

2022년 IoT기반 스마트 솔루션 개발자 양성과정



# Embedded Application

## 10-PPG Sensor

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010-9577-1696

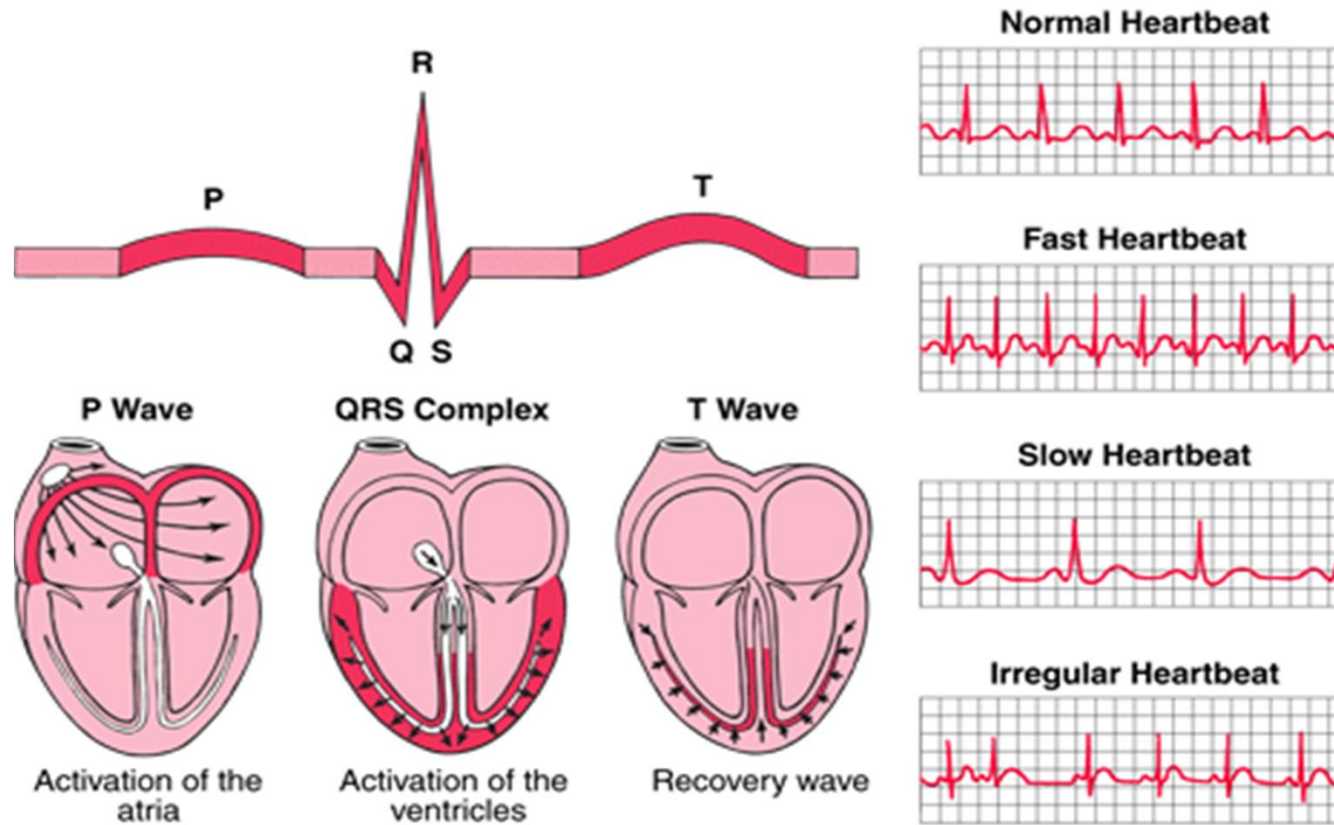
[ojo1696@naver.com](mailto:ojo1696@naver.com)

<https://cafe.naver.com/yoons2022>

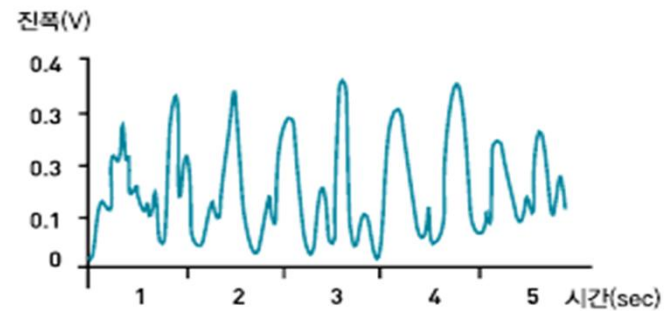
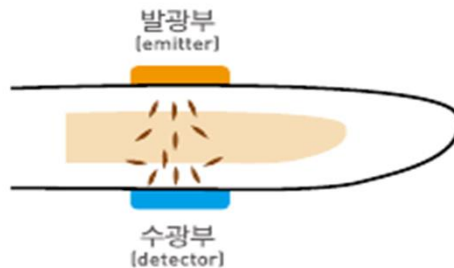
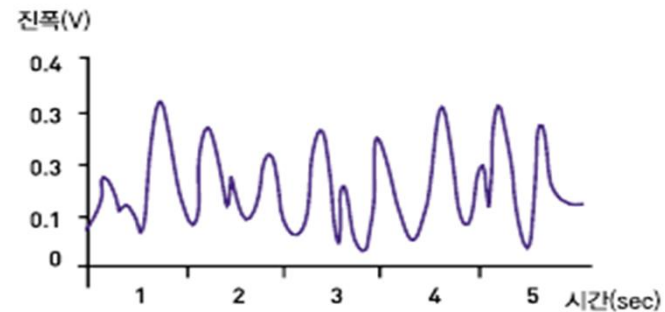
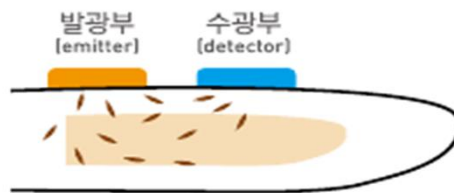


