8lns ps 8

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a) 
$$\int \nabla f \cdot dx = \int \nabla f (g(h)) \cdot g(h) dh$$

$$\int \frac{d}{dt} f(g(h)) dt = f(g(h)) \Big|_{a}^{b}$$

$$= f (g(b)) - f(g(a)) = f(B) - f(A)$$

b) 
$$SH \circ dx = \int_{0}^{2\pi} (-Sint_{3} Cost) \cdot (-Sint_{4} Cost) dt = 2\pi \neq 0$$
  
let C be The unit Circle  $g(t) = (Cost_{4}, Sint_{4})$   
 $g'(t) = (-Sint_{4}, Cost_{4})$ 

so HI # Vf for any C' function f.

C) 
$$\nabla x H = \begin{vmatrix} i & j & k \\ \partial_x & \partial_t & \partial_z \end{vmatrix} = 2k \neq 0 \text{ so } H \neq \nabla f \text{ as}$$

$$\begin{vmatrix} -y & x & 0 \end{vmatrix} = 2k \neq 0 \text{ so } H \neq \nabla f \text{ as}$$

$$\nabla x \nabla f = 0$$

d) 
$$P(x,y) = \frac{-9}{x^2 + y^2} \qquad \frac{\partial Q}{\partial x} = \frac{\partial P}{\partial y} = \frac{x^2 + y^2 - 2x^2}{(x^2 + y^2)^2} = O$$

$$Q(x,y) = \frac{x}{x^2 + y^2} \qquad \iint \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right) dA = O$$

$$S = \frac{1}{2} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right) dA = O$$

$$\int_{0}^{\infty} P dx + Q dy = \int_{0}^{\infty} + \int_{0}^{\infty} + \int_{0}^{\infty} + \int_{0}^{\infty} + \int_{0}^{\infty} P dx + \int_{0}^{\infty} Q dy +$$

$$= \int_{-2}^{2} \frac{2}{x^{2}+4} dx + \int_{-2}^{2} \frac{2}{4+y^{2}} dy + \int_{-2}^{2} \frac{-2}{t^{2}+4} dt + \int_{-2}^{2} \frac{-2}{4+t^{2}} dt$$

$$= \int_{-2}^{2} \frac{2}{x^{2}+4} dx + \int_{-2}^{2} \frac{2}{t^{2}+4} dt + \int_{-2}^{2} \frac{-2}{t^{2}+4} dt + \int_{-2}^{2} \frac{-2}{t^{2}+4} dt$$

$$= \int_{-2}^{2} \frac{2}{x^{2}+4} dx + \int_{-2}^{2} \frac{-2}{t^{2}+4} dt + \int_{-2}^{2} \frac{-2}{t^{2}+4} dt + \int_{-2}^{2} \frac{-2}{t^{2}+4} dt$$

$$= \int_{-2}^{2} \frac{2}{x^{2}+4} dx + \int_{-2}^{2} \frac{-2}{t^{2}+4} dt + \int_{-2}^{2} \frac{-2}{t^{2}+4} d$$

$$= 4 \int_{-2}^{2} \frac{2dt}{4+t^{2}} = 4 \int_{u=4}^{4} \frac{4du}{4+4u^{2}} = 4 \int_{i+u^{2}}^{i} \frac{du}{4+4u^{2}} = 4 \int_{i+u^{2}}^{4} \frac{du}{4+4u^{2}}$$

$$\nabla \tan \frac{y}{x} = \begin{bmatrix} \frac{-Y/x^2}{1+(\frac{y}{x})^2} \\ \frac{y_x}{1+(\frac{y}{x})^2} \end{bmatrix} = \begin{bmatrix} \frac{-Y}{x^2+y^2} \\ \frac{x}{x^2+y^2} \end{bmatrix}$$

Then 
$$\int H \cdot dx = \int \nabla f \cdot dx = 0$$
 by as lies within The

ragion where tan'x is defined x>0.

$$n_i$$
 is  $u(x,y,z)$ 

$$S_2: G(u,v) = (u,v, 2\sqrt{x^2+v^2})$$

$$\frac{\partial G}{\partial u} = (1,0,\frac{2u}{\sqrt{u^2+v^2}})$$

$$\frac{\partial G}{\partial v} = (0,1,\frac{2v}{\sqrt{u^2+v^2}})$$

$$\frac{\partial G \times \partial G}{\partial u} = \left\langle \frac{-2u}{\sqrt{2}}, \frac{-2v}{\sqrt{2}}, 1 \right\rangle$$

$$\frac{\partial G}{\partial u} \times \frac{\partial G}{\partial v} = \sqrt{\frac{4u^2 + 4v^2 + 1}{u^2 + v^2}}$$

b) S: 
$$G(x,y) = \langle x,y, 4-x^2-y^2 \rangle$$
  $\partial G \times \partial_y G = \begin{vmatrix} i & 0 & -2x \\ 0 & 1 & -2y \end{vmatrix}$   
 $|\partial_x G \times \partial_y G| = \sqrt{1+4x^2+4y^2}$   $=\langle 2x, 2y, 1 \rangle$ 

$$\iint f(x) dA = \iint f(G(x,y)) \sqrt{1 + 4(x^2 + y^2)} dxdy = x^2 + y^2 + y^2$$

