

# On some identities involving exponentials

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Based on work done (along the years) with

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## 0. INTRODUCTION

- $A = \begin{pmatrix} 1 & -1 \\ 2 & -2 \end{pmatrix}$
- $Y' = AY, Y(0) = I$
- Solution:  $Y(t) = e^{At}$

$$e^{tA} = \sum_{k \geq 0} \frac{t^k}{k!} A^k = \begin{pmatrix} 2 - e^{-t} & -1 + e^{-t} \\ 2 - 2e^{-t} & -1 + 2e^{-t} \end{pmatrix}$$

- Main object: **exponential** of a matrix
- Basic property of the exponential of a matrix (of dimension  $N \geq 2$ ):

$$e^A e^B \neq e^{A+B} \quad \text{in general} \quad AB \neq BA$$

- Only if  $AB = BA$  it is true that  $e^A e^B = e^{A+B}$ .

# A trivial example

- Consider

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix}$$

- $A$  and  $B$  do not commute:

$$AB = \begin{pmatrix} 2 & 0 \\ 1 & 0 \end{pmatrix} \quad \text{and} \quad BA = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

- Hence we have

$$e^A = \begin{pmatrix} e & e \\ 0 & e \end{pmatrix} \quad \text{and} \quad e^B = \begin{pmatrix} e & 0 \\ e-1 & 1 \end{pmatrix}$$

# A trivial example

- and

$$e^A e^B = \begin{pmatrix} e & e \\ 0 & e \end{pmatrix} \begin{pmatrix} e & 0 \\ e-1 & 1 \end{pmatrix} = \begin{pmatrix} 2e^2 - e & e \\ e^2 - e & e \end{pmatrix}$$

whereas

$$e^{(A+B)} = e^{3/2} \begin{pmatrix} c + s & 2s \\ 2s & c - s \end{pmatrix}$$

with  $c = \cosh \frac{\sqrt{5}}{2}$ ,  $s = \frac{1}{\sqrt{5}} \sinh \frac{\sqrt{5}}{2}$ .

- Therefore

$$e^A e^B \neq e^{A+B}$$

- Important object: the **commutator**  $[A, B] = AB - BA$

# Problems

- ①  $e^A e^B = e^{A+B+C}$
- ②  $e^{A+B} = e^A e^B e^{C_1} e^{C_2} \dots$
- ③ Given  $Y' = A(t)Y$ ,  $Y(0) = I$ , with  $A(t)$  a  $N \times N$  matrix,
  - $N = 1$ :  $Y(t) = e^{\int_0^t A(s) ds}$
  - $N > 1$ :  $Y(t) = e^{\int_0^t A(s) ds}$  if

$$\left[ A(t), \int_0^t A(s) ds \right] = 0 \quad (\text{Coddington \& Levinson})$$

- General case: can we write  $Y(t) = e^{\Omega(t)}$  with

$$\Omega(t) = \int_0^t A(s) ds + (\text{something else})?$$

Exponential map:

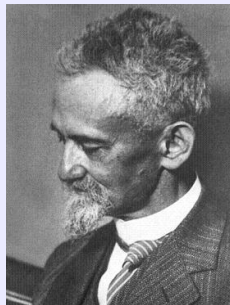
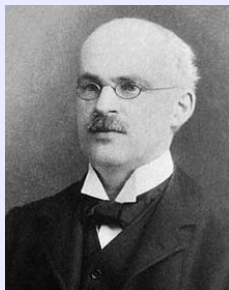
- Fundamental role played by the [exponential transformation](#) in Lie groups and Lie algebras

$$\exp : \mathfrak{g} \longmapsto \mathcal{G}$$

- Kashiwara–Vergne conjecture (with important implicaciones in Lie theory, harmonic analysis, etc.), proved as a theorem in 2006
- Lie groups are ubiquitous in physics: symmetries in classical mechanics, Quantum Mechanics, control theory, etc.

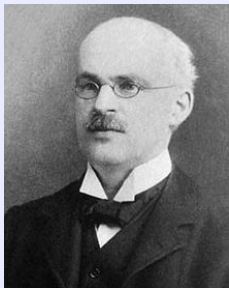




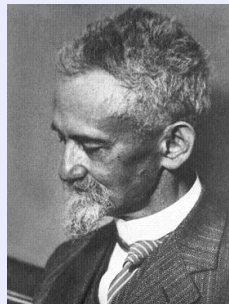




H.F. Baker (1866-1956)

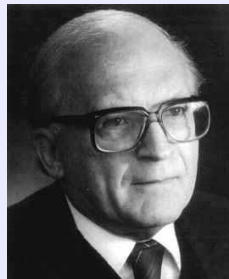


J.E. Campbell (1862-1924)



F. Hausdorff (1868-1942)





E.B. Dynkin (1924-2014)    W. Magnus (1907-1990)    H. Zassenhaus (1912-1991)

# Problems

①  $e^A e^B = e^{A+B+C}$  Baker–Campbell–Hausdorff (BCH) Formula

②  $e^{A+B} = e^A e^B e^{C_1} e^{C_2} \dots$  Zassenhaus Formula

③ Given  $Y' = A(t)Y$ ,  $Y(0) = I$ ,  $A(t)$  a  $N \times N$  matrix,

- $N = 1$ :  $Y(t) = e^{\int_0^t A(s) ds}$
- $N > 1$ :  $Y(t) = e^{\int_0^t A(s) ds}$  if

$$\left[ A(t), \int_0^t A(s) ds \right] = 0$$

- General: can we write  $Y(t) = e^{\Omega(t)}$  with

$$\Omega(t) = \int_0^t A(s) ds + (\text{something else})?$$

Magnus Expansion

These topics have already appeared (several times) at the workshop  
We are mainly concerned by

- **computational aspects**: how to generate *efficiently* the corresponding series
- **Convergence** of the series

Before starting...

- **Lie Product Formula**. Let  $X$  and  $Y$  be  $n \times n$  complex matrices. Then

$$e^{X+Y} = \lim_{m \rightarrow \infty} \left( e^{\frac{X}{m}} e^{\frac{Y}{m}} \right)^m.$$

- A big brother: **Trotter product formula**. The same result when  $X$  and  $Y$  are suitable unbounded operators on an infinite-dimensional Hilbert space.

Many applications in the numerical treatment of PDEs



## II. BCH FORMULA

$$e^X e^Y = e^Z$$

- Let  $X, Y$  be two non commuting operators. Then

$$e^X e^Y = \sum_{p,q=0}^{\infty} \frac{1}{p! q!} X^p Y^q$$

- Substituting this series in the formal series defining the logarithm function

$$\log Z = \sum_{k=1}^{\infty} \frac{(-1)^{k-1}}{k} (Z - 1)^k$$

one gets

$$Z = \log(e^X e^Y) = \sum_{k=1}^{\infty} \frac{(-1)^{k-1}}{k} \sum \frac{X^{p_1} Y^{q_1} \dots X^{p_k} Y^{q_k}}{p_1! q_1! \dots p_k! q_k!},$$

- The inner summations extends over all non-negative integers  $p_1, q_1, \dots, p_k, q_k$  for which  $p_i + q_i > 0$  ( $i = 1, 2, \dots, k$ ).

