

# On the nested $p$ -center problem



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  - the maximum distance of any location to its closest opened location is minimized.

Ales and Elloumi (2018), Contardo, Iori, and Kramer (2019), Gaar and Sinnl (2022), and Hakimi (1964)

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Introduced by Roodman and Schwarz (1975) and used in e.g., Albareda-Sambola et al. (2009), Bakker and Nickel (2024), and Conforti et al. (2014) and reintroduced as nesting by McGarvey and Thorsen (2022)

# $p$ -center problem vs nested $p$ -center problem

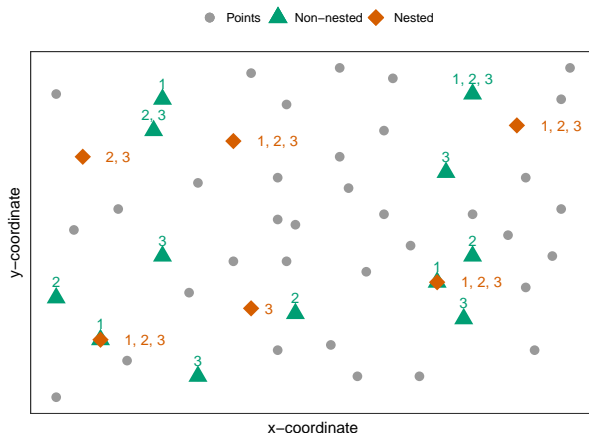


Figure: Optimal solution of ( $p$ CP) with  $p = 4, 5, 6$  and ( $n$ - $p$ CP) with  $\mathcal{P} = \{4, 5, 6\}$

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  - for which  $V^h \subseteq V^{h+1}$  for  $h = 1, \dots, H-1$  holds
- the goal is to find a feasible solution which minimizes  $\sum_{h=1}^H d(V^h)$ ,
  - where  $d(V^h) = \max_{i \in V} \min_{j \in V^h} d_{ij}$  for  $h \in \mathcal{H}$
- objective function can be seen as sum of absolute regrets of nestedness over time periods

# Mixed Integer Linear Programming (MILP) formulations





# Formulation (nPC2)

## Decision variables

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## (nPC2) based on Gaar and Sinnl (2022)

$$\min \sum_{h \in \mathcal{H}} z^h \quad (1a)$$

$$\text{s.t.} \quad \sum_{j \in V} y_j^h = p^h \quad \forall h \in \mathcal{H} \quad (1b)$$

$$z^h \geq d_{ij} - \sum_{j' : d_{ij'} < d_{ij}} (d_{ij} - d_{ij'}) y_{j'}^h \quad \forall i, j \in V, h \in \mathcal{H} \quad (1c)$$

$$y_j^h \geq y_j^{h-1} \quad \forall j \in V, \forall h \in \mathcal{H} \setminus \{1\} \quad (1d)$$

$$(y, z) \in \mathbb{B}^{|V||\mathcal{H}|} \times \mathbb{R}_{\geq 0}^{|\mathcal{H}|} \quad (1e)$$

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## (nPC3) based on Ales and Elloumi (2018)

$$\begin{aligned} \min \quad & \sum_{h \in \mathcal{H}} z^h \\ \text{s.t.} \quad & \sum_{j \in V} y_j^h = p^h \quad \forall h \in \mathcal{H} \\ & D_0 + \sum_{k=1}^K (D_k - D_{k-1}) u_k^h \leq z^h \quad \forall h \in \mathcal{H} \\ & u_k^h + \sum_{j: d_{ij} < D_k} y_j^h \geq 1 \quad \forall i \in V, \forall h \in \mathcal{H}, \forall k \in S_i \cup \{K\} \\ & u_k^h \geq u_{k+1}^h \quad \forall h \in \mathcal{H}, \forall k \in \mathcal{K} \setminus \{K\} \\ & y_j^h \geq y_j^{h-1} \quad \forall h \in \mathcal{H} \setminus \{1\} \\ & (u, y, z) \in \mathbb{B}^{|\mathcal{K}| \cdot |\mathcal{H}|} \times \mathbb{B}^{|\mathcal{V}| \cdot |\mathcal{H}|} \times \mathbb{R}_{\geq 0}^{|\mathcal{H}|} \end{aligned}$$

# Improving the formulations





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## *Lemma 1*

*Let  $\underline{z}^h$  be a lower bound on the decision variable  $z_h$  of (nPC2) for a given  $h$  then for every  $i \in \mathcal{I}, j \in \mathcal{J}$  constraints*

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$$z^h \geq \max\{\underline{z}^h, d_{ij}\} - \sum_{j': d_{ij'} < d_{ij}} \left( \max\{\underline{z}^h, d_{ij}\} - \max\{\underline{z}^h, d_{ij'}\} \right) y_{j'}^h \quad (\text{nL-OPT})$$

The lemma is based on Lemma 5 in Gaar and Sinnl (2022) for the (pCP).