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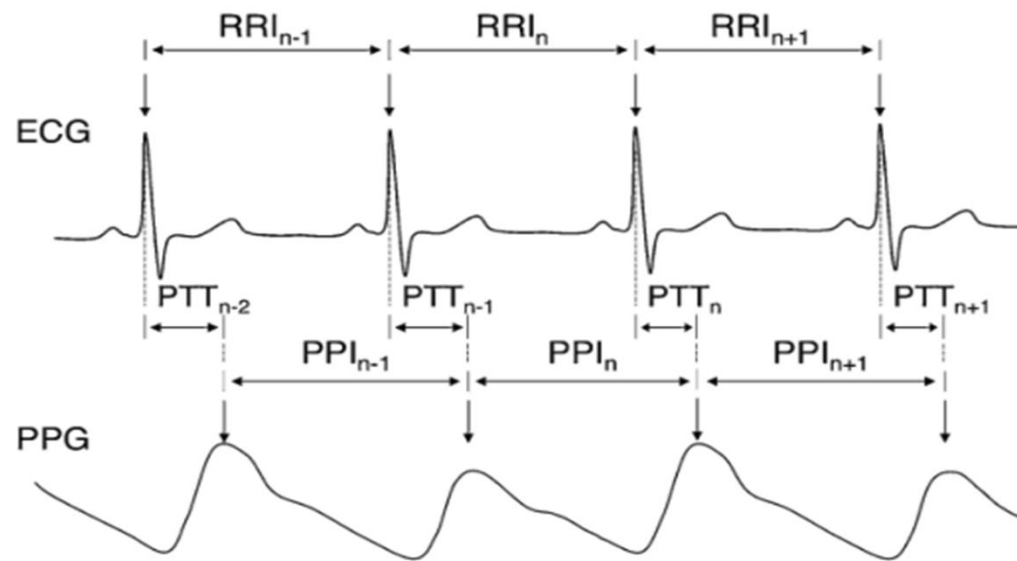
# Heartbeat



# PhotoPlethymoGraph [PPG]

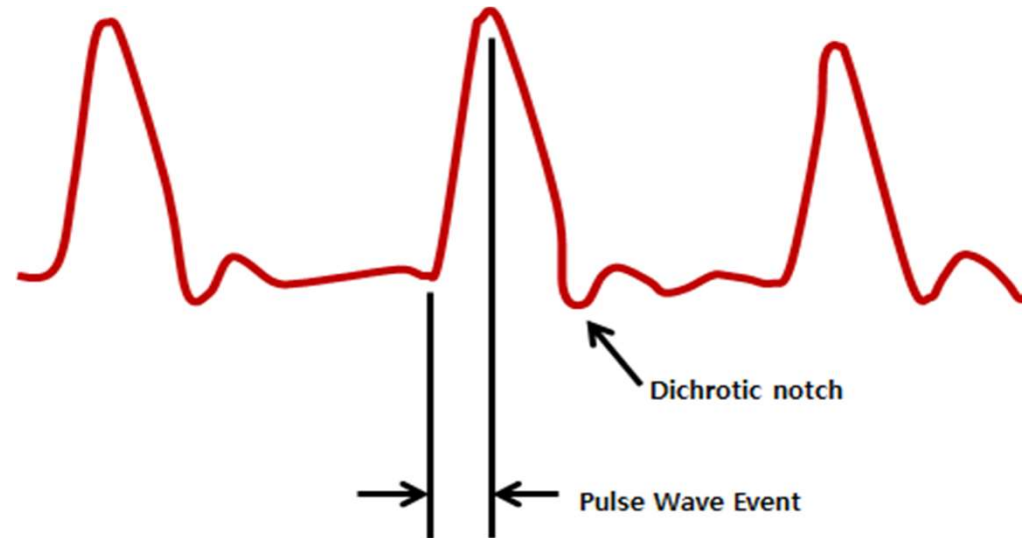


# ECG & PPG



# PPG Sensor 동작

- PPG는 심장박동의 모니터링 용도로 사용 가능한 모듈
- 적외선 LED에서 방출하는 적외선으로 혈관 압력의 미세한 변화를 수신부에서 감지



## 관련 지식

- 실내조명에 의한 간섭이 많이 발생
- 겉에 커버를 사용하여 외부 빛을 차단하여 간섭을 최소화

신생아 (0~3개월)	영아 (3~6개월)	유아 (6~12개월)	어린이 (1~10년)	성인 (10세 이상 어린이 포함)	운동선수
100~150	90~120	80~120	70~130	60~100	40~60

