```
In [1]:  import torch
    from torch import nn
    from d2l import torch as d2l
    import time
    from ptflops import get_model_complexity_info
```

## **Problem 1**

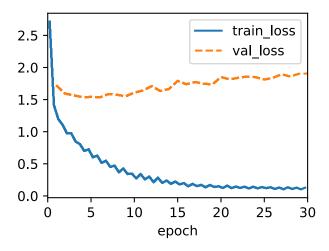
### Part A)

```
In [4]:
         """The RNN decoder for sequence to sequence learning."""
               def init (self, vocab size, embed size, num hiddens, num layers,
                            dropout=0):
                   super().__init__()
                   self.embedding = nn.Embedding(vocab_size, embed_size)
                   self.rnn = d21.GRU(embed size+num hiddens, num hiddens,
                                      num layers, dropout)
                   self.dense = nn.LazyLinear(vocab size)
                   self.apply(init_seq2seq)
               def init_state(self, enc_all_outputs, *args):
                   return enc_all_outputs
               def forward(self, X, state):
                   # X shape: (batch_size, num_steps)
                   # embs shape: (num steps, batch size, embed size)
                   embs = self.embedding(X.t().type(torch.int32))
                   enc output, hidden state = state
                   # context shape: (batch size, num hiddens)
                   context = enc output[-1]
                   # Broadcast context to (num_steps, batch_size, num_hiddens)
                   context = context.repeat(embs.shape[0], 1, 1)
                   # Concat at the feature dimension
                   embs and context = torch.cat((embs, context), -1)
                   outputs, hidden state = self.rnn(embs and context, hidden state)
                   outputs = self.dense(outputs).swapaxes(0, 1)
                   # outputs shape: (batch size, num steps, vocab size)
                   # hidden state shape: (num layers, batch size, num hiddens)
                   return outputs, [enc output, hidden state]
```

```
In [5]:
         ▶ def train encdec(embed size=256, num hiddens=256, num layers=2, dropout=0.2
                engs = ['go .', 'i lost .', 'he\'s calm .', 'i\'m home .']
                fras = ['va !', 'j\'ai perdu .', 'il est calme .', 'je suis chez moi .
                toc = time.perf counter()
                encoder = d21.Seq2SeqEncoder(
                    len(data.src_vocab), embed_size, num_hiddens, num_layers, dropout)
                decoder = Seq2SeqDecoder(
                    len(data.tgt vocab), embed size, num hiddens, num layers, dropout)
                model = d21.Seq2Seq(encoder, decoder, tgt pad=data.tgt vocab['<pad>'],
                trainer = d21.Trainer(max_epochs=30, gradient_clip_val=1, num_gpus=1)
                trainer.fit(model, data)
                tic = time.perf_counter()
                total time = round(tic-toc, 5)
                print(f"Total Training Time : {total_time} s\nEstimated Average Training
                preds, = model.predict step(
                data.build(engs, fras), d21.try_gpu(), data.num_steps)
                for en, fr, p in zip(engs, fras, preds):
                    translation = []
                    for token in data.tgt_vocab.to_tokens(p):
                        if token == '<eos>':
                            break
                        translation.append(token)
                    print(f'{en} => {translation}, bleu,'
                          f'{d21.bleu(" ".join(translation), fr, k=2):.3f}')
                return model
In [6]:
            layers = [1, 2, 3]
            embedding = [128, 256]
            hiddens = [128, 256]
In [7]:
         ▶ encdec_1 = train_encdec(embedding[0], hiddens[0], layers[0])
            Total Training Time : 27.05219 s
            Estimated Average Training Time per Epoch: 0.90174 s
            go . => ['va', '!'], bleu,1.000
            i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
            he's calm . => ['venez', '<unk>', '.'], bleu,0.000
            i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000
             2.5
                                          train loss
                                          val loss
             2.0
             1.5
             1.0
             0.5
             0.0 -
                       5
                            10
                                  15
                                       20
                                             25
                                                   30
                 0
                                epoch
```

