

```
clc
clear
close all
```

```
%% Create the convolution filter
```

```
r = 0.9; % Define filter
om = 0.95;
a = [1 -2*r*cos(om) r^2];
b = [1 r*cos(om)];
h = filter(b, a, [zeros(1,38) 1 zeros(1,40)]);
N = 500;
K = 25;
sigma = 1;
```

```
%% Plot the components of the input signal
```

```
set_plot_defaults('on')
hh = filter(b, a, [1 zeros(1,40)]);

groundtruth = zeros(1, N);
index_random = randperm(N);
index = index_random(1:K);
groundtruth(index) = 10*2*(rand(1,K) - 0.5);
after_conv = conv(groundtruth,h,'same');
noise = sigma * randn(1,N);
input = after_conv + noise;
```

```
figure(1)
```

```
subplot(2,2,1)
plot(1:N, groundtruth)
title('S[n]')
ylim([-10 10])
xlim([1,500])
```

```
box off
```

```
subplot(2,2,2)
plot(1:41, hh)
title('C[n]')
ylim([-1.2 1.8])
xlim([1,41])
```

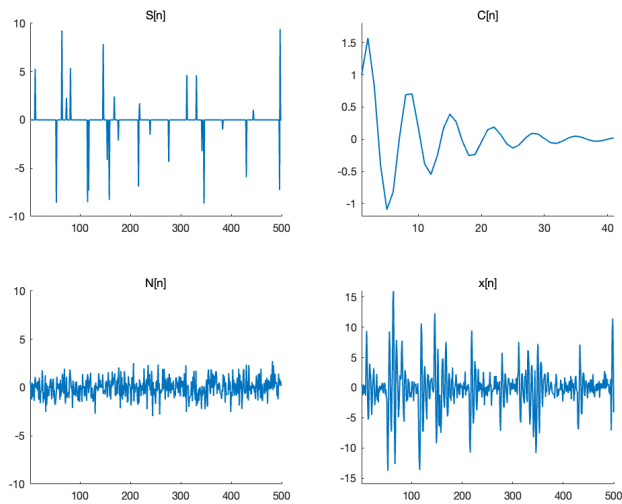
```
box off
```

```
subplot(2,2,3)
plot(1:N, noise)
title('N[n]')
ylim([-10 10])
xlim([1,500])
```

```
box off
```

```
subplot(2,2,4)
plot(1:N, input)
title('x[n]')
ylim([-16 16])
xlim([1,500])
```

```
box off
```



```
% set(gcf, 'PaperPosition', [1 1 14 6])

% print -depsc figures/input

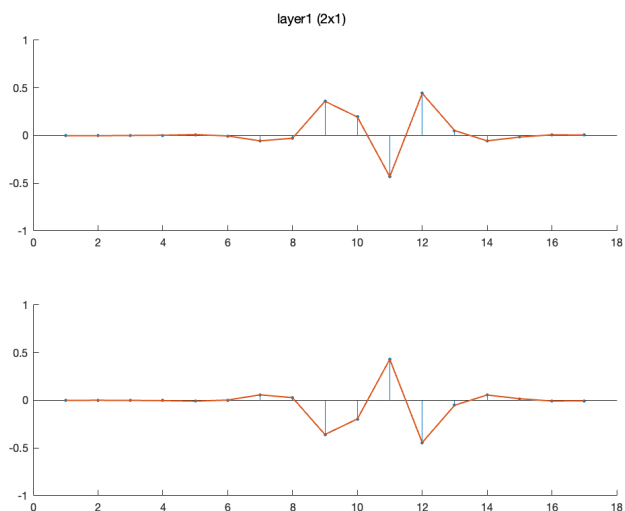
set_plot_defaults('off')
```

```
%% Load the 3-layer deconvolution CNN
```

```
load('in2.mat');
deconvolver{1} = double(conv1);
deconvolver{2} = double(conv2);
deconvolver{3} = double(conv3);
% deconvolver{4} = double(conv4);
% deconvolver{5} = double(conv5);
```

```
%% Plot the structure of the 3-layer CNN
```

```
set_plot_defaults('on')
figure(2)
[r,c,~] = size(deconvolver{1});
for i=1:1:r
    for j=1:1:c
        subplot(r,c,c*i-(c-j))
        stem(flip(squeeze(deconvolver{1}(i,j,:))), 'filled', 'MarkerSize', 2)
        hold on
        plot(flip(squeeze(deconvolver{1}(i,j,:))))
        hold off
        xlim([0,18])
        ylim([-1,1])
        box off
    end
end
sgtitle('layer1 (2x1)', 'FontSize', 10);
```



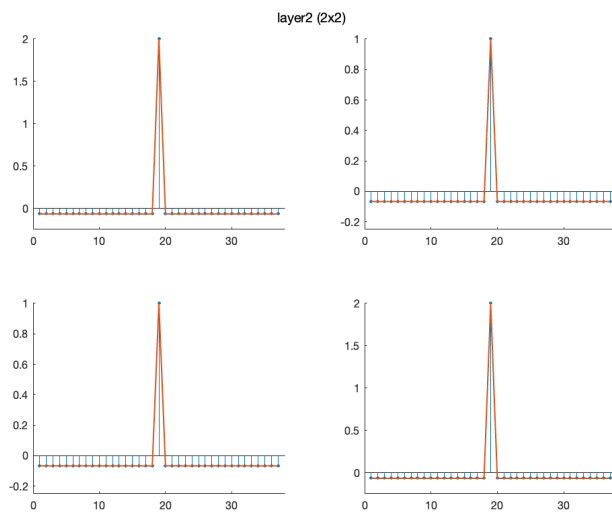
```

% set(gcf, 'PaperPosition', [1 1 3 6])

% print -depsc figures/layer1

figure(3)
title('Layer 2')
[r,c,~] = size(deconvolver{2});
for i=1:1:r
    for j=1:1:c
        subplot(r,c,c*i-(c-j))
        stem(flip(squeeze(deconvolver{2}(i,j,:))), 'filled', 'MarkerSize', 2)
        hold on
        plot(flip(squeeze(deconvolver{2}(i,j,:))))
        hold off
        xlim([0,38])
        ylim([-0.25,inf])
        box off
    end
end
sgtitle('layer2 (2x2)', 'FontSize', 10);

