$F(x,y,z) = x^2 + y^2 - z^2 = 0$ rapresents a double cone Z_Z-axis is axis of revolution, and generator is Z=x or Z=y.

_generador

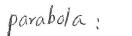
Circle, elipse, paral-ola and hypubold

are called conic Sections because They are made of intersection of L planes with The cone:

Circle: plane perp to
The axis

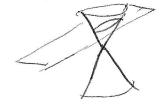


) Slanted plane -> elgs

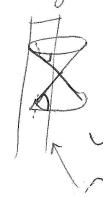


plane is parallel to





hyperbola is when The plane is not parallel to the generator and meets The both Cones:



a)
$$G(x,y,z) = Z-3=0$$
 SIn to $F=0=G$ is
$$\begin{cases}
\chi^{2}+y^{2}-9=0 \\
Z=3
\end{cases}
\text{ or }
\begin{cases}
\chi^{2}+y^{2}=9 \\
Z=3
\end{cases}
\text{ if }
\begin{cases}
2\chi^{2}+y^{2}=9 \\
Z=3
\end{cases}$$

Conversion to (i) is possible as long as a 2x2 Sub-matrix of DF is detected with det ± 0 . For example as long as 10 cally y ± 0 . Then y and z can be Solved in terms of x $y = \sqrt{9-x^2} \quad \text{at pts} \quad (0, \pm 3, 3) \quad \text{only} \quad y^2 \in \mathbb{R}^2 \text{ can be Solved} \\
2 = 3 = f(x) \quad \text{and at The phs} \quad (\pm 3, 0, 3) \quad \text{only} \quad x_2 = x_3 = x_4 = x_4$

b)
$$Y=2$$
 (plane parallel to The axis of rotation)

 $G(x.y.z)=y-2=0$
 $F(x.y.z)=0=\begin{bmatrix} F(x.y.z) \\ G(x.y.z) \end{bmatrix}=\begin{bmatrix} x^2+y^2-z^2 \\ y-2 \end{bmatrix}=\begin{bmatrix} 0 \end{bmatrix}$ no intersection

is $\begin{cases} x^2-z^2-4 \\ y=2 \end{cases}$ hyperbola

 $f(x,y,z)=0=\begin{bmatrix} 2x & 2x & -2z \\ 0 & 1 & 0 \end{bmatrix}$
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 $f(x,y,z)=0=\begin{bmatrix} 2x & 2x & 2x & -2z \\ 0 & 1 &$

C)
$$G(x,y,z) = z + y - 2 = 0$$

$$x^{2} + y^{2} - (2 - y)^{2} = x^{2} + 4y - 4 = 0$$
 $y = 1 - \frac{x^{2}}{4}$

$$DF = \begin{bmatrix} 2x & 2y & -2z \\ 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 2x' & 2y & 2y - 4 \\ 0 & 1 & 1 \end{bmatrix}$$

$$DF = \begin{bmatrix} 2x & 2y & -2z \\ 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 2x & 2y & 2y - 4 \\ 0 & 1 & 1 \end{bmatrix}$$

$$\begin{cases}
Y = 1 - \frac{\chi^{2}}{4} \\
Z = 2 - y = 2 - (1 - \frac{\chi^{2}}{4}) = 1 + \frac{\chi^{2}}{4}
\end{cases}$$

$$G(x, y, z) = 2z + y = 4 = 0$$

is equation of a plane That is not people

The pipper part ; no The resulting

carre à an elipse n

$$\int Z = \frac{8 \pm \sqrt{64 + 20(16 - x^{2})}}{10}$$

of Course old
$$\begin{bmatrix} 24 & 24-4 \end{bmatrix}$$

= $4 \neq 0$

$$\chi_{+}^{2}(4-2Z)+Z=0$$

$$\chi^2 + 52^2 - 8Z = 16$$

Solve
$$y = z = i$$

Solve $y = z = i$

Solve $y = z = i$
 $z = z$

$$\begin{cases} 4y + 2z = 0 & y \neq \frac{3}{4} \\ 2z + 4 = 4 \end{cases}$$

$$\pm rafers + 6 - \frac{1}{2} \times \frac{1}{2} \times$$

Then
$$\chi = -\frac{3}{4}$$
 Then $\chi = \frac{19}{8}$ Then $\chi \neq 0$ (from $\chi^2 + \chi^2 - \chi^2 = 0$)

Then $\chi = \frac{2\chi^2}{4}$ has nonzero determinant and so χ and χ can be solved in torm $\chi = \frac{\chi^2}{4} - 2\chi$

$$\chi = \chi^2 - (4 - 2\chi)^2$$

$$\chi = \chi^2 - (4 - 2\chi)^2$$

2.
$$f(u,v) = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} u C_0 v \\ u S_m v \\ \sqrt{u} \end{bmatrix}$$

note x+y=u and z=vu 10 n2+17=24

So The location of nity=z4 is

so level curves one Z=c (are circles)