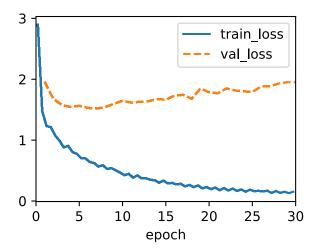
```
In [8]: ▶ encdec_2 = train_encdec(embedding[0], hiddens[0], layers[1])
```

```
Total Training Time : 36.54909 s
Estimated Average Training Time per Epoch : 1.2183 s
go . => ['va', '!'], bleu,1.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['je', 'suis', 'calme', '.'], bleu,0.537
i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000
```



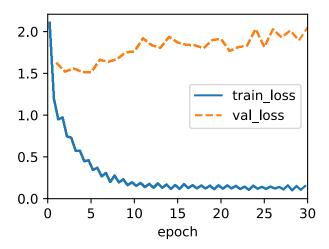
In [9]: encdec\_3 = train\_encdec(embedding[0], hiddens[0], layers[2])

Total Training Time : 46.49739 s
Estimated Average Training Time per Epoch : 1.54991 s
go . => ['va', '!'], bleu,1.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['il', 'court', '.'], bleu,0.000
i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000



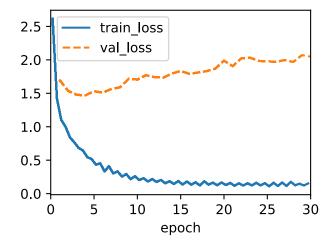
In [10]: ▶ encdec\_4 = train\_encdec(embedding[0], hiddens[1], layers[0])

```
Total Training Time: 42.04985 s
Estimated Average Training Time per Epoch: 1.40166 s
go . => ['va', '!'], bleu,1.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['il', 'court', '.'], bleu,0.000
i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000
```



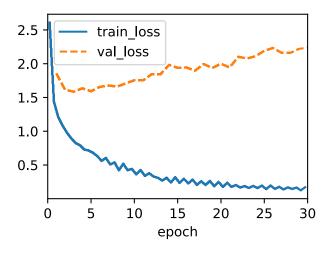
In [11]: ▶ encdec\_5 = train\_encdec(embedding[0], hiddens[1], layers[1])

Total Training Time: 57.73638 s
Estimated Average Training Time per Epoch: 1.92455 s
go . => ['va', '!'], bleu,1.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['il', 'est', 'mouillé', '.'], bleu,0.658
i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000



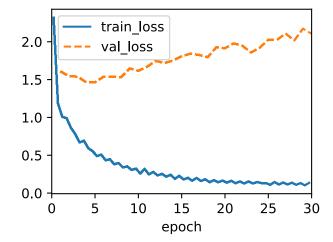
In [12]: ▶ encdec\_6 = train\_encdec(embedding[0], hiddens[1], layers[2])

```
Total Training Time: 78.44506 s
Estimated Average Training Time per Epoch: 2.61484 s
go . => ['va', '!'], bleu,1.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['il', 'est', 'mouillé', '.'], bleu,0.658
i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000
```



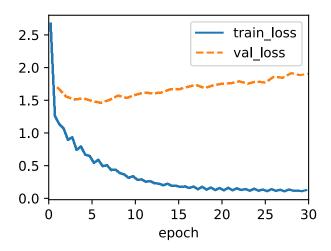
In [13]: ▶ encdec\_7 = train\_encdec(embedding[1], hiddens[0], layers[0])

Total Training Time : 32.12674 s
Estimated Average Training Time per Epoch : 1.07089 s
go . => ['va', '!'], bleu,1.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['il', 'est', 'mouillé', '.'], bleu,0.658
i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000

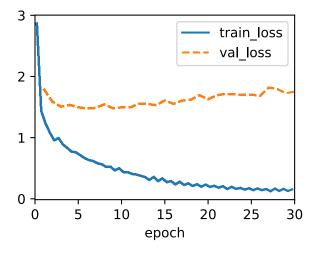


In [14]: ▶ encdec\_8 = train\_encdec(embedding[1], hiddens[0], layers[1])

```
Total Training Time : 39.11131 s
Estimated Average Training Time per Epoch : 1.30371 s
go . => ['va', '!'], bleu,1.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['il', 'est', 'mouillé', '.'], bleu,0.658
i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000
```

