SOUTH CHINA UNIVERSITY OF TECHNOLOGY

SCUT_gugugu

TEMPLATE



Last build at April 19, 2019

CONTENTS 1

Contents

1.1 Shortest Path 1.1.1 Dijkstra 1.1.2 SPFA 1.2 Network Flow 1.2.1 ISAP 1.2.2 HLPP 1.2.3 Dinic 1.2.4 MCMF 1.3 Tree Related 1.3.1 Kruskal 1.3.2 Prim 1.3.3 Tree Divide and Conquer 1.4 LCA 1.4.1 Tree Decomposition LCA 1.4.2 Tarjan LCA 1.5 Tarjan 1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash 3.1.2 KMP && exKMP		4				
1.1.2 SPFA 1.2 Network Flow 1.2.1 ISAP 1.2.2 HLPP 1.2.3 Dinic 1.2.4 MCMF 1.3 Tree Related 1.3.1 Kruskal 1.3.2 Prim 1.3.3 Tree Divide and Conquer 1.4 LCA 1.4.1 Tree Decomposition LCA 1.4.2 Tarjan LCA 1.5 Tarjan 1.5.1 SCC 1.5.2 BCC 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		4				
1.2 Network Flow 1.2.1 ISAP 1.2.2 HLPP 1.2.3 Dinic 1.2.4 MCMF 1.3 Tree Related 1.3.1 Kruskal 1.3.2 Prim 1.3.3 Tree Divide and Conquer 1.4 LCA 1.4.1 Tree Decomposition LCA 1.4.2 Tarjan LCA 1.5 Tarjan 1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		4				
1.2.1 ISAP 1.2.2 HLPP 1.2.3 Dinic 1.2.4 MCMF 1.3 Tree Related 1.3.1 Kruskal 1.3.2 Prim 1.3.3 Tree Divide and Conquer 1.4 LCA 1.4.1 Tree Decomposition LCA 1.4.2 Tarjan LCA 1.5 Tarjan 1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		4				
1.2.2 HLPP 1.2.3 Dinic 1.2.4 MCMF 1.3 Tree Related 1.3.1 Kruskal 1.3.2 Prim 1.3.3 Tree Divide and Conquer 1.4 LCA 1.4.1 Tree Decomposition LCA 1.4.2 Tarjan LCA 1.5 Tarjan 1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		5				
1.2.3 Dinic 1.2.4 MCMF 1.3 Tree Related 1.3.1 Kruskal 1.3.2 Prim 1.3.3 Tree Divide and Conquer 1.4 LCA 1.4.1 Tree Decomposition LCA 1.4.2 Tarjan LCA 1.5 Tarjan 1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		5				
1.2.4 MCMF 1.3 Tree Related 1.3.1 Kruskal 1.3.2 Prim 1.3.3 Tree Divide and Conquer 1.4 LCA 1.4.1 Tree Decomposition LCA 1.4.2 Tarjan LCA 1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		6				
1.3 Tree Related 1.3.1 Kruskal 1.3.2 Prim 1.3.3 Tree Divide and Conquer 1.4 LCA 1.4.1 Tree Decomposition LCA 1.4.2 Tarjan LCA 1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		7				
1.3.1 Kruskal 1.3.2 Prim 1.3.3 Tree Divide and Conquer 1.4 LCA 1.4.1 Tree Decomposition LCA 1.4.2 Tarjan LCA 1.5 Tarjan 1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		8				
1.3.2 Prim 1.3.3 Tree Divide and Conquer 1.4 LCA 1.4.1 Tree Decomposition LCA 1.4.2 Tarjan LCA 1.5 Tarjan 1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		9				
1.3.3 Tree Divide and Conquer 1.4 LCA 1.4.1 Tree Decomposition LCA 1.4.2 Tarjan LCA 1.5 Tarjan 1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		9				
1.4 LCA 1.4.1 Tree Decomposition LCA 1.4.2 Tarjan LCA 1.5 Tarjan 1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		10				
1.4.1 Tree Decomposition LCA 1.4.2 Tarjan LCA 1.5 Tarjan 1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		10				
1.4.2 Tarjan LCA 1.5 Tarjan 1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.3.2 Splay Tree 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		12				
1.5 Tarjan 1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		12				
1.5.1 SCC 1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		12				
1.5.2 BCC 1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		13				
1.6 Cactus 1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		13				
1.6.1 Circle-Square Tree 2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		14				
2 Data Structures 2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		15				
2.1 Basic Structures 2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		15				
2.1.1 RMQ 2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash	1	19				
2.1.2 Divide Blocks 2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash	.1 Basic Structures					
2.2 Tree Structures 2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		19				
2.2.1 Tree Decomposition 2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		19				
2.2.2 Link-Cut Tree 2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		19				
2.3 Sequence Structures 2.3.1 Segment Tree 2.3.2 Splay Tree 2.4 Persistent Data Structures 2.4.1 Chairman Tree 2.4.2 Persistent Trie 3 String 3.1 Basics 3.1.1 Hash		19				
2.3.1 Segment Tree		22				
2.3.2 Splay Tree		23				
2.4 Persistent Data Structures		23				
2.4.1 Chairman Tree		24				
2.4.2 Persistent Trie		26				
3 String 3.1 Basics		26				
3.1 Basics		27				
3.1 Basics	2	28				
		28				
3.1.2 KMP && exKMP		28				
		28				
3.1.3 AC Automaton		29				

CONTENTS 2

	3.2	Suffix Related	30
		3.2.1 Suffix Array	30
		3.2.2 Suffix Automaton	31
	3.3	Palindrome Related	31
		3.3.1 Manacher	31
		3.3.2 Palindromic Tree	31
4	Mat		33
	4.1	Algebra	33
		4.1.1 FFT	33
		4.1.2 NTT	33
		4.1.3 Linear Basis	34
	4.2	Math Theory	35
		4.2.1 Inverse	35
		4.2.2 Lucas	35
		4.2.3 CRT && exCRT	36
		4.2.4 BSGS	37
		4.2.5 Miller-Rabin && PollardRho	37
		4.2.6 $\Phi(n)$	38
		4.2.7 Euler Sieve	38
		4.2.8 Möbius Inversion	39
5		metry	41
	5.1	Commonly Definition and Functions	41
		5.1.1 Const and Functions	41
		5.1.2 Point Definition	41
		5.1.3 Line Definition	41
		5.1.4 Get Area	42
		5.1.5 Get Circumference	42
	5.2	Convex Hull	42
	5.3	Half Plane Intersection	43
	5.4	Min Circle Cover	43
	5.5	Circle Union Area	44
	5.6	Simpson Integrate	46
_	0.1		
6	Oth		47
	6.1	Sample	47
		6.1.1 vimrc	47
		6.1.2 FastIO	47
		6.1.3 Java BigNum	48
	6.2	Offline Algorithm	48
		6.2.1 CDQ Divide and Conquer	48
		one of the contract of the con	
		6.2.2 Mo's Algorithm	49

CONTENTS 3

6.3	Rando	mized Algorithm	2
	6.3.1	Simulated Annealing	2
6.4	Other	Method	2
	6.4.1	Enumerate Subset	2
	6.4.2	Enumerate $\lfloor \frac{n}{d} \rfloor \lfloor \frac{m}{d} \rfloor$	3
6.5	Formu	la	3
	6.5.1	Euler's theorem	3
	6.5.2	Dirichlet Convolution	3
	6.5.3	Möbius Inversion Formula	3

1 Graph Theory

1.1 Shortest Path

1.1.1 Dijkstra

```
typedef pair<int, int> P;
2
   struct Edge {
        int to, nxt;
3
4
        LL w;
5
   }e[MAXM];
   int head[MAXN], ecnt;
   LL d[MAXN];
7
   priority_queue<P, vector<P>, greater<P> > q;
8
   inline void addEdge(int x, int y, LL w) {
9
       e[++ecnt] = (Edge) \{y, head[x], w\}; head[x] = ecnt;
10
11
12
   void dijkstra(int st) {
13
       memset(d, 0x3f, sizeof(d));
14
        d[st] = 0;
15
        q.push(make_pair(0, st));
16
       while(!q.empty()) {
17
            P x = q.top(); q.pop();
18
            int u = x.second;
            for(int i = head[u], v; i; i = e[i].nxt) {
19
                v = e[i].to;
20
                if(d[v] > d[u] + e[i].w) {
21
                    d[v] = d[u] + e[i].w;
22
23
                    q.push(make_pair(d[v], v));
24
                }
25
            }
26
       }
27
   }
```

1.1.2 SPFA

```
struct Edge {
1
2
       int to, nxt;
3
       LL w;
   }e[MAXE];
4
5
   int head[MAXN], ecnt;
6 LL d[MAXN];
7
   bool exist[MAXN];
   queue<int> q;
8
9
   inline void addEdge(int x, int y, LL w) {
       e[++ecnt] = (Edge) \{y, head[x], w\}; head[x] = ecnt;
10
11
   void SPFA(int st) {
12
       memset(d,0x3f,sizeof(d));
13
        d[st] = 0;
14
        q.push(st);
15
        exist[st] = 1;
16
17
       while(!q.empty()) {
18
            int u = q.front(); q.pop();
19
            exist[u] = 0;
            for(int i = head[u], v; i; i = e[i].nxt) {
20
21
                v = e[i].to;
                if(d[v] > d[u] + e[i].w) {
22
```

```
d[v] = d[u] + e[i].w;
23
24
                      //pre[v] = u;
25
                      if(!exist[v]) {
26
                          q.push(v);
                          exist[v] = 1;
27
                      }
28
29
                 }
            }
30
        }
31
   }
32
```

1.2 Network Flow

1.2.1 ISAP

```
namespace NWF {
1
2
          struct Edge{
3
               int to, nxt;LL f;
          e[MAXM << 1];
 4
 5
          int S, T, tot;
          int ecnt, head[MAXN], cur[MAXN], pre[MAXN], num[MAXN], dis[MAXN];
 6
 7
          queue<int> q;
         void init(int _S, int _T, int _tot){
   ecnt = 1; S = _S; T = _T; tot = _tot;
   memset(num, 0, (tot + 1) * sizeof(int));
   memset(head, 0, (tot + 1) * sizeof(int));
 8
 9
10
11
12
          inline void addEdge(int u, int v, LL f) {
13
               e[++ecnt] = (Edge) \{v, head[u], f\}; head[u] = ecnt; e[++ecnt] = (Edge) \{u, head[v], 0\}; head[v] = ecnt;
14
15
16
          void bfs() {
17
               memset(dis, 0, (tot + 1) * sizeof(int));
18
19
               q.push(T);
20
               dis[T] = 1;
21
               while(!q.empty()) {
22
                    int u = q.front(), v; q.pop();
23
                    num[dis[u]]++;
                    for(int i = cur[u] = head[u]; i; i = e[i].nxt) {
24
                         if(!dis[v = e[i].to]) {
25
                              dis[v] = dis[u] + 1;
26
27
                               q.push(v);
28
                         }
29
                    }
               }
30
31
          LL augment() {
32
               LL flow = INF;
33
               for(int i = S; i != T; i = e[cur[i]].to)
34
               flow = min(flow, e[cur[i]].f);
for(int i = S; i != T; i = e[cur[i]].to) {
35
36
                    e[cur[i]].f -= flow;
37
                    e[cur[i] ^ 1].f += flow;
38
39
40
               return flow;
41
          LL isap() {
42
43
               bfs();
               int u = S, v;
44
```

```
LL flow = 0;
45
            while(dis[S] <= tot) {</pre>
46
47
                 if(u == T) {
                     flow += augment();
48
                     u = S;
49
50
                 bool fg = 0;
51
                 for(int i = cur[u]; i; i = e[i].nxt) {
52
                     if(e[i].f && dis[u] > dis[v = e[i].to]) {
53
                          pre[v] = u;
54
                          cur[u] = i;
55
                          u = v;
56
                          fg = 1;
57
                          break;
58
59
                     }
60
                 if(fg) continue;
61
                 if(!--num[dis[u]]) break;
62
                 int maxDis = tot;
63
                 for(int i = head[u]; i; i = e[i].nxt) {
64
                     if(e[i].f \&\& maxDis > dis[v = e[i].to]) {
65
                          maxDis = dis[v];
66
                          cur[u] = i;
67
                     }
68
69
70
                 num[dis[u] = maxDis + 1]++;
71
                 if(u != S) u = pre[u];
72
73
            return flow;
        }
74
   }
75
```

1.2.2 HLPP

```
namespace NWF{
1
2
         struct Edge{
              int to,nxt;LL f;
3
         e[MAXM << 1];
4
5
         int S, T, tot;
         int ecnt, head[MAXN], dis[MAXN], num[MAXN];
6
7
         LL sumf[MAXN];
8
         queue<int> q;
9
         list<int> dep[MAXN];
         void init(int _S,int _T,int _tot){
10
              ecnt = 1;S = _S;T = _T;tot = _tot;
memset(num, 0, (tot + 1) * sizeof(int));
memset(head, 0, (tot + 1) * sizeof(int));
11
12
13
              memset(sumf, 0, (tot + 1) * sizeof(LL));
14
15
         void addEdge(int u,int v,LL f){
16
              e[++ecnt] = (Edge) \{v, head[u], f\}; head[u] = ecnt; e[++ecnt] = (Edge) \{u, head[v], 0\}; head[v] = ecnt;
17
18
19
         void bfs(){
20
              memset(dis, 0, (tot + 1) * sizeof(int));
21
              q.push(T); dis[T] = 1;
22
23
              while(!q.empty()){
24
                    int u=q.front(), v; q.pop();
25
                    for(int i = head[u]; i; i = e[i].nxt)
26
                    if(!dis[v = e[i].to]){
```

```
dis[v] = dis[u] + 1;
27
28
                     q.push(v);
29
                 }
            }
30
31
        LL hlpp(){
32
            bfs();
33
34
            dis[S] = tot + 1;
            for(int i = 1;i <= tot; ++i)num[dis[i]]++;</pre>
35
            for(int i = tot + 1; ~i; --i)dep[i].clear();
36
            int_maxd = dis[S];LL f;
37
            dep[maxd].push_back(S);sumf[S] = INF;
38
39
            for(;;){
                 while(maxd && dep[maxd].empty())maxd--;
40
41
                 if(!maxd)break;
                 int u = dep[maxd].back(), v;dep[maxd].pop_back();
42
                 int minDis = tot + 1;
43
                 for(int i = head[u]; i;i = e[i].nxt)
44
45
                 if(e[i].f){
                     if(dis[u] > dis[v = e[i].to]){
46
                         f = min(sumf[u], e[i].f);
47
                         e[i].f -= f; e[i^1].f += f;
48
                         if(sumf[u] != INF) sumf[u] -= f;
49
50
                         if(sumf[v] != INF) sumf[v] += f;
                         if(v!=S \&\& v!=T \&\& sumf[v] == f){
51
                              maxd = max(maxd, dis[v]);
52
53
                              dep[dis[v]].push_back(v);
54
                         if(!sumf[u])break;
55
                     }else minDis=min(minDis, dis[v] + 1);
56
57
                 if(sumf[u]){
58
                     if(!--num[dis[u]]){
59
                         for(int i = dis[u];i <= maxd;++i){</pre>
60
                              while(!dep[i].empty()){
61
                                  --num[i];
62
                                  dis[dep[i].back()] = tot + 1;
63
                                  dep[i].pop_back();
64
                              }
65
66
                         }
67
                         maxd = dis[u] - 1; dis[u] = tot + 1;
                     }else{
68
                         dis[u] = minDis;
69
                         if(minDis > tot)continue;
70
                         num[minDis]++;
71
                         maxd = max(maxd, minDis);
72
73
                         dep[minDis].push_back(u);
                     }
74
75
                 }
76
            return sumf[T];
77
78
    }
79
```

