

STA457/2202H1S PRACTICE QUESTIONS & SHORT ANSWERS

Question 1 (Random walk): $Y_t = Y_{t-1} + e_t$, $e_t \sim NID(0, \sigma_e^2)$. Show that for $1 \leq t \leq s$

- (1) $E(Y_t) = 0$
- (2) $var(Y_t) = t\sigma_e^2$
- (3) $\gamma(t, s) = t\sigma_e^2$
- (4) $\rho(t, s) = \sqrt{t/s}$
- (5) Show that $\lim_{t \rightarrow \infty} \rho(h) = 1$ for moderate h .

Answer: WLOG, we can assume that $Y_1 = e_1$ (i.e., $Y_0 = 0$) and therefore, $Y_t = Y_{t-1} + e_t = e_1 + e_2 + \dots + e_t$.

- (1) $E(Y_t) = E(e_1 + e_2 + \dots + e_t) = 0$
- (2) $Var(Y_t) = Var(e_1 + e_2 + \dots + e_t) = \sum_{i=1}^t Var(e_i) = t\sigma_e^2$
- (3) $\gamma(t, s) = Cov(e_1 + \dots + e_t, e_1 + \dots + e_t + e_{t+1} + \dots + e_s) = \sum_{i=1}^s \sum_{j=1}^t Cov(e_i, e_j) = t\sigma_e^2$ for $1 \leq t \leq s$
- (4) $\rho(t, s) = \frac{\gamma(t, s)}{\sqrt{\gamma(t, t)\gamma(s, s)}} = \frac{t\sigma_e^2}{\sqrt{t\sigma_e^2 \times s\sigma_e^2}} = \sqrt{t/s}$.
- (5) $\rho(h) = \rho(t, t+h) = \sqrt{t/(t+h)}$.

Question 2 (Moving average of order 2): $Y_t = 0.5 e_t + 0.5 e_{t-1}$, $e_t \sim NID(0, \sigma_e^2)$. Show that

- (1) $E(Y_t) = 0$
- (2) $var(Y_t) = 0.5 \sigma_e^2$
- (3) $\gamma(t, s) = \begin{cases} 0.5 \sigma_e^2, & t = 0 \\ 0.25 \sigma_e^2, & |t - s| = 1 \\ 0, & |t - s| > 1 \end{cases}$
- (4) $\rho(t, s) = \begin{cases} 1, & t = 0 \\ 0.5, & |t - s| = 1 \\ 0, & |t - s| > 1 \end{cases}$

Answer:

$$\mu_t = E(Y_t) = E\left\{\frac{e_t + e_{t-1}}{2}\right\} = \frac{E(e_t) + E(e_{t-1})}{2} = 0$$

$$Var(Y_t) = Var\left\{\frac{e_t + e_{t-1}}{2}\right\} = \frac{Var(e_t) + Var(e_{t-1})}{4} = 0.5\sigma_e^2$$

$$\begin{aligned}
Cov(Y_t, Y_{t-1}) &= Cov\left\{\frac{e_t + e_{t-1}}{2}, \frac{e_{t-1} + e_{t-2}}{2}\right\} \\
&= \frac{Cov(e_t, e_{t-1}) + Cov(e_t, e_{t-2}) + Cov(e_{t-1}, e_{t-1})}{4} \\
&\quad + \frac{Cov(e_{t-1}, e_{t-2})}{4} \\
&= \frac{Cov(e_{t-1}, e_{t-1})}{4} \quad (\text{as all the other covariances are zero}) \\
&= 0.25\sigma_e^2
\end{aligned}$$

Furthermore,

$$\begin{aligned}
Cov(Y_t, Y_{t-2}) &= Cov\left\{\frac{e_t + e_{t-1}}{2}, \frac{e_{t-2} + e_{t-3}}{2}\right\} \\
&= 0 \quad \text{since the } e's \text{ are independent.}
\end{aligned}$$

