

5.4

Vector derivatives

∇ del operator is the main tool in defining vector derivatives

$\frac{d}{dx}$ is the derivative operator, applied to scalar functions $f(x)$

$\frac{d}{dx} f(x) \rightarrow$ The result is a new function

$$\nabla(?) = \left(\frac{\partial}{\partial x_1} [?], \dots, \frac{\partial}{\partial x_n} [?] \right)$$

eg $\nabla f(x) = \left(\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n} \right)$ a vector
grad "f"

That captures direction of fastest change in values of $f(x)$

for a v.f.
 $F = \langle F_1, \dots, F_n \rangle$

We can apply ∇ in two ways

$\nabla \cdot F = \frac{\partial F_1}{\partial x_1} + \dots + \frac{\partial F_n}{\partial x_n}$
dot product, divergence, $\text{div } F$

measures expansion of F

$\nabla \times F = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}$
curl F
measure rotational component of F

Algebraic properties:

$\nabla \cdot (F \pm G) = \nabla \cdot F \pm \nabla \cdot G$
 $\nabla \times (F \pm G) = \nabla \times F \pm \nabla \times G$
etc

Second derivatives:

$\nabla \cdot \nabla f = \nabla^2 f$
Laplacian

Product rules (many possibilities)

$\nabla fg = f \nabla g + g \nabla f$

$\nabla (F \cdot G) = (F \cdot \nabla) G + F \times (\text{curl } G) + (G \cdot \nabla) F + G \times (\text{curl } F)$

$\nabla \cdot f F =$ See Pg 237

$\nabla \times f F = \nabla \times (F \times G) = \dots$
 $\nabla \cdot F \times G = \dots$

$\nabla \times F = 0$ can be generalized to \mathbb{R}^n by assuming

$\frac{\partial F_i}{\partial x_j} - \frac{\partial F_j}{\partial x_i} = 0$

See 5.61

$\nabla \times \nabla f = 0$

$\nabla \cdot \nabla \times F = 0$

$\nabla \cdot \nabla \times F \rightarrow \nabla \times \nabla f$
not!

grad f : applies on scalar f gives vector field

div F : applies on a v.f. F , produces a scalar function

curl F : applies on a v.f. produces a v.f.

like acceleration in higher dimension