University of Toronto Department of Mathematics

MAT224H1S

Linear Algebra II

Midterm Examination

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Duration: 1 hour 50 minutes

Last Name:	
Given Name:	
Student Number:	
Tutorial Group:	

No calculators or other aids are allowed.

FOR MARKER USE ONLY		
Question	Mark	
1	/10	
2	/10	
3	/10	
4	/10	
5	/10	
6	/10	
TOTAL	/60	

[10] 1. Let $T: \mathbb{Z}_2^3 \to \mathbb{Z}_2^3$ be the linear operator defined by

$$T(x_1, x_2, x_3) = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}.$$

- (a) Find the matrix of T with respect to the basis $\alpha = \{(1,0,0),(1,1,0),(1,1,1)\}$.
- (b) Find bases for Ker(T) and Im(T).

Solution:

(a) We have (keeping in mind that we're working over \mathbb{Z}_2 , where 2=0 and -1=1)

$$T(1,0,0) = (1,1,1) = [(0,0,1)]_{\alpha}$$

$$T(1,1,0) = (2,1,2) = (0,1,0) = [(1,1,0)]_{\alpha}$$

$$T(1,1,1) = (2,2,2) = (0,0,0) = [(0,0,0)]_{\alpha}.$$

Thus

$$[T]_{\alpha} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}.$$

(b) We know that $Ker(T) = null([T]_{\alpha})$ and $Im(T) = col([T]_{\alpha})$, so let's row reduce $[T]_{\alpha}$:

$$[T]_{\alpha} \longrightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

Hence

$$\operatorname{null}([T]_{\alpha}) = \left\{ \begin{bmatrix} 0 \\ 0 \\ t \end{bmatrix}_{\alpha} \right\} = \left\{ (t, t, t) \right\} = \left\{ (1, 1, 1)t \right\}.$$

So a basis for Ker(T) is $\{(1,1,1)\}$.

Next, as the leading 1s in $\operatorname{rref}([T]_{\alpha})$ occur in columns 1 and 2, we conclude that the corresponding columns of $[T]_{\alpha}$ form a basis for its column space. Thus

$$\left\{ \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}_{\alpha}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}_{\alpha} \right\} = \left\{ (1, 1, 1), (0, 1, 0) \right\}$$

is a basis for Im(T).

[10] **2.** Let $T: \mathbb{R}^4 \to P_2(\mathbb{R})$ be the linear transformation that is represented by the matrix

$$\begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 1 & 1 & 0 & 1 \end{bmatrix}$$

relative to the standard bases of \mathbb{R}^4 and $P_2(\mathbb{R})$. Find the matrix of T with respect to the bases $\alpha = \{(1,0,0,0), (0,0,1,0), (1,-1,0,0), (0,-1,1,1)\}$ and $\beta = \{x^2 + 1, x, 1\}$.

Solution #1:

We have:

$$T(1,0,0,0) = \begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 1 & 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}_{\text{std}} = 1 + x^2 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}_{\beta}.$$

Similarly,

$$T(0,0,1,0) = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}_{\text{std}} = x = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}_{\beta}$$

$$T(1,-1,0,0) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}_{\text{std}} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}_{\beta}$$

$$T(0,-1,1,1) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}_{\text{std}} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}_{\beta}$$

Thus our desired matrix is

$$[T]_{\beta\alpha} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

Solution #2:

Let $S_{\beta,\text{std}}$ and $S_{\text{std},\alpha}$ denote the change of bases matrices from the standard basis for $P_2(\mathbb{R})$ to β and from the α to the standard basis for \mathbb{R}^4 , respectively. Then the matrix we want is

$$[T]_{\beta\alpha} = S_{\beta,\text{std}} \begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 1 & 1 & 0 & 1 \end{bmatrix} S_{\text{std},\alpha}.$$

So let's determine these change of basis matrices. Let's start with $S_{\beta,\text{std}}$:

$$[1]_{\beta} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \quad [x]_{\beta} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad [x^2]_{\beta} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}.$$

Thus

$$S_{\beta, \text{std}} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & -1 \end{bmatrix}.$$

