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# **SAXS Documentation**

***Release 0.3.0***

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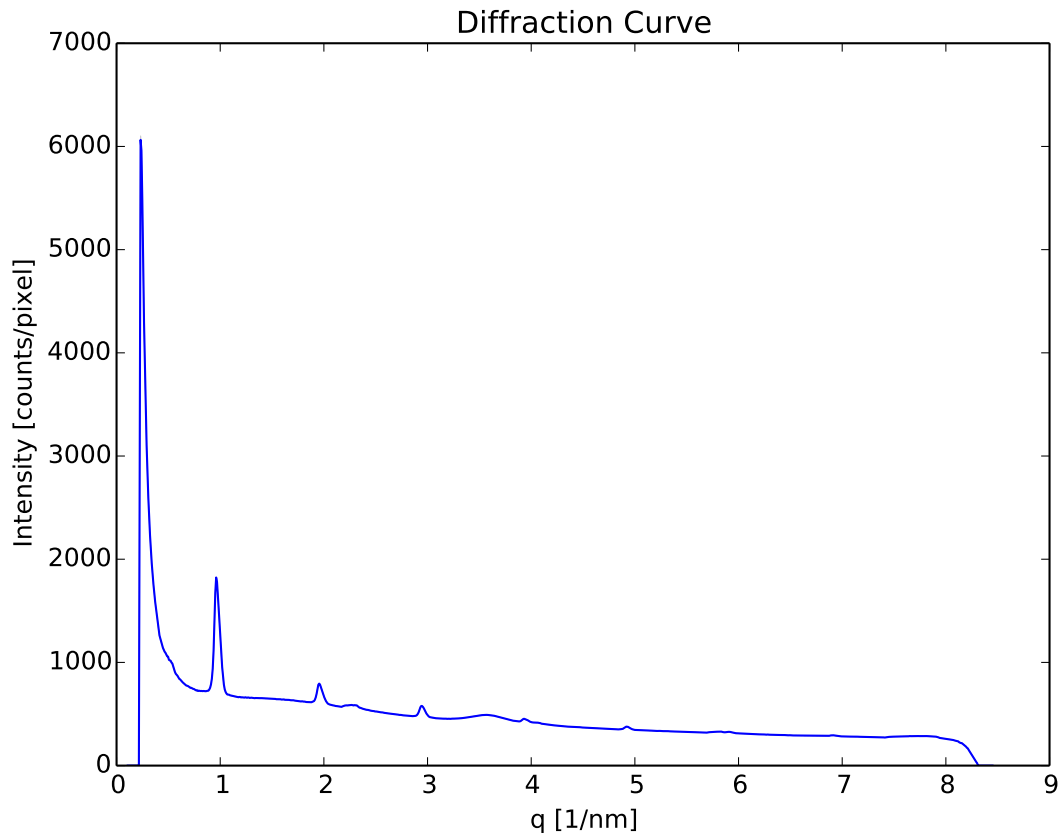


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The SAXS python package implements analysis tools for Small Angle X-Ray Scattering (SAXS) data analysis. The first and most important one is to efficiently integrate 2d sensor data to an angle dependent diffraction curve.



The SAXS module consists of a Python library and 3 command line tools: *The Saxsdog*, *Plotchi* and *The Converter*



## INSTALL

The SAXS Package is distributed as a Python package. So in order to use it, you need a Python system installed. It depends on following Python modules that don't come with the standard Python:

```
numpy scipy matplotlib jsonschema bitarray watchdog sphinxcontrib-programoutput
```

they are all available through “pip” so the command:

```
>>pip install numpy scipy matplotlib jsonschema bitarray watchdog sphinxcontrib-programoutput
```

Should get all the modules. For Windows, use the Anaconda Python distribution which includes pip.

The code can be obtained on github: <https://github.com/ChristianMeisenbichler/SAXS> where you would also find a “Download Zip” button. After unpacking or cloning with git you end up with a directory called “SAXS” containing the files. Go there, and type into the command line:

```
python setup.py install
```

This installs the Python module where it is found by Python, creates the command line tools and installs them on the system. Where that is, depends on the Python installation.





## THE TOOLS

### 2.1 The Saxsdog

The saxsdog is a script that converts directories with images to curves. It can use multiple threads and watch the file system for changes.

For Help on the usage type:

```
$ saxsdog --help
Usage: saxsdog [options] directory/to/watch

Options:
  -h, --help                Show this help message and exit.
  -c FILE, --calibration=FILE
                             Path to calibration file (JSON).
  -t THREADS, --threads=THREADS
                             Number of concurrent threads.
  -m, --plotmonitor         Show a live updating plot window.
  -w, --watch               Watch directory for changes, using file system events
                             recursively for all sub directories.
  -r, --resume              Skip files that are already converted.
  -o OUTDIR, --out=OUTDIR   Specify output directory. Default is './out'.
  -i, --inplace             Files are written, in place, in the directory of the
                             image.
  -s, --svg                 Write plot to svg file.
  -p, --png                 Write png of original.
  -P, --profile             Make a time Profile and print it.
  -S, --silent              Less output.
  -n, --nowalk              Don't scan for files already there, only watch file
                             system if -w flag is given.
  -D, --walkdirinthreads    Search all directories in parallel process.
```

The calibration file must be a valid *root*

### 2.2 The Converter

The converter extracts information from the calibration.txt generated by fit2d and adds them to a SAXS.calibration configuration file. (*root*)

```
$ saxsconverter --help
Usage: saxsconverter [options] calibration.txt ouput.json
```

```
Options:
  -h, --help                show this help message and exit
```

```
-t FILE, --template=FILE
                        Path to calibration file which serves as template.
```

If there is a target file and it is a valid *root*, the parsed values are added or updated in place.

## 2.3 Plotchi

The tool “plotchi” plots a list of “.chi”-files:

```
$ plotchi --help
Usage: plotchi [options] CHIFILE [List of more ".chi" files]

Options:
  -h, --help                show this help message and exit
  -o FILE, --out=FILE       Write the plot to FILE. The format is derived from the
                             suffix, e.g. '.svg', '.pdf'.
  -c, --compare              Compare datasets to first one.
  -l, --log                  Use log scale.
  -n, --no-legend            Hide legend.
  -t TITLE, --title=TITLE   Give plot title.
  -s N, --skip=N             Skip first N points.
  -k N, --clip=N             Clip last N points.
  -x TYPE, --xaxisistype=TYPE
                             Select type of X axis scale, might be
                             [linear|log|symlog]
  -y TYPE, --yaxisistype=TYPE
                             Select type of Y axis scale, might be
                             [linear|log|symlog]
```

## THE CALIBRATION FILE

The `SAXS.calibration` class and the `saxsdog` tool accept a input file with the calibration data. This input file is written as a JSON file. This is a common syntax to express structured data as text. You might want to read a bit about it before moving on.

### 3.1 Calibration file Reference

The ‘\*’ signifies a required Field.

The SAXS configuration file specifies the parameters of a SAXS sensor calibration. It is written in the JSON format which governs the general syntax.

**Type** object

**Contains** *Title*, *Tilt\**, *BeamCenter\**, *DedectorDistanceMM\**, *Imagesize\**, *MaskFile\**, *Oversampling\**, *PixelSizeMicroM\**, *PixelPerRadialElement\**, *Wavelength\**, *PolarizationCorrection*

**Required** True

**JSON Path** #

Example JSON:

```
{
  "PixelSizeMicroM": [
    172.0
  ],
  "Imagesize": [
    1043,
    981
  ],
  "PixelPerRadialElement": 1,
  "Tilt": {
    "TiltRotDeg": 0,
    "TiltAngleDeg": 0
  },
  "MaskFile": "AAA_integ.msk",
  "Oversampling": 3,
  "Wavelength": 1.54,
  "BeamCenter": [
    808.37,
    387.772
  ],
  "DedectorDistanceMM": 1031.657
}
```

#### 3.1.1 Title

**Type** string

**Required** False

**JSON Path** # [*Title*]

Example JSON:

```
{"Title": ""}
```

### 3.1.2 Tilt

The sensor, usually is not perfectly perpendicular to the ray direction. The tilt angle can be specified by giving the following parameters.

**Type** object

**Contains** *TiltRotDeg*\*, *TiltAngleDeg*\*

**Required** True

**JSON Path** # [*Tilt*]

Example JSON:

```
{"Tilt": {"TiltRotDeg": 0, "TiltAngleDeg": 0}}
```

### 3.1.3 TiltRotDeg

This gives the angle of the tilt direction.

**Type** number in degree

**Required** True

**Default** 0

**JSON Path** # [*Tilt*][*TiltRotDeg*]

Example JSON:

```
{"TiltRotDeg": 0}
```

### 3.1.4 TiltAngleDeg

This gives the angle between the ray direction and the normal to the sensor plane.

**Type** number in degree

**Required** True

**Default** 0

**JSON Path** # [*Tilt*][*TiltAngleDeg*]

Example JSON:

```
{"TiltAngleDeg": 0}
```

### 3.1.5 BeamCenter

Gives the beam center in pixel coordinates.

**Type** array(2) items: number number

**Required** True

**Default** [808.37, 387.772]

**JSON Path** # ['*BeamCenter*']

Example JSON:

```
{"BeamCenter": [808.37, 387.772]}
```

### 3.1.6 DedectorDistanceMM

Distance between diffraction center and sensor.

**Type** number in Millimeters

**Required** True

**Default** 1031.657

**JSON Path** # ['*DedectorDistanceMM*']

Example JSON:

```
{"DedectorDistanceMM": 1031.657}
```

### 3.1.7 Imagesize

Size of sensor image in pixel.

**Type** array(2) items: number number

**Required** True

**Default** [1043, 981]

**JSON Path** # ['*Imagesize*']

Example JSON:

```
{"Imagesize": [1043, 981]}
```

### 3.1.8 MaskFile

Path of Maskfile

**Type** string

**Required** True

**Default** AAA\_integ.msk

**JSON Path** # ['*MaskFile*']

Example JSON:

```
{"MaskFile": "AAA_integ.msk"}
```

### 3.1.9 Oversampling

Oversampling factor for radial integration. The higher, the longer the setup but the higher the accuracy. More than 3 is probably overkill.

