

2 - Discrete-Time Signals

Energy $E_x = \|x\|_2^2 = \sum_{n=-\infty}^{\infty} |x[n]|^2$

Power $P_x = \lim_{N \rightarrow \infty} \frac{1}{2N} \sum_{n=-N}^N |x[n]|^2$
Finite support $\exists M$ s.t $x[n] = 0, \forall n < M$ and $n > M + N - 1$

3 - Signals and Hilbert Spaces

Vector Space

Commutativity $x + y = y + x$

Associativity $(x + y) + z = x + (y + z)$

Distributivity $\alpha(x + y) = \alpha x + \alpha y$

$(\alpha + \beta)x = \alpha x + \beta y$

Null vector $\exists 0 \in V$ s.t $x + 0 = x \forall x$

Inverse $x + y = y + x$

Identity element $\exists 1$ s.t $x.1 = 1.x = x$

Inner Product Space

Distributivity $\langle x + y, z \rangle$

Scaling property $\langle x, \alpha y \rangle = \alpha^* \langle x, y \rangle$

Commutative $\langle x, y \rangle = \langle y, x \rangle^*$

Self-product positive $\langle x, x \rangle \geq 0$

$\langle x, x \rangle = 0 \Leftrightarrow x = 0$ An inner product space is a vector space equipped with an inner product.

Complete space sequences converge in the space

Hilbert space space is a complete inner product space

Subspace

- Closure under additions :

$$\forall x, y \in P \Rightarrow x + y \in P$$

- Closure under scalar multiplication:

$$\forall x \in P, \forall \alpha \in S \Rightarrow \alpha x \in P$$

Span set of all linear combinations of the vectors in W.

Basis set linearly independant, its span covers the region, ie $\text{span}(W) = P$

Norm : $\geq 0, \|\alpha x\| = |\alpha| \|x\|$. triangle inequality

Orthogonal/Orthonormal Basis

Parseval's Identity

$$\|y\| = \sum_{k=0}^{K-1} \left| \langle x^{(k)}, y \rangle \right|^2$$

Bassel's Identity

$$\|y\| \geq \sum_{l=0}^{L-1} \left| \langle g^{(l)}, y \rangle \right|^2, \text{ with } G \subset P$$

Best Approximations

$$\hat{y} = \sum_{k=0}^{K-1} \langle x^{(k)}, y \rangle x^{(k)}$$

Notations

- ℓ_1 : absolutely summable sequence

- ℓ_2 : square summable sequence

- L_1 : absolutely integrable function

Cauchy Sequence

$$\forall \epsilon > 0, \exists N \in \mathbb{N} \mid \forall n, m \geq N, |x_n - x_m| < \epsilon$$

4 - Fourier Analysis

Discrete-Time Fourier Transform (DTFT)

used for: infinite, two sided signals ($x[n] \in \ell_2(\mathbb{Z})$)

analysis formula: $X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$

synthesis formula: $x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) e^{j\omega n} d\omega$

symmetries: $x[-n] \xleftrightarrow{DTFT} X(e^{-j\omega})$
 $x^*[n] \xleftrightarrow{DTFT} X^*(e^{-j\omega})$

shifts: $x[n - n_0] \xleftrightarrow{DTFT} e^{-j\omega n_0} X(e^{j\omega})$
 $e^{-j\omega_0 n} x[n] \xleftrightarrow{DTFT} X(e^{j(\omega - \omega_0)})$

Parseval: $\sum_{n=-\infty}^{\infty} |x[n]|^2 = \frac{1}{2\pi} \int_{-\pi}^{\pi} |X(e^{j\omega})|^2 d\omega$

