CENTER FOR ECONOMIC BEHAVIOR & INEQUALITY

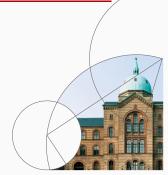


Consumption-Saving Models

An Introduction to Dynamic Programming

Jeppe Druedahl 2020







Introduction

Introduction

- Why are consumption-saving models important?
 - 1. Important topic in itself (70 percent of GDP)
 - 2. Central aspect of many other decisions
 - a) Labor supply, retirement, and fertility choices
 - b) Portfolio choices and asset pricing
 - c) Housing and location choices
 - Households are the cornerstone of general equilibrium models designed to study the cause and effect of inequality
- Dynamic programming essential for recent advances
 - 1. Idiosyncratic and aggregate uncertainty
 - 2. Ex ante and ex post heterogeneity
 - Internal and external optimization frictions (bounded rationality, adjustment costs etc.)

Introduction

- Part of mini-course on dynamic programming: ConsumptionSavingNotebooks/DynamicProgramming
- Focus in the partial equilibrium (PE) part of these slides:
 Carroll (2020, QE), Theoretical foundations of buffer stock saving
- Acknowledgments: Christoffer Jessen Weissert, Emil Holst Partsch, Anders Yding, previous students in Dynamic Programming

General references

- Dynamic programming and computational methods in general: Stokey and Lucas (1989), Judd (1998), Adda and Cooper (2003), Ljungqvist and Sargent (2004), Puterman (2009), Powell (2011), Bertsekas (2012), Schmedders and Judd (2013)
- Surveys of consumption-saving litteratures: Browning and Lusardi (1996), Browning and Crossley (2001), Heathcote et al. (2009), Krusell and Smith (2006), Krueger et al. (2016), Pistaferri (2017), Kaplan and Violante (2018)
- End-of-slides: Many more references

Plan

- 1. Introduction
- 2. PIH
- 3. Buffer-stock
- 4. EGM
- 5. Further perspectives
- 6. Estimation
- 7. GE
- 8. Summary

PIH

Permanent Income Hypothesis (PIH)

• Household problem

$$V_{0}(M_{0}, P_{0}) = \max_{\{C_{t}\}_{t=0}^{T}} \sum_{t=0}^{T} \beta^{t} \frac{C_{t}^{1-\rho}}{1-\rho}, \quad \beta < 1, \ \rho \geq 1$$
s.t.
$$A_{t} = M_{t} - C_{t}$$

$$B_{t+1} = R \cdot A_{t}, \quad R > 0$$

$$M_{t+1} = B_{t+1} + P_{t+1}$$

$$P_{t+1} = G \cdot P_{t}, \quad G > 0$$

$$A_{T} > 0$$

- ullet Well-defined analytical solution, also for $T o \infty$ if
 - 1. Return impatience (RI): $(\beta R)^{1/\rho}/R < 1$
 - 2. Finite human wealth (FHW): G/R < 1
- What do you think is missing?

The Intertemporal Budget Constraint (IBC)

Substitution implies

$$A_{T} = M_{T} - C_{T} = (RA_{T-1} + P_{T}) - C_{T}$$

$$= R(M_{T-1} - C_{T-1}) + P_{T} - C_{T}$$

$$= R^{2}A_{T-2} + RP_{T-1} - RC_{T-1} + P_{T} - C_{T}$$

$$= R^{T+1}A_{-1} + \sum_{t=0}^{T} R^{T-t}(P_{t} - C_{t})$$

• Use **terminal condition** $A_T = 0$ (why equality?)

$$R^{-T}A_T = 0 \Leftrightarrow B_0 + H_0 = \sum_{t=0}^{T} R^{-t}C_t$$

where
$$H_0 \equiv \sum_{t=0}^{T} (G/R)^t P_0 = \frac{1 - (G/R)^{T+1}}{1 - G/R} P_0$$

$\textbf{Static problem} \rightarrow \textbf{Lagrangian}$

$$\mathcal{L} = \sum_{t=0}^{T} \beta^{t} \frac{C_{t}^{1-\rho}}{1-\rho} + \lambda \left[\sum_{t=0}^{T} R^{-t} C_{t} - (B_{0} + H_{0}) \right]$$

First order conditions

$$\forall t: \ 0 = \beta^t C_t^{-\rho} - \lambda R^{-t}$$

- Short-run Euler equation: $\frac{C_{t+1}}{C_t} = (\beta R)^{1/\rho}$
- Long-run Euler equation: $\frac{C_t}{C_0} = (\beta R)^{t/\rho}$

Consumption function

Insert Euler into IBC

$$\sum_{t=0}^{T} R^{-t} (\beta R)^{t/\rho} C_0 = B_0 + H_0 \Leftrightarrow$$

$$C_0 \sum_{t=0}^{T} ((\beta R)^{1/\rho} / R)^t = B_0 + H_0$$

• Solve for C₀

$$C_0 = \frac{1 - (\beta R)^{1/\rho}/R}{1 - ((\beta R)^{1/\rho}/R)^{T+1}} (B_0 + H_0)$$

- MPC: $\frac{\partial C_0}{\partial B_0} \approx 1 [(\beta R)^{1/\rho}/R] \approx 1 R^{-1} \approx r$, where R = 1 + r
- MPCP: $\frac{\partial C_0}{\partial P_0} \approx 1 [(\beta R)^{1/\rho}/R] \frac{\partial H_0}{\partial P_0} \approx \frac{1 1/R}{1 G/R} \approx 1$

Side-note: Value function

• Analytical expression for the value function

$$V_0(M_0, P_0) = \sum_{t=0}^{T} \beta^t u((\beta R)^{t/\rho} C_0)$$

$$= \sum_{t=0}^{T} \beta^t (\beta R)^{(1-\rho)t/\rho} \frac{C_0^{1-\rho}}{1-\rho}$$

$$= \sum_{t=0}^{T} ((\beta R)^{1/\rho}/R)^t \frac{C_0^{1-\rho}}{1-\rho}$$

$$= \frac{1 - ((\beta R)^{1/\rho}/R)^{T+1}}{1 - (\beta R)^{1/\rho}/R} \frac{C_0^{1-\rho}}{1-\rho}$$

Empirical evidence

Pro

- 1. Micro-founded consumption-saving
 - Theoretically appealing (humans are intentional)
 - Empirically appealing (testable implications on micro-data)
- 2. Larger responses to permanent than to transitory shocks
- 3. Consumption smoothing save for retirement (future low income)

Con

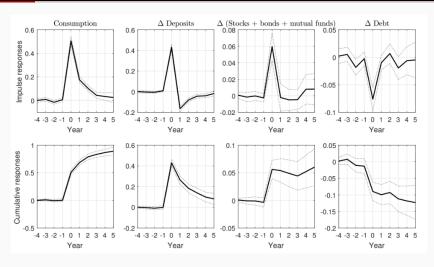
- 1. Households seems to have a high MPC in the range 0.20-0.40
 - Survey studies (Kreiner et al., 2019)
 - Tax rebates studies (Johnson et al., 2006; Parker et al., 2013)
 - Lottery studies (Fagereng et al., 2020)
 - ARM payments studies (Di Maggio et al., 2017; Druedahl et al., 2020b)
- 2. Consumption responds to anticipated income changes
- 3. Households with more volatile income have larger savings
- 4. Consumption tracks income over the life-cycle
- 5. (Households are only boundedly rational)

High MPC: Danish SP payout

Figure 4: Spending and the size of the SP payout 30000 Spending (DKK) 10000 20000 10000 30000 SP payout (DKK) Local polynomial regression Data points NOTE: 5055 observations.

Source: Kreiner, Lassen og Leth-Petersen (AEJ:Pol, 2019)

High MPC: Norwegian lottery winners



Source: Fagereng, Holm, Natvik (AEJ:Macro, 2020)

Buffer-stock

Buffer-stock model (Deaton-Carroll)

- + borrowing constraints
- + income uncertainty

$$\Rightarrow V_0(M_0, P_0) = \max_{\{C_t\}_{t=0}^T} \mathbb{E}_0 \sum_{t=0}^T \beta^t \frac{C_t^{1-\rho}}{1-\rho}$$
s.t.
$$A_t = M_t - C_t$$

$$M_{t+1} = RA_t + Y_{t+1}$$

$$Y_{t+1} = \xi_{t+1}P_{t+1}$$

$$\xi_{t+1} = \begin{cases} \mu & \text{with prob. } \pi \\ (\epsilon_{t+1} - \pi\mu)/(1-\pi) & \text{else} \end{cases}$$

$$\epsilon_t \sim \exp \mathcal{N}(-0.5\sigma_{\xi}^2, \sigma_{\xi}^2)$$

$$P_{t+1} = GP_t\psi_{t+1}, \ \psi_t \sim \exp \mathcal{N}(-0.5\sigma_{\psi}^2, \sigma_{\psi}^2)$$

$$A_t \geq -\lambda P_t$$

Note: Later analytical results hold only for $\mu=0$ and $\pi>0$

How to solve the model?