- First terms:

$$\begin{aligned}
 Z &= (X + Y + XY + \frac{1}{2}X^2 + \frac{1}{2}Y^2 + \dots) \\
 &\quad - \frac{1}{2}(XY + YX + X^2 + Y^2 + \dots) + \dots \\
 &= X + Y + \frac{1}{2}(XY - YX) + \dots = X + Y + \frac{1}{2}[X, Y] + \dots
 \end{aligned}$$

- Baker, Campbell, Hausdorff analyzed whether  $Z$  can be written as a series only in terms of (nested) commutators
- The answer is yes, but they weren't able to provide a rigorous proof
- Bourbaki: "*chacun considère que les démonstrations de ses prédécesseurs ne sont pas convaincantes*"
- Finally, Dynkin (1947): explicit formula for  $Z$ .
- Sometimes it is called BCH-D (for Dynkin) formula (Bonfiglioli & Fulci)

- Dynkin:

$$Z = \sum_{k=1}^{\infty} \sum_{p_i, q_i} \frac{(-1)^{k-1}}{k} \frac{[X^{p_1} Y^{q_1} \dots X^{p_k} Y^{q_k}]}{(\sum_{i=1}^k (p_i + q_i)) p_1! q_1! \dots p_k! q_k!} \quad (1)$$

- Inner summation over all non-negative integers  $p_1, q_1, \dots, p_k, q_k$  for which  $p_1 + q_1 > 0, \dots, p_k + q_k > 0$
- $[X^{p_1} Y^{q_1} \dots X^{p_k} Y^{q_k}]$  denotes the right nested commutator based on the *word*  $X^{p_1} Y^{q_1} \dots X^{p_k} Y^{q_k}$ :

$$[XY^2X^2Y] \equiv [X, [Y, [Y, [X, [X, Y]]]]$$

- Gathering terms together

$$Z = \log(e^X e^Y) = X + Y + \sum_{m=2}^{\infty} Z_m, \quad (2)$$

- $Z_m(X, Y)$ : homogeneous Lie polynomial in  $X, Y$  of degree  $m$ , i.e., a  $\mathbb{Q}$ -linear combination of commutators of the form  $[V_1, [V_2, \dots, [V_{m-1}, V_m] \dots]]$  with  $V_i \in \{X, Y\}$  for  $1 \leq i \leq m$ .

# First terms

$$Z_2 = \frac{1}{2}[X, Y]$$

$$Z_3 = \frac{1}{12}[X, [X, Y]] - \frac{1}{12}[Y, [X, Y]]$$

$$Z_4 = -\frac{1}{24}[Y, [X, [X, Y]]]$$

$$\begin{aligned} Z_5 = & \frac{1}{720}[X, [X, [X, [X, Y]]]] - \frac{1}{180}[Y, [X, [X, [X, Y]]]] \\ & + \frac{1}{180}[Y, [Y, [X, [X, Y]]]] + \frac{1}{720}[Y, [Y, [Y, [X, Y]]]] \\ & - \frac{1}{120}[[X, Y], [X, [X, Y]]] - \frac{1}{360}[[X, Y], [Y, [X, Y]]] \end{aligned}$$

Fundamental role in different fields:

- Mathematics: theory of linear differential equations, Lie groups, numerical analysis of differential equations
- Theoretical Physics: perturbation theory, quantum mechanics, statistical mechanics, quantum computing
- Control theory: design and analysis of nonlinear control mechanisms, nonlinear filters, stabilization of rigid bodies,...

## Quantum Mechanics

- $i\hbar\dot{U} = HU(t)$ ,  $U(t_0) = I$ , so that  $\psi(t) = U(t)\psi_0$
- $H(t) = K + V = -\frac{\hbar^2}{2m}p^2 + V$
- Solution:  $U(t) = e^{-iHt/\hbar}$ .
- Very often, computing  $e^{-iKt/\hbar}$ ,  $e^{-iVt/\hbar}$  is easier

# Applications

## Quantum Monte Carlo methods

- Partition function

$$Z = \text{Tr}(e^{-\beta H}) = \sum_{\alpha} \langle \alpha | e^{-\beta H} | \alpha \rangle,$$

for the orthogonal complete set of states  $|\alpha\rangle$ . Here  $\beta = 1/T$  and  $H = K + V$

- All practical implementations intended for Monte Carlo estimations of  $Z$  rely on approximating

$$e^{-\beta(K+V)} = \left( e^{-\varepsilon(K+V)} \right)^M,$$

with  $\varepsilon = \beta/M$  and  $M$  is the number of convolution terms (*beads*).

- Product of exponentials

$$e^{-\varepsilon(K+V)} \simeq \prod_{i=1}^m e^{-a_i \varepsilon K} e^{-b_i \varepsilon V}$$



- **Lie groups theory:** Lie algebra  $\leftrightarrow$  Lie group. Multiplication law in the group is determined uniquely by the Lie algebra structure, at least in a neighborhood of the identity
- Helpful also to prove the existence of a local Lie group with a given Lie algebra
- The particular structure of the series is not very important in this setting...
- ...But in other fields it *is* relevant to analyze the combinatorial aspects and its efficient computation

- **Lie groups theory:** Lie algebra  $\leftrightarrow$  Lie group. Multiplication law in the group is determined uniquely by the Lie algebra structure, at least in a neighborhood of the identity
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# Example

- Splitting and composition methods

$$\dot{u} = F(u) = A(u) + B(u), \quad u(0) = u_0$$

- Flows of  $A(u)$  and  $B(u)$ ,  $e^{tA}$ ,  $e^{tB}$  can be obtained explicitly
- Approximation (for  $t = h$ , the time step)

$$\Psi_h \equiv \exp(ha_1A) \exp(hb_1B) \cdots \exp(ha_kA) \exp(hb_kB)$$

- **Order conditions** to be satisfied by  $a_i$ ,  $b_i$  so that

$$\Psi_h \equiv \exp(ha_1A) \exp(hb_1B) \cdots \exp(ha_kA) \exp(hb_kB)$$

verifies  $\Psi_h(u_0) = u(h) + \mathcal{O}(h^{r+1})$  when  $h \rightarrow 0$ .

- They are obtained by applying BCH in sequence:

$$\Psi_h = \exp(p_{1,1}A + p_{1,2}B + p_{2,1}[A, B] + \cdots)$$

with  $p_{i,j}$  polynomials in  $a_i$ ,  $b_i$ .

- $p_{1,1} = p_{1,2} = 1$ ,  $p_{2,1} = 0$ , etc.