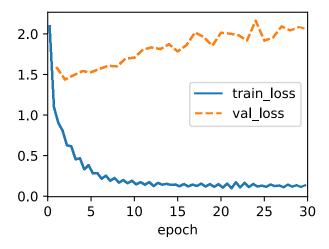


Total Training Time: 50.53455 s
Estimated Average Training Time per Epoch: 1.68449 s
go . => ['va', '!'], bleu,1.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['elle', 'est', '<unk>', '.'], bleu,0.000
i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000

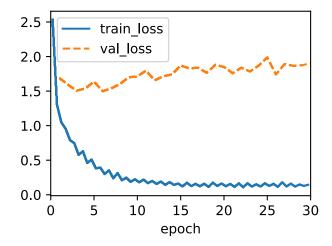


```
In [16]: ▶ encdec_10 = train_encdec(embedding[1], hiddens[1], layers[0])
```

```
Total Training Time : 54.37041 s
Estimated Average Training Time per Epoch : 1.81235 s
go . => ['va', '!'], bleu,1.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['<unk>', '.'], bleu,0.000
i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000
```



Total Training Time : 55.52804 s
Estimated Average Training Time per Epoch : 1.85093 s
go . => ['va', '!'], bleu,1.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['je', 'sais', '.'], bleu,0.000
i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000



```
In [18]:
         Total Training Time: 78.93496 s
           Estimated Average Training Time per Epoch : 2.63117 s
           go . => ['va', '!'], bleu,1.000
           i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
           he's calm . => ['je', "l'ai", '.'], bleu,0.000
           i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000
            2.5
                     train loss
                      val loss
            2.0
            1.5
            1.0
            0.5
            0.0
                    5
                              15
                                        25
                         10
                                   20
               0
                                             30
```

epoch

#### Part B)

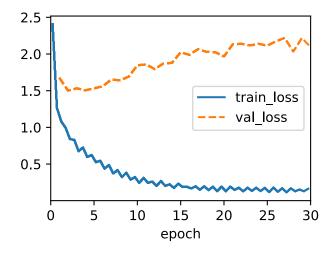
```
In [19]:
             class Seq2SeqEncoder 2(d21.Encoder):
                 """The RNN encoder for sequence to sequence learning.
                 Defined in :numref: `sec seq2seq`"""
                 def __init__(self, vocab_size, embed_size, num_hiddens, num_layers,
                              dropout=0):
                     super(). init ()
                     self.embedding = nn.Embedding(vocab size, embed size)
                     self.rnn = d21.GRU(embed_size, num_hiddens, num_layers, dropout)
                     self.apply(init seq2seq)
                 def forward(self, X, *args):
                     # X shape: (batch size, num steps)
                     embs = self.embedding(d21.astype(d21.transpose(X), d21.int64))
                     # embs shape: (num_steps, batch_size, embed_size)
                     outputs, state = self.rnn(embs)
                     # outputs shape: (num steps, batch size, num hiddens)
                     # state shape: (num_layers, batch_size, num_hiddens)
                     return outputs, state[-2:][:][:]
```

```
In [80]:

    toc = time.perf counter()

             encoder = Seq2SeqEncoder 2(len(data.src vocab), 256, 256, 3, 0.2)
             decoder = Seq2SeqDecoder(len(data.tgt vocab), 256, 256, 2, 0.2)
             model = d21.Seq2Seq(encoder, decoder, tgt pad=data.tgt vocab['<pad>'], lr=0
             trainer = d21.Trainer(max epochs=30, gradient clip val=1, num gpus=1)
             trainer.fit(model, data)
             tic = time.perf_counter()
             total time = round(tic-toc, 5)
             print(f"Total Training Time : {total_time} s\nEstimated Average Training Ti
             preds, _ = model.predict_step(
             data.build(engs, fras), d21.try gpu(), data.num steps)
             for en, fr, p in zip(engs, fras, preds):
                 translation = []
                 for token in data.tgt vocab.to tokens(p):
                     if token == '<eos>':
                         break
                     translation.append(token)
                 print(f'{en} => {translation}, bleu,'
                       f'{d21.bleu(" ".join(translation), fr, k=2):.3f}')
```

```
Total Training Time: 68.38796 s
Estimated Average Training Time per Epoch: 2.2796 s
go . => ['va', '!'], bleu,1.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['il', 'court', '.'], bleu,0.000
i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000
```



