

**FORMULE KOJE JE DOZVOLJENO IMATI NA KOLOKVIJU I PISMENOM ISPITU IZ  
KOLEGIJA "SIGNALI I SUSTAVI", Studij Računarstvo. 120**

**Eulerove relacije:**

$$Ae^{j\omega_0 t} = A \cos(\omega_0 t) + j A \sin(\omega_0 t)$$

$$Ae^{-j\omega_0 t} = A \cos(\omega_0 t) - j A \sin(\omega_0 t)$$

$$\cos(\omega_0 t) = \frac{e^{j\omega_0 t} + e^{-j\omega_0 t}}{2}$$

$$\sin(\omega_0 t) = \frac{e^{j\omega_0 t} - e^{-j\omega_0 t}}{2j}$$

$$\int \ln x \, dx = x \ln x - x + C$$

$$\int \log_b x \, dx = x \log_b x - x \log_b e + C$$

$$\int e^x \, dx = e^x + C$$

$$\int a^x \, dx = \frac{a^x}{\ln a} + C$$

$$\int \frac{dx}{\sqrt{a^2 - x^2}} = \arcsin \frac{x}{a} + C$$

$$\int \frac{dx}{a^2 + x^2} = \frac{1}{a} \arctan \frac{x}{a} + C$$

$$\int \frac{dx}{a^2 - x^2} = \frac{1}{a} \operatorname{arth} \frac{x}{a} + C = \frac{1}{2a} \ln \left| \frac{a+x}{a-x} \right| + C$$

$$\int \frac{dx}{x^2 - a^2} = -\frac{1}{a} \operatorname{arth} \frac{x}{a} + C = \frac{1}{2a} \ln \left| \frac{x-a}{x+a} \right| + C$$

**Osnovne trigonometrijske relacije:**

$$\sin(x \pm y) = \sin(x)\cos(y) \pm \cos(x)\sin(y)$$

$$\cos(x \pm y) = \cos(x)\cos(y) \mp \sin(x)\sin(y)$$

$$\sin(x)\sin(y) = 0.5(\cos(x-y) - \cos(x+y))$$

$$\cos(x)\cos(y) = 0.5(\cos(x-y) + \cos(x+y))$$

$$\sin(x)\cos(y) = 0.5(\sin(x-y) + \sin(x+y))$$

$$\sin(2x) = 2\sin(x)\cos(x)$$

$$\cos(2x) = \cos^2(x) - \sin^2(x)$$

$$2\sin^2(x) = 1 - \cos(2x)$$

$$2\cos^2(x) = 1 + \cos(2x)$$

**Sume:**

$$\sum_{k=0}^{\infty} \alpha^k = \frac{1}{1-\alpha}, \text{ ako je } 0 < |\alpha| < 1$$

$$\sum_{k=0}^n \alpha^k = \frac{1-\alpha^{n+1}}{1-\alpha}$$

$$\sum_{i=1}^n i = \frac{n(n+1)}{2}$$

$$\sum_{i=1}^n i^2 = \frac{n(n+1)(2n+1)}{6}$$

$$\int x^n \, dx = \frac{x^{n+1}}{n+1} + C, n \neq -1$$

$$\int \frac{dx}{x} = \ln |x| + C$$

$$\int \sin x \, dx = -\cos x + C$$

$$\int \cos x \, dx = \sin x + C$$

$$\int \frac{dx}{\sin^2 x} = -\operatorname{ctg} x + C$$

$$\int \frac{dx}{\cos^2 x} = \operatorname{tg} x + C$$

$$\int \operatorname{sh} x \, dx = \operatorname{ch} x + C$$

**Laplace-ova transformacija:**

$$L\{x(t)\} = X(s) = \int_{-\infty}^{\infty} x(t)e^{-st} \, dt,$$

$$s = \sigma + j\omega$$

za  $x(t) = 0$  pri  $t < 0$ :

$$L\{x(t)\} = X(s) = \int_0^{\infty} x(t)e^{-st} \, dt$$

**Tablica Laplace-ovih transformacija osnovnih funkcija:**

$x(t)$ , pri čemu je $x(t) = 0$ za $t < 0$	$X(s)$		$x(t)$ , pri čemu je $x(t) = 0$ za $t < 0$	$X(s)$		$x(t)$ , pri čemu je $x(t) = 0$ za $t < 0$	$X(s)$
$\delta(t)$	1		$\sin(\omega t)$	$\frac{\omega}{s^2 + \omega^2}$		$e^{\pm at} \sin(\omega t)$	$\frac{\omega}{(s \mp a)^2 + \omega^2}$
$u(t)$	$1/s$		$\cos(\omega t)$	$\frac{s}{s^2 + \omega^2}$		$e^{\pm at} \cos(\omega t)$	$\frac{s \mp a}{(s \mp a)^2 + \omega^2}$
$t$	$1/s^2$		$e^{\pm at}$	$\frac{1}{s \mp a}$		$te^{\pm at}$	$\frac{1}{(s \mp a)^2}$
$t^2$	$2/s^3$		$t^n$	$n! / s^{n+1}$			

**LT pomaknutog signala:**

$$L\{x(t \pm a)u(t \pm a)\} = e^{\pm as} X(s)$$

$$L\{e^{\pm as} x(t)u(t)\} = X(s \mp a)$$

**LT derivacije signala:**

$$L\left\{\frac{d^n x(t)}{dt^n}\right\} = s^n X(s) - s^{n-1}x(0) - s^{n-2}\dot{x}(0) - s^{n-3}\ddot{x}(0) - \dots$$

**LT integrala signala:**

$$L\{n - \operatorname{tog} \operatorname{integrala} \text{ od } x(t)\} = \frac{1}{s^n} X(s)$$

**Formula za određivanje residuuma višestrukih polova prijenosne funkcije:**

$$W(s) = \frac{Br(s)}{(s-p_1)^m (s-p_2) \dots (s-p_n)} = \frac{K_1}{(s-p_1)^m} + \frac{K_2}{(s-p_1)^{m-1}} + \frac{K_3}{(s-p_1)^{m-2}} + \dots + \frac{K_m}{s-p_1} + \frac{K_{m+1}}{s-p_2} + \dots + \frac{K_{m+n-1}}{s-p_n}$$

$$K_1 \dots K_i \dots K_m: \text{ residuumi } m\text{-strukog pola računaju se prema formuli: } K_i = \frac{1}{(i-1)!} \frac{d^{i-1}}{ds^{i-1}} [(s-p_1)^m W(s)] \Big|_{s=p_1}$$