Saarland University

Summary

Elements of Machine Learning

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Contents

Intr	oduction
1.1	Advertising
1.2	Why estimate f ?
	1.2.1 Prediction
	1.2.2 Inference
1.3	
	1.3.1 Parametric Methods
	1.3.2 Nonparametric Methods
1.4	Accuracy vs. Interpretability
1.5	Supervised vs. Unsupervised Learning
	1.5.1 Supervised Learning
	1.5.2 Semi-supervised Learning
	1.5.3 Unsupervised Learning
1.6	Assessing model accuracy
1.7	Bias-Variance
	1.7.1 Tradeoff
	1.7.2 Bias-Variance Decomposition
1.8	
	1.8.1 Bayes Classifier
19	Example Binary Classification
	1.9.1 Nearest Neighbors
	1.1 1.2 1.3 1.4 1.5

Introduction

1.1 Advertising

- $X_{1,\ldots,p}$ are input variables (aka predictors, features, independent variables)
- Y is the output variable (aka response, dependent variable)

In general, we assume a relationship between X and Y of the form

$$Y = f(X) + \epsilon = f(X_1, X_2, ..., X_p) + \epsilon$$

where ϵ is a random additive error term with zero mean.

1.2 Why estimate f?

1.2.1 Prediction

Often inputs X are available, output Y is not, but is **desired**.

• estimating the output then effects a **prediction**

$$\hat{Y} = \hat{f}(X)$$

We often treat \hat{f} as a black box whose form is not of interest.

- e.g., input is blood profile of a patient, and output is the patient's risk of a severe reaction to a drug.
- the accuracy of \hat{Y} depends on the **reducible error** and the **irreducible error**
- for fixed X and f we have

$$\underbrace{E[Y-\hat{Y}]^2}_{\text{Expectation over all possible training sets}} = E[f(X) + \epsilon - \hat{f}(X)]^2 = \underbrace{E[f(X) - \hat{f}(X)]^2}_{\text{reducible error}} + \underbrace{Var(\epsilon)}_{\text{irreducible error}}$$

The goal of prediction is to minimize the reducible error. The irreducible error cannot be avoided.

1.2.2 Inference

Often we want to go beyond treating \hat{f} as a black box. Rather, we want to **understand the relation** between input and output

- which predictors strongly associate with the response? (Often only few)
- what is the relationship between the response and each predictor? Is it positive or negative? (Sometimes this depends on other predictors)
- is the relationship between the predictors linear or more complicated?

An **example** for inference is the advertising data with questions as:

- which media contribute to sales? which generate the biggest boost?
- how much increase in sales is associated with a given increase in TV ads?

Sometimes both prediction and inference are of interest. There is, however, a **tradeoff** between the two. Linear models, for example, allow easily interpretable predictions but may not be very accurate.

1.3 How to estimate *f*?

We have a set of n observations with inputs and outputs (training data), $\{(x_1, y_1), (x_2, y_2), ..., (x_n, y_n)\}$, and are looking for a function \hat{f} such that $Y \approx \hat{f}(X)$ for any observation (X, Y). In the following we dinstinguish between **parametric** and **nonparametric** methods:

1.3.1 Parametric Methods

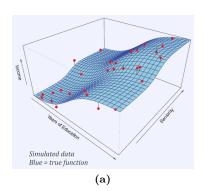
• have a given functional form, usually simple such as a linear model

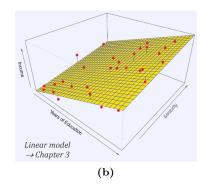
$$f(X) = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \dots + \beta_p X_p$$

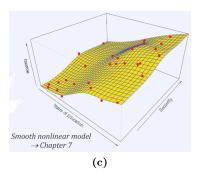
- estimating \hat{f} means choosing the model parameters.
- **problem:** the model may not match the true form of f.

1.3.2 Nonparametric Methods

- here we aim at finding the form of f
- choosing the form gives us much more freedom
- we have to choose many parameters; this requires many observations
- otherwise, we risk modelling the noise in the training set: overfitting







1.4 Accuracy vs. Interpretability

Why would we ever prefer a more restricted model over a more flexible one?

A flexible model entails a large number of parameters

- 1. Estimating all parameters is computationally expensive.
- 2. Complicated models are hard to interpret, so especially when inference is the goal, simple models are preferred.
- 3. If we have only few observations, we do not have enough information to accurately estimate many parameters. In such cases flexible models incur a high risk of overtraining.

1.5 Supervised vs. Unsupervised Learning

1.5.1 Supervised Learning

- Data: inputs and outputs (x_i, y_i) for observations i = 1, ..., n following some unknown functional pattern with noise, e.g. $Y = f(X) + \epsilon$
- Goal: find function \hat{f} such that $Y \approx \hat{f}(X)$ for every conceivably seen input X (setting is like that of a student who learns from a teacher (supervisor) giving examples)

1.5.2 Semi-supervised Learning

- Data: inputs x_i for observations i = 1, ..., n, only some outputs y_i
- Goal: same as for supervised learning, but also leverages unlabeled data

1.5.3 Unsupervised Learning

- Data: inputs x_i for observations i = 1, ..., n, no outputs
- Goal: elucidate relationships between the variables or the observations (often equated with cluster analysis, but many more aspects exist)

1.6 Assessing model accuracy

In regression problems we use the **mean squared error** to assass the quality of fit, here over the training data

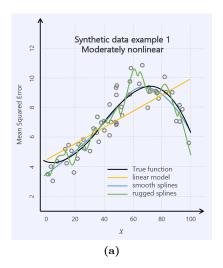
$$MSE = \frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{f}(x_i))^2$$

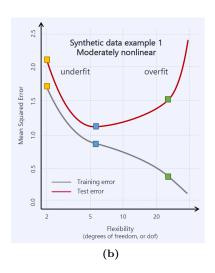
We call this the **training error**.