- Borrowing constraints → inequalities → high-dimensional Kuhn-Tucker problem
- ullet Uncertainty o fully dynamic problem o no simple Lagrangian
- No analytical solution with CRRA preferences
 - Quadratic or CARA utility, which give some analytical results, have implausible properties

CRRA:
$$u(c) = \frac{c^{1-\rho}}{1-\rho} \rightarrow \text{RRA} = \rho$$

Qudratic: $u(c) = ac - \frac{b}{2}c^2 \rightarrow \text{RRA} = \frac{b}{a-bc}c$

CARA: $u(c) = \frac{1}{\alpha}e^{-\alpha c} \rightarrow \text{RRA} = \alpha c$

where RRA = relative risk aversion = $\frac{-u''(c)}{u'(c)}c$

ullet Solution: Bellman equation o numerical dynamic programming

Bellman equation

$$V_t(M_t, P_t) = \max_{C_t} \frac{C_t^{1-
ho}}{1-
ho} + \beta \mathbb{E}_t \left[V_{t+1}(M_{t+1}, P_{t+1}) \right]$$
 s.t.
$$A_t = M_t - C_t$$

$$M_{t+1} = RA_t + Y_{t+1}$$

$$Y_{t+1} = \xi_{t+1} P_{t+1}$$

$$\xi_{t+1} = \begin{cases} \mu & \text{with prob. } \pi \\ (\epsilon_{t+1} - \pi \mu)/(1-\pi) & \text{else} \end{cases}$$

$$P_{t+1} = GP_t \psi_{t+1}$$

$$A_t \geq -\lambda P_t$$

$$A_T > 0$$

Normalization I

• **Defining** $c_t \equiv C_t/P_t, m_t \equiv M_t/P_t$ etc. implies

$$A_t = M_t - C_t \Leftrightarrow A_t/P_t = M_t/P_t - C_t/P_t$$

$$\Leftrightarrow a_t = m_t - c_t$$

$$\begin{aligned} M_{t+1} &= RA_t + Y_{t+1} &\Leftrightarrow & M_{t+1}/P_{t+1} = RA_t/P_{t+1} + Y_{t+1}/P_{t+1} \\ &\Leftrightarrow & m_{t+1} = Ra_tP_t/P_{t+1} + \xi_{t+1} \\ &\Leftrightarrow & m_{t+1} = \frac{R}{G\psi_{t+1}} a_t + \xi_{t+1} \end{aligned}$$

The adjustment factor $\frac{1}{G\psi_{t+1}}$ is due to changes in permanent income

Normalization II

• **Defining** $v_t(m_t) = V_t(M_t, P_t)/P_t^{1-\rho}$ finally implies

$$V_{t}(M_{t}, P_{t}) = \max_{C_{t}} \frac{C_{t}^{1-\rho}}{1-\rho} + \beta \mathbb{E}_{t} \left[V_{t+1}(M_{t+1}, P_{t+1}) \right]$$

$$= \max_{c_{t}} \frac{(c_{t}P_{t})^{1-\rho}}{1-\rho} + \beta \mathbb{E}_{t} \left[V_{t+1}(M_{t+1}, P_{t+1}) \right] \Leftrightarrow$$

$$V_{t}(M_{t}, P_{t})/P_{t}^{1-\rho} = \max_{c_{t}} \frac{(c_{t}P_{t})^{1-\rho}/P_{t}^{1-\rho}}{1-\rho} + \beta \mathbb{E}_{t} \left[V_{t+1}(M_{t+1}, P_{t+1})/P_{t}^{1-\rho} \right] \Leftrightarrow$$

$$v_{t}(m_{t}) = \max_{c_{t}} \frac{c_{t}^{1-\rho}}{1-\rho} + \beta \mathbb{E}_{t} \left[V_{t+1}(M_{t+1}, P_{t+1})/P_{t+1}^{1-\rho} \cdot P_{t+1}^{1-\rho}/P_{t}^{1-\rho} \right]$$

$$= \max_{c_{t}} \frac{c_{t}^{1-\rho}}{1-\rho} + \beta \mathbb{E}_{t} \left[(G\psi_{t+1})^{1-\rho} v_{t+1}(m_{t+1}) \right]$$

Bellman equation in ratio form

$$v_t(m_t) = \max_{c_t} \frac{c_t^{1-\rho}}{1-\rho} + \beta \mathbb{E}_t \left[(G\psi_{t+1})^{1-\rho} v_{t+1}(m_{t+1}) \right]$$
s.t.
$$a_t = m_t - c_t$$

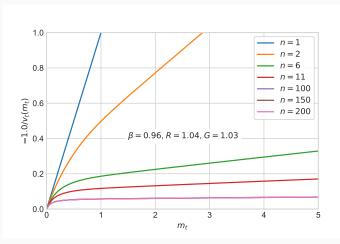
$$m_{t+1} = \frac{1}{G\psi_{t+1}} R a_t + \xi_{t+1}$$

$$\xi_{t+1} = \begin{cases} \mu & \text{with prob. } \pi \\ (\epsilon_{t+1} - \pi \mu)/(1-\pi) & \text{else} \end{cases}$$

$$a_t \geq -\lambda$$

- Benefit: Dimensionality of state space reduced
 Can this always be done?
- Easy to solve by VFI

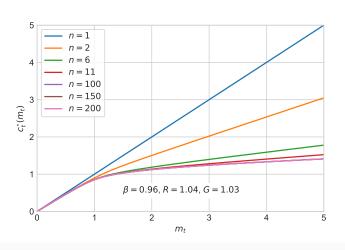
$T \to \infty$; Convergence of $-1.0/v_t(m_t) \to -1.0/v^*(m_t)$



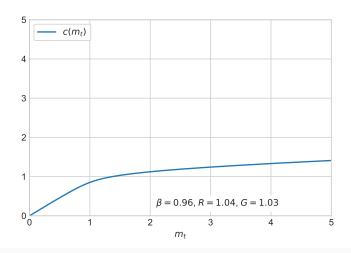
Other parameters: $\rho=$ 2, $\pi=$ 0.005, $\mu=$ 0.0, $\sigma_{\psi}=\sigma_{\xi}=$ 0.10

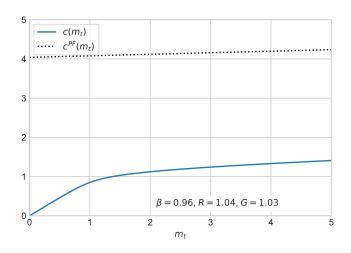
Note: $-1.0/v_t(m_t)$ is a numerically more stable object than $v_t(m_t)$

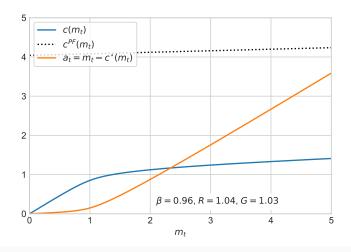
$T \to \infty$: Convergence of $c_t(m_t) \to c^*(m_t)$

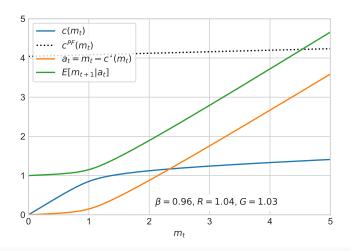


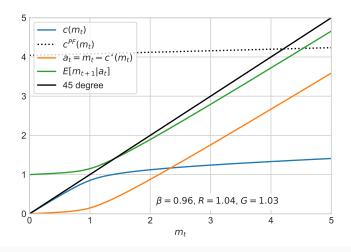
• What is the MPC?

