Stochastic Processes: Midterm Exam

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Problem 1.

(A) We know the deck contains 10 cards and that the draws are independent and uniform. Hence, the probability of drawing any single card is $\frac{1}{10}$. So, if we suppose that we have seen a certain card i times in a row, the probability of selecting that card for the i+1 time in a row would be $\frac{1}{10}$. Thus, it is clear that, for $n \geq 1$, we have $P(X_{n+1} = i + 1 | X_n = i, X_{n-1} = i_{n_1}, \dots, X_0 = 0) = \frac{1}{10} = P(X_{n+1} = i + 1 | X_n = i)$.

In the case of n=0, we have $X_0=0$ by definition. In addition, note that $P(X_{n+1}=0|X_n=i)=\frac{9}{10}$ for $i\neq 0$. Since $X_{n+1}=i+1, X_{n+1}=0$ are the only possible transitions from $X_n=i, i\neq 0$, we have that they add up to 1 as required. Moreover, we can define any other transitions as 0 probability, so $p(i,j)\geq 0$ for any i,j in the state space as required. In the case of i=0, these conditions still hold, as the only possible transition is $P(X_{n+1}=1|X_n=0)=1$.

As a result, we have that this defines a valid Markov chain with the following transition probability matrix,

$$p = \begin{pmatrix} 0 & 1 & 2 & 3 & 4 & \cdots \\ 0 & 1 & 0 & 0 & 0 & \cdots \\ 9/10 & 0 & 1/10 & 0 & 0 & \cdots \\ 9/10 & 0 & 0 & 1/10 & 0 & \cdots \\ 9/10 & 0 & 0 & 0 & 1/10 & \cdots \\ \vdots & & \vdots & & \cdots \end{pmatrix}$$

That is, we have,

$$p(0,1) = 1$$

and for i > 0, we have,

$$p(i,0) = 9/10$$
$$p(i,i+1) = 1/10$$

(B) Let us consider the transition matrix \tilde{p} , where we eliminate every state after 9 and consider state 9 an absorbing state:

We are able to make this change because we have not altered any of the states which lead to 9 and for the purposes of this analysis, we do not need to consider any of the states which come after 9. Let us now construct the matrix r by removing the rows and columns corresponding to state 9:

$$r = \begin{pmatrix} 0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 9/10 & 0 & 1/10 & 0 & 0 & 0 & 0 & 0 & 0 \\ 9/10 & 0 & 0 & 1/10 & 0 & 0 & 0 & 0 & 0 \\ 9/10 & 0 & 0 & 0 & 1/10 & 0 & 0 & 0 & 0 \\ 9/10 & 0 & 0 & 0 & 1/10 & 0 & 0 & 0 \\ 5 & 9/10 & 0 & 0 & 0 & 0 & 1/10 & 0 & 0 \\ 6 & 7 & 9/10 & 0 & 0 & 0 & 0 & 0 & 1/10 & 0 \\ 7 & 9/10 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/10 \\ 8 & 9/10 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Now we must evaluate I - r, where I is the 9×9 identity matrix,

$$I - r = \begin{bmatrix} 0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ -9/10 & 1 & -1/10 & 0 & 0 & 0 & 0 & 0 & 0 \\ -9/10 & 0 & 1 & -1/10 & 0 & 0 & 0 & 0 & 0 \\ -9/10 & 0 & 0 & 1 & -1/10 & 0 & 0 & 0 & 0 \\ -9/10 & 0 & 0 & 1 & -1/10 & 0 & 0 & 0 \\ 5 & -9/10 & 0 & 0 & 0 & 1 & -1/10 & 0 & 0 \\ 6 & -9/10 & 0 & 0 & 0 & 0 & 1 & -1/10 & 0 \\ 7 & -9/10 & 0 & 0 & 0 & 0 & 0 & 1 & -1/10 \\ 8 & -9/10 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Once we take the inverse and multiply by the column vector of all 1s, we get,

$$(I-r)^{-1}\mathbb{1} = \begin{pmatrix} 211, 111, 110 \\ \vdots \end{pmatrix}$$

So the expected number of moves starting from state 0 is 211, 111, 110. For a brief sanity check, we see that the probability of seeing a specific card 9 times in a row is

$$1 \cdot \frac{1}{10^8} = \frac{1}{100,000,000}$$
$$= 1 \times 10^{-8}$$

So our answer makes sense given the extremely low probability of reaching state 9.

Problem 2.

