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## Introduction to machine learning

### **Lecture #11 : Python programming for ANN – 1**





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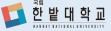
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## **Contents**

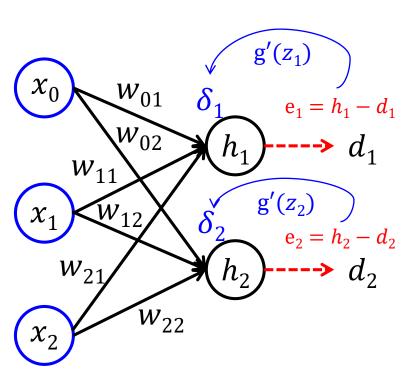
1

**Lecture #10 Review** 



### Weight update (training) summary

Neural networks also use gradient descent for parameter (weight) update.



 $d_1$ ,  $d_2$ : desired values

$$\begin{split} w_{jk} &= w_{jk} - \alpha \frac{\partial J(w_{01}, w_{02}, w_{11}, w_{12}, w_{21}, w_{22})}{\partial w_{jk}} \\ &= w_{jk} - \alpha \frac{\partial J}{\partial w_{jk}} \text{, } \alpha = \text{learning rate} \end{split}$$

$$\frac{\partial J}{\partial w_{jk}} = \frac{\partial J}{\partial h_k} \frac{\partial h_k}{\partial z_k} \frac{\partial z_k}{\partial w_{jk}} = (h_k - d_k) h_k (1 - h_k) x_j$$

$$= e_k g(z_k) (1 - g(z_k)) x_j$$

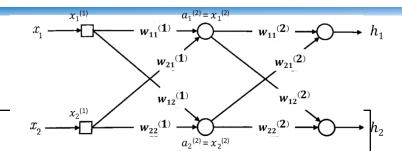
$$= e_k g'(z_k) x_j = \delta_k x_j$$

$$\rightarrow w_{jk} = w_{jk} - \alpha \frac{\partial J}{\partial w_{jk}} = w_{jk} - \alpha \delta_k x_j$$

(this is called as the delta rule.)

### Process of the weight update in multi-layer ANN





- 1) Initialize the weight values properly
- 2) By entering the feature values of the training data into the neural network and feeding forward, obtain the output value h (this process is also called inference)

$$z^{(2)} = x^{(1)} \cdot w^{(1)}$$
  $x^{(2)} = g(z^{(2)})$   
 $z^{(3)} = x^{(2)} \cdot w^{(2)}$   $x^{(3)} = g(z^{(3)}) = h$ 

3) Calculate the error at the output layer

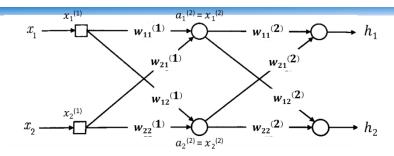
$$e^{(3)} = h - d$$

4) Conduct back propagation to calculate delta at the hidden layer.

$$e^{(3)} = h - d$$
,  $\delta^{(3)} = e^{(3)} * g'(z^{(3)})$   
 $e^{(2)} = \delta^{(3)} \cdot (w^{(2)})^T$ ,  $\delta^{(2)} = e^{(2)} * g'(z^{(2)})$ 

## 다층신경망의 가중치 학습 – process





5) Calculate the amount of weight update based on the delta values.

$$\Delta w^{(2)} = -\alpha (x^{(2)})^T \cdot \delta^{(3)}$$
  

$$\Delta w^{(1)} = -\alpha (x^{(1)})^T \cdot \delta^{(2)}$$

6) Update the weights.

$$w^{(2)} = w^{(2)+} \Delta w^{(2)}$$
  
$$w^{(1)} = w^{(1)+} \Delta w^{(1)}$$

- 1) 7) Repeat the above 1-6 for the entire training data (1 epoch)
- 1) 8) Repeat the above epoch until the error becomes sufficiently small.

Even if the number of hidden layers increases, the overall concept is the same.