**Type** number

**Required** True

**Default** 3

**JSON Path** # ['*Oversampling*']

Example JSON:

```
{"Oversampling": 3}
```

### 3.1.10 PixelSizeMicroM

The pixel size on the sensor.

**Type** array(2) items: number

**Required** True

**Default** [172.0]

**JSON Path** # ['*PixelSizeMicroM*']

Example JSON:

```
{"PixelSizeMicroM": [172.0]}
```

### 3.1.11 PixelPerRadialElement

Expresses the width of a radial step in terms of pixels. '1' means  $\delta R \approx 1$  *PixelSizeMicroM*.

**Type** number

**Required** True

**Default** 1

**JSON Path** # ['*PixelPerRadialElement*']

Example JSON:

```
{"PixelPerRadialElement": 1}
```

### 3.1.12 Wavelength

Refined wavelength.

**Type** number in Angstrom

**Required** True

**Default** 1.54

**JSON Path** # ['*Wavelength*']

Example JSON:

```
{"Wavelength": 1.54}
```

### 3.1.13 PolarizationCorrection

The scattering direction is dependent on the light polarization. This may be accounted for with the polarization correction.

**Type** object

**Contains** *Fraction*\*, *Angle*\*

**Required** False

**Default** OrderedDict([(u'Fraction', 0.95), (u'Angle', 0)])

**JSON Path** # ['*PolarizationCorrection*']

Example JSON:

```
{"PolarizationCorrection": {"Angle": 0.0, "Fraction": 0.95}}
```

### 3.1.14 Fraction

Fraction of light polarized in the given (*Angle*) direction.

**Type** number

**Required** True

**Default** 0.95

**JSON Path** # ['*PolarizationCorrection*']['*Fraction*']

Example JSON:

```
{"Fraction": 0.95}
```

### 3.1.15 Angle

Angle of the polarization plane.

**Type** number in degree

**Required** True

**Default** 0.0

**JSON Path** # ['*PolarizationCorrection*']['*Angle*']

Example JSON:

```
{"Angle": 0.0}
```





## THE TECHNOLOGY

### 4.1 Integration as Matrix-Vector Multiplication

Every SAXS image  $\mathbf{p}$  is a list of pixels that have an intensity value. This 2d array might as well be addressed as a vector with all the pixels addressable with one index  $\mathbf{p}_i$ .

The integration over pixels that are within a certain radial interval is in any case a weighted sum of some of the pixels.

This weighted sum is a scalar product with another vector containing the weight factors. As only the pixels in a radius interval are counted, most of these factors are 0.

$$r = \mathbf{c} \cdot \mathbf{p}$$

As we intend to do all the radial intervals at once, we write it as a matrix vector product.

$$\mathbf{r} = \mathbf{X} \cdot \mathbf{p}$$

The columns are the weight factors for the  $i^{th}$  radial element. Rearranged in the order of the image, this looks like the ring element relevant for the radial Point.

This matrix would be quite big as it has the dimensions  $\text{len}(\mathbf{r}) \cdot \text{len}(\mathbf{p})$ . Fortunately most of the entries are 0 and we can use a sparse matrix representation which uses only about  $\sim \text{len}(\mathbf{p})$  of memory, as every pixel is counted only once, or, as we will see, about once.

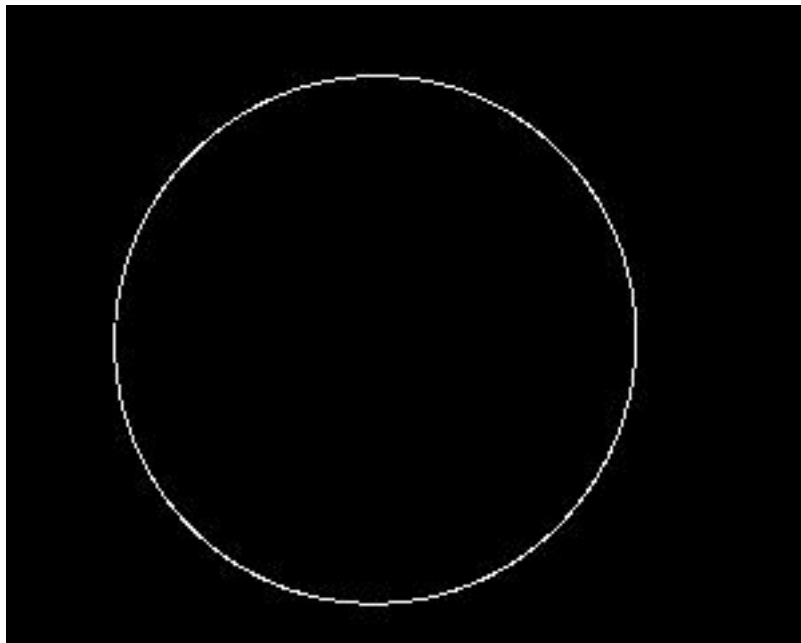


Figure 4.1: The vector  $\mathbf{c}$  displayed as image.

Figure *CircleNoAA* Scows the data of such a matrix column.

## 4.2 Oversampling

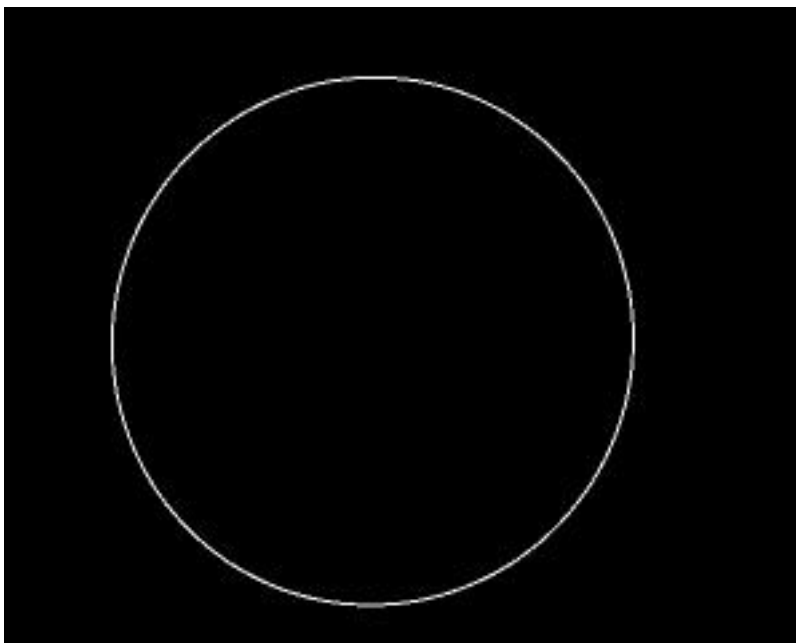


Figure 4.2: Ring with antialiasing / oversampling.

A pixel might lie on the border of two radial intervals, making it unclear to which one it should be added. By only choosing the nearest one, one may get artifacts in the resulting curve especially when only few pixels contribute. So, how could we calculate to which fraction a pixel should account to one radial interval?

The idea here is to use an algorithm comparable to antialiasing in computer graphics. We will divide a much larger picture into the radial intervals and downsample it to the real pixels. Which results in nicely balanced factors for the border pixels that add up nicely over joining intervals such that the intensity is conserved. If one looks closer at image [Ring with antialiasing / oversampling](#), one sees that the ring has soft edges. Quite as it would have through antialiasing.

## 4.3 The Geometry

The plane of the sensor is not perfectly normal to the beam. So in order to calculate which pixel is on which cone in the diffracted light, we need to express the geometry somehow.

Every pixel has the polar coordinates  $r, \phi$  with the projected diffraction center in the origin. For each pixel (P) the triangle S,C,P (Sample, Center, Pixel,  $\theta, \beta, \gamma$ ) can be fully expressed with the law of cosines.

$l$  is the distance the light travels from the diffraction center to the sensor.

$$l^2 = d^2 + r^2 - 2dr \cos(\pi/2 + \alpha)$$

$r$  is the radial coordinate of the pixel P.

$$r^2 = l^2 + d^2 - 2ld \cos(\theta)$$

from these two formulas the diffraction angle (here)  $\theta$  can be computed.

$$\theta = \arccos(-r^2 - l^2 - d^2 / 2ld)$$

$\alpha$  comes from the following relation in figure [Angle between two planes](#).

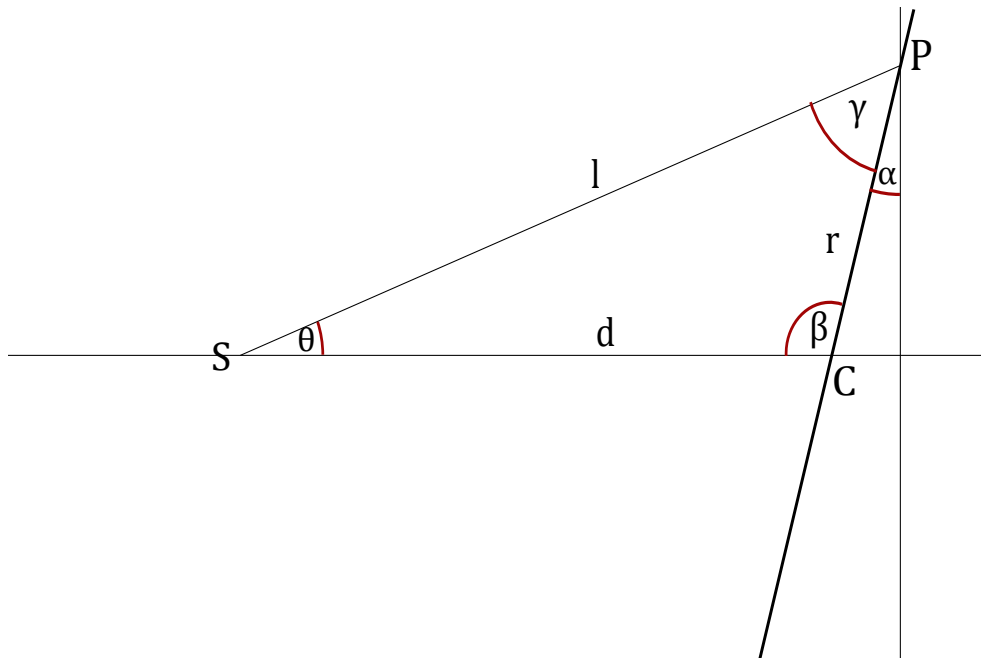


Figure 4.3: The SCP triangle.

