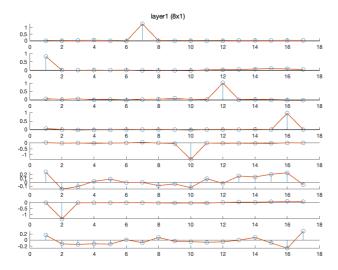
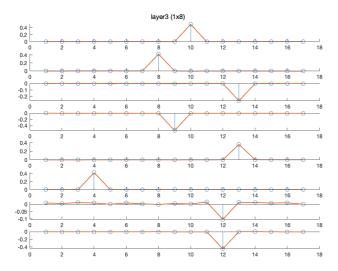
```
clc;
clear;
close all;
```

```
% Plot the previous training CNN.
set_plot_defaults('on')
load('denoiser_sparse.mat');
h1{1} = double(conv1);
h1{2} = double(conv2);
h1{3} = reshape(double(conv3),[8,1,17]);
figure(1)
[r,c,~] = size(h1{1});
for i=1:1:r
   for j=1:1:c
   subplot(r,c,c*i-(c-j))
   stem(flip(squeeze(h1{1}(i,j,:))))
   hold on
   plot(flip(squeeze(h1{1}(i,j,:))))
   hold off
   box off
   end
sgtitle('layer1 (8x1)', 'FontSize', 10);
```



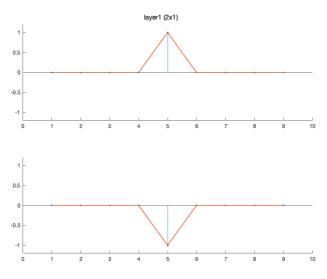
```
% set(gcf, 'PaperPosition', [1 1 7 15])
% print -depsc figures/previous_layer1

figure(2)
[r,c,~] = size(h1{3});
for i=1:1:r
    for j=1:1:c
    subplot(r,c,c*i-(c-j))
    stem(flip(squeeze(h1{3}(i,j,:))))
    hold on
    plot(flip(squeeze(h1{3}(i,j,:))))
    hold off
    box off
    end
end
sgtitle('layer3 (1x8)', 'FontSize', 10);
```



```
% set(gcf, 'PaperPosition', [1 1 7 15])
% print -depsc figures/previous_layer3
set_plot_defaults('off')
```

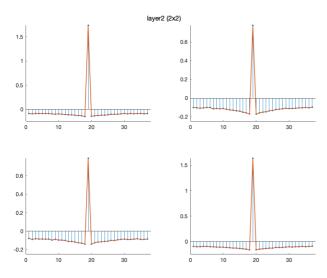
```
% Plot the previous training CNN.
load('remove_13_retrained.mat');
h1{1} = double(conv1);
h1{2} = double(conv2);
h1{3} = double(conv3);
set_plot_defaults('on')
figure(3)
[r,c,~] = size(h1{1});
for i=1:1:r
    for j=1:1:c
        subplot(r,c,c*i-(c-j))
        stem(flip(squeeze(h1{1}(i,j,:))), 'filled', 'MarkerSize', 2)
        hold on
        plot(flip(squeeze(h1{1}(i,j,:))))
        hold off
        xlim([0,10])
        ylim([-1.2,1.2])
        box off
    end
end
sgtitle('layer1 (2x1)', 'FontSize', 10);
```



```
% set(gcf, 'PaperPosition', [1 1 3 6])
```

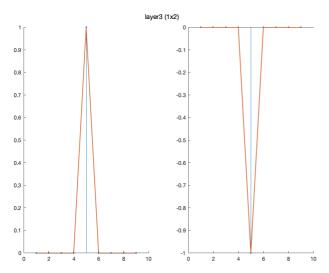
```
% print -depsc figures/layer1_train

figure(4)
[r,c,~] = size(h1{2});
for i=1:1:r
    for j=1:1:c
        subplot(r,c,c*i-(c-j))
        stem(flip(squeeze(h1{2}(i,j,:))), 'filled', 'MarkerSize', 2)
        hold on
        plot(flip(squeeze(h1{2}(i,j,:))))
        hold off
        xlim([0,38])
        ylim([-0.25,inf])
        box off
    end
end
sgtitle('layer2 (2x2)', 'FontSize', 10);
```



```
% set(gcf, 'PaperPosition', [1 1 6 6])
% print -depsc figures/layer2_train

figure(5)
[r,c,~] = size(h1{3});
for i=1:1:r
    for j=1:1:c
        subplot(r,c,c*i-(c-j))
        stem(flip(squeeze(h1{3}(i,j,:))), 'filled', 'MarkerSize', 2)
        hold on
        plot(flip(squeeze(h1{3}(i,j,:))))
        hold off
        box off
    end
end
sgtitle('layer3 (1x2)', 'FontSize', 10);
```

