#### 2022년 IoT기반 스마트 솔루션 개발자 양성과정



#### **Embedded Application**

#### 2-Bluetooth

담당 교수 : 윤 종 이
010-9577-1696
ojo1696@naver.com
https://cafe.naver.com/yoons2022



#### BlueTooth [블루투스]

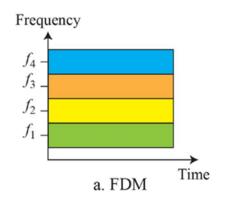
- Harald BlueTooth
  - 10세기 스칸디나비아 국가인 덴마크와 노르웨이를 통일한 바이킹
- 의미
  - 해럴드가 스칸디나비아 통일 : 블루투스 기술이 서로 다른 통신 간에 선 없이 단일화된 연결 장치
  - 해럴드가 여행가로 유명 : 세계 어디에서도 단일 장비로 통신할 수 있도록 모든 통신 환경을 일원화
- 초기에는 진행중인 프로젝트 이름

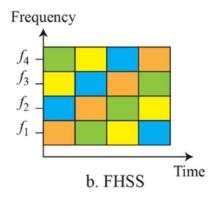
• 현재 스마트폰에 내장되어 있으며, PAN(Persnal Area NetWork)의 핵심이 됨



## 블루투스 특징

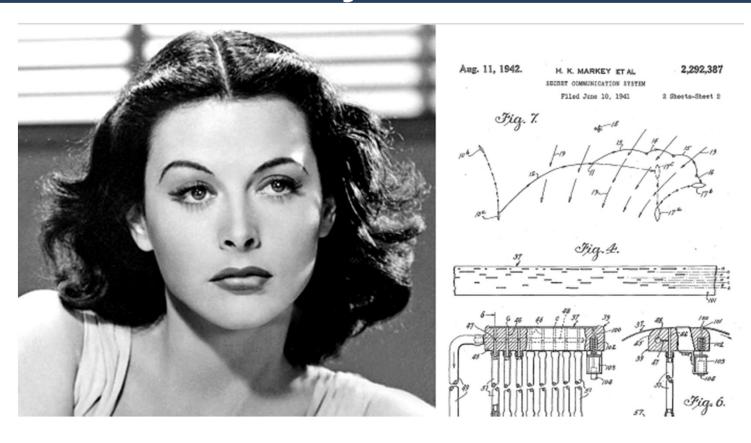
- IEEE 802.15.1
- 저렴, 작고, 적은 소비전력, 작은 구역
- 무선 키보드, 마우스, 헤드셋, 스마트 워치 ..
- 주파수 분할 스펙트럼 확산(FHSS)방식



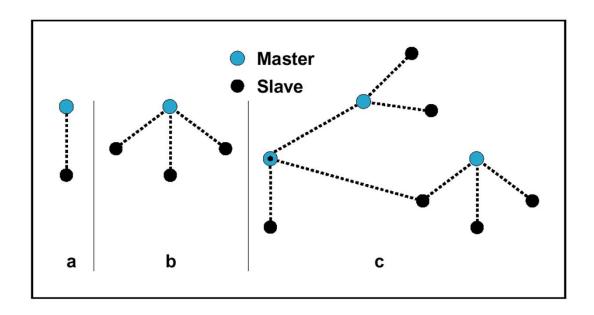




# **Hedy Lamarr**

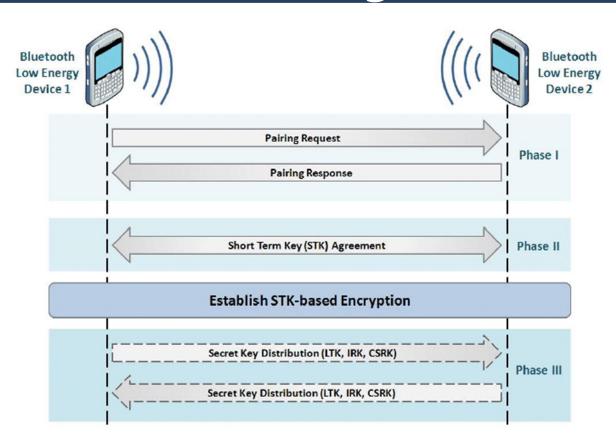


#### **Bluetooth Network**

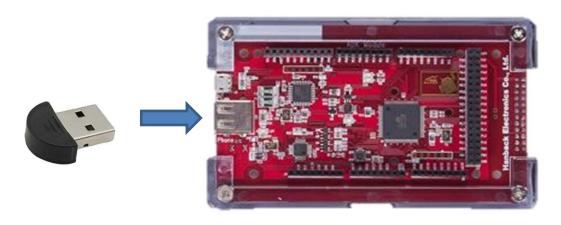


Piconets with a single slave operation (a), a multi-slave operation (b) and a scatternet operation (c).

