Image Processing and Computer Vision (IPCV)



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Example Solutions for Homework Assignment 2 (H2)

Problem 1 (Properties of the continuous Fourier transform)

Verify that the following properties of the continuous Fourier transform are true.

Linearity: $\mathcal{F}[a \cdot f(x) + b \cdot g(x)](u) = a \cdot \mathcal{F}[f](u) + b \cdot \mathcal{F}[g](u)$

$$\mathcal{F}[a \cdot f(x) + b \cdot g(x)](u) = \int_{\mathbb{R}} (a \cdot f(x) + b \cdot g(x)) \exp(-i2\pi ux) dx$$
$$= a \int_{\mathbb{R}} f(x) \exp(-i2\pi ux) dx + b \int_{\mathbb{R}} g(x) \exp(-i2\pi ux) dx$$
$$= a \cdot \mathcal{F}[f](u) + b \cdot \mathcal{F}[g](u)$$

Spatial Shift: $\mathcal{F}[f(x-a)](u) = \exp(-i2\pi ua) \cdot \mathcal{F}[f](u)$

$$\mathcal{F}[f(x-a)](u) = \int_{\mathbb{R}} f(x-a) \exp(-i2\pi ux) dx \quad t \leftrightarrow x - a$$

$$= \int_{\mathbb{R}} f(t) \exp(-i2\pi u(t+a)) dt$$

$$= \exp(-i2\pi ua) \int_{\mathbb{R}} f(t) \exp(-i2\pi ut) dt$$

$$= \exp(-i2\pi ua) \mathcal{F}[f](u)$$

Frequency Shift: $\mathcal{F}[f(x) \cdot \exp(-i2\pi u_0 x)](u) = \mathcal{F}[f](u + u_0)$

$$\mathcal{F}[f(x) \cdot \exp(-i2\pi u_0 x)](u) = \int_{\mathbb{R}} f(x) \exp(-i2\pi u_0 x) \exp(-i2\pi u x) dx$$
$$= \int_{\mathbb{R}} f(x) \exp(-i2\pi (u_0 + u)x) dx$$
$$= \mathcal{F}[f](u_0 + u)$$

Scaling: $\mathcal{F}[f(ax)](u) = \frac{1}{|a|} \cdot \mathcal{F}[f](\frac{u}{a})$

$$\mathcal{F}[f(ax)](u) = \int_{\mathbb{R}} f(ax) \exp(-i2\pi ux) dx \quad t \leftrightarrow ax$$
$$= \int_{\mathbb{R}} f(t) \exp\left(-i2\pi u \frac{t}{a}\right) \frac{1}{|a|} dt$$
$$= \frac{1}{|a|} \mathcal{F}[f]\left(\frac{u}{a}\right)$$

Convolution: $\mathcal{F}[f * g(nx)](u) = \mathcal{F}[f](u) \cdot \mathcal{F}[g](u)$

$$\mathcal{F}[f * g(x)](u) = \int_{\mathbb{R}} (f * g)(x) \exp(-i2\pi ux) dx$$

$$= \int_{\mathbb{R}} \left(\int_{\mathbb{R}} f(\xi)g(x - \xi) d\xi \right) \exp(-i2\pi ux) dx$$

$$= \int_{\mathbb{R}} \int_{\mathbb{R}} f(\xi)g(x - \xi) \exp(-i2\pi ux) dx d\xi$$

$$= \int_{\mathbb{R}} f(\xi) \exp(-i2\pi u\xi) \left(\int_{\mathbb{R}} g(x - \xi) \exp(-i2\pi u(x - \xi)) dx \right) d\xi$$

$$= \int_{\mathbb{R}} f(\xi) \exp(-i2\pi u\xi) \left(\int_{\mathbb{R}} g(t) \exp(-i2\pi ut) dt \right) d\xi$$

$$= \int_{\mathbb{R}} f(\xi) \exp(-i2\pi u\xi) d\xi \mathcal{F}[g](u)$$

$$= \mathcal{F}[f](u) \cdot \mathcal{F}[g](u)$$

Problem 2 (Continuous Fourier Transform of a Hat Function)

Let us first discuss how this exercise can be solved efficiently. We know from the first home work, that the convolution of a box function with itself yields a hat function. In particular, the hat function f from this exercise corresponds to a convolution f(x) = g(x) * g(x) where g is the box function from H1, Problem 1:

$$f(x) := \begin{cases} \frac{1}{2} & -1 \le x \le 1\\ 0 & \text{else} \end{cases}$$

From the lecture we know what form the Fourier transform of a box function h with height A on the interval [-R, R] is:

$$\mathcal{F}[h](u) = \frac{A}{2\pi u}\sin(2\pi uR)$$

In the case of our box function g we have $A = \frac{1}{2}$ and R = 1, thus yielding

$$\mathcal{F}[h](u) = \frac{1}{2\pi u}\sin(2\pi u) = \operatorname{sinc}(2\pi u)$$