1.2.3 Dinic

```
namespace NWF {
struct Edge {
    int to, nxt;LL f;
} e[MAXM << 1];</pre>
```

```
5
         int S, T, tot;
         int ecnt, head[MAXN], cur[MAXN], dis[MAXN];
 6
         queue<int> q;
 7
         void init(int _S, int _T, int _tot){
    ecnt = 1; S = _S; T = _T; tot = _tot;
    memset(head, 0, (tot + 1) * sizeof(int));
 8
 9
10
11
         void addEdge(int u, int v, LL f) {
    e[++ecnt] = (Edge) {v, head[u], f}; head[u] = ecnt;
    e[++ecnt] = (Edge) {u, head[v], 0}; head[v] = ecnt;
12
13
14
15
         bool bfs() {
16
              memset(dis, 0, (tot + 1) * sizeof(int));
17
              q.push(S); dis[S] = 1;
18
19
              while (!q.empty()) {
                   int u = q.front(), v; q.pop();
20
                   for (int i = cur[u] = head[u]; i ; i = e[i].nxt) {
21
22
                        if (e[i].f && !dis[v = e[i].to]) {
23
                              q.push(v);
                              dis[v] = dis[u] + 1;
24
                        }
25
                   }
26
27
              }
28
              return dis[T];
29
30
         LL dfs(int u, LL maxf) {
31
              if (u == T) return maxf;
              LL sumf = maxf;
32
              for (int &i = cur[u]; i; i = e[i].nxt) {
33
                   if (e[i].f && dis[e[i].to] > dis[u]) {
34
                        LL tmpf = dfs(e[i].to, min(sumf, e[i].f));
35
                        e[i].f -= tmpf; e[i ^ 1].f += tmpf;
36
                        sumf -= tmpf;
37
                        if (!sumf) return maxf;
38
39
                   }
              }
40
              return maxf - sumf;
41
42
43
         LL dinic() {
44
              LL ret = 0;
45
              while (bfs()) ret += dfs(S, INF);
46
              return ret;
47
         }
48
```

1.2.4 MCMF

```
1
    namespace NWF{
2
        struct Edge {
3
            int to, nxt;LL f, c;
4
        } e[MAXM << 1];</pre>
        int S, T, tot;
int ecnt, head[MAXN], cur[MAXN];LL dis[MAXN];
5
6
7
        bool exist[MAXN];
        queue<int> q;
8
        void init(int _S, int _T, int _tot){
9
            ecnt = 1; S = _S; T = _T; tot = _tot;
10
11
            memset(head, 0, (tot + 1) * sizeof(int));
12
13
        void addEdge(int u, int v, LL f, LL c) {
```

```
e[++ecnt] = (Edge) \{v, head[u], f, c\}; head[u] = ecnt;
14
              e[++ecnt] = (Edge) \{u, head[v], 0, -c\}; head[v] = ecnt;
15
16
         bool spfa() {
17
              for(int i = 0;i <= tot; ++i){</pre>
18
                   dis[i] = INF; exist[i] = cur[i] = 0;
19
20
              q.push(S);dis[S] = 0;exist[S] = 1;
21
              while(!q.empty()) {
22
                   int u = q.front(), v; q.pop();exist[u] = 0;
23
                   for(int i = head[u]; i; i = e[i].nxt) {
    if(e[i].f && dis[v = e[i].to] > dis[u] + e[i].c) {
24
25
26
                            dis[v] = dis[u] + e[i].c;
                            cur[v] = i;
27
                            if(!exist[v]) {
28
                                 q.push(v);
29
                                 exist[v] = 1;
30
31
                            }
32
                        }
                   }
33
              }
34
              return dis[T] != INF;
35
36
         LL mcmf() {
37
              LL cost = 0;
38
              while(spfa()) {
39
40
                   LL flow = INF;
41
                   for(int i = T; i != S; i = e[cur[i] ^ 1].to)
                   flow = min(flow, e[cur[i]].f);
for(int i = T; i != S; i = e[cur[i] ^ 1].to) {
    e[cur[i]].f -= flow;
42
43
44
                        e[cur[i] ^ 1].f += flow;
45
46
                   cost += flow * dis[T];
47
              }
48
              return cost;
49
50
         }
51
    }
```

1.3 Tree Related

1.3.1 Kruskal

```
namespace MST{
1
2
        struct Edge{
3
            int u,v; LL w;
            bool operator < (const Edge& x) const { return w < x.w; }</pre>
4
        }e[MAXM];
5
        int ecnt, fa[MAXN];
6
        void addEdge(int u, int v, LL w) {
7
            e[++ecnt] = (Edge)\{v, u, w\}; headp[u] = ecnt;
8
9
        int Find(int x) { return x == fa[x] ? x : fa[x] = Find(fa[x]); }
10
        LL kruskal(int n) {
11
12
            sort(e + 1, e + ecnt + 1);
            for(int i = 1; i <= n; i++) fa[i] = i;
13
            LL sum = 0;
14
            for (int i = 1; i <= ecnt; i++){
15
                int fu = Find(e[i].u), fv = Find(e[i].v);
16
```

```
if(fu != fv){
    fa[fu] = fv;
    sum += e[i].w;

return sum;
}
```

1.3.2 Prim

```
namespace MST {
1
2
        struct Edge{
3
             int to,nxt; LL w;
        }e[MAXM];
4
5
        int ecnt, head[MAXN], vis[MAXN]; // pre[MAXN];
        LL dis[MAXN];
6
        void addEdge(int u, int v, LL w){
7
8
             e[++ecnt] = (Edge)\{v, head[u], w\}; head[u] = ecnt;
9
             e[++ecnt] = (Edge)\{u, head[v], w\}; head[v] = ecnt;
10
        LL Prim(int n){
11
             for (int i = 1; i <= n; i++){</pre>
12
13
                  //pre[i] = 0;
                 vis[i] = 0;
14
                 dis[i] = INF;
15
16
             vis[1] = 1;
17
             LL sum = 0;
18
             for (int i = head[1]; i; i = e[i].nxt)
19
20
                 dis[e[i].to] = min(dis[e[i].to],e[i].w);
             for (int j = 1; j < n; j++){
   int u; LL minDis = INF;</pre>
21
22
                 for (int i = 1; i <= n; ++i)</pre>
23
                      if (!vis[i] && dis[i] < minDis){</pre>
24
25
                          minDis = dis[i];
26
                          u = i;
27
                 if (minDis == INF) return -1;
28
                 vis[u] = 1;
29
30
                 sum += minDis;
                 for (int i = head[u], v; i; i = e[i].nxt)
31
                 if (!vis[v = e[i].to] && e[i].w < dis[v]){</pre>
32
                      //pre[u] = v;
33
                      dis[v] = e[i].w;
34
35
36
             return sum;
37
38
        }
39
   }
```

1.3.3 Tree Divide and Conquer

```
struct Edge {
    int to, nxt, w;
}e[MAXM];
int head[MAXN], ecnt;
int sz[MAXN];
```

```
int d[MAXN], t[5], ans;
7
    bool vis[MAXN];
   inline void add_edge(int u, int v, int w) {
   e[++ecnt] = (Edge) {v, head[u], w}; head[u] = ecnt;
8
9
        e[++ecnt] = (Edge) \{u, head[v], w\}; head[v] = ecnt;
10
11
12
    int getsz(int x, int fa) {
        sz[x] = 1;
13
        for(int i = head[x]; i; i = e[i].nxt) {
14
15
             int y = e[i].to;
            if(vis[y] || y == fa) continue;
16
17
            sz[x] += getsz(y, x);
        }
18
19
        return sz[x];
20
21
    int getrt(int x) {
        int tot = getsz(x, 0) >> 1;
22
23
        while(1) {
24
             int u = -1;
             for(int i = head[x]; i; i = e[i].nxt) {
25
26
                 int y = e[i].to;
                 if(vis[y] || sz[y] > sz[x]) continue;
27
                 if(u == -1 \mid | sz[y] > sz[u]) u = y;
28
29
30
            if(\sim u \&\& sz[u] > tot) x = u;
31
            else break;
32
        }
33
        return x;
34
    void getdep(int x, int fa) {
35
36
        t[d[x]]++;
        for(int i = head[x]; i; i = e[i].nxt) {
37
             int y = e[i].to;
38
            if(vis[y] || y == fa) continue;
39
            d[y] = (d[x] + e[i].w) % 3;
40
            getdep(y, x);
41
        }
42
   }
43
    int cal(int x, int v) {
44
45
        t[0] = t[1] = t[2] = 0;
46
        d[x] = v \% 3;
47
        getdep(x, 0);
        return t[0] * t[0] + t[1] * t[2] * 2;
48
49
   void solve(int x) {
50
        vis[x] = 1;
51
52
        ans += cal(x, 0);
        for(int i = head[x]; i; i = e[i].nxt) {
53
             int y = e[i].to;
54
55
             if(vis[y]) continue;
            ans -= cal(y, e[i].w);
56
             solve(getrt(y));
57
        }
58
59
   int main() {
60
        solve(getrt(1));
61
62
   }
```

1.4 LCA

1.4.1 Tree Decomposition LCA

```
int sz[MAXN], dep[MAXN], top[MAXN], fa[MAXN], son[MAXN], num[MAXN], totw;
   struct Edge {
        int to, nxt;
   }e[MAXN << 1];
   int head[MAXN], ecnt;
   inline void add_edge(int x, int y) {
6
        e[++ecnt] = (Edge) \{y, head[x]\}; head[x] = ecnt;
7
8
9
   void dfs1(int x) {
10
        sz[x] = 1; son[x] = 0;
11
        for(int i = head[x]; i; i = e[i].nxt) {
12
            int v = e[i].to;
13
            if(v == fa[x]) continue;
14
            fa[v] = x;
            dep[v] = dep[x] + 1;
15
16
            dfs1(v);
            sz[x] += sz[v];
17
            if(sz[v] > sz[son[x]]) son[x] = v;
18
       }
19
   }
20
   void dfs2(int x) {
21
        B[num[x]] = A[x];
22
        if(son[x]) {
23
24
            top[son[x]] = top[x];
25
            num[son[x]] = ++totw;
26
            dfs2(son[x]);
27
        for(int i = head[x]; i; i = e[i].nxt) {
28
            int v = e[i].to;
29
            if(v == fa[x] | | v == son[x]) continue;
30
            top[v] = v;
31
32
            num[v] = ++totw;
33
            dfs2(v);
34
       }
35
36
   int lca(int u, int v) {
        if(u == v) return u;
37
       while(top[u] != top[v]) {
38
            if(dep[top[u]] > dep[top[v]]) swap(u, v);
39
            v = fa[top[v]];
40
41
       if(dep[u] > dep[v]) swap(u, v);
42
        return u;
43
44
   inline void init() {
45
       memset(head, 0, sizeof(head)); ecnt = 0;
46
        fa[1] = 0; dep[1] = 1; top[1] = 1; num[1] = 1; totw = 1;
47
48
   inline void pre() {
49
50
        dfs1(1); dfs2(1);
51
   }
```

1.4.2 Tarjan LCA

```
vector< pair<int,int> > G[MAXN],ask[MAXN];
```

```
int fa[MAXN], ans[MAXN], vis[MAXN] ,dis[MAXN];
2
3
   int Find(int x){
        return x == fa[x] ? x : fa[x] = Find(fa[x]);
4
5
   void init(int n){
6
        memset(ans, 0,sizeof ans);
7
8
        memset(vis, 0,sizeof vis);
        for(int i = 0; i \le n; i++){
9
            G[i].clear();
10
            ask[i].clear();
11
        }
12
   }
13
    void LCA(int u){
14
15
        int v;
        fa[u] = u;
16
        vis[u] = true;
17
        for(auto it : ask[u])
18
19
            if(vis[v = it.first])
                ans[it.second] = dis[u] + dis[v] - 2 * dis[Find(it.first)];
20
        for(auto it : G[u])
21
        if(!vis[v = it.first]){
22
            dis[v] = dis[u] + it.second;
23
            LCA(v);
24
25
            fa[v] = u;
26
        }
27
   }
```

1.5 Tarjan

1.5.1 SCC

```
namespace SCC{
1
2
        vector<int> G[MAXN];
3
        int dfs_clock, scc_cn, dfn[MAXN], low[MAXN], sccno[MAXN];
        stack<int> S;
4
5
        void addEdge(int u, int v) {
6
            G[u].push_back(v);
7
        void tarjan(int u) {
8
            dfn[u] = low[u] = ++dfs\_clock;
9
            S.push(u);
10
            for(auto v : G[u]) {
11
                 if(!dfn[v]) {
12
                    tarjan(v);
13
                     low[u] = min(low[u], low[v]);
14
                }else if(!sccno[v]) {
15
16
                     low[u] = min(low[u], dfn[v]);
17
18
            if(dfn[u] == low[u]) {
19
20
                scc_cnt++;
21
                for(;;) {
                     int v = S.top(); S.pop();
22
                     sccno[v] = scc_cnt;
23
                     if(v == u) break;
24
25
                }
26
            }
27
        void findSCC(int n) {
28
```

```
for(int i = 1; i <= n; i++)</pre>
29
30
                  if(!dfn[i]) tarjan(i);
31
        void init(int n){
32
             dfs_clock = scc_cnt = 0;
33
             for(int i = 0;i <= n;++i){</pre>
34
35
                  dfn[i] = low[i] = sccno[i] = 0;
36
                  G[i].clear();
             }
37
        }
38
    }
39
```