```



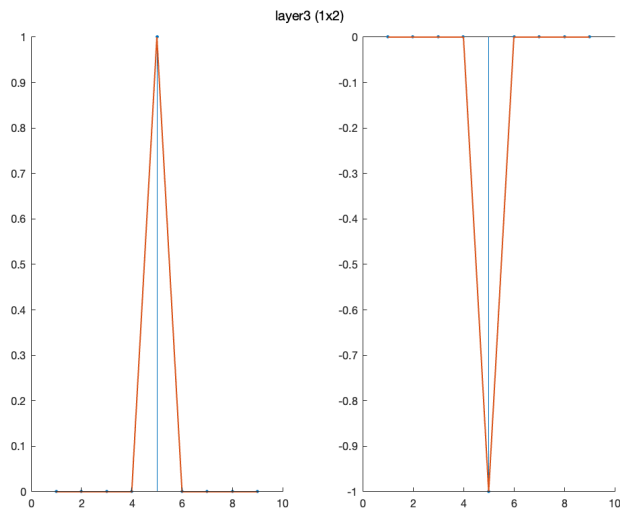
```

% set(gcf, 'PaperPosition', [1 1 6 6])

% print -depsc figures/layer2

figure(4)
title('Layer 3')
[r,c,~] = size(deconvolver{3});
for i=1:1:r
    for j=1:1:c
        subplot(r,c,c*i-(c-j))
        stem(flip(squeeze(deconvolver{3}(i,j,:))), 'filled', 'MarkerSize', 2)
        hold on
        plot(flip(squeeze(deconvolver{3}(i,j,:))))
        hold off
        box off
    end
end
sgtitle('layer3 (1x2)', 'FontSize', 10);

```



```
% set(gcf, 'PaperPosition', [1 1 6 6])

% print -depsc figures/layer3

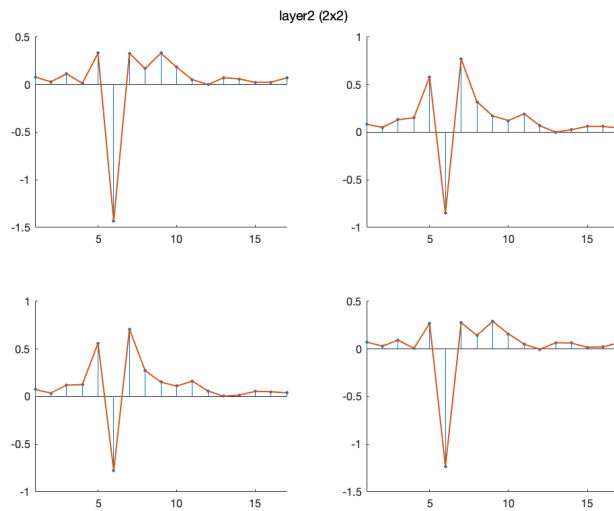
set_plot_defaults('off')
```

```
%% Load the proposed CNN
```

```
load('sin23_2.mat');
deconvolver{1} = double(conv1);
deconvolver{2} = double(conv2);
deconvolver{3} = double(conv3);
deconvolver{4} = double(conv4);
deconvolver{5} = double(conv5);
```

```
%% Plot the second and third layer of the proposed CNN
```

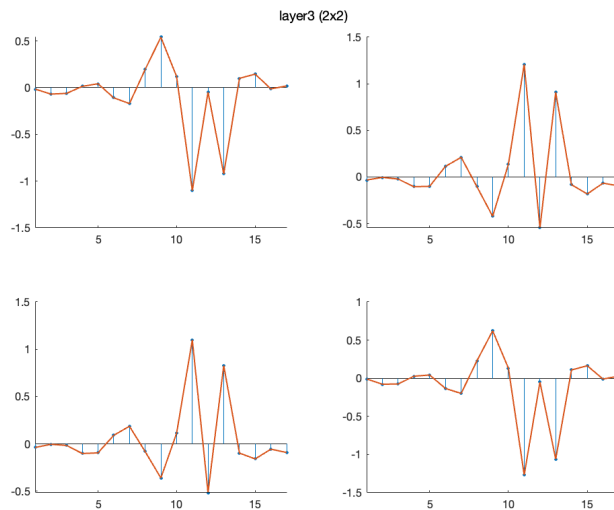
```
set_plot_defaults('on')
figure(5)
[r,c,~] = size(deconvolver{2});
for i=1:1:r
    for j=1:1:c
        subplot(r,c,i-(c-j))
            stem(flip(squeeze(deconvolver{2}(i,j,:))), 'filled', 'MarkerSize', 2)
            hold on
            plot(flip(squeeze(deconvolver{2}(i,j,:))))
            hold off
            xlim([1,17])
            box off
    end
end
sgtitle('layer2 (2x2)', 'FontSize', 10);
```



```
% set(gcf, 'PaperPosition', [1 1 6 6])

% print -depsc figures/layer2_retrain

figure(6)
[r,c,~] = size(deconvolver{3});
for i=1:1:r
    for j=1:1:c
        subplot(r,c,c*i-(c-j))
        stem(flip(squeeze(deconvolver{3}(i,j,:))), 'filled', 'MarkerSize', 2)
        hold on
        plot(flip(squeeze(deconvolver{3}(i,j,:))))
        hold off
        xlim([1,17])
        box off
    end
end
end
sgtitle('layer3 (2x2)', 'FontSize', 10);
```



```
% set(gcf, 'PaperPosition', [1 1 6 6])

% print -depsc figures/layer3_retrain

set_plot_defaults('off')
```

```
%% Plot the output of each layer

set_plot_defaults('on')

groundtruth = zeros(1, N);
index_random = randperm(N);
index = index_random(1:K);
groundtruth(index) = 10*2*(rand(1,K) - 0.5);
```

```

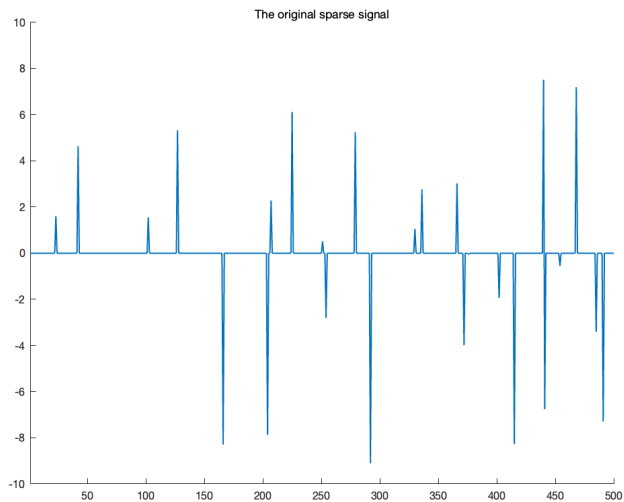
after_conv = conv(groundtruth,h,'same');
noise = sigma * randn(1,N);
input = after_conv + noise;

