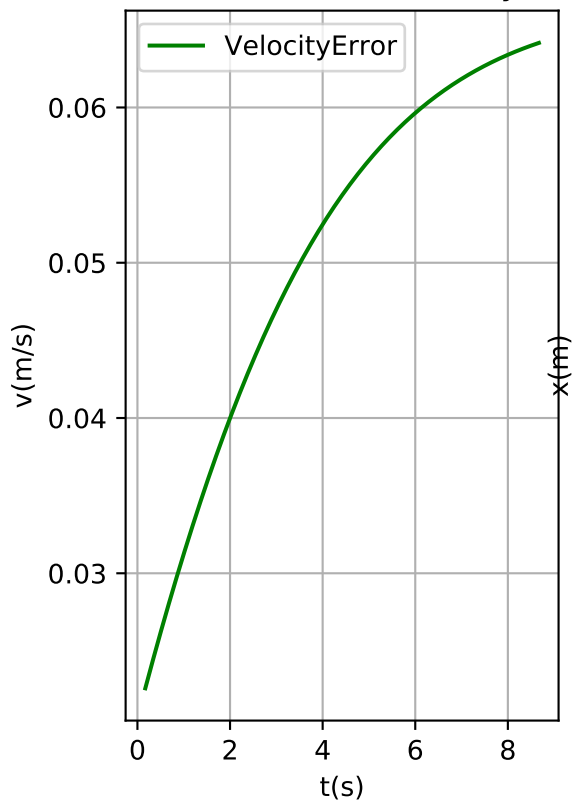


Percent Error (Velocity)



Percent Error (Position)

