

Image Analysis And Computer Vision
Exercises

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Abstract

The topics of the course are:

- Introduction.
- Camera sensors: transduction, optics, geometry, distortion
- Basics on Projective geometry: modelling basic primitives (points, lines, planes, conic sections, quadric surfaces) and projective spatial transformations and projections.
- Camera geometry, and single view analysis: calibration, image rectification, localization of 3D models.
- Multi-view analysis: 3D shape reconstruction, self-calibration, 3D scene understanding.
- Linear filters and convolutions, space-invariant filters, Fourier Transform, sampling and aliasing.
- Nonlinear filters: image morphology and morphology operators (dilate, erode, open, close), median filters.
- Edge detection and feature detection techniques. feature matching and feature tracking along image sequences.
- Inferring parametric models from noisy data (including outliers), contour segmentation, clustering, Hough Transform, Ransac (random sample consensus).
- Applications: object tracking, object recognition, classification.

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