```

```

figure(7)
plot(1:N, groundtruth)
title('The original sparse signal')
xlim([1,500])
ylim([-10,10])
box off

```



```

% set(gcf, 'PaperPosition', [1 1 6 6])

```

```

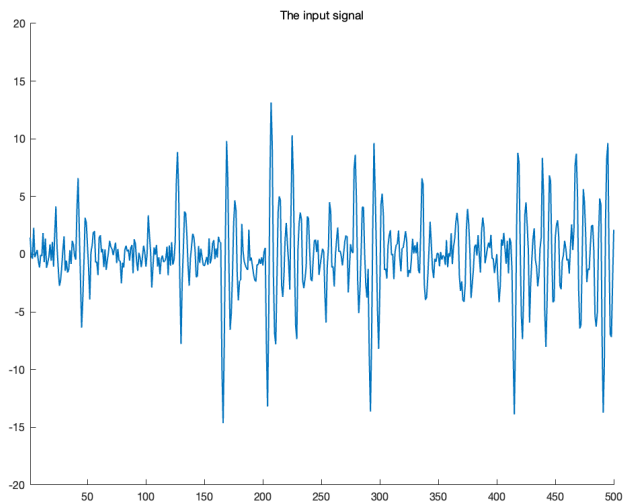
% print -depsc figures/original

```

```

figure(8)
plot(1:N, input)
title('The input signal')
xlim([1,500])
ylim([-20,20])
box off

```



```

% set(gcf, 'PaperPosition', [1 1 6 6])

```

```

% print -depsc figures/input_retrain

```

```

%% Plot the output of each layer

```

```

set_plot_defaults('on')

```

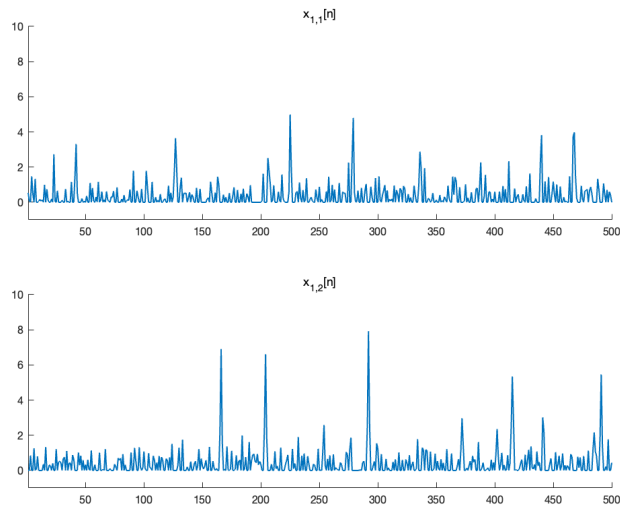
```

l1 = layer(input,deconvolver{1});
l2 = layer(l1,deconvolver{2});
l3 = layer(l2,deconvolver{3});
l4 = layer(l3,deconvolver{4});

```

```
output = CNN(input,deconvolver);
```

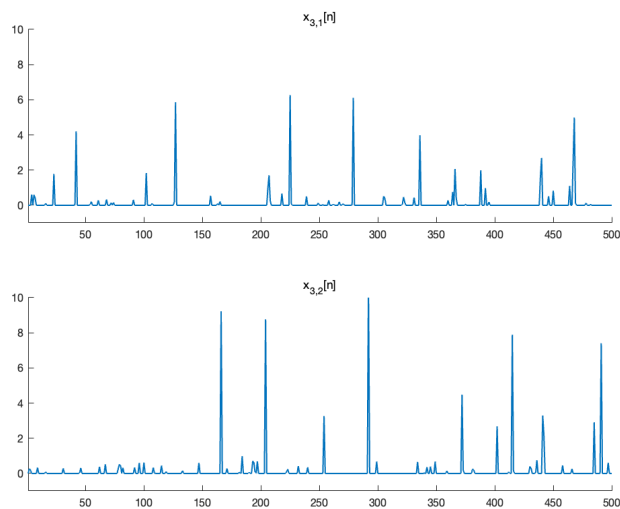
```
figure(9)
subplot(2,1,1)
plot(1:N, l1(1,:))
title('x_{1,1}[n]')
xlim([1,500])
ylim([-1,10])
box off
subplot(2,1,2)
plot(1:N, l1(2,:))
title('x_{1,2}[n]')
xlim([1,500])
ylim([-1,10])
box off
```



```
% set(gcf, 'PaperPosition', [1 1 6 6])
```

```
% print -depsc figures/output1_retrain
```

```
figure(10)
subplot(2,1,1)
plot(1:N, l3(1,:))
title('x_{3,1}[n]')
xlim([1,500])
ylim([-1,10])
box off
subplot(2,1,2)
plot(1:N, l3(2,:))
title('x_{3,2}[n]')
xlim([1,500])
ylim([-1,10])
box off
```



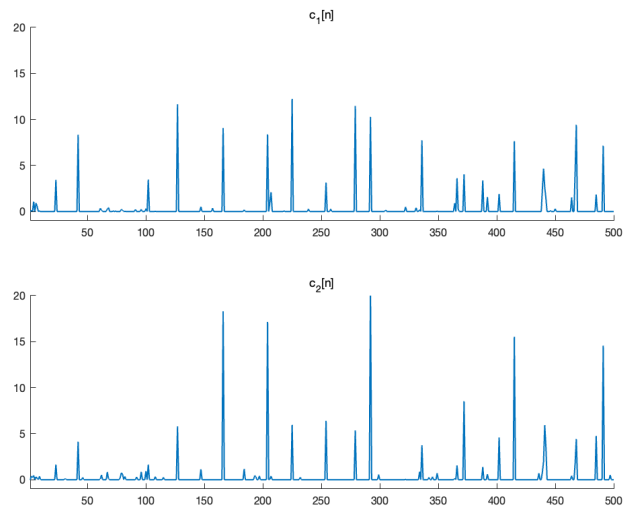
```
% set(gcf, 'PaperPosition', [1 1 6 6])
```

```
% print -depsc figures/output3_retrain
```

```

figure(11)
subplot(2,1,1)
plot(1:N, l4(1,:))
title('c_1[n]')
xlim([1,500])
ylim([-1,20])
box off
subplot(2,1,2)
plot(1:N, l4(2,:))
title('c_2[n]')
xlim([1,500])
ylim([-1,20])
box off