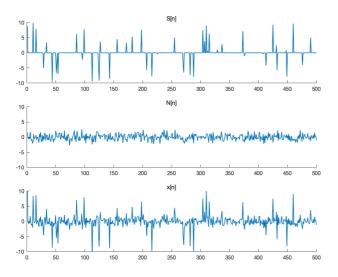


```
% set(gcf, 'PaperPosition', [1 1 6 6])
% print -depsc figures/layer3_train
set_plot_defaults('off')
```

```
% clc
clear
% close all

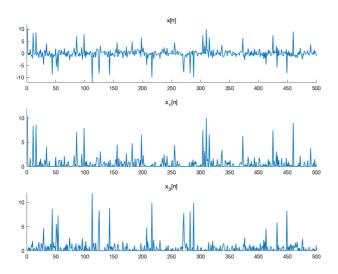
N = 500;
K = 50;
sigma = 1;
groundtruth = zeros(1, N);
index_random = randperm(N);
index = index_random(1:K);
groundtruth(index) = 10*2*(rand(1,K) - 0.5);
noise = sigma * randn(1,N);
input = groundtruth + noise;
```

```
% Plot the components of the input signal.
set_plot_defaults('on')
figure(6)
subplot(3,1,1)
plot(1:N, groundtruth)
title('5[n]')
ylim([-10 10])
box off
subplot(3,1,2)
plot(1:N, noise)
title('N[n]')
ylim([-10 10])
box off
subplot(3,1,3)
plot(1:N, input)
title('x[n]')
ylim([-10 10])
```



```
% set(gcf, 'PaperPosition', [1 1 10 8])
% print -depsc figures/input
set_plot_defaults('off')
```

```
% Plot the output of each layer
set_plot_defaults('on')
figure(7)
l1 = layer(input, h1{1});
subplot(3,1,1)
plot(1:N,input)
title('x[n]')
ylim([-12,12])
xlim([0,500])
box off
subplot(3,1,2)
plot(1:N, l1(1,:))
title('x_1[n]')
ylim([0,12])
xlim([0,500])
box off
subplot(3,1,3)
plot(1:N,l1(2,:))
title('x_2[n]')
ylim([0,12])
xlim([0,500])
box off
```



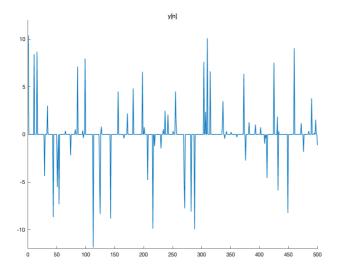
```
% set(gcf, 'PaperPosition', [1 1 8 9])
% print -depsc figures/l1
figure(8)
l2_NR = conv1d(l1,h1{2});
12 = ReLU(12_NR);
subplot(2,2,1)
plot(1:N, l2_NR(1,:))
title('c_1[n]')
ylim([-10,20])
xlim([0,500])
box off
subplot(2,2,3)
plot(1:N, l2_NR(2,:))
title('c_2[n]')
ylim([-10,20])
xlim([0,500])
box off
subplot(2,2,2)
plot(1:N,l2(1,:))
title('c_1[n] after ReLU')
ylim([0,12])
xlim([0,500])
box off
```

```
subplot(2,2,4)
plot(1:N,12(1,:))
title('c_1[n] after ReLU')
ylim([0,12])
xlim([0,500])
box off
```

```
20 c<sub>1</sub>[n] 12 c<sub>2</sub>[n] 12 c<sub>3</sub>[n] after ReLU 2 c<sub>4</sub>[n] after ReLU 2 c<sub>5</sub>[n] after ReLU 2 c<sub>6</sub>[n] after ReLU 2 c<sub>7</sub>[n] after ReLU 2 c<sub>7</sub>[
```

```
% set(gcf, 'PaperPosition', [1 1 10 6])
% print -depsc figures/l2

figure(9)
l3 = conv1d(l2,h1{3});
plot(1:N,l3)
title('y[n]')
ylim([-12,12])
xlim([0,500])
box off
title('y[n]')
```

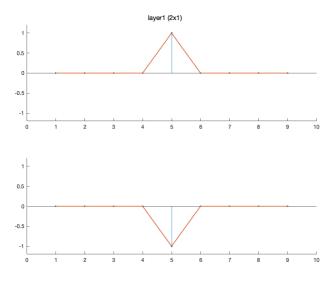


```
% set(gcf, 'PaperPosition', [1 1 8 3])
% print -depsc figures/l3
set_plot_defaults('off')
```

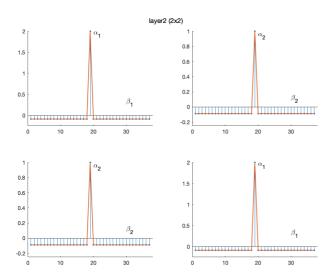
```
% Plot the structure of the proposed CNN

set_plot_defaults('on')
figure(10)
[r,c,~] = size(h1{1});
for i=1:1:r
    for j=1:1:c
        subplot(r,c,c*i-(c-j))
        stem(flip(squeeze(h1{1}(i,j,:))), 'filled', 'MarkerSize', 2)
        hold on
```

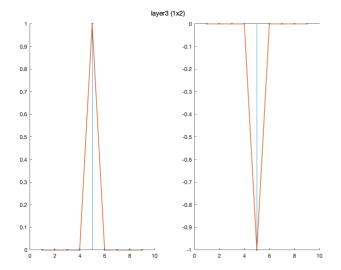
```
plot(flip(squeeze(h1{1}(i,j,:))))
    hold off
    xlim([0,10])
    ylim([-1.2,1.2])
    box off
end
end
sgtitle('layer1 (2x1)', 'FontSize', 10);
```



```
% set(gcf, 'PaperPosition', [1 1 3 6])
% print -depsc figures/layer1
figure(11)
title('Layer 2')
[r,c,~] = size(h1{2});
for i=1:1:r
    for j=1:1:c
         subplot(r,c,c*i-(c-j))
         stem(flip(squeeze(h1{2}(i,j,:))), 'filled', 'MarkerSize', 2)
         hold on
         plot(flip(squeeze(h1{2}(i,j,:))))
         hold on
         plot(19,h1{2}(i,j,19), 'MarkerSize', 10)
         hold on
         if i == j
              text(20,h1{2}(i,j,19)-0.05, '\alpha_1')
text(30,h1{2}(i,j,8)+0.4, '\beta_1')
              text(20,h1{2}(i,j,19)-0.05, '\alpha_2')
text(30,h1{2}(i,j,8)+0.2, '\beta_2')
         end
         plot(30,h1{2}(i,j,8), 'MarkerSize', 10)
         hold off
         xlim([0,38])
         ylim([-0.25,inf])
         box off
    end
sgtitle('layer2 (2x2)', 'FontSize', 10);
```