### Part C)

```
In [22]:
         """The RNN encoder for sequence to sequence learning.
                Defined in :numref: `sec seq2seq`"""
                def __init__(self, vocab_size, embed_size, num_hiddens, num_layers,
                            dropout=0):
                    super(). init ()
                    self.embedding = nn.Embedding(vocab size, embed size)
                    self.rnn = LSTM(embed size, num hiddens, num layers, dropout)
                    self.apply(init seq2seq)
                def forward(self, X, *args):
                    # X shape: (batch size, num steps)
                    embs = self.embedding(d21.astype(d21.transpose(X), d21.int64))
                    # embs shape: (num steps, batch size, embed size)
                    outputs, state = self.rnn(embs)
                    # outputs shape: (num steps, batch size, num hiddens)
                    # state shape: (num_layers, batch_size, num_hiddens)
                    return outputs, state
```

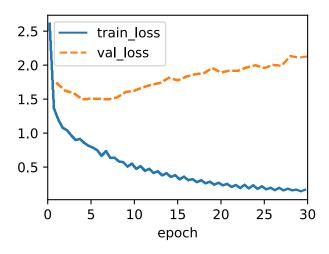
```
class Seq2SeqDecoder LSTM(d21.Decoder):
In [23]:
                 """The RNN decoder for sequence to sequence learning."""
                 def init (self, vocab size, embed size, num hiddens, num layers,
                              dropout=0):
                     super().__init__()
                     self.embedding = nn.Embedding(vocab size, embed size)
                     self.rnn = LSTM(embed size+num hiddens, num hiddens,
                                        num layers, dropout)
                     self.dense = nn.LazyLinear(vocab size)
                     self.apply(init seq2seq)
                 def init state(self, enc all outputs, *args):
                     return enc all outputs
                 def forward(self, X, state):
                     # X shape: (batch size, num steps)
                     # embs shape: (num_steps, batch_size, embed_size)
                     embs = self.embedding(X.t().type(torch.int32))
                     enc output, hidden state = state
                     # context shape: (batch size, num hiddens)
                     context = enc_output[-1]
                     # Broadcast context to (num steps, batch size, num hiddens)
                     context = context.repeat(embs.shape[0], 1, 1)
                     # Concat at the feature dimension
                     embs and context = torch.cat((embs, context), -1)
                     outputs, hidden state = self.rnn(embs and context, hidden state)
                     outputs = self.dense(outputs).swapaxes(0, 1)
                     # outputs shape: (batch size, num steps, vocab size)
                     # hidden state shape: (num layers, batch size, num hiddens)
                     return outputs, [enc output, hidden state]
```

```
In [81]:

    toc = time.perf counter()

             encoder = Seq2SeqEncoder_LSTM(len(data.src_vocab), 256, 256, 2, 0.2)
             decoder = Seq2SeqDecoder LSTM(len(data.tgt vocab), 256, 256, 2, 0.2)
             model = d21.Seq2Seq(encoder, decoder, tgt pad=data.tgt vocab['<pad>'], lr=0
             trainer = d21.Trainer(max_epochs=30, gradient_clip_val=1, num_gpus=1)
             trainer.fit(model, data)
             tic = time.perf counter()
             total time = round(tic-toc, 5)
             print(f"Total Training Time : {total_time} s\nEstimated Average Training Ti
             preds, _ = model.predict_step(
             data.build(engs, fras), d21.try_gpu(), data.num_steps)
             for en, fr, p in zip(engs, fras, preds):
                 translation = []
                 for token in data.tgt vocab.to tokens(p):
                     if token == '<eos>':
                         break
                     translation.append(token)
                 print(f'{en} => {translation}, bleu,'
                       f'{d21.bleu(" ".join(translation), fr, k=2):.3f}')
```

```
Total Training Time: 77.27733 s
Estimated Average Training Time per Epoch: 2.57591 s
go . => ['va', '!'], bleu,1.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['<unk>', 'ceci', '.'], bleu,0.000
i'm home . => ['je', 'suis', '<unk>', '.'], bleu,0.512
```