# How to obtain the BCH formula

- Different procedures in the literature:
  - **Goldberg form** + Dynkin (Specht-Wever) theorem (**explicit**)

$$Z = X + Y + \sum_{n=2}^{\infty} \frac{1}{n} \sum_{w, |w|=n} g_w [w], \quad (3)$$

with  $w = w_1 w_2 \dots w_n$ , each  $w_i$  is  $X$  or  $Y$ ,  
 $[w] = [w_1, [w_2, \dots [w_{n-1}, w_n] \dots]]$ , the coefficient  $g_w$  is a rational number and  $n$  is the word length.

- **Varadarajan** (**recursive**)

$$Z_1 = X + Y \quad (4)$$

$$(n+1)Z_{n+1} = \frac{1}{2}[X - Y, Z_n] + \sum_{p=1}^{[n/2]} \frac{B_{2p}}{(2p)!} \sum [Z_{k_1}, [\dots [Z_{k_{2p}}, X + Y] \dots]], \quad n \geq 1$$

Second sum: over all positive integers such that  
 $k_1 + \dots + k_{2p} = n$

- *Diffman* (Trondheim-Bergen). Matlab toolbox for computations in a free Lie algebra.
- The computation of the BCH formula is carried out in *Diffman* by integrating numerically

$$Z' = d \exp_Z^{-1}(X) \equiv \sum_{k=1}^{\infty} \frac{B_k}{k!} \operatorname{ad}_Z^k X, \quad Z(0) = Y$$

from  $t = 0$  to  $t = 1$  using a single step of a Runge–Kutta method. ( $e^{Z(t)} = e^{tX} e^Y$ )

- Koseleff (1993): explicit expression in the Lyndon basis up to  $n = 10$  *by using only manipulations of Lie polynomials*, without resorting to the associative algebra

- Reinsch (2000): Simple derivation with matrices of rational numbers. Mathematica program. The expression is *not* written in terms of commutators
- A recent (much simpler) modification in 2015
- *Lie Tools Package (LTP)* (Torres-Torriti & Michalska, 2003).
  - Package in Maple for carrying out Lie algebraic symbolic computations.
  - Special function for the computation of BCH formula in the Dynkin form in terms of Lie monomials in the Hall basis.
  - Reported results in 2003: up to order 10 in 25 hours with maximum memory usage of 17.5 Mbytes on a Pentium III, 550 MHz, 256 Mbytes RAM, Maple 7, Linux

# Bottleneck in the computation

- The iterated commutators are not all linearly independent, due to the Jacobi identity

$$[X_1, [X_2, X_3]] + [X_2, [X_3, X_1]] + [X_3, [X_1, X_2]] = 0$$

(and other identities involving nested commutators of higher degree originated by it)

- All the previous expressions for the BCH series are *not* formulated directly in terms of a basis of the free Lie algebra  $\mathcal{L}(X, Y)$
- Problematic when designing numerical integrators for ODEs (*one condition per element in the basis*)
- Very difficult to study specific properties of the series: distribution of coefficients, combinatorial properties, etc.

- It is possible to rewrite the formulas in terms of a basis of  $\mathcal{L}(X, Y)$ , but this process is very time consuming and requires lots of memory resources
- The complexity grows exponentially with  $m$ : the number of terms involved in the series grows as the dimension  $c_m$  of the homogeneous subspace  $\mathcal{L}(X, Y)_m$
- $c_m = \mathcal{O}(2^m/m)$  (Witt's formula)



- To express the BCH series as

$$Z = \log(\exp(X)\exp(Y)) = \sum_{i \geq 1} z_i E_i, \quad (5)$$

where  $z_i \in \mathbb{Q}$  ( $i \geq 1$ ) and  $\{E_i : i = 1, 2, 3, \dots\}$  is a basis of  $\mathcal{L}(X, Y)$  whose elements are of the form

$$E_1 = X, \quad E_2 = Y, \quad \text{and} \quad E_i = [E_{i'}, E_{i''}] \quad i \geq 3, \quad (6)$$

for appropriate values of the integers  $i', i'' < i$  ( $i = 3, 4, \dots$ ).

- In particular: classical Hall basis, Lyndon basis
- Design an efficient algorithm
- Analyze the series (coefficients, convergence)

# Summary of the algorithm

- Starting point: vector space  $\mathfrak{g}$  of maps  $\alpha : \mathcal{T} \rightarrow \mathbb{R}$
- $\mathcal{T}$ : set of rooted trees with black and white vertices

$$\mathcal{T} = \left\{ \bullet, \circ, \begin{array}{c} \bullet \\ | \\ \bullet \end{array}, \begin{array}{c} \circ \\ | \\ \bullet \end{array}, \begin{array}{c} \bullet \\ | \\ \circ \end{array}, \begin{array}{c} \circ \\ | \\ \circ \end{array}, \begin{array}{c} \bullet \quad \bullet \\ \diagdown \quad \diagup \\ \bullet \end{array}, \begin{array}{c} \bullet \quad \circ \\ \diagdown \quad \diagup \\ \bullet \end{array}, \begin{array}{c} \circ \quad \bullet \\ \diagdown \quad \diagup \\ \bullet \end{array}, \begin{array}{c} \circ \quad \circ \\ \diagdown \quad \diagup \\ \bullet \end{array}, \dots, \right. \\ \left. \begin{array}{c} \bullet \quad \bullet \\ \diagdown \quad \diagup \\ \bullet \end{array}, \begin{array}{c} \bullet \quad \circ \\ \diagdown \quad \diagup \\ \bullet \end{array}, \begin{array}{c} \circ \quad \circ \\ \diagdown \quad \diagup \\ \bullet \end{array}, \begin{array}{c} \bullet \quad \bullet \\ \diagdown \quad \diagup \\ \circ \end{array}, \dots \right\}.$$

- $\mathcal{T}$  is typically referred to as the set of labeled rooted trees with two labels, 'black' and 'white'.
- elements of  $\mathcal{T}$ : bicoloured rooted trees.

- $\mathfrak{g}$  is endowed with a Lie algebra structure by defining the Lie bracket  $[\alpha, \beta] \in \mathfrak{g}$ , of two arbitrary maps  $\alpha, \beta \in \mathfrak{g}$  as
- For each  $u \in \mathcal{T}$ ,

$$[\alpha, \beta](u) = \sum_{j=1}^{|u|-1} (\alpha(u_{(j)})\beta(u^{(j)}) - \alpha(u^{(j)})\beta(u_{(j)})), \quad (7)$$

- $|u|$  denotes the number vertices of  $u$
- each of the pairs of trees  $(u_{(j)}, u^{(j)}) \in \mathcal{T} \times \mathcal{T}$ ,  $j = 1, \dots, |u| - 1$ , is obtained from  $u$  by removing one of the  $|u| - 1$  edges of the rooted tree  $u$ , the root of  $u_{(j)}$  being the original root of  $u$ .