1.5.2 BCC

```
namespace BCC{
 1
 2
         struct Edge {
              int to, nxt;
 3
         e[MAXM << 1];
 4
 5
         int ecnt, head[MAXN];
 6
         int dfs_clock, dfn[MAXN], low[MAXN];
 7
         int is_vertex[MAXN], vbcc_cnt, vbccno[MAXN];
 8
 9
         vector<int> vbcc[MAXN];
10
         stack<int> vS;
11
         int ebcc_cnt, ebccno[MAXN];
12
13
         stack<int> eS;
14
         inline void addEdge(int u, int v) {
    e[++ecnt] = (Edge) {v, head[u]}; head[u] = ecnt;
    e[++ecnt] = (Edge) {u, head[v]}; head[v] = ecnt;
15
16
17
18
         inline void init(int n) {
19
              ecnt = 1;
20
21
              dfs\_clock = 0;
22
              vbcc\_cnt = 0;
23
              ebcc\_cnt = 0;
              for(int i = 1; i <= n; ++i){</pre>
24
                  head[i] = dfn[i] = low[i] = 0;
25
26
                   is_vertex[i] = 0;
27
                  vbccno[i] = 0;
28
                  ebccno[i] = 0;
29
              while(!vS.empty()) vS.pop();
30
         }
31
32
         //root 's edge = -1;
33
         void tarjan(int u, int edge) {
              dfn[u] = low[u] = ++dfs\_clock;
34
35
              int ch = 0;
36
              vS.push(u);
37
              eS.push(u);
              for(int i = head[u], v; i; i = e[i].nxt) {
    if(!dfn[v = e[i].to]) {
38
39
                       tarjan(v, i ^ 1)
40
                       low[u] = min(low[u], low[v]);
41
                       if(low[v] >= dfn[u]) {
42
                            ++ch;
43
                            if(edge > 0 || ch > 1) is_vertex[u] = 1;
44
45
                            vbcc[++vbcc_cnt].clear();
46
                            vbcc[vbcc_cnt].push_back(u);
```

```
for(int x;;){
47
                               x = vS.top();vS.pop();
48
                               vbcc[vbcc_cnt].push_back(x);
49
50
                               vbccno[x] = vbcc_cnt;
51
                               if(x == v)break;
52
53
                      if(low[v] > dfn[u]) {
// i && i ^ 1 is bridge
}
54
55
56
57
                 else if(dfn[v] < dfn[u] && i != edge)</pre>
58
                      low[u] = min(low[u], dfn[v]);
59
60
             if(dfn[u] == low[u]) {
61
                 ebcc_cnt++;
62
                 for(int v;;) {
63
                      v = eS.top(); eS.pop();
64
65
                      ebccno[v] = ebcc_cnt;
                      if(v == u) break;
66
                 }
67
             }
68
69
        void findBCC(int n){
70
71
             for(int i = 1; i <= n; i++)
72
                 if(!dfn[i]) tarjan(i, -1);
73
74
             //findBridge
             for(int u = 1; u <= n; u++) {
75
                  for(int i = head[u], v; i; i = e[i].nxt)
76
                 if(ebccno[u] != ebccno[v = e[i].to]) {
77
78
                      //is bridge
79
            }
80
        }
81
   }
82
```

1.6 Cactus

1.6.1 Circle-Square Tree

```
#include <bits/stdc++.h>
1
2
   using namespace std;
3
   typedef pair<int, int> P;
   const int MAXN = 2e4 + 5;
4
   const int S = 15;
5
6
   namespace Tree {
7
        struct Edge {
8
            int to, nxt, w;
        }e[MAXN << 1];
9
        int ecnt, head[MAXN];
10
        int rt, isrt[MAXN], fa[MAXN][S + 3];
11
        int sz[MAXN];
12
        inline void addEdge(int u, int v, int w) {
13
            e[++ecnt] = (Edge) \{v, head[u], w\}; head[u] = ecnt;
14
            fa[v][0] = u;
15
       }
16
17
   int n, m, Q;
```

```
namespace BCC {
19
20
        struct Edge {
21
            int to, nxt, w;
        }e[MAXN << 1];</pre>
22
        int ecnt, head[MAXN];
23
        int dfs_clock, dfn[MAXN], low[MAXN];
24
25
        int is_vertex[MAXN], vbcc_cnt, vbccno[MAXN];
26
        vector<P> vbcc[MAXN];
        stack<P> vs;
27
        int tag[MAXN];
28
        inline void addEdge(int u, int v, int w) {
29
            e[++ecnt] = (Edge) \{v, head[u], w\}; head[u] = ecnt;
30
            e[++ecnt] = (Edge) \{u, head[v], w\}; head[v] = ecnt;
31
32
33
        inline void init(int n) {
34
            ecnt = 1;
            dfs\_clock = 0;
35
            vbcc\_cnt = 0;
36
            for(int i = 0; i <= 2 * n; i++){</pre>
37
38
                 head[i] = dfn[i] = low[i] = 0;
                 vbccno[i] = 0;
39
                 tag[i] = 0;
40
41
            while(!vs.empty()) vs.pop();
42
        }
43
44
        //root 's edge = -1;
45
        void tarjan(int u, int edge) {
46
            dfn[u] = low[u] = ++dfs\_clock;
47
            vs.push(P(u, e[edge ^ 1].w));
            for(int i = head[u], v; i; i = e[i].nxt) {
   if(!dfn[v = e[i].to]) {
48
49
                     tarjan(v, i ^ 1)
50
                     low[u] = min(low[u], low[v]);
51
                     if(low[v] >= dfn[u]) {
52
                          if(vs.top().first == v) {
53
                              Tree::addEdge(u, v, vs.top().second);
54
                              vs.pop();
55
                              continue;
56
57
58
                          vbcc[++vbcc_cnt].clear();
59
                          vbcc[vbcc_cnt].push_back(P(u, 0));
                          Tree::isrt[u] = 1;
60
                          int &sz = Tree::sz[n + vbcc_cnt];
61
                          tag[vs.top().first] = n + vbcc_cnt;
62
63
                          //Tree::addEdge(u, rt, 0);
                          for(P x;;) {
64
65
                              x = vs.top(); vs.pop();
66
                              sz += x.second;
67
                              //Tree::addEdge(rt, x.first, sz);
                              vbcc[vbcc_cnt].push_back(x);
68
                              vbccno[x.first] = vbcc_cnt;
69
                              if(x.first == v) break;
70
71
                          }
                     }
72
73
                 else if(dfn[v] < dfn[u] && i != edge)</pre>
74
75
                     low[u] = min(low[u], dfn[v]);
76
            for(int i = head[u], v; i; i = e[i].nxt) {
77
                 if(tag[v = e[i].to]) {
78
79
                     int r = tag[v]; Tree::sz[r] += e[i].w;
```

```
tag[v] = 0;
80
                 }
81
82
             }
83
         void findBCC(int n) {
84
             for(int i = 1; i <= n; i++)
85
                 if(!dfn[i]) tarjan(i, -1);
86
87
        }
88
    namespace Tree {
89
         int dis[MAXN], dep[MAXN], len[MAXN];
90
         inline void init(int n) {
91
             BCC::init(n);
92
93
             rt = n;
94
             ecnt = 1;
             for(int i = 0; i <= 2 * n; i++) {
95
                 head[i] = 0;
96
                 fa[i][0] = isrt[i] = dis[i] = dep[i] = len[i] = 0;
97
98
             }
99
         void dfs(int x) {
100
             for(int i = head[x], y; i; i = e[i].nxt) {
101
                 if(!dep[y = e[i].to]) {
102
                      dep[y] = dep[x] + 1;
103
                      dis[y] = dis[x] + e[i].w;
104
105
                      dfs(y);
106
                 }
             }
107
108
         void pre() {
109
             for(int k = 1; k <= BCC::vbcc_cnt; k++) {</pre>
110
111
                  rt++;
                 vector<P> &E = BCC::vbcc[k];
112
                 addEdge(E[0].first, rt, 0);
113
                 int cnt = 0;
114
                 for(int i = E.size() - 1; i >= 1; i--) {
115
                      cnt += E[i].second;
116
                      len[E[i].first] = cnt;
117
                      addEdge(rt, E[i].first, min(cnt, sz[rt] - cnt));
118
119
                 }
120
             for(int k = 1; k <= S; k++) {</pre>
121
                 for(int i = 1; i <= rt; i++) {</pre>
122
                      fa[i][k] = fa[fa[i][k - 1]][k - 1];
123
124
125
             dep[1] = 1;
126
             dfs(1);
127
128
         int up(int x, int d) {
129
             for(int i = S; i >= 0; i--) {
130
                  if(dep[fa[x][i]] >= d) x = fa[x][i];
131
132
             return x;
133
134
         int lca(int u, int v) {
135
             if(dep[u] > dep[v]) swap(u, v);
136
             v = up(v, dep[u]);
137
             if(u == v) return u;
138
             for(int i = S; i >= 0; i--) {
139
                 if(fa[u][i] != fa[v][i]) {
140
```

```
u = fa[u][i], v = fa[v][i];
141
142
               }
143
               return fa[u][0];
144
145
          int query(int u, int v) {
146
               int l = lca(u, v);
if(l <= n) return dis[u] + dis[v] - 2 * dis[l];</pre>
147
148
               int x = up(u, dep[l] + 1), y = up(v, dep[l] + 1);
int res = dis[u] - dis[x] + dis[v] - dis[y];
149
150
               int tmp = abs(len[x] - len[y]);
return res + min(tmp, sz[l] - tmp);
151
152
153
          }
     }
154
155
     int main() {
156
          ios::sync_with_stdio(0); cin.tie(0); cout.precision(6); cout << fixed;</pre>
157
158
          using namespace Tree;
159
          cin >> n >> m >> 0;
          init(n);
160
          for(int i = 1, u, v, w; i <= m; i++) {
161
               cin >> u >> v >> w;
162
               BCC::addEdge(u, v, w);
163
164
165
          BCC::findBCC(n);
          pre();
166
          int u, v;
167
168
          while(Q--) {
169
               cin >> u >> v;
               cout << query(u, v) << endl;</pre>
170
171
172
          return 0;
     }
173
```

2 Data Structures

2.1 Basic Structures

2.1.1 RMQ

```
1
   struct RMQ {
       int d[MAXN][S + 3];
2
3
       inline void init(int *a, int n) {
            for(int i = 0; i < n; i++) d[i][0] = a[i];</pre>
4
5
            for(int k = 1; (1 << k) < n; k++)
                for(int i = 0; i + (1 << k) - 1 < n; i++)
6
7
                    d[i][k] = min(d[i][k - 1], d[i + (1 << (k - 1))][k - 1]);
8
9
       inline int query(int 1, int r) {
10
            if(l > r) swap(l, r);
            int k = 0;
11
12
            while((1 << (k + 1)) <= r - l + 1) k++;
13
            return min(d[l][k], d[r - (1 << k) + 1][k]);
14
   }rmq;
15
```

2.1.2 Divide Blocks

```
int belong[MAXN], l[MAXN], r[MAXN];
2
   int sz, num;
   void build(int n) {
3
        sz = sqrt(n);
4
5
        num = n / sz; if(n % sz) num++;
6
        for(int i = 1; i <= num; i++) {</pre>
            l[i] = (i - 1) * sz + 1;
7
8
            r[i] = i * sz;
9
        }
10
        r[num] = n;
11
        for(int i = 1; i <= n; i++) {</pre>
12
            belong[i] = (i - 1) / sz + 1;
13
14
   }
```

2.2 Tree Structures

2.2.1 Tree Decomposition

```
int sz[MAXN], dep[MAXN], top[MAXN], fa[MAXN], son[MAXN], num[MAXN], totw;
   struct Edge {
2
       int to, nxt;
3
   e[MAXN << 1]
4
   int head[MAXN], ecnt;
5
6
  int n, m, Q;
   #define Ls(x) (x << 1)
7
   #define Rs(x) (x << 1 | 1)
8
   struct Tree {
9
       int l, r, lazy;
10
11
       LL sum, mx;
12 }tree[MAXN << 2];</pre>
int A[MAXN], B[MAXN];
```

```
void push_up(int x) {
14
        tree[x].sum = tree[Ls(x)].sum + tree[Rs(x)].sum;
15
        tree[x].mx = max(tree[Ls(x)].mx, tree[Rs(x)].mx);
16
17
   void push_down(int x) {
18
        if(tree[x].lazy) {
19
            tree[Ls(x)].sum += tree[x].lazy * (tree[Ls(x)].r - tree[Ls(x)].l + 1);
20
            tree[Rs(x)].sum += tree[x].lazy * (tree[Rs(x)].r - tree[Rs(x)].l + 1);
21
            tree[Ls(x)].mx += tree[x].lazy;
22
            tree[Rs(x)].mx += tree[x].lazy;
23
            tree[Ls(x)].lazy += tree[x].lazy;
24
            tree[Rs(x)].lazy += tree[x].lazy;
25
26
            tree[x].lazy = 0;
27
        }
28
   void build(int x, int L, int R) {
29
        tree[x].lazy = 0;
30
        tree[x].l = L; tree[x].r = R;
31
32
        if(L == R) {
33
            tree[x].sum = B[L];
            tree[x].mx = B[L];
34
35
            return;
36
        int mid = (L + R) \gg 1;
37
        build(Ls(x), L, mid);
38
39
        build(Rs(x), mid + 1, R);
40
        push_up(x);
41
42
    void update(int x, int L, int R, LL val)
        if(tree[x].l >= L && tree[x].r <= R) {
43
44
            tree[x].lazy += val;
            tree[x].sum += val * (tree[x].r - tree[x].l + 1);
45
            tree[x].mx += val;
46
            return;
47
        }
48
        push_down(x);
49
50
        int mid = (tree[x].l + tree[x].r) >> 1;
        if(L \Leftarrow mid) update(Ls(x), L, R, val);
51
52
        if(R > mid) update(Rs(x), L, R, val);
53
        push_up(x);
54
   LL query(int x, int L, int R) {
55
        if(tree[x].l >= L \&\& tree[x].r <= R)
56
57
            return tree[x].sum;
58
        push_down(x);
59
        int mid = (tree[x].l + tree[x].r) >> 1;
60
        LL res = 0;
        if(L \le mid) res += query(Ls(x), L, R);
61
        if(R > mid) res += query(Rs(x), L, R);
62
63
        return res;
64
   LL query2(int x, int L, int R) {
65
        if(tree[x].1 >= L && tree[x].r <= R)
66
            return tree[x].mx;
67
        push_down(x);
68
        int mid = (tree[x].l + tree[x].r) >> 1;
69
        LL res = -INF;
70
71
        if(L \le mid) res = max(res, query2(Ls(x), L, R));
        if(R > mid) res = max(res, query2(Rs(x), L, R));
72
        return res;
73
74
   }
```

```
inline void add_edge(int x, int y) {
75
        e[++ecnt] = (Edge) \{y, head[x]\}; head[x] = ecnt;
76
77
    void dfs1(int x) {
78
         sz[x] = 1; son[x] = 0;
79
         for(int i = head[x]; i; i = e[i].nxt) {
80
             int v = e[i].to;
81
82
             if(v == fa[x]) continue;
             fa[v] = x;
83
             dep[v] = dep[x] + 1;
84
             dfs1(v);
85
             sz[x] += sz[v];
86
             if(sz[v] > sz[son[x]]) son[x] = v;
87
88
        }
89
    }
    void dfs2(int x) {
90
         B[num[x]] = A[x];
91
         if(son[x]) {
92
93
             top[son[x]] = top[x];
94
             num[son[x]] = ++totw;
             dfs2(son[x]);
95
96
         for(int i = head[x]; i; i = e[i].nxt) {
97
             int v = e[i].to;
98
99
             if(v == fa[x] | | v == son[x]) continue;
100
             top[v] = v;
101
             num[v] = ++totw;
102
             dfs2(v);
103
        }
104
    void up(int a, int b, int c) {
105
         int f1 = top[a], f2 = top[b];
106
        while(f1 != f2) {
107
             if(dep[f1] < dep[f2]) { swap(a, b); swap(f1, f2); }</pre>
108
             update(1, num[f1], num[a], c);
109
             a = fa[f1];
110
             f1 = top[a];
111
112
         if(dep[a] > dep[b]) swap(a, b);
113
114
        update(1, num[a], num[b], c);
115
116
    int qsum(int a, int b) {
         if(a == b) return query(1, num[a], num[a]);
117
         int f1 = top[a], f2 = top[b];
118
         int res = 0;
119
        while(f1 != f2) {
120
             if(dep[f1] < dep[f2]) { swap(a, b); swap(f1, f2); }</pre>
121
             res += query(1, num[f1], num[a]);
122
             a = fa[f1];
123
124
             f1 = top[a];
125
         if(dep[a] > dep[b]) swap(a, b);
126
127
         res += query(1, num[a], num[b]);
         return res;
128
129
    int qmax(int a, int b) {
130
         if(a == b) return query2(1, num[a], num[a]);
131
         int f1 = top[a], f2 = top[b];
132
         int res = -10000000000;
133
        while(f1 != f2) {
134
             if(dep[f1] < dep[f2]) { swap(a, b); swap(f1, f2); }
135
```

```
res = max(res, query2(1, num[f1], num[a]));
136
             a = fa[f1];
137
             f1 = top[a];
138
139
        if(dep[a] > dep[b]) swap(a, b);
140
         res = max(res, query2(1, num[a], num[b]));
141
142
        return res;
143
    inline void init() {
144
        memset(head, 0, sizeof(head)); ecnt = 0;
145
         fa[1] = 0; dep[1] = 1; top[1] = 1; num[1] = 1; totw = 1;
146
147
    inline void pre() {
148
         dfs1(1); dfs2(1); build(1, 1, totw);
149
150
    }
```

2.2.2 Link-Cut Tree

```
namespace LCT {
2
        int fa[MAXN], rev[MAXN], tr[MAXN][2];
3
        int s[MAXN], val[MAXN];
4
        void push_up(int x) {
            int l = tr[x][0], r = tr[x][1];
5
            s[x] = s[l] + s[r] + val[x];
6
 7
8
        void Rev(int x) {
            rev[x] ^= 1; swap(tr[x][0], tr[x][1]);
9
10
        void push_down(int x) {
11
12
            if(!rev[x]) return;
13
            int l = tr[x][0], r = tr[x][1];
            rev[x] = 0;
14
            if(l) Rev(l); if(r) Rev(r);
15
16
17
        bool isroot(int x) {
            return tr[fa[x]][0] != x && tr[fa[x]][1] != x;
18
19
        void pre(int x) {
20
            if(!isroot(x)) pre(fa[x]);
21
22
            push_down(x);
23
        void rotate(int x) {
24
            int y = fa[x]; int z = fa[y];
25
            int l = tr[y][1] == x;
26
            int r = 1 \wedge 1;
27
28
            if(!isroot(y)) tr[z][tr[z][1] == y] = x;
29
            fa[x] = z; fa[y] = x; fa[tr[x][r]] = y;
            tr[y][l] = tr[x][r]; tr[x][r] = y;
30
31
            push_up(y);
32
        void splay(int x) {
33
34
            pre(x);
35
            int y, z;
            while(!isroot(x)) {
36
37
                y = fa[x]; z = fa[y];
                if(!isroot(y)) {
38
                     if((tr[z][0] == y) == (tr[y][0] == x))rotate(y);
39
                     else rotate(x);
40
41
                rotate(x);
```

```
43
            push_up(x);
44
45
46
        void access(int x) {
47
            int y = 0;
            while(x) {
48
                splay(x); tr[x][1] = y;
49
                push_up(x);
50
51
                y = x; x = fa[x];
            }
52
53
        void makeroot(int x) {
54
            access(x); splay(x); Rev(x);
55
56
        void lnk(int x, int y) {
57
            makeroot(x); fa[x] = y;
58
59
        void cut(int x, int y) {
60
            makeroot(x); access(y); splay(y);
61
62
            tr[y][0] = fa[x] = 0; push_up(y);
63
        void update(int x, int y) {
64
            makeroot(x); val[x] = y; push_up(x);
65
66
        int query(int x, int y) {
67
68
            makeroot(x); access(y); splay(y);
            return s[y];
69
70
        bool check(int x, int y) {
71
72
            int tmp = y;
            makeroot(x); access(y); splay(x);
73
            while(!isroot(y)) y = fa[y];
74
            splay(tmp);
75
76
            return x == y;
        }
77
   }
78
```

2.3 Sequence Structures

2.3.1 Segment Tree

```
#define Ls(x) (x << 1)
1
   #define Rs(x) (x << 1 | 1)
2
   struct Tree {
3
4
        int l, r, lazy;
5
        LL sum, mx;
   }tree[MAXN << 2];</pre>
6
   int A[MAXN];
7
   void push_up(int x) {
8
        tree[x].sum = tree[Ls(x)].sum + tree[Rs(x)].sum;
9
        tree[x].mx = max(tree[Ls(x)].mx, tree[Rs(x)].mx);
10
11
   void push_down(int x) {
12
        if(tree[x].lazy) {
13
            tree[Ls(x)].sum += tree[x].lazy * (tree[Ls(x)].r - tree[Ls(x)].l + 1);
14
            tree[Rs(x)].sum += tree[x].lazy * (tree[Rs(x)].r - tree[Rs(x)].l + 1);
15
            tree[Ls(x)].mx += tree[x].lazy;
16
            tree[Rs(x)].mx += tree[x].lazy;
17
18
            tree[Ls(x)].lazy += tree[x].lazy;
```

```
19
            tree[Rs(x)].lazy += tree[x].lazy;
20
            tree[x].lazy = 0;
21
        }
   }
22
   void build(int x, int L, int R) {
23
        tree[x].lazy = 0;
24
25
        tree[x].l = L; tree[x].r = R;
        if(L == R) {
26
27
             tree[x].sum = A[L];
            tree[x].mx = A[L];
28
29
             return;
30
        int mid = (L + R) \gg 1;
31
        build(Ls(x), L, mid);
32
33
        build(Rs(x), mid + 1, R);
34
        push_up(x);
35
    void update(int x, int L, int R, LL val) {
36
37
        if(tree[x].l >= L && tree[x].r <= R) {
38
            tree[x].lazy += val;
            tree[x].sum += val * (tree[x].r - tree[x].l + 1);
39
            tree[x].mx += val;
40
             return;
41
42
        push_down(x);
43
44
        int mid = (tree[x].l + tree[x].r) >> 1;
45
        if(L <= mid) update(Ls(x), L, R, val);</pre>
        if(R > mid) update(Rs(x), L, R, val);
46
47
        push_up(x);
48
   LL query(int x, int L, int R) {
   if(tree[x].l >= L && tree[x].r <= R)</pre>
49
50
             return tree[x].sum;
51
        push_down(x);
52
        int mid = (tree[x].l + tree[x].r) >> 1;
53
        LL res = 0;
54
        if(L <= mid) res += query(Ls(x), L, R);</pre>
55
        if(R > mid) res += query(Rs(x), L, R);
56
57
        return res;
58
59
   LL query2(int x, int L, int R) {
60
        if(tree[x].l >= L && tree[x].r <= R)
61
             return tree[x].mx;
62
        push_down(x);
        int mid = (tree[x].l + tree[x].r) >> 1;
63
        LL res = -INF;
64
        if(L <= mid) res = max(res, query2(Ls(x), L, R));</pre>
65
        if(R > mid) res = max(res, query2(Rs(x), L, R));
66
        return res;
67
68
```

2.3.2 Splay Tree

```
namespace splay{
   int n, m, sz, rt;
   int val[MAXN], id[MAXN];
   int tr[MAXN][2], size[MAXN], rev[MAXN], s[MAXN], lazy[MAXN];
   void push_up(int x) {
      int l = tr[x][0], r = tr[x][1];
      s[x] = max(val[x], max(s[l], s[r]));
```

```
size[x] = size[l] + size[r] + 1;
8
9
10
        void push_down(int x) {
11
            int l = tr[x][0], r = tr[x][1];
12
            if(lazy[x]) {
                if(1) {
13
                     lazy[l] += lazy[x];
14
                     s[l] += lazy[x];
15
                     val[l] += lazy[x];
16
17
                 if(r) {
18
                     lazy[r] += lazy[x];
19
                     s[r] += lazy[x];
20
                     val[r] += lazy[x];
21
22
                 lazy[x] = 0;
23
24
            if(rev[x]) {
25
26
                 rev[x] = 0;
                 rev[l] ^= 1; rev[r] ^= 1;
27
                 swap(tr[x][0], tr[x][1]);
28
            }
29
30
        void rotate(int x, int &k) {
31
32
            int y = fa[x];
33
            int z = fa[y];
            int l, r;
34
35
            if(tr[y][0] == x) l = 0;
36
            else l = 1;
            r = 1 \wedge 1;
37
            if(y == k) k = x;
38
            else {
39
                 if(tr[z][0] == y) tr[z][0] = x;
40
                else tr[z][1] = x;
41
42
            fa[x] = z; fa[y] = x; fa[tr[x][r]] = y;
43
            tr[y][l] = tr[x][r]; tr[x][r] = y;
44
            push_up(y); push_up(x);
45
46
47
        void splay(int x, int &k) {
48
            int y, z;
            while(x != k) {
49
50
                y = fa[x];
                z = fa[y];
51
52
                 if(y != k) {
                     if((tr[y][0] == x) \land (tr[z][0] == y)) rotate(x, k);
53
54
                     else rotate(y, k);
55
                 rotate(x, k);
56
57
            }
58
        int find(int x, int rank) {
59
60
            push_down(x);
            int l = tr[x][0], r = tr[x][1];
61
            if(size[l] + 1 == rank) return x;
62
            else if(size[l] >= rank) return find(l, rank);
63
            else return find(r, rank - size[l] - 1);
64
65
        void update(int 1, int r, int v) {
66
            int x = find(rt, 1), y = find(rt, r + 2);
67
            splay(x, rt); splay(y, tr[x][1]);
```

```
69
             int z = tr[y][0];
70
             lazy[z] += v;
71
             val[z] += v;
72
             s[z] += v;
73
74
         void reverse(int 1, int r) {
             int x = find(rt, 1), y = find(rt, r + 2);
75
76
             splay(x, rt); splay(y, tr[x][1]);
             int z = tr[y][0];
77
             rev[z] ^= \overline{1};
78
79
         void query(int 1, int r) {
80
             int x = find(rt, 1), y = find(rt, r + 2);
81
82
             splay(x, rt); splay(y, tr[x][1]);
             int z = tr[y][0];
83
             printf("%d\n", s[z]);
84
85
         void build(int 1, int r, int f) {
86
87
             if(l > r) return;
88
             int now = id[l], last = id[f];
89
             if(l == r) {
                 fa[now] = last; size[now] = 1;
90
                 if(1 < f) tr[last][0] = now;
91
                 else tr[last][1] = now;
92
93
                 return;
94
             }
95
             int mid = (l + r) \gg 1; now = id[mid];
96
             build(l, mid - 1, mid); build(mid + 1, r, mid);
97
             fa[now] = last;
98
             push_up(now);
             if(mid < f) tr[last][0] = now;</pre>
99
100
             else tr[last][1] = now;
101
         void init() {
102
             s[0] = -INF;
103
             scanf("%d%d", &n, &m);
104
             for(int i = 1; i <= n + 2; i++) id[i] = ++sz;</pre>
105
             build(1, n + 2, 0); rt = (n + 3) >> 1;
106
107
        }
108
```

2.4 Persistent Data Structures

2.4.1 Chairman Tree

```
struct Node {
1
2
        int l, r;
3
        LL sum;
   }t[MAXN * 40];
4
5
   int cnt, n;
   int rt[MAXN];
6
7
   void update(int pre, int &x, int l, int r, int v) {
       x = ++cnt; t[x] = t[pre]; t[x].sum++;
8
9
        if(l == r) return;
        int mid = (l + r) >> 1;
10
        if(v \leftarrow mid) update(t[pre].l, t[x].l, l, mid, v);
11
        else update(t[pre].r, t[x].r, mid + 1, r, v);
12
13
   int query(int x, int y, int l, int r, int v) {
```

```
if(l == r) return l;
int mid = (l + r) >> 1;
int sum = t[t[y].l].sum - t[t[x].l].sum;
if(sum >= v) return query(t[x].l, t[y].l, l, mid, v);
else return query(t[x].r, t[y].r, mid + 1, r, v - sum);
}
```

2.4.2 Persistent Trie

```
//区间异或最值查询
   const int N=5e4+10;
   int t[N];
3
   int ch[N*32][2],val[N*32];
4
   int cnt;
5
   void init(){
6
7
        mem(ch,0);
8
        mem(val,0);
9
        cnt=1;
10
   }
11
   int add(int root,int x){
12
        int newroot=cnt++,ret=newroot;
13
        for(int i=30;i>=0;i--){
            ch[newroot][0]=ch[root][0];
14
            ch[newroot][1]=ch[root][1];
15
            int now=(x>>i)&1;
16
            root=ch[root][now];
17
            ch[newroot][now]=cnt++;
18
            newroot=ch[newroot][now];
19
20
            val[newroot]=val[root]+1;
21
        }
22
        return ret;
23
    int query(int lt,int rt,int x){
24
25
        int ans=0;
        for(int i=30;i>=0;i--){
26
            int now=(x>>i)&1;
27
            if(val[ch[rt][now^1]]-val[ch[lt][now^1]]){
28
                ans l = (1 << i);
29
                rt=ch[rt][now^1];
30
                lt=ch[lt][now^1];
31
32
                } else{
                rt=ch[rt][now];
33
34
                lt=ch[lt][now];
            }
35
36
37
        return ans;
38
   }
```

3 String

3.1 Basics

3.1.1 Hash

```
const LL p1 = 201, p2 = 301, mod1 = 12000000319, mod2 = 2147483647;
2
   struct Hash {
3
        LL a, b;
        void append(Hash pre, int v) {
4
5
            a = (pre.a * p1 + v) \% mod1;
            b = (pre.b * p2 + v) \% mod2;
6
7
        void init(string S) {
8
            a = b = 0;
9
            for(int i = 0; i < S.size(); i++) append(*this, S[i]);</pre>
10
11
12
        bool operator == (const Hash &x) const {
13
            return a == x.a \&\& b == x.b;
14
15
        bool operator < (const Hash &x) const {</pre>
16
            return a < x.a \mid | (a == x.a \&\& b < x.b);
17
        }
18
   };
```

3.1.2 KMP && exKMP

```
namespace KMP {
1
2
        int f[MAXN];
3
        void get_fail(string A) {
            f[0] = 0; f[1] = 0;
4
5
            for(int i = 1; i < A.size(); i++) {</pre>
6
                int j = f[i];
7
                while(j && A[i] != A[j]) j = f[j];
8
                f[i + 1] = A[i] == A[j] ? j + 1 : 0;
9
            }
        }
10
11
        void kmp(string A, string B) {
12
            get_fail(B);
13
            int j = 0;
14
15
            for(int i = 0; i < A.size(); i++) {</pre>
16
                while(j && B[j] != A[i]) j = f[j];
                if(B[j] == A[i]) j++;
17
18
                if(j == B.size()) {
19
                    ans++;
20
                     j = f[j];
                }
21
            }
22
23
        }
   }
24
   namespace exKMP {
25
26
        int nxt[MAXN], ext[MAXN];
27
        //ext[i]表示S以i开头的后缀与T的前缀相同的长度
28
        void get_nxt(string T) {
29
            int j = 0, mx = 0;
            int m = T.size();
30
            nxt[0] = m;
31
```

```
for(int i = 1; i < m; i++) {</pre>
32
33
                 if(i >= mx || i + nxt[i - j] >= mx) {
34
                     if(i >= mx) mx = i;
                     while(mx < m && T[mx] == T[mx - i]) mx++;
35
36
                     nxt[i] = mx - i;
37
                     j = i;
38
39
                 else nxt[i] = nxt[i - j];
            }
40
41
        void exkmp(string S, string T) {
42
            int j = 0, mx = 0;
43
            get_nxt(T);
44
            int n = S.size(), m = T.size();
45
            for(int i = 0; i < n; i++) {</pre>
46
                 if(i \ge mx \mid | i + nxt[i - j] \ge mx) {
47
                     if(i >= mx) mx = i;
48
                     while(mx < n && mx - i < m && S[mx] == T[mx - i]) mx++;
49
                     ext[i] = mx - i;
50
51
52
                 else ext[i] = nxt[i - j];
53
            }
54
        }
55
56
   }
```

3.1.3 AC Automaton

```
namespace AC {
        int ch[MAXN][sigma_size], last[MAXN];
2
3
        int val[MAXN], f[MAXN], sz;
        inline void init() { sz = 1; memset(ch[0], 0, sizeof(ch[0])); }
4
        inline int idx(char c) { return c - 'a'; }
5
        void insert(string s, int v) {
6
7
            int u = 0;
            for(int i = 0; i < s.size(); i++) {</pre>
8
                 int c = idx(s[i]);
9
                 if(!ch[u][c]) {
10
                     memset(ch[sz], 0, sizeof(ch[sz]));
11
12
                     val[sz] = 0;
13
                     ch[u][c] = sz++;
14
                u = ch[u][c];
15
16
            val[u] = v;
17
18
        void get_fail() {
19
20
            queue<int> q;
            f[0] = 0;
21
22
            for(int c = 0; c < sigma_size; c++) {</pre>
                 int u = ch[0][c];
23
                 if(u) { f[u] = 0; q.push(u); last[u] = 0; }
24
25
            while(!q.empty()) {
26
                 int r = q.front(); q.pop();
27
                 for(int c = 0; c < sigma_size; c++) {</pre>
28
                     int u = ch[r][c];
29
30
                     if(!u) { ch[r][c] = ch[f[r]][c]; continue; }
31
                     q.push(u);
32
                     int v = f[r];
```

```
while(v && !ch[v][c]) v = f[v];
33
34
                     f[u] = ch[v][c];
35
                     last[u] = val[f[u]] ? f[u] : last[f[u]];
36
                 }
            }
37
38
        inline void solve(int j) {
39
40
            if(j) {
                 ans += val[j];
41
                 solve(last[j]);
42
            }
43
44
        void find(string T) {
45
            int j = 0;
46
            for(int i = 0; i < T.size(); i++) {</pre>
47
                 int c = idx(T[i]);
48
                 j = ch[j][c];
49
                 if(val[j]) solve(j);
50
51
                 else if(last[j]) solve(last[j]);
52
            }
        }
53
   }
54
```

3.2 Suffix Related

3.2.1 Suffix Array

```
namespace SA {
1
        char s[MAXN];
2
        int sa[MAXN], rank[MAXN], height[MAXN];
3
       int t[MAXN], t2[MAXN], c[MAXN], n;
4
       void clear() { n = 0; memset(sa, 0, sizeof(sa)); }
5
       void build(int m) {
6
            int *x = t, *y = t2;
7
            for(int i = 0; i < m; i++) c[i] = 0;
8
            for(int i = 0; i < n; i++) c[x[i] = s[i]]++;</pre>
9
10
            for(int i = 1; i < m; i++) c[i] += c[i - 1];
11
            for(int i = n - 1; i >= 0; i--) sa[--c[x[i]]] = i;
12
            for(int k = 1; k <= n; k <<= 1) {
                int p = 0;
13
                for(int i = n - k; i < n; i++) y[p++] = i;
14
                for(int i = 0; i < n; i++) if(sa[i] >= k) y[p++] = sa[i] - k;
15
                for(int i = 0; i < m; i++) c[i] = 0;
16
                for(int i = 0; i < n; i++) c[x[y[i]]]++;
17
                for(int i = 1; i < m; i++) c[i] += c[i - 1];
18
                for(int i = n - 1; i \ge 0; i--) sa[--c[x[y[i]]]] = y[i];
19
20
                swap(x, y);
                p = 1; x[sa[0]] = 0;
21
                for(int i = 1; i < n; i++)</pre>
22
                    x[sa[i]] = y[sa[i - 1]] == y[sa[i]] & y[sa[i - 1] + k] == y[sa[i] + k]
23
       ? p - 1 : p++;
24
                if(p >= n) break;
25
                m = p;
26
            }
27
        void buildHeight() {
28
            int k = 0;
29
            for(int i = 0; i < n; i++) rank[sa[i]] = i;
30
31
            for(int i = 0; i < n; i++) {
```

```
32
                if(k) k--;
                 int j = sa[rank[i] - 1];
33
34
                while(s[i + k] == s[j + k]) k++;
35
                height[rank[i]] = k;
36
            }
37
38
        void init() {
39
            n = strlen(s) + 1;
            build('z' + 1);
40
            buildHeight();
41
        }
42
   }
43
```

3.2.2 Suffix Automaton

3.3 Palindrome Related

3.3.1 Manacher

```
namespace Palindrome {
2
        char s1[MAXN], s2[MAXN];
        int len1, len2, ans;
3
        int p[MAXN]; //p[i] - 1 void init() {
4
5
             len1 = strlen(s1);
6
             s2[0] = '$';
7
             s2[1] = '\#';
8
             for(int i = 0; i < len1; i++) {</pre>
9
                 s2[2 * i + 2] = s1[i];
10
                 s2[2 * i + 3] = '\#';
11
12
             len2 = len1 * 2 + 2;
13
             s2[len2] = \frac{1}{2};
14
15
        void manacher() {
16
             int id = 0, mx = 0;
17
             for(int i = 1; i < len2; i++) {</pre>
18
                 if(mx > i) p[i] = min(p[2 * id - i], mx - i);
19
                 else p[i] = 1;
20
                 while(s2[i + p[i]] == s2[i - p[i]]) p[i]++;
21
22
                 if(i + p[i] > mx) {
                      mx = i + p[i];
23
                      id = i;
24
25
                 }
26
            }
27
        }
28
   }
```

3.3.2 Palindromic Tree

```
struct PalindromicTree {
    int len[MAXN]; //节点 i表示的回文串的长度
    int fail[MAXN]; //fail指针
    int cnt[MAXN]; //节点 i表示的本质不同的串的个数(调用 count())
    int num[MAXN]; //以节点 i表示的最长回文串的最右端点为回文串结尾的回文串个数
```

```
int nxt[MAXN][sigma_size]; //编号为i的节点表示的回文串在两边添加字符c以后变成的回文
6
        串的编号
7
        int S[MAXN]; //存放添加的字符(S[0]=-1(or '\#'))
        int last, p, n;
8
        int newnode(int 1) {
9
10
            for(int i = 0; i < sigma_size; i++) nxt[p][i] = 0;
11
            cnt[p] = 0;
12
            num[p] = 0;
            len[p] = 1;
13
14
            return p++;
15
        inline void init() {
16
            p = 0;
17
            newnode(0);
18
            newnode(-1);
19
            S[0] = -1;
20
            n = 0;
21
            fail[0] = 1;
22
23
        int getfail(int x) {
24
            while(S[n - len[x] - 1] != S[n]) x = fail[x];
25
26
            return x;
27
       void insert(int c) {
28
29
            S[++n] = c;
30
            int cur = getfail(last);
31
            if(!nxt[cur][c]) {
                int now = newnode(len[cur] + 2);
fail[now] = nxt[getfail(fail[cur])][c];
32
33
                nxt[cur][c] = now;
34
                num[now] = num[fail[now]] + 1;
35
36
            last = nxt[cur][c];
37
            cnt[last]++;
38
39
       }
       void count() {
40
            for(int i = p - 1; i >= 0; i--) cnt[fail[i]] += cnt[i];
41
42
43
   };
```

MATH 33

4 Math

4.1 Algebra

4.1.1 FFT

```
const double pi = acos(-1.0);
   const int MAXN = 300003;
   struct comp {
4
        double x, y;
        comp operator + (const comp a) const { return (comp) \{x + a.x, y + a.y\}; }
5
6
        comp operator - (const comp a) const { return (comp) {x - a.x, y - a.y}; }
        comp operator * (const comp a) const { return (comp) \{x * a.x - y * a.y, x * a.y + y\}
7
        * a.x}; }
8
   };
   int rev[MAXN], T;
9
   comp tmp;
10
   void fft(comp *a, int r) {
11
12
        if(r == -1) for(int i = 0; i < T; i++) A[i] = A[i] * A[i];
        for(int i = 0; i < T; i++) if(rev[i] > i) swap(a[rev[i]], a[i]);
13
14
        for(int i = 2, mid = 1; i \le T; mid = i, i \le 1) {
15
            comp step = (comp) \{cos(pi / mid), r * sin(pi / mid)\};
            for(int j = 0; j < T; j += i) {
16
                 comp cur = (comp) \{1, 0\};
17
                 for(int k = j; k < j + mid; k++, cur = cur * step) {
    tmp = a[k + mid] * cur;</pre>
18
19
                     a[k + mid] = a[k] - tmp;
20
                     a[k] = a[k] + tmp;
21
                }
22
            }
23
24
25
        if(r == -1) for(int i = 0; i < T; i++) a[i].y = (int)(a[i].y / T / 2 + 0.5);
26
   }
27
   int n, m;
   comp A[MAXN];
28
29
   void init() {
        for(T = 1; T \le n + m; T \le 1);
30
31
        for(int i = 1; i < T; i++) {</pre>
32
            if(i & 1) rev[i] = (rev[i >> 1] >> 1) ^ (T >> 1);
33
            else rev[i] = rev[i >> 1] >> 1;
34
        }
35
   }
```

4.1.2 NTT

```
const int MAXN = 300005, G = 3, mod = 998244353; //or (479LL << 21) + 1
   int rev[MAXN], T;
   LL qpow(LL x, LL y) {
3
       LL res = 1;
4
       while(y) {
5
           if(y \& 1) res = res * x % mod;
6
7
           x = x * x % mod;
8
           y >>= 1;
9
       }
10
       return res;
11
   }
   void ntt(LL *a, int r) {
   if(r == -1) for(int i = 0; i < T; i++) A[i] = A[i] * B[i] % mod;
```

MATH 34

```
for(int i = 0; i < T; i++) if(rev[i] > i) swap(a[rev[i]], a[i]);
14
        for(int i = 2, mid = 1; i <= T; mid = i, i <<= 1) {
15
16
             LL gn = qpow(G, (mod - 1) / i);
17
             if(r == -1) gn = qpow(gn, mod - 2);
             for(int j = 0; j < T; j += i) {
18
                 LL cur = 1, tmp;
19
                 for(int k = j; k < j + mid; k++, cur = cur * gn % mod) {
    tmp = a[k + mid] * cur % mod;</pre>
20
21
                     a[k + mid] = ((a[k] - tmp) \% mod + mod) \% mod;
22
                     a[k] = (a[k] + tmp) \% mod;
23
                 }
24
            }
25
26
        if(r == -1) {
27
             LL inv = qpow(T, mod - 2);
28
             for(int i = 0; i < T; i++) a[i] = a[i] * inv % mod;
29
        }
30
   }
31
   int n, m;
32
33 LL A[MAXN], B[MAXN];
   void init() {
34
        for(T = 1; T \le n + m; T \le 1);
35
        for(int i = 0; i < T; i++) {</pre>
36
37
            if(i & 1) rev[i] = (rev[i >> 1] >> 1) ^ (T >> 1);
38
            else rev[i] = rev[i >> 1] >> 1;
39
        }
40
   }
```

4.1.3 Linear Basis

```
int Gauss(int n, int m) {
1
2
        int num = 1;
3
        for(int x = 1; x <= n && x <= m; x++) {
            int t = 0;
4
            for(int j = x; j \le m; j++) if(g[j][x]) { t = j; break; }
5
6
            if(t) {
7
                 swap(g[x], g[t]);
                 for(int i = x + 1; i \le n; i++) {
8
9
                     if(g[i][x]) {
10
                         for(int k = 1; k \le m; k++) g[i][k] ^= g[x][k];
11
12
                num++;
13
            }
14
15
16
        return --num;
17
   }
18
    //long long
   int Gauss() {
19
20
        int num = 1;
        for(int k = 61; k >= 0; k--) {
21
22
            int t = 0;
            for(int j = num; j \le cnt; j++) if((A[j] >> k) & 1) { t = j; break; }
23
24
            if(t) {
                 swap(A[t], A[num]);
25
                 for(int j = num + 1; j \leftarrow cnt; j++) if((A[j] >> k) & 1) A[j] ^- A[num];
26
27
                num++;
28
            }
29
        }
30
        return --num;
```

MATH 35

31 }

4.2 Math Theory

4.2.1 Inverse

```
//O(logn) 求n的 逆元
2
    const int mod = 1e6 + 3;
   int exgcd(int a, int b, int &x, int &y) {
3
        int d = a;
4
5
        if(b != 0) {
            d = exgcd(b, a \% b, y, x);
6
            y -= (a / b) * x;
7
8
9
        else {
10
            x = 1; y = 0;
11
        return d;
12
   }
13
   int inverse(int a) {
14
        int x, y;
15
16
        exgcd(a, mod, x, y);
17
        return (x % mod + mod) % mod;
18
19
   int inverse(int a) { return qpow(a, mod - 2); }
20
    //O(n) 求1~n的 逆元
21
   int inv[MAXN];
   void init() {
22
23
        inv[0] = inv[1] = 1;
        for(int i = 2; i < MAXN; i++) inv[i] = (long long)(mod - mod / i) * <math>inv[mod \% i] \%
24
       mod;
25
   }
```

4.2.2 Lucas

```
//mod很小可以预处理逆元的情况
   void init() {
3
        fac[0] = 1;
        for(int i = 1; i < mod; i++) fac[i] = (long long)fac[i - 1] * i % mod;
4
       inv[0] = inv[1] = 1;
5
       for(int i = 2; i < mod; i++) inv[i] = (long long)(mod - mod / i) * inv[mod % i] %</pre>
6
7
       for(int i = 1; i < mod; i++) inv[i] = (long long)inv[i] * <math>inv[i - 1] % mod;
8
9
   int C(int a, int b) {
       if(b > a) return 0;
10
       if(a < mod) return (long long)fac[a] * inv[b] % mod * inv[a - b] % mod;</pre>
11
        return (long long)C(a / mod, b / mod) * C(a % mod, b % mod) % mod;
12
   }
13
14
    //mod过大不能预处理逆元的情况
   LL qpow(LL x, LL y) {
15
       LL res = 1;
16
       while(y) {
17
           if(y \& 1) res = res * x % mod;
18
           x = x * x % mod;
19
20
           y >>= 1;
21
       }
       return res;
```

```
23
    LL C(LL a, LL b) {
24
25
        if(b > a) return 0;
26
        if(b > a - b) b = a - b;
27
         LL s1 = 1, s2 = 1;
         for(LL i = 0; i < b; i++) {
  s1 = s1 * (a - i) % mod;
28
29
             s2 = s2 * (i + 1) % mod;
30
31
         return s1 * qpow(s2, mod - 2) % mod;
32
33
    LL lucas(LL a, LL b) {
34
        if(a < mod) return C(a, b);</pre>
35
         return lucas(a / mod, b / mod) * C(a % mod, b % mod);
36
37
    }
```

4.2.3 CRT && exCRT

```
1
    namespace CRT {
         LL m[MAXN], a[MAXN]; //x_i = a[i] \pmod{m[i]}
2
3
         LL exgcd(LL _a, LL _b, LL &x, LL &y) {
4
             if(!_b) {
5
                  x = 1; y = 0;
6
                  return _a;
7
             LL d = exgcd(_b, _a % _b, y, x);
8
             y = (_a / _b) * x;
9
             return d;
10
11
         LL crt(int n) {
12
             LL M = 1, tmp, res = 0, x, y;
for(int i = 1; i <= n; i++) M *= m[i];
13
14
             for(int i = 1; i <= n; i++) {</pre>
15
                  tmp = M / m[i];
16
                  exgcd(tmp, m[i], x, y);
17
                  x = (x + m[i]) % m[i];
18
                  res = (a[i] * x % M * tmp % M + res) % M;
19
20
21
             return res;
22
        }
23
    namespace EXCRT {
24
        LL m[MAXN], a[MAXN];
25
26
         LL exgcd(LL _a, LL _b, LL &x, LL &y) {
27
             if(!_b) {
28
                  x = 1; y = 0;
                  return _a;
29
30
             LL d = exgcd(_b, _a % _b, y, x);
y -= (_a / _b) * x;
31
32
33
             return d;
34
         LL excrt(int n) {
35
             LL M = m[1], A = a[1], x, y, d, tmp;
for(int i = 2; i <= n; i++) {
36
37
                  d = exgcd(M, m[i], x, y);
38
39
                  if((A - a[i]) % d) return -1; //No solution
40
                  tmp = M / d; M *= m[i] / d;
                  y = (A - a[i]) / d % M * y % M;
41
                  y = (y + tmp) \% tmp;
```

```
A = (m[i] % M * y % M + a[i]) % M;

A = (A + M) % M;

Feturn A;

A = (m[i] % M * y % M + a[i]) % M;

A = (A + M) % M;

A
```

4.2.4 BSGS

```
const int MOD = 76543;
   int hs[MOD + 5], head[MOD + 5], nxt[MOD + 5], id[MOD + 5], ecnt;
   void insert(int x, int y) {
3
        int k = x \% MOD;
4
       hs[ecnt] = x, id[ecnt] = y, nxt[ecnt] = head[k], head[k] = ecnt++;
5
   }
6
7
   int find(int x) {
        int k = x \% MOD;
8
        for(int i = head[k]; i; i = nxt[i])
9
            if(hs[i] == x)
10
11
                return id[i];
12
        return -1;
13
   }
14
   int BSGS(int a, int b, int c){
       memset(head, 0, sizeof head); ecnt = 1;
15
        if(b == 1) return 0;
16
        int m = sqrt(c * 1.0), j;
17
18
        LL x = 1, p = 1;
        for(int i = 0; i < m; i++, p = p * a % c)
19
            insert(p * b % c, i);
20
21
        for(LL i = m; ; i += m){
            if((j = find(x = x * p % c)) != -1) return i - j;
22
23
            if(i > c) break;
24
25
        return -1;
26
   }
```

4.2.5 Miller-Rabin && PollardRho

```
LL ksc(LL a,LL n,LL mod){
1
2
        LL ret=0;
3
        for(;n;n>>=1){
             if(n&1){ret+=a;if(ret>=mod)ret-=mod;}
4
5
            a \le 1; if(a \ge mod)a = mod;
6
        }
7
        return ret;
8
   LL ksm(LL a,LL n,LL mod){
9
10
        LL ret = 1;
        for(;n;n>>=1){
11
             if(n&1)ret=ksc(ret,a,mod);
12
13
            a=ksc(a,a,mod);
        }
14
        return ret;
15
16
    int millerRabin(LL n){
17
        if(n<2 || (n!=2 && !(n&1)))return 0;
18
        LL d=n-1; for(;!(d&1); d>>=1);
19
        for(int i=0;i<20;++i){</pre>
20
```

```
LL a=rand()%(n-1)+1;
21
            LL t=d, m=ksm(a,d,n);
22
23
             for(;t!=n-1 && m!=1 && m!=n-1;m=ksc(m,m,n),t<<=1);</pre>
24
            if(m!=n-1 && !(t&1)) return 0;
25
        }
26
        return 1;
27
28
   LL cnt, fact[100];
   LL gcd(LL a,LL b){return !b?a:gcd(b,a%b);}
29
   LL pollardRho(LL n, int a){
30
        LL x=rand()%n, y=x, d=1, k=0, i=1;
31
        while(d==1){
32
33
            ++k;
34
            x=ksc(x,x,n)+a;if(x>=n)x-=n;
35
            d=gcd(x>y?x-y:y-x,n);
            if(k==i){y=x;i<<=1;}</pre>
36
37
        if(d==n)return pollardRho(n,a+1);
38
39
        return d;
40
   void findfac(LL n){
41
        if(millerRabin(n)){fact[++cnt]=n;return;}
42
        LL p=pollardRho(n,rand()%(n-1)+1);
43
        findfac(p);
44
        findfac(n/p);
45
46
   }
```

4.2.6 $\Phi(n)$

```
1
    int phi(int x) {
        int res = x;
for(int i = 2; i * i <= x; i++) {</pre>
2
3
             if(x \% i == 0) {
4
                  res = res / i * (i - 1);
5
6
                  while(x % i == 0) x /= i;
7
             }
8
        if(x > 1) res = res / x * (x - 1);
9
10
         return res;
11
    }
```

4.2.7 Euler Sieve

```
1
   int prime[MAXN], cnt, phi[MAXN], mu[MAXN];
2
   bool isp[MAXN];
3
   int min_pow[MAXN];
4
                          //最小质因子最高次幂
   int min_sum[MAXN];
                          //1+p+p^2+\ldots+p^k
5
   int div_sum[MAXN];
6
                          //约数和
   int min_index[MAXN]; //最小质因子的指数
8
   int div_num[MAXN];
                          //约数个数
9
   void Euler(int n) {
10
        mu[1] = phi[1] = div_num[1] = div_sum[1] = 1;
for(int i = 2; i <= n; i++) {</pre>
11
12
            if(!isp[i]) {
13
                prime[++cnt] = min_pow[i] = i;
14
15
                phi[i] = i - 1;
```

```
16
                 mu[i] = -1;
                 min_index[i] = 1; div_num[i] = 2;
17
                 div_sum[i] = min_sum[i] = i + 1;
18
19
            for(int j = 1; j <= cnt && i * prime[j] <= n; j++) {</pre>
20
                 isp[i * prime[j]] = 1;
21
22
                 if(i % prime[j] == 0) {
                     phi[i * prime[j]] = phi[i] * prime[j];
mu[i * prime[j]] = 0;
23
24
25
                     min_index[i * prime[j]] = min_index[i] + 1;
26
                     div_num[i * prime[j]] = div_num[i] / (min_index[i] + 1) * (min_index[i *
27
        prime[j]] + 1);
28
                     min_sum[i * prime[j]] = min_sum[i] + min_pow[i] * prime[j];
29
                     div_sum[i * prime[j]] = div_sum[i] / min_sum[i] * min_sum[i * prime[j]];
30
                     min_pow[i * prime[j]] = min_pow[i] * prime[j];
31
32
33
                 phi[i * prime[j]] = phi[i] * (prime[j] - 1);
34
                 mu[i * prime[j]] = -mu[i];
35
36
                 div_num[i * prime[j]] = div_num[i] << 1;</pre>
37
                 min_index[i * prime[j]] = 1;
38
39
40
                 div_sum[i * prime[j]] = div_sum[i] * (prime[j] + 1);
                 min_pow[i * prime[j]] = prime[j];
41
42
                 min_sum[i * prime[j]] = prime[j] + 1;
            }
43
        }
44
   }
45
```

4.2.8 Möbius Inversion

$$\sum_{i}^{n} \sum_{j}^{m} lcm(i, j) (mod \ p)$$

```
int mu[MAXN], prime[MAXN], sum[MAXN], cnt;
   bool isp[MAXN];
2
3
   void getmu(int n) {
       mu[1] = 1;
4
        for(int i = 2; i <= n; i++) {
5
6
            if(!isp[i]) {
7
                mu[i] = -1;
8
                prime[++cnt] = i;
9
            for(int j = 1; j <= cnt && i * prime[j] <= n; j++) {</pre>
10
                isp[i * prime[j]] = 1;
11
                if(i % prime[j] == 0) {
12
                    mu[i * prime[j]] = 0;
13
                    break;
14
15
16
                mu[i * prime[j]] = -mu[i];
17
            }
       }
18
19
   ll n, m, ans;
20
   ll query(ll x, ll y) { return (x * (x + 1) / 2 % mod) * (y * (y + 1) / 2 % mod) % mod; }
```

```
22
    ll F(ll x, ll y) {
23
          ll res = 0, last;
          for(ll i = 1; i <= min(x, y); i = last + 1) {
    last = min(x / (x / i), y / (y / i));
    res = (res + (sum[last] - sum[i - 1]) * query(x / i, y / i) % mod) % mod;</pre>
24
25
26
          }
27
28
          return res;
29
    int main() {
30
31
          cin>>n>>m;
          getmu(min(n, m));
32
          for(ll\ i = 1;\ i \leftarrow min(n,\ m);\ i++)\ sum[i] = (sum[i - 1] + (i * i * mu[i]) % mod) %
33
          mod;
          ll last;
34
          for(ll d = 1; d <= min(n, m); d = last + 1) {</pre>
35
               last = min(n / (n / d), m / (m / d));
ans = (ans + (last - d + 1) * (d + last) / 2 % mod * F(n / d, m / d) % mod) %
36
37
          mod;
38
          }
          ans = (ans + mod) \% mod;
39
          cout<<ans<<endl;</pre>
40
          return 0;
41
42
    }
```

5 Geometry

5.1 Commonly Definition and Functions

5.1.1 Const and Functions

```
namespace CG{
1
        #define Point Vector
2
3
        const double pi=acos(-1.0);
        const double inf=1e100;
4
5
        const double eps=1e-9;
        template <typename T> inline T Abs(T x){return x>0?x:-x;}
6
        template <typename T> inline bool operator == (T x, T y){return Abs(x-y)<eps;}
7
8
        int sqn(double x){
9
            if (Abs(x)<eps) return 0;</pre>
            if (x>0) return 1;
10
            else return -1;
11
12
        }
13
   }
```

5.1.2 Point Definition

```
1
   namespace CG{
2
        struct Point{
3
            double x,y;
4
           Point(double x=0, double y=0):x(x),y(y){}
5
6
        Vector operator + (const Vector a,const Vector b){return Vector(a.x+b.x,a.y+b.y);}
       Vector operator - (const Vector a,const Vector b){return Vector(a.x-b.x,a.y-b.y);}
7
       Vector operator * (const Vector a,const double k){return Vector(a.x*k,a.y*k);}
8
       Vector operator / (const Vector a,const double k){return Vector(a.x/k,a.y/k);}
9
10
       bool operator < (const Vector a,const Vector b) {return a.x==b.x?a.y<b.y:a.x<b.x;}</pre>
11
       bool operator == (const Vector a,const Vector b) {return a.x==b.x && a.y==b.y;}
12
        double Dot(const Vector a,const Vector b){return a.x*b.x+a.y*b.y;}
        double Cross(const Vector a,const Vector b){return a.x*b.y-a.y*b.x;}
13
14
        double Norm(const Vector a){return sqrt(Dot(a,a));}
       double Angle(const Vector a,const Vector b){return acos(Dot(a,b)/Norm(a)/Norm(b));}
15
       Vector Rotate(const Vector a, const double theta){return Vector(a.x*cos(theta)-a.y*
16
       sin(theta),a.x*sin(theta)+a.y*cos(theta));}
       bool ToLeftTest(const Vector a,const Vector b){return Cross(a,b)<0;}</pre>
17
18
       double DisPP(const Vector a, const Vector b) \{return \ sqrt((a.x-b.x)*(a.x-b.x)+(a.y-b.y)\}
       )*(a.y-b.y));}
19
   }
```

5.1.3 Line Definition

```
namespace CG{
1
2
         struct Line{
3
               Point p0, v, p1;
               double t, theta;
4
               Line(Point _p0=0, Point _v=0, _{double} _t=1):_p0(_p0),_v(_v),_t(_t)_{p1=p0+v*t}; theta=
5
         atan2(v.y,v.x);}
               // \ Line \left( Point \ \_p0 = 0, Point \ \_v = 0, double \ \_t = 1 \right) : p0 \left( \_p0 \right), p1 \left( \_v \right) \left\{ v = (p1 - p0) / t \ ; \ theta = 1 \right\} = 0
6
         atan2(v.y,v.x);
         };
7
         bool operator < (const Line n,const Line m) {return n.theta<m.theta;}</pre>
```

```
Point GetIntersection(const Line n,const Line m){return n.p0+n.v*Cross(m.v,(n.p0-m.
9
       p0))/Cross(n.v,m.v);}
       bool OnLine(const Vector a,const Line 1){return Cross(1.p0-a,1.p1-a)==0;}
10
11
       bool OnSegment(const Point a,const Line 1){return sgn(Cross(l.p0-a,l.p1-a))==0 &&
       sgn(Dot(l.p0-a,l.p1-a))<0;}
12
       double DisPL(const Point a,const Line 1){return Abs(Cross(1.p1-1.p0,a-1.p0)/Norm(1.
       p1-l.p0));}
        double DisPS(const Point a,const Line 1){
13
            if (l.p0==l.p1) return Norm(a-l.p0);
14
            Vector v1=l.p1-l.p0,v2=a-l.p0,v3=a-l.p1;
15
            if (sgn(Dot(v1,v2))<0) return Norm(v2);</pre>
16
            if (sgn(Dot(v1,v3))>0) return Norm(v3);
17
            return DisPL(a,1);
18
19
20
        Point GetProjection(const Point a, const Line 1){
            Vector v=l.p1-l.p0;
21
            return 1.p0+v*(Dot(v,a-1.p0)/Dot(v,v));
22
23
24
       bool SegmentIntersection(const Line n,const Line m,bool p){
25
            double c1=Cross(n.p1-n.p0,m.p1-m.p0);
            double c2=Cross(n.p1-n.p0,m.p1-n.p0);
26
            double c3=Cross(m.p1-m.p0,n.p0-m.p0);
27
            double c4=Cross(m.p1-m.p0,n.p1-m.p0);
28
            if (p){
29
                if (!sgn(c1) || !sgn(c2) || !sgn(c3) || !sgn(c4)){
30
31
                    return OnSegment(n.p0,m) || OnSegment(n.p1,m) || OnSegment(m.p0,n) ||
       OnSegment(m.p0,m);
32
33
                }
            }
34
            return (sgn(c1)*sgn(c2)<0 && sgn(c3)*sgn(c4)<0);</pre>
35
       }
36
   }
37
```

5.1.4 Get Area

```
namespace CG{
double GetArea(Point *p,int n){
    double area=Cross(p[n],p[1]);
    for (int i=2;i<=n;i++) area+=0.5*Cross(p[i-1],p[i]);
    return Abs(area);
}
</pre>
```

5.1.5 Get Circumference

5.2 Convex Hull

```
1
   namespace CG{
2
        Point p[MAXN],s[MAXN];
3
        int ConvexHull(Point *p,int n){
4
            sort(p+1,p+1+n);
            int m=0;
5
            for (int i=1;i<=n;i++){</pre>
6
7
                 for (;m>=2 && !ToLeftTest(s[m]-s[m-1],p[i]-s[m-1]);m--);
8
                 s[++m]=p[i];
9
            int k=m;
10
            for (int i=n-1;i;i--){
11
                 for (;m>=k+1 && !ToLeftTest(s[m]-s[m-1],p[i]-s[m-1]);m--);
12
                 s[++m]=p[i];
13
14
            }
15
            return m-1;
16
        }
17
   }
```

5.3 Half Plane Intersection

```
namespace CG{
1
2
        void HalfPlaneIntersection(Line 1[],int n){
3
            deque <Point> p;
            sort(l+1,l+1+n);
4
5
            deque <Line> q;
            q.push_back(l[1]);
6
7
            for (int i=2;i<=n;i++){</pre>
                for (;!p.empty() && !ToLeftTest(p.back()-l[i].p0,l[i].v);q.pop_back(),p.
8
       pop_back());
9
                for (;!p.empty() && !ToLeftTest(p.front()-l[i].p0,l[i].v);q.pop_front(),p.
       pop_front());
                if (sgn(Cross(l[i].v,q.back().v))==0)
10
                    if (ToLeftTest(l[i].p0-q.back().p0),q.back().v){
11
12
                        q.pop_back();
13
                        if (!p.empty()) p.pop_back();
14
                if (!q.empty()) p.push_back(GetIntersection(q.back(),l[i]));
15
                q.push_back(l[i]);
16
17
            for (;!p.empty() && !ToLeftTest(p.back()-q.front().p0,q.front().v);q.pop_back(),
18
       p.pop_back());
            p.push_back(GetIntersection(q.back(),q.front()));
19
            double area=0.5*Cross(p.back(),p.front()); Point last=p.front();
20
            for (p.pop_front();!p.empty();last=p.front(),p.pop_front()) area+=0.5*Cross(last
21
       ,p.front());
            printf("%.1f", Abs(area));
22
23
24
   }
```

5.4 Min Circle Cover

```
namespace CG{
    Point GetCircleCenter(const Point a,const Point b,const Point c){
    Point p=(a+b)/2.0,q=(a+c)/2.0;
    Vector v=Rotate(b-a,pi/2.0),w=Rotate(c-a,pi/2.0);
    if (sgn(Norm(Cross(v,w)))==0){
        if (sgn(Norm(a-b)+Norm(b-c)-Norm(a-c))==0) return (a+c)/2;
        if (sgn(Norm(b-a)+Norm(a-c)-Norm(b-c))==0) return (b+c)/2;
}
```

```
if (sgn(Norm(a-c)+Norm(c-b)-Norm(a-b))==0) return (a+c)/2;
8
9
            }
10
            return GetIntersection(Line(p,v),Line(q,w));
11
        void MinCircleCover(Point p[],int n){
12
             random_shuffle(p+1,p+1+n);
13
            Point c=p[1];
14
            double r=0;
15
             for (int i=2;i<=n;i++)</pre>
16
                 if (sgn(Norm(c-p[i])-r)>0){
17
                      c=p[i], r=0;
18
                      for (int j=1;j<i;j++)</pre>
19
20
                          if (sgn(Norm(c-p[j])-r)>0){
                              c=(p[i]+p[j])/2.0;
21
                              r=Norm(c-p[i]);
22
                              for (int k=1;k<j;k++)</pre>
23
                                   if (sgn(Norm(c-p[k])-r)>0){
24
25
                                       c=GetCircleCenter(p[i],p[j],p[k]);
26
                                       r=Norm(c-p[i]);
                                   }
27
                          }
28
29
            printf("%.10f\n%.10f %.10f",r,c.x,c.y);
30
31
        }
32
    }
```

5.5 Circle Union Area

```
//k次覆盖
1
   //圆并去重后s[0]
3 typedef pair<double, int> P;
4 const double pi = acos(-1.0);
5 const int MAXN = 10003;
6 P arc[MAXN << 1];</pre>
7
   int acnt, cnt;
8
   double s[1003];
   bool del[1003];
9
   void add(double st, double en) {
10
        if(st < -pi) {
   add(st + 2 * pi, pi);</pre>
11
12
13
            add(-pi, en);
            return;
14
15
        if(en > pi) {
16
            add(st, pi);
17
            add(-pi, en - 2 * pi);
18
19
            return;
20
        arc[++acnt] = P(st, 1);
21
22
        arc[++acnt] = P(en, -1);
23
   double F(double x) {
24
25
        return (x - \sin(x)) / 2;
26
   }
27
   struct Node {
        int x, y, r;
28
        Node(int _x = 0, int _y = 0, int _r = 0):x(_x), y(_y), r(_r) {}
29
        bool operator == (const Node& t) {
30
            return x == t.x & y == t.y & r == t.r;
31
```

```
32
        inline void read() {
33
34
            scanf("%d%d%d", &x, &y, &r);
35
   }a[1003];
36
37
    int main() {
        int n;
scanf("%d", &n);
38
39
        for(int i = 1; i <= n; i++) a[i].read();</pre>
40
41
        //去重
42
        int nn = 0;
43
        for(int \ i = 1; \ i <= n; \ i++) 
44
            bool\ same = 0;
45
46
            for(int \ j = 1; \ j < i; \ j++) \ \{
                 if(a[i] == a[j]) {
47
                     same = 1; break;
48
49
50
51
            if(!same) \ a/++nn/ = a/i/;
52
53
        n = nn;
        //去包含
54
        for(int \ i = 1; \ i \ll n; \ i++)
55
            for(int j = 1; j \le n; j++) if(i != j) 
56
57
                 if(hypot(a[i].x - a[j].x, a[i].y - a[j].y) < (double)(a[i].r - a[j].r)) \ del[i]
        j = 1;
58
59
60
        nn = 0;
61
        for(int \ i = 1; \ i \le n; \ i++) \ if(!del[i]) 
62
            a/++nn/ = a/i/;
63
64
        n = nn;
65
        for(int i = 1; i <= n; i++) {
66
67
            acnt = 0;
            for(int j = 1; j <= n; j++) if(i != j) {
68
                 int dis = (a[i].x - a[j].x) * (a[i].x - a[j].x) + (a[i].y - a[j].y) * (a[i].
69
       y - a[j].y);
70
                 if(a[j].r > a[i].r & dis <= (a[j].r - a[i].r) * (a[j].r - a[i].r)) add(-pi,
        pi);
                 else if(dis > (a[i].r - a[j].r) * (a[i].r - a[j].r) && dis < (a[i].r + a[j].
71
        r) * (a[i].r + a[j].r)){
72
                     double c = sqrt(dis);
                     double angle = a\cos((a[i].r * a[i].r + c * c - a[j].r * a[j].r) / (2 * a
73
        [i].r * c));
74
                     double k = atan2(a[j].y - a[i].y, a[j].x - a[i].x);
                     add(k - angle, k + angle);
75
76
77
            arc[++acnt] = P(pi, -1);
78
            sort(arc + 1, arc + acnt + 1);
79
            cnt = 0;
80
            double last = -pi;
81
            for(int j = 1; j <= acnt; j++) {</pre>
82
                 s[cnt] += F(arc[j].first - last) * a[i].r * a[i].r; //扇形 - 三角形
83
                 double xa = a[i].x + a[i].r * cos(last);
84
                 double ya = a[i].y + a[i].r * sin(last);
85
86
                last = arc[j].first;
                 double xb = a[i].x + a[i].r * cos(last);
87
```

```
double yb = a[i].y + a[i].r * sin(last);
88
                  s[cnt] += (xa * yb - xb * ya) / 2; //到圆心的三角形面积
89
90
                  cnt += arc[j].second;
91
             }
92
        }
         //printf("\%.3f | n", s[0]);
93
         for (int i = 0; i < n; i++) {
    printf("[%d] = %.3f\n", i + 1, s[i] - s[i + 1]);</pre>
94
95
96
97
         return 0;
    }
98
```

5.6 Simpson Integrate

```
double Simpson(double l,double r){
1
2
       return (r-1)*(F(1)+4*F((1+r)/2)+F(r))/6;
3
4
   double Integrate(double l,double r,double S){
       double mid=(l+r)/2;
5
6
       double A=Simpson(l,mid);
       double B=Simpson(mid,r);
7
8
       if(A+B-S<eps)return S;</pre>
       return Integrate(l,mid,A)+Integrate(mid,r,B);
9
   }
10
```

6 Others

6.1 Sample

6.1.1 vimrc

```
1 set nocompatible
2 source $VIMRUNTIME/vimrc_example.vim
3 source $VIMRUNTIME/mswin.vim
4 nunmap <c-v>
5 set cindent
6 set number
7 set mouse=a
8 set tabstop=4
9 set shiftwidth=4
10 set cursorline
set guifont=Consolas:h12
12 inoremap kj <esc>
13 inoremap jk <esc>
   inoremap { {}<left>
14
15
   syntax enable
16
   func! Compile()
17
        exec "w"
        exec "! g++ % -o %< -Wall -Wextra -Wshadow -Wconversion --std=c++14 -02"
18
        exec "! ./%<"
19
   endfunc
20
   func! Debug()
21
        exec "w"
22
        exec "! g++ % -o %< -g -Wall --std=c++14 && gdb %<"
23
24
   endfunc
   func! AddTitle()
25
        call append(0,"// Cease to struggle and you cease to live")
26
        call append(1,"#include <bits/stdc++.h>")
call append(2,"using namespace std;")
call append(3,"")
call append(4,"int main() {")
27
28
29
30
        call append(5,"
                              ios::sync_with_stdio(0); cin.tie(0); cout.precision(6); cout <<</pre>
31
        fixed;")
        call append(6,"")
call append(7,"
32
33
                              return 0;")
        call append(8,"}")
34
    endfunc
35
36 map <F9> :call Compile()<CR>
37 map <F5> :call Debug()<CR>
38 map <F8> :call AddTitle()<CR>
```

6.1.2 FastIO

```
namespace IO {
1
        const int MB = 1048576;
2
3
        const int RMAX = 16 * MB;
       const int WMAX = 16 * MB;
4
5
       #define getchar() *(rp++)
6
       #define putchar(x) (*(wp++) = (x))
7
        char rb[RMAX], *rp = rb, wb[WMAX], *wp = wb;
8
        inline void init() {
9
            fread(rb, sizeof(char), RMAX, stdin);
10
```

```
template <class _T> inline void read(_T &_a) {
11
             _a = 0; register bool _f = 0; register int _c = getchar(); while (_c < '0' \mid | _c > '9') _f \mid = _c == '-', _c = getchar();
12
13
             while (_c >= '0' \&\& _c <= '9') _a = _a * 10 + (_c ^ '0'), _c = getchar();
14
15
             _a = _f ? -_a : _a;
16
         template <class _T> inline void write(_T _a) {
17
             static char buf[20], *top = buf;
18
19
             if (_a) {
20
                  while (_a) {
                       register _T tm = _a / 10;
21
                       *(++top) = char(_a - tm * 10) | '0';
22
23
                       _a = tm;
24
25
                  while (top != buf) putchar(*(top--));
26
27
             else putchar('0');
28
29
         void output() {
             fwrite(wb, sizeof(char), wp - wb, stdout);
30
31
32
   }
```

6.1.3 Java BigNum

```
import java.math.*;
1
2
   import java.util.*;
    public class Main{
3
        public static void main(String []args){
4
5
            Scanner in = new Scanner(System.in);
            while(in.hasNext()){} //EOF
6
7
            BigInteger zero = BigInteger.valueOf(0);
            BigInteger a = in.nextBigInteger();
8
            BigInteger b = in.nextBigInteger();
9
            BigInteger c = in.nextBigInteger();
10
            int d = in.nextInt();
11
            a.add(b);
12
            a.subtract(b);
13
            a.multiply(b);
14
            a.divide(b);
15
            a.mod(b);
16
17
            a.compareTo(b);
18
            a.negate();
            a.modInverse(b); //a^{\hat{}}(-1)
19
20
            a.modPow(b,c); //a^b\%c
21
            a.pow(d);
22
        }
23
   }
```

6.2 Offline Algorithm

6.2.1 CDQ Divide and Conquer

```
struct Node {
   int x, y, z, ans;
   Node() {}
   Node(int _x, int _y, int _z):x(_x), y(_y), z(_z) {}
   bool operator < (const Node &b) const {</pre>
```

```
if(y == b.y) {
6
7
                 8
                 return z < b.z;</pre>
9
10
            return y < b.y;</pre>
11
    }A[MAXN], B[MAXN], C[MAXN];
12
    int bit[MAXN];
13
    void add(int k, int v) {
14
        for(; k <= m; k += k & -k) bit[k] = max(bit[k], v);</pre>
15
16
    void clear(int k) {
17
        for(; k <= m; k += k & -k) bit[k] = 0;</pre>
18
19
   }
20
   int sum(int k) {
21
        int res = 0;
        for(; k; k \rightarrow k - k) res = max(res, bit[k]);
22
23
        return res;
24
   }
   void solve(int l, int r) {
25
26
        if(l == r) {
            B[l] = A[l];
27
28
            return;
29
        int mid = (l + r) \gg 1;
30
31
        solve(l, mid);
32
        for(int i = mid + 1; i <= r; i++) B[i] = A[i];</pre>
33
        //sort(B + l, B + mid + 1);
        sort(B + mid + 1, B + r + 1);
34
35
        int L = 1;
        for(int R = mid + 1; R <= r; R++) {</pre>
36
            while(L \leftarrow mid && B[L].y \leftarrow B[R].y) add(B[L].z, B[L].ans), L++;
37
            A[B[R].x].ans = max(A[B[R].x].ans, sum(B[R].z - 1) + 1);
38
            B[R].ans = A[B[R].x].ans;
39
40
        for(int i = l; i <= L; i++) clear(B[i].z);</pre>
41
42
        solve(mid + 1, r);
        L = 1;
43
        int p = 1, q = mid + 1;
44
45
        while(p \le mid \mid | q \le r) {
46
            if(q > r | | (p \le mid \&\& B[p].y \le B[q].y)) C[L++] = B[p++];
47
            else C[L++] = B[q++];
48
49
        for(int i = 1; i <= r; i++) B[i] = C[i];
50
```

6.2.2 Mo's Algorithm

```
struct Node{
1
2
        int l, r, t, id;
        bool operator < (const Node& a) const {</pre>
3
4
             if(l /sz == a.l / sz) {
                 if(r == a.r) return t < a.t;</pre>
5
6
                 return r < a.r;</pre>
             }
7
             return l / sz < a.l / sz;</pre>
8
9
   }q[MAXN];
10
   void solve() {
11
        while (t < q[i].t) addTime(t++, 1);
```

```
13     while (t > q[i].t) addTime(--t, -1);
14     while(L < q[i].l) add(L++, -1);
15     while(L > q[i].l) add(--L, 1);
16     while(R < q[i].r) add(++R, 1);
17     while(R > q[i].r) add(R--, -1);
18 }
```

6.2.3 Mo's Algorithm On Tree

```
struct Edge {
1
2
        int to, nxt;
   }e[MAXN << 1];
3
   int head[MAXN], ecnt;
   int stack[MAXN], top, belong[MAXN], cnt, sz;
   struct Node {
7
        int l, r, id, ti;
        bool operator < (const Node &x) const {</pre>
8
            return belong[1] < belong[x.1] || (belong[1] == belong[x.1] && belong[r] <</pre>
9
        belong[x.r]) || (belong[l] == belong[x.l] && belong[r] == belong[x.r] && ti < x.ti);
10
   }q[MAXN];
11
12
   struct Node2 {
13
        int l, r, ti;
   }qq[MAXN];
14
   int n, m, Q, Q0, Q1;
int V[MAXN], W[MAXN], C[MAXN];
15
16
   int fa[MAXN][S + 3], dep[MAXN];
17
    long long ans[MAXN], tans;
18
   int vis[MAXN], cur[MAXN];
19
20
   long long sum[MAXN];
   int l, r, tm;
21
   inline int read() {
22
        int x = 0; char ch = getchar(); bool fg = 0;
while(ch < '0' || ch > '9') { if(ch == '-') fg = 1; ch = getchar(); }
23
24
        while(ch >= 0, && ch <= 9) { x = x * 10 + ch - 0; ch = getchar(); }
25
        return fg ? -x : x;
26
27
   inline void add_edge(int u, int v) {
        e[++ecnt] = (Edge) \{v, head[u]\}; head[u] = ecnt;
29
        e[++ecnt] = (Edge) \{u, head[v]\}; head[v] = ecnt;
30
31
   void dfs(int u, int f) {
32
        fa[u][0] = f;
33
        dep[u] = dep[f] + 1;
34
35
        int bot = top;
36
        for(int i = head[u]; i; i = e[i].nxt) {
            int v = e[i].to;
37
38
            if(v == f) continue;
            dfs(v, u);
39
            if(top - bot >= sz) {
40
41
                 cnt++;
                 while(top != bot) belong[stack[top--]] = cnt;
42
            }
43
44
        stack[++top] = u;
45
46
   void G(int &u, int step) {
47
        for(int i = 0; i < S; i++) if((1 << i) & step) u = fa[u][i];</pre>
48
49
   int lca(int u, int v) {
```

```
if(dep[u] > dep[v]) swap(u, v);
51
52
         G(v, dep[v] - dep[u]);
53
         if(u == v) return u;
         for(int i = S; i >= 0; i--) if(fa[u][i] != fa[v][i]) {
54
55
             u = fa[u][i]; v = fa[v][i];
56
57
         return fa[u][0];
58
    inline void modify(int u) {
59
         tans -= V[C[u]] * sum[cur[C[u]]];
60
         cur[C[u]] += vis[u];
61
         vis[u] = -vis[u];
tans += V[C[u]] * sum[cur[C[u]]];
62
63
64
65
    inline void update(int u, int v) {
         if(u == v) return;
66
         if(dep[u] > dep[v]) swap(u, v);
67
         while(dep[v] > dep[u]) {
68
69
             modify(v);
70
             v = fa[v][0];
71
         while(u != v) {
72
             modify(u); modify(v);
73
             u = fa[u][0]; v = fa[v][0];
74
75
76
    inline void upd(int t) {
77
78
         if(vis[qq[t].l] == -1) {
79
             modify(qq[t].l);
80
             swap(C[qq[t].1], qq[t].r);
             modify(qq[t].l);
81
82
         else swap(C[qq[t].l], qq[t].r);
83
84
    inline void moveto(int u, int v) {
85
         update(l, u); update(r, v);
86
87
         l = u; r = v;
    }
88
    int main() {
89
90
         n = read(); m = read(); Q = read();
91
         sz = (int)pow(n, 2.0 / 3.0);
         for(int i = 1; i <= m; i++) V[i] = read();</pre>
92
         for(int i = 1; i <= n; i++) W[i] = read();</pre>
93
         for(int i = 1, u, v; i < n; i++) {
94
             u = read(); v = read();
95
             add_edge(u, v);
96
97
         for(int i = 1; i <= n; i++) {
98
             C[i] = read();
99
             vis[i] = 1;
100
             sum[i] = sum[i - 1] + W[i];
101
102
         for(int i = 1, tp; i <= Q; i++) {
103
             tp = read();
104
             if(tp) {
105
                  ++01;
106
                 q[Q1].l = read(); q[Q1].r = read();
107
                 q[Q1].id = Q1;
108
                 q[Q1].ti = i;
109
             }
110
111
             else {
```

```
112
                  ++Q0;
                  qq[Q0].l = read(); qq[Q0].r = read();
113
114
                  qq[Q0].ti = i;
115
              }
116
         dfs(1, 0);
117
         while(top) belong[stack[top--]] = cnt;
118
119
         sort(q + 1, q + Q1 + 1);
         for(int k = 1; k <= S; k++) {
   for(int i = 1; i <= n; i++) {</pre>
120
121
                  fa[i][k] = fa[fa[i][k - 1]][k - 1];
122
123
124
         for(int i = 1; i <= Q1; i++) {
125
              if(belong[q[i].l] > belong[q[i].r]) swap(q[i].l, q[i].r);
126
127
              moveto(q[i].1, q[i].r);
              int lc = lca(l, r);
128
129
              modify(lc);
              while(qq[tm + 1].ti < q[i].ti && tm < Q0) upd(++tm);</pre>
130
131
              while(qq[tm].ti > q[i].ti) upd(tm--);
132
              ans[q[i].id] = tans;
              modify(lc);
133
134
         for(int i = 1; i <= Q1; i++) printf("%lld\n", ans[i]);</pre>
135
         return 0;
136
137
    }
```

6.3 Randomized Algorithm

6.3.1 Simulated Annealing

```
1
   void solve() {
2
       while(T > eps) {
           double alpha = ((rand() % 30001) / 15000.0) * pi;
3
           double theta = ((rand() % 10001) / 10000.0) * pi;
4
           tmp.x = cur.x + T * sin(theta) * cos(alpha);
5
           tmp.y = cur.y + T * sin(theta) * sin(alpha);
6
           tmp.z = cur.z + T * cos(theta);
7
           tmp.dis = cal(tmp);
8
           if(tmp.dis < cur.dis || (tmp.dis * 0.999 < cur.dis && (rand() & 7) == 7)) cur =
9
       tmp;
10
           //if(exp((cur.d - tmp.d) / T) > ((double)rand() / RAND_MAX)) cur = tmp;
11
           T *= 0.999;
12
       }
13
   }
14
```

6.4 Other Method

6.4.1 Enumerate Subset

```
for(int i = 0; i < (1 << k); i++) {
  for(int j = i; ; --j &= i) {
      // work();
      if(j == 0) break;
    }
}</pre>
```

6.4.2 Enumerate $\lfloor \frac{n}{d} \rfloor \lfloor \frac{m}{d} \rfloor$

```
int cal(int n, int m) {
   if(n > m) swap(n, m);
   int res = 0, last;

for(int i = 1; i <= n; i = last + 1) {
      last = min(n / (n / i), m / (m / i));
      res += (n / i) * (m / i) * (sum(last) - sum(i - 1));
}
return res;
}</pre>
```

6.5 Formula

6.5.1 Euler's theorem

$$a^{x} \equiv \begin{cases} a^{b\%\phi(p)} & \gcd(a,p) = 1 \\ a^{b} & \gcd(a,p) \neq 1, b < \phi(p) \\ a^{b\%\phi(p) + \phi(p)} & \gcd(a,p) \neq 1, b \geq \phi(p) \end{cases}$$
 $(mod \ p)$

6.5.2 Dirichlet Convolution

$$(f \times g)(N) = \sum_{d|N} f(d) * g(\frac{N}{d})$$

$$\sum_{d|N} \phi(d) * \frac{N}{d} = \phi \times id$$

$$n = \sum_{d|n} \phi(d)$$

$$e(n) = \sum_{d|n} \mu(d)$$

$$id = \phi \times 1$$

$$e = \mu \times 1$$

6.5.3 Möbius Inversion Formula

$$id = \phi \times 1$$

$$\phi = id \times \mu$$

$$f = g \times 1$$

$$g = \mu \times f$$