# **Problem 2**

### Part A)

```
▶ class EncoderDecoder(d21.Classifier):

In [39]:
                 """The base class for the encoder-decoder architecture.
                 Defined in :numref: `sec encoder-decoder`"""
                 def __init__(self, encoder, decoder):
                     super(). init ()
                     self.encoder = encoder
                     self.decoder = decoder
                 def forward(self, enc_X, dec_X, *args):
                     enc all outputs = self.encoder(enc X, *args)
                     dec state = self.decoder.init state(enc all outputs, *args)
                     # Return decoder output only
                     return self.decoder(dec X, dec state)[0]
                 def predict step(self, batch, device, num steps,
                                  save attention weights=False):
                     """Defined in :numref:`sec_seq2seq_training`"""
                     batch = [d21.to(a, device) for a in batch]
                     src, tgt, src_valid_len, _ = batch
                     enc_all_outputs = self.encoder(src, src_valid_len)
                     dec state = self.decoder.init state(enc all outputs, src valid len)
                     outputs, attention weights = [d2l.expand dims(tgt[:, 0], 1), ], []
                     for _ in range(num_steps):
                         Y, dec state = self.decoder(outputs[-1], dec state)
                         outputs.append(d21.argmax(Y, 2))
                         # Save attention weights (to be covered later)
                         if save attention weights:
                             attention weights.append(self.decoder.attention weights)
                     return d2l.concat(outputs[1:], 1), attention_weights
```

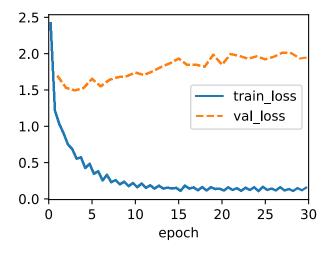
```
In [63]:
          def init (self, vocab size, embed size, num hiddens, num layers,
                             dropout=0):
                    super(). init ()
                    self.attention = d21.AdditiveAttention(num hiddens, dropout)
                    self.embedding = nn.Embedding(vocab size, embed size)
                    self.rnn = nn.GRU(
                         embed size + num hiddens, num hiddens, num layers,
                         dropout=dropout)
                    self.dense = nn.LazyLinear(vocab_size)
                    self.apply(d21.init seq2seq)
                def init state(self, enc outputs, enc valid lens):
                    # Shape of outputs: (num steps, batch size, num hiddens).
                    # Shape of hidden state: (num layers, batch size, num hiddens)
                    outputs, hidden state = enc outputs
                    return (outputs.permute(1, 0, 2), hidden state, enc valid lens)
                def forward(self, X, state):
                    # Shape of enc outputs: (batch size, num steps, num hiddens).
                    # Shape of hidden state: (num layers, batch size, num hiddens)
                    enc_outputs, hidden_state, enc_valid_lens = state
                    # Shape of the output X: (num steps, batch size, embed size)
                    X = self.embedding(X).permute(1, 0, 2)
                    outputs, self. attention weights = [], []
                    for x in X:
                        # Shape of query: (batch size, 1, num hiddens)
                        query = torch.unsqueeze(hidden state[-1], dim=1)
                        # Shape of context: (batch size, 1, num hiddens)
                        context = self.attention(
                            query, enc_outputs, enc_outputs, enc_valid_lens)
                        # Concatenate on the feature dimension
                        x = torch.cat((context, torch.unsqueeze(x, dim=1)), dim=-1)
                        # Reshape x as (1, batch size, embed size + num hiddens)
                        out, hidden_state = self.rnn(x.permute(1, 0, 2), hidden_state)
                        outputs.append(out)
                        self. attention weights.append(self.attention.attention weights
                    # After fully connected layer transformation, shape of outputs:
                    # (num steps, batch size, vocab size)
                    outputs = self.dense(torch.cat(outputs, dim=0))
                    return outputs.permute(1, 0, 2), [enc_outputs, hidden_state,
                                                      enc valid lens]
```

```
In [75]:
           def train enc attdec(embed size=256, num hiddens=256, num layers=2, dropout
                  engs = ['go .', 'i lost .', 'he\'s calm .', 'i\'m home .']
fras = ['va !', 'j\'ai perdu .', 'il est calme .', 'je suis chez moi .
                  toc = time.perf counter()
                  encoder = d21.Seq2SeqEncoder(
                      len(data.src_vocab), embed_size, num_hiddens, num_layers, dropout)
                  decoder = Seq2SeqAttentionDecoder(
                      len(data.tgt vocab), embed size, num hiddens, num layers, dropout)
                  model = d21.Seq2Seq(encoder, decoder, tgt pad=data.tgt vocab['<pad>'],
                  trainer = d21.Trainer(max_epochs=30, gradient_clip_val=1, num_gpus=1)
                  trainer.fit(model, data)
                  tic = time.perf_counter()
                  total time = round(tic-toc, 5)
                  print(f"Total Training Time : {total time} s\nEstimated Average Training
                  preds, _ = model.predict_step(
                  data.build(engs, fras), d21.try_gpu(), data.num_steps)
                  for en, fr, p in zip(engs, fras, preds):
                      translation = []
                      for token in data.tgt vocab.to tokens(p):
                          if token == '<eos>':
                              break
                          translation.append(token)
                      print(f'{en} => {translation}, bleu,'
                            f'{d21.bleu(" ".join(translation), fr, k=2):.3f}')
                    _, dec_attention_weights = model.predict_step(data.build([engs[-1]],
              #
                    attention_weights = torch.cat([step[0][0][0] for step in dec_attention_
                    attention weights = attention weights.reshape((1, 1, -1, data.num ste
              #
                    # Plus one to include the end-of-sequence token
                    d2L.show heatmaps(
                        attention_weights[:, :, :, :len(engs[-1].split()) + 1].cpu(),
                        xlabel='Key positions', ylabel='Query positions')
                  return model
```

