

Design Theory for Relational Databases

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Originally based on slides by Jeff Ullman

Introduction

- ◆ There are always many different **schemas** for a given set of data.
- ◆ E.g., you could combine or divide tables.
- ◆ How do you pick a schema? Which is better? What does “better” mean?
- ◆ Fortunately, there are some principles to guide us.



Database Design Theory

- ◆ It allows us to improve a schema **systematically**.
- ◆ General idea:
 - ◆ Express **constraints** on the relationships between attributes
 - ◆ Use these to **decompose** the relations
- ◆ Ultimately, get a schema that is in a “**normal form**” that guarantees good properties, such as no *anomalies*.
- ◆ “Normal” in the sense of conforming to a standard.
- ◆ The process of converting a schema to a normal form is called **normalization**.

Agenda

- ◆ Functional Dependencies (FD)
- ◆ Closure
- ◆ FD Projection
- ◆ Minimal Cover
- ◆ Normalization: BCNF, 3NF

Part I:

Functional Dependency Theory



A poorly designed table

part	manufacturer	manAddress	seller	sellerAddress	price
1983	Hammers `R Us	99 Pinecrest	ABC	1229 Bloor W	5.59
8624	Lee Valley	102 Vaughn	ABC	1229 Bloor W	23.99
9141	Hammers `R Us	99 Pinecrest	ABC	1229 Bloor W	12.50
1983	Hammers `R Us	99 Pinecrest	Walmart	5289 St Clair W	4.99

- ◆ In any domain, there are relationships between attribute values.
- ◆ Perhaps:
 - ◆ Every part has 1 manufacturer
 - ◆ Every manufacture has 1 address
 - ◆ Every seller has 1 address
- ◆ If so, this table will have redundant data.

Principle: Avoid redundancy

Redundant data can lead to **anomalies**.

part	manufacturer	manAddress	seller	sellerAddress	price
1983	Hammers `R Us	99 Pinecrest	ABC	1229 Bloor W	5.59
8624	Lee Valley	102 Vaughn	ABC	1229 Bloor W	23.99
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- **Update anomaly**: if Hammers `R Us moves and we update only one tuple, the data is inconsistent.
- **Deletion anomaly**: If ABC stops selling part 8624 and Lee Valley makes only that one part, we lose track of its address.

Definition of FD

- ◆ Suppose R is a relation, and X and Y are subsets of the attributes of R .
- ◆ $X \rightarrow Y$ asserts that:
 - ◆ If two tuples agree on all the attributes in set X , they must also agree on all the attributes in set Y .
- ◆ We say that " $X \rightarrow Y$ holds in R ", or " X functionally determines Y ."
- ◆ An FD constrains what can go in a relation.

More formally...

$A \rightarrow B$ means:

\forall tuples t_1, t_2 ,

$$(t_1[A] = t_2[A]) \Rightarrow (t_1[B] = t_2[B])$$

Or equivalently:

$\neg \exists$ tuples t_1, t_2 such that

$$(t_1[A] = t_2[A]) \wedge (t_1[B] \neq t_2[B])$$

Generalization to multiple attributes

$A_1 A_2 \dots A_m \rightarrow B_1 B_2 \dots B_n$ means:

\forall tuples $t_1, t_2,$

$(t_1[A_1] = t_2[A_1] \wedge \dots \wedge t_1[A_m] = t_2[A_m]) \Rightarrow$

$(t_1[B_1] = t_2[B_1] \wedge \dots \wedge t_1[B_n] = t_2[B_n])$

Or equivalently:

$\neg \exists$ tuples t_1, t_2 such that

$(t_1[A_1] = t_2[A_1] \wedge \dots \wedge t_1[A_m] = t_2[A_m]) \wedge$

$\neg (t_1[B_1] = t_2[B_1] \wedge \dots \wedge t_1[B_n] = t_2[B_n])$

Why “functional dependency”?

