RP HW

Problem1 - Obtain and plot the values of $R_{ss}[m], \forall 0 \leq m \leq 20$, in Figure 1.

By Yule-Walker equations , We can get

$$R_{ss}[0] + a_1 R_{ss}[1] a_2 R_{ss}[2] + a_3 R_{ss}[3] + \dots + a_{20} R_{ss}[20] = b_0^2$$

$$R_{ss}[1] + a_1 R_{ss}[0] a_2 R_{ss}[1] + a_3 R_{ss}[2] + \dots + a_{19} R_{ss}[20] = 0$$

$$\vdots$$

$$R_{ss}[20] + a_1 R_{ss}[19] a_2 R_{ss}[18] + a_3 R_{ss}[17] + \dots + a_{20} R_{ss}[0] = 0$$

Calculate and plot the values of $R_{ss}[m]$ for $0 \le m \le 20$ by substituting the values of a_1, a_2, \ldots, a_{20} , and b_0 into the equation.

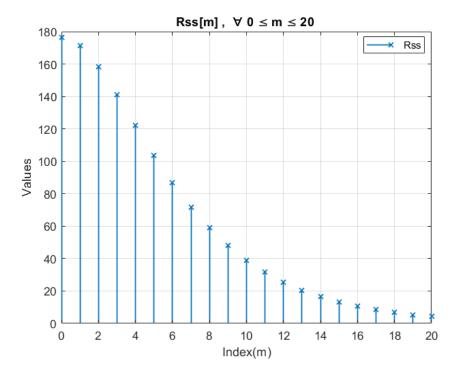


Figure 1: Rss

```
1 noiseLength = 1000000; % length s[n],n=[1:1000000]
2 s=zeros([1 noiseLength+3]); % s inital value
3 a=[1,-1.9,1.18,-0.24]; % mean a0,a1,a2,a3
4 b0=2;
5 % set white Gaussian noise value
7
   meanValue = 0;
                       % mean value
8
   whiteNoise = meanValue + randn(1, noiseLength);
9
   varianceValue = var(whiteNoise);
10 disp('White Noise Variance :');
11 disp(varianceValue);
12
13
   % find s[n] value
14
   % Note matlab idx from 1 not 0
15
   for i=4:noiseLength+3
16
        s(i)=b0*whiteNoise(i-3)-a(2)*s(i-1)-a(3)*s(i-2)-a(4)*s(i-3);
17
18
   s=s(4:end); % remove init point
19
20 M = 20;
21
   \% slove 4-order equation at first
22
   \% Ax=b find x , where x is Rss[0]~Rss[3]
23
   A = [a(1), a(2), a(3), a(4);
24
      a(2),a(1)+a(3),a(4),0;
25
      a(3), a(2)+a(4), a(1), 0;
26
      a(4),a(3),a(2),a(1)];
27 b=[b0^2;0;0;0];
28 Rss=transpose(A\b);
29 disp('Rss[0] ~ Rss[3]:');
30 disp(Rss);
31 Rss=[Rss,zeros([1,17])];
32 % slove Rss[4]~Rss[20]
33 \quad for \quad i=5:M+1
34
       % Rss[4(i)]=-a1*Rss[3(i-1)]-a2*Rss[2(i-2)]-a3*Rss[1(i-3)]
35
        Rss(i)=-a(2)*Rss(i-1)-a(3)*Rss(i-2)-a(4)*Rss(i-3);
   end
```

Listing 1: Problem1 Matlab Code

Problem2 - plot $\{\hat{s}_{20}[n], \forall 10000 \leq n \leq 10100\}$ and $\{s[n], \forall 10000 \leq n \leq 10100\}$, in Figure 2 According to the definition of $\hat{s}_M[n] = \hat{E}\{s[n] \mid s[n-k], 1 \leq k \leq M\}$ and substituting M=20, $\forall 10000 \leq n \leq 10100$ into the definition , we can get

$$\hat{s}_{20}[n] = \hat{E}\{s[n] \mid s[n-k], 1 \le k \le 20\}$$

Based on theorem 13-1 , we know that $E[(s[n] - \sum_{k=1}^N h[k]s[n-k])s[n-m]] = 0, \forall 1 \leq m \leq 20$. According to the result obtained from the previous equation , We can determine the value of $h[k], where \forall 1 \leq k \leq 20$, by solving the following system of simultaneous equations :

$$R_{ss}[1] - \sum_{k=1}^{N} h[k]R_{ss}[1-k] = 0$$

$$R_{ss}[2] - \sum_{k=1}^{N} h[k]R_{ss}[2-k] = 0$$

$$\vdots$$

$$R_{ss}[20] - \sum_{k=1}^{N} h[k]R_{ss}[20-k] = 0$$

Finally , we can calculate the $\hat{s}_{20}[n] = \sum_{k=1}^N h[k] s[n-k], \forall 10000 \leq n \leq 10100$

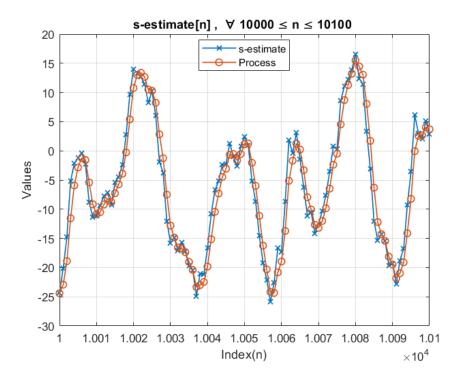


Figure 2: $\hat{s}_{20}[n], \forall 10000 \leq n \leq 10100$

```
1 b=transpose(Rss(2:21));
2 A=[];
3
   for i=1:M
       tmp=flip(Rss(1:i));
5
       if M-i>0
           tmp=[tmp,Rss(2:M-i+1)];
7
8
       A = [A; tmp];
9
   end
10
11
   if transpose(A) == A
12
       disp('Problem2 - A matrix is same');
13
14 h=transpose(A\b);
15
16
   s_estimate = [];
17
   for i=n
18
        tmp=h.*flip(s(i-M+1:i));
19
        s_estimate=[s_estimate,sum(tmp)];
20
   end
```

Listing 2: Problem2 Matlab Code

Problem3 - $\hat{P}_{20}[n]$, $\forall n \in \{10, 10^2, 10^3, 10^4, 10^5, 10^6\}$ in Figure 3 Based on definition $\hat{P}_M[n] = \frac{1}{n} \sum_{k=1}^n (\hat{s}_M[k] - s[k])^2$, we can directly calculate the error between predicted values and actual values.

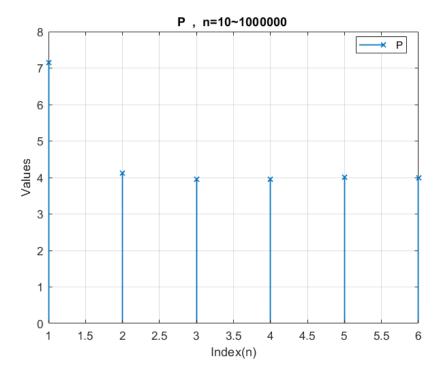


Figure 3: $\hat{P}_{20}[n], \forall n \in \{10, 10^2, 10^3, 10^4, 10^5, 10^6\}$

```
%% Count all s_estimate
 1
   s_estimate=zeros([1 noiseLength]); % clean all
 3
   for n=1:M
 4
        tmp=0;
 5
        for k=1:M
 6
            if n-k>0
 7
                 tmp=tmp+h(k)*s(n-k);
 8
 9
        end
10
        s_estimate(n)=tmp;
11
   end
12
13
   for n=M+1:noiseLength
14
        s_{estimate(n)=sum(h.*flip(s(n-M:n-1)));
15
   %%
       Problem - 3 n=10-1
16
17
   p_10=0;
18
   n_10=10;
19
   for i=1:n_10
20
        tmp=(s_estimate(i)-s(i))^2;
21
        p_10=p_10+tmp;
22
   end
23
   p_10=p_10/10;
24 d
25 %% Problem - 3 n = 100 - 2
26 p_100=0;
27
  n_100=100;
28
   for i=n_10+1:n_100
29
        tmp=(s_estimate(i)-s(i))^2;
30
        p_100 = p_100 + tmp;
31
   end
32
   p_100 = ((p_10*n_10) + p_100)/n_100;
33
34 \% \text{ Problem} -3 n = 1000 - 3
35 p_1000=0;
36
   n_1000=1000;
37
   for i=n_100+1:n_1000
38
        tmp=(s_estimate(i)-s(i))^2;
39
        p_1000 = p_1000 + tmp;
40
   p_1000 = ((p_100*n_100) + p_1000)/n_1000;
41
42
43
   %% Problem-3 n=10000-4
   p_10000=0;
44
45
   n_10000=10000;
46
   for i=n_1000+1:n_10000
47
        tmp=(s_estimate(i)-s(i))^2;
48
        p_10000 = p_10000 + tmp;
49
50
  p_10000 = ((p_1000*n_1000) + p_10000)/n_10000;
51 %% Problem-3 n=100000-5
52 p_100000=0;
53 n_100000 = 100000;
   for i=n_10000+1:n_100000
54
55
        tmp=(s_estimate(i)-s(i))^2;
56
        p_100000 = p_100000 + tmp;
57
   end
   p_100000 = ((p_10000*n_10000) + p_100000)/n_100000;
58
59
   %% Problem-3 n=1000000-6
60
   p_1000000=0;
61
   n_1000000=1000000;
   for i=n_100000+1:n_1000000
62
63
        tmp = (s_estimate(i) - s(i))^2;
64
        p_1000000 = p_1000000 + tmp;
65
   end
   p_1000000 = ((p_100000*n_100000) + p_1000000)/n_10000000;
66
```

Listing 3: Problem3 Matlab Code

Problem4 - Consider the case in which $\{i[n], -\infty < n < \infty\}$ is a white noise process but i[n] has the following probability density function for each $n \in \mathbb{Z}$.

$$f_{i[n]}(t) = \begin{cases} 0.5e^{-t}, \forall t > 0\\ 0.5e^{t}, \forall t < 0 \end{cases}$$

Plot $\hat{P}_{20}[n], \forall n \in \{10, 10^2, 10^3, 10^4, 10^5, 10^6\}$, in Figure 4 Based on definition $\hat{P}_M[n] = \frac{1}{n} \sum_{k=1}^n (\hat{s}_M[k] - s[k])^2$, we can directly calculate the error between predicted values and actual values.

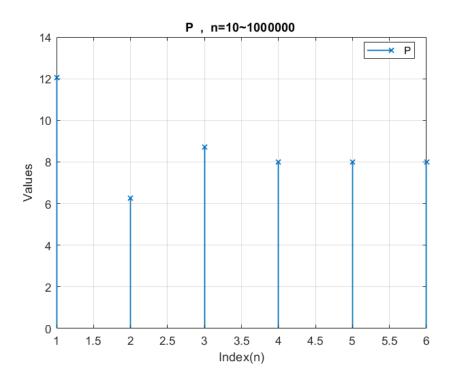


Figure 4: $\hat{P}_{20}[n], \forall n \in \{10, 10^2, 10^3, 10^4, 10^5, 10^6\}$

```
\%\% create Laplace distribution noise
   noiseLength=1000000;
   s=zeros([1 noiseLength+3]); % s inital value
4
   a=[1,-1.9,1.18,-0.24]; % mean a0,a1,a2,a3
5
   b0=2;
6
7
   m=1;
8
   mu = 0;
9
   sigma = sqrt(2);
10
   u = rand(m, noiseLength)-0.5;
11
   b = sigma / sqrt(2);
   laplaceRandomNoise = mu - b * sign(u).* log(1- 2* abs(u));
12
13
14
   for i=4:noiseLength+3
       s(i)=b0*laplaceRandomNoise(i-3)-a(2)*s(i-1)-a(3)*s(i-2)-a(4)*s(i-3);
15
16
17
   s=s(4:end); % remove init point
18
```