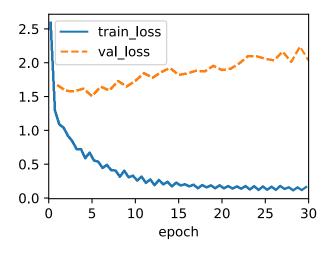
```
model2_1 = train_enc_attdec(num_layers=1)
In [85]:
             go . => ['va', '!'], bleu,1.000
             i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
             he's calm . => ['soyez', 'calme', '.'], bleu,0.492
             i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000
               2.0
               1.5
                                            train loss
               1.0
                                            val_loss
               0.5
                        5
                              10
                                   15
                                         20
                                               25
                                                     30
                                  epoch
```

### In [82]: M model2\_2 = train\_enc\_attdec(num\_layers=2)

Total Training Time: 85.56423 s
Estimated Average Training Time per Epoch: 2.85214 s
go . => ['va', '!'], bleu,1.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['soyez', 'calmes', '!'], bleu,0.000
i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000

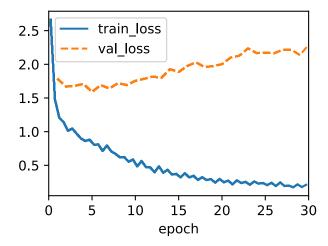


```
Total Training Time: 112.20182 s
Estimated Average Training Time per Epoch: 3.74006 s
go . => ['va', '!'], bleu,1.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['il', 'est', 'mouillé', '.'], bleu,0.658
i'm home . => ['je', 'suis', 'chez', 'moi', '.'], bleu,1.000
```



In [84]: M model2\_4 = train\_enc\_attdec(num\_layers=4)

Total Training Time: 128.83769 s
Estimated Average Training Time per Epoch: 4.29459 s
go . => ['pars', '!'], bleu,0.000
i lost . => ["j'ai", 'perdu', '.'], bleu,1.000
he's calm . => ['<unk>', '.'], bleu,0.000
i'm home . => ['je', 'suis', 'porte', 'bien', '.'], bleu,0.548



