AST325 Lab 3

Chris Compierchio

December 6 2021

1 Abstract

In this report, CCD images were taken to measure the positions of stars relative to the celestial coordinate system. The proper motions of asteroids were also observed. Datasets were taken from the Dunlap Institute telescope. This telescope is a 50-cm telescope located in New Mexico. It will be evident in this report that the celestial coordinates of a celestial object can be used to evaluate the object's proper motion through the analysis of surrounding stars. Various error analysis techniques were also used throughout the report.

2 Introduction

In astrometry, the proper motion of celestial objects is the measure of the observed changes in the positions of celestial objects in relation to the center of mass of the solar system. The proper motions of celestial objects can be used to determine their distance from Earth, their mass and even their speed as they fly through our solar system. In this lab, the proper motion of an asteroid is found in relation to the position of a group of stars.

The purpose of this lab was to determine the positions of stars as well as the proper motion of a given asteroid. Data taken from the Dunlap Institute telescope was used to measure the positions of the stars in a given CCD image. These stars were then compared to that of the US Naval Observatory B-1.0 star catalog. Using this data, the position of a given asteroid was found, as well as its proper motion.

3 Observations and Data

Due to the ongoing Covid-19 pandemic, the data used for this report was supplied to me by my professor.

4 Data Reduction and Methods

First, the image captured had to be corrected. The raw NGC-7331 file was a raw image of the galaxy, and due to some potential imperfections in the image, a flat correction had to be applied to it. A "dark" image and a "flat" image were both provided. The data in the dark image had to be subtracted from the raw data, and the data from the flat image had to be divided out of the raw data. The following are the dark, flat, and corrected images:

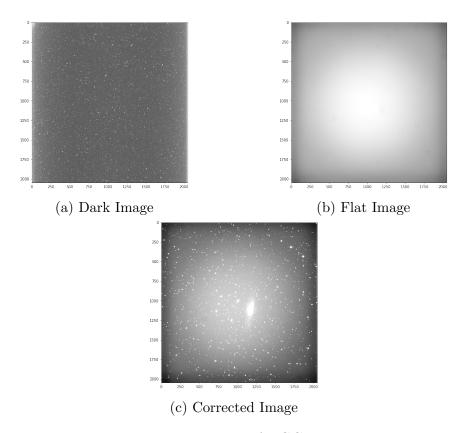


Figure 1: Images of NGC-7331

The stars located in the NGC-7331 image files were located using a centroiding method written in Python (see Appendix). A loop was created to find the brightest pixel in the image. The location of this pixel was recorded and placed in an array. A circle was drawn around this pixel, then the loop was started again. It is important to note that previously found pixels were not included when the loop ran again to avoid overlap. The centroids of each star were calculated using the following formulae:

$$< x > = \sum_{i} x_{i} I_{i} / \sum_{i} I_{i}, < y > = \sum_{i} y_{i} I_{i} / \sum_{i} I_{i}$$

The following was the resultant image:

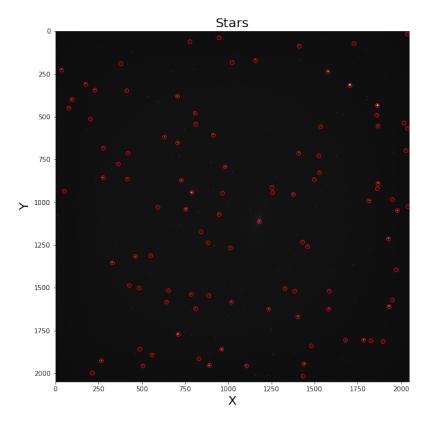


Figure 2: Locations of stars in NGC-7331 Image

Next, the USNO catalog was used to cross-correlate the stars in the NGC image. Since the USNO catalog shows stars on the celestial sphere and are measured in right ascension and declination, the pixel coordinates of the catalog were also plotted. The pixel coordinates were converted from celestial coordinates using the following formulae:

$$X = \frac{-\cos(\delta)\sin(\alpha - \alpha_0)}{\cos(\delta_0)\cos(\delta)\cos(\alpha - \alpha_0) + \sin(\delta)\sin(\delta_0)}$$

$$Y = \frac{-\sin(\delta_0)\cos(\delta)\cos(\alpha - \alpha_0) - \cos(\delta_0)\sin(\delta)}{\cos(\delta_0)\cos(\delta)\cos(\alpha - \alpha_0) + \sin(\delta)\sin(\delta_0)}$$

The following image is the USNO catalog in celestial coordinates:

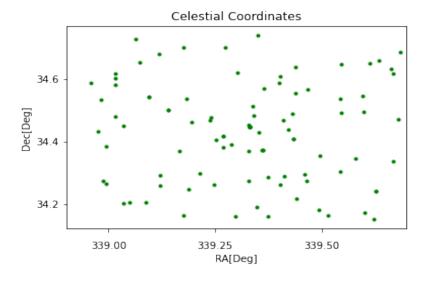


Figure 3: USNO Catalog in Celestial Coordinates

The next step was to correct the raw CCD data so that it fit the USNO data. As explained in the discussion section, the raw CCD data will have some flaws due to various reasons, and thus the data can be corrected to fit that of the USNO catalog. Below is the raw data over the USNO catalog:

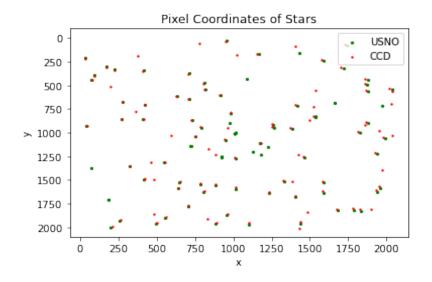


Figure 4: USNO Catalog and CCD data in Pixel Coordinates

As evident in the plot, there are a lot of outlier stars. Most of the stars from the CCD data also do not align with the USNO data, and so this could be fixed. First, removing the outlier stars gives:

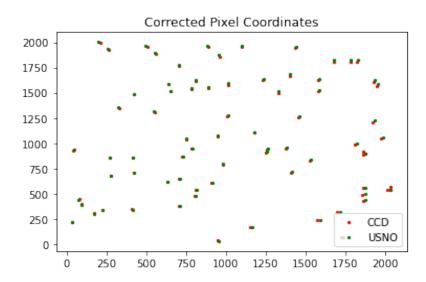


Figure 5: Corrected USNO Catalog and CCD data in Pixel Coordinates

Still, a lot of the stars are not lined up, so a correction can be performed (see appendix) to fix this and to have the raw ccd data be corrected to match that of the USNO catalog:

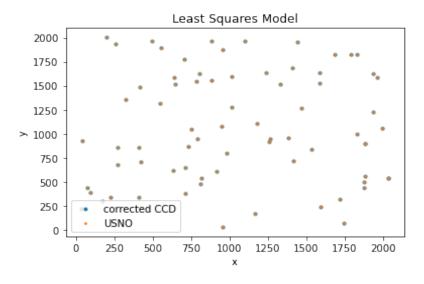


Figure 6: Corrected USNO Catalog and CCD data in Pixel Coordinates

Next, the plate constants were found using a linear least squares regression

method. The following matrix was created to store the X and Y positions of the stars:

$$\mathbf{B} = \begin{pmatrix} (f/p)X_1 & (f/p)Y_1 & 1\\ (f/p)X_2 & (f/p)Y_2 & 1\\ \vdots & \vdots & \vdots\\ (f/p)X_N & (f/p)Y_N & 1 \end{pmatrix}$$

Figure 7: Matrix B from Lab Document Appendix 5

The matrix of plate constants was then solved for by using the following matrix formula:

$$\mathbf{c} = \left(\mathbf{B}^T \mathbf{B}\right)^{-1} \mathbf{B}^T \mathbf{a} .$$

Figure 8: Equation c from Lab Document Appendix 5

where the matrix a contains the NGC star data. The plate constants were found to be 9.91E-1, 6.626E-3, 1.02E3, -4.67E-3, 9.89E-1, 1.02E3.

5 Data Analysis and Modelling

Not much error analysis was completed in this lab due to only some steps being fully completed, however, the reduced chi-squared statistic for the affine transformation was computed using the following formula:

$$\chi^2 = (B - ac)^T (a - Bc) \tag{1}$$

where B is shown in Figure 7, a contains the x or y values, and c contains the plate constants.

6 Discussion

For this lab, I was not able to compute the location nor the proper motion of the asteroid 26 Proserpina, however, I did get up to the point where I had to find the plate constants for NGC-7331. Plate constants are used for shear, rotation, translation, and magnification discrepancies between the measured data and the actual data. In this case, the measured data was the raw NGC-7331 data measured from the Dunlap Institute telescope and the actual data was the data taken from the UNSO catalog. This data was aligned using an affine transformation method shown in the appendix.

Due to the ongoing COVID-19 pandemic, I was not able to collect my own data, thus the errors given in this lab were very minimal, however, one could assume that some error was made throughout the measurement process. Not every telescope is perfect, and so the positions of the stars measured, as well as the position of the NGC-7331 galaxy, may not have been perfect.