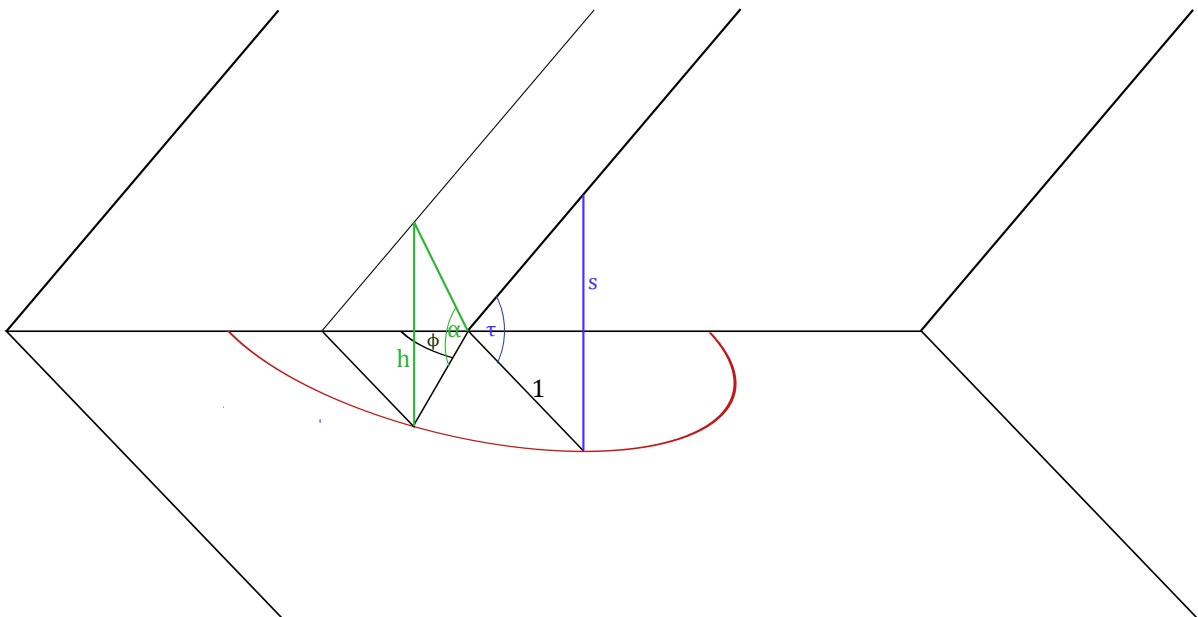


Figure 4.4: Angle between two planes.

The angle between the sensor plane and the normal plane to the ray is given by  $\tau$ . The slope  $s$  derived from  $\tau$  is

$$s = \sin(\tau)$$

On the (red) unit circle in the plane of the sensor the distance to the plane normal to the ray is expressed as

$$h = \sin(\phi)s$$

The angle  $\alpha$  is therefore:

$$\alpha = \arcsin(\sin(\tau)\sin(\phi))$$

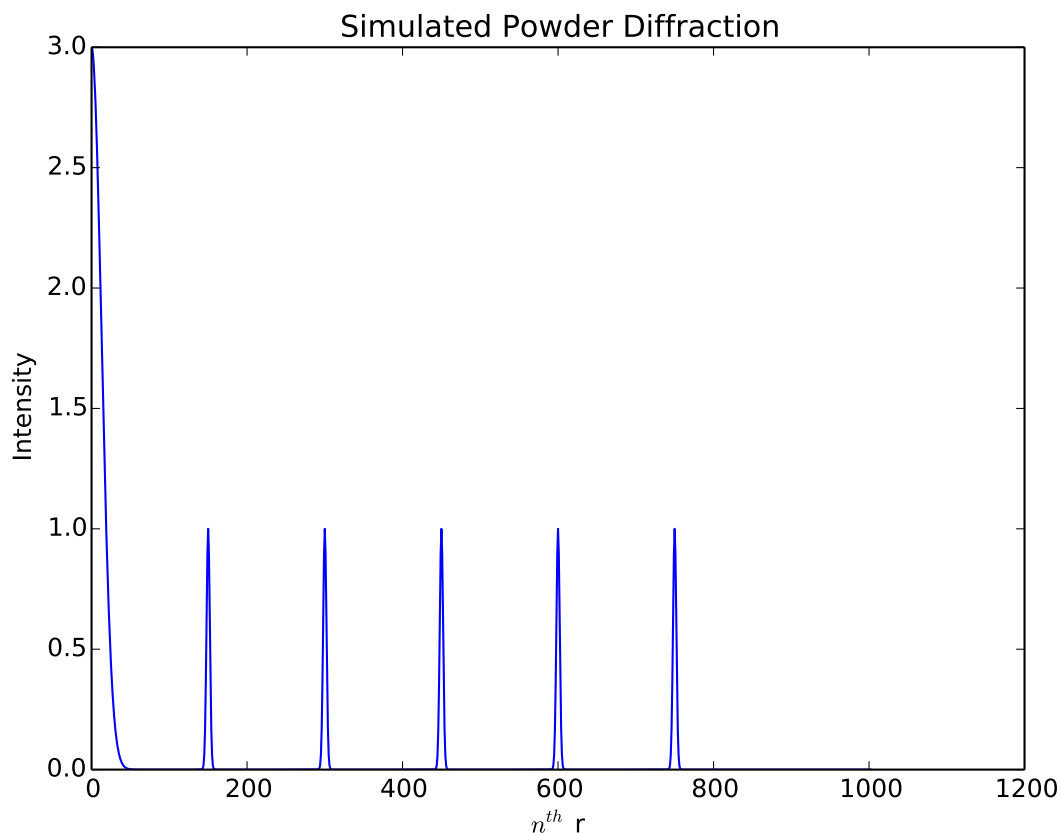
in python code this is `SAXS.calc_theta()`:

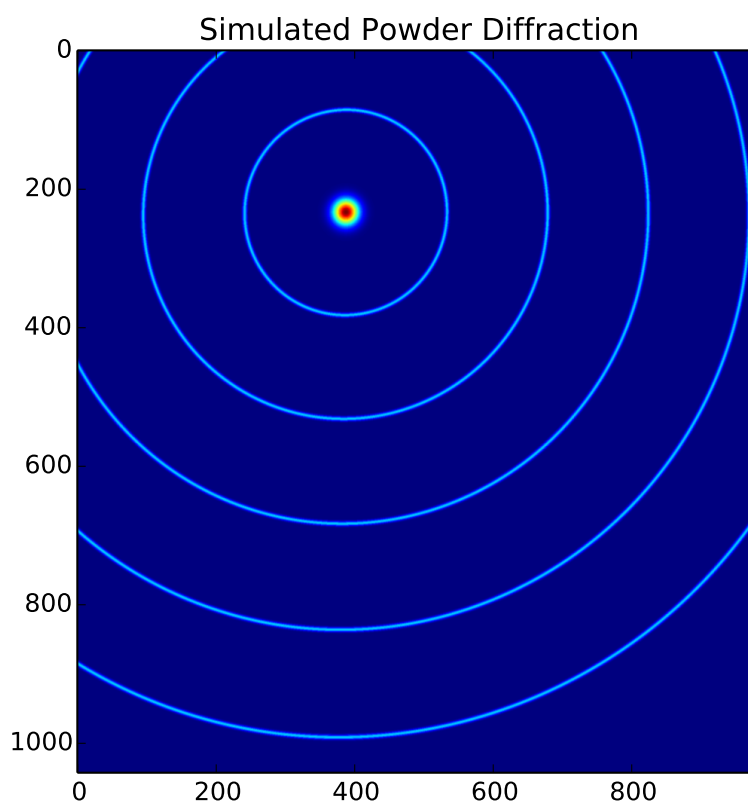
```
def calc_theta(r, theta, d, tilt, tilt_dir):  
    alpha = np.arcsin(np.sin(tilt) * np.sin(theta + tilt_dir))  
    lsquared = d**2 + r**2 - 2*d*r*np.cos(np.pi/2 + alpha)  
    return np.arccos(-(r**2 - lsquared - d**2) / (2*np.sqrt(lsquared)*d))
```

This angle  $\theta$  then is calculated for every sub pixel in the sensor. This number then can be rescaled and rounded to the nearest integer in order to get unique integer labels for all the pixels. This labels are the index of the radial interval.

### 4.3.1 Tilt Angle Correction Test

To check if the tilt angle correction is working, lets create some fake calibration data, with the following peaks in the diffraction curve:





This was done with this configuration file:

```
{
  "PixelPerRadialElement": 1,
  "Imagesize": [
    1043,
    981
  ],
  "Tilt": {
    "TiltAngleDeg": -10,
    "TiltRotDeg": 73.569
  },
  "MaskFile": "emptymask.tif",
  "PixelSizeMicroM": [
    172.0,
    172.0
  ],
  "Wavelength": 1.54,
  "DedectorDistanceMM": 1031.657,
  "BeamCenter": [
    808.37,
    387.772
  ],
  "Oversampling": 2
}
```

Which amounts to a large tilt, lets see what Fit2d makes of it

```
INFO: SOLUTION 2
INFO: Best fit beam centre (X/Y mm) = 66.78356 138.9544
INFO: Best fit beam centre (X/Y pixels) = 388.2765 807.8745
INFO: Cone 1 best fit 2 theta angle (degrees) = 1.392646
```

```
INFO: Cone 2 best fit 2 theta angle (degrees) = 2.780810
INFO: Cone 3 best fit 2 theta angle (degrees) = 4.168858
INFO: Cone 4 best fit 2 theta angle (degrees) = 5.556975
INFO: Cone 5 best fit 2 theta angle (degrees) = 6.944765
INFO: Best fit angle of tilt plane rotation (degrees) = 73.59509
INFO: Best fit angle of tilt (degrees) = -10.00601
INFO: Estimated coordinate radial position error (mm) = 0.7136476E-02
INFO: Estimated coordinate radial position error (X pixels) = 0.4149114E-01
```

Seems OK.

## 4.4 Polarization Correction

The polarization correction is expected to be small at small angles, but it is deemed important.