### Part B)

```
▶ class AdditiveAttention(nn.Module): #@save
In [31]:
                """Additive attention."""
                def __init__(self, num_hiddens, dropout, **kwargs):
                    super(AdditiveAttention, self).__init__(**kwargs)
                    self.W k = nn.LazyLinear(num hiddens, bias=False)
                    self.W q = nn.LazyLinear(num hiddens, bias=False)
                    self.w v = nn.LazyLinear(1, bias=False)
                    self.dropout = nn.Dropout(dropout)
                def forward(self, queries, keys, values, valid lens):
                    queries, keys = self.W q(queries), self.W k(keys)
                    # After dimension expansion, shape of queries: (batch size, no. of
                    # queries, 1, num hiddens) and shape of keys: (batch size, 1, no.
                    # key-value pairs, num hiddens). Sum them up with broadcasting
                    features = queries.unsqueeze(2) + keys.unsqueeze(1)
                    features = torch.tanh(features)
                    # There is only one output of self.w v, so we remove the last
                    # one-dimensional entry from the shape. Shape of scores: (batch siz
                    # no. of queries, no. of key-value pairs)
                    scores = self.w v(features).squeeze(-1)
                    self.attention weights = masked softmax(scores, valid lens)
                    # Shape of values: (batch size, no. of key-value pairs, value
                    # dimension)
                    return torch.bmm(self.dropout(self.attention weights), values)
          In [46]:
                """The RNN encoder for sequence to sequence learning."""
                def __init__(self, vocab_size, embed_size, num_hiddens, num_layers,
                             dropout=0):
                    super(). init ()
                    self.embedding = nn.Embedding(vocab size, embed size)
                    self.rnn = LSTM(embed_size, num_hiddens, num_layers, dropout)
                    self.apply(init seq2seq)
                def forward(self, X, *args):
                    # X shape: (batch size, num steps)
                    embs = self.embedding(X.t().type(torch.int64))
```

# embs shape: (num\_steps, batch\_size, embed\_size)

# outputs shape: (num\_steps, batch\_size, num\_hiddens)
# state shape: (num layers, batch size, num hiddens)

outputs, state = self.rnn(embs)