- ◆ “dependency” because the value of Y depends on the value of X .
- ◆ “functional” because there is a function that takes a value for X and gives a *unique* value for Y .
- ◆ (It’s not a typical function; just a lookup.)

Equivalent sets of FDs

- ◆ When we write a set of FDs, we mean that all of them hold.
- ◆ We can very often rewrite sets of FDs in equivalent ways.
- ◆ When we say S_1 is equivalent to S_2 we mean that:
 - ▶ S_1 holds in a relation iff S_2 does.

FD - Exercises

- ◆ 1. Create an instance of **R** that violates $BC \rightarrow D$
 - ▶ Any tuple with equal values of B,C but unequal D values!
- ◆ 2.a) Is the FD $A \rightarrow BC$ equivalent to the two FDs $A \rightarrow B$, $A \rightarrow C$?
 - ▶ Yes!
- ◆ 2.b) Is the FD $PQ \rightarrow R$ equivalent to the two FDs $P \rightarrow Q$, $P \rightarrow R$?
 - ▶ No.
 - ▶ Example..

P		Q		R

2		1		4
2		3		5

Splitting rules for FDs

- ◆ Can we split the RHS of an FD and get multiple, equivalent FDs?



- ◆ Can we split the LHS of an FD and get multiple, equivalent FDs?

Coincidence or FD?

- ◆ An FD is an assertion about *every* instance of the relation.
- ◆ You can't know it holds just by looking at one instance.
- ◆ You must use knowledge of the domain to determine whether an FD holds.

FDs are closely related to **keys**

- ◆ Suppose K is a set of attributes for relation R .
- ◆ Our old definition of superkey:
a set of attributes for which no two rows can have the same values.
- ◆ A claim about FDs:
 K is a **superkey** for R iff
 K functionally determines all of R .

FDs are a *generalization* of keys

- ◆ Superkey:

$X \rightarrow R$ ← All attributes

- ◆ Functional dependency:

$X \rightarrow Y$

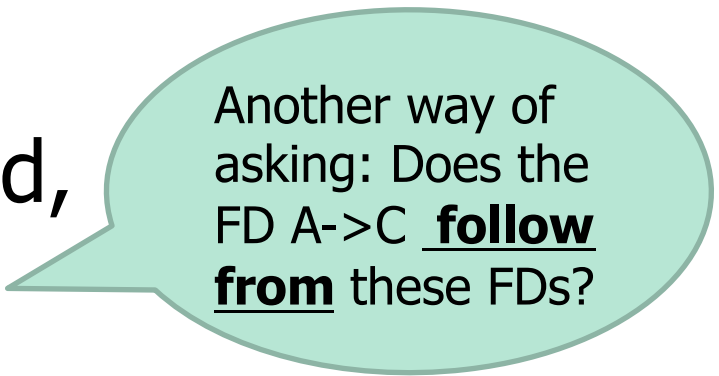
- ◆ A superkey must include *all* the attributes of the relation on the RHS.
- ◆ An FD can have just a subset of them.

Inferring FDs

- ◆ Given a set of FDs, we can often infer further FDs.
- ◆ This will come in handy when we apply FDs to the problem of database design.
- ◆ Big task: given a set of FDs, infer *every* other FD that must also hold.
- ◆ Simpler task: given a set of FDs, infer whether *a given* FD must also hold.

Examples

- ◆ If $A \rightarrow B$ and $B \rightarrow C$ hold, must $A \rightarrow C$ hold?



Another way of asking: Does the FD $A \rightarrow C$ **follow from** these FDs?

- ◆ If $A \rightarrow H$, $C \rightarrow F$, and $FG \rightarrow AD$ hold, must $FA \rightarrow D$ hold?
must $CG \rightarrow FH$ hold?

- ◆ Aside: we are not generating new FDs, but testing specific possible FD(s).