- For instance

$$\begin{aligned} [\alpha, \beta](\text{hook}) &= \alpha(\text{circle})\beta(\text{dot}) - \alpha(\text{dot})\beta(\text{circle}), \quad [\alpha, \beta](\text{cup}) = 0 \\ [\alpha, \beta](\text{cap}) &= 2(\alpha(\text{hook})\beta(\text{dot}) - \alpha(\text{dot})\beta(\text{hook})) \\ [\alpha, \beta](\text{cross}) &= \alpha(\text{cup})\beta(\text{dot}) + \alpha(\text{hook})\beta(\text{circle}) \\ &\quad - \alpha(\text{dot})\beta(\text{cup}) - \alpha(\text{circle})\beta(\text{hook}) \end{aligned}$$

- The Lie subalgebra of  $\mathfrak{g}$  generated by the maps  $X, Y \in \mathfrak{g}$  defined as

$$X(u) = \begin{cases} 1 & \text{if } u = \bullet \\ 0 & \text{if } u \in \mathcal{T} \setminus \{\bullet\} \end{cases}, \quad Y(u) = \begin{cases} 1 & \text{if } u = \circ \\ 0 & \text{if } u \in \mathcal{T} \setminus \{\circ\} \end{cases}$$

is a free Lie algebra over the set  $\{X, Y\}$

- $\mathcal{L}(X, Y)$ : Lie subalgebra of  $\mathfrak{g}$  generated by the maps  $X$  and  $Y$ .

- For each particular Hall–Viennot basis  $\{E_i : i = 1, 2, 3, \dots\}$ , and  $X$  and  $Y$  as above, *one can associate a bicoloured rooted tree  $u_i$  to each element  $E_i$  such that, for any map  $\alpha \in \mathcal{L}(X, Y)$ ,*

$$\alpha = \sum_{i \geq 1} \frac{\alpha(u_i)}{\sigma(u_i)} E_i, \quad (9)$$

- For each  $i$ ,  $\sigma(u_i)$  is certain positive integer associated to the bicoloured rooted tree  $u_i$  (the number of symmetries of  $u_i$ )
- if  $\alpha \in \mathcal{L}(X, Y)$ , then its projection  $\alpha_n$  to the homogeneous subspace  $\mathcal{L}(X, Y)_n$  is given by

$$\alpha_n(u) = \begin{cases} \alpha(u) & \text{if } |u| = n \\ 0 & \text{otherwise} \end{cases} \quad (10)$$

for each  $u \in \mathcal{T}$ .

- Lie series:

$$\alpha = \alpha_1 + \alpha_2 + \alpha_3 + \cdots, \quad \text{where } \alpha_n \in \mathcal{L}(X, Y)_n.$$

- A map  $\alpha \in \mathfrak{g}$  is then a Lie series if and only if (9) holds
- The corresponding BCH series *is* a Lie series

$$\begin{aligned} Z &= \sum_{i \geq 1} z_i E_i = \sum_{i \geq 1} \frac{Z(u_i)}{\sigma(u_i)} E_i \\ &= Z(\bullet)X + Z(\circ)Y + Z(\bullet \circ)[Y, X] \\ &\quad + \frac{Z(\bullet \circ \bullet)}{2} [[Y, X], X] + Z(\bullet \circ \circ)[[Y, X], Y] + \cdots, \end{aligned}$$

- The coefficients  $Z(u_i)$  can be determined by recursive procedures for BCH (Varadarajan)

In summary:

- Construct algorithmically a sequence of labeled rooted trees in a one-to-one correspondence with a Hall basis
- In addition, they must verify

$$\alpha = \sum_{i \geq 1} \frac{\alpha(u_i)}{\sigma(u_i)} E_i,$$

- In this way, one can build Lie series
- In particular, the BCH series
- A very efficient algorithm written in Mathematica allows us to get the BCH series up to a prescribed value of  $m$  in the Hall and Lyndon basis

# Some results

- Comparison:
  - with the best previous algorithm: 17.5 MBytes up to  $m = 10$ .
  - ours: 5.4 MBytes
- In less than 15 min. of CPU (2008) and 1.5 GBytes we get up to  $m = 20$
- 109697 non vanishing terms out of 111013 elements  $E_i$  of grade  $|i| \leq 20$  in the Hall basis
- Last element:

$$E_{111013} = \begin{aligned} &[[[[[Y, X], Y], [Y, X]], [[Y, X], X], [Y, X]], \\ &[[[Y, X], Y], [Y, X]], [[[[Y, X], Y], Y], Y]], \end{aligned}$$

with coefficient

$$z_{111013} = -\frac{19234697}{140792940288}.$$



- An observation: In the basis of P. Hall there are 1316 zero coefficients out of 111013 up to degree  $m = 20$ , whereas in the Lyndon basis the number of vanishing terms rises to 34 253 (more than 30% of the total number of coefficients!!)
- More remarkably, one notices that the distribution of these vanishing coefficients in the Lyndon basis follows a very specific pattern
- It is possible to explain this pattern
- In a sense, the Lyndon basis seems the natural choice to get systematically the BCH series with the minimum number of terms
- Variations: symmetric BCH formula

$$e^{\frac{1}{2}X} e^Y e^{\frac{1}{2}X} = e^W$$

## Theorem

(Mityagin) *The Baker–Campbell–Hausdorff series converges absolutely when  $\|X\| + \|Y\| < \pi$ .*

- This result can be generalized to any set  $X_1, X_2, \dots, X_k$  of bounded operators in a Hilbert space  $\mathcal{H}$ :

$$e^{X_1} e^{X_2} \dots e^{X_k} = e^Z$$

converges if

$$\|X_1\| + \|X_2\| + \dots + \|X_k\| < \pi$$

- Optimal bound

# An example

Let

$$X_1 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad X_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

and let  $X = \alpha X_1$ ,  $Y = \beta X_2$ , with  $\alpha, \beta \in \mathbb{C}$ . Then

$$\log(e^X e^Y) = \alpha X_1 + \frac{2\alpha\beta}{1 - e^{-2\alpha}} X_2,$$

analytic function for  $|\alpha| < \pi$  with first singularities at  $\alpha = \pm i\pi$ .  
Then BCH cannot converge if  $|\alpha| \geq \pi$ , independently of  $\beta \neq 0$ .