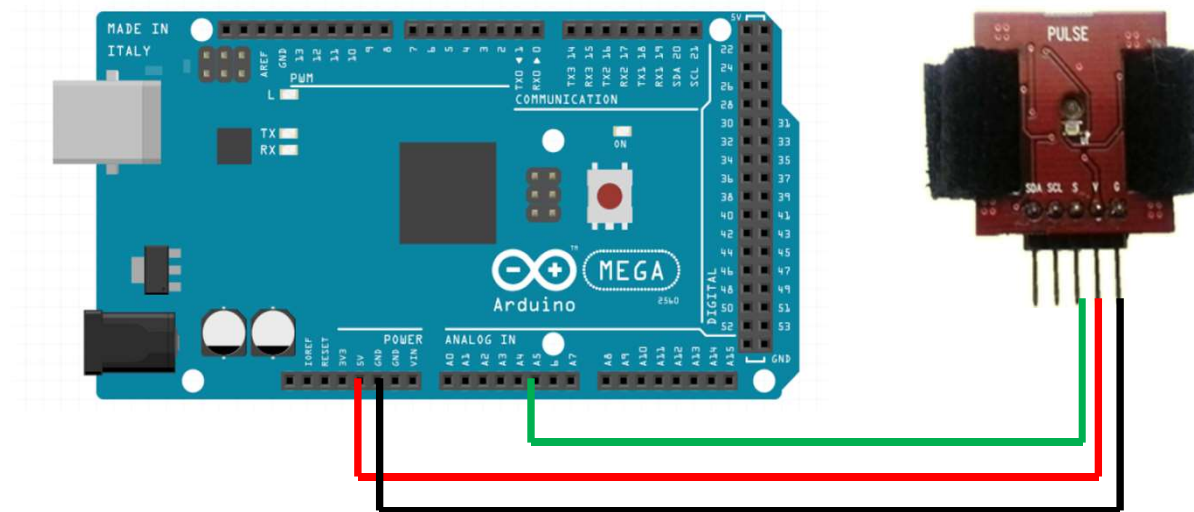


# PPG Sensor

센서 모듈 외형	모듈 항목	모듈 항목의 내용
	펄스 센서	MCP6004
	감지 센서	Light Photo Sensor
	동작 전압	3.3V
	입력/출력	5pin Header (2.54mm pitch)
	크기	27x33mm
적외선 LED에서 방출하는 적외선이 혈관압력의 변화에 따라서 심박을 측정하는 센서		



# Wiring



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# PPG Wave

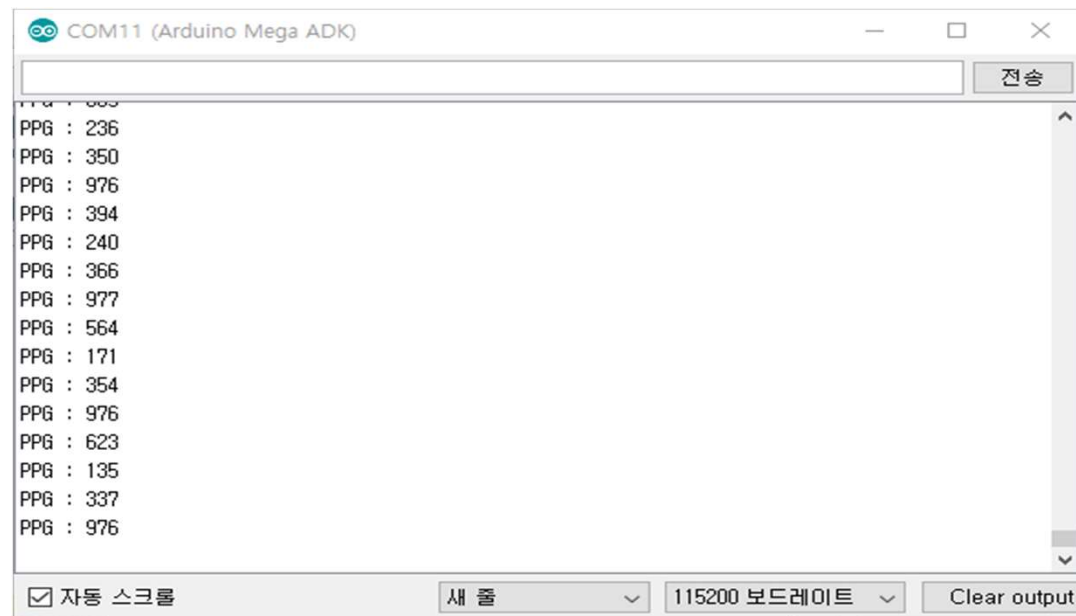
```
#define PPG A5
unsigned int adPulse;

void setup( ) {
  Serial.begin(115200);
  pinMode(PPG, INPUT);
}

void loop( ) {
  adPulse = analogRead(PPG);
  Serial.print("PPG : ");
  Serial.println(adPulse);
  delay(10);
}
```