In terms of calculated errors for this lab, the reduced chi-squared values were recorded for the affine transformation portion, as discussed in the Data Analysis and Modelling section. The values were about 6.187 for the x coordinates of the raw NGC data and about 23.96 for the y coordinates. These are quite high compared to a perfect value of 1, so this means the fit was somewhat poor. Perhaps the fit could have been improved by calibrating the telescope better.

7 Conclusion

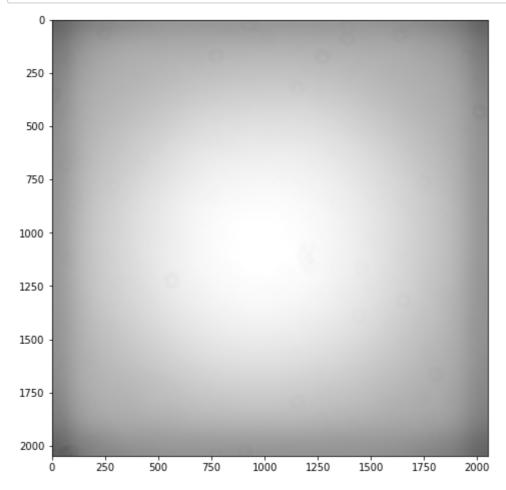
To conclude, the purpose of this lab was to perform an affine transformation to find the location of stars in an image of NGC-7331. The plate constants were found to apply transformations to a raw data image of the galaxy to align the image with the USNO catalog.

8 Appendix A

```
In [1]: #import libraries
    import numpy as np
    from scipy.optimize import curve_fit
    import matplotlib.pyplot as plt
    %matplotlib inline
    from scipy.stats import *
    import scipy as sp
    from astropy.io import fits
    import urllib as url
    from matplotlib.colors import LogNorm
    from scipy.optimize import curve_fit
    import os
    from matplotlib.ticker import MultipleLocator
    import urllib.request
    from array import *
```

```
In [2]: #open and disply the flat field data
    combflat = fits.open('combflatr.fits')
    header = combflat[0].header

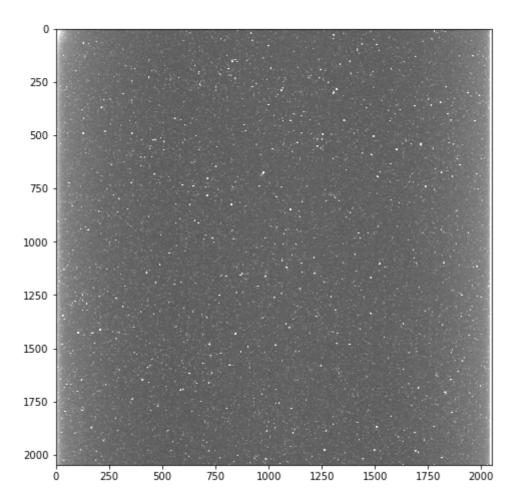
    data1 = combflat[0].data
    data1.shape
    plt.figure(figsize=(8, 8))
    plt.imshow(data1.squeeze(), vmax=np.percentile(data1, 99), cmap="gray")
    plt.show()
```



```
In [3]: #open and display the dark field data
    dark = fits.open('Dark-S001-R003-C003-B2.fts')
    header = dark[0].header

data2 = dark[0].data
    data2.shape
    plt.figure(figsize=(8, 8))
```