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## Observation 1

Let  $\underline{z}^h$  be a valid lower bound and  $\overline{z}^h$  be a valid upper bound on the decision variable  $z^h$  for  $h \in \mathcal{H}$ , then the distinct distance  $D_k$  can only be the optimal distance for  $z^h$  if  $\underline{z}^h \leq D^k \leq \overline{z}^h$  holds.

## Observation 2

Following Observation 1, we observe that decision variables  $u_h^k = 0$  for  $k : D_k > \overline{z}^h$  and  $u_h^k = 1$  for  $k : D_k < \underline{z}^h$  in any optimal solution.

$\implies$  these variables can be removed

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## Observation 3

*For  $\mathcal{H} = \{1\}$  the  $(n\text{-}p\text{CP})$  reduces to the  $(p\text{CP})$  where  $p = p^1$ , so the optimal objective value  $(z'^{h*})$  of the  $(p\text{CP})$ , where  $p = p^h$  is a lower bound  $\underline{z}^h$  on the decision variable  $z^h$  of the  $(n\text{-}p\text{CP})$ .*



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## Proposition 1

Given an valid upper bound  $UB$  on the objective value of the  $(n-pCP)$  and valid lower bounds  $\underline{z}^h$  on the variable  $z^h$  can be obtained by the following equation:

$$\overline{z}^h = \frac{UB - \sum_{h'=h+1}^H \underline{z}^{h'}}{h} \quad (3)$$

# Computational results



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- instance set **PMED** Beasley (1985)
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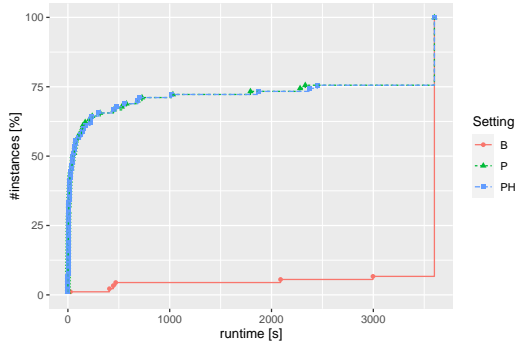
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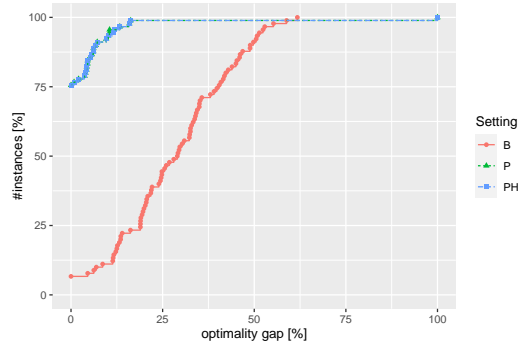
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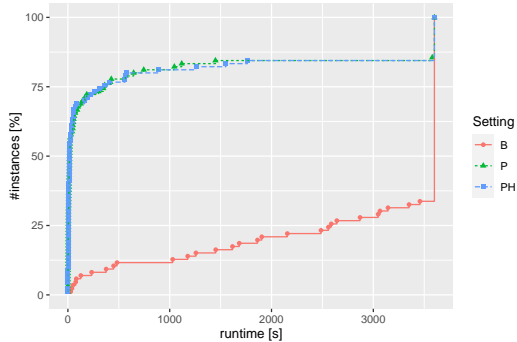


