

DiffEqSolutions

November 12, 2018

1 DiffEq Solutions

1.1 Solution to the Lorenz Problem

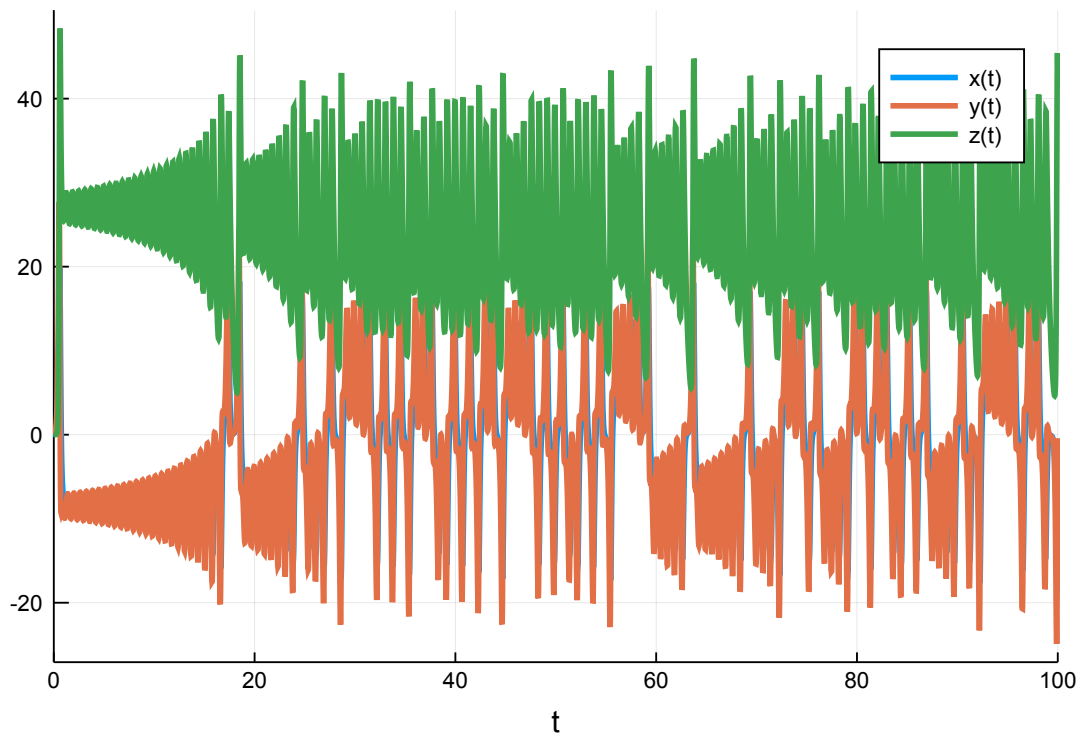
```
In [1]: using DifferentialEquations
```

```
f = @ode_def_nohes LorenzExample begin
    dx = *(y-x)
    dy = x*(-z) - y
    dz = x*y - *z
end

u0 = big.([0.1;0.0;0.0])
tspan = (big(0.0),big(100.0))
prob = ODEProblem(f,u0,tspan,(10.0,28.0,2.6666))
sol = solve(prob);
```

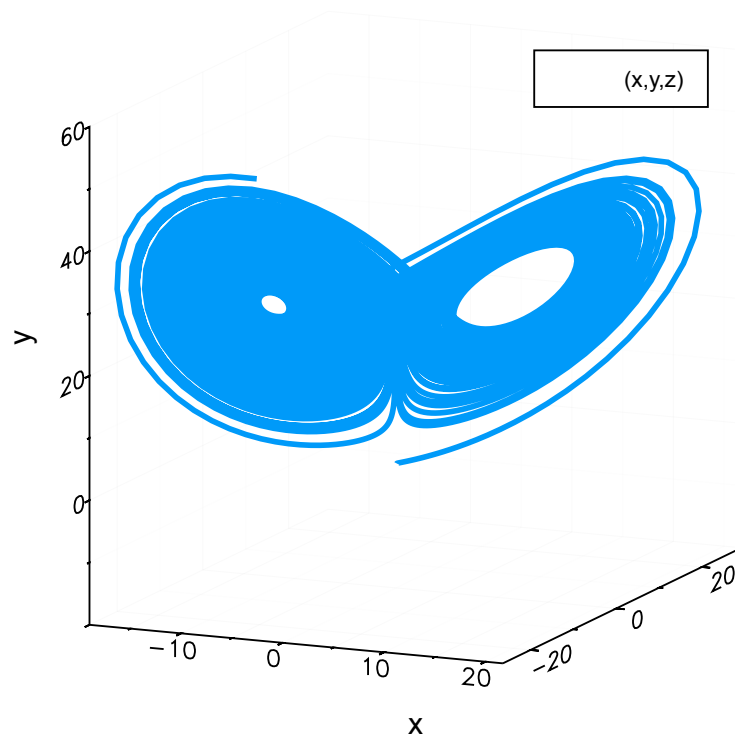
```
In [2]: using Plots; gr(); plot(sol)
```

Out[2]:



In [3]: `plot(sol,vars=(:x,:y,:z))`

Out [3]:



1.2 Solution to the Ball Bounce Problem

```
In [5]: f = function (du,u,p,t)
        du[1] = u[2]
        du[2] = -9.81
    end

    condtion = function (u,t,integrator) # Event when event_f(t,u,k) == 0
        u[1]
    end

    affect! = nothing
    affect_neg! = function (integrator)
        integrator.u[2] = -0.8integrator.u[2]
    end

    callback = ContinuousCallback(condtion,affect!,affect_neg!,interp_points=100)

    u0 = [50.0,0.0]
    tspan = (0.0,15.0)
    prob = ODEProblem(f,u0,tspan)

    sol = solve(prob,Tsit5(),callback=callback,adaptive=false,dt=1/4)
    plot(sol)
```

Out [5] :