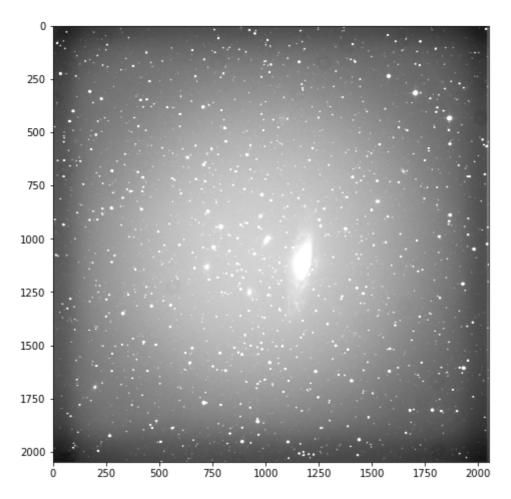
```
plt.imshow(data2.squeeze(), vmax=np.percentile(data2, 99), cmap="gray")
plt.show()
```



```
In [4]: #open and display the raw NGC data

    ngc = fits.open('NGC7331-S001-R001-C001-r.fts')
    header = ngc[0].header

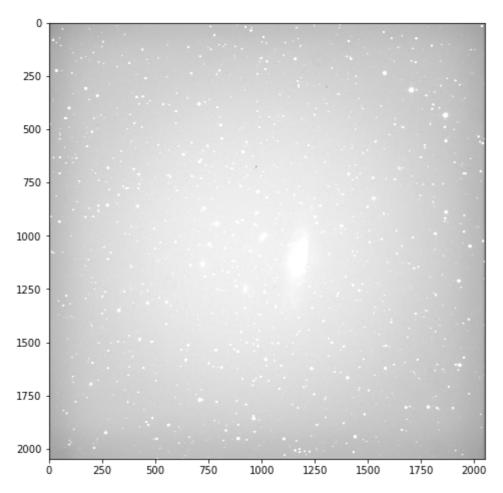
    data3 = ngc[0].data
    data3.shape
    plt.figure(figsize=(8, 8))
    plt.imshow(data3.squeeze(), vmax=np.percentile(data3, 99), cmap="gray")
    plt.show()
```



```
In [5]: #Apply data corrections

   dark_corrected_image = data3 - data1
   flat_image = dark_corrected_image/data2

   flat_image.shape
   plt.figure(figsize=(8, 8))
   plt.imshow(flat_image.squeeze(), vmax=np.percentile(flat_image, 99), cmap="gray")
   plt.show()
```



```
In [6]:
        ngc[0].header
Out[6]:
        SIMPLE
                                    16 /8 unsigned int, 16 & 32 int, -32 & -64 rea
        BITPIX
        1
                                      2 /number of axes
        NAXIS
                                  2048 /fastest changing axis
        NAXIS1
        NAXIS2
                                  2048 /next to fastest changing axis
        BSCALE
                    1.000000000000000 /physical = BZERO + BSCALE*array value
                    32768.000000000000 /physical = BZERO + BSCALE*array value
        DATE-OBS= '2011-10-13T03:18:59' / [ISO 8601] UTC date/time of exposure sta
                    2.4000000000E+002 / [sec] Duration of exposure
        EXPTIME =
        EXPOSURE=
                    2.4000000000E+002 / [sec] Duration of exposure
                   -20.00000000000000 /CCD temperature setpoint in C
        SET-TEMP=
                   -20.022502500000002 /CCD temperature at start of exposure in C
        CCD-TEMP=
                    18.00000000000000 /Pixel Width in microns (after binning)
        XPIXSZ =
                    18.00000000000000 /Pixel Height in microns (after binning)
        YPIXSZ
                                     2 / Binning level along the X-axis
        XBINNING=
        YBINNING=
                                     2 / Binning level along the Y-axis
        XORGSUBF=
                                     O /Subframe X position in binned pixels
                                     0 /Subframe Y position in binned pixels
        YORGSUBF=
        READOUTM= 'Monochrome'
                                        Readout mode of image
               = 'r
                                        / Filter name
        FILTER
        IMAGETYP= 'Light Frame' /
                                        Type of image
                    2455847.6381828706 /Julian Date at start of exposure
```

```
SWCREATE= 'MaxIm DL Version 5.15' /Name of software that created the image
SBSTDVER= 'SBFITSEXT Version 1.0' /Version of SBFITSEXT standard in effect
OBJECT = 'NGC7331 ' / Target object name
TELESCOP= 'ACP->AstroPhysicsV2' / Telescope name
INSTRUME= 'Apogee USB/Net' / Detector instrument name
OBSERVER= 'pearl '
                               / Observer name
NOTES = '
FLIPSTAT= '