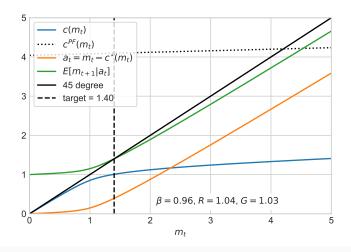












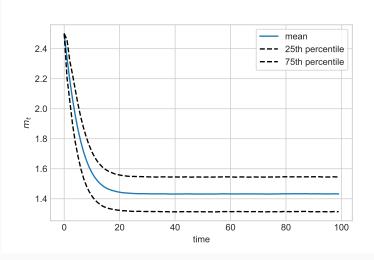
Simulation for $t \in \{0, 1, \dots, T-1\}$

- 1. Choose m_0 and set t=0
- 2. Calculate $c_t = c^*(m_t)$
- 3. Calculate $a_t = m_t c_t$
- 4. Draw (pseudo-)random numbers

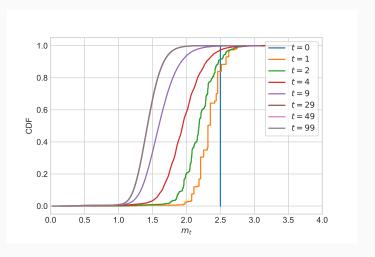
$$\begin{array}{lcl} \epsilon_{t+1} & \sim & \exp \mathcal{N}(-0.5\sigma_{\xi}^2, \sigma_{\xi}^2) \\ \psi_{t+1} & \sim & \exp \mathcal{N}(-0.5\sigma_{\psi}^2, \sigma_{\psi}^2) \\ \eta_{t+1} & \sim & \mathcal{U}(0, 1) \end{array}$$

- 5. Calculate $\xi_{t+1} = egin{cases} \mu & \text{if } \eta_{t+1} < \pi \\ (\epsilon_{t+1} \pi \mu)/(1-\pi) & \text{else} \end{cases}$
- 6. Calculate $m_{t+1} = \frac{R}{G\psi_{t+1}} a_t + \xi_{t+1}$
- 7. Set t = t + 1
- 8. Stop if $t \geq T$ else go to step 2

Simulation: Avg. cash-on-hand



Simulation: Distribution of cash-on-hand

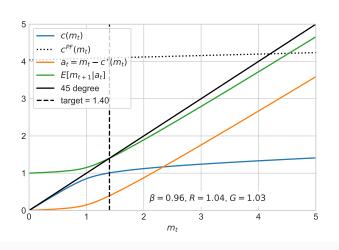


• Proof of convergence: Szeidl (2006)

Buffer-stock

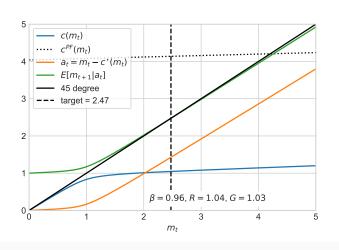
Details

Precautionary saving: $\sigma_{\psi} = 0.10$



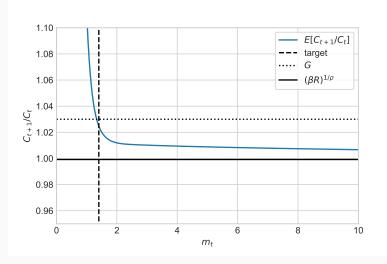
Target with baseline risk: 1.40

Precautionary saving: $\sigma_{\psi} = 0.15$



Target with high risk: 2.47

Consumption growth I



Consumption growth II

• Remember Euler-equation

$$C_t^{-
ho} = \beta R \mathbb{E}_t \left[C_{t+1}^{-
ho} \right]$$
 if no uncertainty $\Rightarrow C_{t+1}/C_t = (\beta R)^{1/
ho}$

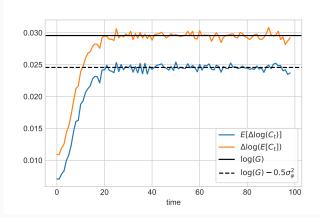
Results

- 1. C_{t+1}/C_t is declining in m_t
- 2. $\lim_{m_t \to \infty} C_{t+1}/C_t = (\beta R)^{1/\rho} = RI$
- 3. $\lim_{m_t\to 0} C_{t+1}/C_t = \infty$
- 4. $C_{t+1}/C_t < G$ at buffer-stock target
- Intuition for $C_{t+1}/C_t > (\beta R)^{1/\rho}$
 - 1. Uncertainty \Rightarrow expected marginal utility $\uparrow [C_{t+1}^{-\rho}]$ is convex function]
 - 2. Consumer must be lowered today, $C_t \downarrow$
 - 3. Consumption growth will increase, $C_{t+1}/C_t \uparrow$

Further: The above arguments are stronger for lower cash-on-hand relative to permanent income

Consumption growth III

- 1. Growth of average consumption = G
- 2. Average consumption growth $=G-0.5\sigma_{\psi}^2$

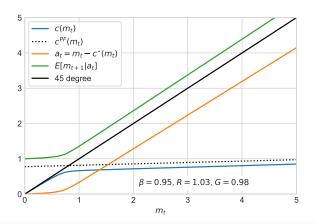


Always a buffer-stock target? I

- 1. Utility impatience (UI): $\beta < 1$
- 2. Return impatience (RI): $(\beta R)^{1/\rho}/R < 1$
- 3. Weak return impatience (WRI): $\pi^{1/\rho}(\beta R)^{1/\rho}/R < 1$
- 4. Growth impatience (GI): $(\beta R)^{1/\rho}\mathbb{E}_t[\psi_{t+1}^{-1}]/G < 1$
- 5. Absolute impatience (AI): $(\beta R)^{1/\rho} < 1$
- 6. Finite value of autarky (FVA): $\beta \mathbb{E}_t[(G\psi_{t+1})^{1-\rho}] < 1$

Always a buffer-stock target? II

- GI ensures buffer-stock target
- If not GI then inifinite accumulation is possible like:



Existence of solution

- Existence of solution: WRI + FVA
 - Proof: Use Boyds weighted contraction mapping theorem
 - Standard assumptions: FHW, RI, GI
- The consumption function is twice continuously differentiable, increasing and concave

The borrowing constraint

- Assume perfect foresight ($\sigma_{\psi} = \sigma_{\epsilon} = \pi = 0$), but no borrowing, $\lambda = 0$.
- **Solution:** RI + FHW is still *sufficient* (with $\lambda = \infty$ they are *necessary*)
- Standard solutions: RI + FHW
 - 1. $GI \Rightarrow constraint will eventually be binding$

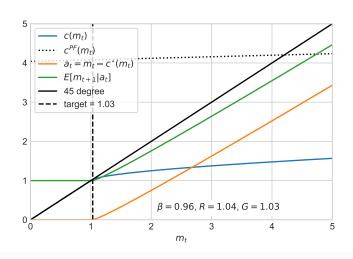
$$c^{\star}(m_t)$$
 converge to $c^{ extit{PF}}(m_t)$ from below as $m_t o \infty$

2. **Not GI** \Rightarrow constraint is never reached

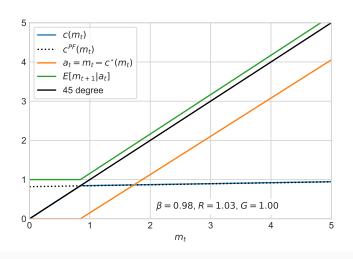
$$c^{\star}(m_t) = c^{PF}(m_t)$$
 for $m_t \geq 1$

Exotic solutions without FHW exists (GI necessary)

Perfect foresight with $\lambda = 0$ and GI



Perfect foresight with $\lambda = 0$, but not GI



Buffer-stock

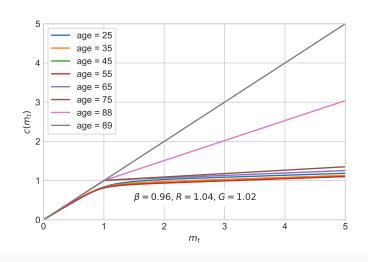
Life-cycle

Adding a life-cycle (normalized)

$$\begin{array}{lcl} v_t(m_t,z_t) & = & \displaystyle \max_{c_t} \frac{v(z_t)c_t^{1-\rho}}{1-\rho} + \beta \mathbb{E}_t \left[\left(GL_{t+1}\psi_{t+1} \right)^{1-\rho} v_{t+1}(\bullet) \right] \\ & \text{s.t.} \\ \\ a_t & = & m_t - c_t \\ \\ m_{t+1} & = & \displaystyle \frac{1}{GL_t\psi_{t+1}} Ra_t + \xi_{t+1} \\ \\ \xi_{t+1} & = & \begin{cases} \mu & \text{with prob. } \pi \\ (\epsilon_{t+1} - \pi\mu)/(1-\pi) & \text{else} \end{cases} \\ \\ a_t & \geq & \lambda_t = \begin{cases} -\lambda & \text{if } t < T_R \\ 0 & \text{if } t > T_R \end{cases} \end{array}$$