### Different cost function (cross entropy)

- It doesn't change the process much.
- Only the method for obtaining delta at the output layer changes.
- 1) Initialize the weight values properly
- 2) By entering the feature values of the training data into the neural network and feeding forward, obtain the output value h (this process is also called inference)

$$z^{(1)} = x^{(1)} \cdot w^{(1)}$$
  $x^{(2)} = g(z^{(1)})$   
 $z^{(2)} = x^{(2)} \cdot w^{(2)}$   $x^{(3)} = g(z^{(2)}) = h$ 

3) Calculate the error at the output layer

$$e^{(3)} = h - d$$

4) Conduct back propagation to calculate delta at the hidden layer.

$$e^{(3)} = h - d$$
,  $\delta^{(3)} = e^{(3)}$   
 $e^{(2)} = \delta^{(3)} \cdot (w^{(2)})^T$ ,  $\delta^{(2)} = e^{(2)} * g'(z^{(2)})$ 

### **Contents**

2 Simple programming (XOR)



 XOR
 Input 1
 Input 2

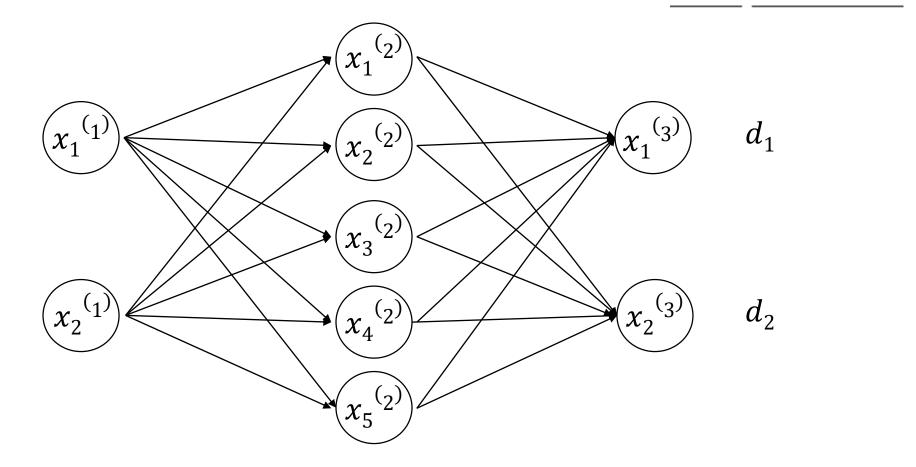
 0
 1
 1

 1
 1
 0

 1
 0
 1

 0
 0
 0

Let's make the ANN with the 5 neurons in the hidden layer.
(there is no bias)



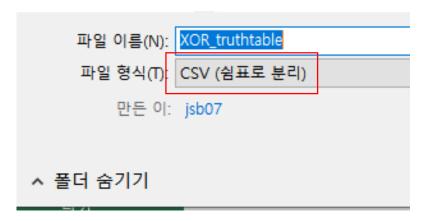


#### 1. Dataset preparation

XOR	Input 1	Input 2
0	1	1
1	1	0
1	0	1
0	0	0

0	1	1
1	1	0
0	1	1
0	0	0

Excel → save as CSV format



CSV: comma-separated values 0,1,1

→ If we open the file with notepad, it will be displayed as the picture on the rieght. 0,1,1

0	1	1
1	1	0
0	1	1
0	0	0

### **2.** Data Reading

```
import numpy as np

training_data_file = open('C:/Users/jsb07/.spyder-py3/XOR_truthtable.csv', 'r')
training_data_list = training_data_file.readlines()
training_data_file.close()

print (training_data_list)
```

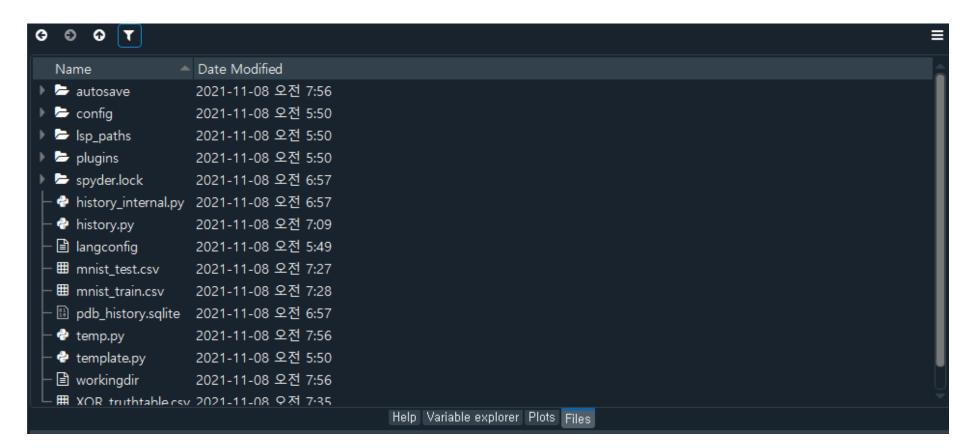
```
['0,1,1\n', '1,1,0\n', '0,1,1\n', '0,0,0\n']
```

Readlines(): Read all the line of the file and save the lines as a list

Line space \n is also included. Then all the elements (lines) are saved in str type.