Some DTFT pairs

$$\begin{aligned} x[n] &= \delta[n - k] & X(e^{j\omega}) &= e^{-j\omega k} \\ x[n] &= 1 & X(e^{j\omega k}) &= \tilde{\delta}(\omega) \\ x[n] &= u[n] & X(e^{j\omega}) &= \frac{1}{1 - e^{-j\omega}} + \frac{1}{2} \tilde{\delta}(\omega) \\ x[n] &= a^n u[n], |a| < 1 & X(e^{j\omega}) &= \frac{1}{1 - ae^{-j\omega}} \\ x[n] &= e^{j\omega_0 n} & X(e^{j\omega}) &= \tilde{\delta}(\omega - \omega_0) \\ x[n] &= \cos(\omega_0 n + \phi) & X(e^{j\omega}) &= \frac{1}{2} [e^{j\phi} \tilde{\delta}(\omega - \omega_0) + e^{-j\phi} \tilde{\delta}(\omega + \omega_0)] \\ x[n] &= \sin(\omega_0 n + \phi) & X(e^{j\omega}) &= \frac{j}{2} [e^{j\phi} \tilde{\delta}(\omega - \omega_0) - e^{-j\phi} \tilde{\delta}(\omega + \omega_0)] \end{aligned}$$

$$x[n] = \begin{cases} 1 & \text{for } 0 \leq n \leq N-1 \\ 0 & \text{otherwise} \end{cases} \quad X(e^{j\omega}) = \frac{\sin((N/2)\omega)}{\sin(\omega/2)} e^{-j\frac{N-1}{2}\omega}$$

Discrete Fourier Series(DFS)

used for: periodic signals ($\tilde{x}[n] \in \tilde{\mathbb{C}}^N$)

analysis formula: $\tilde{X}[k] = \sum_{n=0}^{N-1} \tilde{x}[n] e^{-j\frac{2\pi}{N}nk}, k = 0, \dots, N-1$

synthesis formula: $\tilde{x}[n] = \frac{1}{N} \sum_{k=0}^{N-1} \tilde{X}[k] e^{j\frac{2\pi}{N}nk}, n = 0, \dots, N-1$

symmetries: $\tilde{x}[-n] \xleftrightarrow{DFS} \tilde{X}[-k]$
 $\tilde{x}^*[n] \xleftrightarrow{DFS} \tilde{X}^*[-k]$

shifts: $\tilde{x}[n - n_0] \xleftrightarrow{DFS} e^{-j\frac{2\pi}{N}kn_0} \tilde{X}[k]$
 $e^{j\frac{2\pi}{N}nk_0} \tilde{x}[n] \xleftrightarrow{DFS} \tilde{X}[k - k_0]$

Parseval: $\sum_{n=0}^{N-1} |\tilde{x}[n]|^2 = \frac{1}{N} \sum_{k=0}^{N-1} |\tilde{X}[k]|^2 d\omega$

Discrete Fourier Transform(DFT)

used for: finite support signals ($x[n] \in \mathbb{C}^N$)

analysis formula: $X[k] = \sum_{n=0}^{N-1} x[n] e^{-j\frac{2\pi}{N}nk}, k = 0, \dots, N-1$

synthesis formula: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j\frac{2\pi}{N}nk}, n = 0, \dots, N-1$

symmetries: $x[-n \bmod N] \xleftrightarrow{DFT} X[-k \bmod N]$
 $x^*[n] \xleftrightarrow{DFT} X^*[-k \bmod N]$

shifts: $x[(n - n_0) \bmod N] \xleftrightarrow{DFT} e^{-j\frac{2\pi}{N}kn_0} X[k]$
 $e^{j\frac{2\pi}{N}nk_0} x[n] \xleftrightarrow{DFT} X[(k - k_0) \bmod N]$

Parseval: $\sum_{n=0}^{N-1} |x[n]|^2 = \frac{1}{N} \sum_{k=0}^{N-1} |X[k]|^2 d\omega$

Some DFT pairs for length- N signals

$$\begin{aligned}x[n] &= \delta[n - k] & X[k] &= e^{-j\frac{2\pi}{N}k} \\x[n] &= 1 & X[k] &= N\delta[k] \\x[n] &= e^{j\frac{2\pi}{N}L} & X[k] &= N\delta[k - L]\end{aligned}$$

