
Final Project Proposal

COMP4102A

Blah blah subtitle

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1 Summary

The goal of this project is to create a car safety suite using computer vision. The initial targets are to create a system that tracks pedestrians, road signs, and stop lights as well as tracking the driver's attentiveness to the road. A secondary goal is to make the system highly modular, so new components can be easily added in or create interactions between modules.

2 Background

3 The Challenge

This space has a number of challenges. While any one component of this project has many implementations even within the computer vision space, making them all work together in real time on mid to low end hardware. In addition, gaze tracking with a single camera is a more difficult area with no simple, of-the-shelf implementation in openCV.

4 Goals and Deliverables

4.1 Primary Goals

4.2 Evaluation

4.3 Stretch Goals

The primary stretch goal for us to add an interaction between the modules. As a proof of concept, we would implement a system to ensure a driver has actually looked in the direction of a pedestrian or sign. An additional goal would be to validate it running on a Raspberry Pi Zero as a proof it can be embedded into an actually.

5 Schedule for Completion