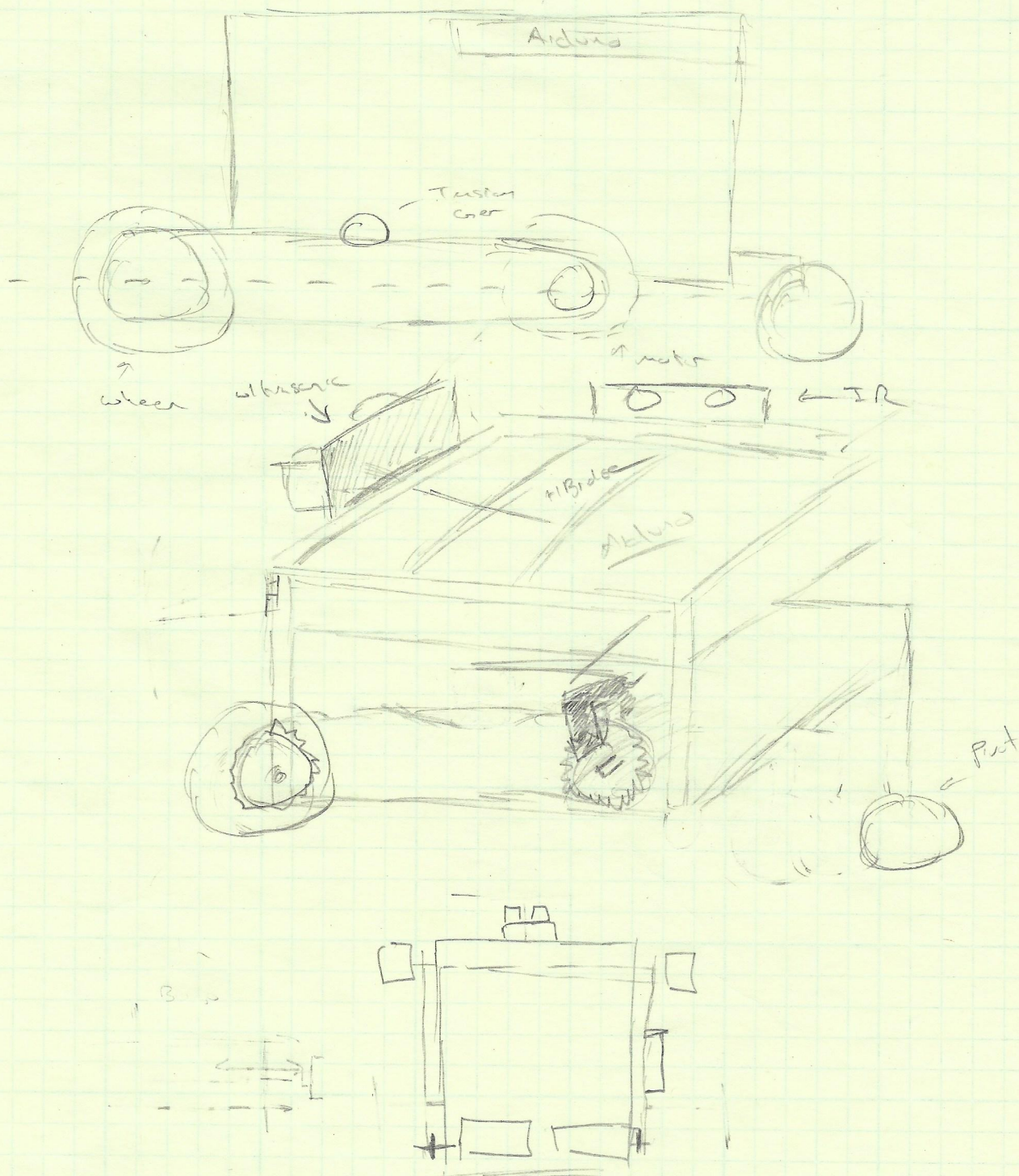


Mechanical



Ms

330k + 0 = GND
 GND = 0 + 0.1k

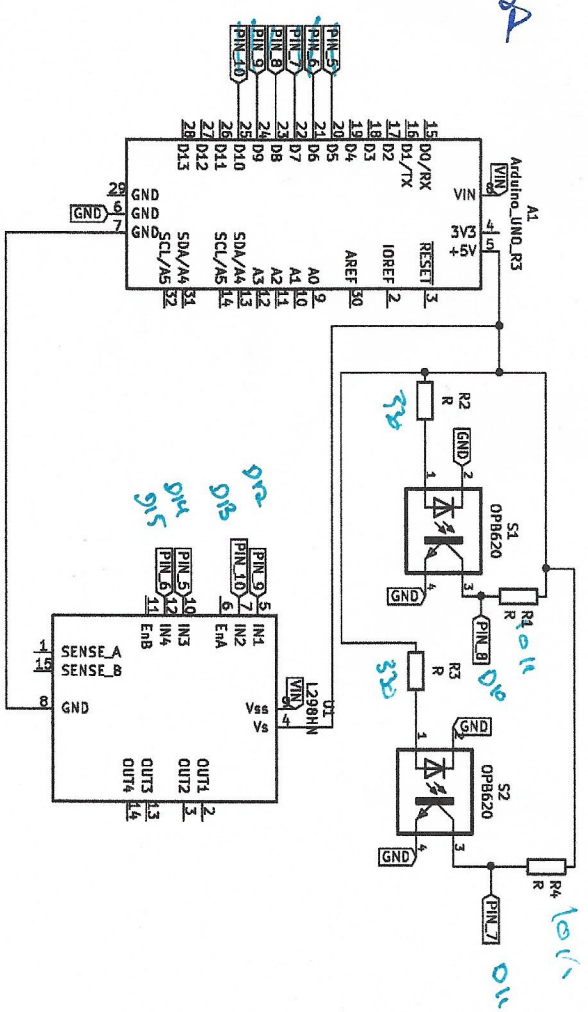
1 4
 2 3

Default = 0 = 0.1k

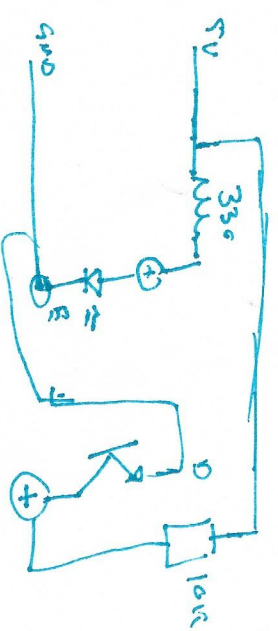
2 + 0.1k 0.3k
 1.1k + 4k

Sending One Interrupt
 to Arduino!

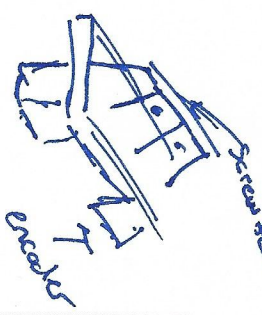
16-31