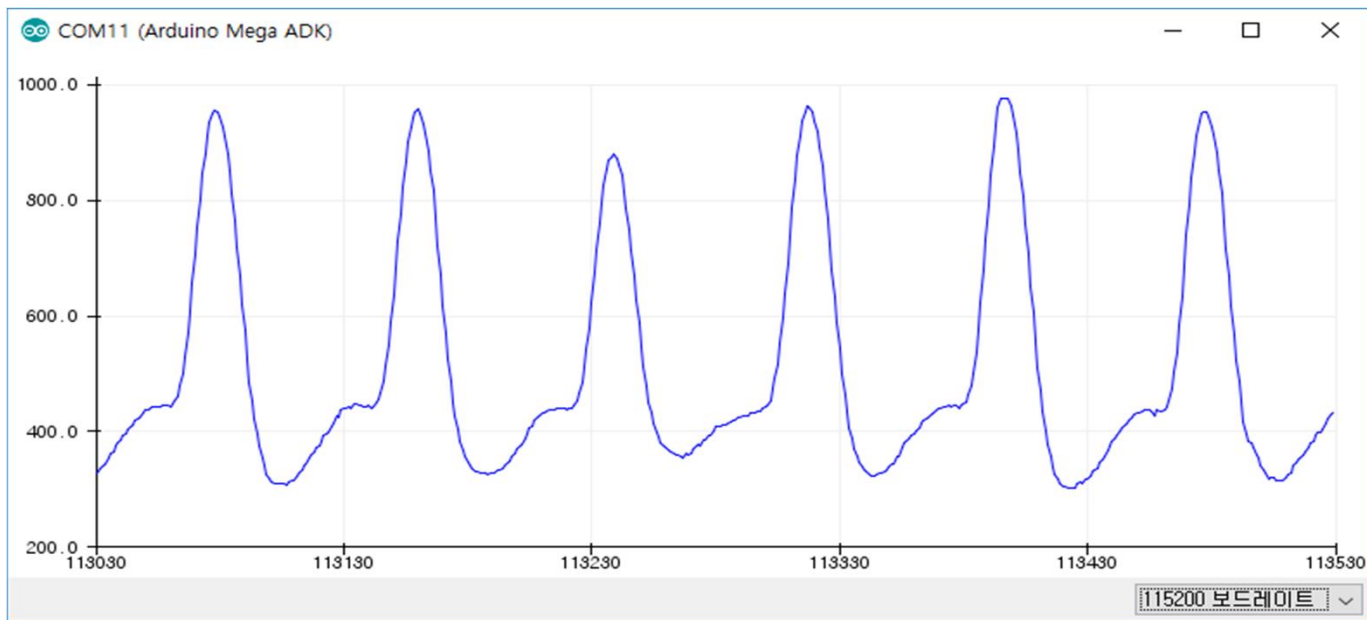


# Serial Monitor



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# Serial Plotter



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# PPG SPP

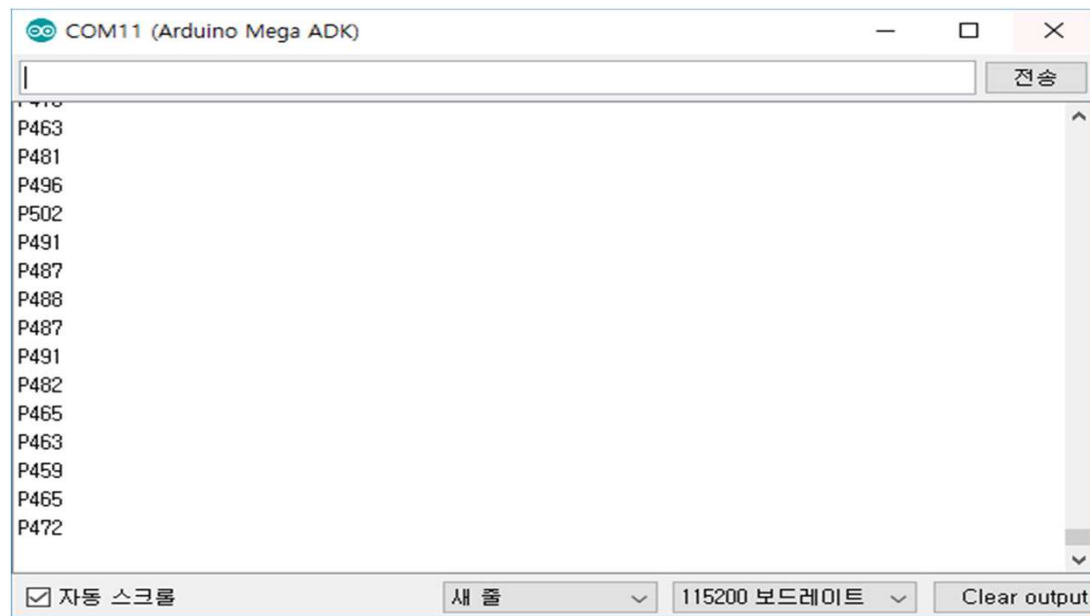
```
#define PPG A5
unsigned int adPulse;

void setup( ) {
  Serial.begin(115200);
  pinMode(PPG, INPUT);
}

void loop( ) {
  adPulse = analogRead(PPG);
  Serial.print('P');
  Serial.print(adPulse);
  Serial.print('\n');
  delay(20);
}
```