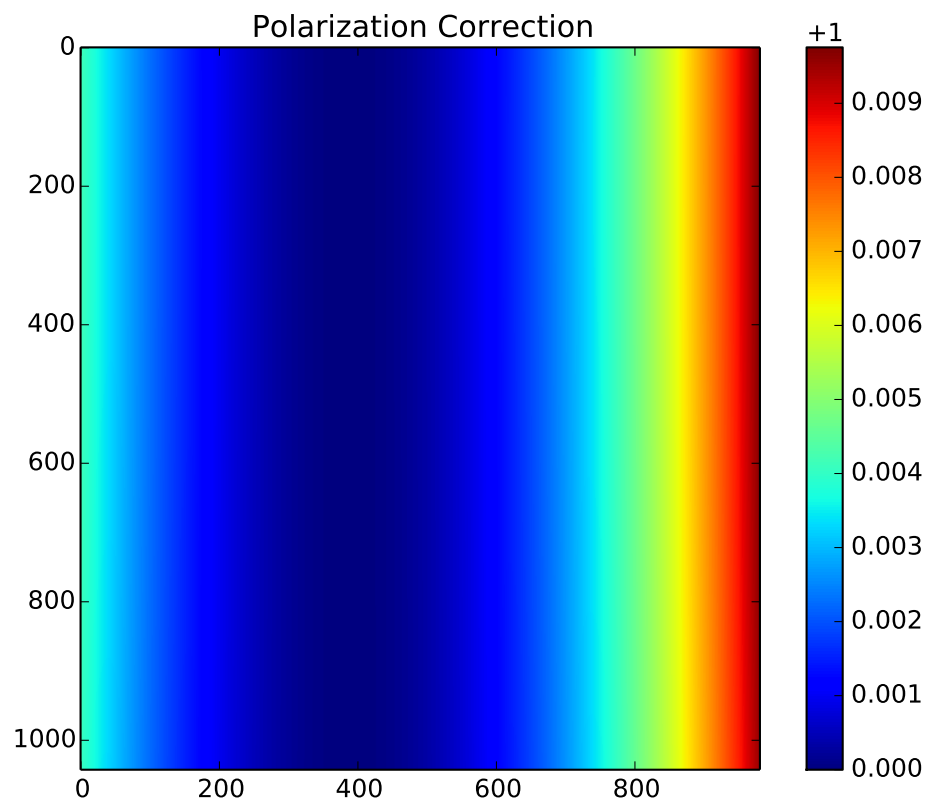
$$I_{cor} = I_j [P(1 - (\sin(\phi)\sin(2\theta))^2)(1 - P)(1 - (\cos(\phi)\sin(2\theta))^2)]$$

where  $\phi$  is the azimuthal angle on the detector surface (defined here clockwise, 0 at 12 o'clock)  $2\theta$  the scattering angle, and  $P$  the fraction of incident radiation polarized in the horizontal plane (azimuthal angle of  $90^\circ$ ) The polarization correction is configured by two parameters in *PolarizationCorrection*. Its factors are included in the integration matrix (operator).

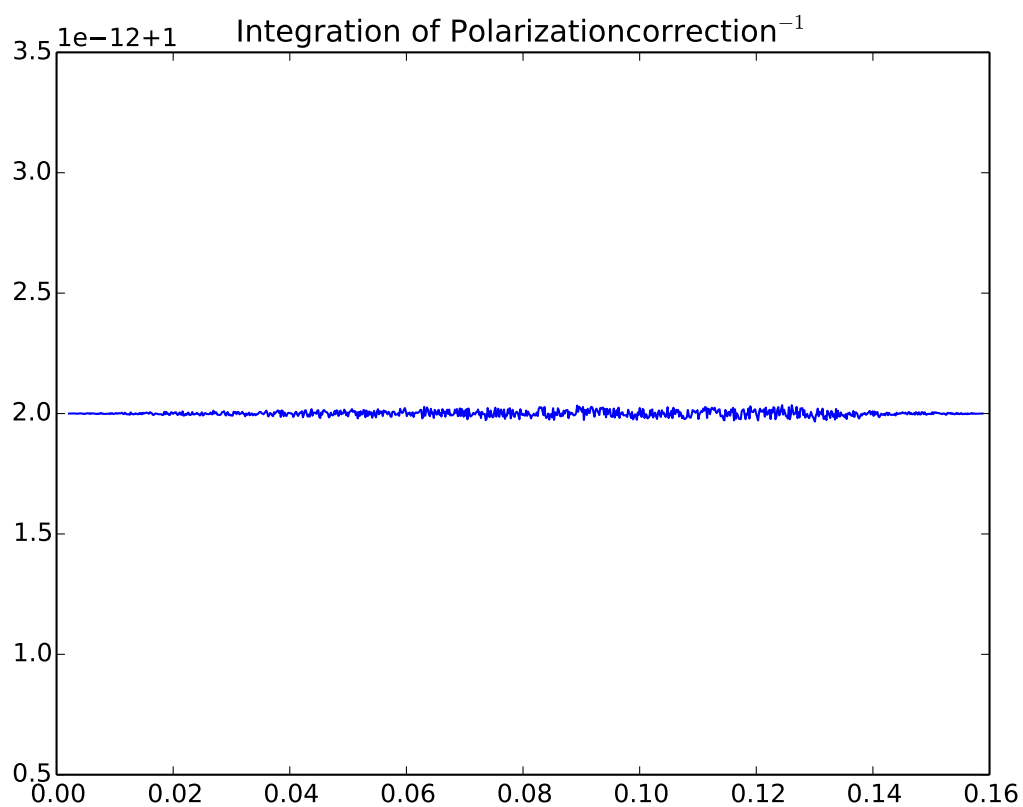
This input:

```
{
  "PixelPerRadialElement": 1,
  "Imagesize": [
    1043,
    981
  ],
  "Tilt": {
    "TiltAngleDeg": -0.56,
    "TiltRotDeg": 73.569
  },
  "MaskFile": "../data/AAA_integ.msk",
  "PolarizationCorrection": {
    "Angle": 0,
    "Fraction": 1
  },
  "Oversampling": 2,
  "Wavelength": 1.54,
  "DetectorDistanceMM": 1031.657,
  "BeamCenter": [
    808.37,
    387.772
  ],
  "PixelSizeMicroM": [
    172.0,
    172.0
  ]
}
```

Gives:

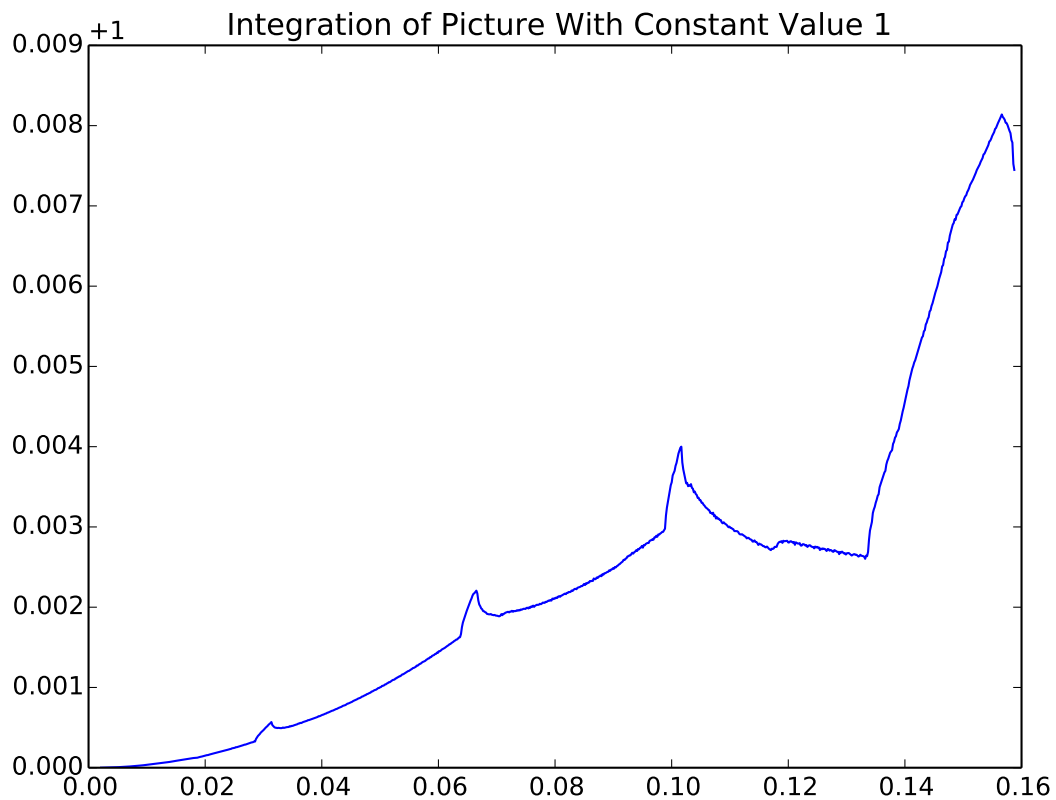


If the correction factors are all correctly in the algorithm, the integration of an image containing  $1/I_{corr}$  should give constant 1.0.