Next, let's find $S_{\mathrm{std},\alpha}$:

$$[(1,0,0,0)]_{\text{std}} = \begin{bmatrix} 1\\0\\0\\0 \end{bmatrix}$$

and similarly for the other vectors in α . Thus

$$S_{\mathrm{std},lpha} = egin{bmatrix} 1 & 0 & 1 & 0 \ 0 & 0 & -1 & -1 \ 0 & 1 & 0 & 1 \ 0 & 0 & 0 & 1 \end{bmatrix}$$

Finally,

$$[T]_{\beta\alpha} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 1 & 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 0 & -1 & -1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 0 & -1 & -1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$
$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

[10] **3.** Let $W = \{p(x) \in P_2(\mathbb{R}) \mid p(0) = 0\}$. Show that W and \mathbb{R}^2 are isomorphic and find an isomorphism $T: W \to \mathbb{R}^2$.

Solution:

A polynomial $p(x) = a_0 + a_1 x + a_2 x^2 \in P_2(\mathbb{R})$ is in W iff p(0) = 0 iff $a_0 = 0$. That is,

$$p(x) \in W \iff p(x) = a_1 x + a_2 x^2.$$

This shows that

$$W = \{a_1x + a_2x^2 \in P_2(\mathbb{R}) \mid a_1, a_2 \in \mathbb{R}\} = \operatorname{span}\{x, x^2\}.$$

Since the set $\{x, x^2\}$ is clearly linearly independent, we conclude that dim $W = 2 = \dim \mathbb{R}^2$. Hence W and \mathbb{R}^2 are isomorphic, as they have the same dimension.

An isomorphism $T: W \to \mathbb{R}^2$ is given by

$$T(a_1x + a_2x^2) = (a_1, a_2).$$

Indeed, T is linear:

$$T((a_1x + a_2x^2) + \lambda(b_1x + b_2x^2)) = T((a_1 + \lambda b_1)x + (a_2 + \lambda b_2)x^2)$$

$$= (a_1 + \lambda b_1, a_2 + \lambda b_2)$$

$$= (a_1, a_2) + \lambda(b_1, b_2)$$

$$= T(a_1x + a_2x^2) + \lambda T(b_1x + b_2x^2);$$

T is injective:

$$T(a_1x + a_2x^2) = (0,0) \iff (a_1, a_2) = (0,0) \iff a_1x + a_2x^2 = 0;$$

hence T is also surjective because dim $W=\dim \mathbb{R}^2$. (We can also check surjectivity directly: given $(a,b)\in \mathbb{R}^2$, we have $ax+bx^2\in W$ and $T(ax+bx^2)=(a,b)$, so $(a,b)\in \mathrm{Im}(T)$.)

[10] **4.** Let $T: \mathbb{C}^3 \to \mathbb{C}^3$ be the linear transformation defined by

$$T(z_1, z_2, z_3) = ((1+i)z_1, -2iz_1 + (1+i)z_2 + 2iz_3, iz_1 + z_3),$$

where \mathbb{C}^3 is seen as a vector space over the field of complex numbers. Find the eigenvalues of T and bases for each of the corresponding eigenspaces.

Solution:

Let's find the standard matrix of T:

$$T(1,0,0) = (1+i,-2i,i)$$

$$T(0,1,0) = (0,1+i,0)$$

$$T(0,0,1) = (0,2i,1).$$

Thus

$$[T]_{\text{std}} = \begin{bmatrix} 1+i & 0 & 0\\ -2i & 1+i & 2i\\ i & 0 & 1 \end{bmatrix}.$$

The characteristic polynomial of this matrix is

$$\det([T]_{\text{std}} - \lambda I) = \det \begin{bmatrix} (1+i) - \lambda & 0 & 0 \\ -2i & (1+i) - \lambda & 2i \\ i & 0 & 1 - \lambda \end{bmatrix} = ((1+i) - \lambda)((1+i) - \lambda)(1 - \lambda),$$

where the last equality was obtained by cofactor expansion along the first row. So the eigenvalues of A are

$$\lambda = 1$$
 and $\lambda = 1 + i$

(with multiplicities 1 and 2, respectively).