CSTRETCH= 'Medium ' /
                                 Initial display stretch mode
                           4758 /Initial display black level in ADUs
CBLACK =
CWHITE =
                           6798 /Initial display white level in ADUs
                              0 /Correction to add for zero-based ADU
PEDESTAL=
SWOWNER = 'Nicholas Law' /
                              Licensed owner of software
PIERSIDE= 'WEST '
READMODE= 'Monochrome'
HISTORY File was processed by PinPoint 5.1.8 at 2011-10-13T03:23:09
DATE = '13/10/11' / [old format] UTC date of exposure start
TIME-OBS= '03:18:59' / [old format] UTC time of exposure start
UT = '03:18:59' / [old format] UTC time of exposure start
TIMESYS = 'UTC ' / Default time system
RADECSYS= 'FK5 ' / Equatorial coordinate system
AIRMASS = 1.01786463149E+000 / Airmass (multiple of zenithal airmass)
ST = '21 46 26.71' / Local apparent sidereal time of exp. star
LAT-OBS = 3.29027777778E+001 / [deg +N WGS84] Geodetic latitude
\texttt{LONG-OBS=} \quad -1.055294444444E+002 \; / \; [\texttt{deg} \; + \texttt{E} \; \texttt{WGS84}] \; \; \texttt{Geodetic longitude}
ALT-OBS = 2.28600000000E+003 / [metres] Altitude above mean sea level
OBSERVAT= 'Dunlap Institute Telescope' / Observatory name
RA = '22 37 18.00' / [hms J2000] Target right ascension

OBJCTRA = '22 37 18.00' / [hms J2000] Target right ascension

DEC = '+34 26 37.0' / [dms +N J2000] Target declination

OBJCTDEC= '+34 26 37.0' / [dms +N J2000] Target declination

CLRBAND = 'R ' / [J-C std] Std. color band of image or C=C
HISTORY File was processed by PinPoint 5.1.8 at 2011-10-13T03:23:12
FWHM = 3.00714285374E+000 / [pixels] Mean Full-Width-Half-Max of imag
e star
ZMAG = 2.13868141962E+001 / Mag zero point for 1 sec exposure
EQUINOX =
                         2000.0 / Equatorial coordinates are J2000
EPOCH =
                         2000.0 / (incorrect but needed by old programs)
       = 3.59607090401E+002 / [deg, 0-360 CCW] Position angle of plate
CTYPE1 = 'RA---TAN'
                                / X-axis coordinate type
CRVAL1 = 3.39323757154E+002 / X-axis coordinate value
CRPIX1 = 1.02400000000E+003 / X-axis reference pixel
CDELT1 = -3.02101567107E-004 / [deg/pixel] X-axis plate scale
CROTA1 = 3.92909599100E-001 / [deq] Roll angle wrt X-axis
CTYPE2 = 'DEC--TAN'
                                / Y-axis coordinate type
CRVAL2 = 3.44422583580E+001 / Y-axis coordinate value
CRPIX2 = 1.02400000000E+003 / Y-axis reference pixel
CDELT2 = -3.02093176153E-004 / [deg/pixel] Y-Axis Plate scale
CROTA2 = 3.92909599100E-001 / [deg] Roll angle wrt Y-axis
CD1 1 = -3.02094463788E-004 / Change in RA---TAN along X-Axis
CD1 2 = 2.07160770733E-006 / Change in RA---TAN along Y-Axis
CD2 1 = -2.07166524840E-006 / Change in DEC--TAN along X-Axis
CD2 2 = -3.02086073032E-004 / Change in DEC--TAN along Y-Axis
TR1 0 = 1.02400018028E+003 / [private] X-axis distortion coefficients
TR1 1 = 2.04799671349E+003
TR1 2 = 3.72920358941E-001
TR1 3 = -1.10176001632E+000
TR1 4 = 6.14118869027E-001
TR1 5 = 1.33546162035E+000
TR1 6 = -1.68132125691E+001
```