```



```

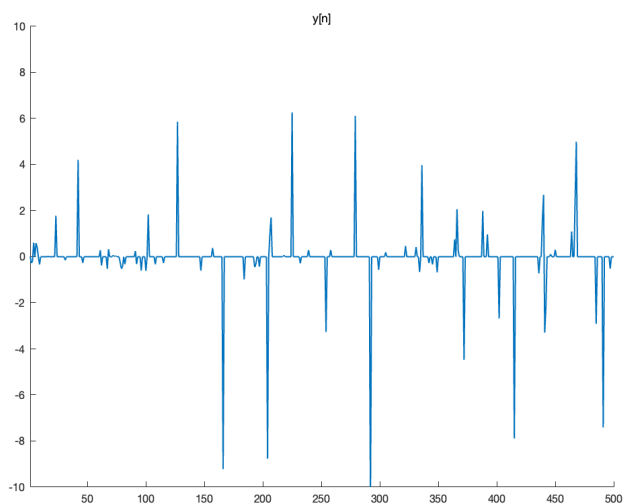
% set(gcf, 'PaperPosition', [1 1 6 6])
% print -depsc figures/output4_retrain

```

```

figure(12)
plot(1:N, output)
title('y[n]')
xlim([1,500])
ylim([-10,10])
box off

```



```

% set(gcf, 'PaperPosition', [1 1 6 6])
% print -depsc figures/output5_retrain

```

```

set_plot_defaults('off')

```



```
%% Create the convolution filter and load the proposed CNN
```

```
clc;
clear
r = 0.9; % Define filter
om = 0.95;
a = [1 -2*r*cos(om) r^2];
b = [1 r*cos(om)];
h = filter(b, a, [zeros(1,38) 1 zeros(1,40)]);
hh = filter(b, a, [1 zeros(1,40)]);
inverse = filter(1,hh,[zeros(1,36) 1 zeros(1,34)]);
load('sin23_2.mat');
deconvolver{1} = double(conv1);
deconvolver{2} = double(conv2);
deconvolver{3} = double(conv3);
deconvolver{4} = double(conv4);
deconvolver{5} = double(conv5);
```

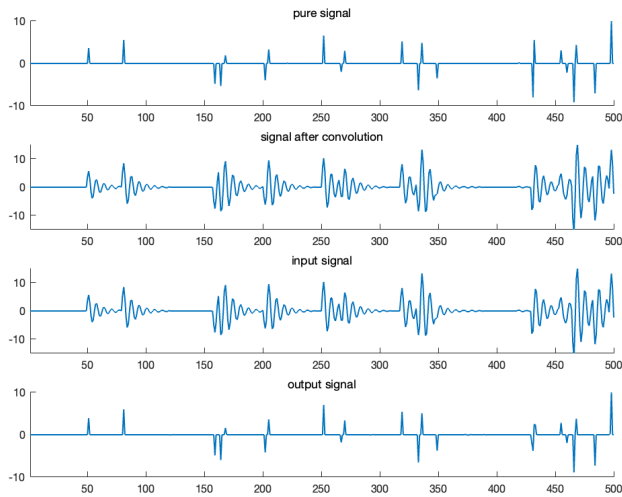
```
%% Create the test signal
```

```
K = 25;
N = 500;
sigma = 0.5;
groundtruth = zeros(1, N);
index_random = randperm(N);
index = index_random(1:K);
groundtruth(index) = 10*2*(rand(1,K) - 0.5);
after_conv = conv(groundtruth,h,'same');
noise = sigma*randn(1,N);
input = after_conv + noise;
```

```
%% Plot input v.s. output in pure signal case
```

```
set_plot_defaults('on')

figure(13)
output = CNN(after_conv,deconvolver);
subplot(4,1,1)
plot(1:N, groundtruth)
xlim([1,500])
ylim([-10,10])
title('pure signal')
box off
subplot(4,1,2)
plot(1:N, after_conv)
xlim([1,500])
ylim([-15,15])
title('signal after convolution')
box off
subplot(4,1,3)
plot(1:N, after_conv)
xlim([1,500])
ylim([-15,15])
title('input signal')
box off
subplot(4,1,4)
plot(1:N, output)
xlim([1,500])
ylim([-10,10])
title('output signal')
box off
```



```
% set(gcf, 'PaperPosition', [1 1 14 12])
```

```
% print -depsc figures/pure1
```

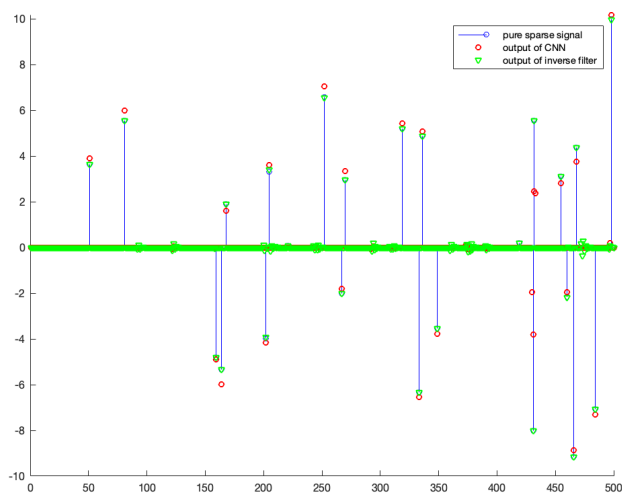
```
MSE = mean((output-groundtruth).^2)
```

```
MSE = 0.0781
```

```
SNR = 10*log10(mean(groundtruth.^2)/MSE)
```

```
SNR = 12.2005
```

```
figure(14)
output1 = conv(after_conv,inverse,'same');
stem(1:N, groundtruth, 'b', 'MarkerSize', 4)
hold on
plot(1:N, output, 'ro', 'MarkerSize', 4)
hold on
plot(1:N, output1, 'gv', 'MarkerSize', 4)
hold off
legend('pure sparse signal', 'output of CNN', 'output of inverse filter')
box off
```



```
% set(gcf, 'PaperPosition', [1 1 14 10])
```

```
% print -depsc figures/pure2
```

```
set_plot_defaults('off')
```