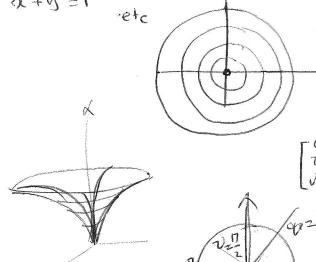
Birda eyes View:

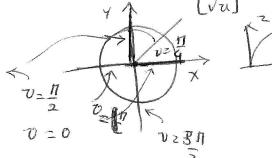
2=0 => 71=0 => x+y=u=0

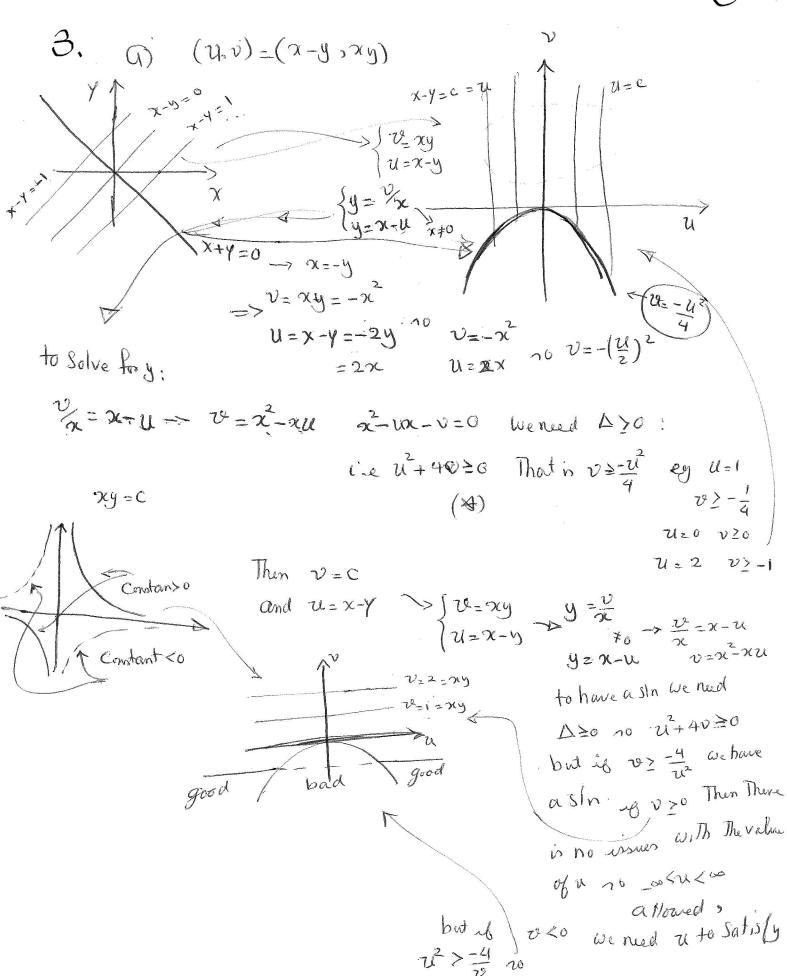
a point only Z=1 2+5=1

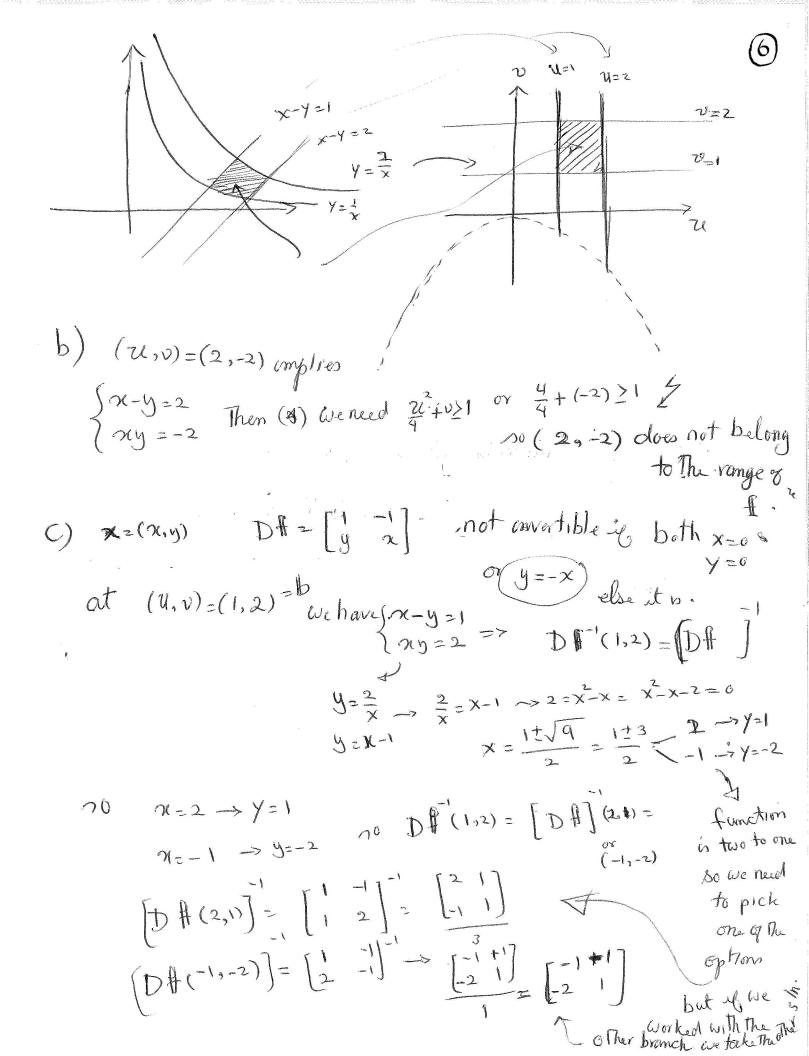
-U=0,1,4,9 gives

W=0 gives











- Assume $f: \mathbb{R}^2 \longrightarrow \mathbb{R}$ is C^1 . Show that f cannot be a one to one function in two ways:
 - a) using implicit function theorem:

sln: This is an important technique: using a function like f(x,y) to define a function F(x,y) which satisfies the conditions of the IFT (3.1). At a point (a,b) we define F(x,y)=f(x,y)-f(a,b) and note that since f is C^1 then so is F, and furthermore if either of the $f_x(a,b)$ or $f_y(a,b)$ is non-zero (which should be, as otherwise $\nabla f(a,b)=0$ and therefore f would be constant,) then one of the $F_x(a,b)$ or $F_y(a,b)$ should be non-zero. Now the conditions of the IFT are satisfied and then there must be some $r_0>0$ such that $\forall x, |x-a|< r_0$ implies there is a unique g such that f(x,y)=0. But this means f(x,y)=f(a,b), which means that f is not 1-1 near f(a,b). Indeed this function is not one to one in the neighborhood of any point.

b) using the Inverse Mapping Theorem

sln: Of course the inverse mapping theorem is to be applied to the functions from \mathbb{R}^n to \mathbb{R}^n . So to apply the IMT to this questions we must convert our problem into one that fits the description of the IMT. Assuming that $f_x(a,b) \neq 0$ we define a new function g(x,y) = (f(x,y),y) and notice that