Finally, we apply the convolution theorem and get:

$$\mathcal{F}[f](u) = \mathcal{F}[g * g](u) = (\mathcal{F}[g](u))^2 = \operatorname{sinc}^2(2\pi u)$$

For the sake of completeness, we also demonstrate how to solve the exercise in the more tedious,

straightforward way by computing $\mathcal{F}[f](u)$ directly:

$$\mathcal{F}[f](u) = \underbrace{\int_{-\infty}^{-2} 0 \cdot \exp(-i2\pi ux) dx}_{=0} + \int_{-2}^{2} \frac{1}{4} (2 - |x|) \cdot \exp(-i2\pi ux) dx + \underbrace{\int_{2}^{\infty} 0 \cdot \exp(-i2\pi ux) dx}_{=0}$$

$$= \underbrace{\int_{-2}^{2} \frac{1}{4} (2 - |x|) \cdot (\cos(2\pi ux) - i\sin(2\pi ux)) dx}_{=0 \text{ (odd function)}}$$

$$= \underbrace{\frac{1}{2} \int_{-2}^{2} \cos(2\pi ux) dx}_{=0 \text{ (odd function)}} - \underbrace{\frac{1}{4} \int_{-2}^{2} |x| \cos(2\pi ux) dx}_{=0 \text{ (odd function)}} + \underbrace{\frac{1}{4} \int_{-2}^{2} |x| \sin(2\pi ux) dx}_{=0 \text{ (odd function)}}$$

$$= 2 \cdot \frac{1}{2} \int_{0}^{2} \cos(2\pi ux) dx - 2 \cdot \frac{1}{4} \int_{0}^{2} x \cos(2\pi ux) dx$$

Applying the product rule for integrals to the right part of that term gives:

$$\begin{split} &= \int_0^2 \cos(2\pi u x) dx - \frac{1}{2} \left[x \frac{\sin(2\pi u x)}{2\pi u} \right]_0^2 + \frac{1}{2} \int_0^2 \frac{\sin(2\pi u x)}{2\pi u} dx \\ &= \left[\frac{\sin(2\pi u x)}{2\pi u} \right]_0^2 - \frac{1}{2} \left[x \frac{\sin(2\pi u x)}{2\pi u} \right]_0^2 + \frac{1}{2} \left[\frac{-\cos(2\pi u x)}{(2\pi u)^2} \right]_0^2 \\ &= \left(\frac{\sin(4\pi u)}{2\pi u} - \frac{\sin(0)}{2\pi u} \right) - \frac{1}{2} \left(2 \frac{\sin(4\pi u)}{2\pi u} - \frac{\sin(0)}{2\pi u} \right) + \frac{1}{2} \left(-\frac{\cos(4\pi u)}{(2\pi u)^2} + \frac{\cos(0)}{(2\pi u)^2} \right) \\ &= \frac{1 - \cos(4\pi u)}{2(2\pi u)^2} \end{split}$$

Using the addition theorems we finally get:

$$= \frac{\cos^2(2\pi u) + \sin^2(2\pi u) - \cos(2\pi u + 2\pi u)}{2(2\pi u)^2}$$

$$= \frac{\cos^2(2\pi u) + \sin^2(2\pi u) - (\cos^2(2\pi u) - \sin^2(2\pi u))}{2(2\pi u)^2}$$

$$= \left(\frac{\sin(2\pi u)}{2\pi u}\right)^2 = \operatorname{sinc}^2(2\pi u)$$

This exercise demonstrates the importance of the convolution theorem.

Problem 3 (Continuous Fourier Transform of a Discrete Filter)

Computing the Fourier transform of g gives:

$$\mathcal{F}[g](u) \stackrel{(i)}{=} \frac{1}{h^4} \left(\mathcal{F}[f(x+2h)](u) - 4\mathcal{F}[f(x+h)](u) + 6\mathcal{F}[f(x)](u) - 4\mathcal{F}[f(x-h)](u) + \mathcal{F}[f(x-2h)](u) \right)$$

$$\stackrel{(ii)}{=} \frac{1}{h^4} \left[\exp\left(4\pi i h u\right) - 4\exp\left(2\pi i h u\right) - 4\exp\left(-2\pi i h u\right) + \exp\left(-4\pi i h u\right) + 6\right] \mathcal{F}[f](u)$$

$$\stackrel{(iii)}{=} \frac{1}{h^4} \left[2\cos\left(4\pi h u\right) - 8\cos\left(2\pi h u\right) + 6\right] \mathcal{F}[f](u)$$

$$= \frac{2}{h^4} \left[\cos\left(4\pi h u\right) - 4\cos\left(2\pi h u\right) + 3\right] \mathcal{F}[f](u)$$

- i. Linearity
- ii. Shift-Theorem
- iii. since $\cos(\phi) = (\frac{e^{i\phi} + e^{-i\phi}}{2})$

So we see that the Fourier transform of the function g is essentially the Fourier transform of the original signal multiplied by a combination of trigonometric functions. This result will help us to understand the lowpass effect of derivative filters later on.