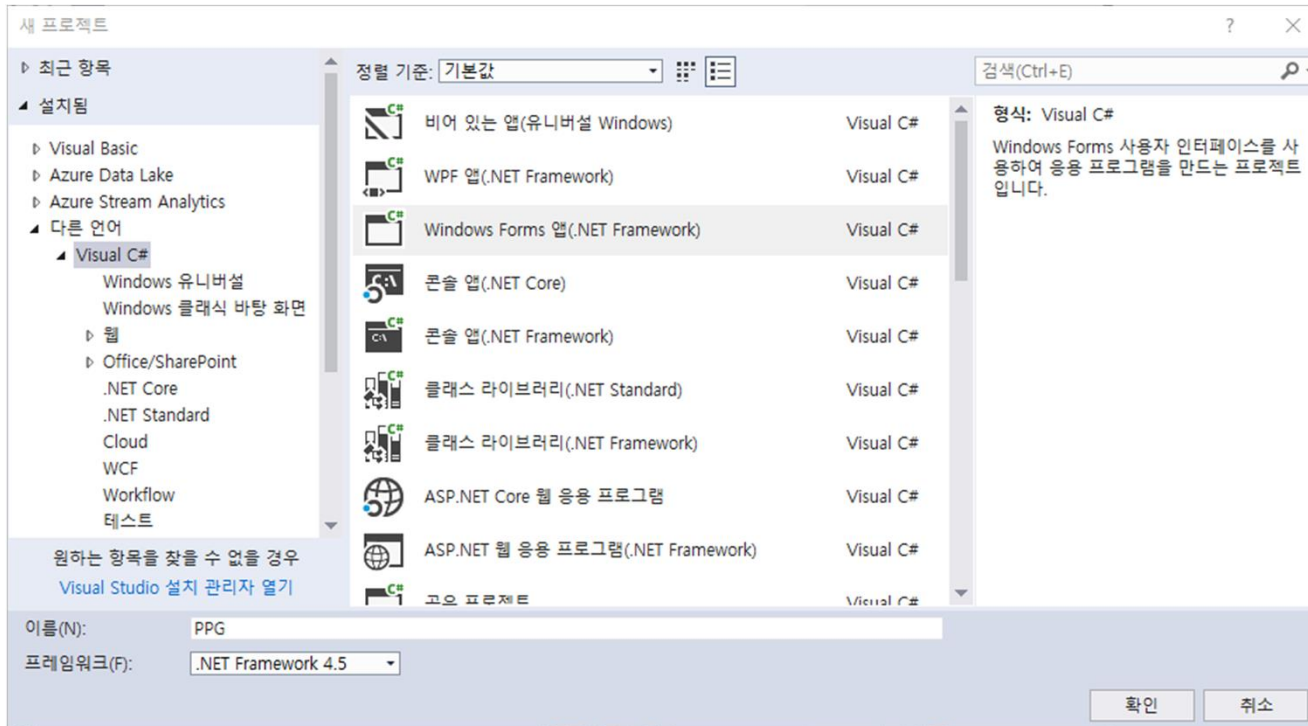


# Serial Monitor



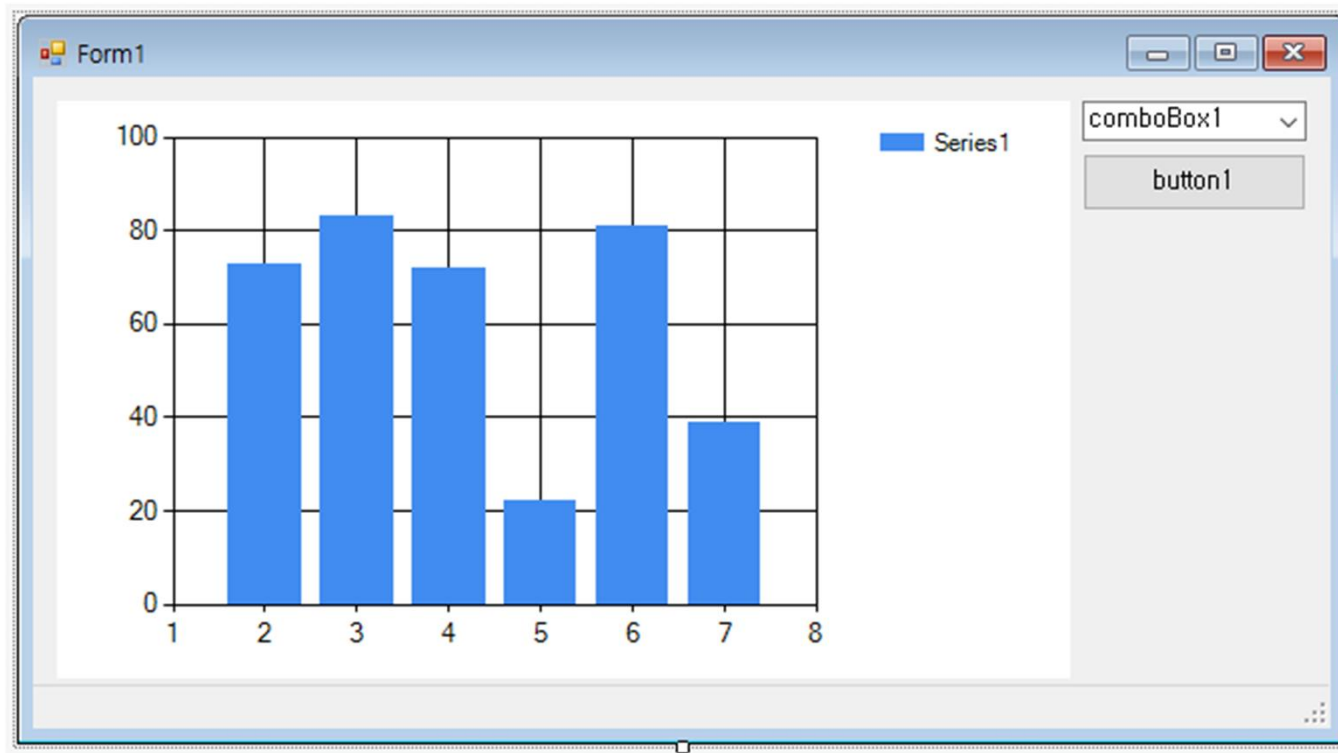
충북대학교 공동훈련센터

# C# PPG - 새 프로젝트

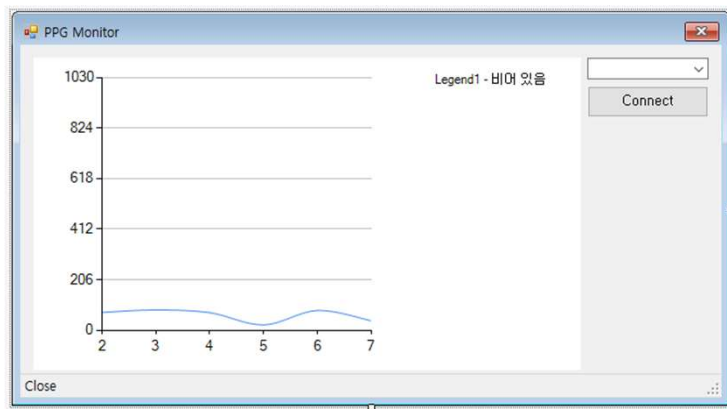


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# Form Design



# Property

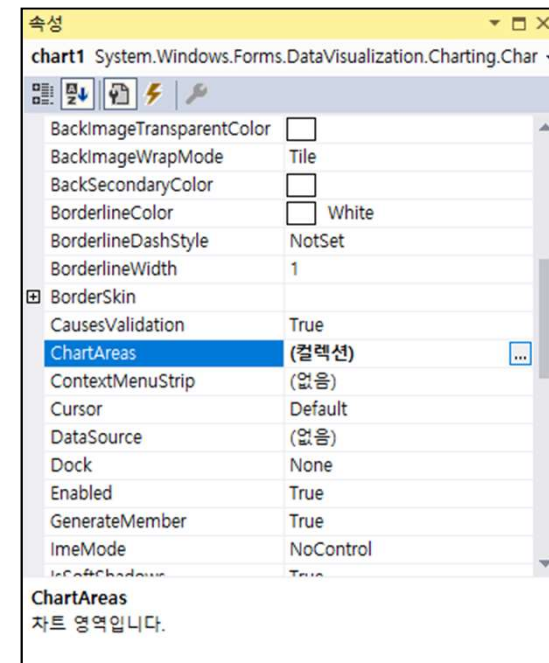
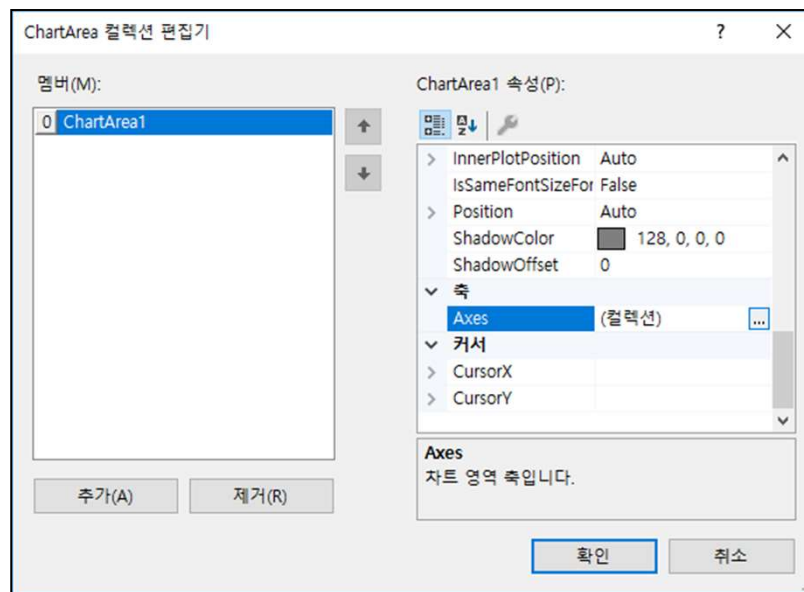