The system of equations for f_1 is,

$$f_1(a) = \frac{1}{3}$$

$$f_1(b) = \frac{1}{6}$$

$$f_1(c) = \frac{1}{3}$$

$$f_1(d) = 0$$

$$f_1(e) = \frac{1}{6}$$

Then for f_2 we have,

$$f_2(a) = \frac{1}{6}$$

$$f_2(b) = \frac{1}{6}$$

$$f_2(c) = \frac{1}{12}$$

$$f_2(d) = \frac{1}{4}$$

$$f_2(e) = \frac{1}{6}$$

And for f_3 ,

$$f_3(a) = \frac{1}{12}$$

$$f_3(b) = \frac{1}{8}$$

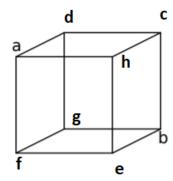
$$f_3(c) = \frac{5}{24}$$

$$f_3(d) = \frac{1}{8}$$

$$f_3(e) = \frac{5}{12}$$

Problem 3.

Let us label the vertices as follows:



Since each vertex is connected to three other vertices, we have that the transition probability is 1/3 between any two vertices sharing an edge and 0 between all others. This yields the following transition probability matrix:

$$p = \begin{pmatrix} a & b & c & d & e & f & g & h \\ 0 & 0 & 0 & 1/3 & 0 & 1/3 & 0 & 1/3 \\ 0 & 0 & 1/3 & 0 & 1/3 & 0 & 1/3 & 0 \\ 0 & 1/3 & 0 & 1/3 & 0 & 0 & 0 & 1/3 \\ d & 1/3 & 0 & 1/3 & 0 & 0 & 0 & 1/3 & 0 \\ e & d & 0 & 1/3 & 0 & 0 & 0 & 1/3 & 0 \\ 0 & 1/3 & 0 & 0 & 0 & 1/3 & 0 & 1/3 \\ f & 1/3 & 0 & 0 & 0 & 1/3 & 0 & 1/3 & 0 \\ g & 0 & 1/3 & 0 & 1/3 & 0 & 1/3 & 0 & 0 \\ h & 1/3 & 0 & 1/3 & 0 & 1/3 & 0 & 0 & 0 \end{pmatrix}$$

Now we need to find $P(T_a < T_b | X_0 = a)$. That is, the probability that the first return to a will be sooner than the first return to b when we start from state a.

We have three distinct cases here: $X_1 = d$, $X_1 = h$, and $X_1 = f$. We will consider all three cases with both a and b as absorbing states. Thus, the probability $P(T_a < T_b | X_0 = a)$ will be equivalent to $\frac{1}{3}(\lim_{n\to\infty} \tilde{p}^n(d,a) + \lim_{n\to\infty} \tilde{p}^n(h,a) + \lim_{n\to\infty} \tilde{p}^n(f,a))$. This is true because, since a and b are both absorbing states, $\lim_{n\to\infty} \tilde{p}^n(d,a)$ will show the probability

of reaching a (and therefore not reaching b) starting from state d. The case of the other two states is the same. We multiply by 1/3 because each possibility for $X_1 = d, h, f$ has a 1/3 chance of occurring.

Let us now set up the new transition probability matrix:

$$\tilde{p} = \begin{pmatrix} a & b & c & d & e & f & g & h \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1/3 & 0 & 1/3 & 0 & 0 & 0 & 1/3 \\ 1/3 & 0 & 1/3 & 0 & 0 & 0 & 1/3 & 0 \\ 0 & 1/3 & 0 & 0 & 0 & 1/3 & 0 & 1/3 \\ f & 1/3 & 0 & 0 & 0 & 1/3 & 0 & 1/3 & 0 \\ g & h & 1/3 & 0 & 1/3 & 0 & 1/3 & 0 & 0 \\ h & 1/3 & 0 & 1/3 & 0 & 1/3 & 0 & 0 & 0 \end{pmatrix}$$

Note that we can reformulate our above discussion such that,

$$P(T_a < T_b | X_0 = a) = \frac{1}{3} (\lim_{n \to \infty} \tilde{p}^n(d, a) + \lim_{n \to \infty} \tilde{p}^n(h, a) + \lim_{n \to \infty} \tilde{p}^n(f, a))$$

$$= \frac{1}{3} (P(V_a < V_b | X_0 = d) + P(V_a < V_b | X_0 = h) + P(V_a < V_B | X_0 = f))$$

This is possible since a and b are both absorbing states now.

