

# Chris Sha

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## EDUCATION

**Columbia University, Fu Foundation School of Engineering and Applied Science** New York, NY

- Bachelor of Science in Applied Mathematics, GPA: 4.0
- Minors: Computer Science, Philosophy
- Expected Graduation: May 2026
- Relevant Coursework: Machine Learning, Robot Learning, Deep Learning for Robotics, Modern Analysis, Parallel Optimization, Probability Theory, Linear Algebra

## RESEARCH EXPERIENCE

**Undergraduate Research Assistant** New York, NY

Robotic Perception, Interaction, and Learning Lab, *Columbia University* Sep. 2024 – Present

- Advisor: Yunzhu Li, Assistant Professor of Computer Science, Columbia University.
- Designed a teleoperation interface that integrates a residual RL policy to enhance data quality and improve teleoperation performance for both precision and dynamic rigid-body tasks.
- Aiming for submission to the Conference of Robot Learning (CoRL) 2025.

**Summer Intern** Beijing, China

Multimodal Interaction Research Center, *Beijing Academy of Artificial Intelligence* Jun. 2024 – Sep. 2024

- Advisor: Zongqing Lu, Associate Professor of Computer Science, Peking University.
- Developed an autonomous vision-based locomotion policy for Unitree H1 Humanoid robot, guided by a Video-Language Model (VLM) to perform parkour tasks.
- Enabled the VLM to select task-specific low-level policies (e.g., leaping, squat-walking, and hurdling) based on language instructions and visual inputs.
- Aiming for submission to the International Conference on Machine Learning (ICML) 2025.

**Undergraduate Research Assistant** New York, NY

The Accessible and Accelerated Robotics Lab, *Columbia University* Sep. 2023 – Dec. 2024

- Advisor: Brian Plancher, Assistant Professor of Computer Science, Barnard College.
- Implemented an online parameter estimation algorithm leveraging the Kaczmarz method to effectively address the overdeterminedness of online system identification problems.
- Aiming for submission to International Conference on Intelligent Robots and Systems (IROS) 2025.

**Summer Intern** Beijing, China

State Key Laboratory of Intelligent Control and Decision of Complex Systems, *Beijing Institute of Technology*

Jun. 2023 – Sep. 2023

- Developed algorithms for registration, segmentation, and sample consensus of industrial parts point clouds using the Open3D library in Python.
- Collaborated with two lab members to enhance point cloud registration accuracy for objects with distinguishable geometric features, utilizing differential geometry methods for feature extraction.

**High School Research Program** Beijing, China

*Beijing International Studies University, Department of Mathematics* Jun. 2022 – Mar. 2023

- Advisor: Hua Zhu, Associate Professor of Mathematics, Beijing International Studies University.
- Analyzed the well-posedness of time-harmonic 2D Maxwell's equations that model the Transverse Magnetic Problem using variational formulation and constructed an internal approximation using the finite element method.

## PUBLICATIONS

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**"Analysis of 2D Maxwell's equations in a time-harmonic regime", Journal of Mathematics Research,**  
Canadian Center of Science and Education Apr. 2023

- Publication Details: Vol. 15, No. 2, April 2023 Issue (ISSN: 1916-9809).
- DOI: [10.5539/jmr.v15n2p1](https://doi.org/10.5539/jmr.v15n2p1).

## ACADEMIC HONORS

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**Semi-finalist, S.-T Yau High School Science Award** Jan. 2023

- Received the Regional Second Prize, a recognition of the top 8 teams in the Mainland China region, in a global science competition sponsored by Harvard mathematics professor Shing-Tung Yau that includes more than 5800 teams from over 1200 schools.

## LEADERSHIP & OUTREACH

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**Student Advisor** Irvine, CA

Math Community Education Outreach Program, UC Irvine Nov. 2022 – May 2023

- Taught pre-calculus to students at Carr Intermediate School, designing engaging problems to inspire interest in mathematics.
- Attended weekly coaching sessions to develop effective teaching strategies for middle school students.

## SKILLS

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**Programming:** Python, C++, MATLAB, CUDA, JAVA

**Frameworks:** PyTorch, Isaac Lab, OpenCV

**Robots & Hardware:** Unitree H1/G1/GO2, XArm, Franka Panda