Form1	
Text	PPG Monitor
MaximizeBox	False
MinimizeBox	False
FormBorderStyle	FixedSingle
ToolStripComboBox1	
Name	cmbComPort
ToolStripButton1	
Name	btnConnect
Text	Connect
ToolStripStatusLabel1	
Name	Status
Text	Close





# Chart Area Collection



# Axis Collection

Y (Value) axis	
Maximum	1030
Minimum	0

Axis 컬렉션 편집기

멤버(M):

- 0 X axis
- 1 Y (Value) axis
- 2 Secondary X axis
- 3 Secondary Y (Value) axis

Y (Value) axis 속성(P):

IsLogarithmic False

IsMarginVisible True

IsReversed False

IsStartedFromZero True

LogarithmBase 10

Maximum 1030

Minimum 0

> ScaleBreakStyle

▼ 제목

TextOrientation Auto

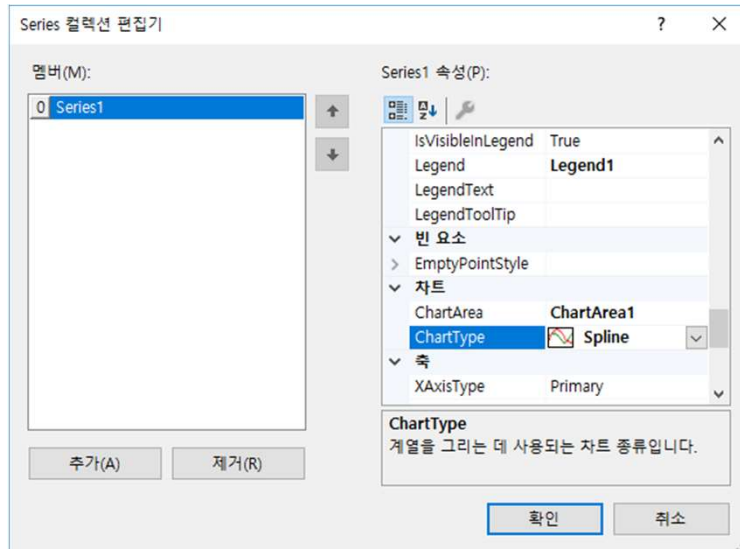
Title

Maximum  
최대 축 값입니다.

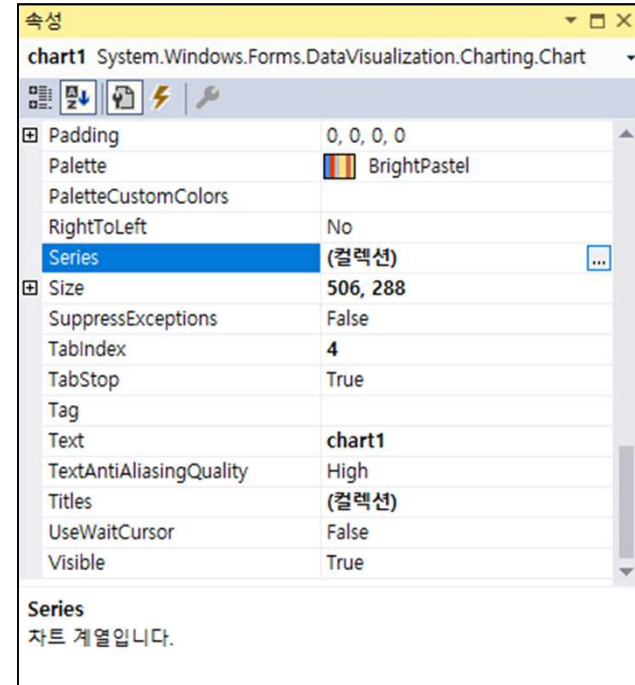
확인 취소



# Series Collection



Series1	
ChartType	Spline
isVisibleInLegend	False



# Define

```
using System;
using System.Collections.Generic;
using System.ComponentModel;
using System.Data;
using System.Drawing;
using System.Linq;
using System.Text;
using System.Threading.Tasks;
using System.Windows.Forms;
using System.IO.Ports;

namespace PPG
{
    public partial class Form1 : Form
    {
        SerialPort ComPort = new SerialPort();
        private delegate void SetTextDelegate(string getString);

        public Form1()
        {
            InitializeComponent();
            ComPort.DataReceived += new SerialDataReceivedEventHandler(DataReceived);
        }
    }
}
```



# Form

```
private void Form1_Load(object sender, EventArgs e)
{
    cmbComPort.Items.Clear();
    var portName = System.IO.Ports.SerialPort.GetPortNames();
    cmbComPort.Items.AddRange(portName);
    cmbComPort.SelectedIndex = cmbComPort.Items.Count - 1;
}

private void Form1_FormClosing(object sender, FormClosingEventArgs e)
{
    if (ComPort.IsOpen)
    {
        ComPort.Close();
        ComPort.Dispose();
        ComPort = null;
    }
    Status.Text = "Form Closing.";
}
```



