Eg. (Complementary slackness & degeneracy)

Consider the primial problem

See"A Degenerate Optimal Solution . pdf"

A Degenerate Optimal Solution

Maximize  $z = 3x_1 + 7x_2 s.t.$ 

$$X_1 + SX_2 \le 19$$
  
 $X_1 - X_2 \le 1$   
 $-X_1 + 2X_2 \le 2$   
 $X_1 \ge 0$ ,  $X_2 \ge 0$ 

Given:  $\begin{bmatrix} \chi_1 \\ \chi_2 \end{bmatrix} = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$  is optimal

(with 3 constraints this problem has 3

basic variables. At [4], Here is no slack in any constraint, So at least one basic variable is zero:

a degenerate solution)

We will write the dual problem and some it:

Maximize z'= 19w1+12+2W3 s.t.

 $W_1 + W_2 - W_3 \ge 3$  $5w_1 - w_2 + 2w_3 \ge 7$ 

W, ≥0, Wz≥0, W3 ≥0

At primal optimality, X170, X270 so at dual optimality, both dual constraints are tight. Since there's no slack at primal optimality in any primal constraint, complementary slackness does not say whether w, we or we is 0 at dual optimality.

So, complementary slackness only

Solution of the system =  $\begin{bmatrix} 0 & 1 & -1 & 3 \\ 5 & -1 & 2 & 7 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & -1 & 3 \\ 0 & 6 & 7 & -8 \end{bmatrix}$ 

$$\simeq \begin{bmatrix} 1 & 0 & -\frac{1}{6} & \frac{5}{3} \\ 0 & 1 & -\frac{7}{6} & \frac{4}{3} \end{bmatrix}$$

Such [w] include each optimal dual solution, but also include some infeasible solution

We have  $w_1 \ge 0 \Rightarrow w_3 \le 10$  (solve  $\frac{5}{3} - \frac{1}{6}w_3 \ge 0$ )  $\frac{w_2 \ge 0}{w_3 \ge 0}$ So  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$  and  $\begin{bmatrix} w_1 \\ w_3 \end{bmatrix} = \begin{bmatrix} \frac{5}{3} - \frac{1}{6}w_3 \\ \frac{7}{3} + \frac{7}{6}w_3 \end{bmatrix}$  are feasible provided  $0 \le w_3 \le 10$ 

But Z=31,+7  $X_2=3.4+7.3=$3$   $Z'=19w_1+w_2+2w_3=19(\frac{5}{3}-\frac{1}{6}w_3)+(\frac{4}{3}+\frac{7}{6}w_3)+2w_3=\frac{95}{3}+\frac{4}{3}=33$ So both solutions are optimal (weak duality theorem)

Another optimality criterion is:

If No and we are feasible, for respective primal and dual problems, and No + We satisfy the conclusion of the complementary slackness theorem. Then both solutions are optimal.

These are called Karush-Kuhn-Tucker (or KKT) conditions.