Just for checking: integrating a picture with only ones gives something different:





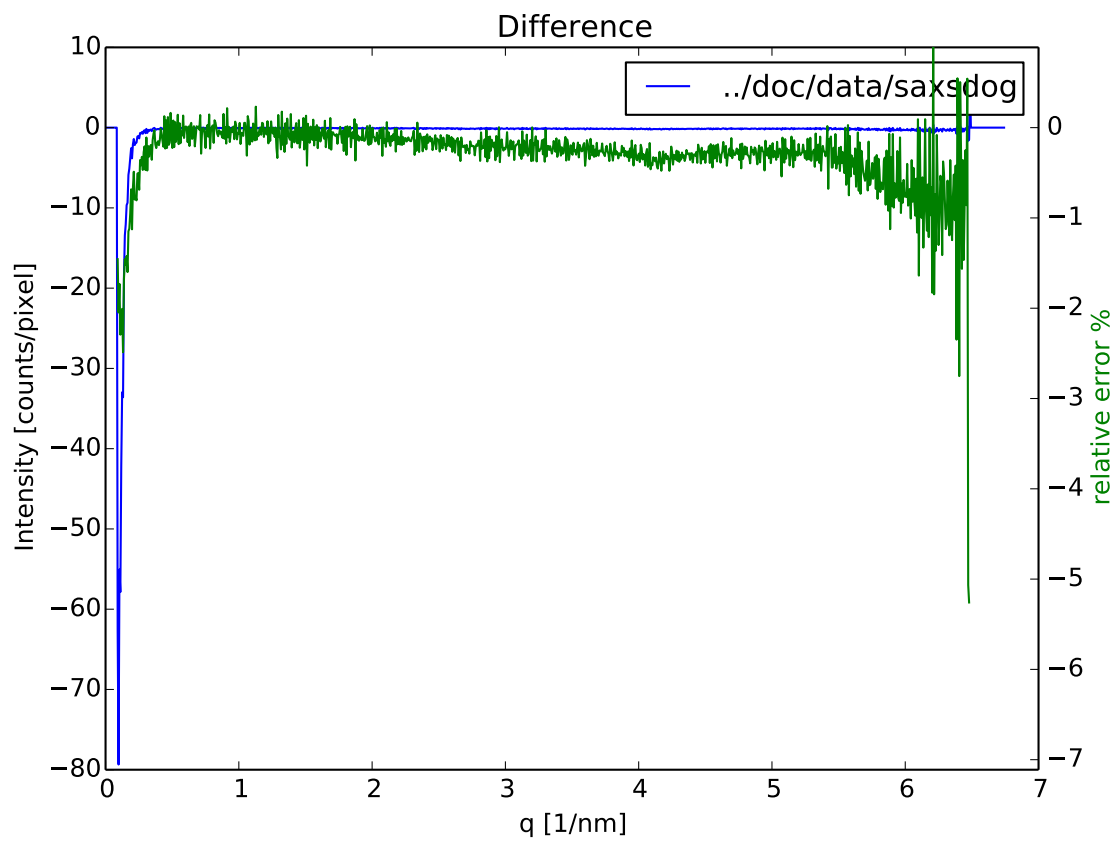
This are the wiggles that come from the polarisation corection pattern

## 4.5 Compare With Fit2d

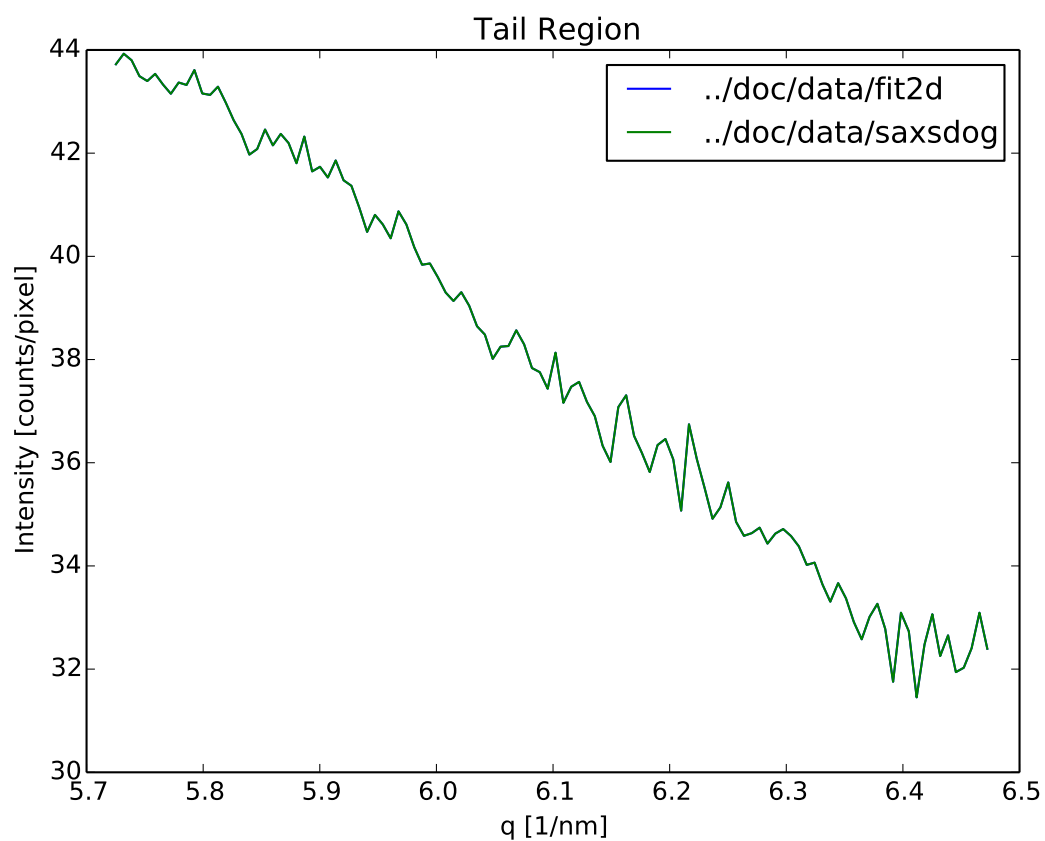
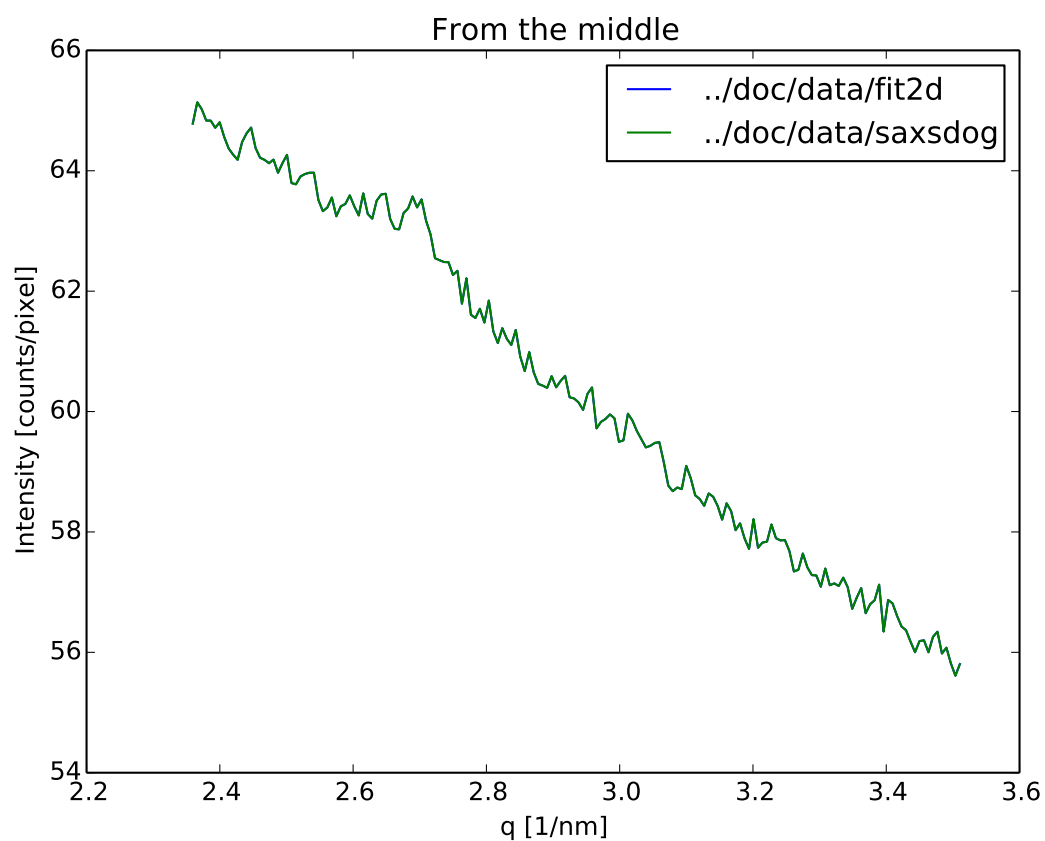
The program fit2d, which this package aims to partly replace, is the standard, so we better include a comparison plot here:



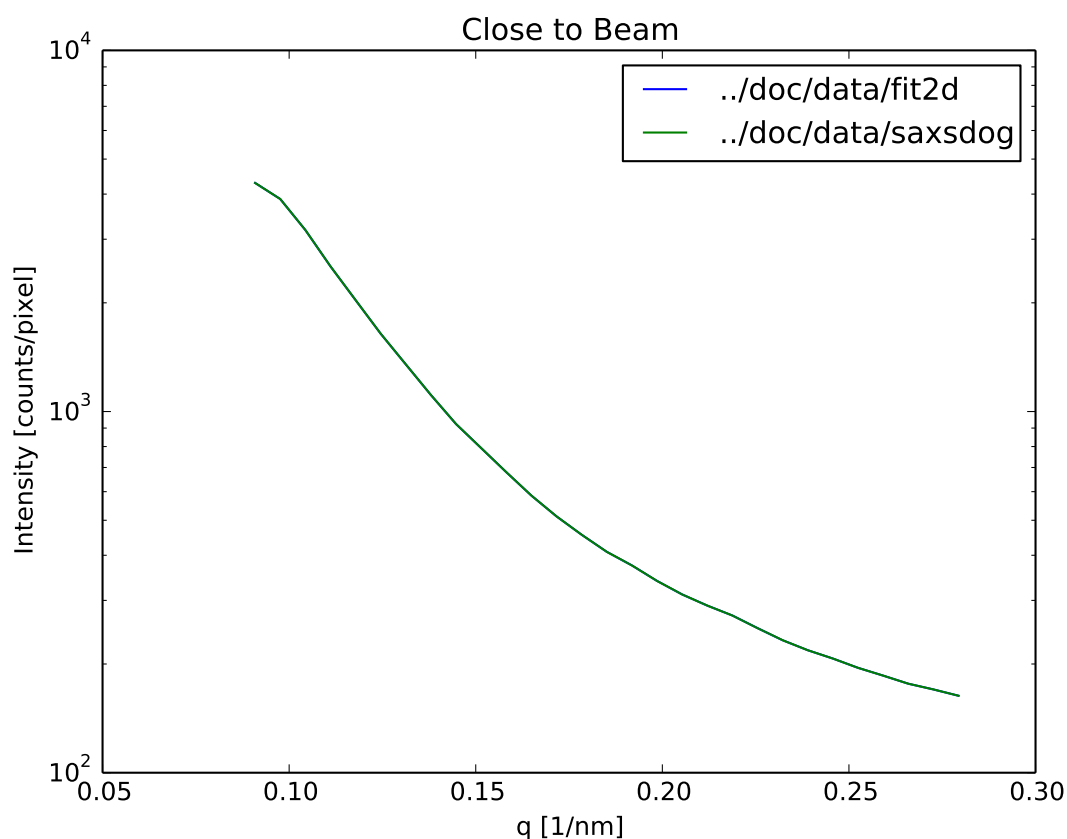
Okay, this doesn't show much but if we plot the difference:



Still looks okay.



