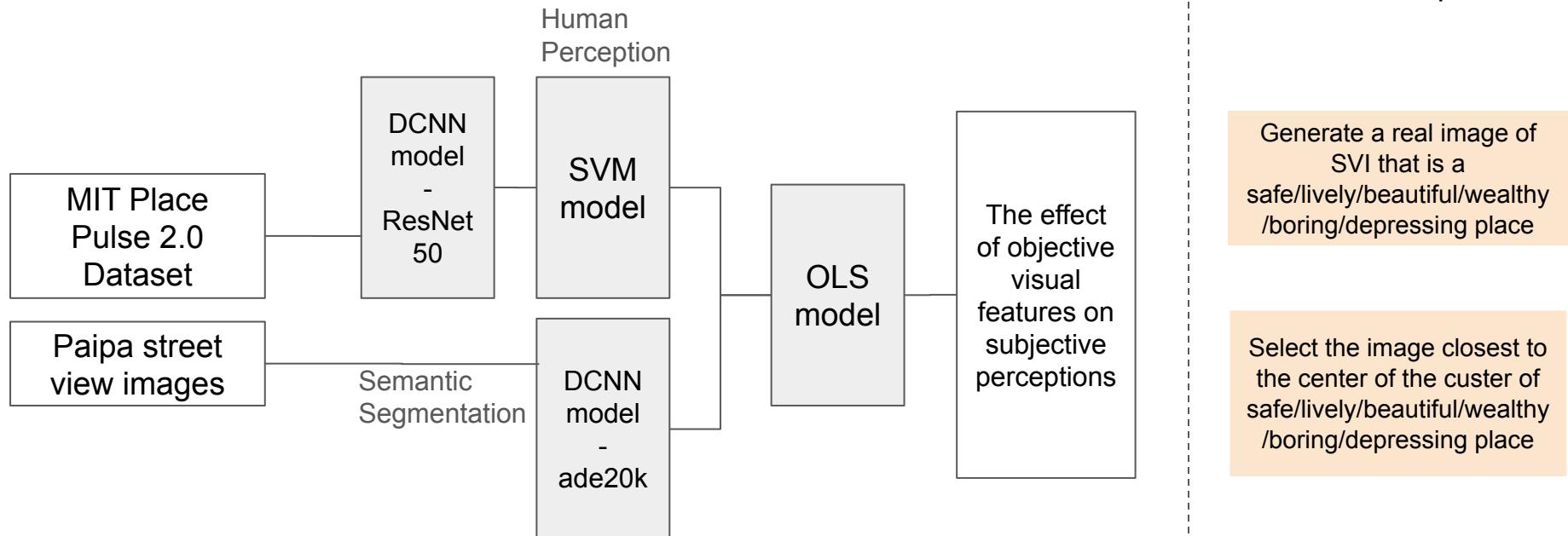
- Enhancing street walkability
-

Depressing places

- Reducing enclosed spaces

Conclusion

Next Step



Generate a real image of SVI that is a safe/lively/beautiful/wealthy /boring/depressing place

Select the image closest to the center of the cluster of safe/lively/beautiful/wealthy /boring/depressing place