(a) Runtimes

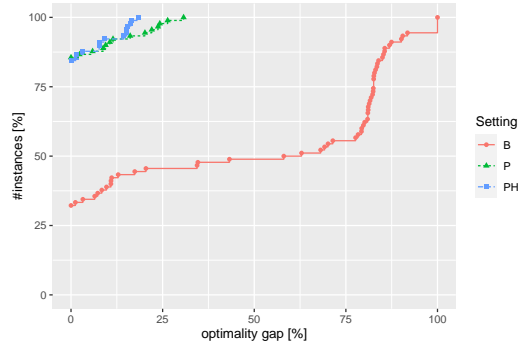


(b) Optimality gaps  $\left[ \frac{UB-LB}{UB} 100 \right]$

# Setting comparison on formulation (nPC3)

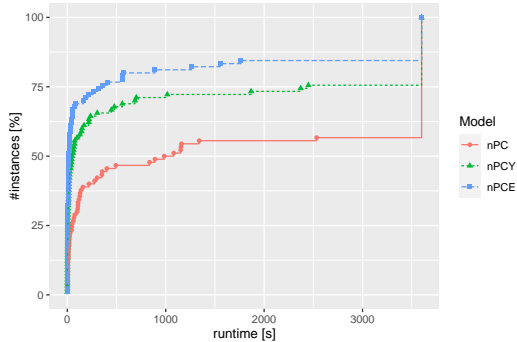


(c) Runtimes

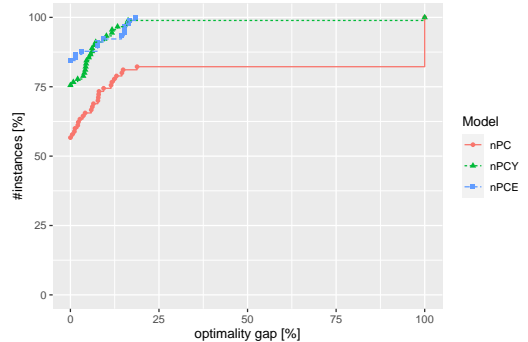


(d) Optimality gaps  $\left[ \frac{UB-LB}{UB} 100 \right]$

# Formulation comparison on setting PH



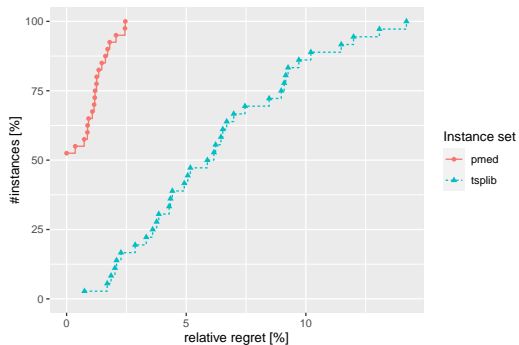
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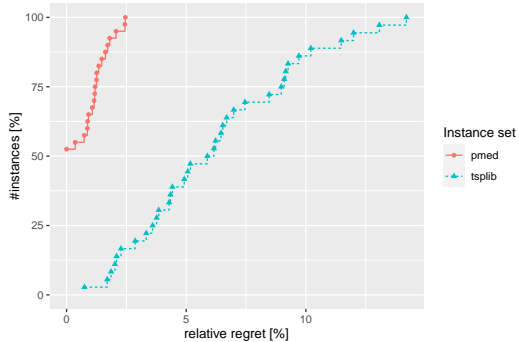


# Managerial insights

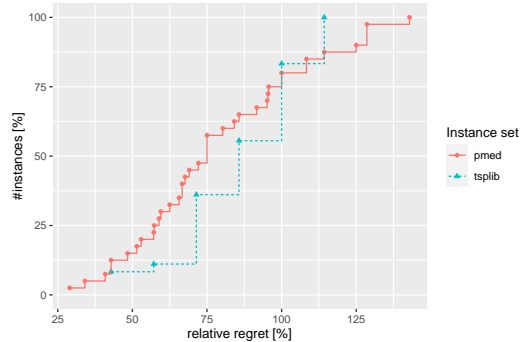


(g) Relative regrets of the optimal solution value

# Managerial insights



(i) Relative regrets of the optimal solution value



(j) Relative regrets of # of opened facilities

# Conclusion

- introduced nested  $p$ -center problem
- three mixed integer formulations
- improvement of formulations
- preprocessing brings a large speed up on all formulations
- starting heuristic little effect, shows good upper bound obtained in preprocessing
- nested facility location with uncertainty interesting for future work
- or nested maximum coverage problem