$$D\mathbf{g}(a,b) = \begin{bmatrix} f_x(a,b) & 0 \\ f_y(a,b) & 1 \end{bmatrix}$$

which is invertible as $f_x(a,b) \neq 0$, so that by an application of IMT there are two neighborhoods U and V (of (a,b) and (f(a,b),b) on which \mathbf{g} is a one to one function, and on V the function \mathbf{g}^{-1} is defined. In the neighborhood V consider two points with different values of y and same values for x (there must be a 'vertical' line in V); call these points P and Q. Because of the inverse function here must be two distinct points of U that correspond to these two points; call them (x_1,y_1) and (x_2,y_2) , say $\mathbf{g}(x_1,y_1)=P$ and $\mathbf{g}(x_2,y_2)=Q$. Therefore $(f(x_1,y_1),y_1)=P$ and $(f(x_2,y_2),y_2)=Q$. Recall that the y coordinates of the points P and Q are different (that is $y_1 \neq y_2$) and the x coordinates are the same, (that is $f(x_1,y_1)=f(x_2,y_2)$.) This implies the function f is not one to one. (Of course $y_1 \neq y_2$ implies that the points (x_1,y_1) and (x_2,y_2) are distinct points.)

5. (in general when f is only integrall. and not necessarily Continuous part (b) of FTC downot apply)

$$\int_{a}^{b} 2x f(x^{2}) dx = \int_{u=a^{2}}^{b^{2}} f(u) du = \int_{x=a^{2}}^{b^{2}} f(x) dx \quad \text{(when } a < a < b < a)$$

$$\int_{u=a^{2}}^{b} f(u) du = \int_{x=a^{2}}^{b^{2}} f(u) du = \int_{x=a^{2}}^{a} f(u) du = \int_{a}^{a} f(u) du = \int_{a$$

19'(x) make a

Sign Correction