# **Paring**



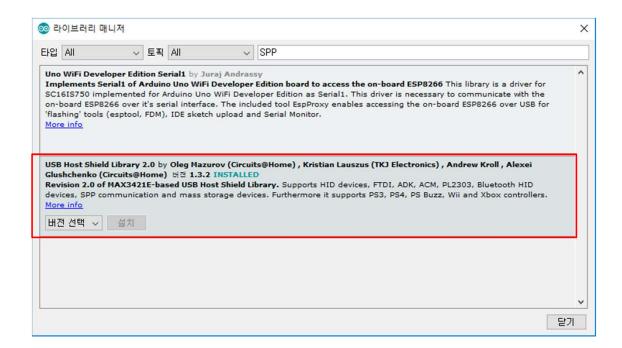
## **Bluetooth Dongle**





### **USB Host Shield Library**

- [스케치] [라이브러리 포함하기] [라이브러리 관리]
- 검색 : SPP



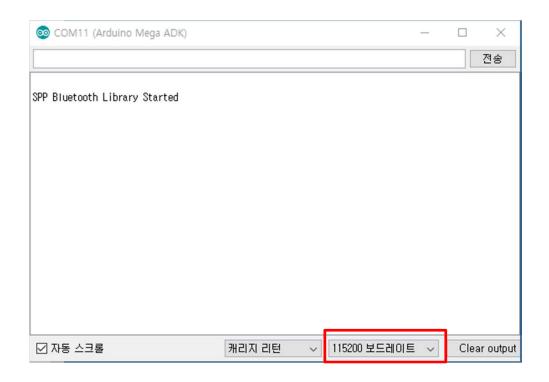
## M2-1: SPP define, setup()

```
#include <SPP.h>
#include <SPI.h>
USB Usb;
BTD Btd(&Usb);
//SPP SerialBT(&Btd); // defaults: Name ->"Arduino", pin -> "0000"
SPP SerialBT(&Btd, "YOONS-BT", "1234");
bool firstMessage = true;
void setup() {
 Serial.begin(115200);
 if (Usb.Init() == -1) {
   Serial.println(F("₩r₩nOSC did not start"));
   while (1); //halt
 Serial.println(F("₩r₩nSPP Bluetooth Library Started"));
```

## M2-1: SPP loop()

```
void loop() {
 Usb.Task();
 if (SerialBT.connected) {
   if (firstMessage) {
     firstMessage = false;
     SerialBT.println(F("Hello from Arduino")); // Send welcome message
   if (Serial.available( ))
     SerialBT.write(Serial.read( ));
   if (SerialBT.available( ))
     Serial.write(SerialBT.read( ));
 } else {
   firstMessage = true;
```

#### M2-1: Serial Monitor



# Bluetooth 설정



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## Play.google.com/store/apps



#### Bluetooth SPP &TCP/IP Terminal

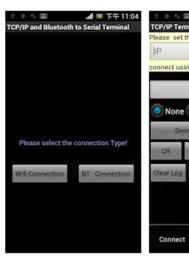
 Jason Hsu
 至子
 ★★★★★7息

 ③

⚠ 계정에 연결된 기기가 없습니다.