TR1 7

= -5.28489033454E-001

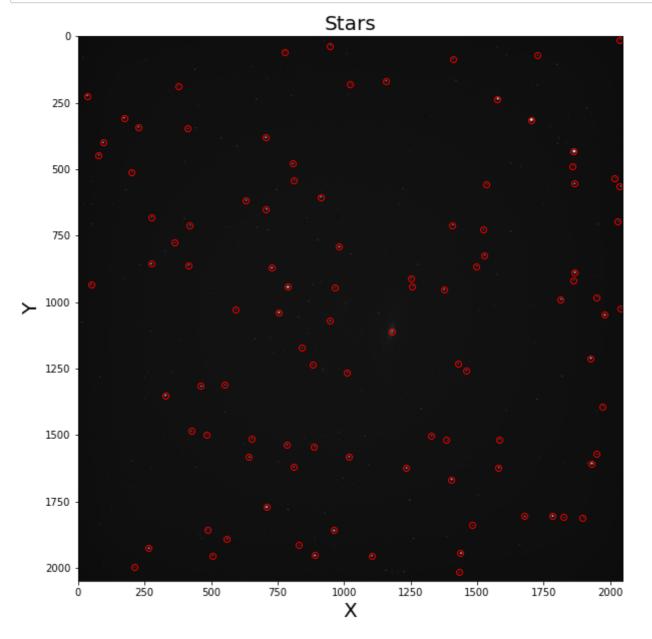
```
TR1 8 = -1.66768099978E+001
TR1 9 = -8.70764421003E-001
TR1\ 10 = 6.74820735702E+000
TR1 \ 11 = -3.41773431836E-001
TR1 12 = -1.97099962308E+000
TR1 13 = -4.09332492302E+000
TR1 14 = -6.97403954973E+000
TR2 0 = 1.02400000190E+003 / [private] Y-axis distortion coefficients
TR2\ 1 = 8.14160451750E-004
TR2\ 2 = 2.04800325275E+003
TR2_3 = -1.30017295160E+000
TR2 \ 4 = 2.02862478441E-001
TR2 5 = 1.42480374856E+000
TR2 6 = 3.95929171698E-001
TR2 7 = -1.75225246797E+001
TR2 8 = -1.85398173971E-002
TR2 9 = -1.65353549125E+001
TR2\ 10 = 3.68000553150E+000
TR2 11 = 1.31069271342E-001
TR2 12 = 2.31093410921E+000
TR2 13 = -1.19829063444E+000
TR2 14 = -1.08828903572E+001
HISTORY WCS added by PinPoint 5.1.8 at 2011-10-13T03:23:12
HISTORY Matched 239 stars from the Gray GSC-ACT Catalog
HISTORY Average residual was 0.26 arc-seconds
PLTSOLVD=
                           T / Plate has been solved by PinPoint
```

```
In [7]: #function that finds centroid of image
        def centroid(image):
            xvals = np.arange(image.shape[1])
            yvals = np.arange(image.shape[0])
            centroid x = np.sum(xvals*image)/np.sum(image)
            centroid y = np.sum(yvals*image.T)/np.sum(image)
            return np.array([centroid y, centroid x])
        background = np.median(flat image)
        star locations = []
        BOX SIZE = 10
        im = flat image.copy()
        #find stars
        for i in range (100):
            #find brightest pixel in the image
            brightest pixel = np.array([np.where(im == np.max(im))[0][0], np.where(i
        m == np.max(im))[1][0]]
            #create a "box" around that pixel
            box = im[brightest pixel[0]-BOX SIZE:brightest pixel[0]+BOX SIZE+1,
                     brightest pixel[1]-BOX SIZE:brightest pixel[1]+BOX SIZE+1]
            box -= background
            #Get the centroid of that box
            c = centroid(box)
            #Map the centroid of the box back onto the orginal image
            c = np.array([box.shape[1]//2,box.shape[0]//2])
            c += brightest pixel
            star locations.append(c)
            #Remove that star from the image so it isn't the brightest pixel anymore
```

```
box[:,:] = background

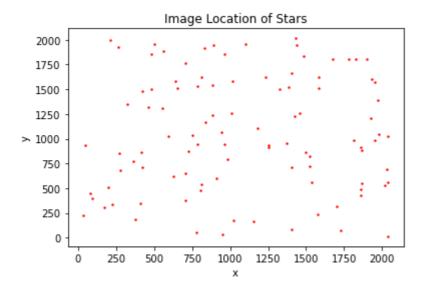
#store and plot star locations
star_locations = np.array(star_locations)

plt.figure(figsize=(10,10))
plt.plot(star_locations[:,1], star_locations[:,0], 'o', color = 'r', alpha = 1, fillstyle = "none")
plt.imshow(flat_image, cmap = 'gray')
plt.title("Stars", size = 20)
plt.xlabel("X", size = 20)
plt.ylabel("Y", size = 20)
plt.show()
```



```
In [8]: #plot star locations off of picture
   plt.scatter(star_locations[:,1], star_locations[:,0], color='r', s =2)
    plt.title("Image Location of Stars")
    plt.xlabel("x")
   plt.ylabel("y")
```

Out[8]: Text(0, 0.5, 'y')