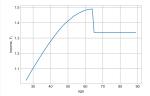
- **Demographics**: z_t (exogenous). What could it be specifically?
- Income profile: $P_{t+1} = GL_tP_t\psi_{t+1}$
- No shocks in retirement: $\psi_t = \xi_t = 1$ if $t > T_R$
- Euler equation: $C_t^{-\rho} = \beta R \mathbb{E}_t \left[\frac{v(z_{t+1})}{v(z_t)} C_{t+1}^{-\rho} \right]$

Consumption functions $(v(z_t) = 1)$

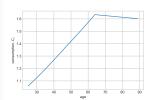


Simulation: LIfe-cycle profiles ($v(z_t) = 1$)

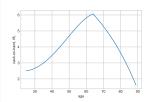
Income, Y_t (implied by G and L_t)



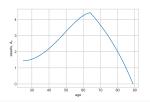
Consumption, C_t



Cash-on-hand, M_t



End-of-period assets, A_t



What is the most unrealistic here?

EGM

Euler-equation

- Reference: Carroll (2006)
- Assume for simplicity **no borrowing**: $\lambda = 0$
- All optimal interior choices must satisfy

$$C_t^{-\rho} = \beta R \mathbb{E}_t \left[C_{t+1}^{-\rho} \right] \Leftrightarrow c_t^{-\rho} = \beta R \mathbb{E}_t \left[\left(G \psi_{t+1} c_{t+1} \right)^{-\rho} \right]$$

• Else optimal choice is constrained

$$C_{t}^{-\rho} \geq \beta R \mathbb{E}_{t} \left[C_{t+1}^{-\rho} \right] \Leftrightarrow$$

$$C_{t} = M_{t} \Leftrightarrow$$

$$c_{t} = m_{t}$$

Endogenous grid method: Intuition

• **Obs.:** Given $C_{t+1}^{\star}(M_{t+1}, P_{t+1})$ and A_t and P_t we have

$$C_{t}^{-\rho} = \beta R \mathbb{E}_{t} \left[(C_{t+1}^{\star}(M_{t+1}, P_{t+1}))^{-\rho} \right] \Leftrightarrow$$

$$C_{t} = \mathbb{E}_{t} \left[\beta R (C_{t+1}^{\star}(M_{t+1}, P_{t+1}))^{-\rho} \right]^{-\frac{1}{\rho}}$$

$$= \mathbb{E}_{t} \left[\beta R (C_{t+1}^{\star}(RA_{t} + Y_{t+1}, P_{t+1}))^{-\rho} \right]^{-\frac{1}{\rho}}$$

$$= \mathbb{E}_{t} \left[\beta R (C_{t+1}^{\star}(RA_{t} + P_{t}\psi_{t+1}\xi_{t+1}, P_{t}\psi_{t+1}))^{-\rho} \right]^{-\frac{1}{\rho}}$$

$$\equiv F(A_{t}, P_{t})$$

- Endogenous grid: $A_t = M_t C_t \Leftrightarrow M_t = C_t + A_t$
- Conclusion: (M_t, P_t, C_t) is a solution to the Bellman equation because it satisfies the Euler equation
- **Perspectives:** Varying A_t (and P_t) we can map out the consumption function without using any numerical solver!
- Borrowing constraint: Binding below lowest generated M_t

... in ratio form

- Prerequisites:
 - 1. Next-period **consumption function**: $c_{t+1}^{\star}(m_{t+1})$
 - 2. Asset grid: $G_a = \{a_1, a_2, \dots, a_\#\}$ with $a_1 = 10^{-6}$
- **Algorithm:** For each $a_i \in \mathcal{G}_a$
 - 1. Find consumption using Euler equation

$$c_i = \mathbb{E}_t \left[\beta R \left(G \psi_{t+1} c_{t+1}^{\star} \left(\frac{R}{G \psi_{t+1}} a_i + \xi_{t+1} \right) \right)^{-\rho} \right]^{-\frac{1}{\rho}}$$

- 2. Find endogenous state: $a_i = m_i c_i \Leftrightarrow m_i = a_i + c_i$
- The **consumption function**, $c_t(m_t)$, is given by interpolating

$$\{0, c_1, c_2, \dots, c_\#\}$$
 for $\{\underline{a}_t, m_1, m_2, \dots, m_\#\}$

• We can find all consumption functions in this way!

Addendum: The natural borrowing constraint $(\lambda > 0)$

 The optimal end-of-period asset choice satisfies the backwards recursion

$$a_t \ge \underline{a}_t = \begin{cases} 0 & \text{if } t \ge T_R \\ -\min\left\{\Lambda_t, \lambda_t\right\} GL_t \underline{\psi} & \text{if } t < T_R \end{cases}$$

where

$$\Lambda_t \equiv \begin{cases} R^{-1} G L_t \underline{\psi} \, \underline{\xi} & \text{if } t = T_R - 1 \\ R^{-1} \left[\min \left\{ \Lambda_{t+1}, \lambda_t \right\} + \underline{\xi} \right] G L_t \underline{\psi} & \text{if } t < T - 1 \end{cases}$$

and $\underline{\psi}$ and $\underline{\xi}$ are the minimum realizations of ψ_{t+1} and ξ_{t+1}

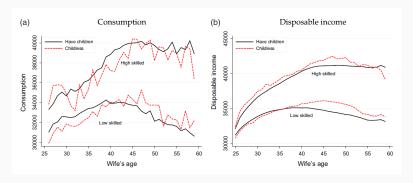
• **Proof:** Can be shown as a consequence of the household wanting to avoid $c_t = 0$ at any cost because $\lim_{c_t \to 0} u'(c_t) = \infty$.

Further perspectives

Three generations of models

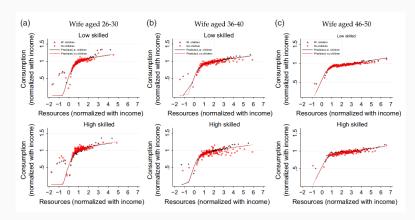
- 1st: Permanent income hypothesis (Friedman, 1957) or life-cycle model (Modigliani and Brumburg, 1954)
- 2nd: Buffer-stock consumption model (Deaton, 1991, 1992; Carroll, 1992, 1997, 2020)
- **3nd:** *Multiple-asset buffer-stock consumption models* (e.g. Kaplan and Violante (2014))

Denmark: Life-cycle profiles fit



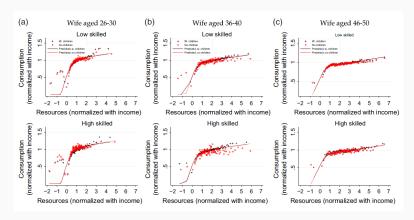
Source: Jørgensen (2017)

Denmark: Consumption function fit



Source: Jørgensen (2017)

Denmark: Consumption function fit

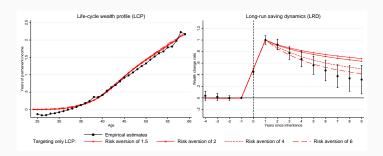


Source: Jørgensen (2017)

Level of wealth and long-run dynamics I

- Best test of a life-cycle consumption-saving model:
 - A sudden, sizable and salient shock to wealth
 - + long panel to observe how the extra wealth is spend
- My own research: Druedahl and Martinello (2018)
 Compare individuals in the Danish register data who
 - 1. Receive a similar inheritance, but at different points in time
 - 2. From parents dying due to heart attacks or car crashes

Level of wealth and long-run dynamics II



- Net worth: Good fit for different levels of risk-aversion (ρ) when re-calibrating patience (β)
- Also dynamics: Good fit only if risk-aversion (ρ) is high

MPC out of future shocks

- Central property of buffer-stock model:
 - Non-constrained: Increase consumption today when obtaining information of higher income tomorrow
 - 2. Constrained: Increase consumption when cash flow arrives
- How to test test this?
- A paper of mine: The Intertemporal Marginal Propensity to Consume out of Future Persistent Cash-Flows
 - 1. Data: Account data for all Nykredit customers
 - Experiment: Letter with bank's expectations for interest rate in next mortgage auction 2-3 months ahead
 - Result: Observed behavior can be rationalized in a simple buffer-stock consumption model
 - 4. Code: GitHub