Prove an FD (LHS->RHS) **follows**

Method 1: using first principles

- ◆ You can prove it by referring back to
 - ◆ The FDs that you know hold, and
 - ◆ Apply FD inference rules (axioms)
- ◆ But the **Closure Test** is easier!

Prove an FD ($LHS \rightarrow RHS$) follows

Method 2: using the Closure Test

- ◆ Assume you know the values of the LHS attributes, and figure out:
everything else that is determined.

<e.g. restaurant name>

→ everything I can learn about it...?



- ◆ If the result includes the RHS attributes, then you know that $LHS \rightarrow RHS$ holds
- ◆ This is called the closure test.

***Y** is a set of attributes, **S** is a set of **FDs**.*

*Return the closure of **Y** under **S**.*

Attribute_closure(Y, S):

Initialize Y^+ to Y

Repeat until no more changes occur:

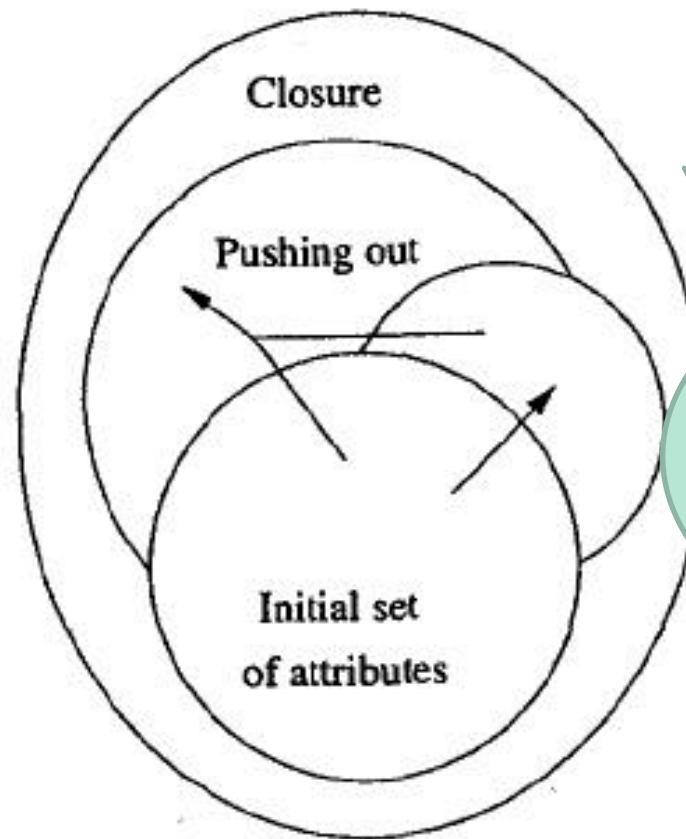
 If there is an FD **LHS \rightarrow RHS** in S
 such that LHS is in Y^+ :

 Add RHS to Y^+

Return Y^+

If LHS is in Y^+ and LHS \rightarrow RHS holds, we can add RHS to Y^+

Visualizing attribute closure



We can use closures to answer the **follows from** question!

If LHS is in Y^+ and $LHS \rightarrow RHS$ holds, we can add RHS to Y^+

*S is a set of FDs; LHS \rightarrow RHS is a single FD.
Return true iff LHS \rightarrow RHS follows from S.*

FD_follows(S, LHS \rightarrow RHS):

$Y^+ = \text{Attribute_closure}(\text{LHS}, S)$

return (RHS is in Y^+)

Exercise

- ◆ Suppose we have a relation on attributes **ABCDEF**, with FDs:

$AC \rightarrow F$, $CEF \rightarrow B$, $C \rightarrow D$, $DC \rightarrow A$

- a) Does it follow that **$C \rightarrow F$** ?

Ans: $C^+ = \dots$?

$C^+ = CDAF$

Then, $C \rightarrow F$ follows



- b) Does it follow that **$ACD \rightarrow B$** ?

