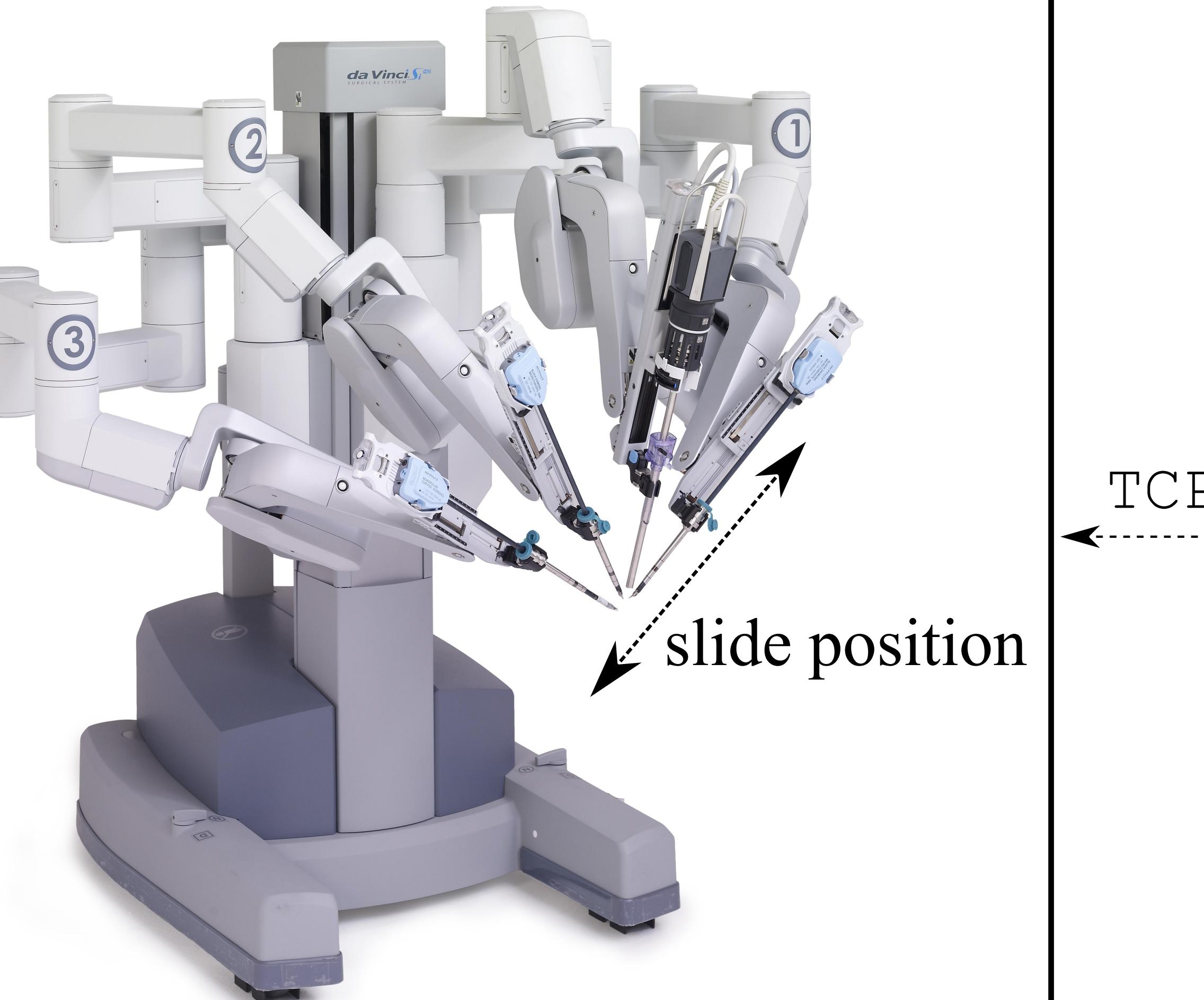


Da Vinci Robot



TCP / IP



Laptop

```
(1) $ roscore  
...  
...  
...  
(2) $ roslaunch davinci_driver davinci_driver.launch  
...  
...  
...  
...  
...  
...  
...  
(3) $ python run_controllers.py  
...  
...  
...  
...  
(5) $ rostopic echo joint_states/position[6]  
...  
...
```