

Machine Learning *Theory*

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Academic Year 2023-2024

Abstract

The course is composed by a set of lectures on autonomous robotics, ranging from the main architectural patterns in mobile robots and autonomous vehicles to the description of sensing and planning algorithms for autonomous navigation. The course outline is:

- Mobile robots' kinematics.
- Sensors and perception.
- Robot localization and map building.
- Simultaneous Localization and Mapping (SLAM).
- Path planning and collision avoidance.
- Robot development via ROS.

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