Now let $P_x(V_a < V_b) =: j(x)$. Let j(a) = 1 and j(b) = 0. Then we have the following system of equations,

$$j(a) = 1$$

$$j(b) = 0$$

$$j(c) = \frac{1}{3}(j(d) + j(h))$$

$$j(d) = \frac{1}{3}(1 + j(c) + j(g))$$

$$j(e) = \frac{1}{3}(j(f) + j(h))$$

$$j(f) = \frac{1}{3}(1 + j(e) + j(g))$$

$$j(g) = \frac{1}{3}(j(d) + j(f))$$

$$j(h) = \frac{1}{3}(1 + j(c) + j(e))$$

Note also that we must have j(d) = j(h) = j(f) and j(g) = j(e) = j(c) because each of these vertices are the same number of moves away from a and b and each move has the same probability. In addition, each vertex that they can possibly move to is the same number of

moves from a or b. So let's revise this system of equations, using one representative from each equivalence class,

$$j(a) = 1$$

$$j(b) = 0$$

$$j(c) = \frac{2j(d)}{3}$$

$$j(d) = \frac{1}{3}(1 + 2j(g))$$

$$j(e) = \frac{2j(d)}{3}$$

$$j(f) = \frac{1}{3}(1 + 2j(g))$$

$$j(g) = \frac{2j(d)}{3}$$

$$j(h) = \frac{1}{3}(1 + 2j(g))$$

Plugging j(g) into the equation for j(d) yields,

$$j(d) = \frac{3}{5}$$

and

$$j(g) = \frac{2}{5}$$

Hence, our system of equations is,

$$j(a) = 1$$

$$j(b) = 0$$

$$j(c) = \frac{2}{5}$$

$$j(d) = \frac{3}{5}$$

$$j(e) = \frac{2}{5}$$

$$j(f) = \frac{3}{5}$$

$$j(g) = \frac{2}{5}$$

$$j(h) = \frac{3}{5}$$

Thus, we have,

$$P(T_a < T_b | X_0 = a) = \frac{1}{3} (P(V_a < V_b | X_0 = d) + P(V_a < V_b | X_0 = h) + P(V_a < V_B | X_0 = f))$$

$$= \frac{1}{3} (\frac{3}{5} + \frac{3}{5} + \frac{3}{5})$$

$$= \frac{3}{5}$$

For a quick sanity check, we compute the matrix powers of \tilde{p} (done in the R programming language) and find,

$$\tilde{p}^{1000} = \begin{pmatrix} a & b & c & d & e & f & g & h \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0.4 & 0.6 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0.6 & 0.4 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0.4 & 0.6 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0.6 & 0.4 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0.4 & 0.6 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0.4 & 0.6 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0.6 & 0.4 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Hence, we have $P(V_a < V_b | X_0 = d) = P(V_a < V_b | X_0 = h) = P(V_a < V_B | X_0 = f) = 0.6 = \frac{3}{5}$ as required.

Problem 4.

Fix $i \in \mathcal{S}$. Suppose $X_n = i$ for some n. Now consider the state $j \in \mathcal{S}$ such that j < i. It is possible to reach j from i because p(i,0) = 1/4. Once we are at 0, we have that p(0,1) = 3/4, p(1,2) = 3/4. Hence, by induction, we have p(j-1,j) = 3/4.

Now assume j > i. We can perform the same process, except without returning to 0. We have $p(i, i+1) = p(i+1, i+2) = \cdots = p(j-1, j) = 3/4$. Thus, we can reach j from i when j > i.

Lastly, when j = i, we need to perform the same process as j < i. We can return to 0 with probability p(i,0) = 1/4, and then we have, $p(0,1) = p(1,2) = \cdots p(i-1,i) = 3/4$. Hence, we have that we can reach i from state i.

Since i was arbitrary and we covered every possible case for another state j, this holds for any state in S. Thus, every state in S communicates with every other state, and so the chain is irreducible.

Now we need to show that there is a positive recurrent state in the chain. Let us consider state 0. Consider $P_0(T_0 = \infty) = 1 - P_0(T_0 < \infty)$. We have that,

$$P_0(T_0 = \infty) = p(0,1) \cdot p(1,2) \cdot p(2,3) \cdot p(3,4) \cdots$$
$$= \sum_{i=0}^{\infty} p(i,i+1)$$

Since p(i, i + 1) = 3/4 for every $i \in \mathcal{S}$, this sum is equivalent to,

$$\lim_{n\to\infty} 3n/4$$

Thus, we have that,

$$P_0(T_0 < \infty) = 1 - P_0(T_0 = \infty)$$

= $1 - \lim_{n \to \infty} 3n/4$
= $1 - 0 = 1$

Hence, 0 is recurrent in the sense that we will certainly return. Now consider E_0T_0 . Note that from each state x, we have probability 1/4 of returning to 0. Define g(x) as the function which denotes the expected time to return to 0 from state x. Then we have,

$$g(x) = 1 + \frac{3}{4}g(x+1)$$

So, we have,

$$g(0) = 1 + \frac{3}{4} \sum_{i=1}^{\infty} g(i)$$