To find the eigenvectors of $\lambda = 1$, we need to determine $\ker(T - \lambda I) = \ker(T - I)$. For this we row reduce $[T]_{\text{std}} - I$:

$$\begin{bmatrix} i & 0 & 0 \\ -2i & i & 2i \\ i & 0 & 0 \end{bmatrix} \xrightarrow{R_2 + 2iR_1, R_3 - R_1} \begin{bmatrix} i & 0 & 0 \\ 0 & i & 2i \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_1 \times \frac{1}{i}, R_2 \times \frac{1}{i}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}.$$

Thus

$$\ker(T - I) = \left\{ \begin{bmatrix} 0 \\ -2t \\ t \end{bmatrix} \right\}$$

and $\{(0, -2, 1)\}$ is a basis for the eigenspace corresponding to $\lambda = 1$.

Now we do the same thing for $\lambda = 1 + i$. Here we row reduce $[T]_{\text{std}} - (1 + i)I$:

$$\begin{bmatrix} 0 & 0 & 0 \\ -2i & 0 & 2i \\ i & 0 & -i \end{bmatrix} \xrightarrow{R_2 + (2i)R_3, R_3 \times \frac{1}{i}} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & -1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_3} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

Thus

$$\ker(T - (i+1)I) = \left\{ \begin{bmatrix} t \\ s \\ t \end{bmatrix} \right\} = \operatorname{span}\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$$

and $\{(1,0,1),(0,1,0)\}$ is a basis for the eigenspace corresponding to $\lambda=1+i$.

[10] **5.** Let $T: \mathbb{R}^3 \to \mathbb{R}^3$ be the linear operator defined by

$$T(x_1, x_2, x_3) = (ax_1 + bx_2, bx_1 + ax_2 + bx_3, bx_2 + ax_3).$$

Show that T is diagonalizable for all values of $a, b \in \mathbb{R}$.

Solution:

Let's find the standard matrix of T:

$$T(1,0,0) = (a,b,0)$$

 $T(0,1,0) = (b,a,b)$
 $T(0,0,1) = (0,b,a)$.

Thus

$$[T]_{\text{std}} = \begin{bmatrix} a & b & 0 \\ b & a & b \\ 0 & b & a \end{bmatrix}.$$

The characteristic polynomial of this matrix is

$$\det \begin{bmatrix} a - \lambda & b & 0 \\ b & a - \lambda & b \\ 0 & b & a - \lambda \end{bmatrix} = (a - \lambda)((a - \lambda)^2 - b^2) - b(b(a - \lambda))$$
$$= (a - \lambda)((a - \lambda)^2 - 2b^2)$$
$$= (a - \lambda)(a - \lambda - b\sqrt{2})(a - \lambda + b\sqrt{2}b).$$

Hence the eigenvalues of T are

$$\lambda = a, a \pm b\sqrt{2}.$$

So if $b \neq 0$ then we have 3 distinct eigenvalues, and since $[T]_{\text{std}}$ is 3×3 , this means that T is diagonalizable in this case. On the other hand, if b = 0 then we see that $[T]_{\text{std}} = \text{diag}(a, a, a)$ is already diagonal. So in either case T is diagonalizable.

[Side note: A very quick proof is possible if we simply observe that the matrix $[T]_{\text{std}}$ is symmetric hence diagonalizable, by a theorem to be covered later in the course.]

[10] **6.** Let $T: V \to W$ be an injective linear transformation. Prove that if $T(v_4)$ is dependent on $\{T(v_1), T(v_2), T(v_3)\}$, then v_4 is dependent on $\{v_1, v_2, v_3\}$.

Solution:

If $T(v_4)$ is dependent on $\{T(v_1), T(v_2), T(v_3)\}$ then we can find scalars a_1, a_2, a_3 such that

$$T(v_4) = a_1T(v_1) + a_2T(v_2) + a_3T(v_4)$$

= $T(a_1v_1 + a_2v_2 + a_3v_3)$.

Hence

$$0 = T(v_4) - T(a_1v_1 + a_2v_2 + a_3v_3) = T(v_4 - (a_1v_1 + a_2v_2 + a_3v_3)),$$

i.e., $v_4 - (a_1v_1 + a_2v_2 + a_3v_3)$ is in the kernel of T. But T is injective, so its kernel is $\{0\}$, and consequently

$$v_4 - (a_1v_1 + a_2v_2 + a_3v_3) = 0,$$

or, in other words,

$$v_4 = a_1 v_1 + a_2 v_2 + a_3 v_3.$$

This shows that v_4 is dependent on $\{v_1, v_2, v_3\}$, as desired.