

Lecture 9

Independent Component Analysis (ICA)

\underline{X} mean vector $\underline{\mu}$, covariance matrix C

Model: $\underline{X} = \underline{\mu} + A \underline{Y}$ where $\underline{Y} = \begin{pmatrix} Y_1 \\ \vdots \\ Y_p \end{pmatrix}$ with Y_1, \dots, Y_p independent $E(Y_i) = 0, \text{Var}(Y_i) = 1$

$$C = AA^T$$

Assumption: At most one of Y_1, \dots, Y_p are normal

Given data $\underline{X}_1, \dots, \underline{X}_n$, estimate mixing matrix A and independent components Y_1, \dots, Y_p .

Fast ICA

① Rewhitening: Transform center data $\underline{X}_1 - \bar{\underline{X}}, \dots, \underline{X}_n - \bar{\underline{X}}$ to make variables uncorrelated.

$$\underline{Z}_i = L(\underline{X}_i - \bar{\underline{X}})$$

$$\frac{1}{n-1} \sum_{i=1}^n \underline{Z}_i \underline{Z}_i^T = \overset{p \times p}{I}$$

- use principle components for L .

$$\hat{C} = \frac{1}{n-1} \sum_{i=1}^n (\underline{X}_i - \bar{\underline{X}})(\underline{X}_i - \bar{\underline{X}})^T$$

estimated
covariance
matrix

$$L = \Lambda^{-\frac{1}{2}} V^T$$

② Try to find projections of $\{\underline{Z}_i\}$ that are as normal as possible, vector \underline{w} with $\underline{w}^T \underline{w} = 1$
 \Rightarrow maximize non-normality of $\{\underline{w}^T \underline{Z}_i\}$

Find $\underline{w}_1, \dots, \underline{w}_p$ with $\underline{w}_i^T \underline{w}_j = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{otherwise} \end{cases}$ with $\{\underline{w}_i^T \underline{Z}_i\}$ as non-normal as possible

Two methods:

Find $\underline{w}_1, \dots, \underline{w}_p$ in one shot
 \Rightarrow simultaneous

Sequential: Find \underline{w}_1 , then $\underline{w}_2 \Rightarrow$ deflations.

Fast ICA - deflation

Prewhitened data $\{\underline{Z}_i\}$. Find \underline{w} to minimize $J(\underline{w}) = \frac{1}{n} \sum_{i=1}^n H(\underline{w}^T \underline{Z}_i)$ over \underline{w} with $\underline{w}^T \underline{w} = 1$

Add Lagrange multiplier:

$$\text{Minimize } J(\underline{w}) + \lambda [\underline{w}^T \underline{w} - 1] = J^*(\underline{w})$$

$$\nabla_{\underline{w}} J^*(\underline{w}) = \frac{1}{n} \sum_{i=1}^n H(\underline{w}^T \underline{Z}_i) \underline{Z}_i + 2\lambda \underline{w} \quad (= 0)$$

Newton-Raphson algorithm

One dimension:

$$g(x) = 0$$

$$x_{k+1} = x_k - \frac{g(x_k)}{g'(x_k)}$$

Need matrix of derivatives:

$$\nabla_{\underline{w}}^2 J^*(\underline{w}) = \frac{1}{n} \sum_{i=1}^n H''(\underline{w}^T \underline{z}_i) \underline{z}_i \underline{z}_i^T + 2\lambda \mathbf{I}$$

$$\nabla_{\underline{w}}^2 J^*(\underline{w}) = \underbrace{\left[\frac{1}{n} \sum_{i=1}^n H''(\underline{w}^T \underline{z}_i) + 2\lambda \right]}_{\text{scalar}} \mathbf{I}$$

Modified N-R update

$$\begin{aligned} \underline{w}_{k+1} &= \underline{w}_k - \frac{\frac{1}{n} \sum_{i=1}^n H'(\underline{w}_k^T \underline{z}_i) \underline{z}_i + 2\lambda \underline{w}_k}{\frac{1}{n} \sum_{i=1}^n H'(\underline{w}_k^T \underline{z}_i) + 2\lambda} \\ &= \frac{\frac{1}{n} \sum_{i=1}^n H''(\underline{w}_k^T \underline{z}_i) \underline{w}_k - \frac{1}{n} \sum_{i=1}^n H'(\underline{w}_k^T \underline{z}_i) \underline{z}_i}{\frac{1}{n} \sum_{i=1}^n H''(\underline{w}_k^T \underline{z}_i) \underline{w}_k + 2\lambda} \implies = \underline{v}_k \\ &\qquad\qquad\qquad \|\underline{w}_{k+1}\| = 1 \end{aligned}$$

$$\underline{w}_{k+1} = \frac{\underline{v}_k}{\|\underline{v}_k\|} = \frac{\underline{v}_k}{\sqrt{\underline{v}_k^T \underline{v}_k}}$$

Now iterate until convergence.

How to compute other \underline{w} 's? Add orthogonality conditions \rightarrow extra Lagrange multipliers

Examples Track records. (see Blackboard)

8 variables (national records in 8 events)

55 countries

-R package: fast ICA.

Use deflation method using standardized variables

PCA: First 2 PCs very interpretable.

ICA: Mixing matrix quite incomprehensible!

- outliers are much more apparent in ICA.

- for example, ICA identifies South Korea (KOR) as a clear outlier.

Summary: PCA vs ICA

- similar goals, different results

PCA: Maximize variance of one-dimensional projection subject to orthogonality constraints.

$$\left. \begin{matrix} \hat{\underline{C}} \\ \hat{\underline{R}} \end{matrix} \right\} = \underline{V} \underline{\Lambda} \underline{V}^T$$

- scaling of variables is important - when in doubt, use $\hat{\underline{R}}$!

ICA: $\underline{X} = \underline{w} + \underline{A} \underline{y} \leftarrow$ indep comp

↑
mixing matrix

$$\text{Cov}(\underline{X}) = \underline{C} = \underline{A} \underline{A}^T$$

- in theory, scaling of variables doesn't matter.

- defining criteria for independence.

- components are interchangeable

- scaling can matter!

Implementation of ICA is very complicated.