5 - Discrete-Time Filters**Linear Time-Invariant Systems (LTI)****Time Invariance:**

$$y[n] = \mathcal{H}\{x[n]\} \Leftrightarrow y[n - n_0] = \mathcal{H}\{x[n - n_0]\}$$

$$\textbf{LTI: } y[n] = \mathcal{H}\{x[n]\} = \sum_{k=-\infty}^{\infty} x[k]h[n - k]$$

Filtering in the Time Domain

$$\textbf{Convolution : } \tilde{x}[n] * \tilde{y}[n] = \sum_{k=0}^{N-1} \tilde{x}[k]\tilde{y}[n - k]$$

$$X(e^{j\omega}) * Y(e^{j\omega}) = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\sigma}) * Y(e^{j(\omega-\sigma)}) d\sigma$$

Properties of the Impulse Response**IIR filters:** Infinite Impulse Response.**FIR filters:** Finite Impulse Response.**Causality:** outputs doesn't depend on future values of input.**Stability:** A system is called BIBO stable if its output is bounded for all bounded input sequences.

sufficient condition : absolutely summable

6 - The Z-transformFor DFTs : $z = e^{j\omega}$

Signal	Transform	ROC
$\delta[n]$	1	all z
$\delta[n - n_0]$	z^{-n_0}	$z \neq 0$
$u[n]$	$\frac{1}{1-z^{-1}}$	$ z > 1$
$e^{-\alpha n}u[n]$	$\frac{1}{1-e^{-\alpha}z^{-1}}$	$ z > e^{-\alpha} $
$-u[-n - 1]$	$\frac{1}{1-z^{-1}}$	$ z < 1$
$nu[n]$	$\frac{z^{-1}}{(1-z^{-1})^2}$	$ z > 1$
$-nu[-n - 1]$	$\frac{z^{-1}}{(1-z^{-1})^2}$	$ z < 1$
$n^2u[n]$	$\frac{z^{-1}(1+z^{-1})}{(1-z^{-1})^3}$	$ z > 1$
$-n^2u[-n - 1]$	$\frac{z^{-1}(1+z^{-1})}{(1-z^{-1})^3}$	$ z < 1$
$n^3u[n]$	$\frac{z^{-1}(1+4z^{-1}+z^{-2})}{(1-z^{-1})^4}$	$ z > 1$
$-n^3u[-n - 1]$	$\frac{z^{-1}(1+4z^{-1}+z^{-2})}{(1-z^{-1})^4}$	$ z < 1$
$a^n u[n]$	$\frac{1}{1-az^{-1}}$	$ z > a $
$-a^n u[-n - 1]$	$\frac{1}{1-az^{-1}}$	$ z < a $
$na^n u[n]$	$\frac{az^{-1}}{(1-az^{-1})^2}$	$ z > a $
$-na^n u[-n - 1]$	$\frac{az^{-1}}{(1-az^{-1})^2}$	$ z < a $
$n^2 a^n u[n]$	$\frac{az^{-1}(1+az^{-1})}{(1-az^{-1})^3}$	$ z > a $
$-n^2 a^n u[-n - 1]$	$\frac{az^{-1}(1+az^{-1})}{(1-az^{-1})^3}$	$ z < a $
$\cos(\omega_0 n)u[n]$	$\frac{1-z^{-1}\cos(\omega_0)}{1-2z^{-1}\cos(\omega_0)+z^{-2}}$	$ z > 1$
$\sin(\omega_0 n)u[n]$	$\frac{z^{-1}\sin(\omega_0)}{1-2z^{-1}\cos(\omega_0)+z^{-2}}$	$ z > 1$
$a^n \cos(\omega_0 n)u[n]$	$\frac{1-az^{-1}\cos(\omega_0)}{1-2az^{-1}\cos(\omega_0)+a^2z^{-2}}$	$ z > a $
$a^n \sin(\omega_0 n)u[n]$	$\frac{az^{-1}\sin(\omega_0)}{1-2az^{-1}\cos(\omega_0)+a^2z^{-2}}$	$ z > a $

