

2455 Hilgard Ave.
Berkeley, CA 94709

Chris Powers

chris.powers@berkeley.edu
+1(510) 944-9857
<https://github.com/ChrisP19>
www.linkedin.com/in/chris-powers

EDUCATION

Aug. 2015-May 2019

University of California, Berkeley

EECS undergraduate (GPA: 3.848)

Courses:

Data Structures	Operating Systems
Algorithms	Machine Structures
Machine Learning	Designing Information Devices & Systems
Artificial Intelligence	Linear Algebra and Differential Equations
Discrete Math and Probability Theory	Microelectronic Devices and Circuits

RESEARCH

June 2016-Present

UC Berkeley Automation Lab under Professor Ken Goldberg

Designed algorithms for ABB YuMi robot:

- Built a computer vision library using OpenCV and Python, including implementing image segmentation algorithms
- Synthetically augmented image datasets to teach robot to pick up silverware and tie a rope

Used machine learning for Toyota HSR robot:

- Tested neural net architectures in Tensorflow and analyzed experiment statistics on Tesla K40 GPU
- Taught robot to clear a path to target object in shelf, using kinetic pose estimation network adapted to Python

Created a real time web GUI:

- Used Javascript/HTML/CSS to design web interface for labeling images taken by the robot in real time
- Enabled communication between server and robot, and integrated with Amazon crowd-sourcing platform

Publications:

- Laskey, M.; **Powers, C.**; Goldberg, K. "High Dimensional representations for Learning Grasping in Clutter Policies from Demonstrations." RSS Conference. 2017

EXPERIENCE

EE16B Course Staff:

Feb 2017-Present

- Graded and improved content for Designing Information Devices & Systems course

ULAB Mentoring:

Spring 2017

- Volunteered for ULAB, a program that increases diversity in STEM research
- Mentored Berkeley freshman on their research to design an automated weed-killing robot

EECS Honor Society Officer:

May 2017-Present

- Facilitated class that introduces freshman and transfer students to a wide variety of EECS topics

PROJECTS

Parallel computing: Used OpenMP in C to parallelize an image compression program for 5x speedup

Robotics: Built, wired, and programmed mobile robot that responds to voice commands

Software: Created web-based geographic mapping application in Java

Artificial Intelligence: Created player vs. player Pacman A.I. that placed first in class contest

SKILLS

Programming: Python, Java, C, Javascript, Unix scripting, Robot C, SQL

Software: Tensorflow, OpenCV, HTML/CSS, Flask, NumPy, OpenMP

Interests: Japanese language, gaming, chess, mobile apps