Level of wealth and MPC

- Consumption-saving models a few years ago could not endogenously fit both
 - 1. The level of wealth observed
 - 2. The high MPCs found in quasi experiments
- Three solutions:
 - Exogenous hands-too-mouth households (Campbell and Mankiw, 1990)
 - 2. Preference heterogeneity
 - 3. Wealthy hands-to-mouth (Kaplan and Violante, 2014)

 Many households hold mostly illiquid assets with a high return
 - ightarrow consumption adjust in response to small income shock

Kaplan-Violante model (two-asset model)

$$egin{aligned} V_t(M_t,N_t,P_t) &= \max_{\mathcal{B}_t,C_t} u(C_t,\mathcal{B}_t) + eta \mathbb{E}_t [V_{t+1}(M_{t+1},N_{t+1},P_{t+1})] \end{aligned}$$
 s.t. $A_t &= M_t - C_t + (N_t - B_t) - 1\{N_t
eq B_t\} \omega$ $M_{t+1} &= R + P_{t+1} \xi_{t+1}$ $N_{t+1} &= R_b B_t$ $P_{t+1} &= P_t \psi_{t+1}$ $A_t &> -\lambda P_t.$

- Cost of liquidation: ω
- Illiquid assets give higher return: $R_b > R$ (+ potentially utility)

Kaplan-Violante model (two-asset model)

$$\begin{split} V_t(M_t,N_t,P_t) &= \max \left\{ v_t^{keep}(M_t,N_t,P_t), v_t^{adj.}(M_t+N_t-\lambda,P_t) \right\} \\ v_t^{keep}(M_t,N_t,P_t) &= \max_{C_t} u(C_t,B_t) + \beta W_t(A_t,B_t,P_t) \text{ s.t.} \\ A_t &= M_t - C_t \\ B_t &= N_t \\ A_t &\geq -\omega P_t. \end{split}$$

$$\tilde{v}_t^{adj.}(X_t,P_t) &= \max_{B_t,C_t} u(C_t,B_t) + \beta W_t(A_t,B_t,P_t) \text{ s.t.} \\ M_t &= X_t - B_t \\ A_t &= M_t - C_t \\ A_t &\geq -\omega P_t. \end{split}$$

$$W_t(A_t,B_t,P_t) = \mathbb{E}_t[V_t(RA_t+P_t\psi_{t+1}\xi_{t+1},R_bB_t,P_t\psi_{t+1})]$$

Frontier topics - curated papers

- Durable consumption: Berger and Vavra (2015), Harmenberg and Öberg (2020)
- Labor supply, retirement and family formation: Low et al. (2010), French and Jones (2011), Keane and Wasi (2016), Adda et al. (2016), Blundell et al. (2016)
- Non-Gaussian income uncertainty: Guvenen et al. (2019),
 De Nardi et al. (2020), Druedahl and Munk-Nielsen (2020)
- Housing: Landvoigt (2017), Kaplan et al. (2019)
- Imperfect information and bounded rationality: Pagel (2017).
 Carroll et al. (2019), Moran and Kovacs (2019), Druedahl and Jørgensen (2020)
- Level and dynamics of inequality circumstances or behavior?
 De Nardi and Fella (2017), Hubmer et al. (2020)

Frontier solution methods - curated papers

- EGM in non-convex multi-dimensional models: Druedahl and Jørgensen (2017) and Druedahl (2020)
- Sparse grids: Judd et al. (2014), Brumm and Scheidegger (2017)
- Machine learning: Azinovic et al. (2019), Maliar et al. (2019)

Estimation

Reduced form estimation

- Critic of structural estimation: Requires many assumptions
- But: To turn reduced form parameter estimates into policy advice a lot of assumptions are often implicitely required

»All econometric work relies heavily on a priori assumptions. The main difference between structural and experimental (or "atheoretic") approaches is not in the number of assumptions but the extent to which they are made explicit. « (Keane, 2012)

The beauty of models:

- 1. Ensure consistent world view
- Allow us to combine heterogenous facts and extrapolate from a myriad of past experiences
- Better models are clearly defined even if we never find the true model we can make progress
- Frontier: Combine the two and use exogenous variation to estimate structural model (Nakamura and Steinsson, 2018)

The Lucas critique

- The Lucas critique: Behavioral rules change with policy
 - ⇒ policy advice can not rely on estimated behavioral rules
 - \Rightarrow we need to estimate *structural parameters*

»Invariance of parameters in an economic model is not, of course, a property which can be assured in advance, but it seems reasonable to hope that neither tastes nor technology vary systematically with variations in counter-cyclical policies.« (Lucas, 1977)

- Other stuff might be approximately invariant
- Rigourous microfoundations:
 - Mathematically: Based on (boundedly) rational behavior derived as a solution to a formal optimization problem
 - 2. **Economically:** The assumptions are realistic

Estimation

1. Focus: Closely related estimators *indirectly* using micro-data

```
Simulated Method of Moments (SMM) (McFadden, 1989)
Simulated Minimium Distance (SMD) (Duffie and Singleton, 1990)
Indirect Inference (II) (Gouriéroux and Monfort, 1997)
```

Main alternative:

Simulated Maximum Likelihood (**SML**) *directly* using **micro-data** (see e.g. Adda and Cooper (2003) or Druedahl et al. (2018))

- 2. **Examples:** Gourinchas and Parker (2002), Cagetti (2003), Guvenen and Smith (2014), Druedahl and Jørgensen (2020)
- 3. Extended toolbox: Jørgensen (2020) and Honore et al. (2020)



Heterogenous Agent (HA) models

1. Stationary equilibrium:

Deterministic steady state and transition path

Foundational papers: Bewley (1986), Imrohoroğlu (1989),

Huggett (1993), Aiyagari (1994)

A few policy examples: Aiyagari and McGrattan (1998), Conesa

et al. (2009), Heathcote et al. (2014)

2. Dynamic/recursive/sequential equilibrium:

Aggregate shocks and stochastic dynamics

Foundational papers: Krusell and Smith (1997, 1998), Carroll (2000), Carroll et al. (2015)

(2000), Carroll et al. (2015)

3. **Reviews:** Heathcote et al. (2009), Krusell and Smith (2006), Krueger et al. (2016)

Heterogenous Agent New Keynesian (HANK) models

- Frontier: Kaplan et al. (2018), Bayer et al. (2019), Hagedorn et al. (2019b), Alves et al. (2020), Auclert et al. (2020c), Fernandez-Villaverde et al. (2020)
- Analytical: Bilbiie (2008, 2019a,b), Werning (2015), Challe et al. (2017), Acharya and Dogra (2020), Bilbiie et al. (2020), Debortoli and Galí (2018), Auclert et al. (2018), Broer et al. (2020), Ravn and Sterk (2020), Auclert and Rognlie (2020)
- 3. Others: Oh and Reis (2012), Gornemann et al. (2016), McKay and Reis (2016), McKay et al. (2016), Guerrieri and Lorenzoni (2017), Ravn and Sterk (2017), Den Haan et al. (2018), Luetticke (2020)
- Empirical: Cloyne et al. (2020), Slacalek et al. (2020), Holm and Paul (2020), Wolf (2020)
- 5. Reviews: Kaplan and Violante (2018)

Computational methods

- Early reviews: Den Haan et al. (2010), Schmedders and Judd (2013)
- Continuous time: Achdou et al. (2020) (code),
 Ahn et al. (2018) (code)
- Local aggregate solution:
 - 1. State space: Bayer and Luetticke (2020) (MATLAB, Python)
 - Sequence space: Boppart et al. (2018),
 Auclert et al. (2020c) (code)
- Global aggregate solution: Kubler and Scheidegger (2018),
 Azinovic et al. (2019), Scheidegger and Bilionis (2019), Pröhl (2019) (code),
 Maliar et al. (2019) (code, video),
 Fernandez-Villaverde et al. (2020) (code)

GE

Stationary equilibrium

The Aiyagari model

- Households: Continuum of measure 1 who
 - 1. Own stocks, a_{t-1} (end-of-period)
 - Supply labor with productivity et (exogenous and stochastic, mean one)
 - 3. Consume, c_t
- Firms: Rent capital and hire labor to produce
- Capital:
 - 1. Predetermined: $Y_t = F(Z_t, K_{t-1}, L_t)$, where Z_t is technology, K_{t-1} is capital, and L_t is labor
 - 2. Depreciates with rate δ
- Prices are taken as given by households and firms
 - 1. r_t^k , rental rate
 - 2. $r_t = r_t^k \delta$, interest rate
 - 3. w_t , wage rate