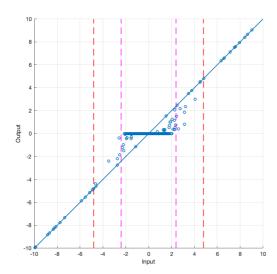
```
% set(gcf, 'PaperPosition', [1 1 6 6])
% print -depsc figures/layer2
figure(12)
title('Layer 3')
[r,c,~] = size(h1{3});
for i=1:1:r
    for j=1:1:c
        subplot(r,c,c*i-(c-j))
        stem(flip(squeeze(h1{3}(i,j,:))), 'filled', 'MarkerSize', 2)
        hold on
        plot(flip(squeeze(h1{3}(i,j,:))))
        hold off
        box off
    end
end
sgtitle('layer3 (1x2)', 'FontSize', 10);
```



```
% set(gcf, 'PaperPosition', [1 1 6 6])
% print -depsc figures/layer3
set_plot_defaults('off')
```

```
%% Plot the output signal v.s. input signal and display the thresholds.
set_plot_defaults('on')
output = CNN(input,h1);
figure(13)
plot(input, output, 'o', 'MarkerSize', 4)
hold on;
```

```
line([threshold1 threshold1], [-10 10],'Color','magenta','LineStyle','--')
line([threshold2 threshold2], [-10 10],'Color','red','LineStyle','--')
line([-threshold1 -threshold1], [-10 10],'Color','magenta','LineStyle','--')
line([-threshold2 -threshold2], [-10 10],'Color','red','LineStyle','--')
xlabel('Input')
ylabel('Output')
grid
axis equal square
line([-10 10], [-10 10])
axis([-10,10,-10,10])
box off
```



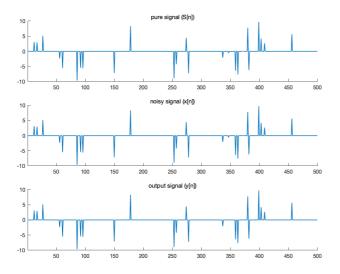
```
% set(gcf, 'PaperPosition', [1 1 9 9])
% print -depsc figures/threshold
set_plot_defaults('off')
```

```
%% Create the proposed CNN
threshold1 = 2.61;
threshold2 = 5.26;
rho = 1;
                        \ensuremath{\$} rho is the ratio between output and input signal.
l = 37;
                        % l is the length of the filters in the second layer.
training_sigma = 2;
                        % The standard deviation of the Gaussian noise in the training data is between 0 and training sigm
training_num = 60000;
                        % training_num is the number of the training signals.
                        \% 1 means Uniform and 2 means Gaussian.
training_type = 1;
istrain_flag = false;
                       % istrain_flag can determine if training a new CNN or directly using the trained parameters.
h1 = create_denoiser(l,rho,threshold1,threshold2,training_type,istrain_flag);
N = 500;
K = 25;
sigma = 0.5;
groundtruth = zeros(1, N);
index_random = randperm(N);
index = index_random(1:K);
groundtruth(index) = 10*2*(rand(1,K) - 0.5);
noise = sigma * randn(1,N);
input = groundtruth + noise;
```

```
%% Display groundtruth, input signal and output signal. Plot input signal v.s. output signal in two forms. Pure signal cas
set_plot_defaults('on')

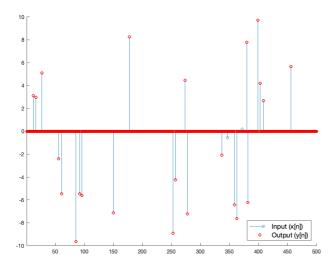
figure(14)
output = CNN(groundtruth, h1);
subplot(3,1,1)
plot(groundtruth)
title('pure signal (S[n])');
xlim([1,500])
ylim([-10,10])
box off
subplot(3,1,2)
plot(groundtruth)
title('noisy signal (x[n])');
xlim([1,500])
ylim([-10,10])
```

```
box off
subplot(3,1,3)
plot(output)
title('output signal (y[n])');
xlim([1,500])
ylim([-10,10])
box off
```



```
% set(gcf, 'PaperPosition', [1 1 14 8])
% print -depsc figures/pure1

n = 1:N;
figure(15)
stem(n, groundtruth, 'MarkerSize', 4)
hold on
plot(n, output, 'ro', 'MarkerSize', 4)
hold off
legend('Input (x[n])', 'Output (y[n])', 'Location', 'SouthEast', 'FontSize', 10)
xlim([1,500])
ylim([-10,10])
% title('Input v.s. output')
box off
```

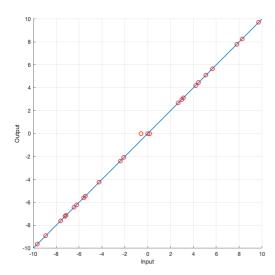


```
% set(gcf, 'PaperPosition', [1 1 14 8])
% print -depsc figures/pure2
loss = mean((output - groundtruth).^2)
loss = 7.2311e-04
```

```
SNR = 10*log10(mean(groundtruth.^2)/loss)
```