$$\begin{aligned}x[n] &= \cos\left(\frac{2\pi}{N}Ln + \phi\right) & X[k] &= \frac{N}{2}[e^{j\phi}\delta[k - L] + e^{-j\phi}\delta[k - N + L]] \\x[n] &= \sin\left(\frac{2\pi}{N}Ln + \phi\right) & X[k] &= \frac{-jN}{2}[e^{j\phi}\delta[k - L] - e^{-j\phi}\delta[k - N + L]]\end{aligned}$$

$$x[n] = \begin{cases} 1 & \text{for } n \leq M-1 \\ 0 & \text{for } M \leq n \leq N-1 \end{cases} \quad X[k] = \frac{\sin((\pi/N)Mk)}{\sin((\pi/N)k)} e^{-j\frac{\pi}{N}(M-1)k}$$

Filtering in the Frequency Domain**Properties of the Frequency response****Magnitude :** lowpass, highpass, bandpass or allpass filter.**Phase :** the phase response acts as a generalized delay.**Linear Phase :** $\angle H(e^{j\omega}) = \omega d$ **Filtering by Example : Frequency Domain**

$$\textbf{Moving Average } H(e^{j\omega}) = \frac{1}{N} \frac{\sin(\omega N/2)}{\sin(\omega/2)} e^{-j\frac{N-1}{2}\omega}$$

$$\textbf{Leaky Integrator } H(e^{j\omega}) = \frac{1-\lambda}{1-\lambda e^{-j\omega}}$$

Ideal Filters

$$\textbf{Ideal Lowpass: } h_{lp}[n] = \frac{\sin(\omega_c n)}{\pi n}; \quad \text{sinc}(x) = \frac{\sin(\pi x)}{\pi x}$$

$$\textbf{Ideal Highpass: } h_{hp}[n] = \delta[n] - \frac{\omega_c}{\pi} \text{sinc}\left(\frac{\omega_c}{\pi}n\right)$$

$$\textbf{Ideal Bandpass: } h_{bp}[n] = 2 \cos(\omega_0 n) \frac{\omega_b}{2\pi} \text{sinc}\left(\frac{\omega_b}{2\pi}n\right)$$

$$\textbf{Hilbert Filter: } H(e^{j\omega}) = \begin{cases} -j & 0 \leq \omega \leq \pi \\ +j & -\pi \leq \omega \leq 0 \end{cases}$$

$$h[n] = \frac{2 \sin^2(\pi n/2)}{\pi n} = \begin{cases} 0 & \text{for } n \text{ even} \\ \frac{2}{n\pi} & \text{for } n \text{ odd} \end{cases}$$

Filter Analysis

$$\textbf{Z-transform: } X(z) = \mathcal{Z}\{x[n]\} = \sum_{n=-\infty}^{\infty} x[n]z^{-n}$$

$$\textbf{Inverse Z-transform: } \mathcal{Z}^{-1}\{X(z)\} = \frac{1}{2\pi j} \oint_C X(z)z^{n-1} dz$$

$$\textbf{Time-shift } \mathcal{Z}\{x[n - N](z)\} = z^{-N}X(z)$$

CCDE: Constant-Coefficient Difference Equation

$$y[n] = \sum_{k=0}^{M-1} b_k x[n-k] - \sum_{k=0}^{N-1} a_k y[n-k], \quad H(z) = \frac{\sum_{k=0}^{M-1} b_k z^{n-k}}{1 + \sum_{k=0}^{N-1} a_k z^{n-k}}$$