#### 2. Data Reading (tip for path error)



files tab (on the right in spyder), you can find your file and path, you can 'copy absolute path' by the right click and paste the copied path on your code.



3. Appropriate data transforming (reading, converting to the number, dimension scaling)

```
import numpy as np
import matplotlib.pyplot as plt
training_data_file = open('C:/Users/jsb07/Documents/XOR truthtable.csv', 'r')
training data list = training data file.readlines()
training data file.close()
print(training_data_list)
for record in training data list:
        all values = record.split(',')
        print (all values)
        feature = np.asfarray(all values[1:])
        print (feature)
        x = np.array(feature, ndmin = 2)
        print (x)
        correct label = int(all values[0])
        d = np.zeros(2)
        d [correct label] = 1
        print (d)
```

```
['0,1,1\n', '1,1,0\n', '1,0,1\n', '0,0,0\n']
['0', '1', '1\n']
[1. 1.]
[[1. 1.]]
[1. 0.]
['1', '1', '0\n']
[1. 0.]
[[1. 0.]]
[0. 1.]
['1', '0', '1\n']
[0. 1.]
[[0. 1.]]
[0. 1.]
['0', '0', '0\n']
[0. 0.]
[[0. 0.]]
[1. 0.]
```

- record.split : data dividing (by ,)
- np.asfarray(): convert the array to float array
- x=np.array(feature,ndmin=2)  $\rightarrow$  feature (2,)  $\rightarrow$  x = (1x2)



#### 3. Appropriate data transforming (one-hot encoding)

```
import numpy as np
import matplotlib.pyplot as plt
training_data_file = open('C:/Users/jsb07/Documents/XOR truthtable.csv', 'r')
training data list = training data file.readlines()
training data file.close()
print(training_data_list)
for record in training data list:
        all_values = record.split(',')
        print (all values)
        feature = np.asfarray(all values[1:])
        print (feature)
        x = np.array(feature,ndmin = 2)
        print (x)
        correct label = int(all values[0])
        d = np.zeros(2)
        d [correct label] = 1
        print (d)
```

```
['0,1,1\n', '1,1,0\n', '1,0,1\n', '0,0,0\n']
['0', '1', '1\n']
[1. 1.]
[[1. 1.]]
[1. 0.]
['1', '1', '0\n']
[1. 0.]
[[1. 0.]]
[0. 1.]
['1', '0', '1\n']
[0. 1.]
[[0. 1.]]
[0. 1.]
[[0. 0.]]
[0. 0.]
[1. 0.]
```

- One-Hot encoding
- → Save the first element in the line to the correct\_label.
- → After defining the zero array, replace the element which index is correct\_label to 1.

#### 4. Declaring the variables

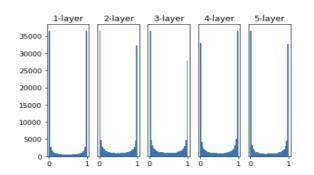
```
epoch = 10000
learning rate = 0.03
input layer = 2
hidden layer = 5
output layer = 2
w1 = np.random.rand(input layer,hidden layer)
w2 = np.random.rand(hidden layer, output layer)
classification accuracy per epoch = np.array([])
total_cost_per_epoch = np.array([])
n epoch = np.array([])
```

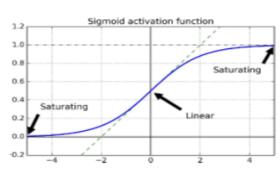
- np.random.rand(row,col)  $\rightarrow$  fill the array with row and col size by random values from 0~1.
- Empty arrays are also needed to store the accuracy, cost and epoch number

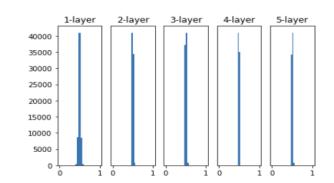
### Other weight initialization techniques