SNR = 33.8549

```
figure(16)
plot(groundtruth, output, 'ro')
hold on
xlabel('Input')
ylabel('Output')
grid
axis equal square
line([-10 10], [-10 10])
hold off
% title('Input v.s. output')
box off
```



```
% set(gcf, 'PaperPosition', [1 1 10 10])
% print -depsc figures/pure3
set_plot_defaults('off')
```

```
% Display groundtruth, input signal and output signal. Plot input signal v.s. output signal in two forms. Pure noise case
set_plot_defaults('on')
figure(17)
output = CNN(noise, h1);
subplot(3,1,1)
plot(zeros(1,N))
title('pure signal (S[n])');
xlim([1,500])
ylim([-10,10])
box off
subplot(3,1,2)
plot(noise)
title('noisy signal (x[n])');
xlim([1,500])
ylim([-10,10])
box off
subplot(3,1,3)
plot(output)
title('output signal (y[n])');
xlim([1,500])
ylim([-10,10])
box off
```

```
pure signal (S[n])

5

10

50

100

150

200

250

300

350

400

450

500

100

150

200

250

300

350

400

450

500

0utput signal (y[n])

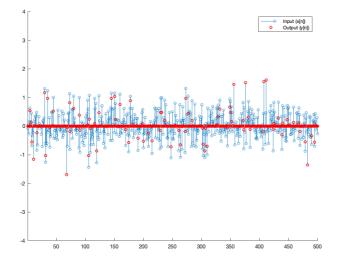
5

0

0utput signal (y[n])
```

```
% set(gcf, 'PaperPosition', [1 1 14 8])
% print -depsc figures/noise1

n = 1:N;
figure(18)
stem(n, noise, 'MarkerSize', 4)
hold on
plot(n, output, 'ro', 'MarkerSize', 4)
hold off
legend('Input (x[n])', 'Output (y[n])')
xlim([1,500])
ylim([-4,4])
% title('Input v.s. output')
box off
```



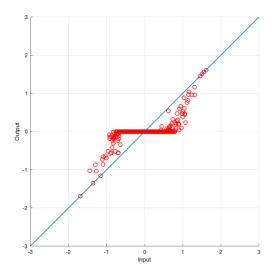
```
% set(gcf, 'PaperPosition', [1 1 14 8])
% print -depsc figures/noise2
loss = mean((output - 0).^2)
```

```
loss = 0.0689

% mean(noise.^2)
% SNR = 10*log10(mean(groundtruth.^2)/loss)

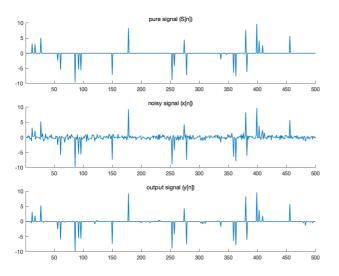
figure(19)
plot(noise, output, 'ro')
hold on
xlabel('Input')
ylabel('Output')
grid
axis equal square
line([-3 3], [-3 3])
```

```
hold off
% title('Input v.s. output')
box off
```



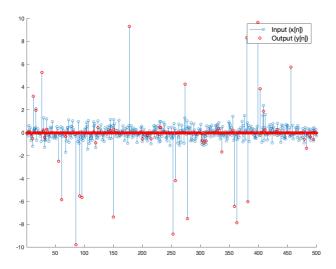
```
% set(gcf, 'PaperPosition', [1 1 9 9])
% print -depsc figures/noise3
set_plot_defaults('off')
```

```
% Display groundtruth, input signal and output signal. Plot input signal v.s. output signal in two forms. Noisy signal ca
set_plot_defaults('on')
figure(20)
output = CNN(input, h1);
subplot(3,1,1)
plot(groundtruth)
title('pure signal (S[n])');
xlim([1,500])
ylim([-10,10])
box off
subplot(3,1,2)
plot(input)
title('noisy signal (x[n])');
xlim([1,500])
ylim([-10,10])
box off
subplot(3,1,3)
plot(output)
title('output signal (y[n])');
xlim([1,500])
ylim([-10,10])
box off
```



```
% set(gcf, 'PaperPosition', [1 1 14 8])
% print -depsc figures/noisy1

n = 1:N;
figure(21)
stem(n, input, 'MarkerSize', 4)
hold on
plot(n, output, 'ro', 'MarkerSize', 4)
hold off
legend('Input (x[n])', 'Output (y[n])', 'FontSize', 10)
xlim([1,500])
ylim([-10,10])
% title('Input v.s. output')
box off
```



```
% set(gcf, 'PaperPosition', [1 1 14 8])
% print -depsc figures/noisy2
loss = mean((output - groundtruth).^2)
```

loss = 0.0232

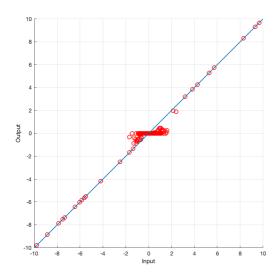
```
output_SNR = 10*log10(mean(groundtruth.^2)/loss)
```

output_SNR = 18.7927

```
input_SNR = 10*log10(mean(groundtruth.^2)/mean((input - groundtruth).^2))
```