 48 49 50 51
 32 33 34 35



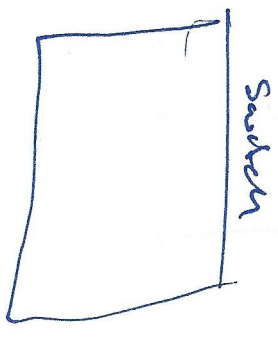
- Design a board for encoder 15



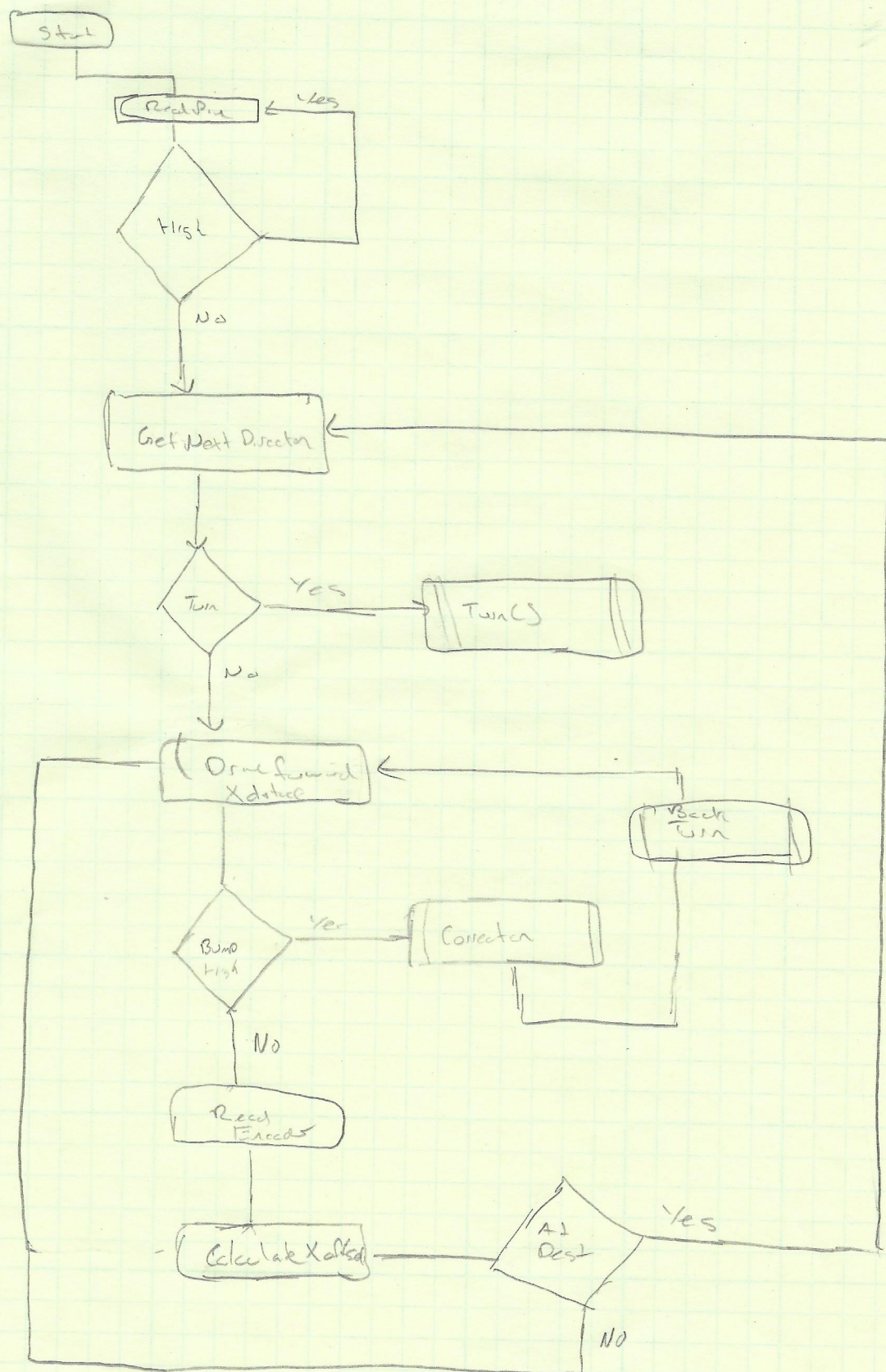
- Add screw terminals for more sensors
- Add DIP switch for on connection?



Jump switch?
 Don't need
 X resistor to 5V
 need to check
 before any
 drive



Flow:



MS