Region of Convergence

The ROC has circular geometry

Anticausal ROC: Disk Causal ROC: plane \ diskStability: a system is BIBO stable if its ROC includes the unit circle.**The Pole-Zero plot**

$$H(z) = b_0 \frac{\prod_{n=0}^{M-1} (1 - z_n z^{-1})}{\prod_{n=0}^{N-1} (1 - p_n z^{-1})}$$

Sketching the Transfer Function from the Pole-Zero Plot

1- Check for the zeros on the unit circle; these correspond to points on the frequency axis in which the magnitude response is exactly zero

2 - Draw a line from the origin of the complex plane to each pole and each zero. The point of intersection of each line with the unit circle gives the location of a local extremum for the magnitude response.

3 - The effect of each pole and each zero is made stronger by their proximity to the unit circle

7 - Filter Design

Filter Specifications and Tradeoffs

Transition Band. Range of frequencies between passband and stopband
Tolerances. Min and Max frequency response over passband and stopband.

FIR Filter Design

FIR Filter Design By Windowing *Impulse Response Truncation*

$$\hat{h}[n] = \begin{cases} h[n] & -N \leq n \leq N \\ 0 & \text{otherwise} \end{cases}$$

The Rectangular Window

$$\hat{h}[n] = h[n]w[n] \quad \text{with : } w[n] = \text{rect}\left(\frac{n}{N}\right) = \begin{cases} 1 & -N \leq n \leq N \\ 0 & \text{otherwise} \end{cases}$$

8 - Stochastic Signal Processing

Random Variables

Expectation: $E[X] = \int_{-\infty}^{\infty} x f_X(x) dx$

$$E[g(X)] = \int_{-\infty}^{\infty} g(x) f_X(x) dx$$

Correlation: $R_{XY} = E[XY]$

Covariance: $K_{XY} = E[XY] - E[X]E[Y]$

Variance: $\sigma_X^2 = E[(W - m_x)^2]$

Random Vectors

Expectation:

$$E[\mathbf{X}] = [E[X_0], E[X_1], \dots, E[X_{N-1}]]^T$$

Correlation: $\mathbf{R}_{\mathbf{X}\mathbf{Y}} = E[\mathbf{X}\mathbf{Y}^T]$

Cov: $\mathbf{K}_{\mathbf{X}\mathbf{Y}} = E[(\mathbf{X} - \mathbf{m}_{\mathbf{X}})(\mathbf{Y} - \mathbf{m}_{\mathbf{Y}})]$

Random Processes

Probability Distribution:

$$f_{X[i_0]X[i_1]\dots X[i_{k-1}]}(x_0, x_1, \dots, x_{k-1})$$

Second Order Description:

$$R_X[l, k] = E[X[l]X[k]], \quad l, k \in \mathbb{Z}$$

$$K_X[l, k] = E[(X[l] - m_{X[l]})(X[k] - m_{X[k]})]$$

$$R_{XY}[l, k] = E[X[l]Y[k]] \quad (\text{cross-correlation})$$

Stationary Processes

Strict sense: The full probabilistic description of the process is time invariant

WSS: mean and variance are constant over time and autocorrelation and covariance only depend on the time lag $(l - k)$

Ergodicity

It is legitimate to estimate expectations from a single realization

Spectral Rep of Statio Rand Processes

$$P_X(e^{j\omega}) = \sum_{k=-\infty}^{\infty} r_X[k] e^{-j\omega k}$$

Stochastic Signal Processing

$$Y[n] = \sum_{k=-\infty}^{\infty} h[k]X[n-k] \quad \text{with stable LTI filter and WSS input process}$$