Firms

- Production function: $Y_t = Z_t K_{t-1}^{\alpha} L_t^{1-\alpha}$
- Define $k_{t-1} \equiv K_{t-1}/L_t$
- Standard pricing equations:

$$r_t^k = \alpha Z_t k_{t-1}^{\alpha - 1}$$

$$w_t = (1 - \alpha) Z_t k_{t-1}^{\alpha}$$

Useful implications:

$$k_{t-1} = \left(\frac{r_t + \delta}{\alpha Z_t}\right)^{\frac{1}{\alpha - 1}} \equiv k(r_t, Z_t)$$

$$r_t = \alpha Z_t k_{t-1}^{\alpha - 1} \equiv r(k_{t-1}, Z_t)$$

$$w_t = (1 - \alpha) Z_t \left(\frac{r_t + \delta}{\alpha Z_t}\right)^{\frac{\alpha}{\alpha - 1}} \equiv w(r_t, Z_t)$$

Households

- **Perfect foresight:** Price sequence known, $\{r_t, w_t\}_{t\geq 0}$
- Households solve:

$$v_t(e_t, a_{t-1}) = \max_{c_t} \frac{c_t^{1-\sigma}}{1-\sigma} + \beta \mathbb{E}_t \left[v_{t+1}(e_{t+1}, a_t) \right]$$
s.t.
$$a_t + c_t = (1+r_t)a_{t-1} + w_t e_t$$

$$a_t \geq 0$$

• Value function: We could write

$$v_t(e_t, a_{t-1}) = \mathcal{V}(e_t, a_{t-1}, \{r_k, w_k\}_{k \geq t})$$

where $\mathcal V$ does not have a time subscript, but where the price sequences are state variables

• Optimal saving and consumption: $a_t^*(e_t, a_{t-1})$ and $c_t^*(e_t, a_{t-1})$

Supply of capital

- **Distribution:** D_t over e_t and a_{t-1}
- Supply of capital: $\mathcal{K}_t = \int a_t^*(e_t, a_{t-1}) dD_t = \int a_t dD_{t+1}$
- Details:
 - Formulation I: $\int a_t^*(e_t, a_{t-1}) dD_t$ is an integral over e_t and a_{t-1} applying the optimal saving function in period t, i.e. $a_t^*(e_t, a_{t-1})$, thus summing up savings at the end-of-period t
 - Formulation II: $\int a_t dD_{t+1}$ is an integral over e_{t+1} and a_t directly summing up savings at the end-of-period t
 - Equivalence: The two formulations gives the same result because D_{t+1} is generated from D_t assuming saving according to $a_t^*(e_t, a_{t-1})$ (and the exogenous process for e_t)

Market clearing

• Market clearing requires

Capital:
$$K_t = \mathcal{K}_t = \int a_t dD_{t+1} = \int a_t^*(e_t, a_{t-1}) dD_t$$

Labour: $L_t = \int e_t dD_t = 1$
Goods: $Y_t = \int c_t^*(e_t, a_{t-1}) dD_t + \delta K_{t-1}$

 The labor market clears trivially, while we can leave out the goods market due to Walras's Law

Solve household problem by EGM

- Grids:
 - 1. $e_t \in \{e^1, \dots, e^{\#_e}\}$ (discretized with Tauchen and Hussey (1991))
 - 2. $a_t \in \{a^1, \ldots, a^{\#_a}\}$
- Guess: $v_{a,t+1}(e^i, a^j), \forall i, j$
- Time iteration:
 - 1. Calculate: $q_t(e^i, a^j) = \sum_{k=1}^{\#_e} \Pr[e^k | e^i] v_{a,t+1}(e^i, a^j)$
 - 2. Calculate $ilde{c}^{ij}=q_t(e^i,a^j)^{-\frac{1}{\sigma}}$ and $ilde{m}^{ij}= ilde{c}^{ij}+a^j$
 - 3. Interpolate $\{\tilde{m}^{ij}, a^j\}_{j=1}^{\#_a}$ at $m^j = (1+r_t)a^j + w_te^i$ to find $a^*(e^i, a^j)$
 - 4. Calculate $c^*(e^i, a^j) = m_t a^*(e^i, a^j)$
 - 5. Calculate $v_{a,t+1}(e^i,a^j)=(1+r)c^*(e^i,a^j)^{-\sigma}$ (use of the envelope theorem)
- Note: Any other solution method could have been used

Simulate household behavior on grid

- Initial distribution: $D_0(e^i, a^j) = \frac{\Pr[e^i]}{\#_a}$ (ergodic in e, uniform in a)
- Idea: Re-distribute mass to grid points, where optimal decisions lie
- **Update:** Calculate $D_{t+1}(e^k, a^l)$ as

$$\sum_{i=1}^{\#_e} \Pr[e^k | e^i] \sum_{j=1}^{\#_s} D_t(e^i, a^j) \omega(a^*(e^i, a^j), a^{\max\{l-1, 1\}}, a^l, a^{\min\{l+1, \#_s\}})$$

where

$$\omega(a,\underline{a},\tilde{a},\overline{a}) = 1\{a \in [\underline{a},\overline{a}]\} \begin{cases} \frac{\overline{a}-a}{\overline{a}-\overline{a}} & \text{if } a \geq \tilde{a} \\ \frac{a-a}{\overline{a}-\underline{a}} & \text{if } a < \tilde{a} \end{cases}$$

- ullet Weight: ω is a weight on each grid point calculated using linear interpolation
- Note: Any other simulation method could have been used

Definition: Stationary equilibrium

A stationary equilibrium for a given Z_{ss} is one where

- 1. Quantities K_{ss} and L_{ss} ,
- 2. prices r_{ss} and w_{ss} ,
- 3. a distribution D_{ss} over e_t and a_{t-1}
- 4. and policy functions $a_{ss}^*(e_t,a_{t-1})$ and $c_{ss}^*(e_t,a_{t-1})$

are such that

- 1. $a_{ss}^*(ullet)$ and $c_{ss}^*(ullet)$ solves the household problem with $\{r_{ss},w_{ss}\}_{k\geq t}$
- 2. $D_{\rm ss}$ is the invariant distribution implied by the household problem
- 3. Firms maximize profits, $r_{ss} = r(K_{ss}/L_{ss}, Z_{ss})$ and $w_{ss} = w(r_{ss}, Z_{ss})$
- 4. The labor market clears, i.e. $L_{ss}=\int e_t dD_{ss}=1$
- 5. The capital market clears, i.e. $K_{ss}=\int a_{ss}^*(e_t,a_{t-1})dD_{ss}$
- 6. The goods market clears, i.e. $Y_{ss} = \int c_{ss}^*(e_t, a_{t-1}) dD_{ss} + \delta K_{ss}$

Finding stationary equilibrium

- 1. Guess on r_{ss}
- 2. Calculate $w_{ss} = w(r_{ss}, Z_{ss})$
- 3. Solve the infinite horizon household problem
- 4. Simulate until convergence of D_{ss}
- 5. Calculate supply $\mathcal{K}_{ss} = \int a_{ss}^*(e_t, a_{t-1}) dD_{ss}$
- 6. Calculate demand $K_{ss} = k(r_{ss}, Z_{ss})L_{ss}$
- 7. If for some tolerance ϵ

$$|\mathcal{K}_{ss} - \mathcal{K}_{ss}| < \epsilon$$

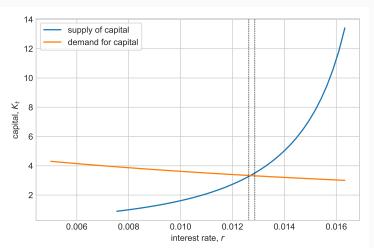
then stop, otherwise update r_{ss} appropriately and return to step 2

This is just a root-finding problem

Equilibrium interest rate

Step 1: Perform grid search

Step 2: Use standard root finder



Precautionary saving and the interest rate

- Baseline: $\sigma_e = 0.1$
 - 1. Interest rate: $r^* = 0.0127$
 - 2. Capital-output ratio: 2.92
- Higher risk: $\sigma_e = 0.2$
 - 1. Interest rate: $r^* = 0.0029$
 - 2. Capital-output ratio: 3.95
- Intuition: Saving motive \uparrow , marginal product of capital \downarrow
- Implication: Important for the »natural« interest rate!
 - **Example:** On Secular Stagnation in the Industrialized World