Similarly, $Cov(Y_t, Y_{t-k}) = 0$ for $k > 1$, so we may write

$$\gamma_{t,s} = \begin{cases} 0.5\sigma_e^2 & \text{for } |t-s| = 0 \\ 0.25\sigma_e^2 & \text{for } |t-s| = 1 \\ 0 & \text{for } |t-s| > 1 \end{cases}$$

$$\begin{aligned}
\gamma_{t,s} &= E\left\{\cos\left[2\pi\left(\frac{t}{12} + \Phi\right)\right]\cos\left[2\pi\left(\frac{s}{12} + \Phi\right)\right]\right\} \\
&= \int_0^1 \cos\left[2\pi\left(\frac{t}{12} + \phi\right)\right]\cos\left[2\pi\left(\frac{s}{12} + \phi\right)\right]d\phi \\
&= \frac{1}{2}\int_0^1 \left\{\cos\left[2\pi\left(\frac{t-s}{12}\right)\right] + \cos\left[2\pi\left(\frac{t+s}{12} + 2\phi\right)\right]\right\}d\phi \\
&= \frac{1}{2}\left\{\cos\left[2\pi\left(\frac{t-s}{12}\right)\right] + \frac{1}{4\pi}\sin\left[2\pi\left(\frac{t+s}{12} + 2\phi\right)\right]\right\}\bigg|_{\phi=0}^1 \\
&= \frac{1}{2}\cos\left[2\pi\left(\frac{t-s}{12}\right)\right]
\end{aligned}$$

Question 4 Consider a MA(1) process as

$$X_t = a_t + \theta a_{t-1}, \quad a_t \sim NID(0, \sigma^2).$$

Calculate $var(X_1 + X_2 + X_3)$.

Answer: Skip

Question 5 (General linear process): A general linear process, or $MA(\infty)$ process in class, is a weighted linear combination of present and past white noise terms as

$$Y_t = a_t + \psi_1 a_{t-1} + \psi_2 a_{t-2} + \dots = \sum_{j=0}^{\infty} \psi_j a_{t-j},$$

where $\psi_0 = 1$, $\sum_{j=1}^{\infty} |\psi_j| < \infty$, and $a_t \sim NID(0, \sigma^2)$. Show that

- (1) $E(Y_t) = 0$,
- (2) $\gamma(h) = \sigma^2 \sum_{i=0}^{\infty} \psi_i \psi_{i+|h|}$ for $|h| = 0, 1, 2, 3, \dots$

Answer: Skip

Question 6 (MA(q) processes): $Y_t = \mu + a_t - \theta_1 a_{t-1} - \dots - \theta_q a_{t-q}$, $a_t \sim NID(0, \sigma^2)$.

Show that

- (1) $E(Y_t) = \mu$,
- (2) $\gamma(0) = \sigma^2(1 + \theta_1^2 + \theta_2^2 + \dots + \theta_q^2)$,
- (3) $\gamma(h) = \text{Cov}(Y_t, Y_{t+h}) = \begin{cases} \sigma^2(-\theta_h + \theta_1 \theta_{h+1} + \dots + \theta_{q-h} \theta_q), & h = 1, 2, \dots, q \\ 0, & h > q \end{cases}$.
- (4) Suppose that $\{Y_t\}$ is invertible and can be expressed as $Y_t = \sum_{j=1}^{\infty} \pi_j X_{t-j} + a_t$. Find π_j for $j = 0, 1, 2, 3, 4, 5$.

Answer: (1), (2) and (3) skip

$$\text{Invertible} \rightarrow \pi(B)X_t = a_t \rightarrow \frac{\phi(B)}{\theta(B)}X_t = a_t \rightarrow \pi(B) = \phi(B)/\theta(B) \rightarrow \pi(B)\theta(B) = \phi(B)$$

$$(1 + \pi_1 B + \pi_2 B^2 + \pi_3 B^3 + \dots)(1 - \theta_1 B - \theta_2 B^2 - \dots - \theta_q B^q) = 1$$

Match coefficients of B^j , $j = 0, 1, 2, 3, 4, 5$. We can solve for π_j for $j = 0, 1, 2, 3, 4, 5$.