- From the above theorem: convergence if  $|\alpha| + |\beta| < \pi$
- In the limit  $|\beta| \rightarrow 0$  this result is optimal

## Second example

$$X = \begin{pmatrix} 0 & 0 \\ \alpha & 0 \end{pmatrix}, \quad Y = \begin{pmatrix} 0 & \alpha \\ 0 & 0 \end{pmatrix}$$

with  $\alpha > 0$ . Then

$$e^{\varepsilon X} e^{\varepsilon Y} = \begin{pmatrix} 1 & \alpha \varepsilon \\ \alpha \varepsilon & 1 + \alpha^2 \varepsilon^2 \end{pmatrix} \quad (11)$$

- convergence of the BCH series in this case whenever  $2\alpha|\varepsilon| < \pi$ , or  $|\varepsilon| < \frac{\pi}{2\alpha}$
- conservative estimate since convergence can be shown for  $|\varepsilon| < \frac{2}{\alpha}$

## Numerical check of convergence for $\alpha = 2$

- $Z^{[M]}(\varepsilon) = \sum_{n=1}^N Z_n(\varepsilon)$
- Compute  $E_r(\varepsilon) = \|e^X e^Y e^{-Z^{[M]}(\varepsilon)} - I\|$
- Convergence if  $\varepsilon < 1$
- $\varepsilon = 1/4$ ; with  $N = 10$ ,  $E_r(\varepsilon) \approx 10^{-7}$ . With  $N = 15$ ,  $E_r(\varepsilon) \approx 10^{-10}$
- $\varepsilon = 0.9$ ; to get  $E_r(\varepsilon) \approx 10^{-8}$  we need  $N = 150$ ; with  $N = 200$  then  $E_r(\varepsilon) \approx 10^{-10}$

## Other results on convergence

- The Baker–Campbell–Hausdorff formula expressed as a series of homogeneous Lie polynomials in  $X, Y \in \mathfrak{g}$  (a Banach Lie algebra), converges absolutely in the domain  $D_1 \cup D_2$  of  $\mathfrak{g} \times \mathfrak{g}$ , where

$$D_1 = \left\{ (X, Y) : \mu \|X\| < \int_{\mu \|Y\|}^{2\pi} \frac{1}{g(x)} dx \right\}$$
$$D_2 = \left\{ (X, Y) : \mu \|Y\| < \int_{\mu \|X\|}^{2\pi} \frac{1}{g(x)} dx \right\}$$

and  $g(x) = 2 + \frac{x}{2}(1 - \cot \frac{x}{2})$ . (Michel 1974, F.C. & S. Blanes 2004)

- Biagi & Bonfiglioli 2014: generalization to arbitrary infinite-dimensional Banach-Lie algebras (in particular, without using the exponential map)

### III. ZASSENHAUS FORMULA

# Zassenhaus formula

- In the paper dealing with ME expansion, Magnus (1954) cites an unpublished reference by Zassenhaus, reporting that there exists a formula which may be called the dual of the (Baker–Campbell–)Hausdorff formula. More specifically,

## Theorem

*(Zassenhaus Formula). Let  $\mathcal{L}(X, Y)$  be the free Lie algebra generated by  $X$  and  $Y$ . Then,  $e^{X+Y}$  can be uniquely decomposed as*

$$e^{X+Y} = e^X e^Y \prod_{n=2}^{\infty} e^{C_n(X,Y)} = e^X e^Y e^{C_2(X,Y)} \dots e^{C_n(X,Y)} \dots ,$$

*where  $C_n(X, Y) \in \mathcal{L}(X, Y)$  is a homogeneous Lie polynomial in  $X$  and  $Y$  of degree  $n$ .*



# Zassenhaus formula

- The existence of this formula is an immediate consequence of the BCH theorem.
- By comparing with the BCH formula it is possible to obtain the first terms as

$$C_2(X, Y) = -\frac{1}{2}[X, Y], \quad C_3(X, Y) = \frac{1}{3}[Y, [X, Y]] + \frac{1}{6}[X, [X, Y]].$$

- Less familiar than the BCH formula but still important in several fields: statistical mechanics, many-body theories, quantum optics, path integrals,  $q$ -analysis in quantum groups, particle accelerators physics, etc.
- Numerical analysis: Iserles *et al.*, 2014.
- Again, two important aspects: *efficient computation* and *convergence* of the formula.

# Some (brief) history

- Several systematic computations of the terms  $C_n$  for  $n > 3$  have been carried out in the literature: Wilcox (1967), Volkin (1968), Suzuki (1976), Baues (1980). All of them give results for  $C_n$  as a linear combination of nested commutators.
- Scholz and Weyrauch (2006): recursive procedure based on upper triangular matrices.
- Weyrauch and Scholz (2009):  $C_n$  up to  $n = 15$  in less than 2 minutes (with another procedure)
- Now

$$C_n = \sum_{w, |w|=n} g_w w, \quad (12)$$

where  $g_w$  is a rational coefficient and the sum is taken over all words  $w$  with length  $|w| = n$  in the symbols  $X$  and  $Y$ , i.e.,  $w = a_1 a_2 \cdots a_n$ , each  $a_i$  being  $X$  or  $Y$ .

- Applying Dynkin–Specht–Wever theorem it is possible to express them in terms of commutators, but in a way that there are redundancies

# Our contribution

- To present a new recurrence that allows one to express the Zassenhaus terms  $C_n$  up to a prescribed degree directly in terms of independent commutators involving  $n$  operators  $X$  and  $Y$ .
- We are able to express directly  $C_n$  with the minimum number of commutators required at each degree  $n$ .
- We obtain sharper bounds for the terms of the Zassenhaus formula which show that the product converges in a larger domain than previous results.

# A new recurrence

- We introduce a parameter  $\lambda$ ,

$$e^{\lambda(X+Y)} = e^{\lambda X} e^{\lambda Y} e^{\lambda^2 C_2} e^{\lambda^3 C_3} e^{\lambda^4 C_4} \dots \quad (13)$$

so that the original Zassenhaus formula is recovered when  $\lambda = 1$ .

- Consider the compositions

$$R_1(\lambda) = e^{-\lambda Y} e^{-\lambda X} e^{\lambda(X+Y)} \quad (14)$$

and for each  $n \geq 2$ ,

$$R_n(\lambda) = e^{-\lambda^n C_n} \dots e^{-\lambda^2 C_2} e^{-\lambda Y} e^{-\lambda X} e^{\lambda(X+Y)} = e^{-\lambda^n C_n} R_{n-1}(\lambda).$$

Then,

$$R_n(\lambda) = e^{\lambda^{n+1} C_{n+1}} e^{\lambda^{n+2} C_{n+2}} \dots$$

- Finally,

$$F_n(\lambda) \equiv \left( \frac{d}{d\lambda} R_n(\lambda) \right) R_n(\lambda)^{-1}, \quad n \geq 1. \quad (15)$$

- We have for  $n \geq 1$

$$F_{n+1}(\lambda) = e^{-\lambda^{n+1} \text{ad}_{C_{n+1}}} G_{n+1}(\lambda), \quad (16)$$

$$C_{n+1} = \frac{1}{(n+1)!} F_n^{(n)}(0), \quad (17)$$

$$G_{n+1}(\lambda) = F_n(\lambda) - \frac{\lambda^n}{n!} F_n^{(n)}(0). \quad (18)$$