In the Tail region the blue halo (Poisson error) signifies that there are not enough counts to make good statistics.



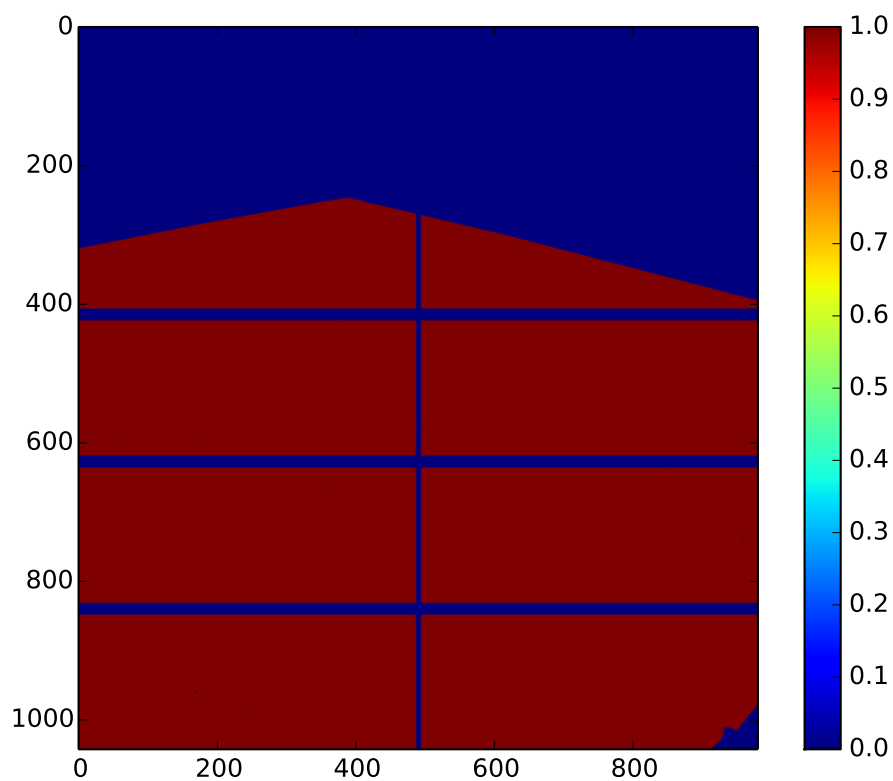
## 4.6 Integrating a Constant Image With Masked Values

This test shows that nothing wrong happens at mask borders. For thos we want to integrate an image that is one everywhere except for the masked regions

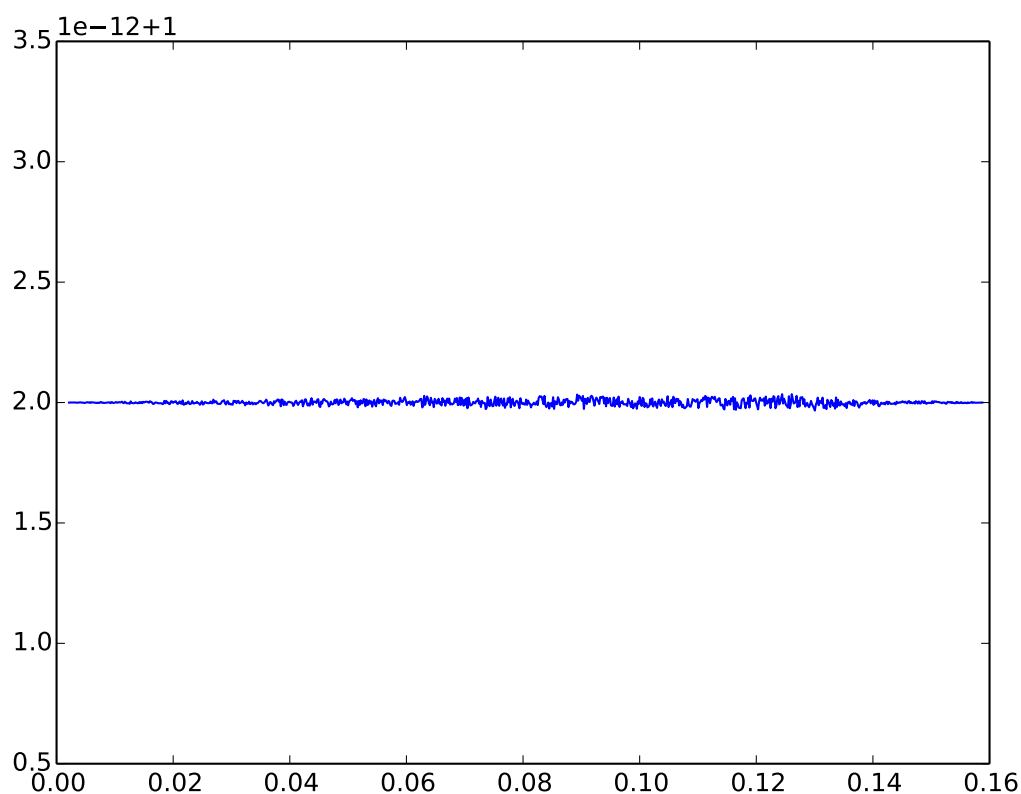
We use the following calibration without Polarization correction and mask:

```
{
  "PixelPerRadialElement": 1,
  "Imagesize": [
    1043,
    981
  ],
  "Tilt": {
    "TiltAngleDeg": -0.56,
    "TiltRotDeg": 73.569
  },
  "MaskFile": "../data/AAA_integ.msk",
  "PixelSizeMicroM": [
    172.0,
    172.0
  ],
  "Wavelength": 1.54,
  "DedectorDistanceMM": 1031.657,
  "BeamCenter": [
    808.37,
    387.772
  ],
  "Oversampling": 2
}
```

The image we are going to integrate is exactly the array the `SAXS.openmask()` returns:



The result is constant 1 (wher the intensity is not 0), save  $2e-12$ .



Doing the same with Fit2d,

```
$ fit2d -svar\#IN=mask.tif -dim2000x2000 -svar\#OUT=data/const.chi -mac../data/AAA_integ_Pilatus1
```

```
-----
PROGRAM  FIT2D  Version: V12.081
-----
```

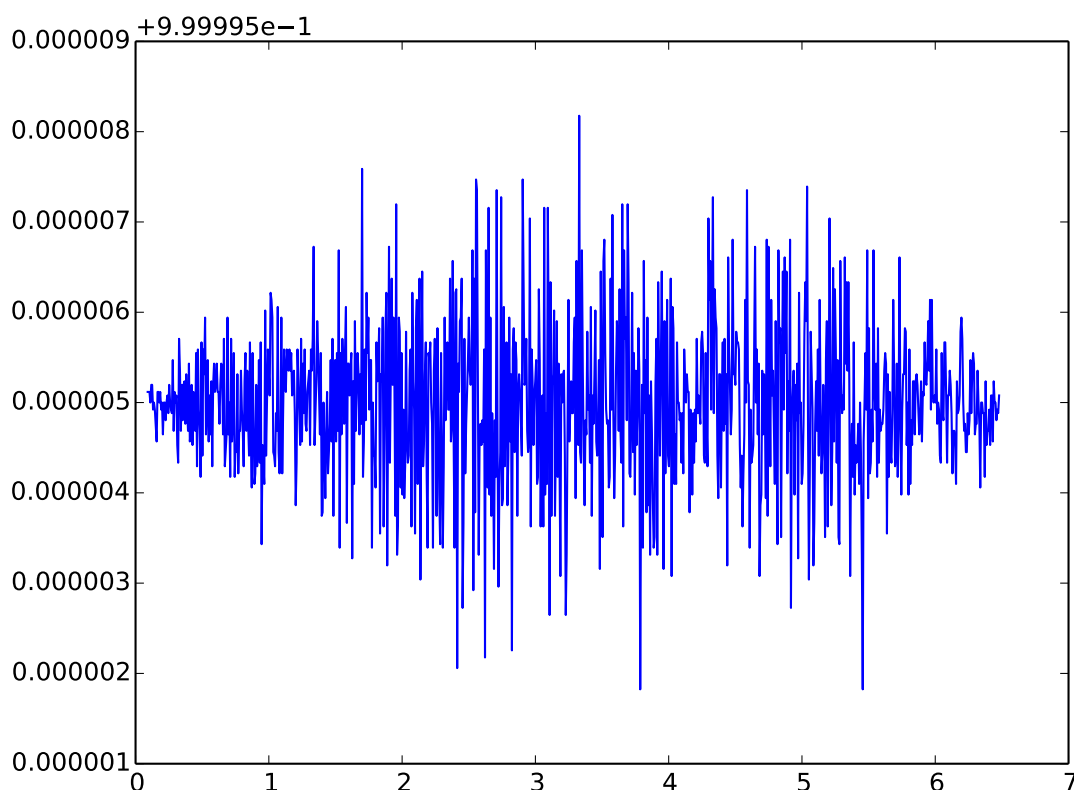
```
Copyright 1987-2005 Andy Hammersley / ESRF (hammersley@esrf.fr)
```

```
FIT2D: 2-D Detector Calibration/Correction; File re-formatting; 2-D Fitting
```

```
YOU CAN ALWAYS ENTER:  ?
```

```
...
```

results in something similar, just with less precision, about  $10e-7$ . Probably because of single precision arithmetics.