Question 6 (Stationary AR(2) processes):

$Y_t - \phi_1 X_{t-1} - \phi_2 X_{t-2} = \mu + a_t$, $a_t \sim NID(0, \sigma^2)$. Show that

- (1) $E(Y_t) = \mu/(1 - \phi_1 - \phi_2)$,
- (2) Write down the corresponding Yule-Walker equations.
- (3) Calculate the partial autocorrelation functions of $\{Y_t\}$ for lag=1, 2, 3, ...
- (4) Suppose that the casual representation of $\{Y_t\}$ is given by $Y_t = \sum_{j=0}^{\infty} \psi_j a_{t-j}$. Find ψ_j for $j = 0, 1, 2, 3, 4, 5$.

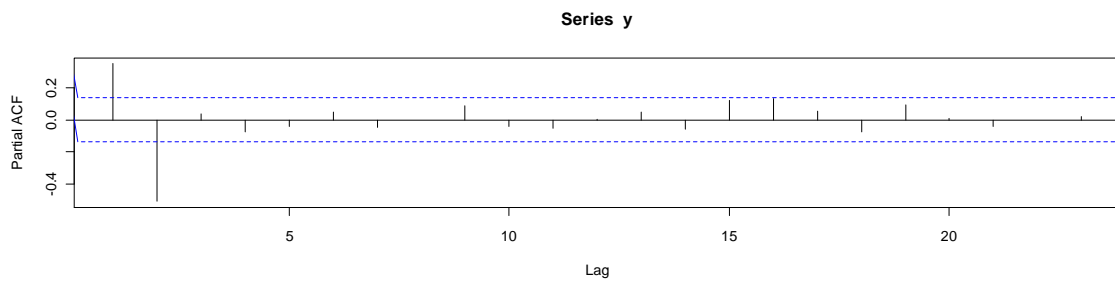
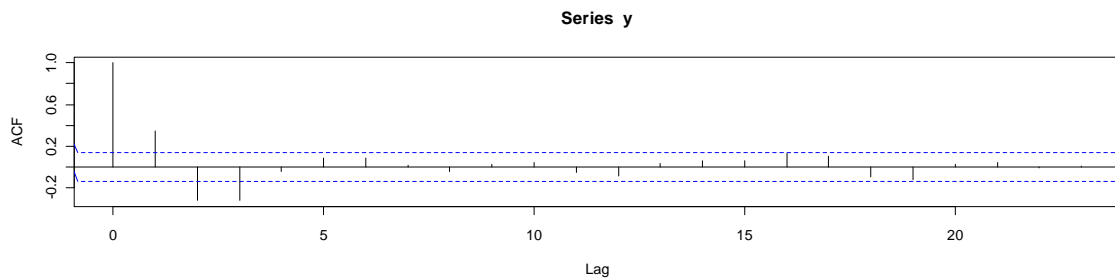
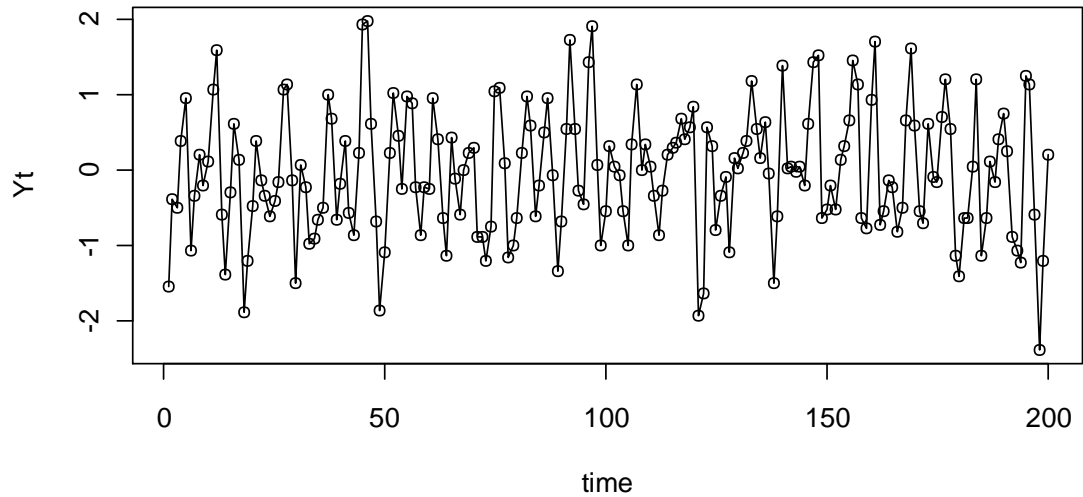
Answer: Skip (See course note).