Expressions (16)–(18) allow one to compute recursively the Zassenhaus terms  $C_n$  starting from  $F_1(\lambda)$ . The sequence is

$$F_n(\lambda) \longrightarrow C_{n+1} \longrightarrow G_{n+1}(\lambda) \longrightarrow F_{n+1}(\lambda) \longrightarrow \dots$$

- For  $n = 1$ ,

$$F_1(\lambda) = e^{-\lambda \operatorname{ad}_Y} (e^{-\lambda \operatorname{ad}_X} - I) Y,$$

that is,

$$F_1(\lambda) = \sum_{i=0}^{\infty} \sum_{j=1}^{\infty} \frac{(-\lambda)^{i+j}}{i!j!} \operatorname{ad}_Y^i \operatorname{ad}_X^j Y \quad (19)$$

or equivalently

$$F_1(\lambda) = \sum_{k=1}^{\infty} f_{1,k} \lambda^k, \quad \text{with} \quad f_{1,k} = \sum_{j=1}^k \frac{(-1)^k}{j!(k-j)!} \operatorname{ad}_Y^{k-j} \operatorname{ad}_X^j Y. \quad (20)$$

- In general ( $n \geq 2$ ),

$$F_n(\lambda) = \sum_{k=n}^{\infty} f_{n,k} \lambda^k, \quad \text{with} \quad f_{n,k} = \sum_{j=0}^{[k/n]-1} \frac{(-1)^j}{j!} \operatorname{ad}_{C_n}^j f_{n-1,k-nj}, \quad (21)$$

- It turns out that

$$F_n(\lambda) = \sum_{k=n+1}^{2n+2} k C_k \lambda^{k-1} + \lambda^{2n+2} H_n(\lambda)$$

where  $H_n(\lambda)$  involves commutators of  $C_j$ ,  $j \geq n+1$

- Notice that the terms  $C_{n+1}, \dots, C_{2n+2}$  of the Zassenhaus formula can be then directly obtained from  $F_n(\lambda)$ .
- In particular,

$$C_{n+1} = \frac{1}{n+1} f_{1,n} = \frac{1}{n+1} \sum_{i=0}^{n-1} \frac{(-1)^n}{i!(n-j)!} \text{ad}_Y^i \text{ad}_X^{n-j} Y, \quad (22)$$

for  $n = 1, 2, 3$ , and

$$C_{n+1} = \frac{1}{n+1} f_{[n/2],n} \quad n \geq 5, \quad (23)$$

$$\begin{aligned}
 &\text{Define } f_{1,k} = \sum_{j=1}^k \frac{(-1)^k}{j!(k-j)!} \text{ad}_Y^{k-j} \text{ad}_X^j Y \\
 &C_2 = (1/2) f_{1,1} \\
 &\text{Define } f_{n,k} \quad n \geq 2, k \geq n \text{ by :} \\
 &f_{n,k} = \sum_{j=0}^{[k/n]-1} \frac{(-1)^j}{j!} \text{ad}_{C_n}^j f_{n-1,k-nj} \\
 &C_n = (1/n) f_{[(n-1)/2], n-1} \quad n \geq 3.
 \end{aligned} \tag{24}$$

- Important property: it provides expressions for  $C_n$  that, by construction, involve only independent commutators. In other words, they cannot be simplified further by using the Jacobi identity and the antisymmetry property of the commutator.
- This can be easily proved by repeated application of the Lazard elimination principle.



# Computational aspects

- The algorithm can be easily implemented in a symbolic algebra package. We need to define an object inheriting only the linearity property of the commutator, the adjoint operator and the functions  $f_{n,k}$  and  $C_n$ .
- We have expressions of  $C_n$  up to  $n = 20$  with a reasonable computational time and memory requirements (35 MB).

$n$	CPU time (seconds)		Memory (MB)	
	<i>W-S</i>	<i>New</i>	<i>W-S</i>	<i>New</i>
14	29.18	0.14	122.90	0.88
16	203.85	0.59	764.32	4.09
18		3.01		11.12
20		19.18		35.27

- $C_{16}$  has 54146 terms when expressed as combinations of words, but only 3711 terms with the new formulation

# Algorithm

```
Clear[Cmt, ad, ff, cc];
$RecursionLimit= 1024;
Cmt[a_, a_] := 0;
Cmt[a___, 0, b___] := 0;
Cmt[a___, c_ + d_, b___] := Cmt[a, c, b] + Cmt[a, d, b];
Cmt[a___, n_ c_Cmt, b___] := n Cmt[a, c, b];
Cmt[a___, n_ X, b___] := n Cmt[a, X, b];
Cmt[a___, n_ Y, b___] := n Cmt[a, Y, b];
Cmt /: Format[Cmt[a_, b_]] := SequenceForm["[", a, ",", b, "]"];

ad[a_, 0, b_] := b;
ad[a_, j_Integer, b_] := Cmt[a, ad[a, j-1, b]];
ff[1, k_] := ff[1, k] =
  Sum[((-1)^k/(j! (k-j)!)) ad[Y, k-j, ad[X, j, Y]], {j, 1, k}];
cc[2] = (1/2) ff[1, 1];
ff[p_, k_] := ff[p, k] =
  Sum[((-1)^j/j!) ad[cc[p], j, ff[p-1, k - p j]], {j, 0,
    IntegerPart[k/p] - 1}];
cc[p_Integer] := cc[p] =
  Expand[(1/p) ff[IntegerPart[(p-1)/2], p-1]];
```

# Convergence

- Suppose now that  $X$  and  $Y$  are defined in a Banach algebra  $\mathcal{A}$
- Then it makes sense to analyze the convergence of the Zassenhaus formula.
- Only two previous results establishing sufficient conditions for convergence of the form  $\|X\| + \|Y\| < r$  with a given  $r > 0$ .
- Suzuki (1976):  $r_s = \log 2 - \frac{1}{2} \approx 0.1931$
- Bayen (1979):  $r_b$  given by the unique positive solution of the equation

$$z^2 \left( 1 + 2 \int_0^z \frac{e^{2w} - 1}{w} dw \right) = 4(2 \log 2 - 1).$$

Numerically,  $r_b = 0.59670569 \dots$

- Thus, for  $\|X\| + \|Y\| < r_b$  one has

$$\lim_{n \rightarrow \infty} e^X e^Y e^{C_2} \dots e^{C_n} = e^{X+Y}. \quad (25)$$

# Our treatment

- Next we use recursion (16)–(18) to show that it converges for  $(x, y) \equiv (\|X\|, \|Y\|) \in \mathbb{R}^2$  in a domain that is larger than  $\{(x, y) \in \mathbb{R}^2 : 0 \leq x + y < r_b\}$ .
- There is convergence if  $\lim_{n \rightarrow \infty} \|R_n(1)\| = 1$ .
- But  $R_n(\lambda)$  is also the solution of

$$\frac{d}{d\lambda} R_n(\lambda) = F_n(\lambda) R_n(\lambda), \quad R_n(0) = I. \quad (26)$$