#### It is not good if the variance is too large or too small.









#### **Xavier initialization**



$$W \sim N(0, Var(W))$$

$$sigma = \sqrt{rac{2}{n_{in} + n_{out}}}$$

 $(n_{in}:$ 이전 layer(input)의 노드 수,  $n_{out}:$  다음 layer의 노드 수)

Xavier Uniform Initialization

$$W \sim U(-\sqrt{rac{6}{n_{in}+n_{out}}}\,, \;\; +\sqrt{rac{6}{n_{in}+n_{out}}}\,)$$



#### He initialization (for ReLU)

He Normal Initialization

$$W \sim N(0, Var(W))$$

$$sigma = \sqrt{rac{2}{n_{in}}}$$

 $(n_{in}:$  이전 layer(input)의 노드 수)

He Uniform Initialization

$$W \sim U(-\sqrt{rac{6}{n_{in}}}, ~+\sqrt{rac{6}{n_{in}}})$$

 $(n_{in}:$ 이전 layer(input)의 노드 수)

w1 = np.random.normal(0,np.sqrt(2/(input\_layer+hidden\_layer)),size=(input\_layer,hidden\_layer)) w2 = np.random.normal(0,np.sqrt(2/(hidden\_layer+output\_layer)),size=(hidden\_layer,output\_layer))





#### 5. Function define

**Activation function** 

```
def activation (z):
    g_z = 1/(1+np.exp(-z))
    return g_z
```

**Feedforward** 

```
def feedforward (feature,w1,w2):
    x = np.array(feature, ndmin=2)
    z2 = np.dot(x,w1)
    x2 = activation(z2)
    z3 = np.dot(x2,w2)
    h = activation(z3)
    return x2, h
```

**X** dimension scaling of the feature is conducted in the Feedforward function.



#### 5. Function define

**Backpropagation** 

Inference

```
def backpropagation (h,d,x1,x2,x3):
    x = np.array(x1, ndmin=2)
    dd = np.array(d,ndmin=2)
    e3 = h-dd
    delta3 = e3
    e2 = np.dot(delta3,w2.T)
    delta2 = e2*x2*(1-x2)

w2_update = -learning_rate*np.dot(x2.T,delta3)
    w1_update = -learning_rate*np.dot(x.T,delta2)

return w1_update, w2_update
```

**X** dimension scaling of the d is conducted in the backpropagation function

```
def inference (h):
   inferred_label = np.argmax(h)
   return inferred_label
```



#### 6. Main Body – 1) Evaluation of classification accuracy before training

```
scorecard = np.array([]) Empty arrays for the score and cost for each example
cost = np.array([])
                                   Open the example one by one
for record in training data list:
       all values = record.split(',')
       feature = np.asfarray(all values[1:])
                                             Make feature and d (correct answer)
       correct label = int(all values[0])
       d = np.zeros(2)
       d [correct label] = 1
                                             Conduct feedforward and print h vector
       x2, h = feedforward (feature,w1,w2)
       print (h)
                                             If inference(h) is equal to the correct_label
       if (inference (h) == correct label):
                                             → Append 1 to the score card.
           scorecard = np.append(scorecard,1)
       else:
                                             \rightarrow If it is not ,append 0 to the score card
         scorecard = np.append(scorecard,0)
       cost_{example} = np.sum(-d*np.log(h)-(1-d)*np.log(1-h)) Calculating the cost for the example
       cost = np.append(cost, cost example)
                                                            and append the cost to the cost array
classification accuracy = np.sum(scorecard)/4
classification accuracy per epoch = np.append(classification accuracy per epoch, classification accuracy)
total cost = np.sum(cost)/4
total cost per epoch = np.append(total cost per epoch, total cost)
n epoch = np.append(n epoch, 0)
```

Check all examples and calculate the classification accuracy and store the results in athe empty array. Calculate the total cost (average after adding all costs) and store it in the empty array. Save Epoch number (save as 0 because it is before the learning).



