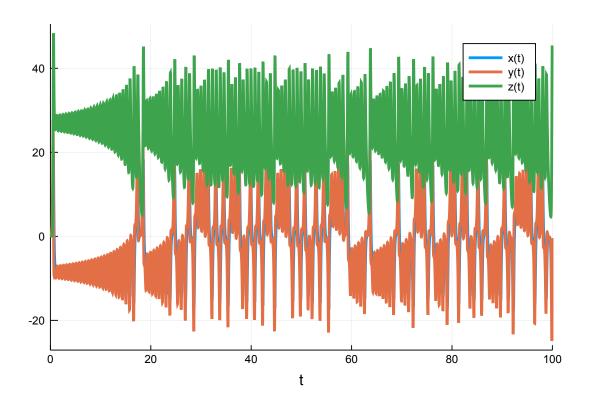
DiffEqSolutions

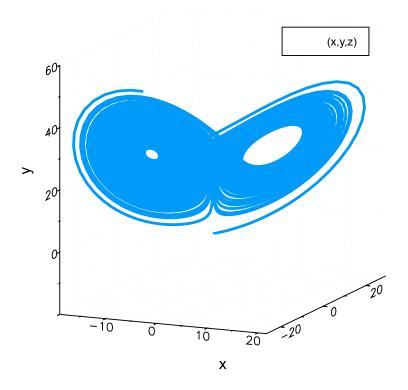
September 11, 2018

1 DiffEq Solutions

1.1 Solution to the Lorenz Problem



In [3]: plot(sol,vars=(:x,:y,:z))
Out[3]:



1.2 Solution to the Ball Bounce Problem

```
In [5]: f = function (du,u,p,t)
          du[1] = u[2]
          du[2] = -9.81
        end
        condtion = function (u,t,integrator) # Event when event_f(t,u,k) == 0
          u[1]
        end
        affect! = nothing
        affect_neg! = function (integrator)
          integrator.u[2] = -0.8integrator.u[2]
        end
        callback = ContinuousCallback(condtion,affect!,affect_neg!,interp_points=100)
        u0 = [50.0, 0.0]
        tspan = (0.0, 15.0)
        prob = ODEProblem(f,u0,tspan)
        sol = solve(prob,Tsit5(),callback=callback,adaptive=false,dt=1/4)
        plot(sol)
   Out[5]:
```