- If  $\int_0^1 \|F_n(\lambda)\| d\lambda < \infty$ , then there exists a unique solution  $R_n(\lambda)$  of (26) for  $0 \leq \lambda \leq 1$ , and  $\|R_n(1)\| \leq \exp(\int_0^1 \|F_n(\lambda)\| d\lambda)$
- In consequence, convergence is guaranteed whenever  $(x, y) = (\|X\|, \|Y\|) \in \mathbb{R}^2$  is such that

$$\lim_{n \rightarrow \infty} \int_0^1 \|F_n(\lambda)\| d\lambda = 0.$$

- We have that  $\|C_{n+1}\| \leq \delta_{n+1}$ , where  $\delta_2 = x y$  and for  $n \geq 2$ ,

$$\delta_{n+1} = \frac{1}{n+1} \sum_{(i_0, i_1, \dots, i_n) \in \mathcal{I}_n} \frac{2^{i_0 + \dots + i_n}}{i_0! i_1! \dots i_n!} \delta_n^{i_n} \dots \delta_2^{i_2} y^{i_1} x^{i_0} y.$$

- Similarly,  $\|F_n(\lambda)\| \leq f_n(\lambda)$  and

$$\int_0^1 f_n(\lambda) d\lambda \leq \sum_{k=n}^{\infty} \delta_k,$$

- Then,  $\lim_{n \rightarrow \infty} \|R_n(1)\| = 1$  if the series  $\sum_{k=2}^{\infty} \delta_k$  converges.
- Let's analyze each term in this series...

- We get from our recurrence

$$\|f_{1,k}\| \leq d_{1,k} \equiv 2^k y \sum_{j=1}^k \frac{1}{j!(k-j)!} x^j y^{k-j} = \frac{2^k}{k!} y ((x+y)^k - y^k)$$

$$\|f_{n,k}\| \leq d_{n,k} = \sum_{j=0}^{[k/n]-1} \frac{2^j}{j!} \delta_n^j d_{n-1,k-nj} \quad (27)$$

- Therefore

$$\|C_n\| \leq \delta_n = \frac{1}{n} d_{[(n-1)/2], n-1}, \quad n \geq 3.$$

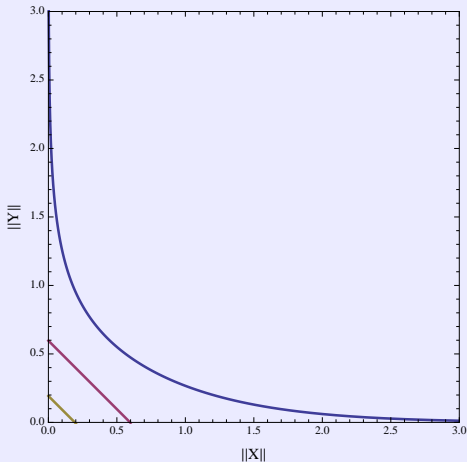
- A sufficient condition for convergence is obtained by imposing

$$\lim_{n \rightarrow \infty} \frac{\delta_{n+1}}{\delta_n} < 1. \quad (28)$$

- Recall that both  $d_{n,k}$  and  $\delta_n$  depend on  $(x, y) = (\|X\|, \|Y\|)$ , so condition (28) implies a constraint on the convergence domain  $(x, y) \in \mathbb{R}^2$

# Convergence domain

Computing numerically for each point the coefficients  $d_{n,k}$  and  $\delta_n$  up to  $n = 1000$  we get



# Example

$$X = \alpha \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \quad \text{and} \quad Y = \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix}$$

- Compute  $R_1 = e^{-Y}e^{-X}e^{X+Y}$
- Compute  $R_2(m) = e^{C_2}e^{C_3} \dots e^{C_m}$
- Finally  $E_m = \|R_1 - R_2(m)\|$
- Particular case:  $\alpha = 0.2$ . Then we are outside the guaranteed domain of convergence
- $m = 10$ ,  $E_{10} \approx 1.3345 \cdot 10^{-4}$
- $m = 15$ ,  $E_{15} \approx 1.9180 \cdot 10^{-6}$
- $m = 20$ ,  $E_{20} \approx 4.7958 \cdot 10^{-9}$



# Generalization

- Sometimes one has to deal with

$$\exp(\lambda A_1 + \lambda^2 A_2 + \cdots + \lambda^n A_n + \cdots)$$

with  $A_k$  non-commuting operators

- In that case it is still possible to generalize the expansion and to get

$$e^{\lambda A_1 + \lambda^2 A_2 + \cdots} = e^{\lambda C_1} e^{\lambda^2 C_2} \cdots e^{\lambda^n C_n} \cdots$$

- Recursive procedure to obtain  $C_k$

## IV. MAGNUS EXPANSION

# General linear differential equation

## Goal

Given the matrix  $A(t)$   $N \times N$ , solve the initial value problem

$$Y'(t) = A(t)Y(t), \quad Y(t_0) = Y_0. \quad (29)$$

- If  $N = 1$ , the solution reads

$$Y(t) = \exp\left(\int_{t_0}^t A(s)ds\right) Y_0. \quad (30)$$

- This is also valid when  $N > 1$  if  $[A(t), \int_0^t A(s)ds] = 0$ .  
Particular case:  $A(t_1)A(t_2) = A(t_2)A(t_1)$  for all  $t_1$  y  $t_2$ . In particular, when  $A$  is constant.
- In general, (30) is *not* the solution

- Typical procedure (Neumann, Dyson):

$$Y(t) = \int_{t_0}^t A(s)ds + \int_{t_0}^t A(s_1) \int_{t_0}^{s_1} A(s_2)ds_2 ds_1 + \cdots$$

- Magnus (1954): construct  $Y(t)$  as a genuine *exponential representation*
- Motivation: problems arising in Quantum Mechanics (in this way, unitary is preserved, and is essential in QM)

# Magnus expansion

- [W. Magnus](#) proposal: to express the solution as the exponential of a certain matrix function  $\Omega(t, t_0)$ ,

$$Y(t) = \exp \Omega(t, t_0) Y_0 \quad (31)$$

- $\Omega$  is built as a series expansion

$$\Omega(t) = \sum_{k=1}^{\infty} \Omega_k(t). \quad (32)$$

- For simplicity,  $\Omega(t) \equiv \Omega(t, t_0)$  y  $t_0 = 0$ .