Time-Domain Analysis

$$m_Y[n] = \sum_{k=-\infty}^{\infty} h[k]m_{n-k} = m_X H(e^{j0})$$

$$r_Y[n] = h[n] * h[-n] * r_X[n]$$

$$r_{XY}[N] = h[n] * r_X[n]$$

Frequency-Domain Analysis

$$P_Y(e^{j\omega}) = |H(e^{j\omega})|^2 P_X(e^{j\omega})$$

$$P_{XY}(e^{j\omega}) = H(e^{j\omega}) P_X(e^{j\omega})$$

9 - Interpolation and Sampling

Continuous-Time Fourier Transform

$$X(j\Omega) = \int_{-\infty}^{\infty} x(t) e^{-j\Omega t} dt$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\Omega) e^{j\Omega t} d\Omega$$

Bandlimited Signals

$$\exists \Omega_N \text{ s.t. } X(j\Omega) = 0 \text{ for } |\Omega| \geq |\Omega_N|$$

Polynomial Interpolation

$$\begin{aligned} L_n^{(N)}(t) &= \prod_{\substack{k=-N \\ k \neq n}}^N \frac{(t - t_k)}{(t_n - t_k)} \\ &= \prod_{\substack{k=-N \\ k \neq n}}^N \frac{(t/T_s - k)}{(n - k)} \end{aligned}$$

10 - A/D and D/A Conversions

Quantization

$$\mathcal{Q}\{x[n]\} = \{k | x[n] \in I_k\} \quad \text{with } I_k = [i_k, i_{k+1})$$

Quantization Error

Quantization is highly non-linear.

Gibbs phenomenon: The maximum error does not decrease with increasing N and, therefore, there are no means to meet a set of specifications which require less than 9% error in either stopband or passband.

This truncation produces 2 main effects :

- Sharp transition from passband to stopband is smoothed by the convolution with the main lobe of width Δ .

- Ripples appear both in the stopband and the passband due to the convolution with the sidelobes (the largest ripple being the Gibbs phenomenon).

$$P(t) = \sum_{n=-N}^N x[n] L_n^{(N)}(t)$$

Sinc Interpolation

$$x(t) = \sum_{n=-\infty}^{\infty} x[n] \text{sinc}\left(\frac{t - nT_s}{T_s}\right)$$

The Sampling Theorem

If $x(t)$ is a Ω_N -bandlimited continuous-time signal, a sufficient representation of $x(t)$ is given by the discrete time signal $x[n] = x(nT_s)$, with $T_s = \pi/\Omega_N$. The continuous time signal $x(t)$ can be exactly reconstructed from the discrete-time signal $x[n]$ as :

$$x(t) = \sum_{n=-\infty}^{\infty} x[n] \text{sinc}\left(\frac{t - nT_s}{T_s}\right)$$

Observation: limited bandwidth in a domain \Leftrightarrow illimited in the other

$$\mathcal{Q}\{x[n] + \epsilon[n]\} = \begin{cases} k-1 & \text{if } \epsilon[n] \leq 0 \\ k & \text{if } \epsilon[n] > 0 \end{cases}$$

$$\mathbb{P}\left(\tilde{X} = \tilde{x} = \frac{i}{2^r}\right) = p\left\{\frac{i}{2^r} \leq x \leq \frac{i+1}{2^r}\right\}$$

$$p_e = \int_{\Omega} (x - \tilde{x})^2 f_x(x) dx$$

11 - Multirate Signal Processing

Downsampling

$$x_{ND}[n] = \mathcal{D}\{x[n]\} = x[nN] ;$$

$$X_{ND}(e^{j\omega}) = \frac{1}{N} \sum_{k=0}^{N-1} X(e^{j(\frac{\omega}{N} - \frac{2\pi}{N}k)}) = \frac{1}{N} \sum_{k=0}^{N-1} X(z^{\frac{1}{N}} e^{-j\frac{2\pi}{N}k})$$