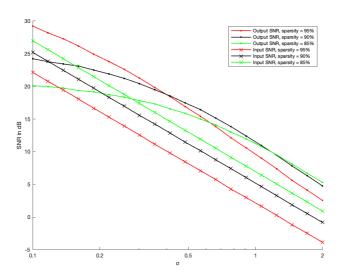
input_SNR = 8.2861

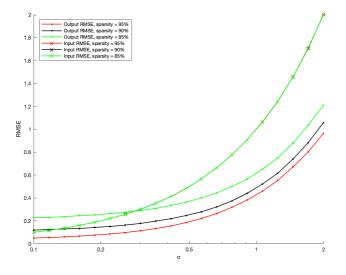
```
figure(22)
plot(input, output, 'ro')
hold on
xlabel('Input')
ylabel('Output')
grid
axis equal square
line([-10 10], [-10 10])
hold off
% title('Input v.s. output')
box off
```



```
% set(gcf, 'PaperPosition', [1 1 9 9])
% print -depsc figures/noisy3
set_plot_defaults('off')
```

```
% Create input signal (noisy signal) and ground truth (pure signal) for the performance part.
% N is the total length of the pure sparse signal.
% K is the number of non-zeros in the pure sparse signal.
\% As a result, 1-K/N determines the sparsity of the pure signal.
N = 500;
num = 1000;
sigma_set = logspace(log10(0.1), log10(2), 20);
% sigma_set = 0.1:0.1:2;
MSE_output_ave = zeros(3,length(sigma_set));
MSE_input_ave = zeros(3,length(sigma_set));
SNR_output_ave = zeros(3,length(sigma_set));
SNR_input_ave = zeros(3,length(sigma_set));
for m = 1:1:3
   K = 25 * m;
    for i = 1:1:length(sigma_set)
        sigma = sigma_set(i);
        SNR_output = zeros(1, num);
        SNR_input = zeros(1,num);
        MSE_output = zeros(1,num);
        MSE_input = zeros(1,num);
        for j = 1:1:num
            groundtruth = zeros(1, N);
            index_random = randperm(N);
            index = index_random(1:K);
            groundtruth(index) = 10*2*(rand(1,K) - 0.5);
              groundtruth(index) = 10*randn(1,K);
            input_noise = sigma*randn(1,N);
            input = groundtruth + input_noise;
            output = CNN(input, h1);
            noise = output - groundtruth;
           MSE_output(j) = mean(noise.^2);
           MSE_input(j) = mean(input_noise.^2);
            SNR_output(j) = 10*log10(mean(groundtruth.^2)/MSE_output(j));
            SNR_{input(j)} = 10*log10(mean(groundtruth.^2)/MSE_{input(j))};
        end
        SNR_output_ave(m,i) = mean(SNR_output);
        SNR_input_ave(m,i) = mean(SNR_input);
          MSE_output_ave(m,i) = mean(MSE_output);
          MSE_input_ave(m,i) = mean(MSE_input);
        MSE_output_ave(m,i) = sqrt(mean(MSE_output));
        MSE_input_ave(m,i) = sqrt(mean(MSE_input));
   end
end
```





```
% print -depsc figures/MSE_sparsity
set_plot_defaults('off')
%% Create the performance form for multiple sparsities
SNR_input_ave = zeros(1,5);
SNR_output_ave = zeros(1,5);
MSE_input_ave = zeros(1,5);
MSE_output_ave = zeros(1,5);
N = 500:
num = 10000;
for i = 1:1:5
    sparsity = 2.5 * (i + 1);
    K = round(500 * sparsity/100);
    SNR_output = zeros(1,num);
   SNR_input = zeros(1,num);
   MSE_output = zeros(1,num);
   MSE_input = zeros(1,num);
    for j = 1:1:num
        groundtruth = zeros(1, N);
        index_random = randperm(N);
        index = index_random(1:K);
        groundtruth(index) = 10*2*(rand(1,K) - 0.5);
          groundtruth(index) = 10*randn(1,K);
        sigma = 2 * rand();
        input_noise = sigma*randn(1,N);
        input = groundtruth + input_noise;
        output = CNN(input, h1);
        noise = output - groundtruth;
        MSE_output(j) = mean(noise.^2);
        MSE_input(j) = mean(input_noise.^2);
        SNR_output(j) = 10*log10(mean(groundtruth.^2)/MSE_output(j));
        SNR_input(j) = 10*log10(mean(groundtruth.^2)/MSE_input(j));
    end
    SNR_input_ave(i) = mean(SNR_input);
    SNR_output_ave(i) = mean(SNR_output);
   MSE_input_ave(i) = mean(MSE_input);
   MSE_output_ave(i) = mean(MSE_output);
end
SNR_input_ave
SNR_input_ave = 1 \times 5
   4.8082 6.5336 7.9970 8.7514 9.5033
SNR_output_ave
SNR\_output\_ave = 1 \times 5
  12.0075 12.7675 12.9235 12.3450 11.8883
MSE_input_ave
MSE_input_ave = 1 \times 5
   1.3255 1.3341 1.3143 1.3607
                                     1.3527
MSE output ave
MSE_output_ave = 1×5
   0.2773 0.3042 0.3438
                            0.4289
                                     0.5134
%% Create the performance form for multiple noise levels
SNR input ave = zeros(1.8);
SNR_output_ave = zeros(1,8);
MSE_input_ave = zeros(1,8);
MSE_output_ave = zeros(1,8);
for i = 1:1:8
    sigma = 0.25 * i;
    SNR_output = zeros(1, num);
```

SNR_input = zeros(1,num);

