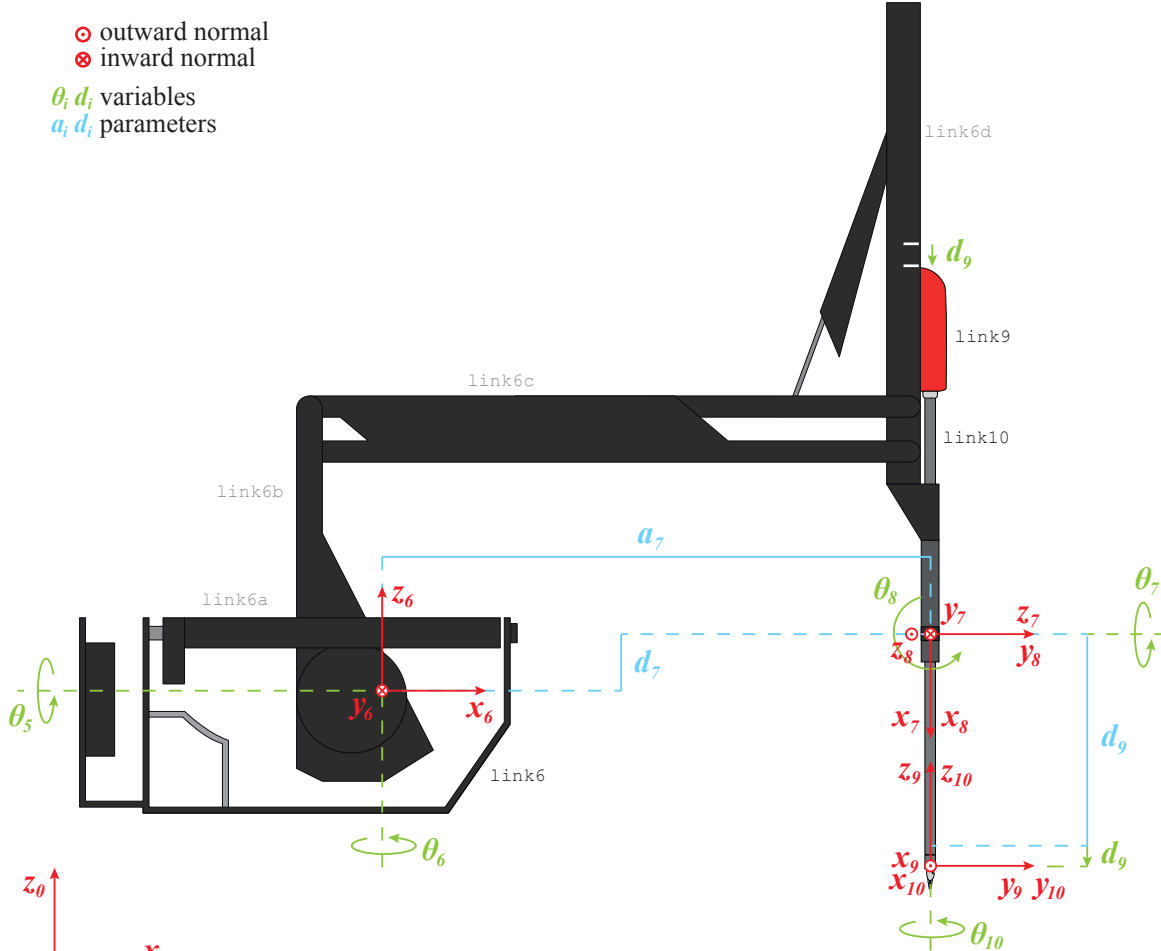


⊙ outward normal
⊗ inward normal

θ_i d_i variables

a_i d_i parameters



side view

front view

