Chapter_4_2D_Steemson_triangle

May 27, 2019

1 Steemson Triangle Test

Set-up Steemson triangle example by forming the IFS for a Steemson triangle with side lengths 1,1.1,0.85. The actual functions used are in Python files, we simply import them here.

```
In [2]: #start Steemson attempt
       a = 1.1
       b = 0.85
       imgxy = 500
       #co ordinates of triangles third vertex
       Cy = (0.5*np.sqrt(-1 + 2*a**2 - a**4 + 2*b**2 + 2*a**2*b**2 - b**4))
       Cx = (0.5*(1 - a**2 + b**2))
       #angles for roatation
       cosA = (Cx/b)
       sinA = (Cy/b)
       cosB = ((1.0-Cx)/a)
       sinB = (Cy/a)
       #scaling factors
       alphaNFF = (b)/((a**2 + b**2))
       betaNFF = (a)/(a**2 + b**2)
       gammaNFF = -1.0*(1.0-a**2-b**2)/(a**2 + b**2)
```

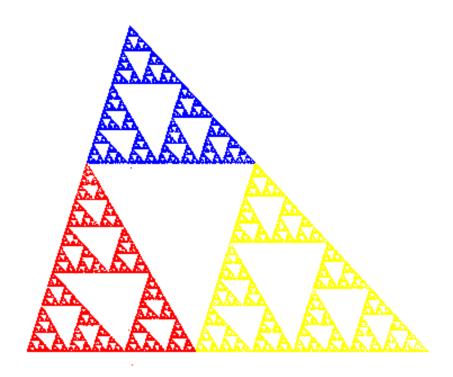
```
alphaNNF = (b/(1.0 + b**2))
        betaNNF
                 = (1.0/(1.0 + b**2))
        gammaNNF = (b**2/(1.0 + b**2))
        alphaNFF = alphaNNF
        betaNFF
                 = betaNNF
        gammaNFF =
                     gammaNNF
       NNF =
                  [[cosA*alphaNNF,sinA*alphaNNF,-cosA*alphaNNF,0.0,0.0],
                   [betaNNF, 0.0, 0.0, betaNNF, (1.0-betaNNF), 0],
                   [gammaNNF,0.0,0.0,gammaNNF,(1.0-gammaNNF)*Cx,(1.0-gammaNNF)*Cy]]
        #qet the dimension
       f_dim_steem =
                        lambda D : np.abs(alphaNNF)**D + np.abs(betaNNF)**D + np.abs(gammaN
                        optimize.root(f_dim_steem, 1.8,method='lm').x
       D_Steem
  Make a picture of our triangle to make sure we got it right
In [3]: IFS_STEEM = se.convertIFS(NNF)
        Steem_mom = se.mom_wrap_Steem(IFS_STEEM,D_Steem,n=21,it = 30)
        img, _{-} = se.chaos(IFS_STEEM,[1/3,1/3,1/3], it = 100000, imgxy=500)
```

Probabilities:

img

[0.33232556 0.36557059 0.30210385]

Out[3]:



Make a function for our operator Φ , and wrap it so we can form pictures for our minimisation

```
In [4]: def Phi_wrap(x,D,it = 1,n=6, sim = False ):
    assert len(x)%6==0

N = len(x)

a_1 = x[:N//6]

b_1 = x[1*(N//6):2*(N//6)]

c_1 = x[2*(N//6):3*(N//6)]

d_1 = x[3*(N//6):4*(N//6)]
```

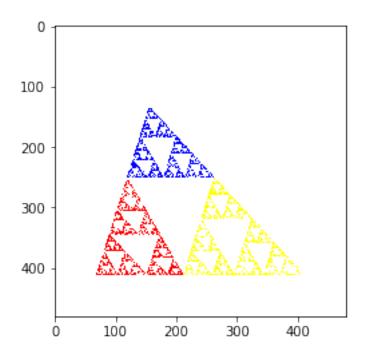
```
e_1 = x[4*(N//6):5*(N//6)]
f_1 = x[5*(N//6):]
if sim:
    ad_1 = (np.abs(a_1)+np.abs(d_1))/2
    a_1 = np.sign(a_1)*ad_1
    d_1 = np.sign(d_1)*ad_1
    bc_1 = (np.abs(b_1)+np.abs(c_1))/2
    b_1 = np.sign(b_1)*bc_1
    c_1 = np.sign(c_1)*bc_1
prob = np.power(np.sqrt(np.abs(a_1*d_1 - b_1*c_1)),D-1)
global p_l
p_l = prob/(np.sum(prob))
global k
if k % 20 == 0:
    print('Current maps:')
    img, _ = se.chaos(x,p_1,it = 20000)
    plt.imshow(img)
    plt.show()
k = k + 1
return mf.Phi(a_1,b_1,c_1,d_1,e_1,f_1,p_1,it = it,n=n)
```

Make a function to minimise and see that our IFS for the Steemson triangle makes the cost small.

Should the reader desire, the 'similitude' line can be changed to True. If this is done, at each step in the minimisation, the affine map is projected to its closest similitude function in the induced L^2 norm.

```
In [24]: k = 0
\# can \ select \ to \ project \ to \ similitude \ transformation
```

```
similitude = False
         def cost_Steem(x):
             return Phi_wrap(x,D_Steem,it = 1,n=len(Steem_mom),sim = similitude)@Steem_mom - S
         print(IFS_STEEM)
         cost_Steem(IFS_STEEM)
[ 0.14876633  0.58055152
                         0.41944848 0.47051039
  0.47051039
                                     -0.14876633
                                                  0.58055152
                                                               0.41944848
  0.
              0.41944848
                         0.14876633 0.
                                                  0.
                                                               0.47051039]
Current image:
```



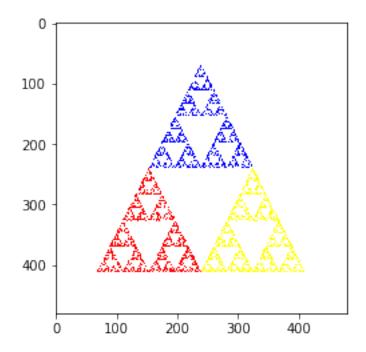
This starting point corresponds to a Sierpinski triangle with orientations with no flips. The Steemson triangle is also known as a FNN triangle, as it contains two maps which do not use conjugation and one that does.

```
In [25]: x0 = np.array([1/2,1/2,1/2,0,0,0,0,0,1/2,1/2,1/2,0,1/2,1/4,0,0,1/2])
```

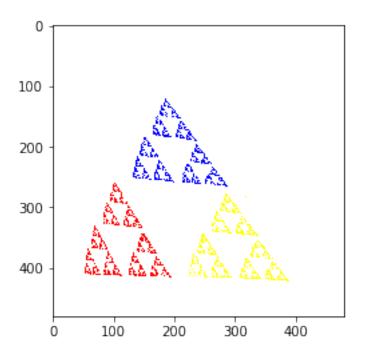
We can now make a minimisation, whereby we also have plotted the attractor for the IFS parameters during the minimisation

```
In [26]: k=0
    t = time.time()
    sol_Steem = least_squares( cost_Steem, x0 , bounds=(-1,1) , verbose = 2)
    t = time.time() - t
```

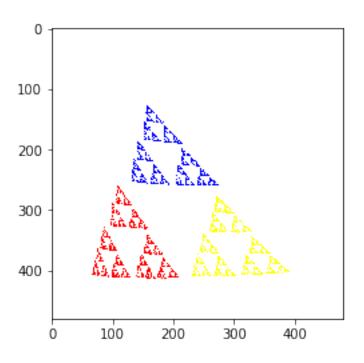
Current image:



Iteration Total nfev Cost Cost reduction Step norm Optimality 0 1 6.9809e-03 1.23e-01 Current image:



1 2 1.1720e-04 6.86e-03 1.30e-01 1.14e-02 Current image:



3

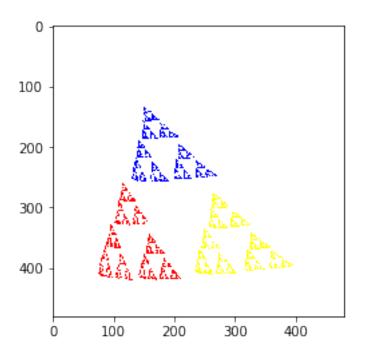
5.1008e-06

1.12e-04

6.71e-02

2.58e-03

Current image:



3 Current image:

4

4.6443e-07

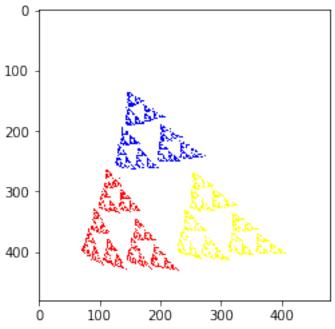
4.64e-06

6.48e-02

3.64e-04

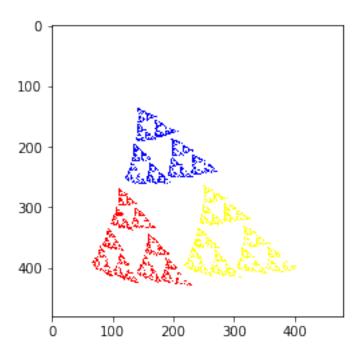
4 5 1.4429e-07 3.20e-07 8.48e-02 4.07e-04

Current image:

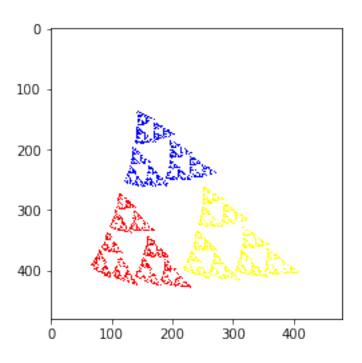


5 6 3.7744e-08 1.07e-07 2.68e-02 4.67e-05

Current image:



6 7 2.0842e-08 1.69e-08 6.07e-02 1.34e-04 Current image:



. .

5.3962e-09

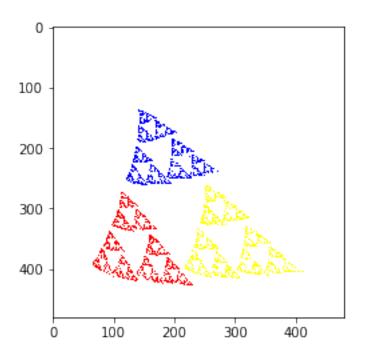
8

1.54e-08

1.96e-02

1.60e-05

Current image:



Current image:

10

3.2061e-09

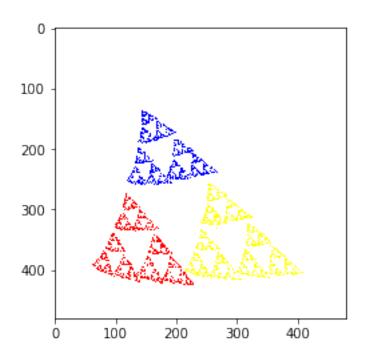
2.19e-09

1.54e-02

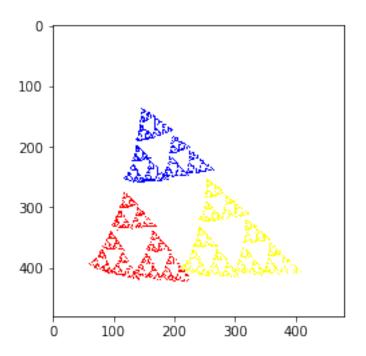
7.27e-06

9 11 1.6310e-09 1.58e-09 2.90e-02 3.13e-05

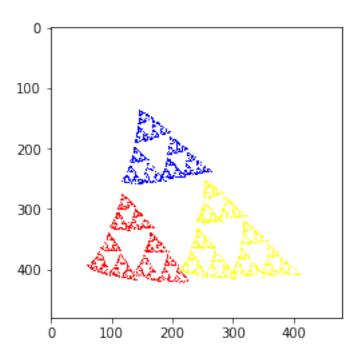
Current image:



10 12 7.2071e-10 9.10e-10 1.04e-02 8.76e-06 Current image:



11 13 5.4347e-10 1.77e-10 1.73e-02 2.20e-05 Current image:



14

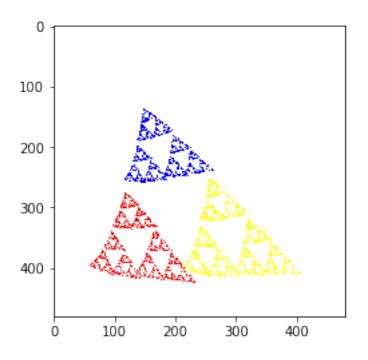
3.2289e-10

2.21e-10

7.01e-03

2.61e-06

Current image:



13 Current image:

16

2.5892e-10

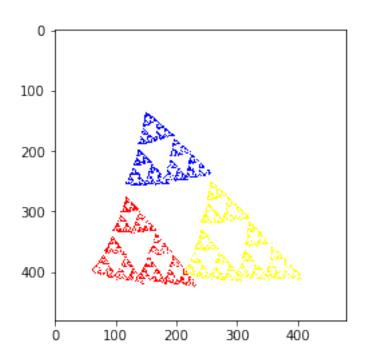
6.40e-11

7.25e-03

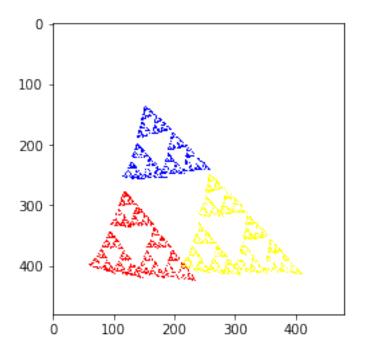
4.12e-06

14 17 2.0629e-10 5.26e-11 1.44e-02 1.06e-05

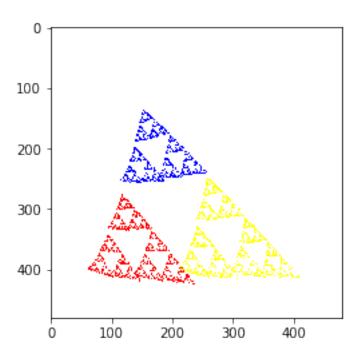
Current image:



15 18 1.2893e-10 7.74e-11 5.31e-03 1.23e-06 Current image:



16 19 1.2227e-10 6.65e-12 1.44e-02 8.26e-06 Current image:



20

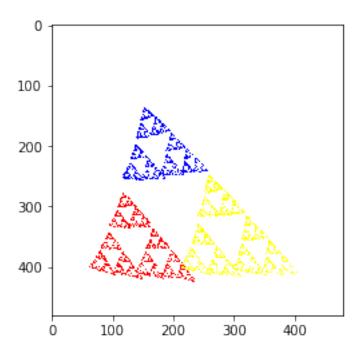
6.5509e-11

5.68e-11

2.89e-03

2.74e-07

Current image:



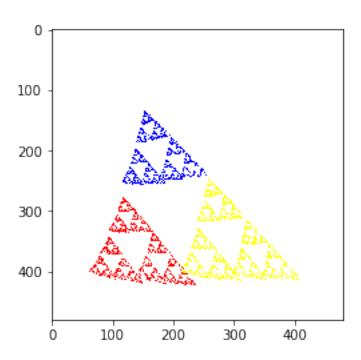
18 Current image: 21

5.7048e-11

8.46e-12

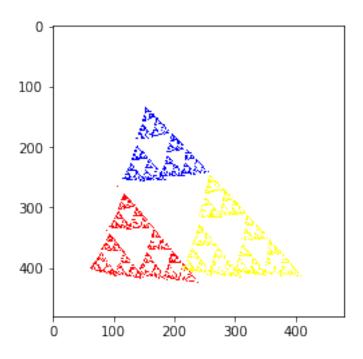
3.56e-03

8.61e-07



19 22 4.9511e-11 7.54e-12 7.05e-03 3.28e-06

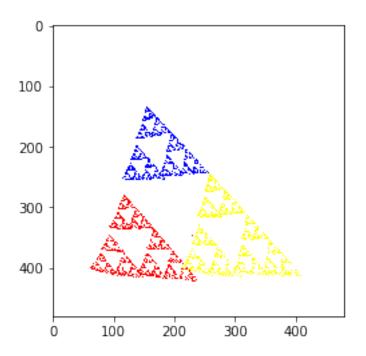
Current image:



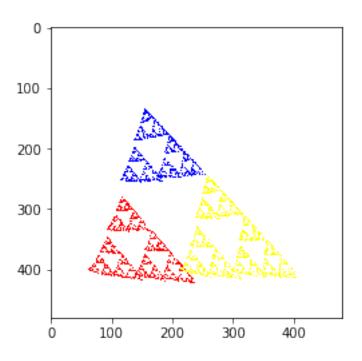
 20
 23
 3.8847e-11
 1.07e-11
 6.16e-03
 2.30e-06

 21
 24
 3.3347e-11
 5.50e-12
 7.20e-03
 2.81e-06

Current image:



22 25 2.5960e-11 7.39e-12 4.98e-03 1.39e-06 Current image:



26

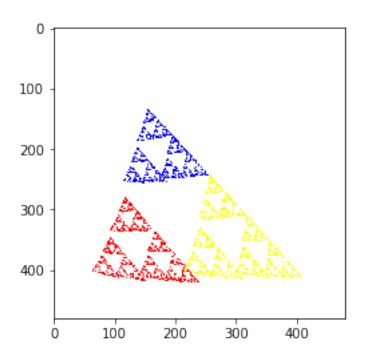
2.4713e-11

1.25e-12

7.28e-03

3.00e-06

Current image:



24 Current image:

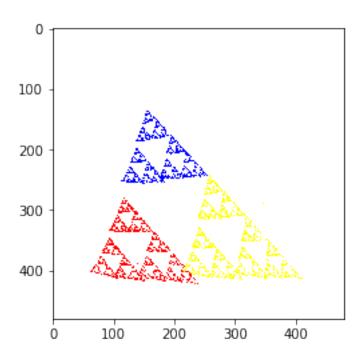
27

1.8665e-11

6.05e-12

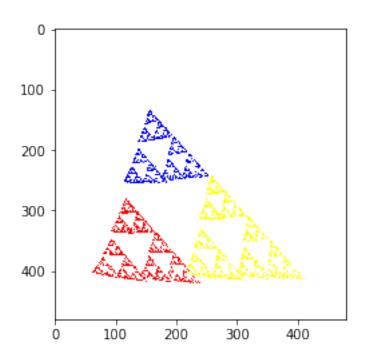
1.82e-03

2.01e-07



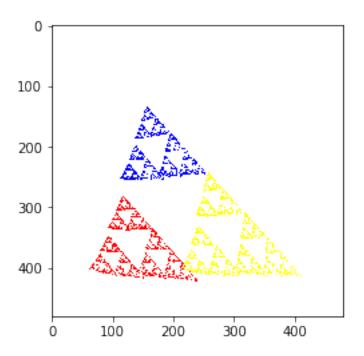
25 28 1.6652e-11 2.01e-12 3.56e-03 8.59e-07

Current image:

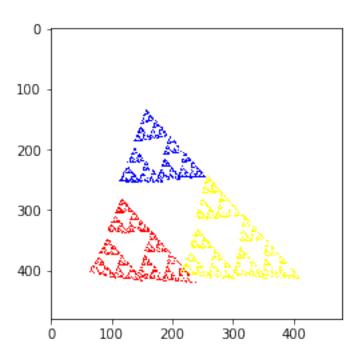


26 29 1.6363e-11 2.89e-13 6.24e-03 2.49e-06

Current image:



27 30 1.2435e-11 3.93e-12 1.57e-03 1.49e-07 Current image:



31

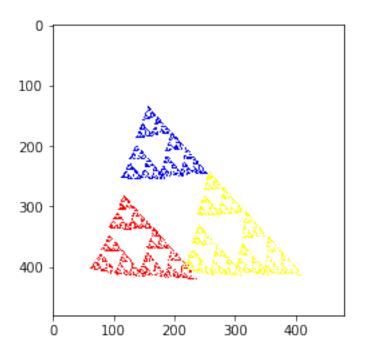
1.1303e-11

1.13e-12

3.19e-03

6.96e-07

Current image:



29 Current image:

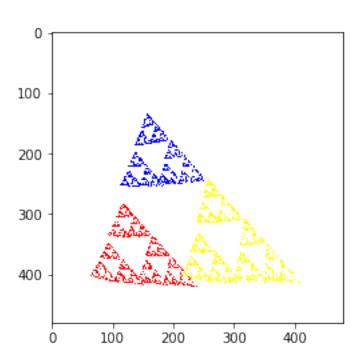
33

1.0516e-11

7.87e-13

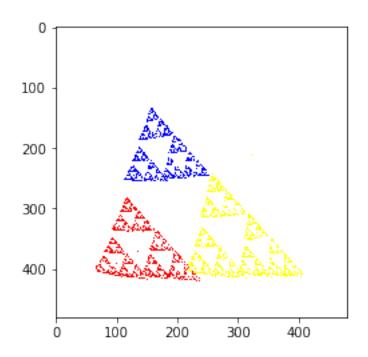
1.46e-03

1.49e-07

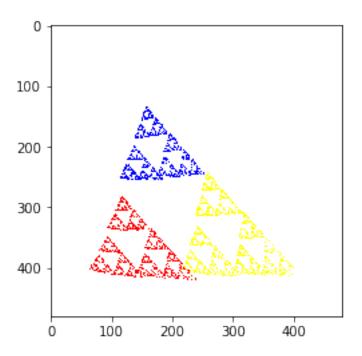


30 34 9.7373e-12 7.78e-13 2.92e-03 6.22e-07

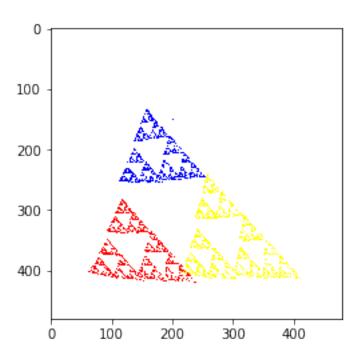
Current image:



31 36 9.1955e-12 5.42e-13 1.22e-03 1.10e-07 Current image:



32 37 8.6893e-12 5.06e-13 2.45e-03 4.62e-07 Current image:



39

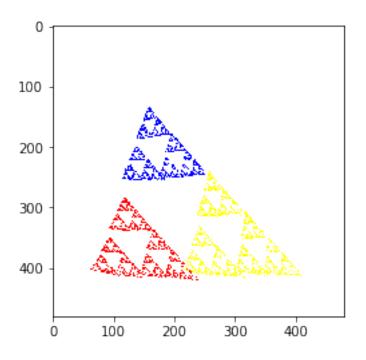
8.3451e-12

3.44e-13

1.15e-03

9.98e-08

Current image:



34 Current image:

40

8.0252e-12

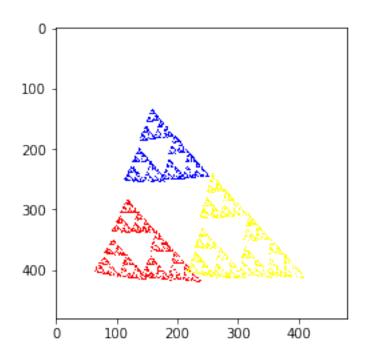
3.20e-13

2.29e-03

4.09e-07

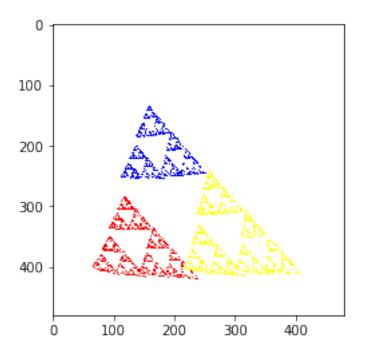
0 100 200 300 400 0 100 200 300 400 35 41 7.9312e-12 9.40e-14 3.65e-03 8.38e-07

Current image:

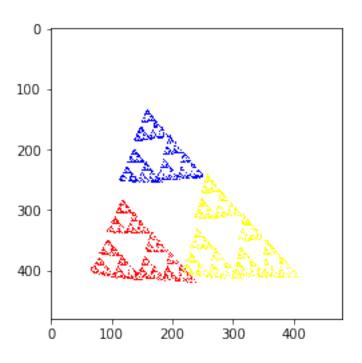


36 42 7.4824e-12 4.49e-13 9.45e-04 5.57e-08

Current image:



37 43 7.3953e-12 8.72e-14 1.87e-03 2.39e-07 Current image:



44

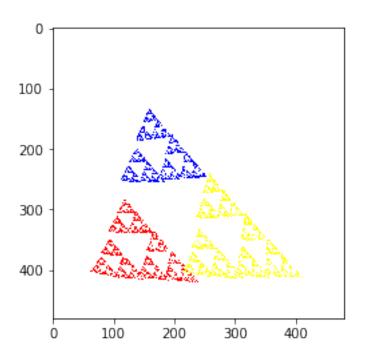
7.3224e-12

7.29e-14

1.83e-03

1.66e-07

Current image:



39 Current image:

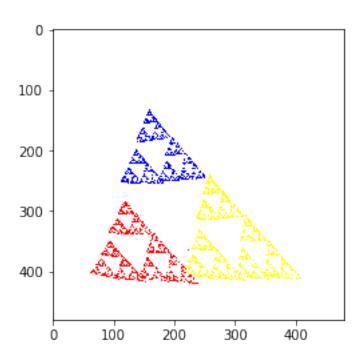
45

7.2857e-12

3.66e-14

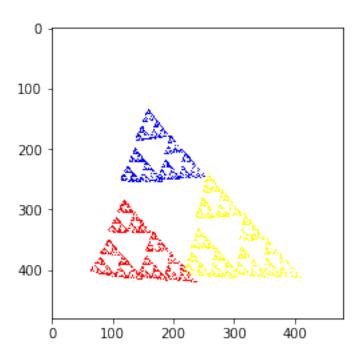
1.23e-03

5.20e-08



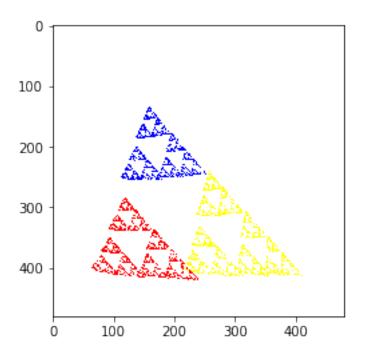
40 46 7.2715e-12 1.42e-14 1.57e-03 9.31e-08

Current image:

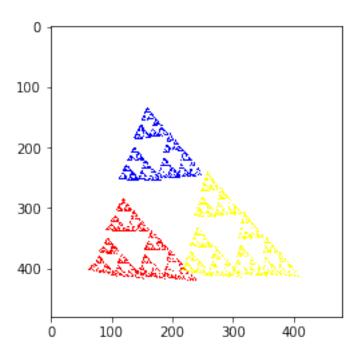


41 47 7.2621e-12 9.44e-15 6.28e-04 1.46e-08 Current image:

30

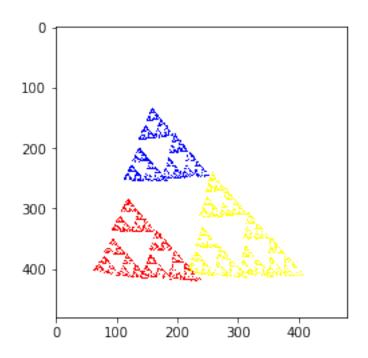


42 49 7.2583e-12 3.85e-15 5.26e-04 1.39e-08 Current image:



43 50 7.2532e-12 5.01e-15 1.04e-03 5.59e-08

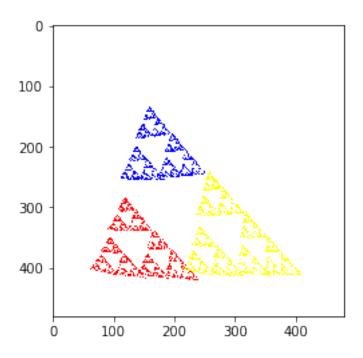
Current image:



 44
 51
 7.2496e-12
 3.62e-15
 5.67e-04
 1.50e-08

 45
 52
 7.2475e-12
 2.15e-15
 1.02e-03
 5.43e-08

Current image:



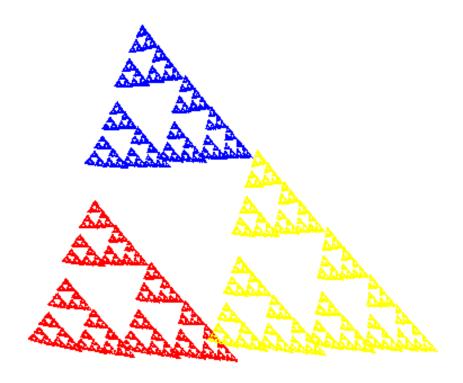
46 53 7.2459e-12 1.58e-15 2.48e-04 2.68e-09 $\$ gtol $\$ termination condition is satisfied.

Function evaluations 53, initial cost 6.9809e-03, final cost 7.2459e-12, first-order optimality

As we can see, the algorithm did not find the global minimum, but the approximation for our local minima is interesting.

In fact this is the evidence for the Collage theorem for moments.

In [28]: img,_ = se.chaos(sol_Steem.x,p_l, it = 100000, imgxy=500)
 img
Out[28]:



We now make a good starting point. This is still a Sierpinski triangle, but with the correct map oreientations to match a Steemson.

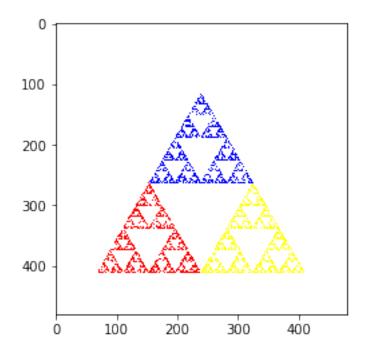
```
In [41]: #start Steemson Sierpinski attempt
    a = 1
    b = 1

imgxy = 500

#co ordinates of triangles third vertex
Cy = (0.5*np.sqrt(-1 + 2*a**2 - a**4 + 2*b**2 + 2*a**2*b**2 - b**4))
Cx = (0.5*(1 - a**2 + b**2))

#angles for roatation
```

```
cosA = (Cx/b)
        sinA = (Cy/b)
        cosB = ((1.0-Cx)/a)
        sinB = (Cy/a)
        #scaling factors
        alphaNFF = (b)/((a**2 + b**2))
                  = (a)/(a**2 + b**2)
        betaNFF
        gammaNFF = -1.0*(1.0-a**2-b**2)/(a**2 + b**2)
        alphaNNF = (b/(1.0 + b**2))
        betaNNF
                  = (1.0/(1.0 + b**2))
        gammaNNF = (b**2/(1.0 + b**2))
        alphaNFF = alphaNNF
                  = betaNNF
        betaNFF
        gammaNFF =
                     gammaNNF
        NNF =
                   [[cosA*alphaNNF,sinA*alphaNNF,sinA*alphaNNF,-cosA*alphaNNF,0.0,0.0],
                    [betaNNF, 0.0, 0.0, betaNNF, (1.0-betaNNF), 0],
                    [gammaNNF, 0.0, 0.0, gammaNNF, (1.0-gammaNNF)*Cx, (1.0-gammaNNF)*Cy]]
        x0 = se.convertIFS(NNF)
In [42]: k=0
        t = time.time()
        sol_Steem = least_squares( cost_Steem, x0 , bounds=(-1,1) , verbose = 2)
        t = time.time() - t
Current image:
```



Iteration 0 Current image:

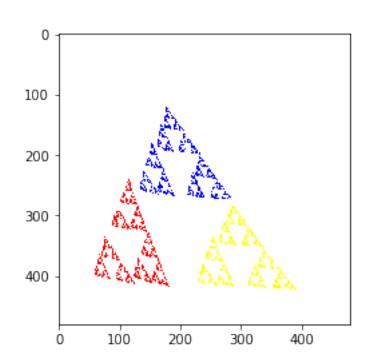
Total nfev 1

Cost 4.9542e-03

 ${\tt Cost\ reduction}$

Step norm

Optimality 1.27e-01



6.2325e-05

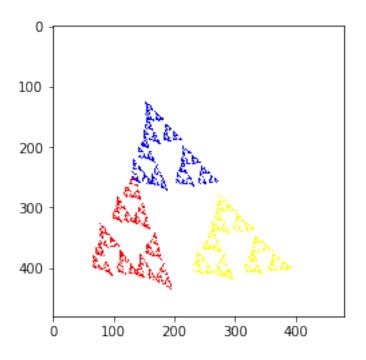
2

4.89e-03

1.50e-01

1.27e-02

Current image:



Current image:

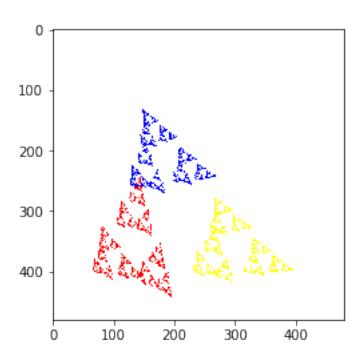
3

4.1105e-06

5.82e-05

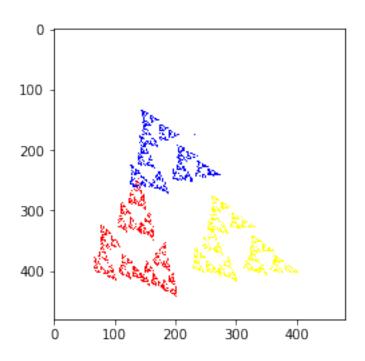
8.35e-02

2.96e-03



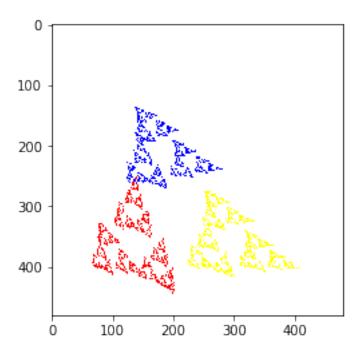
3 4 3.1392e-07 3.80e-06 6.24e-02 3.07e-04

Current image:

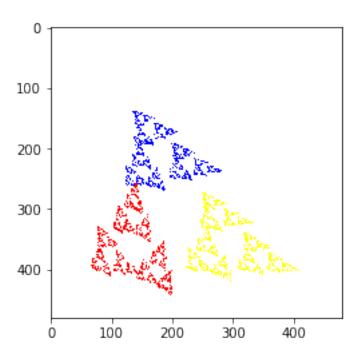


4 5 7.9241e-08 2.35e-07 5.93e-02 1.18e-04 Current image:

38



5 6 2.3343e-08 5.59e-08 4.60e-02 1.00e-04 Current image:



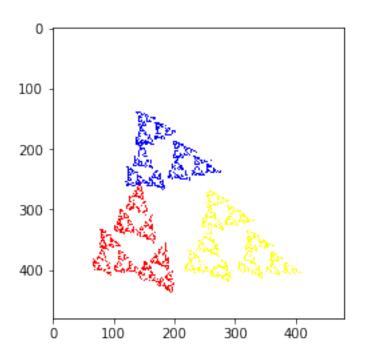
1.0815e-08

1.25e-08

2.70e-02

3.65e-05

Current image:



Current image:

8

7

9.6149e-09

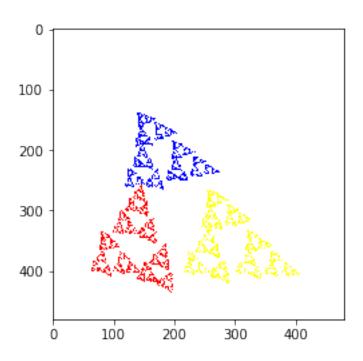
1.20e-09

5.51e-02

8.18e-05

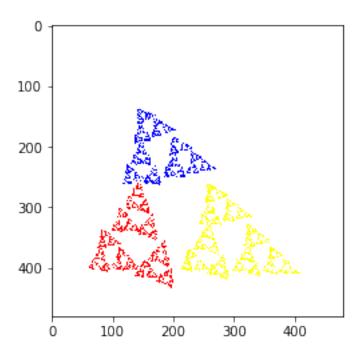
0 100 -200 -300 -400 -0 100 200 300 400 8 9 2.8220e-09 6.79e-09 9.30e-03 5.41e-06

Current image:

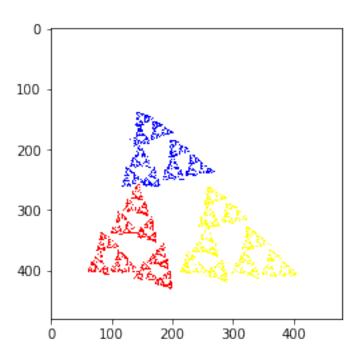


9 10 1.8366e-09 9.85e-10 1.57e-02 5.86e-06 Current image:

41



10 11 1.6099e-09 2.27e-10 2.86e-02 3.43e-05 Current image:



12

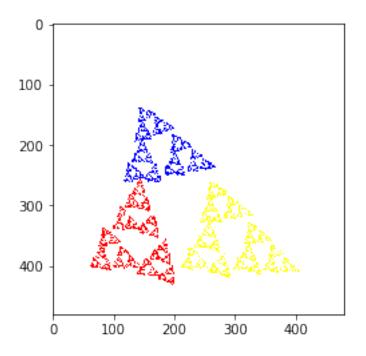
8.4952e-10

7.60e-10

4.66e-03

9.04e-07

Current image:



12 Current image:

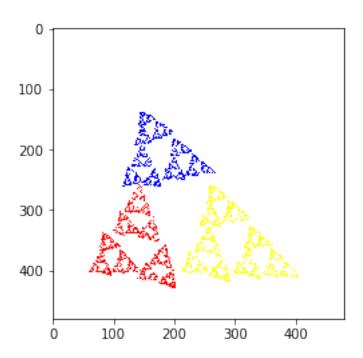
13

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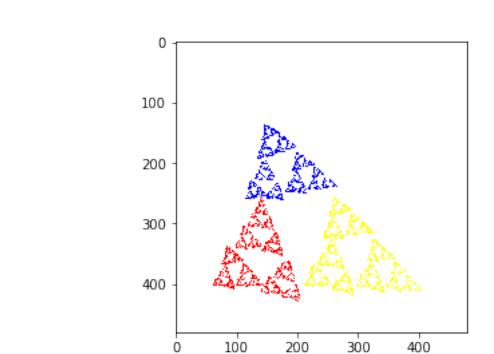
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7.43e-03

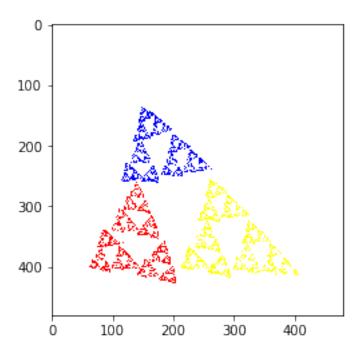
2.44e-06



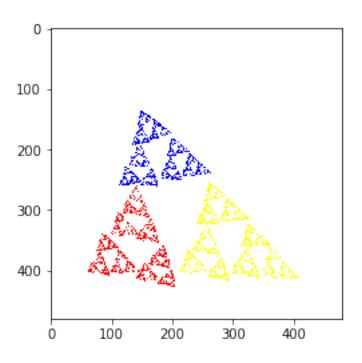
13 14 6.1154e-10 1.35e-10 1.38e-02 6.45e-06 Current image:



14 15 5.0578e-10 1.06e-10 1.41e-02 8.40e-06 Current image:



15 16 4.0441e-10 1.01e-10 9.72e-03 4.11e-06 Current image:



18

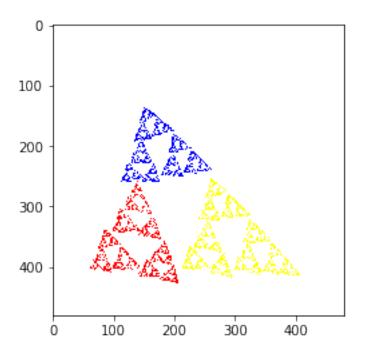
3.6510e-10

3.93e-11

4.47e-03

1.17e-06

Current image:



17 Current image:

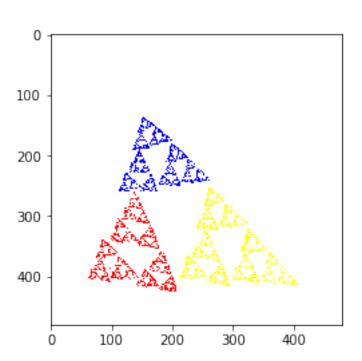
19

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4.05e-11

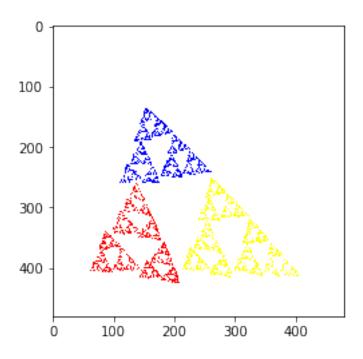
8.96e-03

4.81e-06



18 20 2.7677e-10 4.78e-11 8.79e-03 3.67e-06

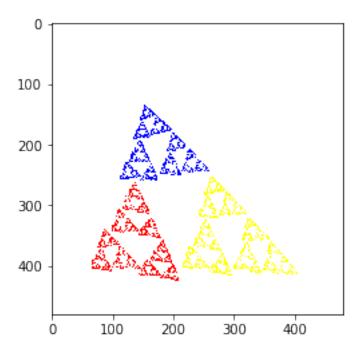
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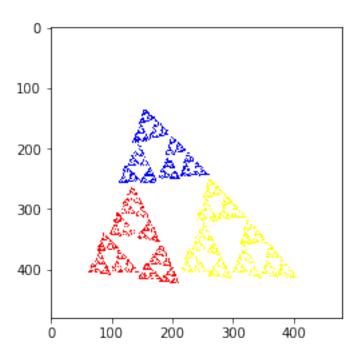
 19
 21
 2.4984e-10
 2.69e-11
 1.32e-02
 7.46e-06

 20
 22
 2.0445e-10
 4.54e-11
 3.29e-03
 3.91e-07

Current image:



21 23 1.8226e-10 2.22e-11 6.71e-03 1.75e-06 Current image:



24

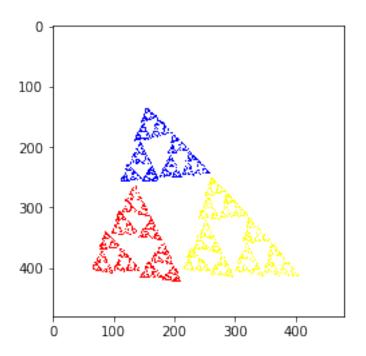
1.5659e-10

2.57e-11

1.30e-02

2.47e-06

Current image:



23 Current image:

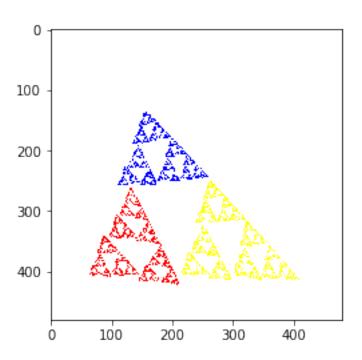
25

1.2518e-10

3.14e-11

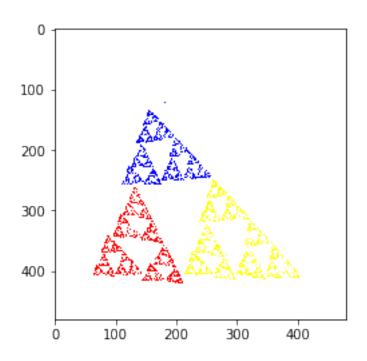
5.44e-03

4.34e-07

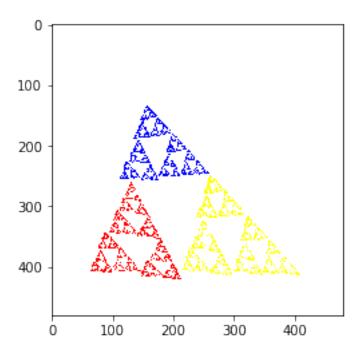


24 26 1.1039e-10 1.48e-11 1.33e-02 2.75e-06

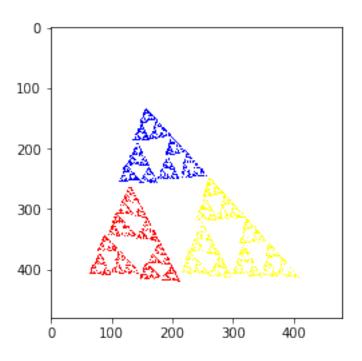
Current image:



25 27 8.3753e-11 2.66e-11 3.99e-03 2.54e-07 Current image:



26 28 7.9454e-11 4.30e-12 1.33e-02 2.89e-06 Current image:



29

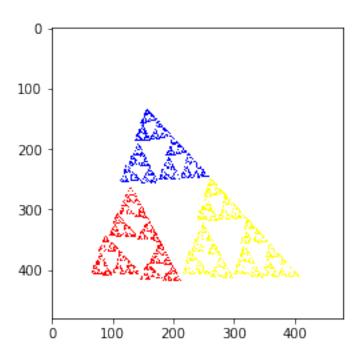
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2.52e-11

3.05e-03

1.59e-07

Current image:



28
Current image:

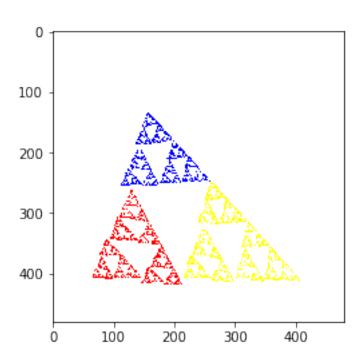
30

4.9247e-11

5.01e-12

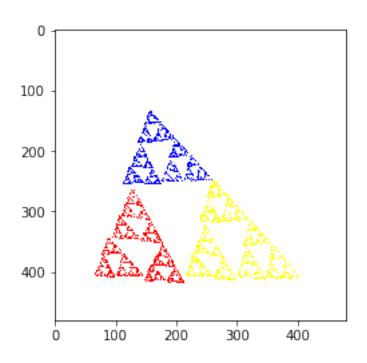
3.21e-03

1.51e-07



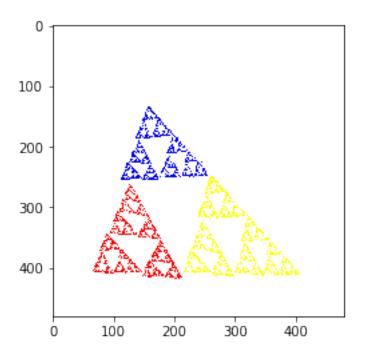
29 31 4.1542e-11 7.70e-12 6.48e-03 7.37e-07

Current image:

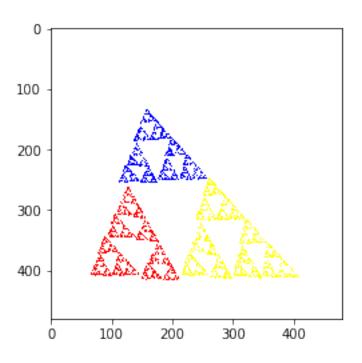


30 32 3.3845e-11 7.70e-12 7.03e-03 8.80e-07

Current image:



31 33 2.7205e-11 6.64e-12 5.74e-03 5.76e-07 Current image:



34

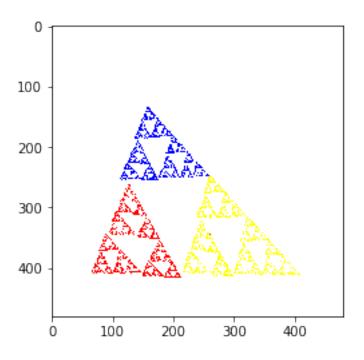
2.2377e-11

4.83e-12

7.02e-03

8.80e-07

Current image:



33
Current image:

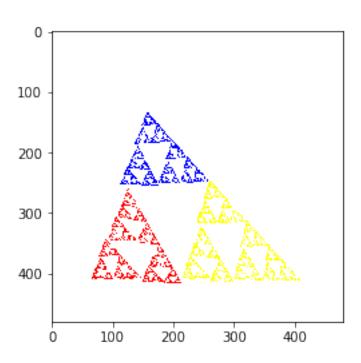
35

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4.18e-12

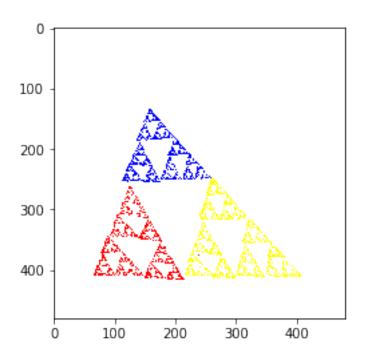
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2.24e-07

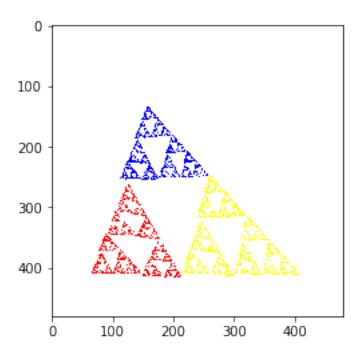


34 37 1.6611e-11 1.58e-12 2.08e-03 7.39e-08

Current image:

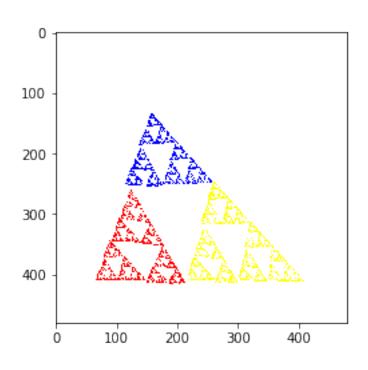


35 38 1.4332e-11 2.28e-12 4.13e-03 3.10e-07 Current image:



36
Current image:

39



1.2074e-11

2.26e-12

4.83e-03

4.28e-07

40

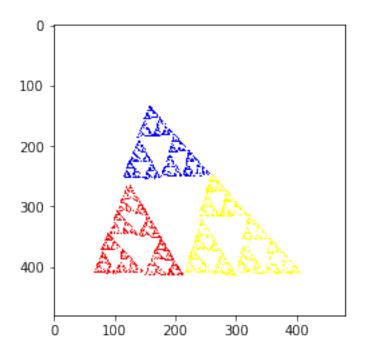
1.0001e-11

2.07e-12

3.02e-03

1.61e-07

Current image:



38
Current image:

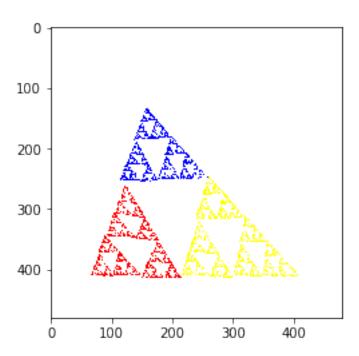
41

9.1590e-12

8.42e-13

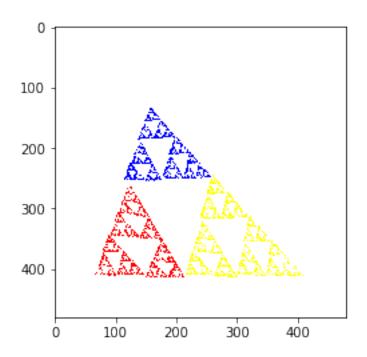
6.15e-03

6.43e-07



39 42 6.8637e-12 2.30e-12 1.41e-03 3.33e-08

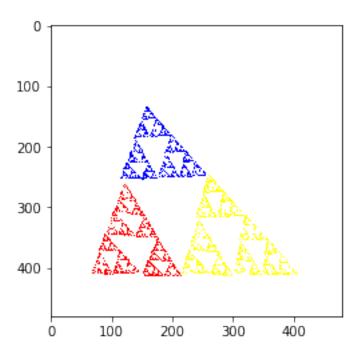
Current image:



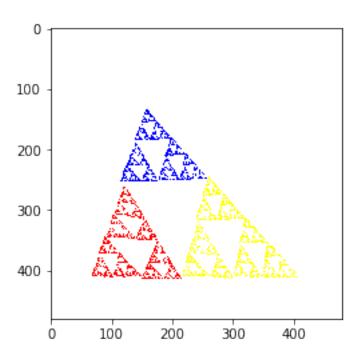
 40
 43
 6.3401e-12
 5.24e-13
 1.53e-03
 3.86e-08

 41
 44
 5.5093e-12
 8.31e-13
 3.07e-03
 1.54e-07

Current image:



42 45 4.6705e-12 8.39e-13 3.86e-03 2.41e-07 Current image:



46

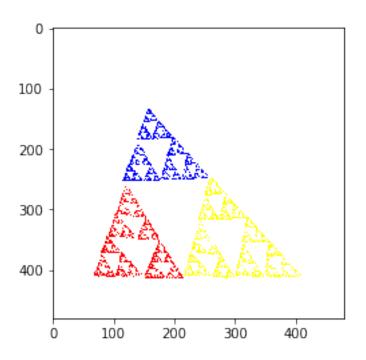
3.9726e-12

6.98e-13

2.21e-03

7.52e-08

Current image:



44 Current image:

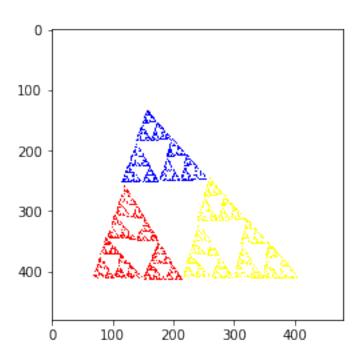
47

3.5451e-12

4.27e-13

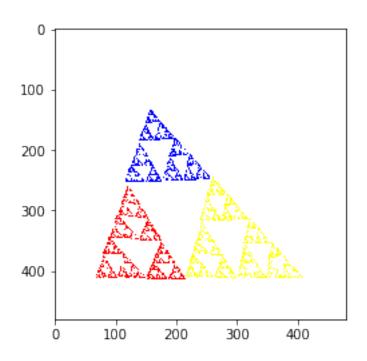
4.88e-03

3.22e-07



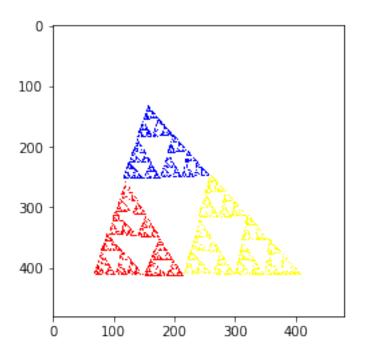
45 48 2.9224e-12 6.23e-13 1.04e-03 1.39e-08

Current image:

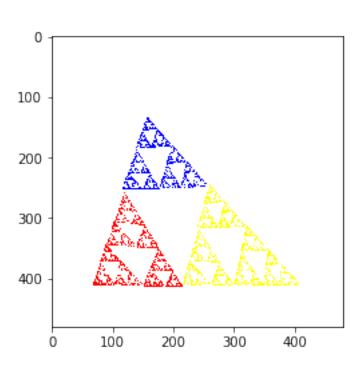


46 49 2.7513e-12 1.71e-13 1.20e-03 1.76e-08 Current image:

62



47
Current image:



2.4615e-12

2.90e-13

2.39e-03

5.12e-08

51

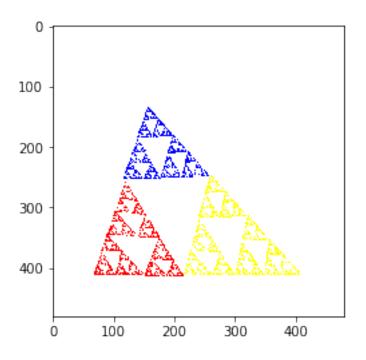
2.0943e-12

3.67e-13

3.88e-03

8.11e-08

Current image:



49 Current image:

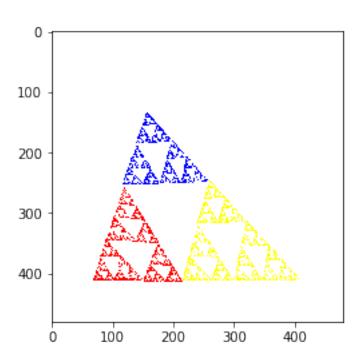
52

1.8256e-12

2.69e-13

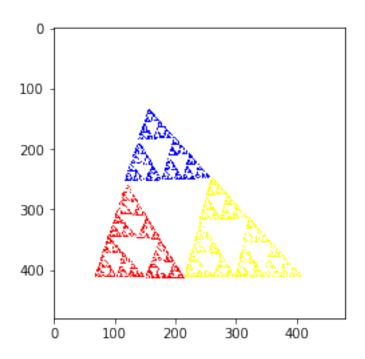
2.74e-03

1.82e-07

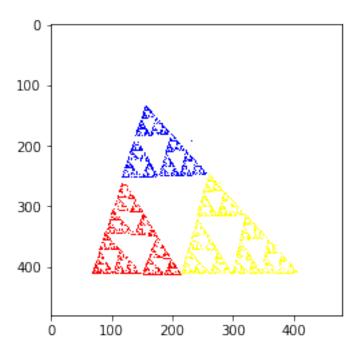


50 53 1.5661e-12 2.60e-13 4.18e-03 1.09e-07

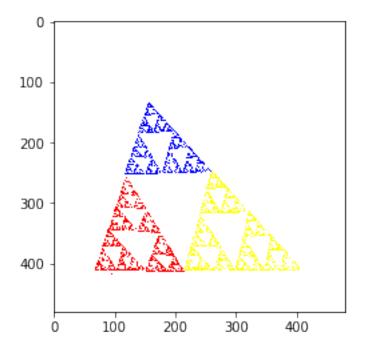
Current image:



51 54 1.3731e-12 1.93e-13 3.02e-03 4.21e-07 Current image:



52 Current image: 55



1.2258e-12

1.47e-13

1.34e-03

4.78e-08

57

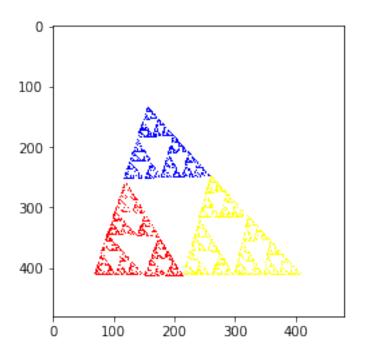
1.1478e-12

7.81e-14

1.31e-03

8.48e-08

Current image:



54
Current image:

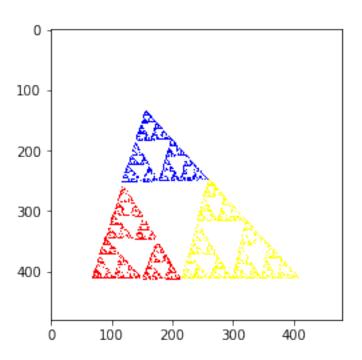
58

1.0450e-12

1.03e-13

2.70e-03

3.72e-07



55 Current image: 59

60

9.3334e-13

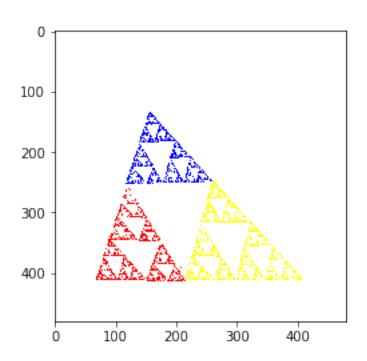
1.12e-13 1.17e-03

8.77e-14

2.60e-03

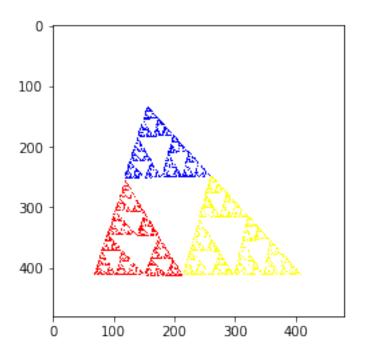
5.34e-08

3.47e-07

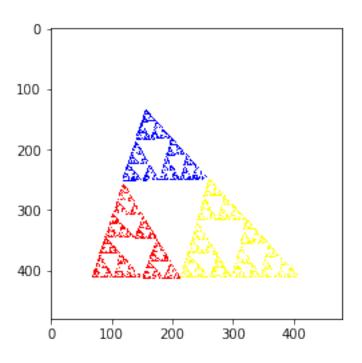


8.4563e-13

56 Current image:



57 61 7.5064e-13 9.50e-14 1.10e-03 5.32e-08 Current image:



62

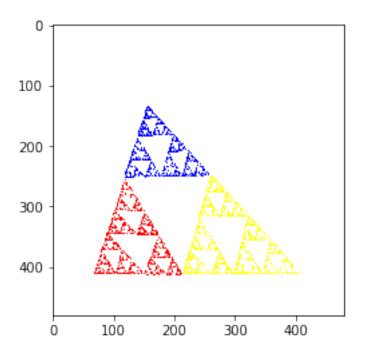
6.7925e-13

7.14e-14

2.61e-03

3.50e-07

Current image:



59
Current image:

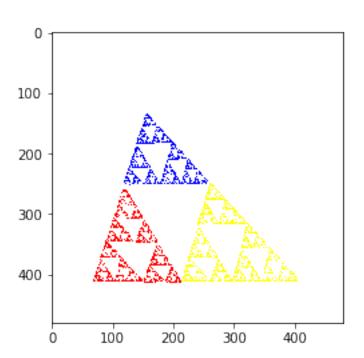
63

5.9513e-13

8.41e-14

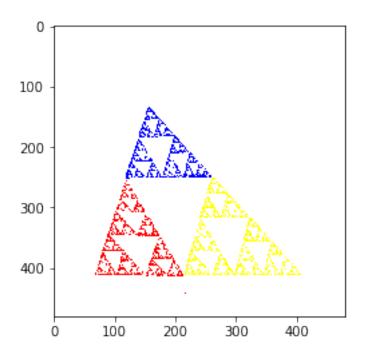
9.47e-04

4.09e-08



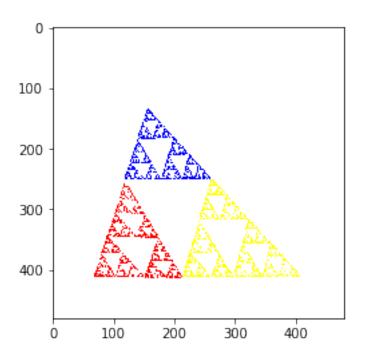
60 64 5.3911e-13 5.60e-14 2.61e-03 3.52e-07

Current image:

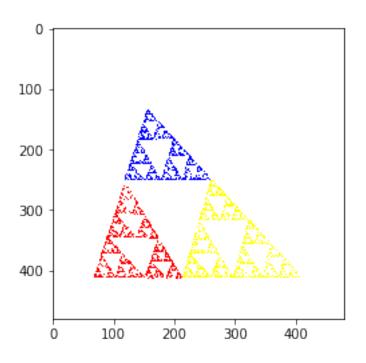


61 65 4.6359e-13 7.55e-14 8.21e-04 3.09e-08 62 66 4.2154e-13 4.20e-14 2.61e-03 3.53e-07

Current image:



63 67 3.5315e-13 6.84e-14 7.09e-04 2.28e-08 Current image:



68

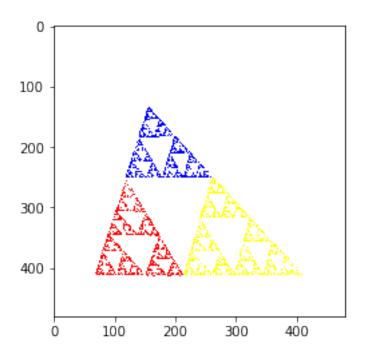
3.2400e-13

2.92e-14

2.61e-03

3.53e-07

Current image:



65
Current image:

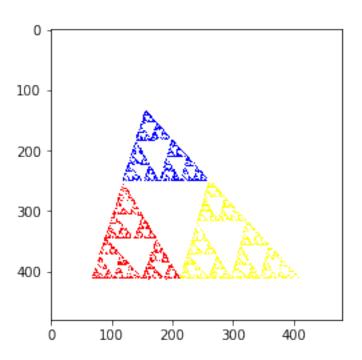
69

2.6146e-13

6.25e-14

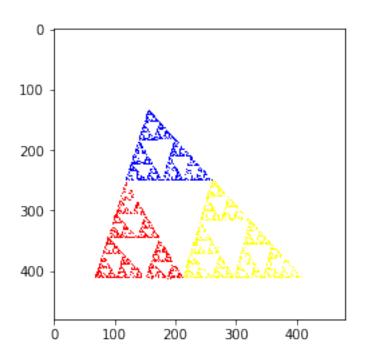
6.05e-04

1.64e-08

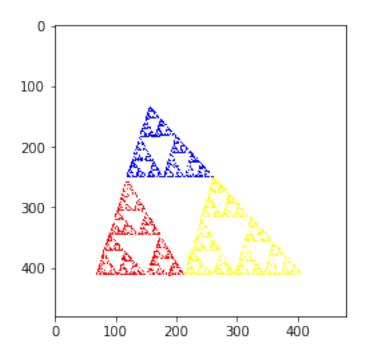


66 70 2.4428e-13 1.72e-14 2.61e-03 3.52e-07

Current image:

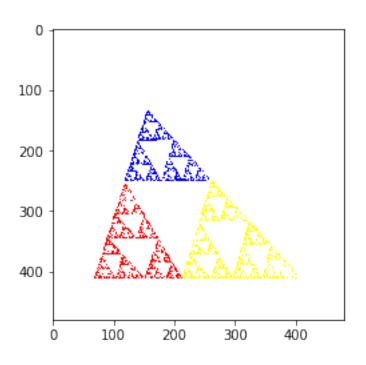


67 71 1.8646e-13 5.78e-14 5.08e-04 1.14e-08 Current image:



68
Current image:

72



1.7235e-13

1.41e-14

6.57e-04

2.19e-08

73

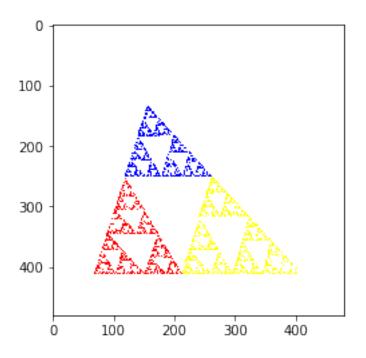
1.4886e-13

2.35e-14

1.30e-03

8.83e-08

Current image:



70 Current image:

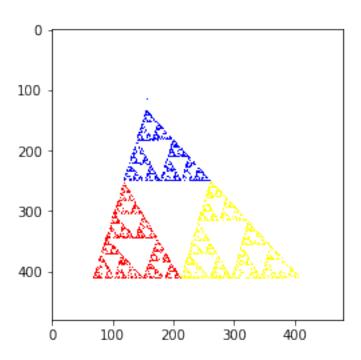
74

1.2325e-13

2.56e-14

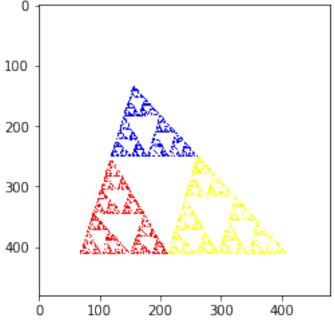
1.52e-03

1.14e-07

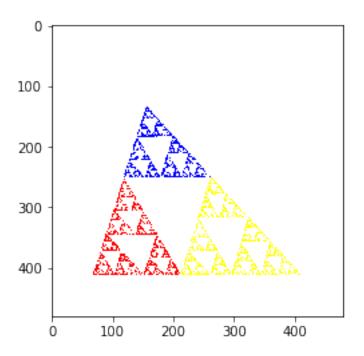


71 75 1.0178e-13 2.15e-14 1.07e-03 5.75e-08

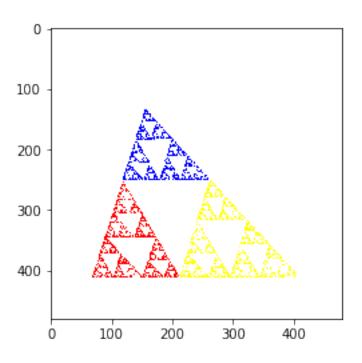
Current image:



72 76 8.4504e-14 1.73e-14 1.80e-03 1.66e-07 Current image:



73 77 6.6398e-14 1.81e-14 5.85e-04 1.74e-08 Current image:



79

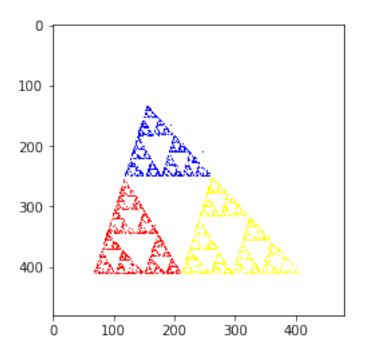
5.8288e-14

8.11e-15

6.57e-04

2.23e-08

Current image:



75
Current image:

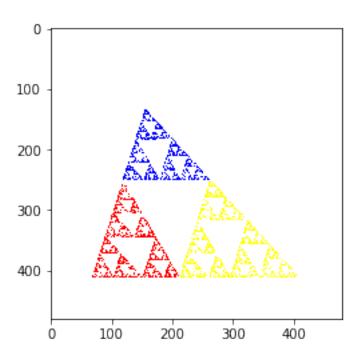
80

4.6556e-14

1.17e-14

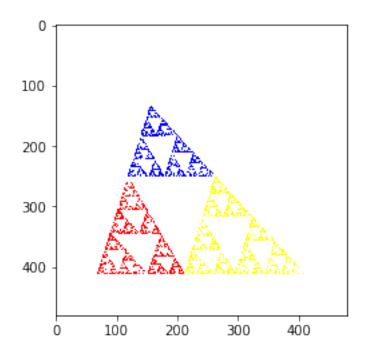
1.30e-03

8.79e-08

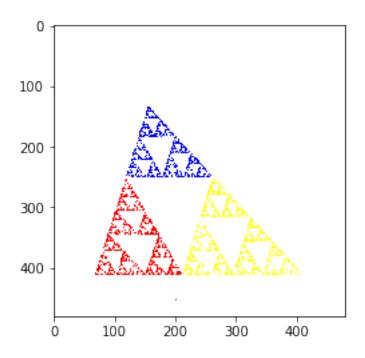


76 81 3.6116e-14 1.04e-14 8.13e-04 Current image:

3.27e-08



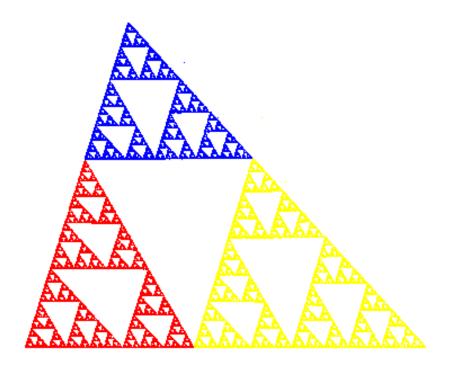
77 82 2.9801e-14 6.32e-15 1.68e-03 1.45e-07 Current image:



78 83 1.9328e-14 1.05e-14 3.55e-04 6.40e-09 \dot{t} termination condition is satisfied. Function evaluations 83, initial cost 4.9542e-03, final cost 1.9328e-14, first-order optimality

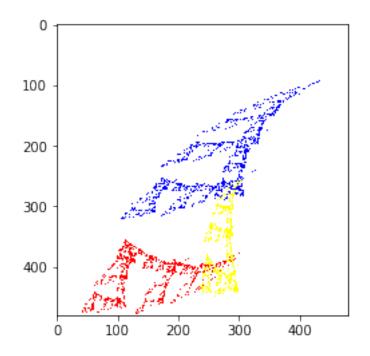
As we can see, we found the global minimum of the function and recovered our Steemson triangle

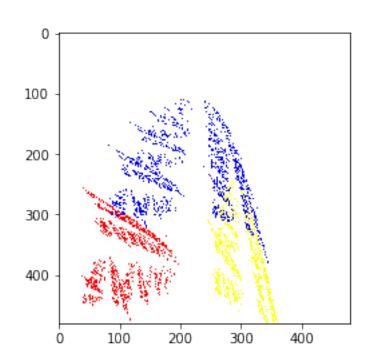
Out[43]:



Now we may add some noise to our initial guess and find that the moments stil recover the Steemson triangle

Current image:

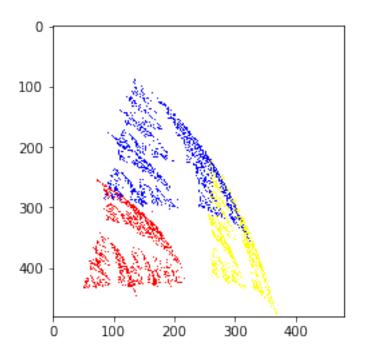




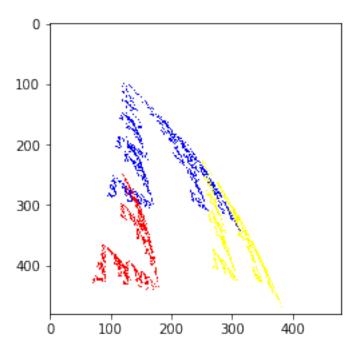
1 2 7.5633e-04 4.53e-03 3.47e-01

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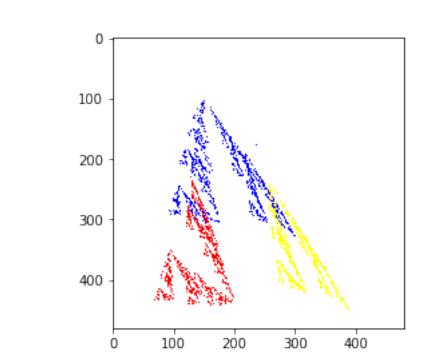
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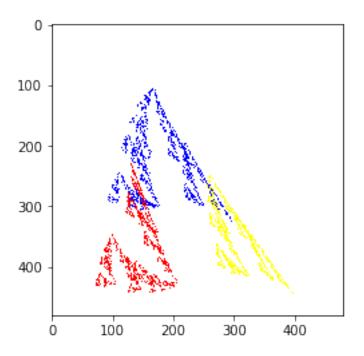
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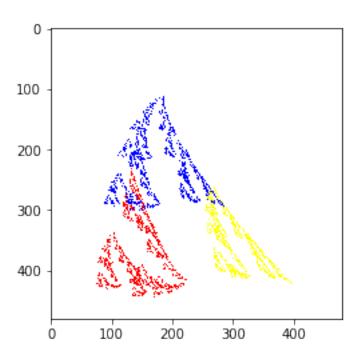
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4 5 4.1631e-06 1.03e-05 1.16e-01 1.47e-03 Current image:



5 7 1.7136e-06 2.45e-06 6.28e-02 3.12e-04 Current image:



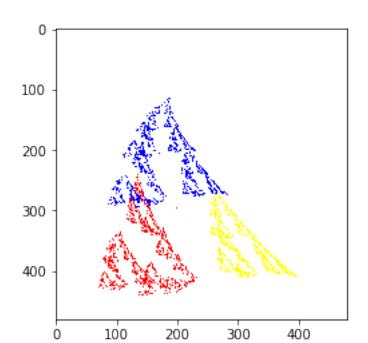
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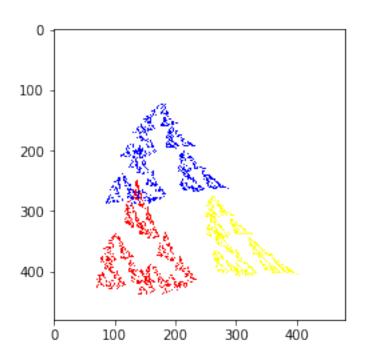
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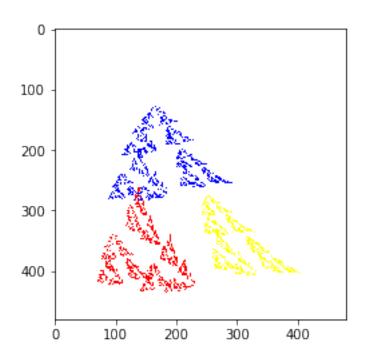
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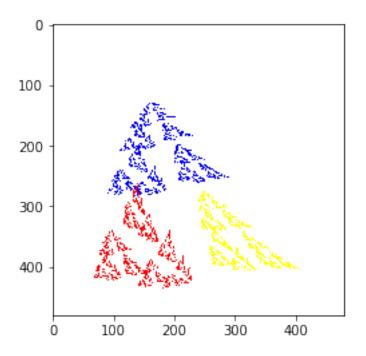
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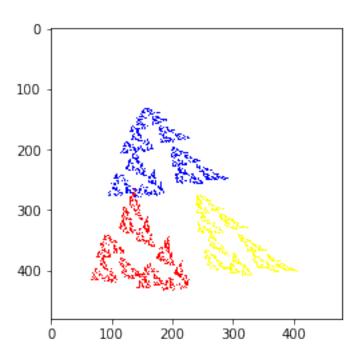


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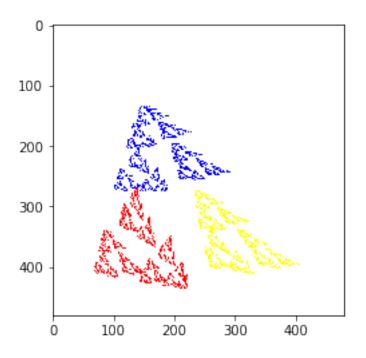
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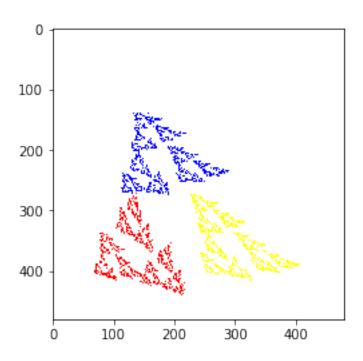
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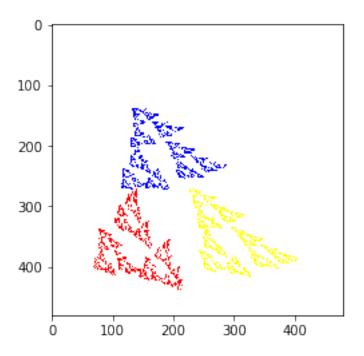
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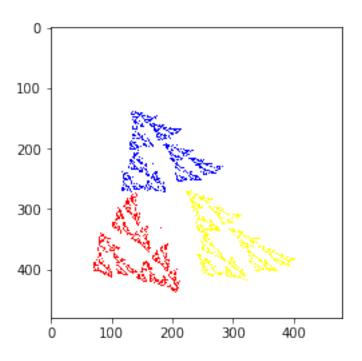
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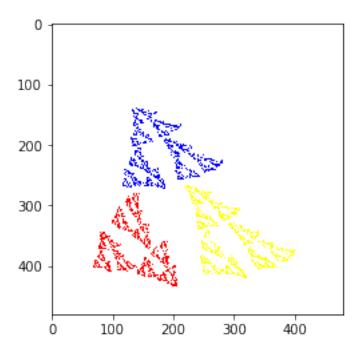
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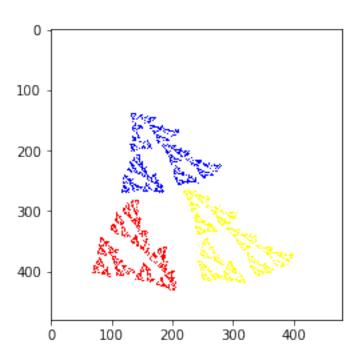
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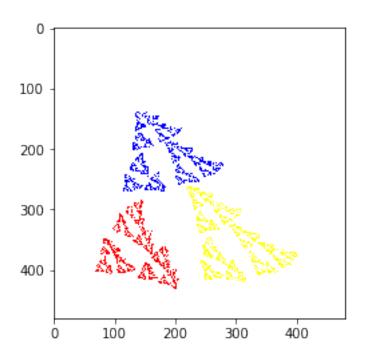
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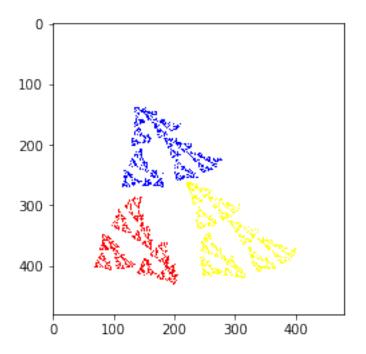


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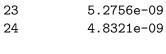
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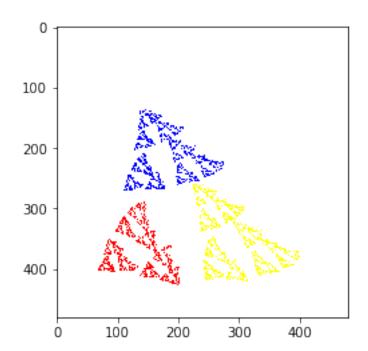
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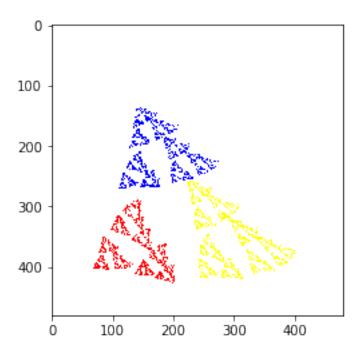
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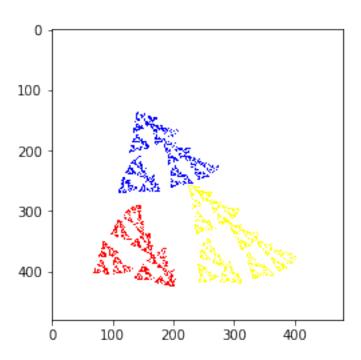
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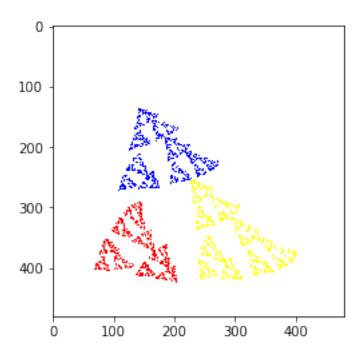
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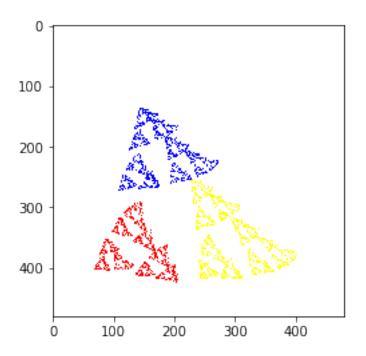


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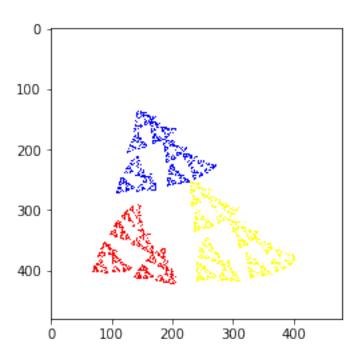
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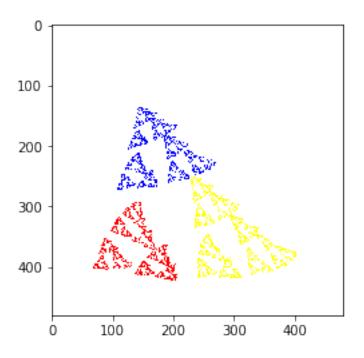
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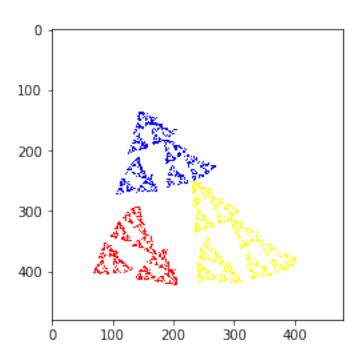
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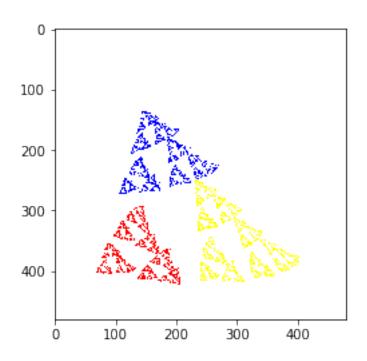
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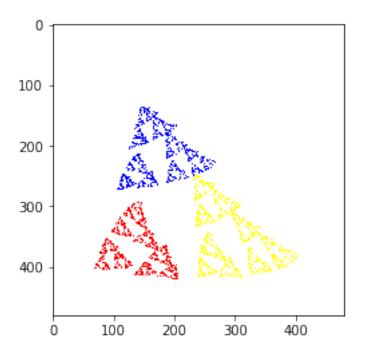


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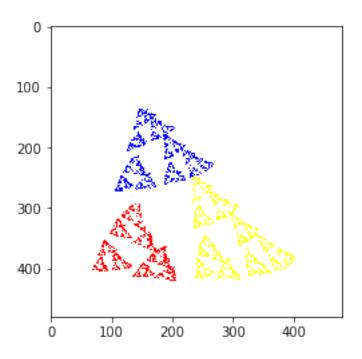
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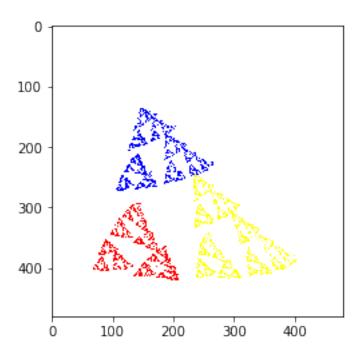
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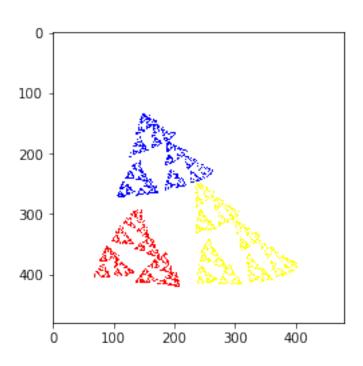
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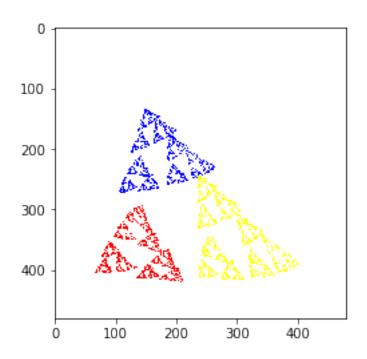
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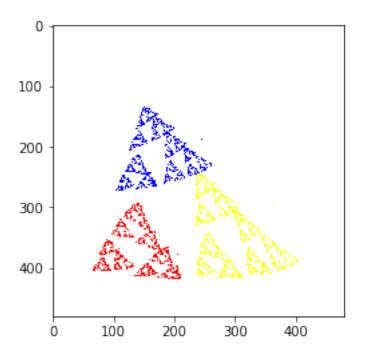