Change to polar 5 = (4-(4-x-y)) \( \tau \) \

$$= \int_{0}^{2\pi} d\theta \int_{0}^{4\pi} \int_{0}^{4\pi} \int_{0}^{4\pi} dr \int_{0}^{2\pi} \int_{0}^{6\pi} \int_{0}^{2\pi} dr \int_{0}^{4\pi} \int_{0}^{4\pi} dr \int_{0}^{2\pi} \int_{0}^{6\pi} \int_{0}^{2\pi} \int_{0}^$$

C) 
$$G(u,v) = (u Cov, u Sin v, v)$$
  $o < v \le 2\pi$   
 $o \le u \le 1$   
 $o \le u \le 1$ 

$$F(G(u,v)) = \left\langle u(\sigma v, uS_{inv}, v-2uS_{inv}) \right\rangle$$

$$\iint F \cdot n dA = \iint \left( \frac{u}{u} \right) du dv = \iint \left[ uv - 2u^2 S_{,nv} \right] du dv$$

$$S \qquad v_{=0} \qquad u_{=0} \qquad v_{=0} \qquad v_{=0}$$

$$= \left(\int_{0}^{2\pi} v \, dv\right) \left(\int_{0}^{1} u \, du\right) - \left(2\int_{0}^{2\pi} u \, du\right) \left(\int_{0}^{2\pi} u \, du\right) \left(\int_{0}^{2\pi} u \, du\right) = 0$$

$$\frac{4\pi^{2}}{2} \times \frac{1}{2} = \pi^{2}$$

$$\frac{4\pi^2}{2} \times \frac{1}{2} = \pi^2$$

3 (a) 
$$g(t) = \langle \frac{dx}{dt}, \frac{dr}{dt} \rangle = \langle \frac{dr}{dt} \cos \frac{d\theta}{dt}, \frac{dr}{dt} \sin \frac{d\theta}{dt}, \frac{dr}{dt} \sin \frac{d\theta}{dt} \rangle$$

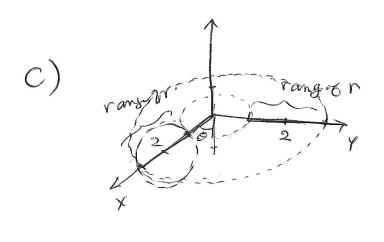
$$|g(t)| = \cdots = \sqrt{\frac{dr}{dt}^2 + r^2 \left(\frac{d\theta}{dt}\right)^2}$$

b) 
$$engh = \int_{0}^{c} g(t) dt = \int_{0}^{c} \sqrt{1+t^{2}} dt$$

$$r = t dr = 1$$

$$0 = t dt$$

$$d\theta = 1$$



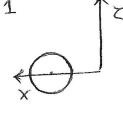


or 
$$(x-2)^2 + z^2 = 1$$

 $(x-2)^2 + \chi^2 = 1$ 

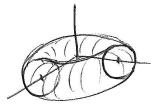
Similarly on the yz plane  $\theta = \frac{\pi}{2}$  no y=r

= Sinu+2



To put This all together

we get



and for any fixed

$$\theta = \theta_0$$
 (it is a plane That

r=

$$\iint \left| \frac{\partial G}{\partial u} \times \frac{\partial G}{\partial v} \right| dadv$$

$$\frac{\partial G}{\partial u} = \left\langle \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \right\rangle =$$

$$= \left\langle \frac{dr}{du} \cos + r \sin \theta \frac{d\theta}{du}, \frac{dr}{du} \sin \theta + r \cos \frac{d\theta}{du}, - \cos u \right\rangle$$

= 
$$\langle \text{Cow Cow}, \text{Cow Sinv}, -\text{Cow} \rangle$$
 Similarly  $\frac{\partial G}{\partial v} = \langle \frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v} \rangle$ 

$$= \left\langle \frac{dr}{dv} \cos \theta - r \sin \theta \frac{d\theta}{dv}, \frac{dr}{dv} \sin \theta + r \cos \frac{d\theta}{dv}, 0 \right\rangle = \left\langle -(2 + \sin u) \sin v, \frac{d\theta}{dv} \right\rangle$$
(2+8\in u) Cov, 0

$$\frac{\partial G}{\partial u} \times \frac{\partial G}{\partial v} = \begin{vmatrix} c_{0}uG_{0}v & G_{0}uS_{0}v & -G_{0}u \\ -(2+S_{0}u)Sv(2+S_{0})G_{0} & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} + S_{0}uC_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} + S_{0}uC_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0 \end{vmatrix} = 2C_{0}u \begin{vmatrix} c_{0}v & Sv & -1 \\ -Sv & Cv & 0$$

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