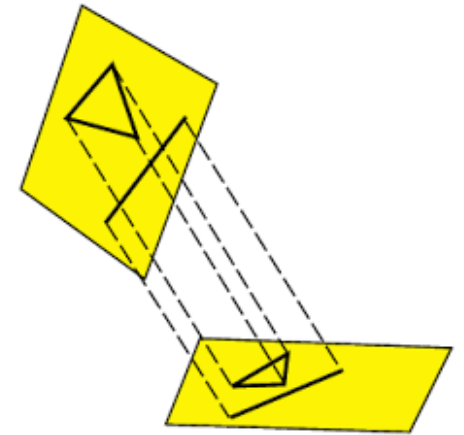
Ans: $ACD^+ = \dots$?

$ACD^+ = ACDF$

Then, $ACD \rightarrow B$ does **not** follow

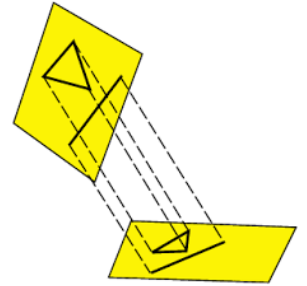


Projecting FDs



- ◆ Later, we will learn how to **normalize** a schema by **decomposing** relations.
(This is the whole point of this theory.)
- ◆ We will need to be aware of what FDs hold in the new, smaller, relations.
- ◆ In other words, we must **project our FDs** onto the attributes of our **new** relations.

Exercise - Projecting FDs



- ◆ Suppose we have a relation on attributes **ABCDE** with FDs: $A \rightarrow C$, $C \rightarrow E$, $E \rightarrow BD$

Project the FDs onto attributes **ABC:**

- ✓ To project onto a set of attributes, we systematically consider every possible LHS of an FD that might hold on those attributes.

$A^+ =$

$B^+ =$

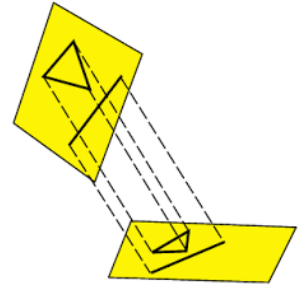
$C^+ =$

$AB^+ =$

$AC^+ =$

$BC^+ =$

Exercise - Projecting FDs



- ◆ Suppose we have a relation on attributes **ABCDE** with FDs: $A \rightarrow C$, $C \rightarrow E$, $E \rightarrow BD$

Project the FDs onto attributes **ABC**:

- ✓ To project onto a set of attributes, we systematically consider every possible LHS of an FD that might hold on those attributes.

$A^+ = ACEBD$

therefore $A \rightarrow BC$.

$B^+ = B$. Yields no FDs for our set of attributes.

$C^+ = CEBD$, therefore $C \rightarrow B$.

- ✓ We don't need to consider any supersets of **A**. A already determines all of our attributes ABC, so supersets of A will be only yield FDs that already *follow* from $A \rightarrow BC$.

- ✓ The only superset left is **BC**:

$BC^+ = BCED$. This yields no FDs for our set of attributes.

- So the projection of the FDs onto ABC is: $\{A \rightarrow BC, C \rightarrow B\}$

S is a set of FDs; L is a set of attributes.

Return the projection of S onto L:

all FDs that follow from S and involve only attributes from L.

Project(S, L):

Initialize T to {}.

For each subset X of L:

Compute X^+ *Close X and see what we get.*

For every attribute A in X^+ :

If A is in L: *$X \rightarrow A$ is only relevant if A is in L (we know X is).*

add $X \rightarrow A$ to T.

Return T.

A few speed-ups

- ◆ No need to add $X \rightarrow A$ if A is in X itself. It's a trivial FD.
- ◆ These subsets of X won't yield anything, so no need to compute their closures:
 - ▶ the empty set
 - ▶ the set of all attributes
- ◆ Neither are big savings, but ...

A big speed-up

- ◆ If we find $X^+ = \text{all attributes}$, we can ignore any *superset* of X .
 - ◆ It can only give use “weaker” FDs (with more on the LHS).
- ◆ This is a big time saver!

