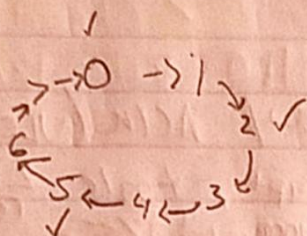


10/8 Timers

Timer A Advanced

- using multiple channels

TAR - 3-bit overflow



- use continuous mode

0 to 7 roll back to 0.

us channel 1 (TACCR1) to get a period of 3 cycle

$$TACCR1 = 2 + 3 = 5, + 3 = 80$$

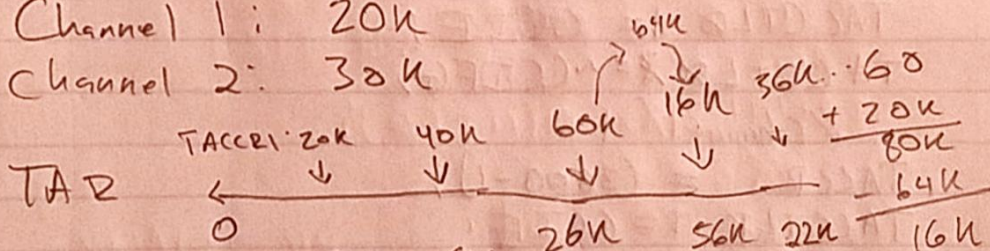
even though we have overflow
the answer is still correct

$$\begin{array}{r} 101 \\ + 011 \\ \hline 000 \end{array}$$

$$\begin{array}{l} 0 + 3 = 3 + 3 = 6 + 3 = 9 \\ ((6 + 3) \text{ Mod } 8 = 1) \end{array}$$

Channel 1: 20K

Channel 2: 30K



$$\begin{array}{r} 60K \\ + 30K \\ \hline 90K \\ - 64K \\ \hline 26K \end{array}$$

Ch. 0

TAR = TACCR0

CCIE/CCIFG \rightarrow TACCTL0

Channel 1

TAR = TACCR1

CCIE/CCIFG \rightarrow TACCTL1

E.g.

Run timer A w/ AC1K (VLO, 12KHz)
channel 0 \rightarrow interrupt, toggle LED each
(9000 cycles) .75s Red (P1.0)
Channel 1 \rightarrow green LED (P1.6)
.3s (3600 cycles)

#Define Red BIT 0

#Define Green BIT 6

main...

P1DIR = (Red | Green);

//channel 0

TACCR0 = (9000 - 1);

TACCTL0 |= CCIE;

TACCTL0 &= ~CCIFG;

//channel 1

TACCR1 = (3600 - 1);

TACCTL1 |= CCIE;

TACCTL1 &= ~CCIFG

//Clock config

TACTL = TASSEL_1 | ID_0 | MC_2 | TACLK;

-load-power-mode -3U; //set GIE

^ISR


```

void TA_A0_ISR() {
    P1Out ^ = red;
    TACCR0 += 9000 // schedule next interrupt
    // Flag cleared by hardware
}

```

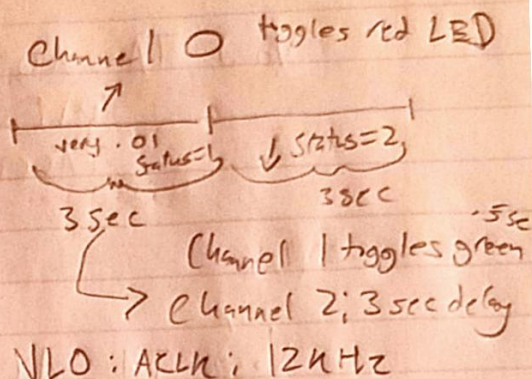
```

void TA_A1_ISR() {
    // Detect channel 1
    if (TACCTL1 & CCIFG) != 0 {
        P1OUT ^ = green;
        TACCR1 += 3000;
        TACCTL1 &= ~CCIFG
    }
}

```


Eg

$$\begin{aligned}
 &1 \text{ sec} \times 12 \text{ kHz} \\
 &= 1200 \text{ cycles Ch0} \\
 &5 \text{ sec} \times 12 \text{ kHz} \\
 &= 6000 \text{ cycles Ch1} \\
 &3 \times 12 \text{ kHz} \\
 &= 36000 \text{ cycles Ch2}
 \end{aligned}$$



#define red BIT0 int status = 1;

#define green BIT6

: main()

PIDIR |= (red | green);

// channel 0

TACCR0 = 1200 - 1

TACCTL0 |= CCIE;