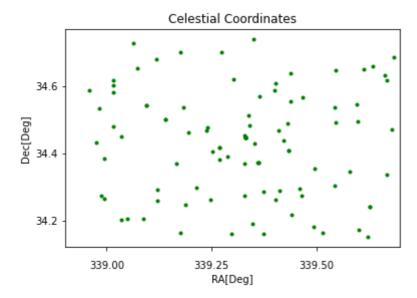


```
In [9]:
         #Get the stars from the USNO catalog
         def usno(radeg, decdeg, fovam):
             str1 = 'http://webviz.u-strasbg.fr/viz-bin/asu-tsv/?-source=USNO-B1'
             str2 = \frac{4.6f}{6-c.dec} = \frac{4.6f}{6-c.bm} = \frac{4.7f}{4.7f} = \frac{4.7f}{6-out.max} = \frac{4.7f}{6-out.max}
         imited'.format(radeg, decdeg, fovam, fovam)
             sr = str1+str2
             f = urllib.request.urlopen(sr)
             s = f.read()
             f.close()
             namecol, RAcol, DECcol, rband = 0, 1, 2, 12
             null1, null2 ='
             s1 = s.splitlines()
             s1 = s1[45:-1] # get rid of header
             name = np.array([])
             rad = np.array([]) # RA in degrees
             ded = np.array([]) # DEC in degrees
             rmag = np.array([]) # rmage
             for k in s1:
                 kw = k.decode().split('\t')
                 if kw[0] != '':
                      name = np.append(name, kw[namecol])
                      rad = np.append(rad,float(kw[RAcol]))
                      ded = np.append(ded, float(kw[DECcol]))
                      # deal with case where no mag is reported
                      if (kw[rband] != null2) and (kw[rband] != null1):
                          rmag = np.append(rmag, float(kw[rband]))
                      else:
                          rmag = np.append(rmag,np.nan)
             return name, rad, ded, rmag
         s1 = ngc
         #readpositionfromtheFITSfileandconvertRA/DECtodegrees
         ras= s1[0].header['ra']
         des = s1[0].header['dec']
```

```
radeg = 15*(float(ras[0:2])+float(ras[3:5])/60.+ float(ras[6:])/3600.)
dsgn = np.sign(float(des[0:3]))
dedeg = float(des[0:3]) + dsgn*float(des[4:6])/60.+ dsgn*float(des[7:])/3600.
fovam=36.4
type (fovam)
#sizeofsquaresearchfieldinarcmin
name, rad, ded, rmag= usno (radeg, dedeg, fovam)
w=np.where(rmag < 13.)[0]
#selectonlybrightstarsr<15mag.
plt.plot(rad[w], ded[w], 'g.')
plt.locator params(axis='x', nbins=4)
plt.locator params(axis='y', nbins=4)
plt.tick params('x',pad=10)
plt.xlabel('RA[Deg]')
plt.ylabel('Dec[Deg]')
plt.title("Celestial Coordinates")
plt.ticklabel format(useOffset=False)
#plt.axis('scaled')
plt.xlim([338.9,339.7])
```

<ipython-input-9-8913fb3dfb1a>:45: RuntimeWarning: invalid value encounter
ed in less
 w=np.where(rmag < 13.)[0]</pre>

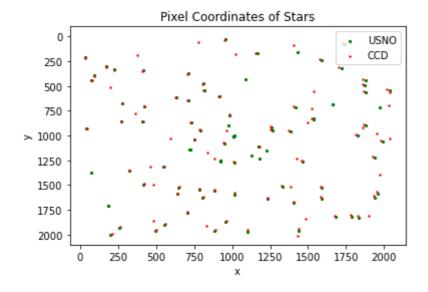
Out[9]: (338.9, 339.7)



```
In [10]: #function that converts from celestial coordinates to standard coordinates
          def standardcoords(rad, dec, a0, d0):
              ra = rad*np.pi/180
              dc = dec*np.pi/180
              a0 = a0*np.pi/180
              d0 = d0*np.pi/180
              cos ra = np.cos(ra)
              sin_ra = np.sin(ra)
              cos dc = np.cos(dc)
              sin dc = np.sin(dc)
              X = -(\cos dc^*np.\sin(ra - a0))/(np.\cos(d0)^*\cos dc^*(np.\cos(ra - a0))+(\sin dc^*np.\sin(ra - a0))
          dc*np.sin(d0))
              Y = -(np.sin(d0)*cos dc*np.cos(ra-a0)-((np.cos(d0)*sin dc)))/(np.cos(d0)
          *cos dc*np.cos(ra-a0)+(sin dc*np.sin(d0)))
              return X, Y
         X, Y = standardcoords(rad[w], ded[w], radeg, dedeg)
```

```
In [11]: | #convert from standard to pixel coordinates
          f = 3454
          p = 0.009*2
          x0 = 1024
          y0 = 1024
          theta = np.pi
          x=((f/p)*(X*np.cos(theta)-Y*np.sin(theta)))+x0
          y = ((f/p)*(X*np.sin(theta)+Y*np.cos(theta)))+y0
          x \text{ new} = \text{list}(\text{map}(\textbf{lambda} \text{ xi: } 2048-\text{xi, } x))
          x new = np.array(x new)
          #plot the raw data over the usno data
          plt.scatter(x_new,y, s = 5, color = "green", label = "USNO")
          plt.title("Pixel Coordinates of Stars")
          plt.xlabel("x")
          plt.ylabel("y")
          plt.ylim(2100, -100)
          plt.scatter(star locations[:,1], star locations[:,0], color='r', s =2, label
          = "CCD")
          plt.legend(loc="best")
```