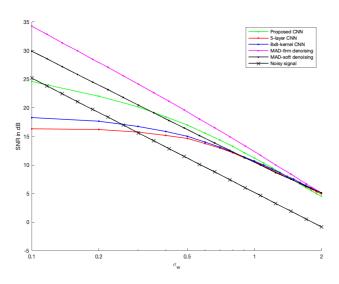
```
MSE output = zeros(1.num):
   MSE_input = zeros(1,num);
    for j = 1:1:num
        K = ceil(50*rand()+25);
        groundtruth = zeros(1, N);
        index_random = randperm(N);
        index = index_random(1:K);
        groundtruth(index) = 10*2*(rand(1,K) - 0.5);
          groundtruth(index) = 10*randn(1,K);
        input_noise = sigma*randn(1,N);
        input = groundtruth + input_noise;
        output = CNN(input, h1);
        noise = output - groundtruth;
        MSE_output(j) = mean(noise.^2);
        MSE_input(j) = mean(input_noise.^2);
        SNR_output(j) = 10*log10(mean(groundtruth.^2)/MSE_output(j));
        SNR_input(j) = 10*log10(mean(groundtruth.^2)/MSE_input(j));
    end
    SNR_input_ave(i) = mean(SNR_input);
    SNR_output_ave(i) = mean(SNR_output);
    MSE_input_ave(i) = mean(MSE_input);
   MSE_output_ave(i) = mean(MSE_output);
end
SNR_input_ave
SNR_input_ave = 1 \times 8
  17.0948 11.0749
                    7.5190
                            5.0472 3.1186 1.5245
                                                        0.1928 -0.9624
SNR output ave
SNR_output_ave = 1×8
  21.1331 16.9353 13.7486 11.2079
                                      9.1184 7.3396
                                                        5.8310
                                                                4.5180
MSE_input_ave
MSE input ave = 1 \times 8
   0.0625 0.2498
                     0.5630
                             0.9996
                                      1.5617
                                               2.2511
                                                        3.0616
MSE_output_ave
MSE\_output\_ave = 1 \times 8
   0.0316 0.0726
                     0.1429
                            0.2524
                                     0.4054
                                             0.6062
                                                        0.8562
                                                               1.1545
%% Compare the proposed CNN with other methods. Create all the methods.
threshold1 = 2.61;
threshold2 = 5.26;
rho = 1;
                        % rho is the ratio between output and input signal.
l = 37;
                  % l is the length of the filters in the second layer.
training_sigma = 2;
                       % The standard deviation of the Gaussian noise in the training data is between 0 and training sigm
training_num = 20000; % training_num is the number of the training signals.
training_type = 1;
                        % 1 means Uniform and 2 means Gaussian.
istrain_flag = false;
                       \$ istrain_flag can determine if training a new CNN or directly using the trained parameters.
h1 = create_denoiser(l,rho,threshold1,threshold2,training_type,istrain_flag);
% h1 = create_denoiser(l,rho,threshold1,threshold2,training_type,istrain_flag,training_num,training_sigma);
% load('CNNs/2hidden_unfix.mat');
h2{1} = conv1;
h2{2} = conv2;
% h2{3} = conv3;
h2{4} = conv4;
load('CNNs/3hidden_unfix.mat');
h3{1} = conv1;
h3{2} = conv2;
h3{3} = conv3;
h3{4} = conv4;
h3{5} = conv5;
% load('CNNs/4kernel_fix.mat');
% h4{1} = conv1;
h4{2} = conv2;
% h4{3} = conv3;
% h4{4} = conv4;
load('CNNs/8kernel_fix.mat');
h4{1} = conv1;
h4{2} = conv2;
h4{3} = conv3;
h4{4} = conv4;
```

%% Create input signal (noisy signal) and groundtruth (pure signal).

```
% N is the total length of the pure sparse signal.
% K is the number of non-zeros in the pure sparse signal.
% As a result, 1-K/N determines the sparsity of the pure signal.
N = 500:
num = 1000;
sigma_set = 0.1:0.1:2;
SNR_1 = zeros(1,length(sigma_set));
MSE_1 = zeros(1,length(sigma_set));
SNR_3 = zeros(1,length(sigma_set));
MSE_3 = zeros(1,length(sigma_set));
SNR_4 = zeros(1,length(sigma_set));
MSE_4 = zeros(1,length(sigma_set));
for i = 1:1:length(sigma_set)
    sigma = sigma_set(i);
    SNR_num1 = zeros(1,num);
    MSE_num1 = zeros(1,num);
    SNR_num3 = zeros(1,num);
    MSE_num3 = zeros(1,num);
    SNR_num4 = zeros(1,num);
    MSE_num4 = zeros(1,num);
    for j = 1:1:num
        K = ceil(50*rand()+25);
        groundtruth = zeros(1, N);
        index_random = randperm(N);
        index = index_random(1:K);
        groundtruth(index) = 10*2*(rand(1,K) - 0.5);
groundtruth(index) = 10*randn(1,K);
        input = groundtruth + sigma*randn(1,N);
        output = CNN(input, h1);
        noise = output - groundtruth;
        MSE_num1(j) = mean(noise.^2);
        SNR_num1(j) = 10*log10(mean(groundtruth.^2)/MSE_num1(j));
        output = CNN(input, h3);
        noise = output - groundtruth;
        MSE_num3(j) = mean(noise.^2);
        SNR_num3(j) = 10*log10(mean(groundtruth.^2)/MSE_num3(j));
        output = CNN(input, h4);
        noise = output - groundtruth;
        MSE_num4(j) = mean(noise.^2);
        SNR_num4(j) = 10*log10(mean(groundtruth.^2)/MSE_num4(j));
    SNR 1(i) = mean(SNR num1);
     MSE_1(i) = mean(MSE_num1);
    MSE_1(i) = sqrt(mean(MSE_num1));
    SNR_3(i) = mean(SNR_num3);
     MSE_3(i) = mean(MSE_num3);
    MSE 3(i) = sqrt(mean(MSE num3));
    SNR_4(i) = mean(SNR_num4);
     MSE_4(i) = mean(MSE_num4);
    MSE_4(i) = sqrt(mean(MSE_num4));
end
\ensuremath{\text{\%}} Plot the performance figures of different methods.
K = 50:
ratio = K/N;
                                       % sparsity level
sigma_x = 10.0;
                                     % Gaussian standard deviation
% [sigma_w_, SNR_x_hat, SNR_y, MSE_mad] = sparse_denoise_MAD_calculate_SNR(N, ratio, sigma_x);
% MSE_mad = sqrt(MSE_mad);
[sigma_w_, SNR_x_soft, SNR_x_firm, SNR_y, MSE_firm, MSE_soft] = sparse_denoise_MAD_calculate_SNR(N, ratio, sigma_x);
progress = 0.050000
progress = 0.100000
progress = 0.150000
progress = 0.200000
progress = 0.250000
progress = 0.300000
progress = 0.350000
progress = 0.400000
progress = 0.450000
progress = 0.500000
```