TACCTL0 &= ~N(CCFG);

// ch 2

TACCR2 = 36000 - 1

TACCTL2 |= CCIE

TACCTL2 &= ~N(CCFG);

TACTL = TASSEL_1 | ID_0 | MC_2 | TACIR

- low-power-mode - 30;


```
void TA_AD_ISR() {
```

```
    P1OUT ^= Red;
```

```
    TACCR0 += 1200;
```

```
    //HW clears Flag
```

```
}
```

```
void TA_AI_ISR() {
```

```
    //Detect 1
```

```
    if (TACCTL1 & CCIFG != 0) {
```

```
        P1OUT ^= Green;
```

```
        TACCR1 += 6000;
```

```
        TACCTL1 &= ~CCIFG
```

```
    }
```

```
    if ((TACCTL2 & CCIFG) != 0) {
```

```
        if (Status == 1) { //stop channel 0
```

```
            TACCTL0 &= ~CCIE;
```

```
            P1OUT &= ~Red; (TAOR)
```

```
            TACCR1 = TAR + 6000;
```

```
            TACCTL1 |= CCIE;
```

```
            TACCTL1 &= ~CCIFG
```

```
            Status = 2;
```

```
        }
```

```
(end of code  
outside IF)
```

```
        if (Status == 2) {
```

```
            TACCTL1 &= ~CCIE;
```

```
            TACCR2 += 36000; P1OUT &= ~GreenLed;
```

```
            TACCTL &= ~CCIFG; TACCR0 = TAOR + 1200;
```

```
            TACCTL0 |= CCIE;
```

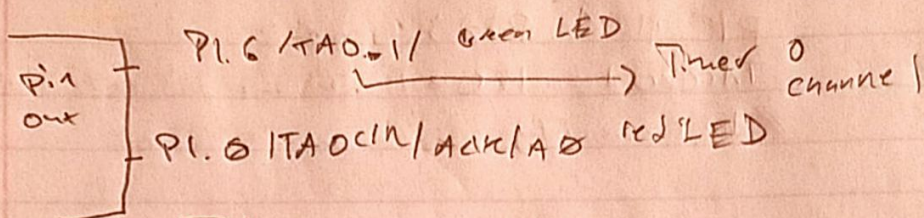
```
            TACCTL0 &= ~CCIFG;
```

```
            Status = 1; }
```

```
}
```


Timer Output

Pin is multi-use



TAx.y

↓

Timer x Channel y

P1.6 as default

look in datasheet
Tables at end
Pg 49

Port 1

PISEL0

PISEL1

PIDIR

8 uses per Pin

PIDIR = 1, PISEL1 = 1, PISEL2 = 0;

// Divert Pin to TA0.1

PIDIR 1 = BIT6;

PISEL1 1 = BIT6;

PISEL2 x = ~ (BIT6);

Patterns

- O: None

1: Set

•

3. Set /resd

4 Toggle

6: Toggle/set

7: reset / set

Eg. Channel

set / reset

Channel

$$(TAR = TACC21)$$

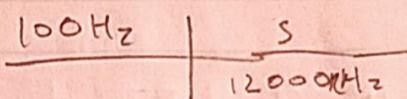
roll back to

၁

Generate a PWM on TAO.1

10042

VLO 12 kHz



120 cycles

NP node

use / set / reset

75% duty

$$TAC(2) = 40$$

TAR

40

120 110

1

28

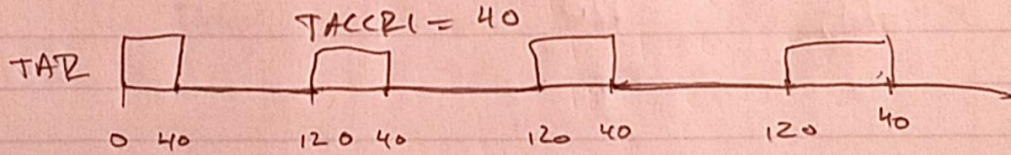
sol.

240

$$\frac{80}{120} = \text{duty cycle} = 66\%$$

120

use reset/set



Duty cycle $\frac{40}{120} = 33\%$

120

1/Divert Pins (3 lines b4)

// timer

$$TAC(20) = 120;$$
$$T_{ACTL} = T_{ASSEL_1} | ID_0 | MC_1 |$$

// (leave)

$\text{TACCR} = 40\%$

$$+ \text{ACCT} \cdot L \mid = \text{OUTMOD}_7$$

//set / reset