Projection is expensive

- ◆ Even with these speed-ups, projection is still expensive.
- ◆ Suppose R_1 has n attributes.
How many subsets of R_1 are there?
(A set of n elements has 2^n subsets)

Minimal Basis (aka Minimal Cover)

- ◆ We saw earlier that we can very often rewrite sets of FDs in equivalent ways.
- ◆ Example: $S_1 = \{A \rightarrow BC\}$ is equivalent to $S_2 = \{A \rightarrow B, A \rightarrow C\}$.
- ◆ Given a set of FDs S , we may want to find a **minimal basis**: A set of FDs that is equivalent, but has
 1. No redundant FDs
 2. No unnecessary attributes on the LHS

S is a set of FDs. Return a minimal basis for S.

Minimal_basis(S):

Repeat until no more changes result:

1. Remove FDs that are implied by the rest.
2. For each FD with 2⁺ attributes on the left:

If you can remove one attribute
from the LHS and get an FD that
follows from the rest:

Do so! (It's a stronger FD.)

Example – Minimal Basis

- ◆ What is the minimal cover of these FDs in ABCDEG:

$$A \rightarrow B, \quad ABCD \rightarrow E, \quad G \rightarrow A, \quad G \rightarrow B$$

Answer:

(1) Can any of the FDs be implied from another FD? (if so, **drop**)

***Systematic approach:**

- Calculate the closure of the LHS in each FD, using the rest of FDs;
Can we reach the RHS using the other FDs?

1. $A \rightarrow B$

A^+ under $\{2,3,4\}$? = ...

2. $ABCD \rightarrow E$

$ABCD^+$ under $\{1,3,4\}$? = ...

3. $G \rightarrow A$

G^+ under $\{1,2,4\}$? = ...

4. $G \rightarrow B$

G^+ under $\{1,2,3\}$? = GAB

- **Drop FD#4.**

Example – Minimal Basis

- ◆ What is the minimal cover of these FDs in ABCDEG:

$A \rightarrow B$, $ABCD \rightarrow E$, $G \rightarrow A$, ~~$G \rightarrow B$~~

Answer:

(2) Check if any LHS can be reduced (any attributes can be removed?). If so, **drop** the extra attributes.

1. $A \rightarrow B$

2. $ABCD \rightarrow E$

Start with removing 1 attribute.. (ACD+, ABC+, BCD+, ..and so on)

ACD+ = ABCD

3. $G \rightarrow A$

Example – Minimal Basis

- ◆ What is the minimal cover of these FDs in ABCDEG:

$$A \rightarrow B, \quad ABCD \rightarrow E, \quad G \rightarrow A, \quad \cancel{G \rightarrow B}$$

Answer:

(2) Check if any LHS can be reduced (any attributes can be removed?). If so, **drop** the extra attributes.

1. $A \rightarrow B$

~~2. $ABCD \rightarrow E$~~

Start with removing 1 attribute.. (ACD+, ABC+, BCD+, ..and so on)

$$ACD+ = ABCD$$

2. $ACD \rightarrow E$

3. $G \rightarrow A$

➤ Result: Minimal basis is $A \rightarrow B, \quad ACD \rightarrow E, \quad G \rightarrow A$

Please check course website for more detailed examples

Some comments on computing a minimal basis

- ◆ Often there are multiple possible results, depending on the order in which you consider the possible simplifications.
- ◆ After you identify a **redundant** FD, you must **not** use it when computing any subsequent closures (as you consider whether other FDs are redundant).

... and some that are less intuitive

- ◆ When you are computing closures to decide whether the LHS of an FD

$$a_1 a_2 \dots a_m \rightarrow b_1 b_2 \dots b_n$$

can be simplified, continue to use that FD.

- ◆ When you have tried to eliminate each FD and to reduce each LHS, you must go back and try again.