## 4.7 Statistics

### 4.7.1 Poisson Statistics

The most important error is the statistical fluctuation that stems from the randomness of the scattering events. Counts of such events follow the Poisson distribution. Such, the error ( $\sigma$ ) is  $\sqrt{n}$  for a count of  $n$ . The result of which is, that the relative error  $\frac{\sqrt{n}}{n}$  rapidly gets small for larger counts.

Each Pixel in the SAXS sensor counts the number of events, and thus follows the Poisson statistics. The error of a sum of pixels is calculated as.

$$\sigma_{sum} = \sqrt{\sum_i \sigma_i^2}$$

which means here

$$\sigma_{sum} = \sqrt{\sum_i n_i}$$

Rescaled over the number of pixels ( $P$ ) in the sum this gives:

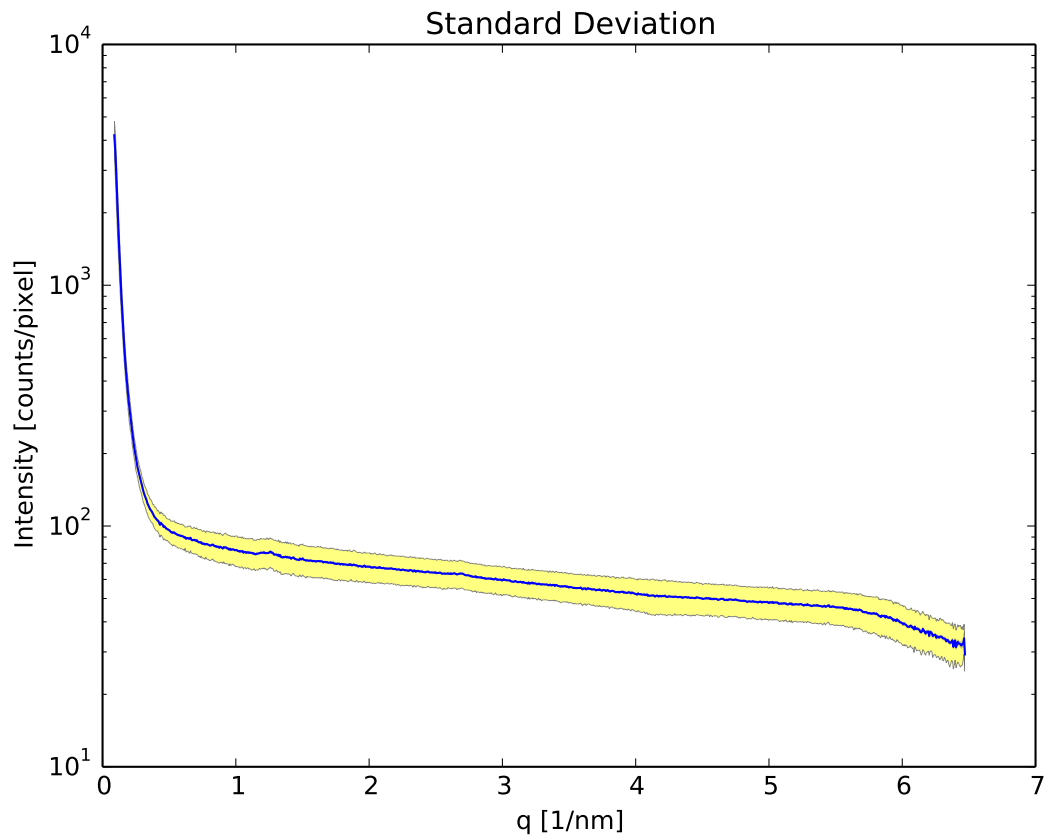
$$\sigma_{sum} = \frac{\sqrt{\sum_{i=1}^P n_i}}{P}$$

The `SAXS.calibration.plot()` method of the `SAXS.calibration` class will give you the Poisson error along with the standard deviation. So for regions, where the total number of counts is too small, you can see if there is a significant error. This might occur, if too few pixels are used for a data point or the intensity is just too small.

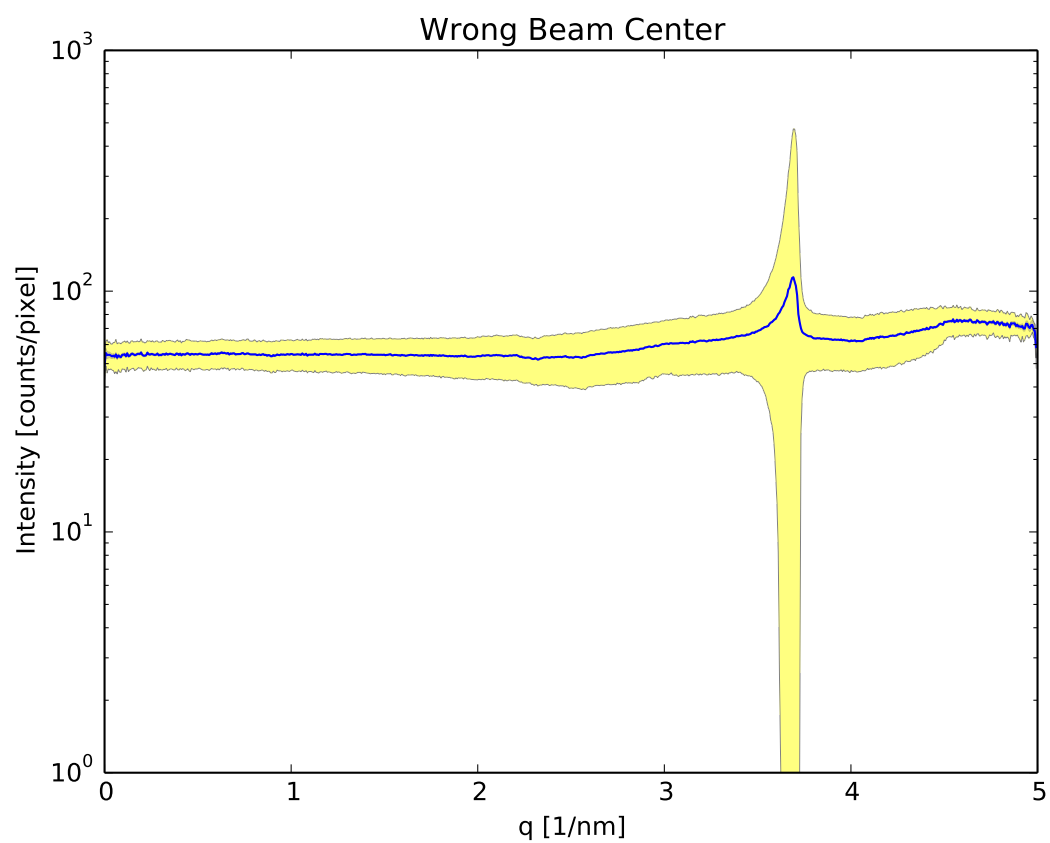


### 4.7.2 Standard Deviation

The standard deviation of the mean that is taken through the integration is not as such particularly useful to estimate the error of the resulting intensities because there are quite a few things that produce an angle dependence. In an optimal case, if the angle dependence can be corrected with the Polarization correction, the standard deviation of the integration might be very small. In an ordinary case the standard deviation gives you a measure of how spread the intensities within a radius interval are.



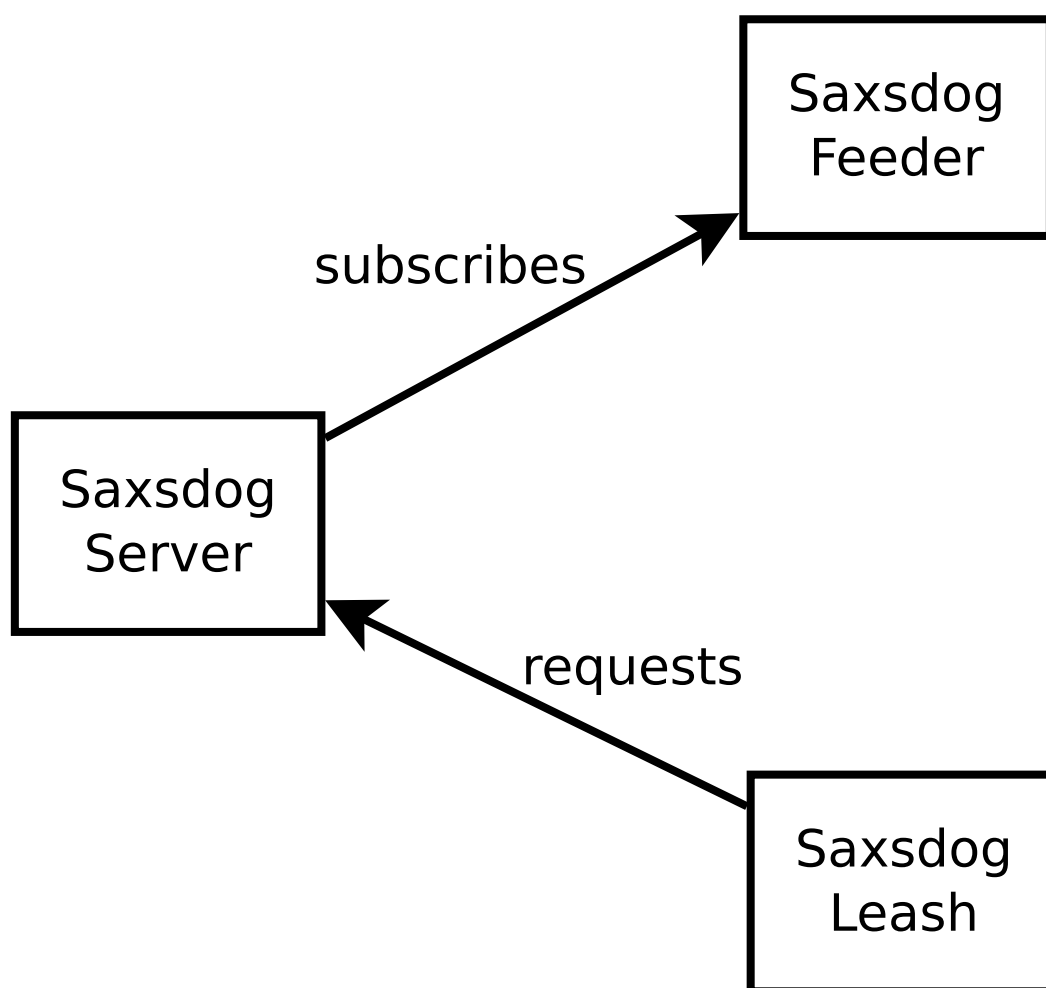
The standard deviation is bright yellow and the Poisson error is blueisch



If the calibration is wrong you will for example see in the standard deviation. Like in this example. Here the beam center is wrong

## THE SAXSDOG NETWORK

The network may consist of 3 different services. The “Saxsdog Server” does the image processing. The “Saxs Feeder” publishes new file Events and the “Saxs Leash” controls and configures the server.