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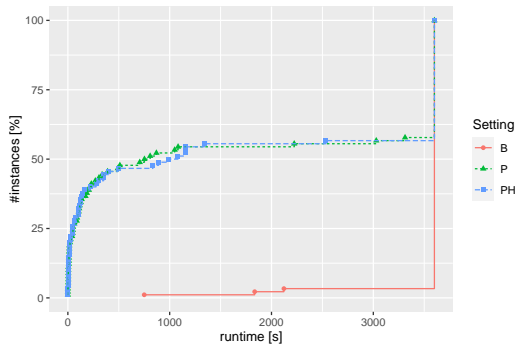
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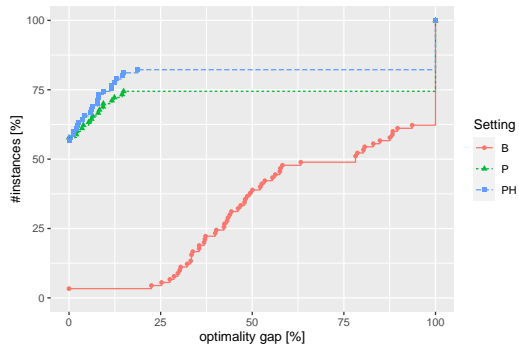
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# Setting comparison on formulation (nPC1)



(k) Runtimes



(l) Optimality gaps [ $\frac{UB-LB}{UB}$ ]



# Formulation (nPC1)

## Decision variables

$$x_{ij}^h \dots \begin{cases} 1 \dots \text{if location } i \text{ is assigned to} \\ \quad \text{location } j \text{ in time period } h \\ 0 \dots \text{otherwise} \end{cases}$$

# Formulation (nPC1)

## Decision variables

$$x_{ij}^h \dots \begin{cases} 1 \dots \text{if location } i \text{ is assigned to} \\ \quad \text{location } j \text{ in time period } h \\ 0 \dots \text{otherwise} \end{cases}$$

$$y_j^h \dots \begin{cases} 1 \dots \text{if location } j \text{ is open in} \\ \quad \text{time period } h \\ 0 \dots \text{otherwise} \end{cases}$$

# Formulation (nPC1)

## Decision variables

$$x_{ij}^h \dots \begin{cases} 1 \dots \text{if location } i \text{ is assigned to} \\ \quad \text{location } j \text{ in time period } h \\ 0 \dots \text{otherwise} \end{cases}$$

$$y_j^h \dots \begin{cases} 1 \dots \text{if location } j \text{ is open in} \\ \quad \text{time period } h \\ 0 \dots \text{otherwise} \end{cases}$$

$$z^h \dots \text{maximum distance between any} \\ \text{customer } i \text{ and its nearest open facility} \\ \text{in period } h$$

# Formulation (nPC1)

## Decision variables

$$x_{ij}^h \dots \begin{cases} 1 \dots \text{if location } i \text{ is assigned to} \\ \text{location } j \text{ in time period } h \\ 0 \dots \text{otherwise} \end{cases}$$

$$y_j^h \dots \begin{cases} 1 \dots \text{if location } j \text{ is open in} \\ \text{time period } h \\ 0 \dots \text{otherwise} \end{cases}$$

$$z^h \dots \text{maximum distance between any} \\ \text{customer } i \text{ and its nearest open facility} \\ \text{in period } h$$

## (nPC1) based on Daskin (2013)

$$\min \sum_{h \in \mathcal{H}} z^h \quad (4a)$$

$$\text{s.t. } \sum_{j \in V} y_j^h = p^h \quad \forall h \in \mathcal{H} \quad (4b)$$

$$\sum_{j \in V} x_{ij}^h = 1 \quad \forall i \in V, h \in \mathcal{H} \quad (4c)$$

$$x_{ij}^h \leq y_j^h \quad \forall i, j \in V, h \in \mathcal{H} \quad (4d)$$

$$\sum_{j \in V} d_{ij} x_{ij}^h \leq z^h \quad \forall i \in V, h \in \mathcal{H} \quad (4e)$$

$$y_j^h \geq y_j^{h-1} \quad \forall h \in \mathcal{H} \setminus \{1\} \quad (4f)$$

$$(x, y, z) \in |V|^2 |\mathcal{H}| \times |V| |\mathcal{H}| \times \mathbb{R}_{\geq 0} \quad (4g)$$