72320 Roversystemtechnik Summer Semester 2021

Phase 0/A-Study of a Rover Mission on the surface of the Jupiter moon: Europa: INSPIRE

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Symbols

a nm Constant for the Geometry of a Porous Media

 $T_{
m Surface}$ K Surface Temperature on Europa

 ϵ - Emissivity

 $\rho_{\rm Ice}$ $\frac{\text{kg}}{m^3}$ Inner Encoder Ring Diameter

Abbreviations

PCDU Power Control and Distribution Unit

2D Two Dimensional3D Three Dimensional

IMU Inertial Measurement Unit

IRS Institute of space Systems at the University of Stuttgart

ESA European Space Agency

 ${\bf SPENVIS} \quad {\bf SPace} \ {\bf ENVironment} \ {\bf Information} \ {\bf System}$

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The Mission

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1.2 Mission Scenario

Operation

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Subsystems

Rover

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3.1

3.2 Structure and Mechanics

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3.3 Communications and Command and Data-Handling

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3.4 Payload

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3.5 Thermal Control

3.6 Electrical Power System

3.7. RADIATION 5

3.7 Radiation

Compared to the radiation environment near Earth the radiation environment near Jupiter is multiple times stronger. It has the highest radiation levels of any planet in our solar systems [Platzhalter]. In order to survive these harsh environmental conditions, special emphasis must be placed on the radiation protection. In Figure 3.1, the average trapped proton and electron fluxes on Europa's orbit around Jupiter are shown in comparison to the outer Van Allen radiation belt around Earth. However, in contrast to the Van Allen radiation belt, the duration within the radiation environment on Europa cannot be minimised and the rover has to be designed to withstand the entire mission duration of 30 days.

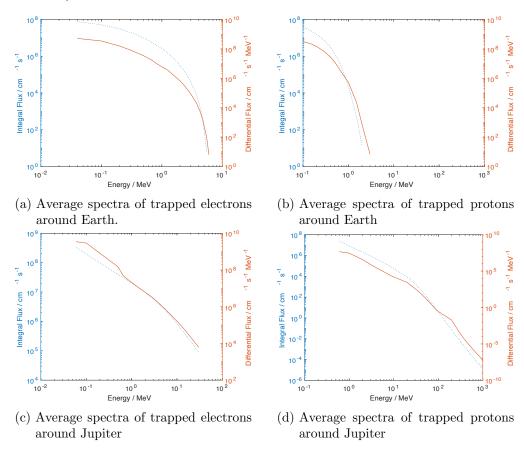


Figure 3.1: Average trapped proton and electron fluxes on an orbit around earth at 25,000 km, through the outer Van Allen radiation belt, and on Europa's orbit around Jupiter.

In oder to design and evaluate different radiation protection approaches, different calculations have to be performed. For this purpose the ESA SPace ENVironment Information System (SPENVIS) is used [**Platzhalter**]. All calculations and figures in section 3.7 are performed with SPENVIS unless otherwise stated.

Lander System

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4.1 Storage Configuration

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Trade-Offs

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Risk and Technology Assessment

6.1 Risk Assessment

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6.1.1 Risk Assessment Subsection

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6.2 Technology Assessment

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6.2.1 Acceleration segment

Appendix

A Appendix 1

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B Appendix 2