GE

Transition path

Definition: Transition path (to MIT shock)

A transition path for $t \in \{0, 1, 2, ...\}$, given an initial distribution D_0 and a path of Z_t , is paths of quantities K_t and L_t , prices r_t and w_t , policy functions $a_t^*(\bullet)$ and $c_t^*(\bullet)$, distributions D_t , such that for all t

- 1. $a_t^*(ullet)$ and $c_t^*(ullet)$ solve the household problem given price paths
- 2. D_t are implied by the household problem given price paths and D_0
- 3. Firms maximizes profit, $r_t = r(K_{t-1}/L_t, Z_t)$ and $w_t = w(r_t, Z_t)$
- 4. The labor market clears, i.e. $L_t = \int e_t dD_t = 1$
- 5. The capital market clears, i.e. $K_{t-1} = \int a_{t-1} dD_t$
- 6. The goods market clears, i.e. $Y_t = \int c_t^*(ullet) dD_t + \delta K_{t-1}$

MIT shock ≡ »Shock in a world without shocks«

Solving the house problem along the transition path

- 1. **Assumption:** Back at stationary equilibrium after $\mathcal T$ periods
- 2. Consequence: $v_{T+1}(e_t, a_{t-1}) = v_{ss}(e_t, a_{t-1})$
- 3. Perfect foresight price paths:

```
 \{r_{k}, w_{k}\}_{k \geq T} = \{r_{T}, w_{T}, r_{ss}, w_{ss} \dots\} 
 \{r_{k}, w_{k}\}_{k \geq T-1} = \{r_{T-1}, w_{T-1}, r_{T}, w_{T}, r_{ss}, w_{ss} \dots\} 
 \vdots 
 \{r_{k}, w_{k}\}_{k \geq 0} = \{r_{0}, w_{0}, \dots, r_{T}, w_{T}, r_{ss}, w_{ss} \dots\}
```

Relaxation-method

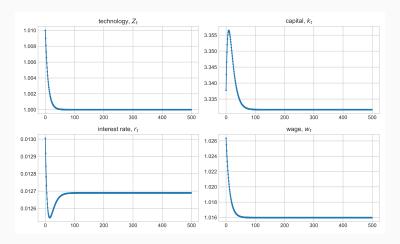
- 1. Guess on $\{r_t\}_{t=0}^{\mathcal{T}} = \{r_{ss}\}_{t=0}^{\mathcal{T}}$ (or something else)
- 2. Calculate $\{w_t\}_{t=0}^{\mathcal{T}} = \{w(r_t, Z_t)\}_{t=0}^{\mathcal{T}}$
- 3. Solve the household problem backwards along the transition path
- 4. Simulate households forward along the transition path
- 5. Calculate $\{k_t\}_{t=0}^{\mathcal{T}} = \{\int a_t^*(ullet) dD_{t-1}\}_{t=0}^{\mathcal{T}}$
- 6. Calculate $\{r_t'\}_{t=0}^{\mathcal{T}} = \{r(k_{t-1}, Z_t)\}_{t=0}^{\mathcal{T}}$
- 7. Stop if for some tolerance ϵ

$$\max_{t \in \{0,1,2,\dots,\mathcal{T}\}} |r_t - r_t'| < \epsilon$$

otherwise return to step 2 with $\{r_t\}_{t=0}^{\mathcal{T}} = \{\nu r_t + (1-\nu)r_t'\}_{t=0}^{\mathcal{T}}$

Note: Typically the relaxation parameter is $\nu=0.90$ (Kirkby, 2017)

Transition path



Remember: We also have a transition path for D_t \rightarrow we can calculate distribution of utility effects!

Sequence space method

• **Reformulation**: K_t given by initial distribution and price sequence

$$K_t = \mathcal{K}_t(\{r_s, w_s\}_{s \ge 0}, D_0))$$
$$= \int a_t^*(e_t, a_{t-1}) dD_t$$

- **Define:** $K = (K_0, K_1, ...)$ and $Z = (Z_0, Z_1, ...)$
- Transition path is, for given Z, solution for t = 0, 1, ..., to

$$H_t(\mathbf{K}, \mathbf{Z}, D_0) \equiv \mathcal{K}_t(\{r(Z_s, K_{s-1}), w(Z_s, K_{s-1})\}_{s \geq 0}, D_0) - K_t = 0$$

or in time-stacked form:

$$\boldsymbol{H}(\boldsymbol{K},\boldsymbol{Z},D_0)=\mathbf{0}$$

• Standard: $D_0 = D_{ss}$

Time-stacked form

Total differentiation implies

$$\mathbf{H}_{\mathbf{K}}d\mathbf{K} + \mathbf{H}_{\mathbf{Z}}d\mathbf{Z} = 0 \Leftrightarrow d\mathbf{K} = -\mathbf{H}_{\mathbf{K}}^{-1}\mathbf{H}_{\mathbf{Z}}d\mathbf{Z}$$

where

$$\boldsymbol{\textit{H}}_{\boldsymbol{\textit{K}}} = \left[\begin{array}{ccc} \frac{\partial \textit{H}_0}{\partial \textit{K}_0} & \frac{\partial \textit{H}_0}{\partial \textit{K}_1} & \cdots \\ \\ \frac{\partial \textit{H}_1}{\partial \textit{K}_0} & \ddots & \ddots \\ \vdots & \ddots & \ddots \end{array} \right], \, \boldsymbol{\textit{H}}_{\boldsymbol{\textit{Z}}} = \left[\begin{array}{ccc} \frac{\partial \textit{H}_0}{\partial \textit{Z}_0} & \frac{\partial \textit{H}_0}{\partial \textit{Z}_1} & \cdots \\ \\ \frac{\partial \textit{H}_1}{\partial \textit{Z}_0} & \ddots & \ddots \\ \vdots & \ddots & \ddots \end{array} \right]$$

Decomposition:
$$H_t = \mathcal{K}_t(\{r(Z_s, K_{s-1}), w(Z_s, K_{s-1})\}_{s \geq 0}, D_0) - K_t$$

$$\begin{aligned} \boldsymbol{H}_{\boldsymbol{K}} &= \mathcal{J}^{\mathcal{K},r} \mathcal{J}^{r,K} + \mathcal{J}^{\mathcal{K},w} \mathcal{J}^{w,K} - \boldsymbol{I} \\ \boldsymbol{H}_{\boldsymbol{Z}} &= \mathcal{J}^{\mathcal{K},r} \mathcal{J}^{r,Z} + \mathcal{J}^{\mathcal{K},w} \mathcal{J}^{w,Z} \end{aligned}$$

where generically

$$\mathcal{J}^{x,y} = \begin{bmatrix} \frac{\partial x_0}{\partial y_0} & \frac{\partial x_0}{\partial y_1} & \cdots \\ \frac{\partial x_1}{\partial y_0} & \ddots & \ddots \\ \vdots & \ddots & \ddots \end{bmatrix}$$

Calculating Jacobians

• Analytical:

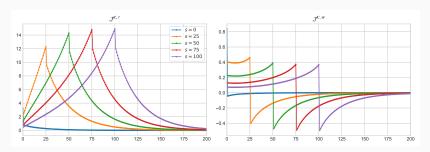
$$\begin{aligned} & \textbf{lytical:} \\ & \mathcal{J}^{r,K} = \alpha(\alpha - 1)Z_t K_t^{\alpha - 2} & \begin{bmatrix} 0 & 0 & \cdots & 0 \\ 1 & 0 & \cdots & 0 \\ \vdots & 1 & 0 & \vdots \\ 0 & 0 & \ddots & 0 \\ 0 & 0 & \cdots & 1 \end{bmatrix}, \mathcal{J}^{r,Z} = \alpha K_t^{\alpha - 1} \textbf{I} \\ & \begin{bmatrix} 0 & 0 & \cdots & 0 \\ 1 & 0 & \cdots & 0 \\ \vdots & 1 & 0 & \vdots \\ 0 & 0 & \cdots & 0 \\ \vdots & 1 & 0 & \vdots \\ 0 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 1 \end{bmatrix}, \mathcal{J}^{w,Z} = (1 - \alpha)K_t^{\alpha} \textbf{I} \end{aligned}$$

Note
$$\forall t \neq s-1: \frac{\partial r_t}{\partial \mathcal{K}_s} = \frac{\partial w_t}{\partial \mathcal{K}_s} = 0$$
 and $\forall s \neq t: \frac{\partial r_t}{\partial \mathcal{Z}_s} = \frac{\partial w_s}{\partial \mathcal{Z}_s} = 0$

