

Please encircle the questions you have solved and are able to present/discuss in class.

9.1(a) 9.1(b) 9.1(c) 9.1(d) 9.2(a) 9.2(b) 9.2(c) 9.2(d)

### Problem 9.1: Fokker-Planck equation and equilibrium distribution (5 points)

In this exercise we want to study *time-dependent fluctuations* over an equilibrium configuration. The equilibrium configuration of the system is described in terms of the usual  $\varphi^4$  action  $S[\varphi]$

$$S[\varphi] = \int_{\mathbb{R}^d} d\vec{r} \mathcal{L}(\varphi(\vec{r})), \quad \text{with} \quad \mathcal{L}(\varphi) = r(t_r)\varphi^2 + \frac{1}{2}\gamma(\nabla\varphi)^2 + \frac{1}{2}b\varphi^4. \quad (1)$$

In the previous equation, we have denoted with  $r(t_r) = r_0 t_r$ , where  $t_r = (T - T_c)/T_c$  is the reduced temperature. We denote it with  $t_r$  in this exercise to distinguish it from the time variable, which we shall denote as  $t$  in the following. The equilibrium configuration  $\bar{\varphi}(\vec{r})$  of the field  $\varphi(\vec{r})$  is given by the equation

$$\left. \frac{\delta S[\varphi]}{\delta \varphi(\vec{r})} \right|_{\bar{\varphi}(\vec{r})} = 0. \quad (2)$$

If the system is not far from equilibrium one can reasonably expect that the rate at which the system relaxes back to the equilibrium configuration  $\bar{\varphi}(\vec{r})$  is proportional to the deviation from equilibrium. From this phenomenological assumption one can write the following equation for the rate of change in time  $t$  of the time-dependent field  $\varphi(\vec{r}, t)$ :

$$\frac{\partial \varphi(\vec{r}, t)}{\partial t} = -\Gamma \frac{\delta S[\varphi]}{\delta \varphi(\vec{r}, t)} + \zeta(\vec{r}, t). \quad (3)$$

In the previous equation,  $\zeta(\vec{r}, t)$  is a noise term which accounts for the fact that thermal fluctuations will sometime cause the system to move further away from equilibrium during its time evolution. We assume that the noise  $\zeta(\vec{r}, t)$  is a Gaussian random function chosen from the functional Gaussian distribution  $P_\zeta[\zeta(\vec{r}, t)]$ :

$$P_\zeta[\zeta(\vec{r}, t)] \propto \exp \left[ -\frac{1}{2D} \int_{\mathbb{R}} dt \int_{\mathbb{R}^d} d\vec{r} \zeta^2(\vec{r}, t) \right], \quad (4)$$

with the variance of the distribution given by  $D$

$$\langle \zeta(\vec{r}, t) \rangle_\zeta = 0; \quad \langle \zeta(\vec{r}, t) \zeta(\vec{r}', t') \rangle_\zeta = D \delta(\vec{r} - \vec{r}') \delta(t - t'). \quad (5)$$

In the previous equation we have denoted with  $\langle \dots \rangle_\zeta$  the average over the probability distribution  $P_\zeta$  in Eq. (4). Equation (3) is usually named Langevin equation. The probability  $P[\varphi(\vec{r}), t]$  of finding a field configuration  $\varphi(\vec{r})$  at time  $t$  is given by

$$P[\varphi(\vec{r}), t] = \langle \delta[\varphi(\vec{r}) - \bar{\varphi}(\vec{r}, t, \{\zeta\})] \rangle_\zeta, \quad (6)$$

where  $\bar{\varphi}(\vec{r}, t, \{\zeta\})$  is a solution of the Langevin equation (3) for a fixed realization  $\zeta(\vec{r}, t)$  of the noise.

In the first exercise we want to derive the Fokker-Planck equation starting from Eq. (6) using the Langevin equation (3).

(a) Using the Langevin equation (3) show that the time derivative of  $P[\varphi(\vec{r}), t]$  in Eq. (6) can be written as

$$\frac{\partial P[\varphi(\vec{r}), t]}{\partial t} = \int_{\mathbb{R}^d} d\vec{r}' \frac{\delta}{\delta \varphi(\vec{r}', t)} \left[ \Gamma P[\varphi(\vec{r}), t] \frac{\delta S}{\delta \varphi(\vec{r}', t)} - \langle \zeta(\vec{r}', t) \delta[\varphi(\vec{r}) - \bar{\varphi}(\vec{r}, t, \{\zeta\})] \rangle_\zeta \right]. \quad (7)$$

(1 point)