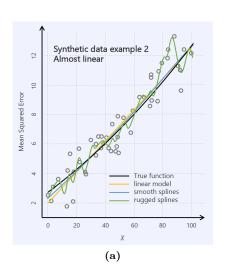
We are more interested in the error over unseen data (x_0, y_0)

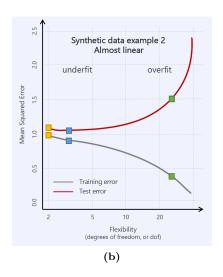
$$Ave(\hat{f}(x_0) - y_0)^2$$

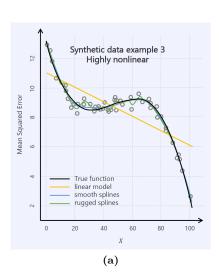
We call this the **test error**, the **generalization error**, or **expected prediction error** (EPE). If the functional dependence between input and output is not known, the test error is hard to estimate.

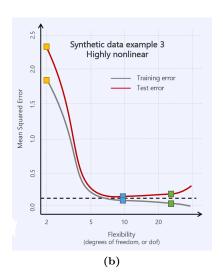












1.7 Bias-Variance

1.7.1 Tradeoff

The shape of the curve for test error is due to a basic tradeoff in the MSE

$$E[y_0 - \hat{f}(x_0)]^2 = Var(\hat{f}(x_0)) + [Bias(\hat{f}(x_0))]^2 + Var(\epsilon)$$

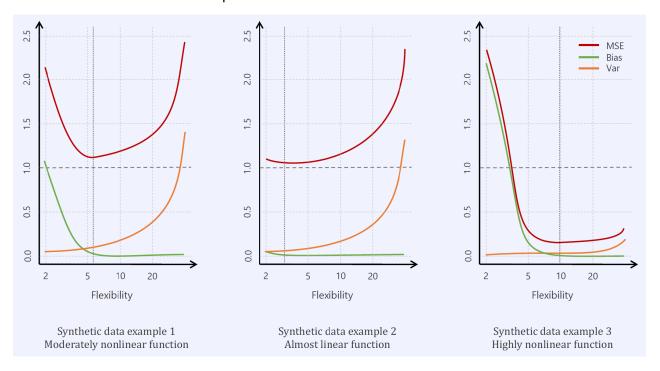
Here bias is the systematic deviation of the estimate from the true value

$$Bias(\hat{f}(x_0)) = E[\hat{f}(x_0) - y_0]$$

and variance is the variation of the estimate between different training sets

$$Var(\hat{f}(x_0)) = E[\hat{f}(x_0) - E[\hat{f}(x_0)]]^2$$

1.7.2 Bias-Variance Decomposition



1.8 The Classification Setting

A popular method of measuring classification error (loss function) is the misclassification error.

On the training set is

$$\frac{1}{n}\sum_{i=1}^{n}I(y_{i}\neq\hat{y}_{i})$$

where for a predicate p,

- I(p) = 1 if p = true and
- I(p) = 0 otherwise.

The test error is

$$AVE(I(y_0 \neq \hat{y}_0))$$

1.8.1 Bayes Classifier

The test error is minimized by the following very simple calssifier

$$arg\max_{j=1,...,k} Pr[Y=j \mid X=x_0]$$

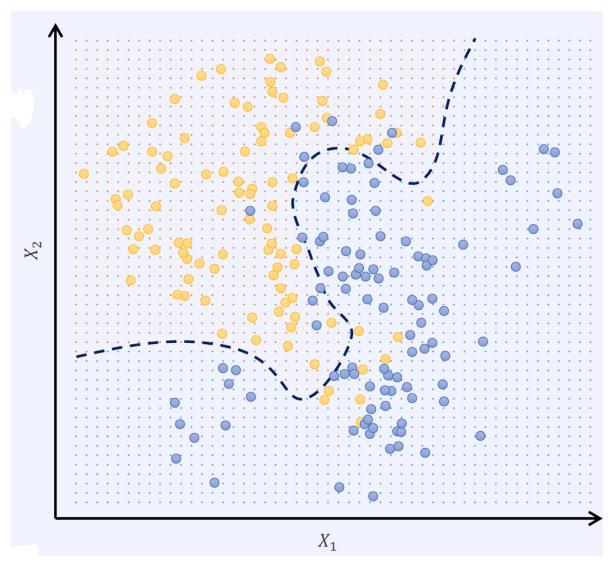
for a classification problem with k classes 1, ..., k.

This classifier can be computed on **synthetic data** for which the **probability distribution is known**, but not for real data, as we do not know the probability distribution.

1.9 Example Binary Classification

100 observations in each of two groups, synthetic data with noise.

- Bayes decision boundary: points with $Pr[Y = 1 \mid X = x_0] = 0.5$ is dashed.
- Bayes error rate: the irreducible error $1 E[\max_{j=1,2} Pr[Y=j \mid X]]$ in genaral, and 0.1304 for this example.



1.9.1 Nearest Neighbors

k-nearest neighbors (kNN)

Classifies each point to the majority class among its \boldsymbol{k} nearest neighbors

$$arg \max_{j=1,\dots,k} \frac{1}{k} \sum_{\mathbb{N}_0} I(y_i = j)$$

where \mathbb{N}_0 is the set of the k data points nearest to x_0 .