$$\text{casual} \rightarrow X_t = \psi(B)a_t \rightarrow X_t = \frac{\theta(B)}{\phi(B)}a_t \rightarrow \psi(B) = \theta(B)/\phi(B) \rightarrow \psi(B)\phi(B) = \theta(B)$$

$$(1 + \psi_1 B + \psi_2 B^2 + \psi_3 B^3 + \dots)(1 - \phi_1 B - \phi_2 B^2) = 1$$

Match coefficients of B^j , $j = 0,1,2,3,4,5$. We can solve for ψ_j for $j = 0,1,2,3,4,5$.

Question 7 (The method of moment estimation): An analyst decides to find an AR(2) model for this time series by observing the time series plot and correlogram of $\{Y_t\}$ below.



The analyst calculated the sample autocorrelation functions of $\{Y_t\}$ for $\hat{\rho}(h)$, $h = 1,2,3, \dots, 10$ and the results are listed below.

lag	1	2	3	4	5	6	7	8	9	10
rho	-0.78	0.64	-0.53	0.43	-0.36	0.29	-0.24	0.20	-0.16	0.13

- (1) Does the analyst make the correct decision to fit an $AR(2)$ model? Why and why not?
- (2) Estimate the autoregressive parameters, i.e., ϕ_1 and ϕ_2 , using the method of moments.
(Hint: Yule-Walker equations)
- (3) Is the model stationary?
- (4) Suppose the residual autocorrelations functions for lag 1,2,3, ... 10 are

$$\{0.030 \quad -0.072 \quad 0.013 \quad 0.020 \quad -0.131 \quad 0.036 \quad 0.057 \quad -0.063 \quad 0.019 \quad 0.054\}$$

Check the model adequacy using the Ljung-box test for $m = 5, 10$.

Answer:

- (1) Yes, PACF cut off at lag 2.
- (2) $\phi_1 \approx -0.7, \phi_2 \approx 0.1$ (since the sample ACF in the question contain rounding errors)
- (3) Solving $1 - \phi_1 B - \phi_2 B^2 = 0$. The time series is stationary if the roots are outside unit circle.
- (4) $Q_{LB}(10) = n(n+2) \sum_{k=1}^{10} (n-k)^{-1} r_k^2 = 200 \cdot 202 \left(\frac{0.03^2}{200-1} + \frac{(-0.072)^2}{200-2} + \dots + \frac{0.054^2}{200-10} \right)$

Question 8 (Definition)

- (1) Define strictly and weakly stationary time series. What is the relationship between them?
- (2) Describe the general approach to time series modeling.
- (3) Define an autoregressive moving average model of order p and q ($ARMA(p, q)$).
- (4) What is the dual relationship between AR and MA models.
- (5) Define *Wold Decomposition*. How does this method provide support to the use of $ARMA$ models?
- (6) Derive the Yule-Walker equations for an $AR(p)$ process.
- (7) Define partial autocorrelation functions.
- (8) Describe two methods of model selection that were introduced in class.

Question 10 (Causal/stationary and invertible process): Determine which of the following processes are causal and/or invertible. Assume that $a_t \sim NID(0,1)$.

- (1) $X_t + 0.2X_{t-1} - 0.48X_{t-2} = a_t$ [causal/stationary and invertible]
- (2) $X_t + 1.9X_{t-1} + 0.88X_{t-2} = a_t + 0.2a_{t-1} + 0.7a_{t-2}$ [causal/stationary and invertible]
- (3) $X_t + 0.6X_{t-2} = a_t + 1.2a_{t-1}$ [causal/stationary but not invertible]
- (4) $X_t + 1.8X_{t-1} + 0.81X_{t-2} = a_t$ [causal/stationary and invertible]
- (5) $X_t + 1.6X_{t-1} = a_t - 0.4a_{t-1} + 0.04a_{t-2}$ [not causal/nonstationary but invertible]