6. Main Body – 1) Evaluation of classification accuracy before training

```
print ("initial cost: ", total_cost)
print ("initial accuracy: ", classification_accuracy)
```

```
[[0.63800817 0.73023477]]
[[0.62912345 0.71562709]]
[[0.62664513 0.71221607]]
[[0.61747738 0.69675864]]
initial cost = 1.5215071060210743
initial_accuracy = 0.5
```



#### 6. Main Body – 2) Training

```
for i in range(epoch):
   scorecard = np.array([])
   cost = np.array([])
                                    Open the example one by one
   for record in training data list:
       all values = record.split(',')
       feature = np.asfarray(all values[1:])
                                           Make feature and d (correct answer)
       correct label = int(all values[0])
       d = np.zeros(2)
                                                            Conduct feedforward
       d [correct label]=1
                                                            And calculate the amount of the
       x2, h = feedforward(feature,w1,w2)
       w1 update, w2 update = backpropagation (h,d,feature,x2,h)
                                                            update by the backpropagation
       w1 = w1+w1 update
                        W1, W2 update
       w2 = w2+w2 update
```



#### 6. Main Body – 2) Epoch test

```
w1 = w1+w1 update
   w2 = w2+w2 update
for record in training_data_list: Open the example one by one
   all values = record.split(',')
   feature = np.asfarray(all values[1:])
   correct_label = int(all values[0])
   d = np.zeros(2)
   d [correct label] = 1
                                                      Same with the evaluation code
   x2, h = feedforward (feature,w1,w2)
                                                      before the training
   if (inference (h)==correct label):
       scorecard = np.append(scorecard,1)
   else:
     scorecard = np.append(scorecard,0)
   cost example = np.sum(-d*np.log(h)-(1-d)*np.log(1-h))
   cost = np.append(cost, cost example)
classification accuracy = np.sum(scorecard)/np.size(scorecard)
classification_accuracy_per_epoch = np.append(classification_accuracy_per_epoch, classification_accuracy)
total cost = np.sum(cost)/4
                                                                Save accuracy and cost of this
total_cost_per_epoch = np.append(total_cost_per_epoch, total_cost)
n epoch = np.append(n epoch, i+1)
                                                                epoch
```



#### 6. Main Body – 3) Checking the final state

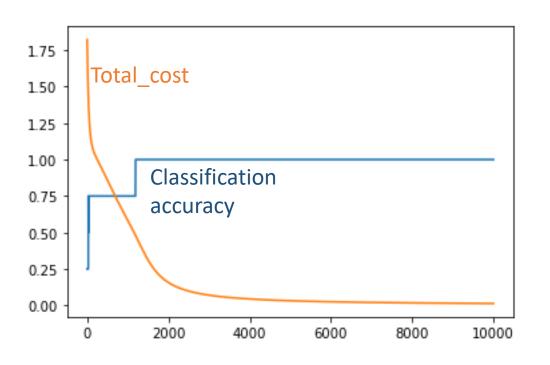
```
scorecard = np.array([])
cost = np.array([])
for record in training data list:
    all values = record.split (',')
    feature = np.asfarray(all values[1:])
    correct label = int(all values[0])
   d = np.zeros(2)
   d [correct label] = 1
   x2, h = feedforward (feature, w1,w2)
    print (h)
    if (inference(h) == correct label):
        scorecard = np.append(scorecard,1)
    else:
        scorecard = np.append(scorecard,0)
    cost example = np.sum(-d*np.log(h)-(1-d)*np.log(1-h))
    cost = np.append(cost, cost example)
classification accuracy = np.sum(scorecard)/4
total cost = np.sum(cost)/4
print ("Final cost: ", total cost)
print ("Final accuracy: ", classification_accuracy)
plt.plot(n epoch, classification accuracy per epoch)
plt.plot(n epoch,total cost per epoch)
```

Same with the evaluation code before the training

Print final cost and accuracy Plot the graphs



#### 6. Main Body – 3) Checking the final state



```
[[9.99755932e-01 2.79294619e-04]]
[[0.0058944 0.9943169]]
[[9.99755932e-01 2.79294619e-04]]
[[0.9927184 0.00700539]]
Final cost: 0.00674907411360905
Final accuracy: 1.0
```

### Mini batch



#### If batch = 2, we can modify the code as follows

```
for i in range(epoch):
   scorecard = np.array([])
   cost = np.array([])
   w1 update temp = np.zeros([input layer, hidden layer])
   w2 update temp = np.zeros([hidden layer, output layer])
   batch = 2
   batch count= 0
   for record in training data list:
       all values = record.split(',')
       feature = np.asfarray(all values[1:])
       correct label = int(all values[0])
       d = np.zeros(2)
       d [correct label]=1
       x2, h = feedforward(feature,w1,w2)
       w1 update, w2 update = backpropagation (h,d,feature,x2,h)
       w1 update temp = w1 update temp+w1 update
       w2 update temp = w2 update temp+w2 update
       batch count=batch count+1
       if (batch count==batch):
           w1 = w1+w1 update temp/batch
           w2 = w2+w2 update temp/batch
           batch count = 0
           w1 update temp = np.zeros([input layer, hidden layer])
           w2 update temp = np.zeros([hidden layer, output layer])
```