- Numerical: $\mathcal{J}^{\mathcal{K},r}$ and $\mathcal{J}^{\mathcal{K},w}$
- ullet Truncation: The matrices are truncated such that they are $\mathcal{T} \times \mathcal{T}$

Interpreting Jacobians

- 1. **Along a row:** The effect on a variable in a given period of a shock in an arbitrary period
- 2. **Along a column:** The effect of a shock in a given period on a variable in an arbitrary period



Transition path after MIT shock

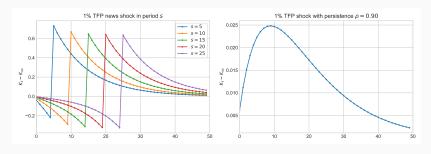
- 1. Assume we start in the stationary equilibrium
- 2. **MIT-shock:** Known path of future Z, i.e. in terms of changes from steady state $dZ = Z Z_{ss}$
- 3. Question: What happens to aggregate capital?
- 4. Answer: To a first order we have

$$G^{K,Z} \equiv \frac{dK}{dZ} = -H_K^{-1}H_Z$$

where all derivatives are **evaluated at the stationary equilibrium Additionally:**

$$\begin{aligned} \boldsymbol{G}^{r,Z} &\equiv \frac{d\boldsymbol{r}}{d\boldsymbol{Z}} = \mathcal{J}^{r,Z} + \mathcal{J}^{r,K}\boldsymbol{G}^{K,Z}, \ \boldsymbol{G}^{w,Z}\frac{d\boldsymbol{w}}{d\boldsymbol{Z}} = \mathcal{J}^{w,Z} + \mathcal{J}^{w,K}\boldsymbol{G}^{K,Z} \\ \boldsymbol{G}^{C,Z} &\equiv \frac{d\boldsymbol{C}}{d\boldsymbol{Z}} = \mathcal{J}^{C,r}\boldsymbol{G}^{r,Z} + \mathcal{J}^{C,w}\boldsymbol{G}^{w,Z}, \ \boldsymbol{G}^{Y,Z} &\equiv \frac{d\boldsymbol{Y}}{d\boldsymbol{Z}} = \mathcal{J}^{Y,Z} + \mathcal{J}^{Y,K}\boldsymbol{G}^{K,Z} \end{aligned}$$

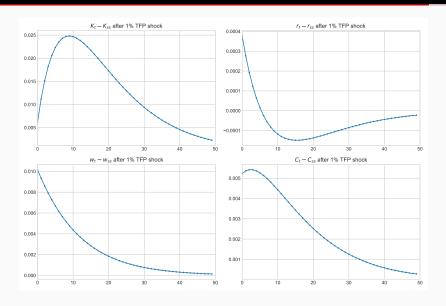
News shock vs. persistent shock



Persistent shock:
$$Z_t = (1 - \rho_Z)Z_{ss} + \rho Z_t$$
 and $Z_0 = (1 + \sigma_Z)Z_{ss}$

Note: One set of Jacobians, infinite many impulse-respones!

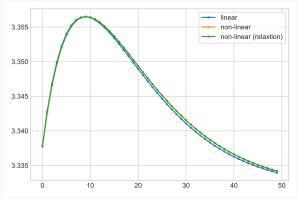
Impulse-responses



Linear vs. non-linear

• **Beyond first order approximation?** Solve full non-linear equation system using the Jacobian at the stationary equilibrium as an approximation of the true Jacobians along the transition path

• Comparison:



GE

Dynamic equilibrium

Household problem with aggregate shocks

- Aggregate shocks: Assume Z_t is a stochastic process
- Root problem: There is no longer perfect foresight wrt. r_t and w_t
- Extended problem:

$$v(e_{t}, a_{t-1}, Z_{t}, D_{t}) = \max_{c_{t}} \frac{c_{t}^{1-\sigma}}{1-\sigma} + \beta \mathbb{E}_{t} \left[v(e_{t+1}, a_{t}, Z_{t+1}, D_{t+1}) \right]$$
s.t.
$$a_{t} + c_{t} = (1 + r_{t})a_{t-1} + w_{t}e_{t}$$

$$k_{t-1} = \int a_{t-1}dD_{t}$$

$$r_{t} = r(k_{t-1}, Z_{t})$$

$$w_{t} = w(r_{t}, Z_{t})$$

$$a_{t} \geq 0$$

• **Ultimate problem:** D_t is not easy to discretize...

Approximate household problem

- Krusell-Smith idea: Approximate D_t with some selected moments, e.g. just the mean
- Approximate problem:

$$v(e_{t}, a_{t-1}, Z_{t}, k_{t-1}) = \max_{c_{t}} \frac{c_{t}^{1-\sigma}}{1-\sigma} + \beta \mathbb{E}_{t} \left[v(e_{t+1}, a_{t}, Z_{t+1}, k_{t}) \right]$$
s.t.
$$a_{t} + c_{t} = (1 + r_{t})a_{t-1} + w_{t}e_{t}$$

$$r_{t} = r(k_{t-1}, Z_{t})$$

$$w_{t} = w(r_{t}, Z_{t})$$

$$k_{t} = PLM(k_{t-1}, Z_{t})$$

$$a_{t} \geq 0$$

where $PLM(k_{t-1}, Z_t)$ is the **perceived law of motion**

For example: $PLM(k_{t-1}, Z_t) = \beta_{Z_t} + \alpha_{Z_t} \log k_{t-1}$

Definition: Dynamic equilibrium

An **(approximate) dynamic equilibrium** is a PLM, policy functions $a^*(\bullet)$ and $c^*(\bullet)$, and paths of quantities K_t and L_t , prices r_t and w_t , distributions D_t such that for all t

- 1. $a^*(\bullet)$ and $c^*(\bullet)$ solve the household problem given the PLM
- 2. D_t is implied by the household problem
- 3. Firms profit maximize $r_t = r(K_{t-1}/L_t, Z_t)$ and $w_t = w(r_t, Z_t)$
- 4. The labor market clears, i.e. $L_t = \int e_t dD_t = 1$
- 5. The capital market clears, i.e. $K_t = \int a^*(e_t, a_{t-1}) dD_t$
- 6. The goods market clears, i.e. $Y_t = \int c^*(e_t, a_{t-1}) dD_t + \delta K_{t-1}$
- 7. $PLM(k_{t-1}, Z_t)$ does not imply systematic expectations errors

Note: When $Z_t = Z_{ss} \forall Z_t$ the dynamic equilibrium does *not* converge to the stationary equilibrium unless the households know Z_t is actually not stochastic.

Finding dynamic equilibrium

- 1. Guess on the $PLM(k_{t-1}, Z_t)$
- 2. Solve the household problem
- 3. Simulate a path of Z_t and D_t and thus k_t
- 4. Compare simulated behavior with the $PLM(k_{t-1}, Z_t)$ Stop if »good enough « otherwise update $PLM(k_{t-1}, Z_t)$ and return to step 2

Terminology:

- 1. The Krusell-Smith method is a global solution method
- The newest local solution methods rely on linearization of the aggregate dynamics, but solve for the full non-linear stationary equilibrium

Connection to sequence space

- Insights in Auclert et al. (2020b):
 - 1. In the limit where the shock variance disappears the dynamic equilibrium path converge to the stationary equilibrium.
 - 2. In the limit where the shock variance disappears the transition path to the MIT shock around the stationary equilibrium is the same as the impulse-response in the dynamic equilibrium.
- **Implications:** From the transition paths first order approximations of variances and co-variances of all variables can be calculated.
- Estimation: Parameters affecting
 - 1. The stationary equilibrium are computationally *very costly*
 - 2. Only the Jacobians are computationally rather costly
 - 3. Only affecting e.g. the shock process are computationally cheap

Summary

Summary

- Dynamic programming is needed to solve empirically realistic consumption-saving models
- The buffer-stock consumption model, and it's two asset cousin, can fit central stylized facts
 - 1. High MPC
 - Responses to expected windfalls
 - 3. Households with more volatile income save more
 - 4. Consumption tracks income over the life-cycle
- Advances in micro-data, numerical methods and computational power are leading to new discoveries
- EGM is a powerful solution method (and can be generalized)
- ullet Realistic consumption-saving behavior can be included in **general** equilibrium models o welfare analysis with full distributional effects

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