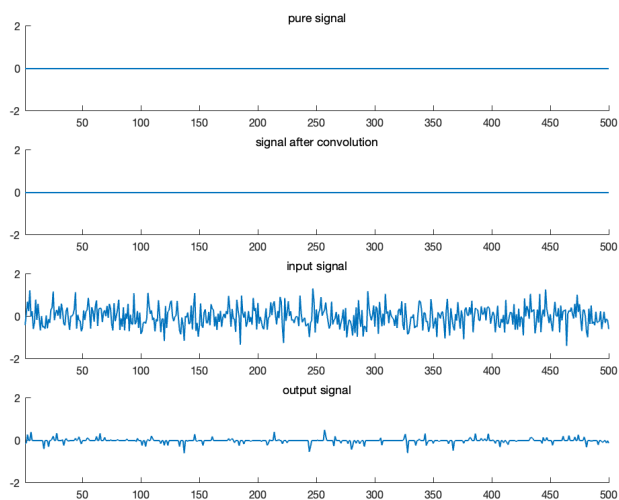
```
%% Plot input v.s. output in pure noise case
```

```
set_plot_defaults('on')
```

```

figure(15)
output = CNN(noise,deconvolver);
subplot(4,1,1)
plot(1:N, zeros(1,N))
xlim([1,500])
ylim([-2,2])
title('pure signal')
box off
subplot(4,1,2)
plot(1:N, zeros(1,N))
xlim([1,500])
ylim([-2,2])
title('signal after convolution')
box off
subplot(4,1,3)
plot(1:N, noise)
xlim([1,500])
ylim([-2,2])
title('input signal')
box off
subplot(4,1,4)
plot(1:N, output)
xlim([1,500])
ylim([-2,2])
title('output signal')
box off

```



```
% set(gcf, 'PaperPosition', [1 1 14 12])
```

```
% print -depsc figures/noise1
```

```
MSE = mean((output-0).^2)
```

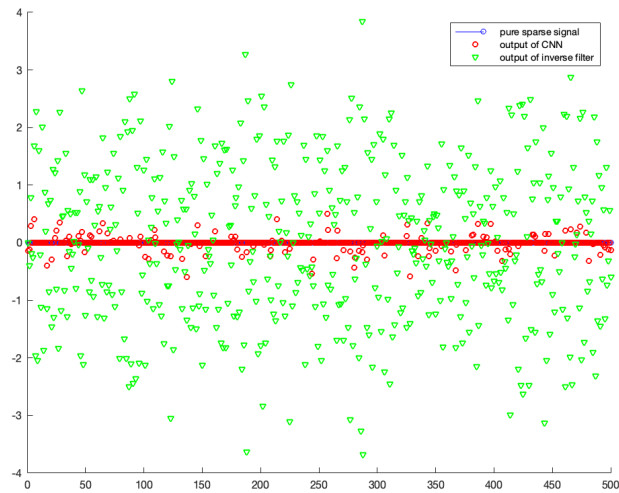
```
MSE = 0.0115
```

```
% SNR = 10*log10(mean(groundtruth.^2)/MSE)
```

```

figure(16)
output1 = conv(noise,inverse,'same');
stem(1:N, zeros(1,N), 'b', 'MarkerSize', 4)
hold on
plot(1:N, output, 'ro', 'MarkerSize', 4)
hold on
plot(1:N, output1, 'gv', 'MarkerSize', 4)
hold off
legend('pure sparse signal', 'output of CNN', 'output of inverse filter')
box off

```



```
% set(gcf, 'PaperPosition', [1 1 14 10])
```

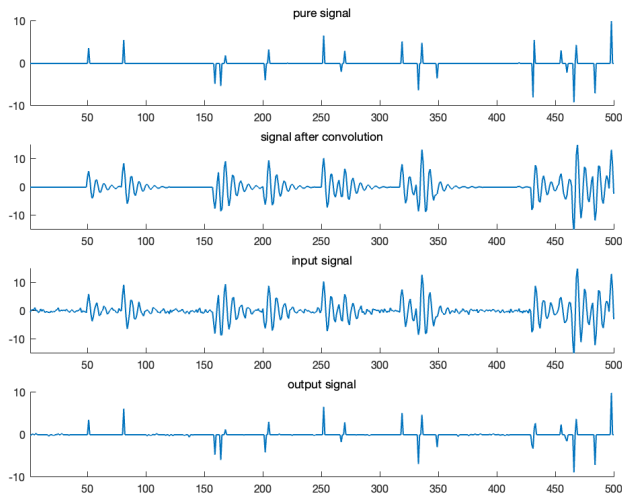
```
% print -depsc figures/noise2
```

```
set_plot_defaults('off')
```

```
%% Plot input v.s. output in noisy signal case
```

```
set_plot_defaults('on')
```

```
figure(17)
output = CNN(input,deconvolver);
subplot(4,1,1)
plot(1:N, groundtruth)
xlim([1,500])
ylim([-10,10])
title('pure signal')
box off
subplot(4,1,2)
plot(1:N, after_conv)
xlim([1,500])
ylim([-15,15])
title('signal after convolution')
box off
subplot(4,1,3)
plot(1:N, input)
xlim([1,500])
ylim([-15,15])
title('input signal')
box off
subplot(4,1,4)
plot(1:N, output)
xlim([1,500])
ylim([-10,10])
title('output signal')
box off
```



```
% set(gcf, 'PaperPosition', [1 1 14 12])
```

```
% print -depsc figures/noisy1
```