progress = 0.550000

```
progress = 0.600000
 progress = 0.650000
 progress = 0.700000
  progress = 0.750000
 progress = 0.800000
 progress = 0.850000
MSE_soft = sqrt(MSE_soft);
MSE_firm = sqrt(MSE_firm);
set_plot_defaults('on')
figure(25)
clf
% semilogx(sigma_set, SNR_1,'g.-', sigma_set, SNR_3,'r.-', sigma_set, SNR_4,'b.-', sigma_w_, SNR_x_hat, 'k.-',sigma_w_, SN semilogx(sigma_set, SNR_1,'g.-', sigma_set, SNR_3,'r.-', sigma_set, SNR_4,'b.-', sigma_w_, SNR_x_firm, 'm.-', sigma_w_, 'm.-', sigm
% legend('Proposed CNN', '5-layer CNN', '8x8-kernel CNN', 'MAD-soft denoising', 'Noisy signal');
legend('Proposed CNN', '5-layer CNN', '8x8-kernel CNN', 'MAD-firm denoising', 'MAD-soft denoising', 'Noisy signal');
xlabel('\sigma_w')
ylabel('SNR in dB')
set(gca, 'xtick', [0.1 0.2 0.5 1 2.0])
xlim([min(sigma_w_) max(sigma_w_)])
box off
```



```
% set(gcf, 'PaperPosition', [1 1 14 10])
% print -depsc figures/SNR_average

figure(26)
clf
% semilogx(sigma_set, MSE_1,'g.-', sigma_set, MSE_3,'r.-', sigma_set, MSE_4,'b.-', sigma_w_, MSE_mad,'k.-');
semilogx(sigma_set, MSE_1,'g.-', sigma_set, MSE_3,'r.-', sigma_set, MSE_4,'b.-', sigma_w_, MSE_firm,'m.-', sigma_w_, MSE_s
hold off;
% legend('Proposed CNN', '5-layer CNN', '8x8-kernel CNN', 'MAD-soft denoising', 'Location','NorthWest');
legend('Proposed CNN', '5-layer CNN', '8x8-kernel CNN', 'MAD-firm denoising', 'MAD-soft denoising', 'Location','NorthWest'
xlabel('Nsigma_w')
ylabel('RMSE')
set(gca, 'xtick', [0.1 0.2 0.5 1 2.0])
xlim([min(sigma_w_) max(sigma_w_)])
box off
```

```
1.2
Proposed CNN
S-slayer CNN
MAD-find denoising
MAD-sort denoising

0.8

0.4

0.2

0.1

0.2

0.5

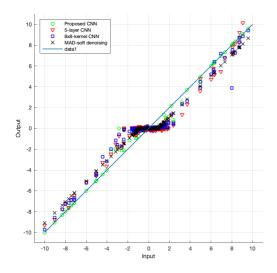
1

2
```

```
% set(gcf, 'PaperPosition', [1 1 14 10])
% print -depsc figures/MSE_average
set_plot_defaults('off')
```

```
%% Create the comparison form for different methods.
num = 1000;
SNR_num1 = zeros(1,num);
MSE_num1 = zeros(1,num);
SNR_num3 = zeros(1,num);
MSE_num3 = zeros(1,num);
SNR num4 = zeros(1,num);
MSE_num4 = zeros(1,num);
MSE_noise = zeros(1,num);
SNR_noise = zeros(1,num);
SNR_mad = zeros(1, num);
MSE_mad = zeros(1,num);
for j = 1:1:num
                                    % change from 0.25 to 1.75
   sigma = 1.75;
   K = ceil(50*rand()+25);
    groundtruth = zeros(1, N);
    index_random = randperm(N);
   index = index_random(1:K);
    groundtruth(index) = 10*2*(rand(1,K) - 0.5);
          groundtruth(index) = 10*randn(1,K);
    ini_noise = sigma*randn(1,N);
   input = groundtruth + ini_noise;
   MSE_noise(j) = mean(ini_noise.^2);
   SNR_noise(j) = 10*log10(mean(groundtruth.^2)/MSE_noise(j));
   output = CNN(input, h1);
   noise = output - groundtruth;
   MSE_num1(j) = mean(noise.^2);
   SNR_num1(j) = 10*log10(mean(groundtruth.^2)/MSE_num1(j));
   output = CNN(input, h3);
   noise = output - groundtruth;
   MSE_num3(j) = mean(noise.^2);
   SNR_num3(j) = 10*log10(mean(groundtruth.^2)/MSE_num3(j));
   output = CNN(input, h4);
   noise = output - groundtruth;
   MSE_num4(j) = mean(noise.^2);
   SNR_num4(j) = 10*log10(mean(groundtruth.^2)/MSE_num4(j));
   output = soft_MAD(input);
   noise = output - groundtruth;
   MSE_mad(j) = mean(noise.^2);
   SNR_mad(j) = 10*log10(mean(groundtruth.^2)/MSE_mad(j));
end
```

```
SNR_1 = mean(SNR_num1)
SNR_1 = 5.8395
MSE_1 = mean(MSE_num1)
MSE_1 = 0.8611
SNR_3 = mean(SNR_num3)
SNR_3 = 6.0348
MSE_3 = mean(MSE_num3)
MSE_3 = 0.8409
SNR_4 = mean(SNR_num4)
SNR_4 = 6.2260
MSE_4 = mean(MSE_num4)
MSE 4 = 0.8054
noiseSNR = mean(SNR_noise)
noiseSNR = 0.2369
noiseMSE = mean(MSE_noise)
noiseMSE = 3.0612
madSNR = mean(SNR_mad)
madSNR = 6.0027
madMSE = mean(MSE_mad)
madMSE = 0.8346
%% Plot output v.s. input for all the methods.
set_plot_defaults('on')
N = 500;
K = 50;
sigma = 0.75;
groundtruth = zeros(1, N);
index_random = randperm(N);
