













2. 
$$\hat{x} = x(1-\hat{x})$$
  
 $\hat{y} = y(3-\hat{y})$   
 $\hat{x} = 0 \Rightarrow x(1-\hat{x}) = 0 \Rightarrow x \in \{0, 1, 1\}$   
 $\hat{y} = 0 \Rightarrow y(3-\hat{y}) = 0 \Rightarrow y \in \{0, 1, 2\}$   
 $\Rightarrow x \in \{0, 1, 2\} = 0 \Rightarrow y \in \{0, 1, 2\}$   
 $\Rightarrow x \in \{0, 1, 2\} = 0 \Rightarrow x \in \{0, 1, 2\}$   
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 $\Rightarrow$ 

II 
$$(1,0) \Rightarrow J(1,0) = \begin{pmatrix} -1 & 0 \\ 0 & 3 \end{pmatrix} \Rightarrow 24 = -1 & 2_2 = 3$$

Saddle point

If  $(1,3) \Rightarrow J(1,3) = \begin{pmatrix} -1 & 0 \\ 0 & -2 \end{pmatrix} \Rightarrow 2_1 = -1 & 2_2 = -3$ 

$$\Rightarrow \text{Stable mode attractor}$$

3.  $1 \times = 4 \times -5 \text{ from a contour}$ 

$$3. \frac{1}{3} \times = 4 \times -5 \text{ from a contour}$$

$$3. \frac{1}{3} \times = 4 \times -5 \text{ from a contour}$$

$$4 = \begin{pmatrix} 4 & -5 \\ 1 & -2 \end{pmatrix}$$

$$4 = \begin{pmatrix} 4 & -5 \\ 1 & -2 \end{pmatrix}$$

$$4 = \begin{pmatrix} 4 & -2 \\ 1 & -2 \end{pmatrix} \Rightarrow$$