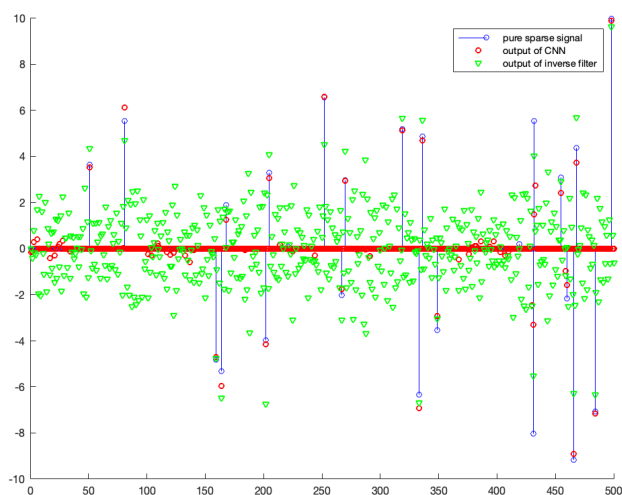
```
MSE = mean((output-groundtruth).^2)
```

```
MSE = 0.1177
```

```
SNR = 10*log10(mean(groundtruth.^2)/MSE)
```

```
SNR = 10.4189
```

```
figure(18)
output1 = conv(input,inverse,'same');
stem(1:N, groundtruth, 'b', 'MarkerSize', 4)
hold on
plot(1:N, output, 'ro', 'MarkerSize', 4)
hold on
plot(1:N, output1, 'gv', 'MarkerSize', 4)
hold off
legend('pure sparse signal', 'output of CNN', 'output of inverse filter')
box off
```



```
% set(gcf, 'PaperPosition', [1 1 14 10])
```

```
% print -depsc figures/noisy2
```

```
set_plot_defaults('off')
```

```
%% Create input signal (noisy signal) and ground truth (pure signal) for the performance part.
```

```
% N is the total length of the pure sparse signal.
```

```
% K is the number of non-zeros in the pure sparse signal.
```

```
% As a result, 1-K/N determines the sparsity of the pure signal.
```

```
N = 500;
num = 2000;
sigma_set = logspace(log10(0.1), log10(2), 20);
% sigma_set = 0.1:0.1:2;

MSE_output_ave = zeros(3,length(sigma_set));
SNR_output_ave = zeros(3,length(sigma_set));

for m = 1:1:3
    K = 25 * m;
    for i = 1:1:length(sigma_set)

        sigma = sigma_set(i);
        SNR_output = zeros(1,num);
        SNR_input = zeros(1,num);
        MSE_output = zeros(1,num);
        for j = 1:1:num

            groundtruth = zeros(1, N);
            index_random = randperm(N);
            index = index_random(1:K);
            groundtruth(index) = 10*2*(rand(1,K) - 0.5);
            % groundtruth(index) = 10*randn(1,K);
            after_conv = conv(groundtruth,h,'same');
            input_noise = sigma*randn(1,N);
            input = after_conv + input_noise;
            output = CNN(input, deconvolver);
            noise = output - groundtruth;
            MSE_output(j) = mean(noise.^2);
            SNR_output(j) = 10*log10(mean(groundtruth.^2)/MSE_output(j));

        end
        SNR_output_ave(m,i) = mean(SNR_output);
        % MSE_output_ave(m,i) = mean(MSE_output);
        MSE_output_ave(m,i) = sqrt(mean(MSE_output));

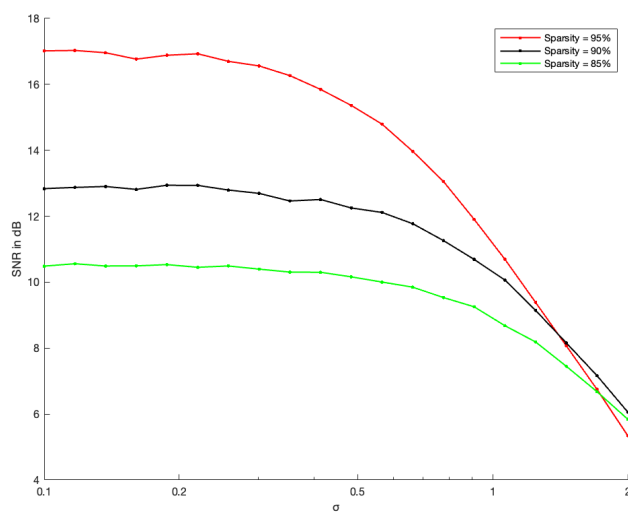
    end
end
```

```
%% Plot the performance v.s. sparsity and noise level
```

```
set_plot_defaults('on')

figure(19)
semilogx(sigma_set,SNR_output_ave(1,:), 'r.-',sigma_set,SNR_output_ave(2,:), 'k.-',sigma_set,SNR_output_ave(3,:), 'g.-')

legend('Sparsity = 95%', 'Sparsity = 90%', 'Sparsity = 85%')
xlabel('σ')
ylabel('SNR in dB')
set(gca, 'xtick', [0.1 0.2 0.5 1 2.0])
xlim([min(sigma_set) max(sigma_set)])
box off
```