# btnConnect\_Click

```
private void btnConnect_Click(object sender, EventArgs e)
{
    if (btnConnect.Text == "Connect")
    {
        if (ComPort.IsOpen)
        {
            Status.Text = "Already used.";
        }
        else
        {
            ComPort.PortName = cmbComPort.Text;
            ComPort.BaudRate = 115200;
            ComPort.DataBits = 8;
            ComPort.Parity = Parity.None;
            ComPort.StopBits = StopBits.One;
            ComPort.Handshake = Handshake.None;
            ComPort.Open();
            ComPort.DiscardInBuffer();
            btnConnect.Text = "Close";
            Status.Text = "Port Open.";
        }
    }
    else
    {
        ComPort.Close();
        Status.Text = "Port Close.";
        btnConnect.Text = "Connect";
    }
}
```



# DataReceived

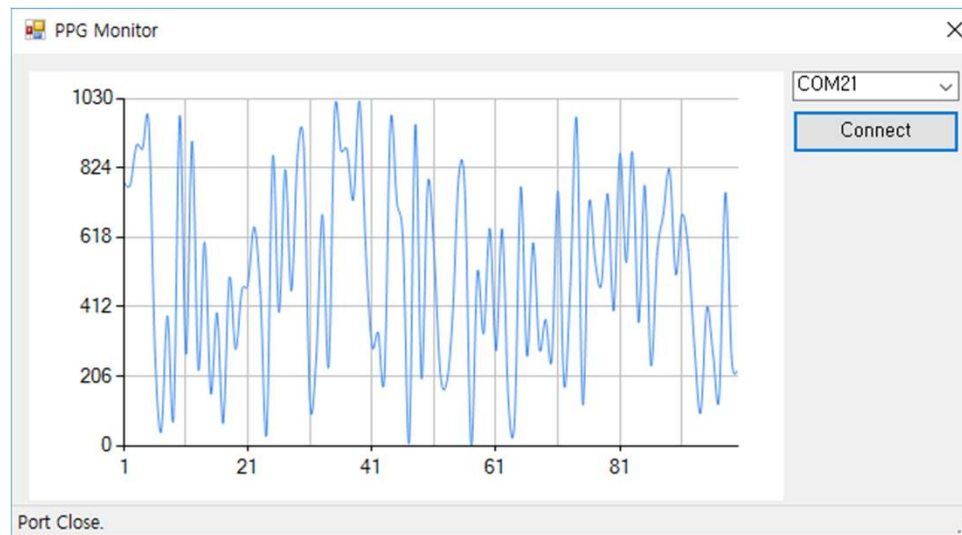
```
private void DataReceived(object sender, System.IO.Ports.SerialDataReceivedEventArgs e)
{
    string rxd = ComPort.ReadTo("\n");
    this.BeginInvoke(new SetTextDelegate(SerialReceived), new object[] { rxd });
}

private void SerialReceived(string inString)
{
    int PPGSignal = Convert.ToInt16(inString.Substring(1, inString.Length - 1));

    chart1.Series["Series1"].Points.Add(PPGSignal);
}
```



# Debug Run



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# Scope Chart Style

Axis Collection : X axis	
Maximum	1030
Minimum	0
Enable	False

```
private void SerialReceived(string inString)
{
    int PPGSignal = Convert.ToInt16(inString.Substring(1, inString.Length - 1));

    chart1.Series["Series1"].Points.Add(PPGSignal);
    if (chart1.Series["Series1"].Points.Count > 100)
    {
        chart1.Series["Series1"].Points.Clear();
    }
}
```






# Strip Chart Style

```
private void SerialReceived(string inString)
{
    int PPGSignal = Convert.ToInt16(inString.Substring(1, inString.Length - 1));

    chart1.Series["Series1"].Points.Add(PPGSignal);
    if (chart1.Series["Series1"].Points.Count > 100)
    {
        chart1.Series["Series1"].Points.RemoveAt(0);
    }
}
```



# Files

lot Base SW Developer-2019 > Arduino_Mega > Program > PPG > bin > Debug				▼ ↺
이름	수정한 날짜	유형	크기	
 PPG.exe	2019-05-12 오후...	응용 프로그램	14KB	
 PPG.exe.config	2019-05-12 오전...	XML Configuratio...	1KB	
 PPG.pdb	2019-05-12 오후...	프로그램 디버그 ...	24KB	



# Heart Rate Setup( )

```
#define PPG A5
unsigned int adPulse;

unsigned long time_20mS = 0, time_3S = 0;
#define index_MAX 20
unsigned char Pulse_Data[index_MAX];
unsigned char Pulse_count = 0;
bool Pulse_Rise = false;
unsigned char Index = 0, Index_flag = 0;
unsigned int ADC_Data[4] = {0, 0, 0, 0};

void setup( ) {
    Serial.begin(115200);
    pinMode(PPG, INPUT);

    time_20mS = millis( );
    time_3S = time_20mS;
}
```



# Heart Rate Loop( ) 1

```
void loop( ) {  
    if((time_20mS + 20) < millis( )){  
        time_20mS += 20;  
        adPulse = analogRead(PPG);  
        if((adPulse < ADC_Data[0]) && (ADC_Data[0] < ADC_Data[1]) &&  
(ADC_Data[1] < ADC_Data[2]) && (ADC_Data[2] < ADC_Data[3]) && Pulse_Rise)    {  
            if((ADC_Data[3] - adPulse) > 100) {  
                Pulse_Rise = false;  
                Pulse_count++;  
            }  
        } else if((adPulse > ADC_Data[0]) && (ADC_Data[0] > ADC_Data[1]) &&  
(ADC_Data[1] > ADC_Data[2]) && (ADC_Data[2] > ADC_Data[3]) && (Pulse_Rise == false)){  
            if((adPulse - ADC_Data[3]) > 100){    Pulse_Rise = true;    }  
        }  
  
        for(char k=3; k>0; k--) ADC_Data[k] = ADC_Data[k-1];  
        ADC_Data[0] = adPulse;  
    }  
}
```