Out[11]: <matplotlib.legend.Legend at 0x1e1dc734310>



```
In [49]: | #define the affine transformation function to solve for the proper positions
         of the stars
         def leastsquares(X,Y, data):
             B = []
             ax = []
             ay = []
             for i in range(X.size):
                  B.append([(f/p)*X[i], (f/p)*Y[i], 1])
                 ax.append(data[0][i])
                  ay.append(data[1][i])
             B = np.array(B)
             ax = np.array(ax)
             ay = np.array(ay)
             Bt = B.T
             Binv = np.linalg.inv(np.dot(Bt,B))
             c x = np.dot(Binv, np.dot(Bt, ax))
```

```
c_y = np.dot(Binv,np.dot(Bt, ay))

a_11 = c_x[0]
a_12 = c_x[1]
x_0 = c_x[2]

a_21 = c_y[0]
a_22 = c_y[1]
y_0 = c_y[2]

chisq_x = np.dot((ax-np.dot(B, c_x)).T, (ax-np.dot(B, c_x)))
chisq_y = np.dot((ay-np.dot(B, c_y)).T, (ay-np.dot(B, c_y)))

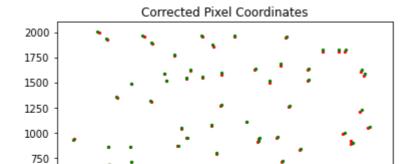
redchi_x = chisq_x/(ax.size-3)
redchi_y = chisq_y/(ay.size-3)

constants = np.array([a_11, a_12, x_0, a_21, a_22, y_0, redchi_x, redchi_y])

return constants
```

```
In [66]: #define a function that removes outlier stars
         def stars(x1, y1, x2, y2, threshold):
             x1new=[]
             y1new=[]
             x2new=[]
             y2new=[]
             for i in range (x1.size):
                  for j in range (x2.size):
                      if (abs(x1[i]-x2[j])<threshold) and (abs(y1[i]-y2[j])<threshold
         ):
                          x1new.append(x1[i])
                          x2new.append(x2[j])
                          ylnew.append(y1[i])
                          y2new.append(y2[j])
                          break
                 return np.array([x1new, x2new, y1new, y2new])
         new_stars = stars(star_locations[:,1],star_locations[:,0],x_new, y, 25)
         x ccd = new stars[0]
         y_ccd = new_stars[2]
         x_usno = new_stars[1]
         y_usno = new_stars[3]
         #plot the raw data over the usno data with outliers removed
         plt.scatter(x ccd, y ccd, color='r', s =5, label = "CCD")
         plt.scatter(x usno, y usno, s = 5, color = "green", label = "USNO")
         plt.legend(loc="best")
         plt.title("Corrected Pixel Coordinates")
```

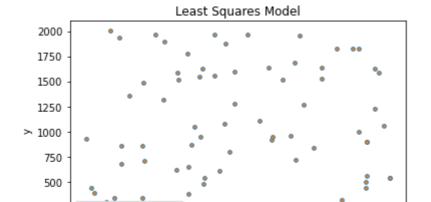
Out[66]: Text(0.5, 1.0, 'Corrected Pixel Coordinates')



```
500
250
                                                         CCD
                                                         USNO
  0
                                     1250
                                            1500
           250
                  500
                         750
                               1000
                                                   1750
                                                          2000
```

```
In [69]:
         #function converts to pixel coords from standard coords
         def pixel(x, y):
             p = 0.018
             f = 3454
             X = np.array(x-1024)*(p/f)
             Y = np.array(y-1024)*(p/f)
             return(X,Y)
         #find plate constants
         pixelxy = pixel(x_usno, y_usno)
         new data = []
         new data.append(x ccd)
         new_data.append(y_ccd)
         plates = leastsquares(pixelxy[0], pixelxy[1], new data)
         plates
Out[69]: array([ 9.90968666e-01, 6.26058014e-03,
                                                   1.01997310e+03, -4.66607055e-03,
                 9.89248758e-01, 1.01942775e+03,
                                                   6.18704091e+00, 2.39578252e+0
         1])
In [70]:
         #use curve fit to find the correct star locations
         def model function (x, a, b, c):
             return (a*x + b*x + c)
         p optx, p covx = curve fit(model function, pixelxy[0], x usno, p0 = [0,0,150
         p opty, p covy = curve fit(model function, pixelxy[1], y usno, p0 = [0,0,150]
         0])
         xs = model function(pixelxy[0], p optx[0], p optx[1], p optx[2])
         ys = model_function(pixelxy[1], p_opty[0], p_opty[1], p_opty[2])
         xs new = list(map(lambda xi: 2048-xi, xs))
         xs new = np.array(xs new)
         #plot corrected star locations over usno data
         plt.scatter(xs,ys, s = 13, label = "corrected CCD")
         plt.scatter(x usno, y usno, s = 3, label = "USNO")
         plt.title("Least Squares Model")
         plt.xlabel("x")
         plt.ylabel("y")
         plt.legend(loc="best")
```

Out[70]: <matplotlib.legend.Legend at 0x1e1e3473280>



250 Corrected CCD USNO 1250 1500 1750 2000 x