#### 72320 Roversystemtechnik Summer Semester 2021

#### Phase 0/A-Study of a Rover Mission on the surface of the Jupiter moon: Europa: INSPIRE

Saskia Sütterlin Denis Acker Krobinian Kasper Daniel Bölke Nicolas Probst Christian Korn

Supervisor: Moritz Nitz M.Sc.

Patrick Winterhalder M.Sc.

University of Stuttgart Institute of Space Systems Prof. Dr. Sabine Klinkner

18.07.2021

# **Symbols**

a nm Constant for the Geometry of a Porous Media

 $T_{
m Surface}$  K Surface Temperature on Europa

 $\epsilon$  - Emissivity

 $ho_{
m Ice}$   $rac{{
m kg}}{m^3}$  Inner Encoder Ring Diameter

### Abbreviations

PCDU Power Control and Distribution Unit

2D Two Dimensional3D Three Dimensional

IMU Inertial Measurement Unit

IRS Institute of space Systems at the University of Stuttgart

ESA European Space Agency

 ${\bf SPENVIS} \quad {\bf SPace} \ {\bf ENVironment} \ {\bf Information} \ {\bf System}$ 

## Contents

1	The	e Mission	1
	1.1	Mission Inspiration	1
	1.2	Mission Scenario	1
2	Оре	eration	2
3	Sub	osystems	3
	3.1	Rover	3
	3.2	Structure and Mechanics	3
	3.3	Communications and Command and Data-Handling	3
	3.4	Payload	3
	3.5	Thermal Control	3
	3.6	Electrical Power System	4
		3.6.1 EPS Requirements	4
		3.6.2 EPS Budget and Overview	4
		3.6.3 EPS Power Control and Distribution	4
		3.6.4 Energy Source	4
		3.6.5 Energy Storage	4
	3.7	Radiation	5
4	Lan	nder System	7
	4.1	Storage Configuration	7
	4.2	Depolyment Strategy	7
K	Тио	do Offe	0

iv CONTENTS

6	Risk and Technology Assessment					
	6.1	Risk Assessment	9			
		6.1.1 Risk Assessment Subsection	9			
	6.2	Technology Assessment	9			
		6.2.1 Acceleration segment	9			
Aı	ppen	dix 1	0			
	A	Appendix 1	0			
	В	Appendix 2	0			

# List of Figures

3.1	Bildbeschreibung	4
3.2	Average trapped proton and electron fluxes on an orbit around earth at 25,000 km, through the outer Van Allen radiation belt,	
	and on Europa's orbit around Jupiter	F

## List of Tables

## The Mission

1.1 Mission Inspiration

. . . .

1.2 Mission Scenario

# Operation

....

## Subsystems

3.1 Rover

3.2 Structure and Mechanics

3.3 Communications and Command and Data-Handling

3.4 Payload

3.5 Thermal Control

...

#### 3.6 Electrical Power System

The EPS (Electrical Power System) is the subsystem responsible for the electrical power supply of INSPIRE. It consists of four funadmental parts, which are the energy source, the PCDU unit (Power Control and Distribution) and the Energy Storage as well as the rover subsystems as the consumers.

#### 3.6.1 EPS Budget and Overview

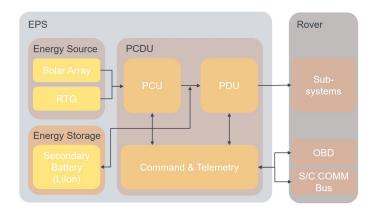


Figure 3.1: Functional Flow Chart for the EPS Subsystem

#### 3.6.2 EPS Power Control and Distribution

#### 3.6.3 Energy Source

#### 3.6.4 Energy Storage

3.7. RADIATION 5

#### 3.7 Radiation

Compared to the radiation environment near Earth the radiation environment near Jupiter is multiple times stronger. It has the highest radiation levels of any planet in our solar systems [Platzhalter]. In order to survive these harsh environmental conditions, special emphasis must be placed on the radiation protection. In Figure 3.2, the average trapped proton and electron fluxes on Europa's orbit around Jupiter are shown in comparison to the outer Van Allen radiation belt around Earth. However, in contrast to the Van Allen radiation belt, the duration within the radiation environment on Europa cannot be minimised and the rover has to be designed to withstand the entire mission duration of 30 days.

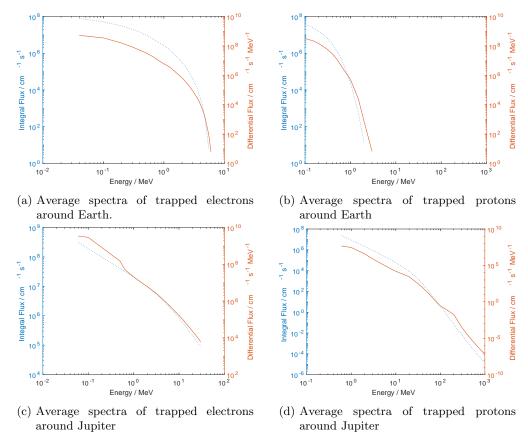


Figure 3.2: Average trapped proton and electron fluxes on an orbit around earth at 25,000 km, through the outer Van Allen radiation belt, and on Europa's orbit around Jupiter.

In oder to design and evaluate different radiation protection approaches, different calculations have to be performed. For this purpose the ESA SPace ENVironment Information System (SPENVIS) is used [**Platzhalter**]. All calculations and figures in section 3.7 are performed with SPENVIS unless otherwise stated.

# Lander System

....

4.1 Storage Configuration

....

4.2 Depolyment Strategy

.... Test 123

Trade-Offs

....

## Risk and Technology Assessment

6.1 Risk Assessment

....

.....

6.1.1 Risk Assessment Subsection

...

6.2 Technology Assessment

. . . .

6.2.1 Acceleration segment

...

# Appendix

A Appendix 1

...

B Appendix 2

...