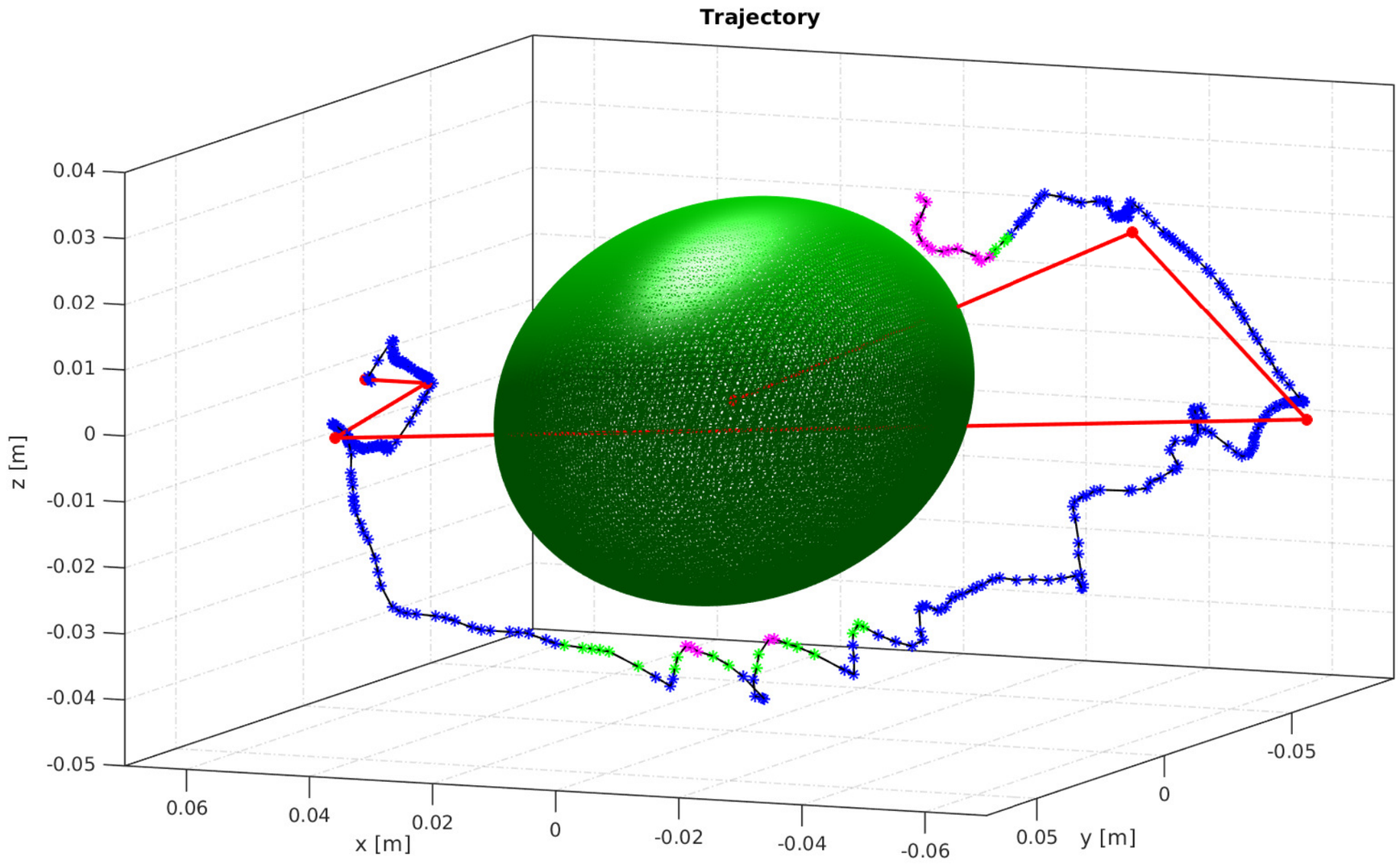
Trajectory
0.04
0.03
0.02
0.01
0
-0.01
-0.02
-0.03
-0.04
-0.05
z [m]
0.06
0.04
0.02
0
-0.02
-0.04
-0.06
x [m]
0.05
0
-0.05
y [m]