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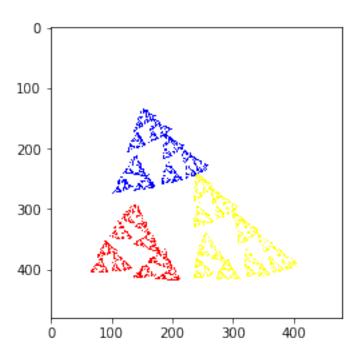
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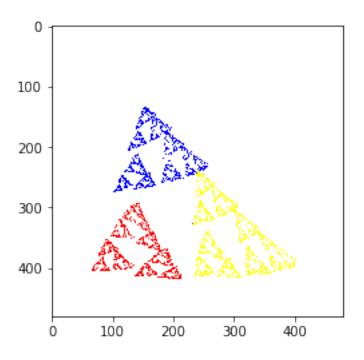
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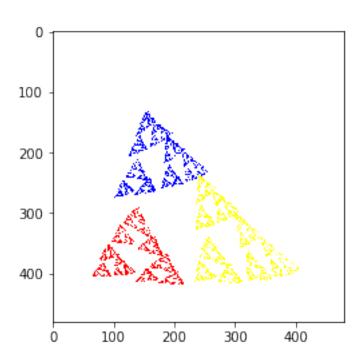
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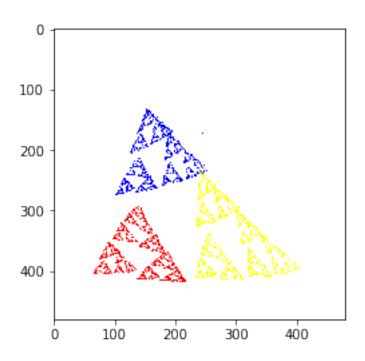
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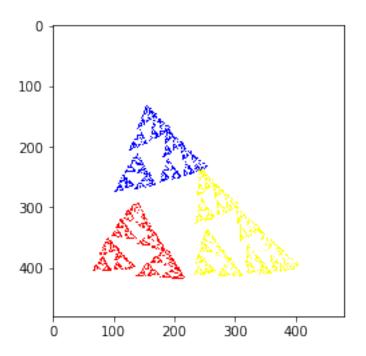
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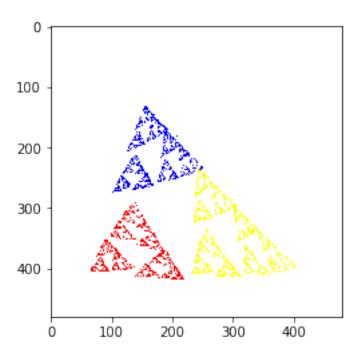


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41 48 7.1191e-10 1.28e-10 1.06e-02 1.53e-05 Current image:



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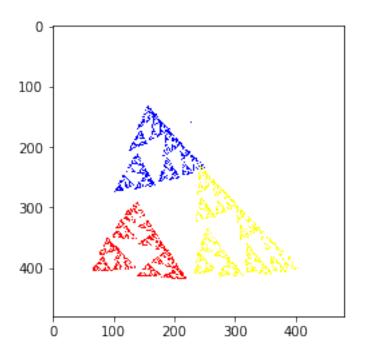
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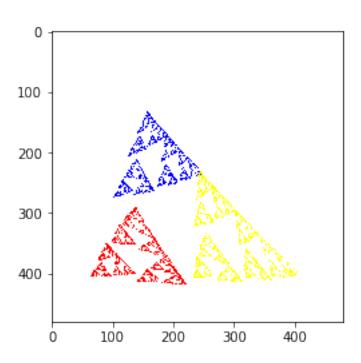
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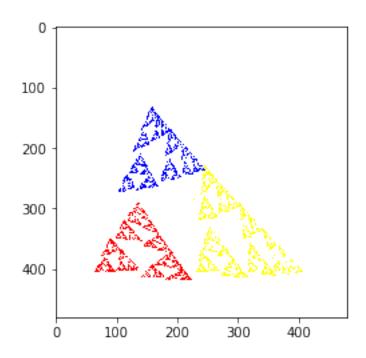
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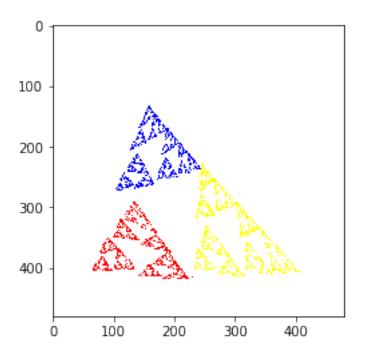
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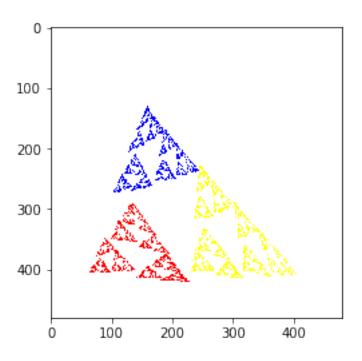
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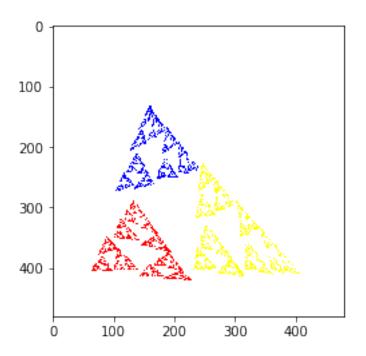
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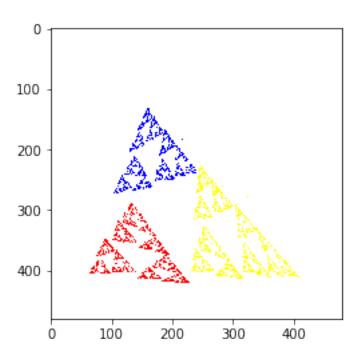
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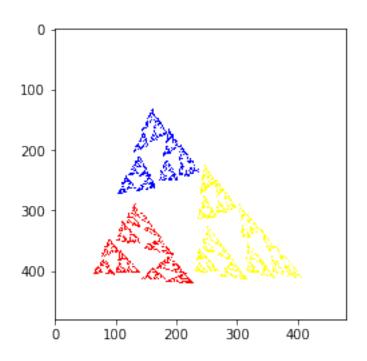
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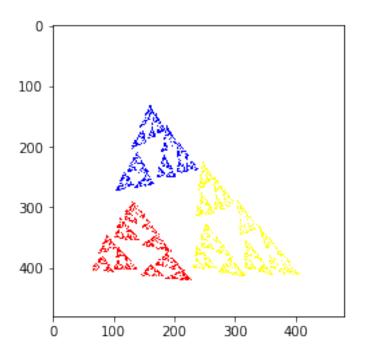


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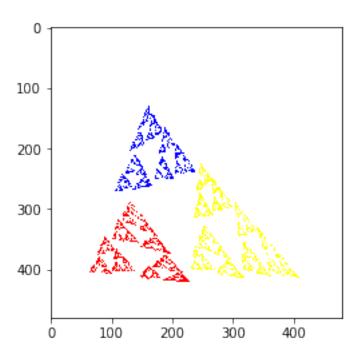
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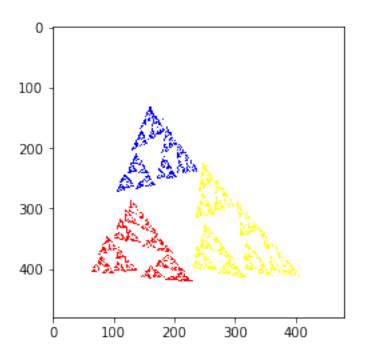
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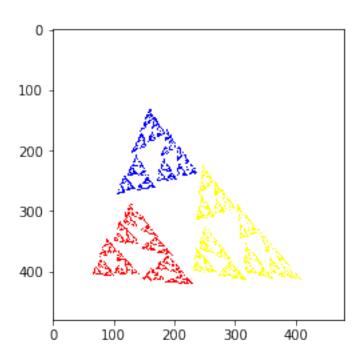
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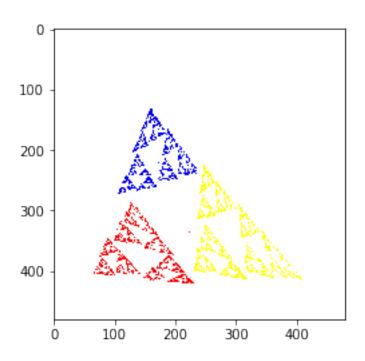
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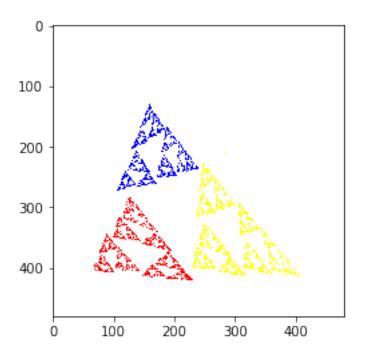


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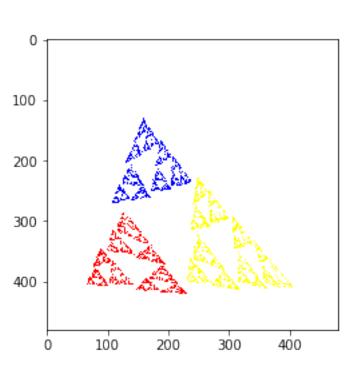
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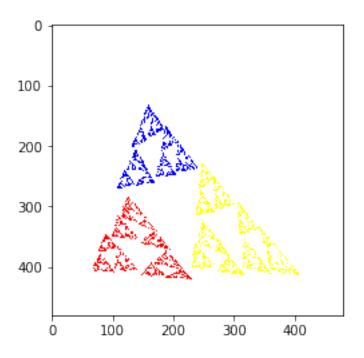
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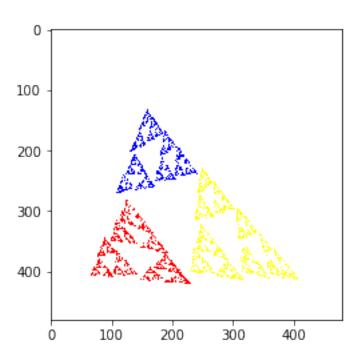
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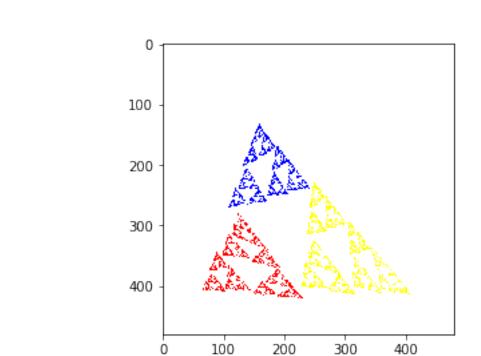
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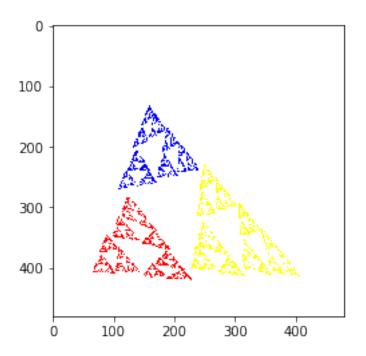
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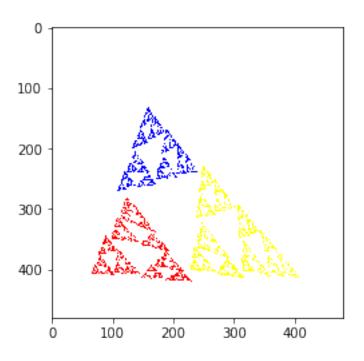
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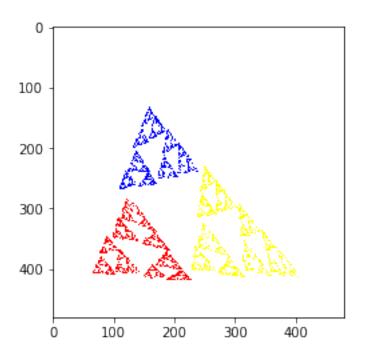
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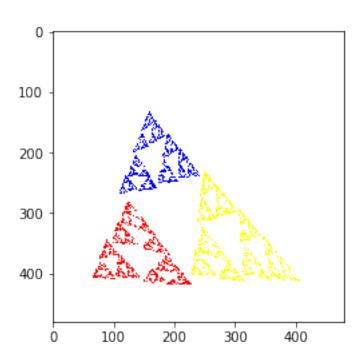
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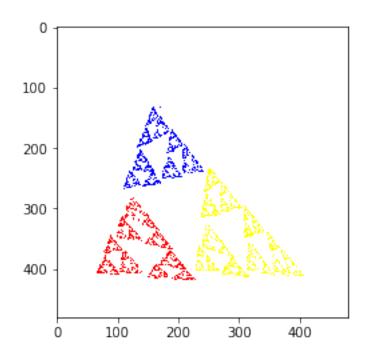
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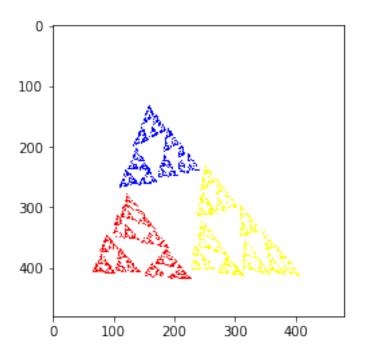


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Current image:

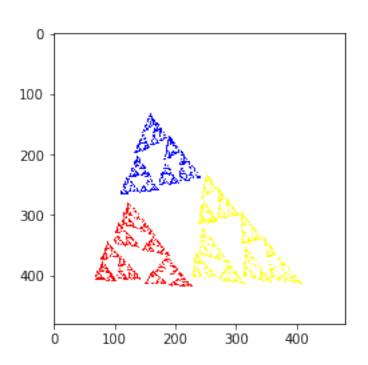
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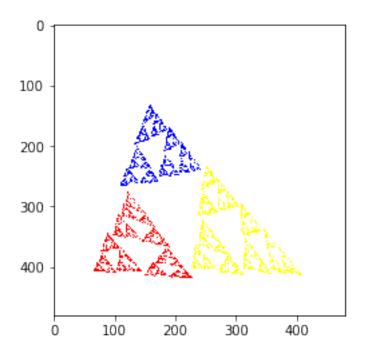
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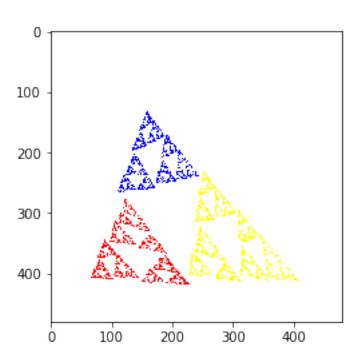
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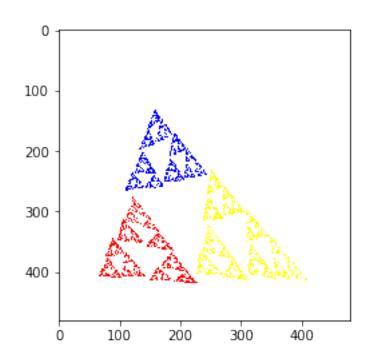
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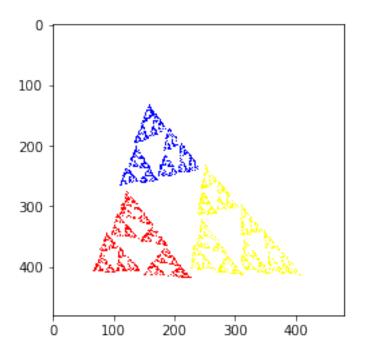
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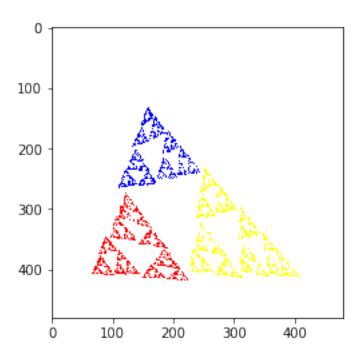
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73 82 4.0763e-11 2.00e-12 4.97e-03 9.96e-07 Current image:



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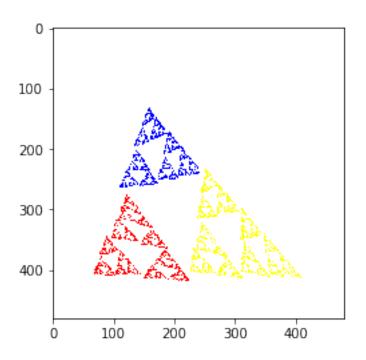
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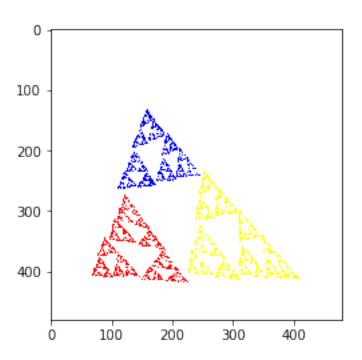
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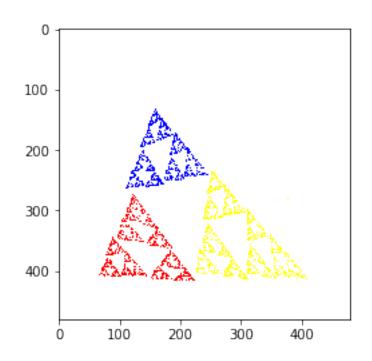
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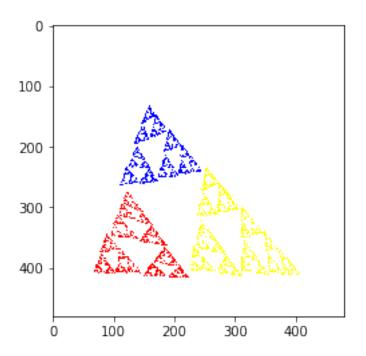
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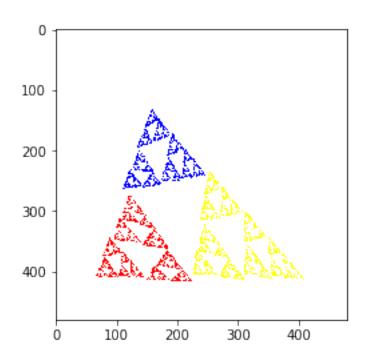


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Current image:

87



3.1974e-11

1.62e-12

3.14e-03

3.96e-07

88

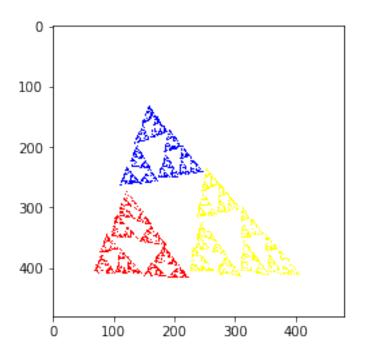
3.0428e-11

1.55e-12

4.97e-03

1.07e-06

Current image:



80 Current image:

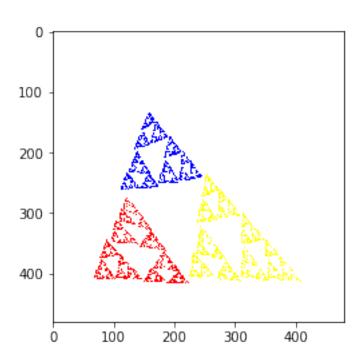
89

2.8913e-11

1.51e-12

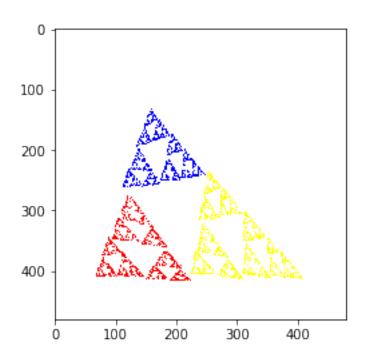
2.98e-03

3.52e-07

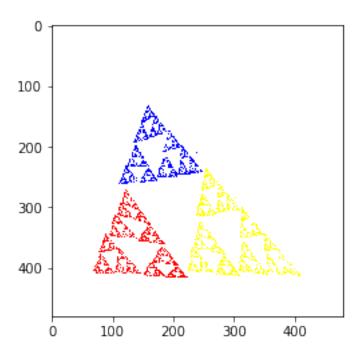


81 90 2.7488e-11 1.42e-12 4.97e-03 1.07e-06

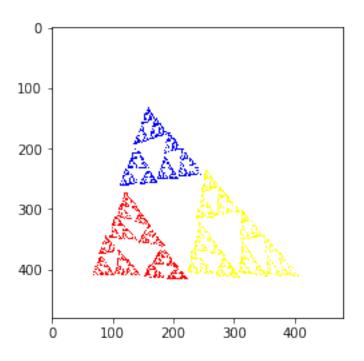
Current image:



82 91 2.6076e-11 1.41e-12 2.84e-03 3.15e-07 Current image:



83 92 2.4774e-11 1.30e-12 4.96e-03 1.09e-06 Current image:



93

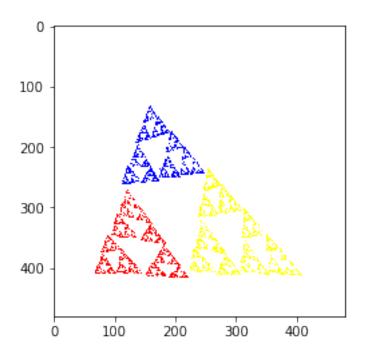
2.3458e-11

1.32e-12

2.68e-03

2.74e-07

Current image:



85
Current image:

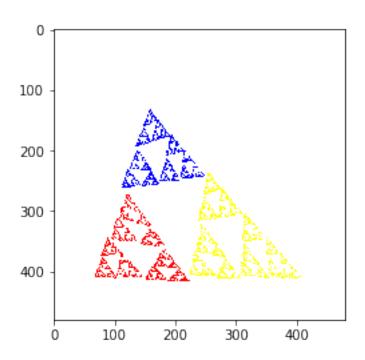
94

2.2276e-11

1.18e-12

4.95e-03

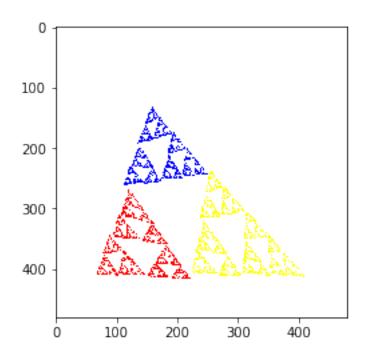
1.10e-06



 86
 95
 2.1048e-11
 1.23e-12
 2.52e-03
 2.36e-07

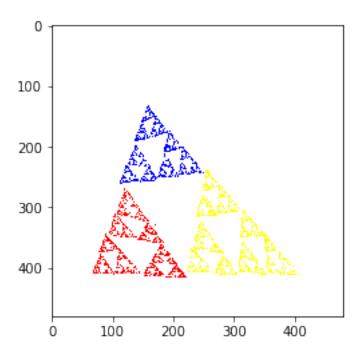
 87
 96
 1.9984e-11
 1.06e-12
 4.94e-03
 1.12e-06

Current image:



88 97 1.8836e-11 1.15e-12 2.37e-03 2.02e-07

Current image:



1.7883e-11

89
Current image:



9.52e-13

4.93e-03

1.13e-06

99

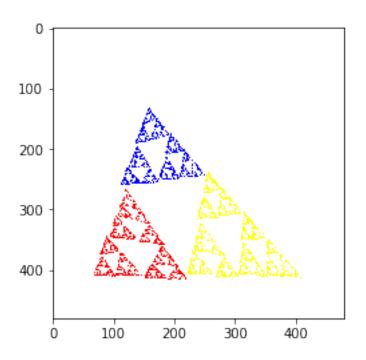
1.6808e-11

1.08e-12

2.22e-03

1.72e-07

Current image:



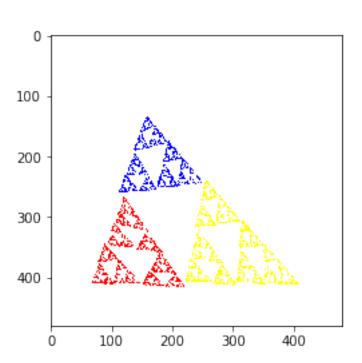
91 Current image: 100

1.5962e-11

8.45e-13

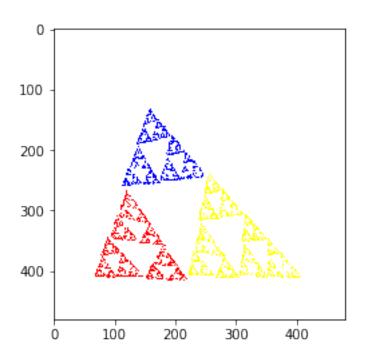
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1.15e-06

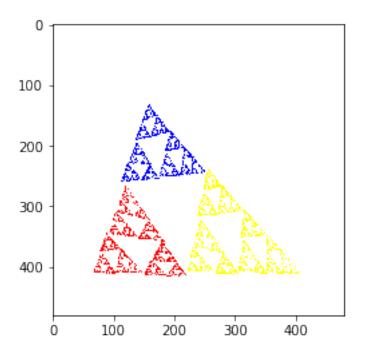


92 101 1.4952e-11 1.01e-12 2.08e-03 1.45e-07

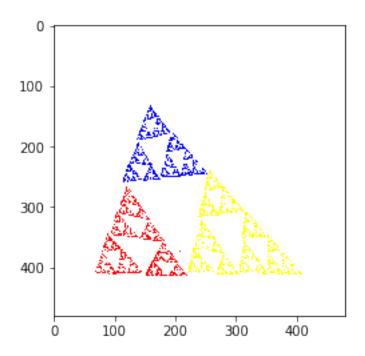
Current image:



93 102 1.4208e-11 7.44e-13 4.90e-03 1.16e-06 Current image:



94 Current image: 103



1.3258e-11

9.50e-13

1.95e-03

1.22e-07

104

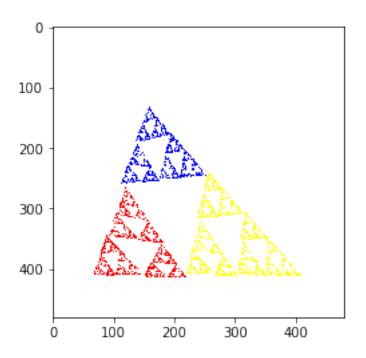
1.2610e-11

6.48e-13

4.89e-03

1.17e-06

Current image:



96
Current image:

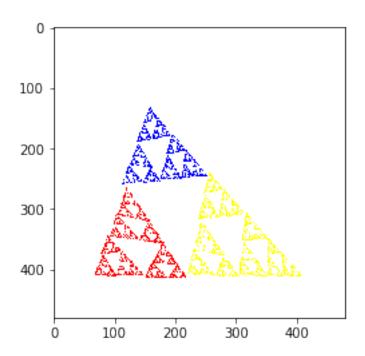
105

1.1714e-11

8.97e-13

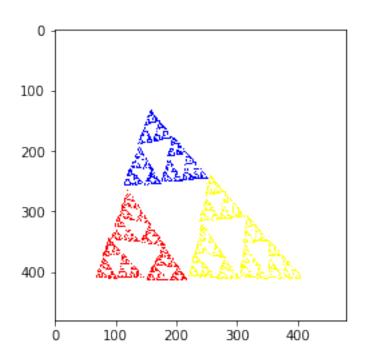
1.82e-03

1.02e-07

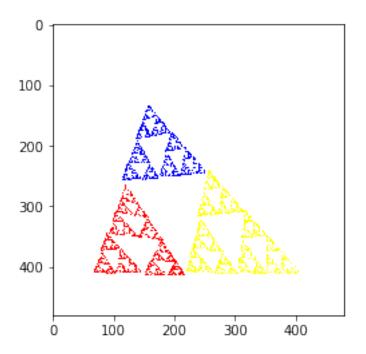


97 106 1.1157e-11 5.57e-13 4.88e-03 1.17e-06

Current image:



98 107 1.0308e-11 8.48e-13 1.69e-03 8.46e-08 Current image:



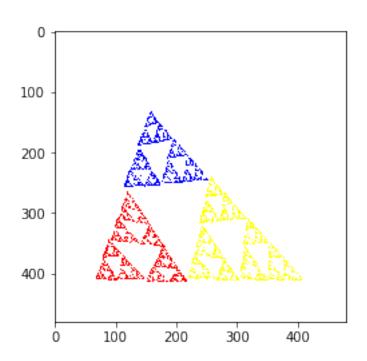
99 Current image: 108

9.8372e-12

4.71e-13

4.87e-03

1.18e-06



109

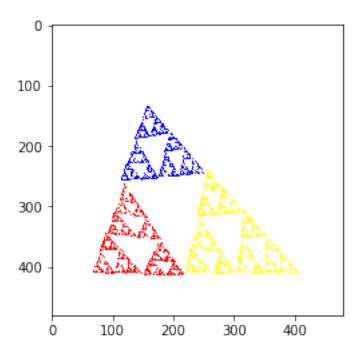
9.0321e-12

8.05e-13

1.57e-03

6.99e-08

Current image:



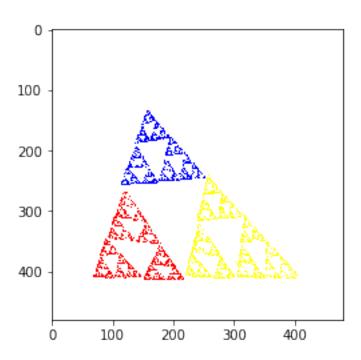
101 Current image: 110

8.6420e-12

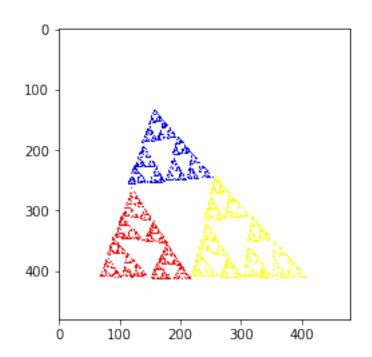
3.90e-13

4.86e-03

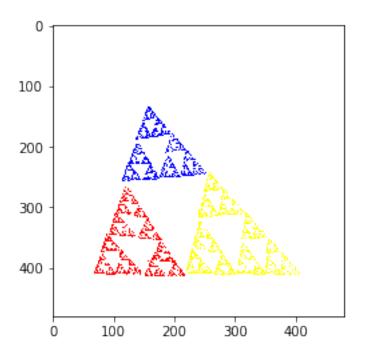
1.18e-06



102 111 7.8759e-12 7.66e-13 1.46e-03 5.74e-08 Current image:



103 112 7.5621e-12 3.14e-13 4.85e-03 1.19e-06 Current image:



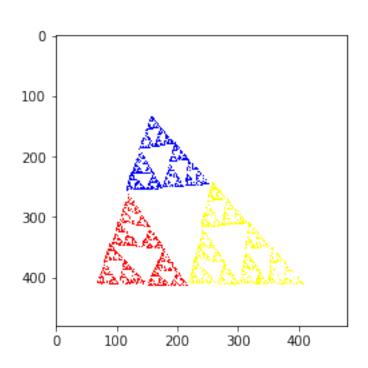
104 Current image: 113

6.8308e-12

7.31e-13

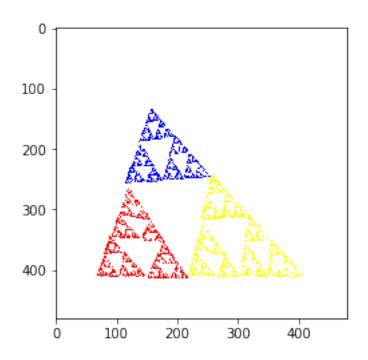
1.35e-03

4.68e-08



105 114 6.4987e-12 3.32e-13 4.61e-03 1.04e-06

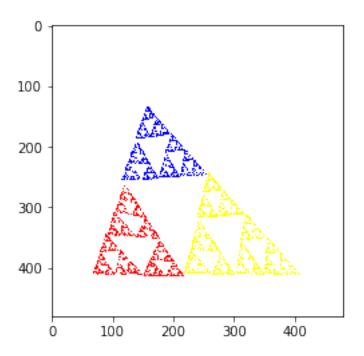
Current image:



 106
 115
 5.8943e-12
 6.04e-13
 1.43e-03
 6.31e-08

 107
 116
 5.7223e-12
 1.72e-13
 4.84e-03
 1.20e-06

Current image:



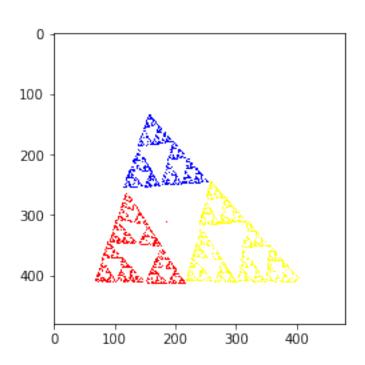
108 Current image: 117

5.0486e-12

6.74e-13

1.10e-03

3.26e-08



118

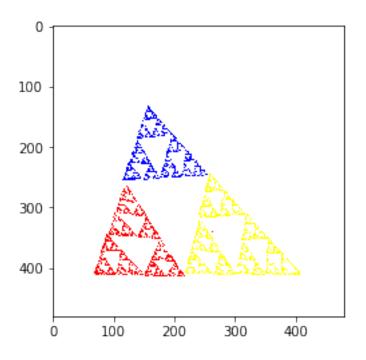
4.7559e-12

2.93e-13

2.32e-03

2.58e-07

Current image:



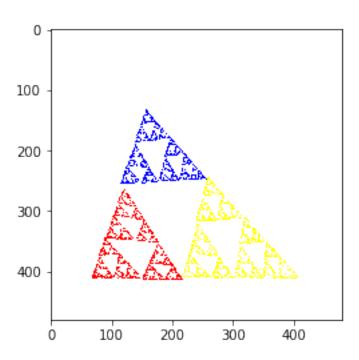
110 Current image: 119

4.4309e-12

3.25e-13

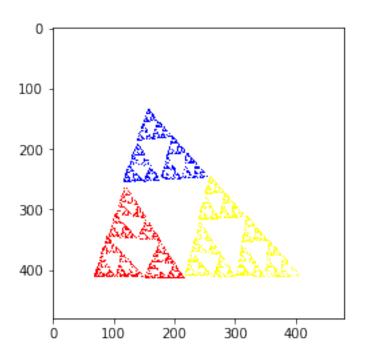
4.15e-03

7.27e-07

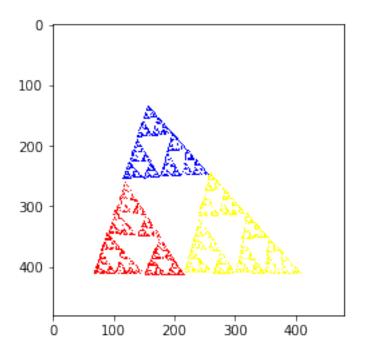


111 120 4.0498e-12 3.81e-13 1.40e-03 7.45e-08

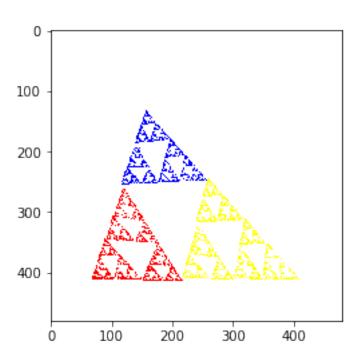
Current image:



112 121 3.9488e-12 1.01e-13 4.61e-03 1.09e-06 Current image:



113 Current image:



3.4128e-12

5.36e-13

9.04e-04

3.30e-08

123

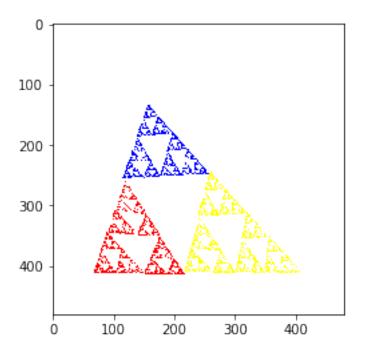
3.2803e-12

1.33e-13

1.22e-03

7.36e-08

Current image:



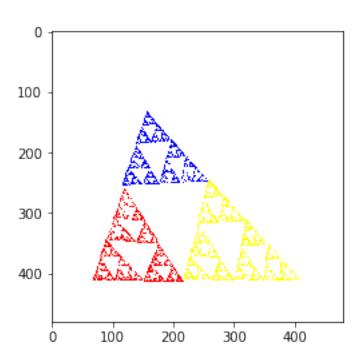
115 Current image: 124

3.0609e-12

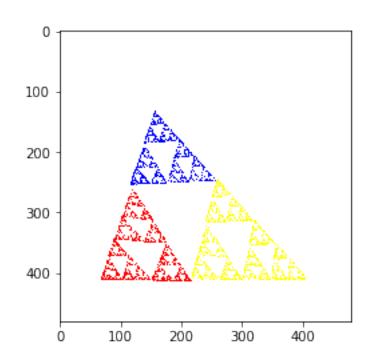
2.19e-13

2.42e-03

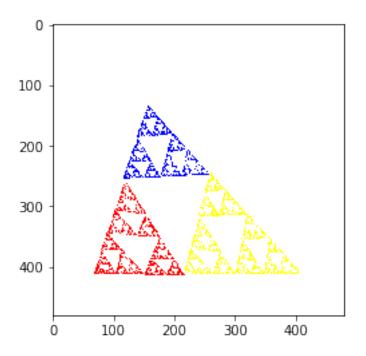
3.11e-07



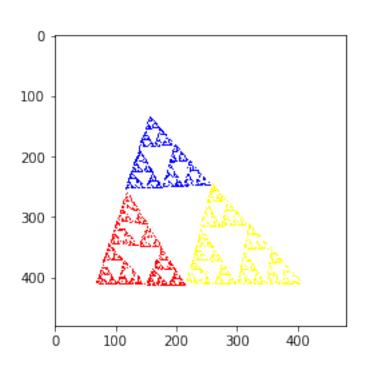
116 125 2.8062e-12 2.55e-13 2.62e-03 2.91e-07 Current image:



117 126 2.5661e-12 2.40e-13 2.57e-03 3.01e-07 Current image:



118
Current image:



2.3467e-12

2.19e-13

2.34e-03

2.62e-07

128

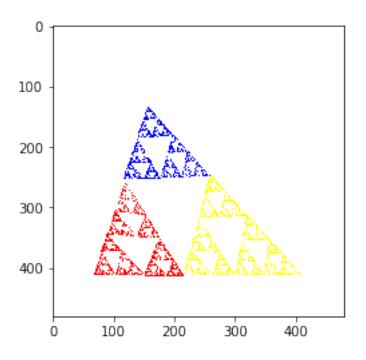
2.1424e-12

2.04e-13

2.52e-03

3.15e-07

Current image:



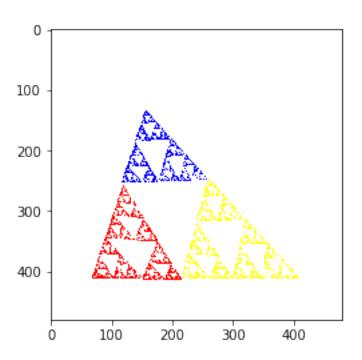
120 Current image: 129

1.9573e-12

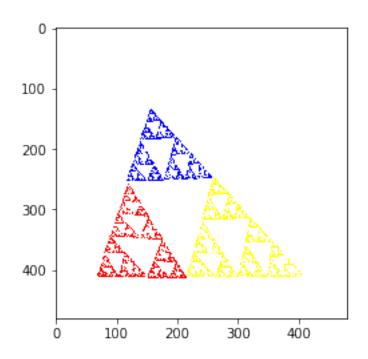
1.85e-13

2.00e-03

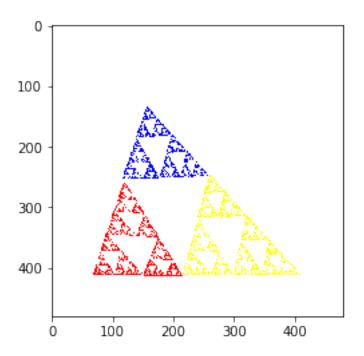
1.98e-07



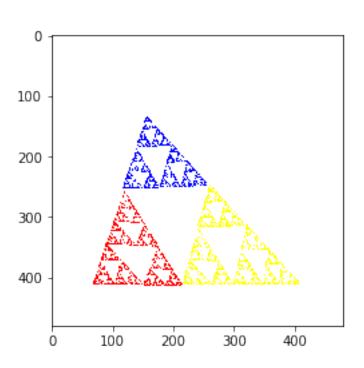
121 130 1.7898e-12 1.68e-13 2.95e-03 4.43e-07 Current image:



122 131 1.6253e-12 1.64e-13 1.27e-03 7.95e-08 Current image:



123 Current image:



1.5374e-12

8.79e-14

1.22e-03

7.60e-08

134

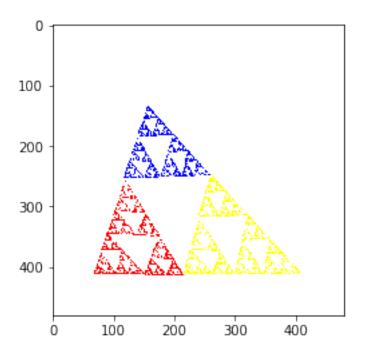
1.4088e-12

1.29e-13

2.42e-03

3.14e-07

Current image:



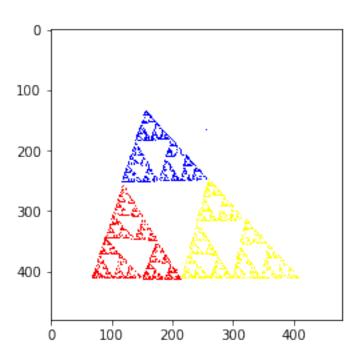
125 Current image: 135

1.2775e-12

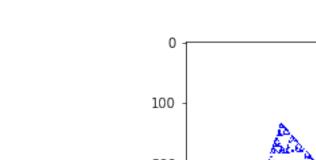
1.31e-13

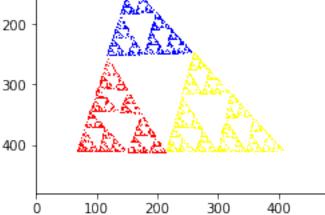
1.61e-03

1.19e-07



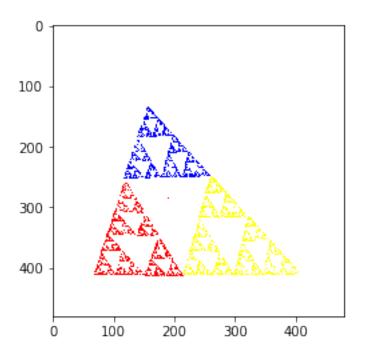
126 136 1.1596e-12 1.18e-13 2.40e-03 2.98e-07 Current image:





127 137 1.0463e-12 1.13e-13 1.50e-03 1.04e-07 128 138 9.4487e-13 1.01e-13 2.30e-03 2.71e-07

Current image:

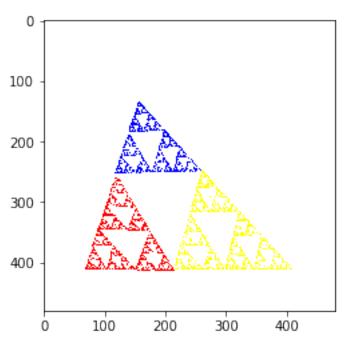


129 Current image: 139 8.4808e-13

9.68e-14

1.46e-03

1.03e-07



140

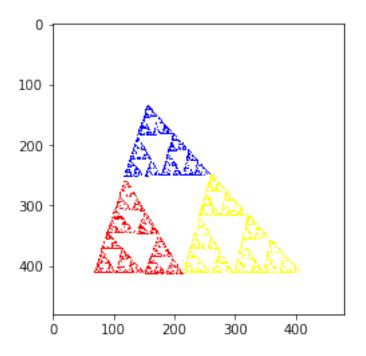
7.6251e-13

8.56e-14

2.40e-03

2.99e-07

Current image:



131 Current image:

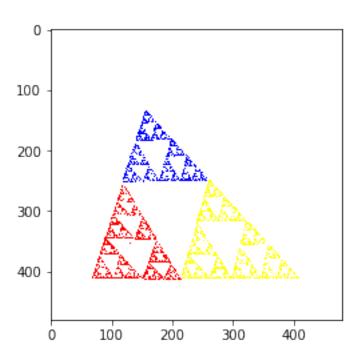
141

6.7897e-13

8.35e-14

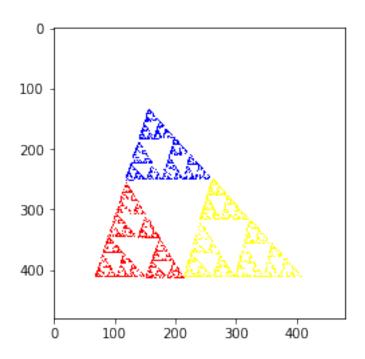
1.16e-03

6.42e-08

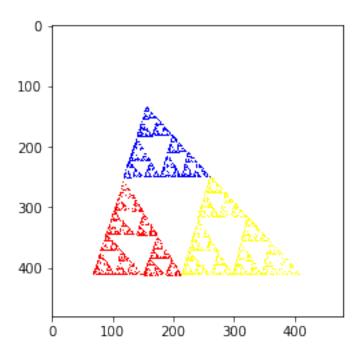


132 142 6.0792e-13 7.11e-14 2.30e-03 2.74e-07

Current image:



133 143 5.3735e-13 7.06e-14 1.12e-03 6.06e-08 Current image:



134 Current image:



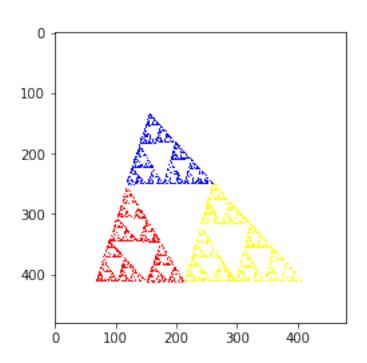
144

4.7868e-13

5.87e-14

2.30e-03

2.74e-07



145

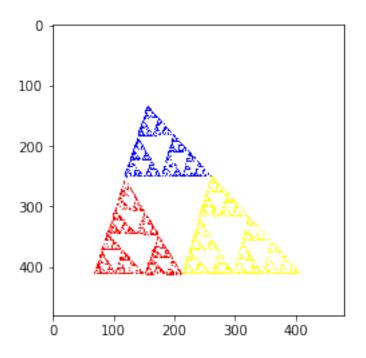
4.1805e-13

6.06e-14

9.79e-04

4.60e-08

Current image:



136
Current image:

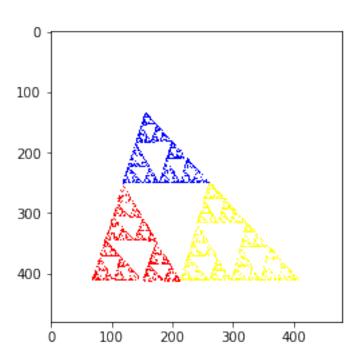
146

3.7139e-13

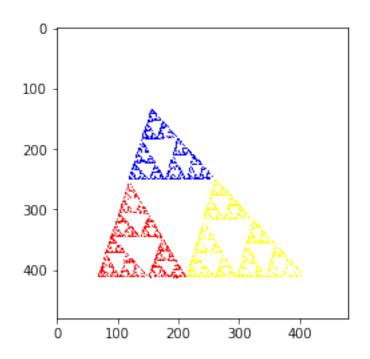
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2.30e-03

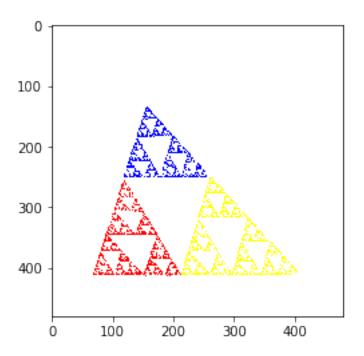
2.74e-07



137 147 3.1875e-13 5.26e-14 8.45e-04 3.40e-08 Current image:



138 148 2.8302e-13 3.57e-14 2.30e-03 2.74e-07 Current image:



139 Current image:

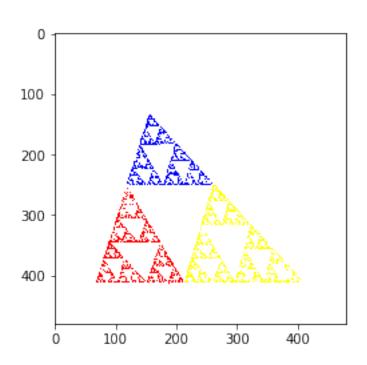


2.3687e-13

4.62e-14

7.22e-04

2.46e-08



150

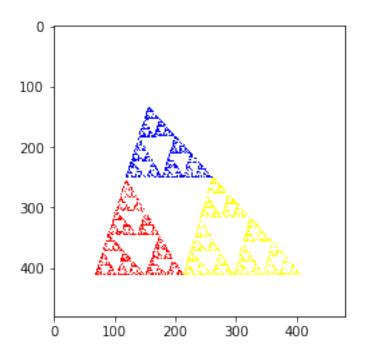
2.1116e-13

2.57e-14

2.30e-03

2.74e-07

Current image:



141 Current image:

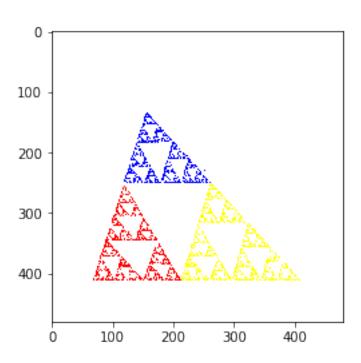
151

1.7021e-13

4.09e-14

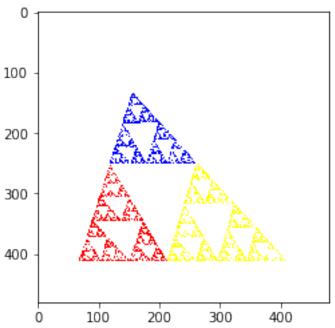
6.08e-04

1.72e-08

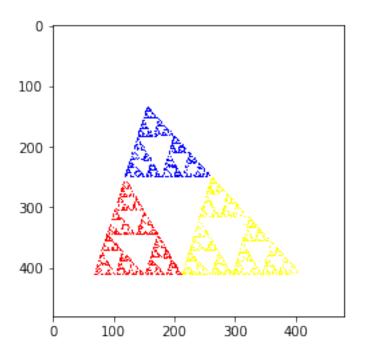


142 152 1.5376e-13 1.65e-14 2.30e-03 2.73e-07

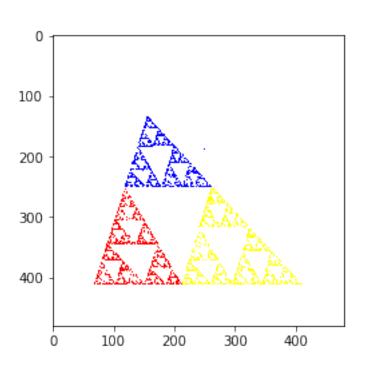
Current image:



143 153 1.1691e-13 3.68e-14 5.01e-04 1.15e-08 Current image:



144 Current image:



1.0902e-13

7.89e-15

2.30e-03

2.73e-07

145 155 7.5357e-14 3.37e-14 4.00e-04 7.22e-09 $\$ gtol $\$ termination condition is satisfied.

Function evaluations 155, initial cost 5.2846e-03, final cost 7.5357e-14, first-order optimali

Out[48]:

