

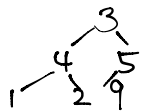
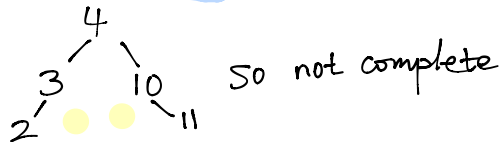
next wednesday midterm 2
cover up and until last week's material.

last week: BSTs, search, insert, delete

a new ADT: priority queue
example: insert some items with priority
related methods: find max, extract max, insert

implement priority queue with an ADT called Heaps.
binary trees with two invariants:
1. "complete"
2. Heap property
but note that it is different from BST

what does **complete** mean? "up and left"



complete \Rightarrow write in a list [3, 4, 5, 1, 2, 9]
b/c there's no gap

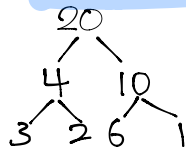
index 1 2 3 4 5 6

↓
 $\text{left} = 2 * \text{index}$
 $\text{right} = 2 * \text{index} + 1$

list representation only works for heaps

heap property:

node item \geq all items in subtrees



```
def __init__(self):  
    self.items = [None]
```

```
def is_empty(self):  
    return self.items == [None]
```

helper

```
def swap(self, i, j):  
    self.items[i], self.items[j] = self.items[j], self.items[i] # multiple assignment
```

```

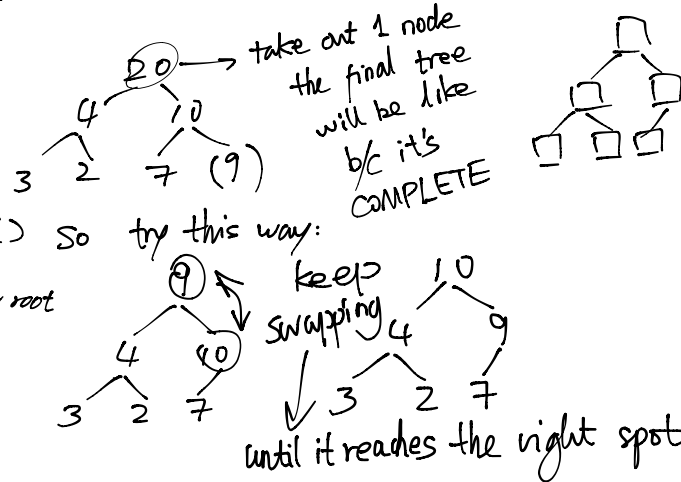
def get_max(self):
    if self.is_empty():
        raise IndexError
    else:
        # remember, self.items[1] is the ROOT of the heap
        return self.items[1]

```

```

def extract_max(self):
    if self.is_empty():
        raise IndexError
    else:
        largest = self.items[1]
        self.items[1] = self.items.pop()
        # last leaf removed
        # and make it the new root
        self.bubble_down(1)

```



return largest

```

def bubble_down(self, index):
    """(Heap, int) → NoneType
    Make it satisfy Heap property.
    """

```