

$$\begin{aligned} \text{DNF}(U) &= (\neg p \wedge q \wedge r) \vee (\neg p \wedge q) \vee (q \wedge r) \\ &\equiv (\neg p \wedge q) \vee (q \wedge r) \end{aligned}$$

$$(A \wedge B) \vee A \equiv A \quad (\text{absorption law})$$

Example 3:

$$\text{DNF}(U) = \underbrace{(q \wedge q)}_F \vee \underbrace{(\neg q \wedge \neg p \wedge q)}_F \vee \underbrace{(q \wedge \neg p \wedge p)}_F$$

Example 2:

$$H_1 \wedge H_2 \wedge H_3 \wedge H_4 \wedge \neg C \quad (1) \checkmark$$

$\neg$  for (1)

$$H_1: K \wedge S \rightarrow M \quad (2) \checkmark$$

|

$$H_2: KE \rightarrow K \quad (3) \checkmark$$

|

$$H_3: \neg KE$$

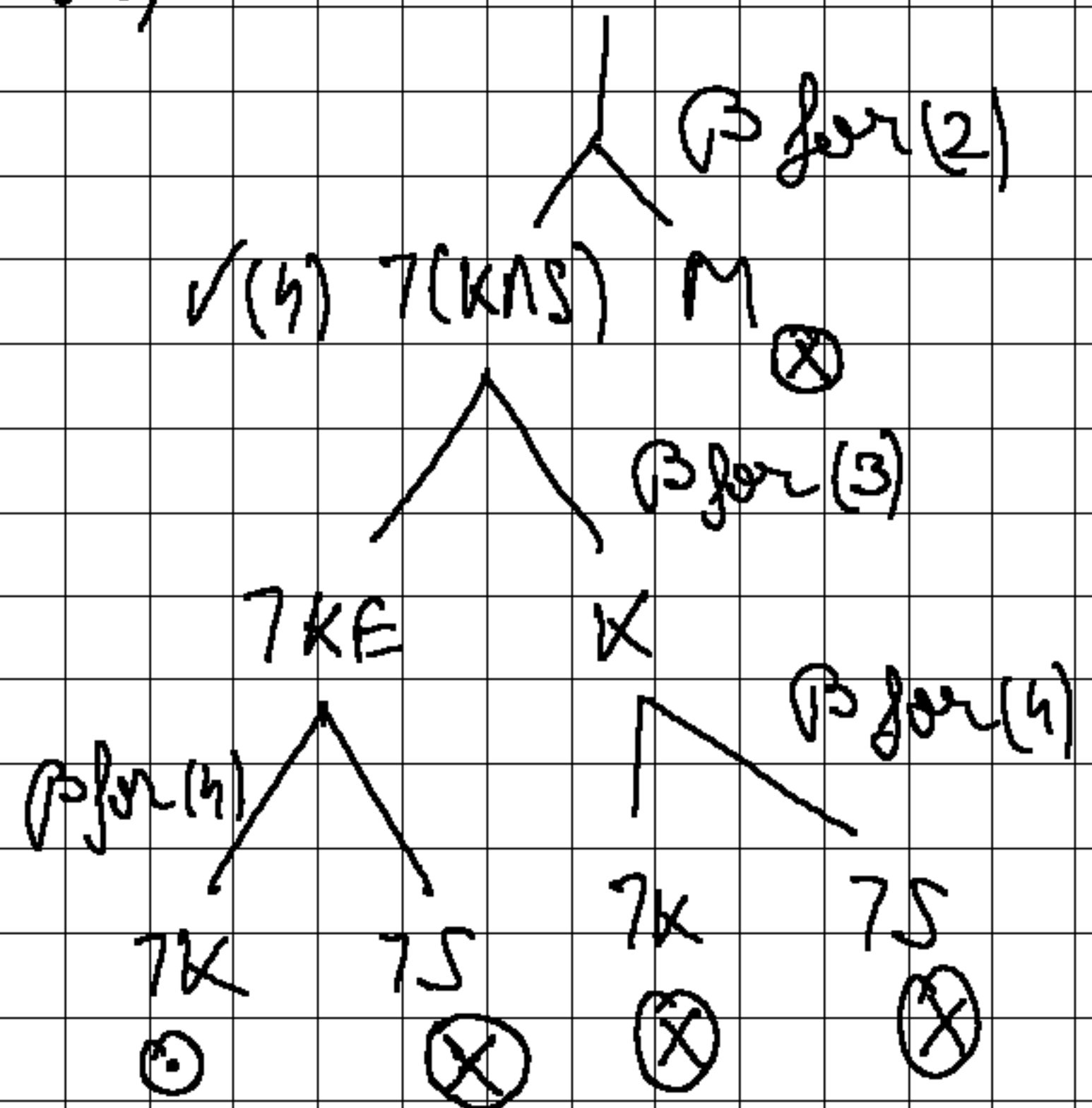
|

$$H_4: S$$

|

$$\neg C: \neg M$$

|



$$(\forall x) A(x) \equiv A(a) \wedge A(b) \wedge A(c)$$

$$x \in D \Rightarrow \{a, b, c\}$$

$$U \equiv V \text{ if}$$

$$U \models V \text{ and } V \models U$$

$$\neg(A \rightarrow B)$$

$$\begin{array}{c} | \text{ 2 rule} \\ A \\ | \\ \neg B \end{array}$$

$$\neg U_2 = \neg ((\forall x) P(x) \rightarrow (\forall x) Q(x)) \rightarrow (\forall x) (P(x) \rightarrow Q(x)) \quad (1)$$

|  $\alpha$  for (1)

$$(\forall x) P(x) \rightarrow (\forall x) Q(x) \quad (2) \checkmark$$

|

$$(\exists x) \neg (P(x) \rightarrow Q(x)) \equiv \neg (\forall x) (P(x) \rightarrow Q(x)) \quad (3) \checkmark$$

|  $\delta$  for (3),  $a$ -new const

$$\neg (P(a) \rightarrow Q(a)) \quad (4) \checkmark$$

|  $\alpha$  for (4)  $\checkmark$

$$P(a)$$

|

$$\neg Q(a)$$

|  $\rho$  for (2)

$$\neg (\forall x) P(x) \quad (5) \checkmark \quad (\forall x) Q(x) \quad (6)$$

$$\equiv (\exists x) \neg P(x)$$

|  $\delta$  for (5)

|  $b$ -new const

$$\neg P(b)$$

⊙

|  $\gamma$  for (6)

$a$ -for inst.

$$Q(a)$$

|

(6) - copy of formula (6)

⊗

$$\neg (A \rightarrow B)$$

|  $\alpha$  rule

$$A$$

|

$$\neg B$$

Models of  $\neg U_2$  are provided by the open branch  
 $i = \langle D, m \rangle$

$$\mathcal{D} = \{a, b\}$$

$$m(p) : \{a, b\} \rightarrow \{T, F\}$$

$$m(q) : \{a, b\} \rightarrow \{T, F\}$$

$$m(p)(a) = T, \quad m(p)(b) = F$$

$$m(q)(a) = F, \quad m(q)(b) = T$$

$$v^i(\neg u_2) = T, \quad v^i(u_2) = F$$

$i$  - generic model that generates concrete models

$$i_1 - \langle \mathcal{D}_1, m_1 \rangle$$

$$\mathcal{D}_1 = \{2, 3\}$$

$$m(p)(x) : "x \text{ is even}"$$

$$m(q)(x) : "x \text{ is odd}"$$