index = index_random(1:K);
groundtruth(index) = 10*2*(rand(1,K) - 0.5);
         groundtruth(index) = 10*randn(1,K);
ini_noise = sigma*randn(1,N);
input = groundtruth + ini_noise;
output1 = CNN(input,h1);
output3 = CNN(input,h3);
output4 = CNN(input,h4);
output_mad = soft_MAD(input);
figure(27)
plot(input, output1, 'go', input, output3, 'rv', input, output4, 'bs', input, output_mad, 'kx', 'MarkerSize',5)
hold on
legend('Proposed CNN', '5-layer CNN', '8x8-kernel CNN', 'MAD-soft denoising', 'Location', 'NorthWest');
xlabel('Input')
ylabel('Output')
grid
axis equal square
line([-10 10], [-10 10])
hold off
xlim([-11,11])
ylim([-11,11])
box off
```



```
% set(gcf, 'PaperPosition', [1 1 14 14])
% print -depsc figures/compare
set_plot_defaults('off')
```

```
%% Adaptive version
threshold1 = 2.61;
threshold2 = 5.26:
rho = 1;
                        % rho is the ratio between output and input signal.
l = 37;
                  % l is the length of the filters in the second layer.
training_sigma = 2;
                        % The standard deviation of the Gaussian noise in the training data is between 0 and training_sigm
training_num = 20000;
                       % training_num is the number of the training signals.
training_type = 1;
                        \% 1 means Uniform and 2 means Gaussian.
                       \$ istrain_flag can determine if training a new CNN or directly using the trained parameters.
istrain_flag = false;
h = create_denoiser(l,rho,threshold1,threshold2,training_type,istrain_flag);
N = 500;
K = 50;
num = 50;
ratio = K/N;
                                      % sparsity level
sigma_x = 10.0;
                                    % Gaussian standard deviation
1 = 37:
[sigma_w_, SNR_x_soft, SNR_x_firm, SNR_y, MSE_firm, MSE_soft] = sparse_denoise_MAD_calculate_SNR(N, ratio, sigma_x);
progress = 0.050000
progress = 0.100000
progress = 0.150000
progress = 0.200000
progress = 0.250000
progress = 0.300000
progress = 0.350000
progress = 0.400000
progress = 0.450000
progress = 0.500000
progress = 0.550000
progress = 0.600000
progress = 0.650000
progress = 0.700000
progress = 0.750000
progress = 0.800000
```

```
mse_soft = sqrt(Mse_soft);
mse_firm = sqrt(Mse_firm);

ratio = 1;
% t1 = 2.61;
% t2 = 5.26;
mse_cnn = zeros(1,length(sigma_w_));
snr_cnn = zeros(1,length(sigma_w_));
snr_cnn = zeros(1,length(sigma_w_));
snr_ori = zeros(1,length(sigma_w_));

for i = 1:1:length(sigma_w_)
    sigma = sigma_w_(i);
    Mse_cnn_epo = zeros(1,num);
    Snr_cnn_epo = zeros(1,num);
    Snr_cnn_epo = zeros(1,num);
    Snr_ori = po = zeros(1,num);
```

```
for j = 1:1:num
        groundtruth = zeros(1, N);
        index_random = randperm(N);
        index = index_random(1:K);
        groundtruth(index) = 10*2*(rand(1,K) - 0.5);
        input = groundtruth + sigma*randn(1,N);
        t1 = 2*1.4826*median(abs(input));
        t2 = 4.4*1.4826*median(abs(input));
        h1 = adaptive_denoiser(input,l,ratio,t1,t2);
        output = CNN(input,h1);
        MSE_CNN_epo(j) = mean((output-groundtruth).^2);
        SNR_CNN_epo(j) = 10*log10(mean(groundtruth.^2)/MSE_CNN_epo(j));
        output = CNN(input,h);
          MSE_CNN_epo(j) = mean((output-groundtruth).^2);
        SNR\_ori\_epo(j) = 10*log10(mean(groundtruth.^2)/mean((output-groundtruth).^2));
    MSE_CNN(i) = sqrt(mean(MSE_CNN_epo));
    SNR_CNN(i) = mean(SNR_CNN_epo);
    SNR_ori(i) = mean(SNR_ori_epo);
end
figure(28)
semilogx(sigma_w_, SNR_ori, 'r.-', sigma_w_, SNR_CNN, 'b.-', sigma_w_, SNR_x_firm, 'm.-', sigma_w_, SNR_x_soft, 'k.-', sigm
legend('Proposed CNN', 'Proposed CNN (adaptive)', 'MAD-firm denoising', 'MAD-soft denoising', 'Noisy signal');
xlabel('\sigma_w')
ylabel('SNR in dB')
set(gca, 'xtick', [0.1 0.2 0.5 1 2.0])
xlim([min(sigma_w_) max(sigma_w_)])
```