return outputs, state

```
In [62]:
          ▶ class Seq2SeqAttentionDecoder LSTM(d21.AttentionDecoder):
                 def __init__(self, vocab_size, embed_size, num hiddens, num layers,
                              dropout=0):
                     super(). init ()
                     self.attention = d21.AdditiveAttention(num hiddens, dropout)
                     self.embedding = nn.Embedding(vocab_size, embed_size)
                     self.rnn = nn.LSTM(embed size + num hiddens, num hiddens, num layer
                     self.dense = nn.LazyLinear(vocab size)
                     self.apply(d21.init seq2seq)
                 def init state(self, enc outputs, enc valid lens):
                     # Shape of outputs: (num_steps, batch_size, num_hiddens).
                     # Shape of hidden_state: (num_layers, batch_size, num_hiddens)
                     outputs, hidden state = enc outputs
                     return (outputs.permute(1, 0, 2), hidden state, enc valid lens)
                 def forward(self, X, state):
                     # Shape of enc_outputs: (batch_size, num_steps, num_hiddens).
                     # Shape of hidden_state: (num_layers, batch_size, num_hiddens)
                     enc outputs, hidden state = state
                     #enc_outputs, hidden_state, enc_valid_lens = state
                     # Shape of the output X: (num_steps, batch_size, embed_size)
                     X = self.embedding(X).permute(1, 0, 2)
                     outputs, self. attention weights = [], []
                     for x in X:
                         # Shape of query: (batch_size, 1, num_hiddens)
                         query = torch.unsqueeze(hidden state[-1].squeeze(0), dim=1)
                         # Shape of context: (batch_size, 1, num_hiddens)
                         context = self.attention(query, enc_outputs, enc_outputs, enc_v
                         # Concatenate on the feature dimension
                         x = torch.cat((context, torch.unsqueeze(x, dim=1)), dim=-1)
                         print(x)
                         # Reshape x as (1, batch_size, embed_size + num_hiddens)
                         out, hidden state = self.rnn(x.permute(1, 0, 2), hidden state)
                         outputs.append(out)
                         self. attention weights.append(self.attention.attention weights
                     # After fully connected layer transformation, shape of outputs:
                     # (num steps, batch size, vocab size)
                     outputs = self.dense(torch.cat(outputs, dim=0))
                     return outputs.permute(1, 0, 2), [enc_outputs, hidden_state,
                                                       enc valid lens]
```

```
In [52]:
          M | model3_1 = train_enc_attdec_lstm(num_layers=1)
             Seq2SeqAttentionEncoder LSTM(
               (embedding): Embedding(194, 256)
               (rnn): LSTM(
                 (rnn): LSTM(256, 256, dropout=0.2)
             )
              Seq2SeqAttentionDecoder_LSTM(
               (attention): AdditiveAttention(
                 (W_k): LazyLinear(in_features=0, out_features=256, bias=False)
                 (W_q): LazyLinear(in_features=0, out_features=256, bias=False)
                 (w_v): LazyLinear(in_features=0, out_features=1, bias=False)
                 (dropout): Dropout(p=0.2, inplace=False)
               (embedding): Embedding(214, 256)
               (rnn): LSTM(512, 256, dropout=0.2)
               (dense): LazyLinear(in_features=0, out_features=214, bias=True)
```

```
ValueError
                                          Traceback (most recent call las
t)
~\AppData\Local\Temp\ipykernel 22816\499448629.py in <module>
----> 1 model3_1 = train_enc_attdec_lstm(num_layers=1)
~\AppData\Local\Temp\ipykernel 22816\1434010974.py in train enc attdec ls
tm(embed size, num hiddens, num layers, dropout)
            model = d21.Seq2Seq(encoder, decoder, tgt pad=data.tgt vocab
['<pad>'], lr=0.005)
            trainer = d21.Trainer(max epochs=30, gradient clip val=1, num
      6
_gpus=1)
            trainer.fit(model, data)
---> 7
~\anaconda3\lib\site-packages\d21\torch.py in fit(self, model, data)
                self.val batch idx = 0
    273
                for self.epoch in range(self.max epochs):
--> 274
                    self.fit epoch()
    275
    276
            def fit epoch(self):
~\anaconda3\lib\site-packages\d21\torch.py in fit epoch(self)
                self.model.train()
    285
    286
                for batch in self.train_dataloader:
--> 287
                    loss = self.model.training step(self.prepare batch(ba
tch))
                    self.optim.zero grad()
    288
    289
                    with torch.no grad():
~\anaconda3\lib\site-packages\d21\torch.py in training_step(self, batch)
                                every n=int(n))
    204
    205
            def training step(self, batch):
--> 206
                l = self.loss(self(*batch[:-1]), batch[-1])
                self.plot('loss', 1, train=True)
    207
    208
                return 1
~\anaconda3\lib\site-packages\torch\nn\modules\module.py in call impl(se
lf, *input, **kwargs)
   1128
                if not (self. backward hooks or self. forward hooks or se
lf._forward_pre_hooks or _global_backward_hooks
   1129
                        or global forward hooks or global forward pre h
ooks):
-> 1130
                    return forward call(*input, **kwargs)
                # Do not call functions when jit is used
   1131
   1132
                full backward hooks, non full backward hooks = [], []
~\anaconda3\lib\site-packages\d2l\torch.py in forward(self, enc X, dec X,
*args)
    909
                dec_state = self.decoder.init_state(enc_all_outputs, *arg
s)
    910
                # Return decoder output only
                return self.decoder(dec_X, dec_state)[0]
--> 911
    912
    913
            def predict step(self, batch, device, num steps,
~\anaconda3\lib\site-packages\torch\nn\modules\module.py in call impl(se
```

```
lf, *input, **kwargs)
               1128
                            if not (self._backward_hooks or self._forward_hooks or se
            lf._forward_pre_hooks or _global_backward_hooks
                                    or _global_forward_hooks or _global_forward_pre_h
            ooks):
            -> 1130
                                return forward_call(*input, **kwargs)
                            # Do not call functions when jit is used
               1131
                            full_backward_hooks, non_full_backward_hooks = [], []
               1132
            ~\AppData\Local\Temp\ipykernel 22816\573968876.py in forward(self, X, sta
            te)
                            # Shape of enc_outputs: (batch_size, num_steps, num_hidde
                 18
            ns).
                            # Shape of hidden state: (num layers, batch size, num hid
                 19
            dens)
            ---> 20
                            enc outputs, hidden state = state
                 21
                 22
                            #enc_outputs, hidden_state, enc_valid_lens = state
            ValueError: too many values to unpack (expected 2)
         ▶ model3 2 = train enc attdec lstm(num layers=2)
In [ ]:
In [ ]:
         ▶ model3 3 = train enc attdec lstm(num layers=3)
         M model3 4 = train enc attdec lstm(num layers=4)
In [ ]:
```