(b) Prove for the Gaussian distribution in Eqs. (4) and (5) that the following relation holds

$$\langle F[\zeta] \zeta \rangle_\zeta = D \left\langle \frac{\delta F}{\delta \zeta} \right\rangle_\zeta, \quad (8)$$

for an arbitrary functional  $F[\zeta]$  of the noise  $\zeta$ . Use the identity in Eq. (8) to simplify the term  $\langle \zeta(\vec{r}', t) \delta[\varphi(\vec{r}) - \bar{\varphi}(\vec{r}, t, \{\zeta\})] \rangle_\zeta$  in Eq. (7). You should get the following result

$$\langle \zeta(\vec{r}', t) \delta[\varphi(\vec{r}) - \bar{\varphi}(\vec{r}, t, \{\zeta\})] \rangle_\zeta = -D \int_{\mathbb{R}^d} d\vec{r}'' \frac{\delta}{\delta \varphi(\vec{r}'', t)} \left\langle \frac{\delta \bar{\varphi}(\vec{r}'', t)}{\delta \zeta(\vec{r}', t)} \delta[\varphi(\vec{r}) - \bar{\varphi}(\vec{r}, t, \{\zeta\})] \right\rangle_\zeta. \quad (9)$$

(1 point)

- (c) We want here to simplify the quantity averaged over the noise  $\zeta$  inside the integral in Eq. (9). To do this, write the Langevin equation in the integral form and verify that

$$\frac{\delta \bar{\varphi}(\vec{r}'', t)}{\delta \zeta(\vec{r}', t)} = \frac{1}{2} \delta(\vec{r}' - \vec{r}''). \quad (10)$$

**(1 point)**

*Hint:* You can write the Langevin equation in its integral form by formally integrating the left and the right hand side of Eq. (3). Then, because of causality, one has that  $\bar{\varphi}(\vec{r}, t)$  only depends on  $\zeta(\vec{r}, t')$  for  $t > t'$ . This causes the appearance of the Heaviside theta function  $\Theta(t'' - t')$ . In this exercise we regularize  $\Theta(0) = 1/2$ , which leads to the factor  $1/2$  in Eq. (10).

- (d) Write the Fokker-Planck equation upon inserting the results obtained in Eqs. (9) and (10) into Eq. (7). You should obtain

$$\frac{\partial P[\varphi(\vec{r}), t]}{\partial t} = \int_{\mathbb{R}^d} d\vec{r}' \frac{\delta}{\delta \varphi(\vec{r}', t)} \left[ \Gamma P[\varphi(\vec{r}), t] \frac{\delta S}{\delta \varphi(\vec{r}', t)} + \frac{D}{2} \frac{\delta P[\varphi(\vec{r}), t]}{\delta \varphi(\vec{r}', t)} \right]. \quad (11)$$

Discuss what is the solution of the Fokker-Planck equation at long times  $t \rightarrow \infty$ , where the system relaxes to thermal equilibrium. What is the relation between  $D$  and  $\Gamma$ ? Discuss and interpret the result physically. **(2 points)**

## Problem 9.2: Dynamic scaling hypothesis and relaxation to the equilibrium **(5 points)**

In this exercise we consider the case where  $T > T_c$  and therefore the equilibrium configuration from Eq. (2), in the absence of noise, is

$$\bar{\varphi}(\vec{r}) \equiv 0. \quad (12)$$

Time dependent fluctuations on top of the solution (12) are generated by the noise term of the Langevin equation.

- (a) Linearize the Langevin equation (3) by expanding up to linear order in  $\delta\varphi(\vec{r}, t) = \varphi(\vec{r}, t) - \bar{\varphi}(\vec{r})$ . You should get the following equation for  $\delta\varphi(\vec{r}, t)$ :

$$\frac{\partial \delta\varphi(\vec{r}, t)}{\partial t} = - \left[ \frac{\delta\varphi(\vec{r}, t)}{\tau_0} - \gamma \Gamma \nabla^2 \delta\varphi(\vec{r}, t) \right] + \zeta(\vec{r}, t). \quad (13)$$

Identify the *relaxation time*  $\tau_0$ . Take the Fourier transform of Eq. (13). You should obtain

$$\frac{\partial \delta\varphi(\vec{k}, t)}{\partial t} = - \left[ \frac{\delta\varphi(\vec{k}, t)}{\tau(k)} \right] + \zeta(\vec{k}, t). \quad (14)$$

Identify the relaxation time  $\tau(k)$  in momentum space. **(1 point)**

*Hint:* Be reminded that the definition  $\hat{f}(\vec{k})$  of the Fourier transform of an arbitrary function of space  $f(\vec{r})$  is

$$\hat{f}(\vec{k}) = \int_{\mathbb{R}^d} d\vec{r} f(\vec{r}) \exp(-i\vec{k} \cdot \vec{r}), \quad \text{with inverse} \quad f(\vec{r}) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} d\vec{k} \hat{f}(\vec{k}) \exp(i\vec{k} \cdot \vec{r}). \quad (15)$$