- First terms:

$$\begin{aligned}
 \Omega_1(t) &= \int_0^t A(t_1) dt_1, \\
 \Omega_2(t) &= \frac{1}{2} \int_0^t dt_1 \int_0^{t_1} dt_2 [A(t_1), A(t_2)] \\
 \Omega_3(t) &= \frac{1}{6} \int_0^t dt_1 \int_0^{t_1} dt_2 \int_0^{t_2} dt_3 ([A(t_1), [A(t_2), A(t_3)]] + \\
 &\quad [A(t_3), [A(t_2), A(t_1)]])
 \end{aligned} \tag{33}$$

$$[A, B] \equiv AB - BA$$

- $\Omega_1(t)$  is exactly the exponent in the scalar case
- If we insist in keeping an exponential representation for  $Y(t)$ , then the exponent must be corrected
- The rest of the series (32) accounts for this correction

# How the series is obtained?

- Insert  $Y(t) = \exp \Omega(t)$  in  $Y' = A(t)Y$ ,  $Y(0) = I$
- Differential equation satisfied by  $\Omega$ :

$$\frac{d\Omega}{dt} = \sum_{n=0}^{\infty} \frac{B_n}{n!} \operatorname{ad}_{\Omega}^n A, \quad (34)$$

where  $\operatorname{ad}_{\Omega}^0 A = A$ ,  $\operatorname{ad}_{\Omega}^{k+1} A = [\Omega, \operatorname{ad}_{\Omega}^k A]$ ,  
and  $B_j$  are the Bernoulli number.

- At first sight, a very bad idea!: we replace a *linear* differential equation by another which is *highly nonlinear*!
- ... But this is defined for  $\Omega$

- We apply Picard's iteration:

$$\Omega^{[0]} = O, \quad \Omega^{[1]} = \int_0^t A(t_1) dt_1,$$

$$\Omega^{[n]} = \int_0^t \left( A(t_1) dt_1 - \frac{1}{2} [\Omega^{[n-1]}, A] + \frac{1}{12} [\Omega^{[n-1]}, [\Omega^{[n-1]}, A]] + \dots \right)$$

so that  $\lim_{n \rightarrow \infty} \Omega^{[n]}(t) = \Omega(t)$  in a neighborhood of  $t = 0$

- Another recursive procedure to obtain the series, based on a generator



- When the recursion is worked out explicitly,

$$\Omega_n(t) = \sum_{j=1}^{n-1} \frac{B_j}{j!} \sum_{\substack{k_1 + \dots + k_j = n-1 \\ k_1 \geq 1, \dots, k_j \geq 1}} \int_0^t \text{ad}_{\Omega_{k_1}(s)} \text{ad}_{\Omega_{k_2}(s)} \cdots \text{ad}_{\Omega_{k_j}(s)} A(s) ds$$

- $\Omega_n$  is a linear combination of  $n$ -multiple integrals of  $n - 1$ -nested commutators containing  $n$  operators  $A$  evaluated at different times
- The expression is increasingly complicated when  $n$  grows

# Some properties

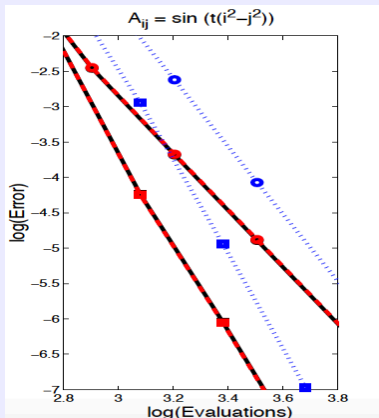
- If  $A(t)$  belongs to some Lie algebra  $\mathfrak{g}$ , then  $\Omega(t)$  (and truncation of the Magnus series) also belongs to  $\mathfrak{g}$  and therefore  $\exp(\Omega) \in \mathcal{G}$ , where  $\mathcal{G}$  is the Lie group with Lie algebra  $\mathfrak{g}$ .
  - ① Symplectic group (in Hamiltonian mechanics)
  - ② Unitary group (for the Schrödinger equation)
- The resulting approximations preserve important qualitative properties of the exact solution (e.g., unitarity, etc.)

- Analytic approximations
- Starting point for the construction of new families of numerical integrators for  $Y' = A(t)Y$
- *Very efficient* high order numerical methods
- *Lie group integrators*, special class of *geometric numerical integration methods*

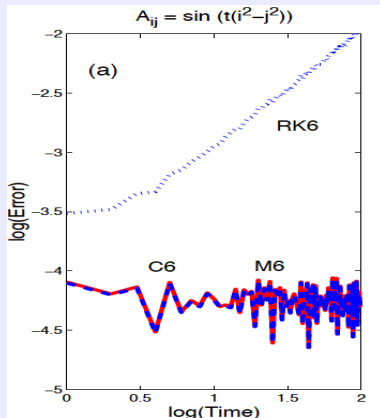
Example:  $Y' = A(t)Y$ ,  $Y(0) = I$

$$A_{ij} = \sin(t(j^2 - i^2)), \quad 1 \leq i < j \leq 10$$

Efficiency diagram



Error as a function of time



# Convergence

- Is this result only formal? What about convergence?
- Specifically, given a certain operator  $A(t)$ , when it is possible to get  $\Omega(t)$  in (31) as the sum of the series
$$\Omega(t) = \sum_{n=1}^{\infty} \Omega_n(t)?$$
- It turns out that the Magnus series converges for  $t \in [0, T)$  such that

$$\int_0^T \|A(s)\| ds < \pi$$

where  $\|\cdot\|$  is the 2-norm

- This is a generic result, in the sense that it is possible to find particular matrices  $A(t)$  so that the series diverges for all  $t > T$ .
- ... But is only a *sufficient* condition: there exist matrices  $A(t)$  so that the expansion converges for  $t > T$ .
- Analysis of the eigenvalues

## Remarks

- The result is valid for *complex* matrices  $A(t)$
- In fact, for any given bounded operator  $A(t)$  in a Hilbert space  $\mathcal{H}$  if  $Y$  is a normal operator (in particular, if  $iY$  is unitary).
- This results can be used in turn to prove the convergence of the Baker–Campbell–Hausdorff formula

# BCH and the Magnus expansion

- Consider the initial value problem

$$U' = A(t)U, \quad U(0) = I, \quad (35)$$

with

$$A(t) = \begin{cases} Y & 0 \leq t \leq 1 \\ X & 1 < t \leq 2 \end{cases}$$

The exact solution of (35) at  $t = 2$  is  $U(2) = e^X e^Y$ .

- But we can apply **Magnus**:  $U(2) = e^{\Omega(2)}$ .
- In this way it is possible to get BCH as a particular case of the Magnus expansion. (Sometimes it is called the *continuous BCH formula* BCH).

- 'Symmetric' Zassenhaus formula: useful for obtaining new numerical methods for certain classes of PDEs (Bader *et al.* 2014)

$$e^{X+Y} = \dots e^{C_3} e^{C_2} e^{\frac{1}{2}Y} e^X e^{\frac{1}{2}Y} e^{C_2} e^{C_3} \dots$$

in an efficient way

- 'Continuous analogue' of the Zassenhaus formula (M. Nadinic's Thesis 2015): Given  $U' = A(t)Y$ ,  $U(0) = I$ ,

$$U(t) = e^{W_1(t)} e^{W_2(t)} \dots e^{W_r(t)} \dots$$

as efficiently as possible



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