Problem 4 (Colour Spaces)

(a) The conversion from RGB to YCbCr images requires to supplement the following code:

(b) The compressed variants of the image baboon.ppm for subsampling factors of S=1,2,4 and 8 are depicted in Tab 1. As one can see, the variants for S=2 and S=4 provide still a quite good quality. This is due to the fact that the details (hairs, patterns) are preserved, since the Y-channel that contains these details is not compressed (downsampled). In the case of S=8, however, slight block artifacts become visible. This is verified by the images in Tab. 2 that depict a zoom of the nose region. Here also for S=2 and S=4 the loss of quality becomes obvious.

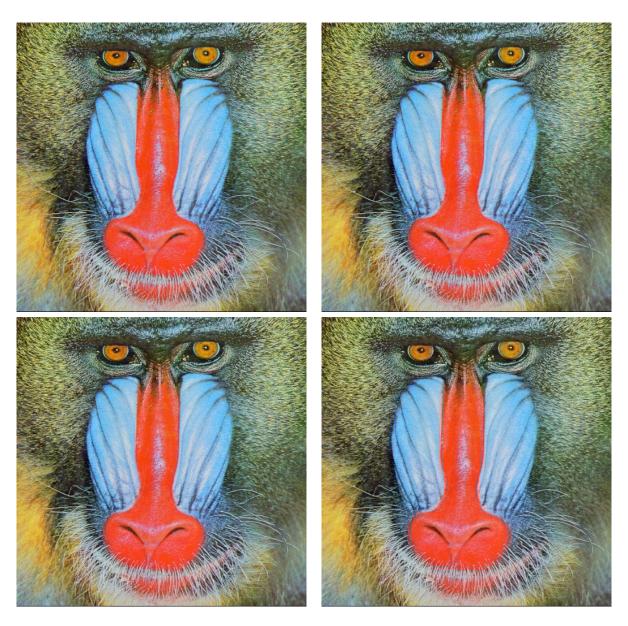


Table 1: Compressed variants of the image baboon.ppm. (a) Top left: Image for S=1 (original image). (b) Top right: S=2. (c) Bottom left: S=4. (d) Bottom right: S=8.

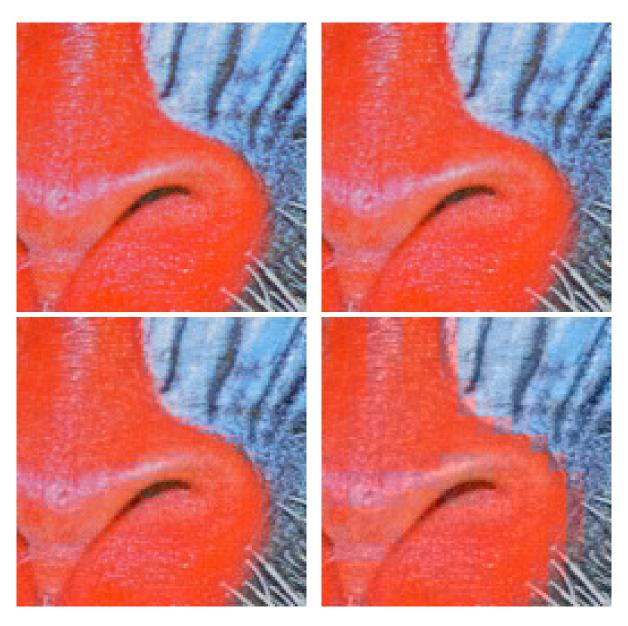


Table 2: Zoom into the compressed variants of the image baboon.ppm. (a) Top left: Image for S=1 (original image). (b) Top right: S=2. (c) Bottom left: S=4. (d) Bottom right: S=8.

(c) While the original RGB image requires 24 bpp to store the information, the requirements of the compressed (subsampled) images is given by

$$v = 8\left(1 + \frac{1}{S^2} + \frac{1}{S^2}\right) .$$

While the Y channels remain uncompressed, the Cb- and Cr-channel are reduced in both dimensions by a factor of S. Thus, 12 bpp for S=2, 9 bpp for S=4, and 8.25 bpp for S=8 are needed. This is in the order of the memory consumption of grey value images.