위시리스트에 추가



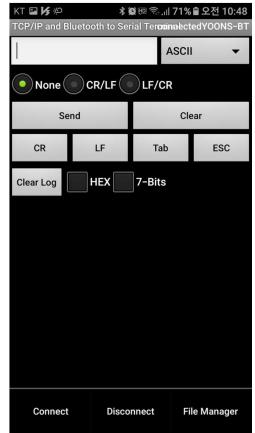






## **Bluetooth SPP App**



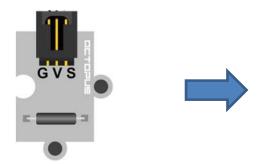






#### M2-2: Tilt Sensor

• Tilt Sensor의 기울어짐을 Bluetooth로 전송하여 보자

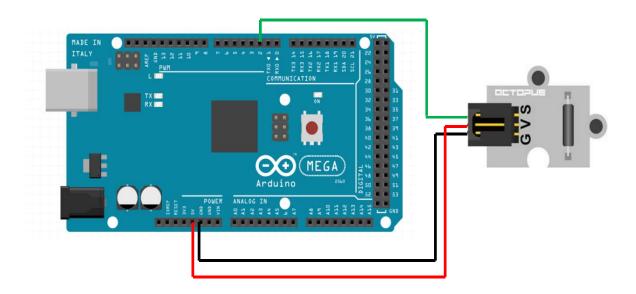




Start	Command	Status	End
'@'	'T'	0 : Normal 1 : Tilt	₩n



## Wiring



#### M2-2: Tilt define

```
#include <SPPh>
#include <SPI.h>
USB Usb;
BTD Btd(&Usb);
SPP SerialBT(&Btd, "YOONS-BT", "1234");
#define TILT 2
#define TX_Event_Packet_length 4
unsigned char TX_Event_data[TX_Event_Packet_length] = {'@', 'T', '0', '\n' };
unsigned char TX_Event_flag = 0;
uint8_t Tilt_Value = 0, Tilt_pre = 0;
uint32 t Time check Tilt = 0;
```

## M2-2: Tilt setup()

```
void setup() {
 Serial.begin(115200);
 if (Usb.Init() == -1) {
   Serial.println(F("₩r₩nOSC did not start"));
   while (1); //halt
 Serial.println(F("₩r₩nSPP Bluetooth Library Started"));
 pinMode(TILT, INPUT_PULLUP);
 attachInterrupt(digitalPinToInterrupt(TILT), TILT_ISR, CHANGE);
```

## M2-2: Tilt loop()

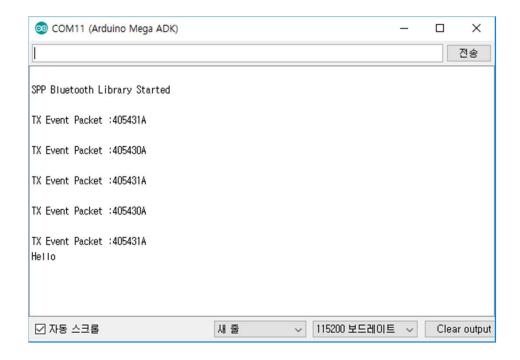
```
void loop() {
 Usb.Task();
 if (SerialBT.connected) {
   if(TX Event flag == 1) {
     SerialBT.write(TX_Event_data, TX_Event_Packet_length);
     Serial.print("₩n₩rTX Event Packet :");
     for (int k=0;k<TX_Event_Packet_length;k++){
      Serial.print(TX_Event_data[k],HEX);
     Serial.println();
    TX_Event_flag = 0;
   if (Serial.available( )) SerialBT.write(Serial.read( ));
   if (SerialBT.available( )) Serial.write(SerialBT.read( ));
```

```
if((Time_check_Tilt + 250) < millis()) {
   if(Tilt_pre != Tilt_Value) {
      Tilt_pre = Tilt_Value;
      TX_Event_data[2] = Tilt_Value | 0x30;
      TX_Event_flag = 1;
   }
}</pre>
```

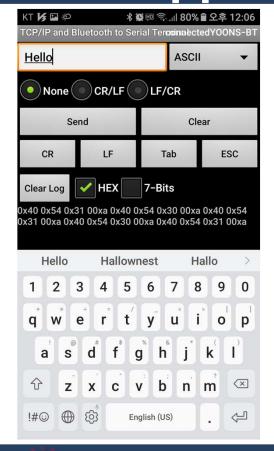
## M2-2: Tilt Tilt\_ISR()

```
void TILT_ISR(void) {
 Tilt_Value = !digitalRead(TILT);
 Time_check_Tilt = millis();
```

#### M2-2: Serial Monitor



## M2-2: App Monitor





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