

# CHRIS POWERS

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## Education

<b>M.S. Electrical Engineering and Computer Science</b> University of California, Berkeley	AUG 2019 - MAY 2020 GPA: 4.00
<b>B.S. Electrical Engineering and Computer Science</b> University of California, Berkeley   <i>High Honors, EECS Honor Society</i>	AUG 2015 - MAY 2019 GPA: 3.91

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## Experience

<b>COBALT ROBOTICS   MACHINE LEARNING ENGINEER</b>	MAR 2021 - CURRENT
<ul style="list-style-type: none"><li>Designed and optimized a tracking system for filtering duplicates, reducing human operator work by 25%.</li><li>Automated detection of security risks, such as open doors, using unsupervised learning and edge detection.</li><li>Built an image labeling and statistical aggregation pipeline that enables fast, data-driven improvements.</li></ul>	
<b>STEALTH STARTUP   MACHINE LEARNING SYSTEMS LEAD</b>	JAN 2020 - JAN 2021
<ul style="list-style-type: none"><li>Designed microservice architecture for our end-to-end learning pipeline, including model training and deployment. Used MongoDB, Amazon S3, and Redis for storage, and GRPC and HTTP for communication.</li><li>Created a real-time analytics dashboard for users to monitor their ML model using React/Redux.</li></ul>	
<b>YELP   SOFTWARE ENGINEERING INTERN</b>	MAY 2018 - AUG 2018
<ul style="list-style-type: none"><li>Improved the experience of thousands of advertising Yelp business users by streamlining frontend flows.</li></ul>	

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## Research

<b>BERKELEY DEEP DRIVE   RESEARCH ASSISTANT</b>	SEP 2018 - MAY 2020
<ul style="list-style-type: none"><li>Led four undergraduates to revamp open source image annotation tool Scalabel, adding real time collaboration between users and interactive model-assisted labeling with PolygonRNN++.</li></ul>	
<b>UC BERKELEY AUTOMATION LAB   RESEARCH ASSISTANT</b>	JUN 2016 - MAY 2018
<ul style="list-style-type: none"><li>Developed robotic decluttering algorithm, first segmenting objects in a pile then using PCA to identify the optimal push trajectory. Came in 1st in TRI hackathon and 2nd in the Siemens FutureMakers Challenge.</li></ul>	

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## Projects

<b>SNOWSIM   C++</b>	SPRING 2020
<ul style="list-style-type: none"><li>Implemented a realistic and performant snow simulation and visualization using the material point method</li></ul>	
<b>REINFORCEMENT LEARNING FOR DISTRIBUTED SCHEDULING   NumPy, SciPy</b>	FALL 2019
<ul style="list-style-type: none"><li>Used parameter estimation on real world server logs to create a realistic distribution of incoming jobs.</li><li>Combined policy gradient and actor critic with a DAgger baseline to beat the Shortest Job First heuristic.</li></ul>	
<b>DEEP ANIME COLORIZATION   Tensorflow, Keras</b>	SPRING 2019
<ul style="list-style-type: none"><li>Trained Pix2Pix conditional GAN (cGAN) to colorize grayscale images in a manner consistent with their original show, then applied transfer learning to colorize images in the style of different shows.</li></ul>	
<b>PIANO PLAYING ROBOT   OpenCV, ROS</b>	FALL 2018
<ul style="list-style-type: none"><li>Used computer vision algorithms to compute 3D poses of piano keys from a 2D camera image of the piano.</li></ul>	

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## Skills

**Languages:** Python, Typescript, C, C++, Java, Golang, Unix scripting, HTML/CSS

**Tools:** Tensorflow, Keras, PyTorch, OpenCV, React, Redux, Node.js, Django, MongoDB, GRPC, Redis, AWS, Docker

**Selected Coursework:** Deep RL, Deep NN, ML, AI, Adv. Probability, Optimization, Algorithms, Robotics, Analysis