Listing 4: Problem4 - Create Laplace distribution noise

```
%% Count Rss
2 M = 20;
   % Ax=b find x , x is Rss[0]~Rss[3]
   A = [a(1), a(2), a(3), a(4);
      a(2),a(1)+a(3),a(4),0;
6
      a(3),a(2)+a(4),a(1),0;
7
      a(4),a(3),a(2),a(1)];
8
   b=[b0^2;0;0;0];
9
   Rss=transpose(A\b);
   disp('Rss[0] ~ Rss[3]:');
10
11
   disp(Rss);
12
   Rss=[Rss,zeros([1,17])];
13
   % slove Rss[4]~Rss[20]
   for i=5:M+1
14
15
        % Rss[4(i)]=-a1*Rss[3(i-1)]-a2*Rss[2(i-2)]-a3*Rss[1(i-3)]
16
        Rss(i)=-a(2)*Rss(i-1)-a(3)*Rss(i-2)-a(4)*Rss(i-3);
17
```

Listing 5: Problem4 - Count Rss

```
%% Count all s_estimate
   s_estimate=zeros([1 noiseLength]); % clean all
 3
   for n=1:M
 4
        tmp=0;
        for k=1:M
 5
 6
            if n-k>0
 7
                 tmp=tmp+h(k)*s(n-k);
 8
            end
9
        end
10
        s_estimate(n) = tmp;
11
   end
12
13
   for n=M+1:noiseLength
        s_{estimate(n)=sum(h.*flip(s(n-M:n-1)));
14
15
   end
```

Listing 6: Problem
4 - Count all \hat{s}

```
%% Problem -4 n=10-1
1
   p_10=0;
2
   n_10=10;
3
   for i=1:n_10
5
        tmp=(s_estimate(i)-s(i))^2;
6
        p_10=p_10+tmp;
7
8
   p_10=p_10/10;
9 disp('p_10 :');
10 disp(p_10);
11 \ \%\% \ Problem-4 \ n=100-2
12 p_100=0;
13 \quad n_100=100;
14
   for i=n_10+1:n_100
15
        tmp=(s_estimate(i)-s(i))^2;
16
        p_100 = p_100 + tmp;
17
18
   p_100 = ((p_10*n_10) + p_100)/n_100;
19
   disp('p_100 :');
20 disp(p_100);
21 %% Problem-4 n=1000-3
22 p_1000=0;
23 n_1000=1000;
24
   for i=n_100+1:n_1000
25
        tmp=(s_estimate(i)-s(i))^2;
26
        p_1000 = p_1000 + tmp;
27 end
28 p_1000 = ((p_100*n_100) + p_1000)/n_1000;
29 disp('p_1000 :');
30 disp(p_1000);
31 %% Problem-4
                  n = 10000 - 4
32 p_10000=0;
33 n_10000=10000;
34 for i=n_1000+1:n_10000
35
        tmp=(s_estimate(i)-s(i))^2;
36
        p_10000 = p_10000 + tmp;
37
   end
38
   p_10000 = ((p_1000*n_1000) + p_10000)/n_10000;
39
   disp('p_10000 :');
40
   disp(p_10000);
41
   %% Problem-4 n=100000-5
42
   p_100000=0;
43
   n_100000 = 100000;
   for i=n_10000+1:n_100000
44
45
        tmp=(s_estimate(i)-s(i))^2;
46
        p_100000 = p_100000 + tmp;
47
   end
48 p_100000 = ((p_10000*n_10000) + p_100000)/n_100000;
49 disp('p_100000 :');
50 disp(p_100000);
51 %% Problem-4 n=1000000-6
52 p_1000000=0;
53 n_1000000=1000000;
54
   for i=n_100000+1:n_1000000
        tmp=(s_estimate(i)-s(i))^2;
55
56
        p_1000000 = p_1000000 + tmp;
57
   end
   p_1000000 = ((p_100000*n_100000) + p_1000000)/n_10000000;
58
59
   disp('p_1000000 :');
60
   disp(p_1000000);
```

Listing 7: Problem4 - Count all P