Rappels

Series

$$\sum_{i=0}^{n-1} q^i = \frac{1-q^n}{1-q}; \quad \sum_{i=1}^n i = \frac{n(n+1)}{2};$$

$$\sum_{i=1}^n i^2 = \frac{n(n+1)(2n+1)}{6}$$

Trigonometry

$$\cos(a+b) = \cos(a)\cos(b) - \sin(a)\sin(b)$$

$$\sin(a+b) = \sin(a)\cos(b) + \cos(a)\sin(b)$$

$$\tan(a+b) = \frac{\tan(a) + \tan(b)}{1 - \tan(a)\tan(b)}$$

$$\cos(p) + \cos(q) = 2\cos\left(\frac{p+q}{2}\right)\cos\left(\frac{p-q}{2}\right)$$

$$\cos(p) - \cos(q) = -2\sin\left(\frac{p+q}{2}\right)\sin\left(\frac{p-q}{2}\right)$$

$$\sin(p) + \sin(q) = 2\sin\left(\frac{p+q}{2}\right)\cos\left(\frac{p-q}{2}\right)$$

$$\sin(p) - \sin(q) = 2\sin\left(\frac{p-q}{2}\right)\cos\left(\frac{p+q}{2}\right)$$

$$\cos(a)\cos(b) = \frac{1}{2}(\cos(a+b) + \cos(a-b))$$

$$\sin(a)\sin(b) = \frac{1}{2}(\cos(a-b) - \cos(a+b))$$

$$\sin(a)\cos(b) = \frac{1}{2}(\sin(a+b) + \sin(a-b))$$

Upsampling

$$x_{NU}[n] = \mathcal{U}\{x[n]\} = \begin{cases} x[k] & \text{for } n = kN, k \in \mathbb{Z} \\ 0 & \text{otherwise} \end{cases} ;$$

$$X_{NU}(e^{j\omega}) = X(e^{j\omega N}) = X(z^N)$$

$$\cos(a) = \frac{1 - \tan^2(\frac{a}{2})}{1 + \tan^2(\frac{a}{2})}$$

$$\sin(a) = \frac{2\tan(\frac{a}{2})}{1 + \tan^2(\frac{a}{2})}$$

$$\tan(a) = \frac{2\tan(\frac{a}{2})}{1 - \tan^2(\frac{a}{2})}$$

Residues

$$\text{Res}(X(z)z^{n-1})|_{z=z_i} = \frac{A(z_i)}{B'(z_i)}z_i^{n-1}$$

Taylor series

$$\log(1+x) = \sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n} x^n$$

$$\frac{1}{1-x} = \sum_{n=1}^{\infty} x^n$$

Bayes' Theorem

$$P(A|B) = \frac{P(A \cap B)}{P(B)} = \frac{P(B|A)P(A)}{P(B)}$$

Chebyshev Polynomials

Used to prove Gibbs Phenomenon

$$T_0(x) = 1, T_1(x) = x, T_2(x) = 2x^2 - 1$$

$$T_{k+1}(x) = 2xT_k(x) - T_{k-1}(x)$$

$$\cos(n\omega) = T_n(\cos(\omega))$$

Gaussian Distribution

$$f(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

Integral Derivation

if $f(t) = \int_{a(t)}^{b(t)} g(x,t)dx$ then

$$\frac{\partial f(t)}{\partial t} = \int_{a(t)}^{b(t)} \frac{g(x,t)}{t} dx + \frac{b(t)}{t} g(b(t),t) - \frac{a(t)}{t} g(a(t),t)$$

Period, pulsation, frequency

$$T = \frac{1}{f}, \quad \omega = 2\pi$$

Multirate identities (Noble identities)

- Downsampling by N followed by filtering by $H(z)$ is equivalent to filtering by $H(z^N)$ followed by downsampling by N .

- Filtering by $H(z)$ followed by upsampling by N is equivalent to upsampling by N followed by filtering by $H(z^N)$.

DTFT

$$x[n] = \begin{cases} 1 & \text{if } |n| \leq T \\ 0 & \text{otherwise} \end{cases}$$

$$\overset{DTFT}{\longleftrightarrow} X(e^{j\omega}) = \frac{\sin(\omega(T+\frac{1}{2}))}{\sin(\omega/2)}$$