- (b) We study in this point the response function  $\hat{\chi}(\vec{k}, \omega)$  in Fourier space both with respect to the space and to the time coordinate:

$$\hat{\chi}(\vec{k}, \omega) = \frac{\langle \delta\varphi(\vec{k}, \omega) \rangle_{\zeta}}{\delta \hat{h}(\vec{k}, \omega)} \Big|_{h=0}. \quad (16)$$

In the previous equation  $\delta \hat{h}(\vec{k}, \omega)$  is the Fourier transform of a small space and time dependent magnetic field  $\delta h(\vec{r}, t)$  added to the right hand side of Eq. (3). The response function is evaluated in the linear response regime where  $\delta h$  is small. Compute  $\hat{\chi}(\vec{k}, \omega)$  starting from the linearized Langevin equation in Eq. (13). You should obtain

$$\hat{\chi}(\vec{k}, \omega) = \frac{1}{\tau(k)^{-1} - i\omega}. \quad (17)$$

**(1 point)**

*Hint:* Be reminded of the definition of the Fourier transform  $\hat{f}(\vec{k}, \omega)$  of an arbitrary function  $f(\vec{r}, t)$  of space : and time

$$f(\vec{r}, t) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} d\vec{k} \frac{1}{2\pi} \int_{\mathbb{R}} d\omega \hat{f}(\vec{k}, \omega) \exp(i(\vec{k} \cdot \vec{r} + \omega t)). \quad (18)$$

- (c) Here we discuss the generalization of the scaling hypothesis discussed in the lectures to the non-equilibrium case analyzed here. We write the following scaling form for the relaxation time  $\tau(k)$  defined after Eq. (14):

$$\tau(k) = t_r^{-y} F_\tau(\vec{k} \xi(t_r)), \quad (19)$$

where  $F_\tau(x)$  is a scaling function and  $t_r$  is the reduced temperature defined after Eq. (1). Determine the relation between the exponents  $y$ ,  $z$  and  $\nu$  that the scaling equation (19) enforces. Compute the exponents  $y$  and  $z$  in the case of the linearized Langevin equation in Eq. (13).

*Hint:* Be reminded that  $\nu$  is the critical exponent describing how the correlation length  $\xi$  diverges at the critical temperature  $T_c$ :

$$\xi(t_r) \propto t_r^{-\nu}. \quad (20)$$

*Hint:* The exponents  $y$  and  $z$  are defined by the following relations

$$\tau(k) \propto \begin{cases} t_r^{-y}, & \text{for } \vec{k} = 0, \\ (k^z)^{-1}, & \text{at } T = T_c \text{ and } \vec{k} \neq 0. \end{cases} \quad (21)$$

**(2 points)**

- (d) Here we discuss the dynamical scaling hypothesis for the response function  $\hat{\chi}(\vec{k}, \omega)$ . We write the following scaling form for  $\hat{\chi}(\vec{k}, \omega)$ :

$$\hat{\chi}(\vec{k}, \omega) = t_r^{-\gamma} F_\chi(\vec{k} \xi(t_r), \omega \tau_0), \quad (22)$$

with  $\gamma$  the critical exponent of the magnetic susceptibility at thermal equilibrium. Compute  $\hat{\chi}(0, \omega)$  when  $\vec{k} = 0$  and  $T \rightarrow T_c$ . Furthermore, prove that the ratio

$$\delta = \arctan \left( \frac{\text{Im} \hat{\chi}(0, \omega)}{\text{Re} \hat{\chi}(0, \omega)} \right), \quad (23)$$

takes a universal expression determined solely by the critical exponents  $z$ ,  $\nu$  and  $\gamma$ . **(1 point)**.

### Problem 9.3: Scaling hypothesis at thermal equilibrium (3 bonus points)

This is a “**bonus exercise**”, i.e., you can gain 2 extra points from this beyond the 10 points given in the previous exercises. You can then use these 2 extra points to fill some points that you could have missed in the previous (or in the following) sheets.

Consider a magnetic system described by the equation of state

$$H = M^\delta F \left( \frac{t}{M^{1/\beta}} \right), \quad (24)$$

where  $H$  is a magnetic field,  $M$  is the magnetization density and  $F$  is a scaling function.

- (a) Prove that  $\delta$  and  $\beta$  in Eq. (24) are the critical exponents as defined in the lecture script. **(1 bonus point)**

- (b) Prove that the scaling relation

$$\gamma = \beta(\delta - 1), \quad (25)$$

starting from Eq. (24). **(2 bonus points)**