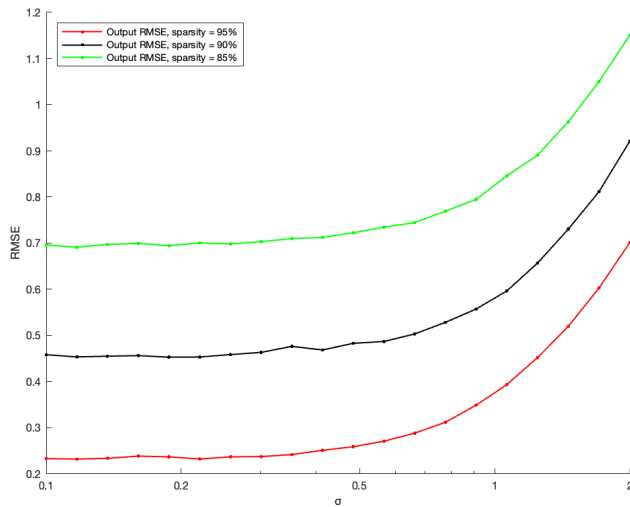


```
% set(gcf, 'PaperPosition', [1 1 14 10])
```

```
% print -depsc figures/SNR_sparsity
```

```
figure(20)
semilogx(sigma_set,MSE_output_ave(1,:), 'r.-',sigma_set,MSE_output_ave(2,:), 'k.-',sigma_set,MSE_output_ave(3,:), 'g.-')

legend('Output RMSE, sparsity = 95%', 'Output RMSE, sparsity = 90%', 'Output RMSE, sparsity = 85%', 'Location', 'NorthWest')
xlabel('σ')
ylabel('RMSE')
set(gca, 'xtick', [0.1 0.2 0.5 1 2.0])
xlim([min(sigma_set) max(sigma_set)])
box off
```



```
% set(gcf, 'PaperPosition', [1 1 14 10])

% print -depsc figures/MSE_sparsity

set_plot_defaults('off')
```

```
%% Create the performance form for multiple sparsities.
```

```
SNR_output_ave = zeros(1,5);
MSE_output_ave = zeros(1,5);

N = 500;
num = 10000;

for i = 1:1:5

    sparsity = 2.5 * (i + 1);
    K = round(500 * sparsity/100);
    SNR_output = zeros(1,num);
    MSE_output = zeros(1,num);
    for j = 1:1:num

        groundtruth = zeros(1, N);
        index_random = randperm(N);
        index = index_random(1:K);
        groundtruth(index) = 10*2*(rand(1,K) - 0.5);
        % groundtruth(index) = 10*randn(1,K);
        sigma = 2 * rand();
        input_noise = sigma*randn(1,N);
        after_conv = conv(groundtruth,h,'same');
        input = after_conv + input_noise;
        output = CNN(input, deconvolver);
        noise = output - groundtruth;
        MSE_output(j) = mean(noise.^2);
        SNR_output(j) = 10*log10(mean(groundtruth.^2)/MSE_output(j));

    end
    SNR_output_ave(i) = mean(SNR_output);
    MSE_output_ave(i) = mean(MSE_output);

end
```

```
SNR_output_ave
```

```
SNR_output_ave = 1x5
    11.4410    10.7692    10.0935     9.2702     8.6978
```

```
MSE_output_ave
```

```
MSE_output_ave = 1×5
    0.1860    0.2853    0.4011    0.5750    0.7527
```

```
%% Create the performance form for multiple noise levels
```

```
SNR_output_ave = zeros(1,8);
MSE_output_ave = zeros(1,8);

for i = 1:1:8

    sigma = 0.25 * i;
    SNR_output = zeros(1,num);
    MSE_output = zeros(1,num);
    for j = 1:1:num

        K = ceil(50*rand()+25);
        groundtruth = zeros(1, N);
        index_random = randperm(N);
        index = index_random(1:K);
        groundtruth(index) = 10*2*(rand(1,K) - 0.5);
%       groundtruth(index) = 10*randn(1,K);
        input_noise = sigma*randn(1,N);
        after_conv = conv(groundtruth,h,'same');
        input = after_conv + input_noise;
        output = CNN(input, deconvolver);
        noise = output - groundtruth;
        MSE_output(j) = mean(noise.^2);
        SNR_output(j) = 10*log10(mean(groundtruth.^2)/MSE_output(j));

    end
    SNR_output_ave(i) = mean(SNR_output);
    MSE_output_ave(i) = mean(MSE_output);

end
```

```
SNR_output_ave
```

```
SNR_output_ave = 1×8
    12.9217    12.3641    11.4108    10.2006     9.0257     7.8732     6.8385     5.9092
```

```
MSE_output_ave
```

```
MSE_output_ave = 1×8
     0.2382     0.2583     0.2982     0.3655     0.4609     0.5801     0.7236     0.8867
```

```
%% Compare the proposed CNN with other methods. Create all the methods.
```

```
r = 0.9; % Define filter
om = 0.95;
a = [1 -2*r*cos(om) r^2];
b = [1 r*cos(om)];
h = filter(b, a, [zeros(1,38) 1 zeros(1,40)]);
hh = filter(b, a, [1 zeros(1,40)]);
inverse = filter(1,hh,[zeros(1,36) 1 zeros(1,34)]);
load('sin23_2.mat');
deconvolver1{1} = double(conv1);
deconvolver1{2} = double(conv2);
deconvolver1{3} = double(conv3);
deconvolver1{4} = double(conv4);
deconvolver1{5} = double(conv5);
load('5layer_compare.mat');
deconvolver2{1} = conv1;
deconvolver2{2} = conv2;
deconvolver2{3} = conv3;
deconvolver2{4} = conv4;
deconvolver2{5} = conv5;
load('7layer_compare.mat');
deconvolver3{1} = conv1;
deconvolver3{2} = conv2;
deconvolver3{3} = conv3;
deconvolver3{4} = conv4;
deconvolver3{5} = conv5;
deconvolver3{6} = conv6;
deconvolver3{7} = conv7;
```

```
%% Create input signal (noisy signal) and ground truth (pure signal).
```

```
% N is the total length of the pure sparse signal.
```



```
% K is the number of non-zeros in the pure sparse signal.
% As a result, 1-K/N determines the sparsity of the pure signal.
```

```
N = 500;
num = 1000;
sigma_set = 0.1:0.1:2;
SNR_1 = zeros(1,length(sigma_set));
MSE_1 = zeros(1,length(sigma_set));
SNR_2 = zeros(1,length(sigma_set));
MSE_2 = zeros(1,length(sigma_set));
SNR_3 = zeros(1,length(sigma_set));
MSE_3 = zeros(1,length(sigma_set));
SNR_4 = zeros(1,length(sigma_set));
MSE_4 = zeros(1,length(sigma_set));

for i = 1:length(sigma_set)

    sigma = sigma_set(i);
    SNR_num1 = zeros(1,num);
    MSE_num1 = zeros(1,num);
    SNR_num2 = zeros(1,num);
    MSE_num2 = zeros(1,num);
    SNR_num3 = zeros(1,num);
    MSE_num3 = zeros(1,num);
    SNR_num4 = zeros(1,num);
    MSE_num4 = zeros(1,num);

    for j = 1:num

        K = ceil(50*rand()+25);
        groundtruth = zeros(1, N);
        index_random = randperm(N);
        index = index_random(1:K);
        groundtruth(index) = 10*2*(rand(1,K) - 0.5);
        after_conv = conv(groundtruth,h,'same');
        % groundtruth(index) = 10*randn(1,K);
        input = after_conv + sigma*randn(1,N);

        output = CNN(input, deconvolver1);
        noise = output - groundtruth;
        MSE_num1(j) = mean(noise.^2);
        SNR_num1(j) = 10*log10(mean(groundtruth.^2)/MSE_num1(j));

        output = CNN(input, deconvolver2);
        noise = output - groundtruth;
        MSE_num2(j) = mean(noise.^2);
        SNR_num2(j) = 10*log10(mean(groundtruth.^2)/MSE_num2(j));

        output = CNN(input, deconvolver3);
        noise = output - groundtruth;
        MSE_num3(j) = mean(noise.^2);
        SNR_num3(j) = 10*log10(mean(groundtruth.^2)/MSE_num3(j));

        output = conv(input,inverse,'same');
        noise = output - groundtruth;
        MSE_num4(j) = mean(noise.^2);
        SNR_num4(j) = 10*log10(mean(groundtruth.^2)/MSE_num4(j));

    end
    SNR_1(i) = mean(SNR_num1);
    % MSE_1(i) = mean(MSE_num1);
    MSE_1(i) = sqrt(mean(MSE_num1));
    SNR_2(i) = mean(SNR_num2);
    % MSE_2(i) = mean(MSE_num2);
    MSE_2(i) = sqrt(mean(MSE_num2));
    SNR_3(i) = mean(SNR_num3);
    % MSE_3(i) = mean(MSE_num3);
    MSE_3(i) = sqrt(mean(MSE_num3));
    SNR_4(i) = mean(SNR_num4);
    % MSE_4(i) = mean(MSE_num4);
    MSE_4(i) = sqrt(mean(MSE_num4));

end
```

```
%% Plot the performance figures of different methods.
```