- L) Temp array
- 2) Batch size & batch count

- Calculate the amount of the updates and add to the temp arrays
   batch\_count +1
- If batch\_count == batch Conduct update and initialize the count and temp arrays

### **Class Exersize (XNOR)**

Implent the program for the XNOR (with 2 hidden layers, minibatch of 2)

XNOR	Input 1	Input 2
1	1	1
0	1	0
0	0	1
1	0	0

## **Contents**

3 MNIST data



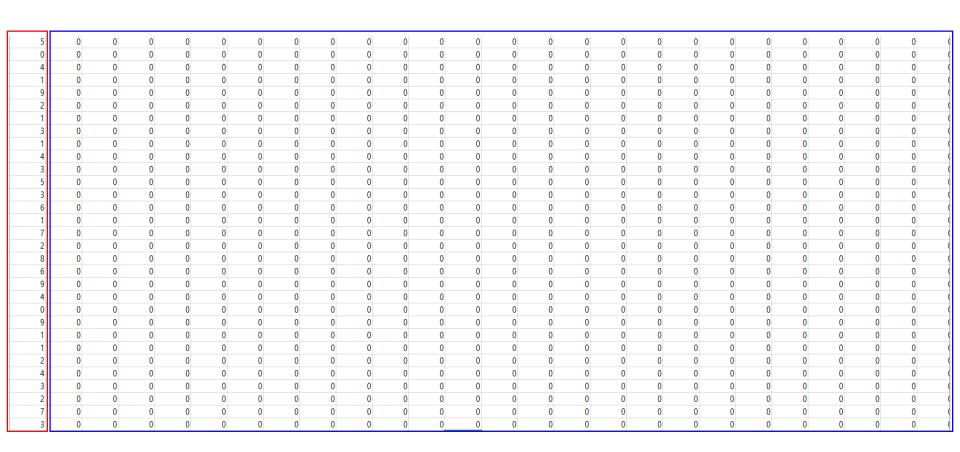
### **MNIST** data



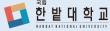
#### https://pjreddie.com/projects/mnist-in-csv/



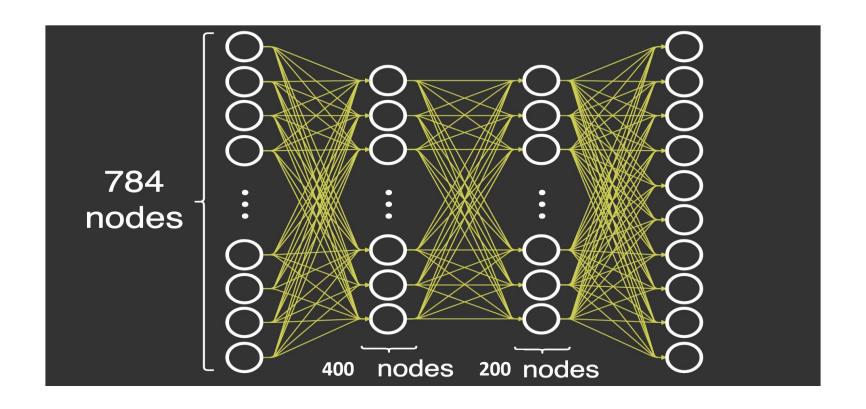
### **MNIST** data



Label Pixel value (x<sub>1</sub>~x<sub>784</sub>)



# **MNIST Programming (Project 2)**



### **MNIST Programming (Project 2)**

- We should modify the number of neurons
- The test should be carried out with the test set
  - → Statesments for Test set open, readline & close are needed.
  - → Classification accuracy & cost calculation should be conducted with the test set.
- Use the mini-batch (start from the batch size of 5)
- Activation function: tanh, use the softmax only for the output layer
- We will only use the first 10,000 examples in the training set and the first 1,000 examples in the test set (because it will take so long time if we use the entire data set.)
- If you finish to implement the code with the guideline above, change the activation function (expect the softmax for the output layer) and compare the results (tanh vs sigmoid)
- Change the batch size to 100 and 200 then compare the results (5 vs 100 vs 200)