# Heart Rate Loop( ) 2

```
if((time_3S + 3000) < millis( )){
    time_3S += 3000;
    if(Pulse_count > 8) Pulse_Data[Index] =0;
    else Pulse_Data[Index] = Pulse_count;

    Pulse_count = 0;

    if (++Index>=index_MAX) Index=0;
    if(Index_flag < index_MAX){ Index_flag++; }

    unsigned int Pulse_sum = 0;
    for(char k=0; k<Index_flag; k++){ Pulse_sum += Pulse_Data[k]; }
    if(Index_flag < index_MAX) Pulse_sum = Pulse_sum * index_MAX / Index_flag;

    if(Pulse_sum < 20) PulseInit( );
    SendPPG(Pulse_sum);
}
}
```

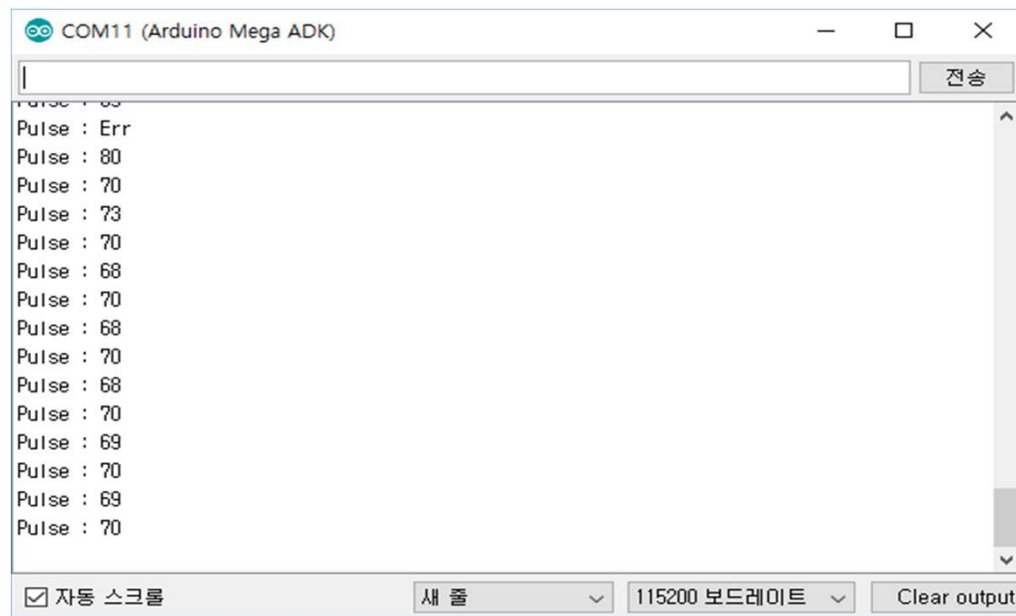


# Heart Rate function

```
void PulseInit( ){  
    Index = 0;  
    Index_flag = 0;  
    time_20mS = millis();  
    time_3S = time_20mS;  
}  
  
void SendPPG(int PulseRate){  
    Serial.print("Pulse : ");  
    if(PulseRate < 20){  
        Serial.println("Err");  
    }else{  
        Serial.println(PulseRate);  
    }  
}
```



# Serial Monitor



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# Heart Rate Setup( )

```
#define PPG A5
unsigned int adPulse;
unsigned int BPM;
unsigned long time_20mS = 0, time_3S = 0;
#define index_MAX 20
unsigned char Pulse_Data[index_MAX];
unsigned char Pulse_count = 0;
bool Pulse_Rise = false;
unsigned char Index = 0, Index_flag = 0;
unsigned int ADC_Data[4] = {0, 0, 0, 0};

void setup( ) {
  Serial.begin(115200);
  pinMode(PPG, INPUT);

  time_20mS = millis( );
  time_3S = time_20mS;
}
```



# Heart Rate Loop( ) 1

```
void loop( ) {  
    if((time_20mS + 20) < millis()){  
        time_20mS += 20;  
        adPulse = analogRead(PPG);  
        if((adPulse < ADC_Data[0]) && (ADC_Data[0] < ADC_Data[1]) &&  
(ADC_Data[1] < ADC_Data[2]) && (ADC_Data[2] < ADC_Data[3]) && Pulse_Rise) {  
            if((ADC_Data[3] - adPulse) > 100) {  
                Pulse_Rise = false;  
                Pulse_count++;  
            }  
        } else if((adPulse > ADC_Data[0]) && (ADC_Data[0] > ADC_Data[1]) &&  
(ADC_Data[1] > ADC_Data[2]) && (ADC_Data[2] > ADC_Data[3]) && (Pulse_Rise == false)){  
            if((adPulse - ADC_Data[3]) > 100){ Pulse_Rise = true; }  
        }  
  
        for(char k=3; k>0; k--) ADC_Data[k] = ADC_Data[k-1];  
        ADC_Data[0] = adPulse;  
        SendPPG();  
    }  
}
```



# Heart Rate function

```
void PulseInit( ){  
    Index = 0;  
    Index_flag = 0;  
    time_20mS = millis( );  
    time_3S = time_20mS;  
}
```

```
void SendPPG( ){  
    Serial.print("P");  
    Serial.print(adPulse);  
    Serial.print('\n');  
  
    Serial.print("B");  
    Serial.print(BPM);  
    Serial.print('\n');  
}
```



# BPM Display



Label1	
AutoSize	False
Font	맑은 고딕, 27.75pt, style=Bold
ForeColor	Blue
Text	65
TextAlign	MiddleCenter



# SerialReceived

```
private void SerialReceived(string inString)
{
    string Code = inString.Substring(0, 1);
    int PPGSignal = Convert.ToInt16(inString.Substring(1, inString.Length - 1));

    if (Code == "P")
    {
        StripChart(PPGSignal);
    }
    else
    {
        label1.Text = PPGSignal.ToString();
    }
}
```