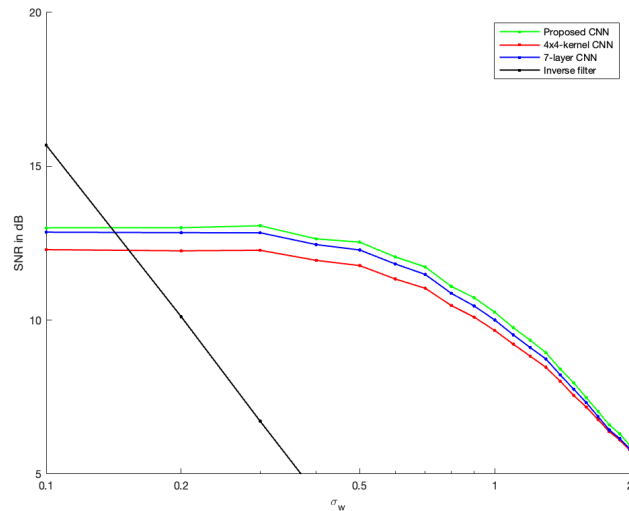
```
set_plot_defaults('on')

figure(21)
clf
semilogx(sigma_set, SNR_1,'g.-', sigma_set, SNR_2,'r.-', sigma_set, SNR_3,'b.-', sigma_set, SNR_4, 'k.-');
legend('Proposed CNN', '4x4-kernel CNN', '7-layer CNN', 'Inverse filter');
xlabel('\sigma_w')
ylabel('SNR in dB')
```

```

set(gca, 'xtick', [0.1 0.2 0.5 1 2.0])
xlim([min(sigma_set) max(sigma_set)])
ylim([5,20])
box off

```



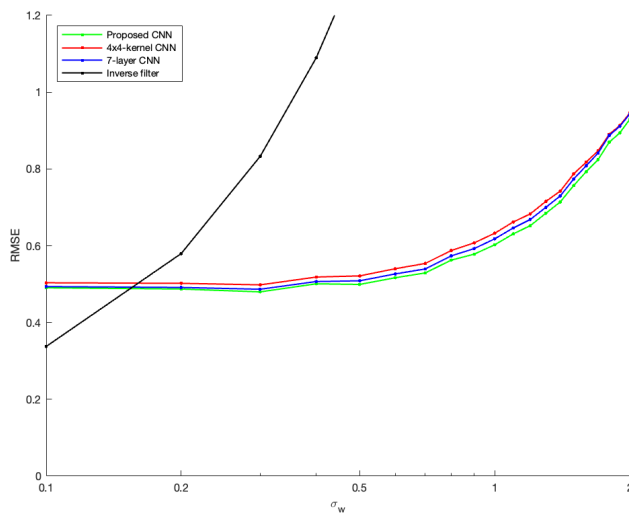
```

% set(gcf, 'PaperPosition', [1 1 14 10])

% print -depsc figures/SNR_average

figure(22)
clf
semilogx(sigma_set, MSE_1, 'g.-', sigma_set, MSE_2, 'r.-', sigma_set, MSE_3, 'b.-', sigma_set, MSE_4, 'k.-');
legend('Proposed CNN', '4x4-kernel CNN', '7-layer CNN', 'Inverse filter', 'Location', 'NorthWest');
xlabel('\sigma_w')
ylabel('RMSE')
set(gca, 'xtick', [0.1 0.2 0.5 1 2.0])
xlim([min(sigma_set) max(sigma_set)])
ylim([0,1.2])
box off

```



```

% set(gcf, 'PaperPosition', [1 1 14 10])

% print -depsc figures/MSE_average

set_plot_defaults('off')

```

```

%% Create the comparison form for different methods.

```

```

num = 1000;
SNR_num1 = zeros(1,num);
MSE_num1 = zeros(1,num);
SNR_num2 = zeros(1,num);
MSE_num2 = zeros(1,num);
SNR_num3 = zeros(1,num);

```

```

MSE_num3 = zeros(1,num);
SNR_num4 = zeros(1,num);
MSE_num4 = zeros(1,num);

for j = 1:1:num

    sigma = 2; % change from 0 to 2 with an interval of 0.5.
    K = ceil(50*rand()+25);
    groundtruth = zeros(1, N);
    index_random = randperm(N);
    index = index_random(1:K);
    groundtruth(index) = 10*2*(rand(1,K) - 0.5);
    after_conv = conv(groundtruth,h,'same');
    % groundtruth(index) = 10*randn(1,K);
    ini_noise = sigma*randn(1,N);
    input = after_conv + ini_noise;

    output = CNN(input, deconvolver1);
    noise = output - groundtruth;
    MSE_num1(j) = mean(noise.^2);
    SNR_num1(j) = 10*log10(mean(groundtruth.^2)/MSE_num1(j));

    output = CNN(input, deconvolver2);
    noise = output - groundtruth;
    MSE_num2(j) = mean(noise.^2);
    SNR_num2(j) = 10*log10(mean(groundtruth.^2)/MSE_num2(j));

    output = CNN(input, deconvolver3);
    noise = output - groundtruth;
    MSE_num3(j) = mean(noise.^2);
    SNR_num3(j) = 10*log10(mean(groundtruth.^2)/MSE_num3(j));

    output = conv(input,inverse,'same');
    noise = output - groundtruth;
    MSE_num4(j) = mean(noise.^2);
    SNR_num4(j) = 10*log10(mean(groundtruth.^2)/MSE_num4(j));

end

SNR_1 = mean(SNR_num1)

```

SNR\_1 = 5.8902

MSE\_1 = mean(MSE\_num1)

MSE\_1 = 0.8636

SNR\_2 = mean(SNR\_num2)

SNR\_2 = 5.7362

MSE\_2 = mean(MSE\_num2)

MSE\_2 = 0.8920

SNR\_3 = mean(SNR\_num3)

SNR\_3 = 5.7450

MSE\_3 = mean(MSE\_num3)

MSE\_3 = 0.8961

SNR\_4 = mean(SNR\_num4)

SNR\_4 = -9.5516

MSE\_4 = mean(MSE\_num4)

MSE\_4 = 28.3626