Recorded at time: 1522186774.33 world Broadcaster: /static_tf_world_to_optical_frame Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 optical_frame Broadcaster: /igtl_transform_to_tf_node Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 z_frame Broadcaster: /robot_state_publisher Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base_link Broadcaster: /robot_state_publisher Average rate: 10.998 Buffer length: 1.0 Most recent transform: 1522186774.31 Oldest transform: 1522186773.31 lateral translation link Broadcaster: /robot_state_publisher Average rate: 10.998 Buffer length: 1.0 Most recent transform: 1522186774.31 Oldest transform: 1522186773.31 axial_translation_link Broadcaster: /robot_state_publisher Average rate: 10.998 Buffer length: 1.0 Most recent transform: 1522186774.31 Oldest transform: 1522186773.31 vertical_translation_link Broadcaster: /robot_state_publisher Average rate: 10.998 Buffer length: 1.0 Most recent transform: 1522186774.31 Oldest transform: 1522186773.31 vertical_translation_follower_link Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Average rate: 10.998 Average rate: 10.998 Buffer length: 1.0 Buffer length: 1.0 Most recent transform: 1522186774.31 Most recent transform: 1522186774.31 Oldest transform: 1522186773.31 Oldest transform: 1522186773.31 yaw_link vertical_translation_mirror_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.998 Average rate: 10.998 Average rate: 10.998 Buffer length: 1.0 Buffer length: 1.0 Buffer length: 1.0 Most recent transform: 1522186774.31 Most recent transform: 1522186774.31 Most recent transform: 1522186774.31 Oldest transform: 1522186773.31 Oldest transform: 1522186773.31 Oldest transform: 1522186773.31 pitch_mirror_link pitch_link axial_translation_mirror_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.998 Average rate: 10.998 Buffer length: 1.0 Buffer length: 1.0 Most recent transform: 1522186774.31 Most recent transform: 1522186774.31 Oldest transform: 1522186773.31 Oldest transform: 1522186773.31 pitch_follower_link pitch_mirror_follower_link Broadcaster: /robot_state_publisher Average rate: 10.998 Buffer length: 1.0 Most recent transform: 1522186774.31 Oldest transform: 1522186773.31 needle_driver_base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.998 Average rate: $1000\overline{0}.0$ Buffer length: 1.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 1522186774.31 Oldest transform: 1522186773.31 Oldest transform: 0.0 needle_driver_link cannula Broadcaster: /robot_state_publisher Average rate: 10.998 Buffer length: 1.0 Most recent transform: 1522186774.31 Oldest transform: 1522186773.31 needle_link