### 5.1 The SAXSNetwork configuration

The Saxsdog Server and the Saxsleash have a common configuration file, which tells them how to connect with each other and which also includes a shared secret for authentication. If you want two computers to connect via the Saxsleash you need to have a copy of the file on each of them.

To create such a configuration, use the command:

```
# saxsnetconf
```

It will ask for the Feeder URL and for the Saxsdog Server URL. Then it will generate a random secret and save the file in file in `$Home/.saxsdognetwork`. You will have to copy the file to the other computers you need to allow to connect to your network. The secret must be the same on all of them.

```
{
  "ServerUrl": "tcp://hostname:port",
  "FeederUrl": "tcp://hostname:port",
  "Secret": "kljjkb4b3kjbk4bkjdbkjsdni8893nslsdf8d7f89diweh"
}
```

The authentication is done by hashing the request and the secret including a timestamp. The timestamp is checked if it lies within 900 seconds of the servers time.

## 5.2 The Saxsdog Server

The Saxdog Server is the program that is started on the processing computer (node). It may subscribe to a “new file” event service.

```
$ saxsdogserver --help
Usage: saxsdogserver [options]
```

Options:

```
-h, --help                show this help message and exit
-p port, --port=port      Port to offer command service. Default is 7777.
-t THREADS, --threads=THREADS
                           Number of concurrent processes.
-f tcp://hostname:port, --feeder=tcp://hostname:port
                           Specify the URL of the new file event service (Saxsdog
                           Feeder)
-w, --watch                Watch directory for changes, using file system events
                           recursively for all sub directories.
```

## 5.3 The Saxs Leash

The “Saxs Leash” client can issue the commands for the Saxsdog Server. It has a commandline interface only, for now.

```
$ saxsleash --help
Usage: saxsleash close|abort|new|plot|readdir|stat [options] [arguments]
```

Options:

```
-h, --help                show this help message and exit
-S tcp://HOSTNAME:PORT, --server=tcp://HOSTNAME:PORT
                           URL of "Saxsdog Server"
-s N, --skip=N             plot: Skip first N points.
-k N, --clip=N             plot: Clip last N points.
-x TYPE, --xaxisistype=TYPE
                           plot: Select type of X axis scale, might be
                           [linear|log|symlog]
-y TYPE, --yaxisistype=TYPE
                           plot: Select type of Y axis scale, might be
                           [linear|log|symlog]
```

Most of the commandline options are about the `plot` command, but in order to visualize the processed data, one has to send the commands to setup a calibration.

### 5.3.1 New

```
# saxsleash new cal.json data/AAA_integ.msk data/
```

The `new` command loads a calibration and starts the queue to receive new files. It requires 3 arguments:

1. Calibration file. as in *The Calibration File*,
2. mask file,
3. directory where the image files are or are going to be.

**If there is a queue running, this command will abort the other one and replace it.** One server can have only one queue at a time.

### 5.3.2 Plot

```
# saxsleash plot
```

The `plot` command will grab the next image and show a plot of the result in a window. This command will be repeated until the user interrupts it with `Ctrl-C`.

### 5.3.3 Close

```
# saxsleash close
```

Closes the queue. Which means, the server will process what is left in the queue but ignore all new files.

### 5.3.4 Abort

```
# saxsleash abort
```

The `abort` command will close the queue and stop all data processing processes. It will only wait for each process to finish the picture they started before. The remaining pictures in the queue are ignored.

### 5.3.5 Stat

```
# saxsleash stat
```

Return basic statistics data about the processes.

### 5.3.6 Read Dir

```
# saxsleash readdir
```

This command will put all the images in the configured directory into the queue. This is useful to reprocess pictures.

## 5.4 The Saxsdog Network Protocol

### 5.4.1 The Saxsdog Server

The saxdog server can watch for filesystem events for himself or subscribe to a zmq service, the Saxsdog Feeder, that publishes new file names. The server can process the new images according to one calibration. The server may only have one calibration at a time, it is not designed to be used by multiple users at the same time.

## 5.4.2 The Saxsdog Feeder

The “Saxsdog Feeder” service offers file events for subscription. It should not do any buffering or preselection, just send a new message when any new file was copied and is ready for processing. Also when a file is overwritten: Send a message. It should however, only send this event, when the file is completely written to the file system.

New file events are composed of the following message:

```
{
  "command": "new file",
  "argument": "/Path/to/file/"
}
```

The service must be a ZeroMQ `zmq.PUP` socket. This code is a simulation of the messages:

```
import zmq
import random
import sys
import time
import os
import json
from optparse import OptionParser

def startfeeder():
    parser = OptionParser()
    usage = "usage: %prog [options] "
    parser = OptionParser(usage)
    parser.add_option("-p", "--port", dest="port",
                    help="Port to offer file changes service", metavar="port", default="5556")
    parser.add_option("-d", "--dir", dest="dir",
                    help="Directory to monitor", metavar="dir", default=".")
    (options, args) = parser.parse_args(args=None, values=None)

    context = zmq.Context()
    socket = context.socket(zmq.PUB)
    print "connecting:", "tcp://*:%s" % options.port
    socket.bind("tcp://*:%s" % options.port)

    fileslist=[]
    for path, subdirs, files in os.walk(options.dir):
        for name in files:
            if name.endswith('.tif'):
                fileslist.append( os.path.join(path, name))
    messageobj={"command": "new file", "argument": ""}
    while True:
        for file in fileslist:
            messageobj['argument']=file
            message=json.dumps(messageobj)
            print message
            socket.send(message)
            time.sleep(.1)

if __name__ == '__main__':
    startfeeder()
```

## 5.4.3 The Saxsdog Leash

The Saxsdog Leash is a user-facing control interface. There, the user should enter new calibrations and specify the data directories connected to it. During the processing, it shows a graph of one of the current images.

It may send the following commands:

### Close

Request:

```
{
  "command": "close queue",
  "time": 1404979588.715198,
  "sign": "Signature generated for request"
}
```

Answer:

```
{
  "result": "queue closed",
  "data": {
    "stat": {
      "time interval": 0.8776118755340576,
      "queue length": 0,
      "frames per sec": 10.25510279760422,
      "images processed": 235, "pics": 9
    }
  }
}
```

### Abort

Request:

```
{
  "command": "abort queue",
  "time": 1404979588.715198,
  "sign": "Signature generated for request"
}
```

Answer:

```
{
  "result": "queue stopped emptied and closed",
  "data": {
    "stat": {
      "time interval": 0.8776118755340576,
      "queue length": 0,
      "frames per sec": 10.25510279760422,
      "images processed": 235,
      "pics": 9
    }
  }
}
```

### New

Request:

```
{
  "command": "new queue",
  "argument": {
    "directory": "directory of data to take into account",
    "calibration": {},
    "maskbin": ""
  }
}
```

```
    },
    "time":1404979588.715198,
    "sign":"Signature generated for request"
}
```

Answer:

```
{ "result":"new queue",
  "data":{
  }
}
```

## Plot

Request:

```
{ "command":"send plot",
  "time":1404979588.715198,
  "sign":"Signature generated for request"
}
```

Answer:

```
{
  "result":"plot data",
  "data":{
    "filename":"/name/.tiv" ,
    "stat": {
      "time interval": 0.8776118755340576,
      "queue length": 0,
      "frames per sec": 10.25510279760422,
      "images processed": 235,
      "pics": 9
    },
    "array":[[0],[0],[0]]
  }
}
```

## Readdir

This puts all existing files in the queue directory into the queue again

Request:

```
{
  "command":"readdir",
  "time":1404979588.715198,
  "sign":"Signature generated for request"
}
```

Answer:

```
{
  "result":"directory refilled queue",
  "data":{
    "stat": {
      "time interval": 0.8776118755340576,
      "queue length": 0,
      "frames per sec": 10.25510279760422,
      "images processed": 235, "pics": 9
    }
  }
}
```



```
    }  
  }  
}
```

## Stat

Get basic processing statistics.

Request:

```
{  "command": "stat", "argument": {},  
    "time": 1404979588.715198,  
    "sign": "Signature generated for request"}
```

Answer:

```
{  
  "data": {  
    "stat": {  
      "time interval": 711.6886098384857,  
      "queue length": 0,  
      "frames per sec": 9.972057866165134,  
      "images processed": 7332,  
      "pics": 7097  
    }  
  },  
  "result": "stat"  
}
```

## Error

In case of error in the Saxsdog Server it will return an error message:

```
{  
  "result": "Error",  
  "data": { "Error": "Error message" }  
}
```

### 5.4.4 Request Schema

The '\*' signifies a required Field.

Schema for requests from Saxs Leash to Saxs Server

**Type** object

**Contains** *command\**, *argument*, *sign*, *time*

**Required** True

**JSON Path** #

Example JSON:

```
{ "command": "close" }
```

#### command

**Type** string

**values** [u'close', u'abort', u'new', u'plot', u'readdir', u'stat']

**Required** True

**JSON Path** # ['*command*']

Example JSON:

```
{"command": "close"}
```

## argument

**Type** object

**Contains** *directory*, *calibration*

**Required** False

**JSON Path** # ['*argument*']

Example JSON:

```
{"argument": {}}
```

## directory

Directory this queue is going to use. New files in other directories are going to be ignored.

**Type** string

**Required** False

**JSON Path** # ['*argument*']['*directory*']

Example JSON:

```
{"directory": ""}
```

## calibration

Calibration data according to *The Calibration File*

**Type** object

**Contains** /

**Required** False

**JSON Path** # ['*argument*']['*calibration*']

Example JSON:

```
{"calibration": {}}
```

## sign

Signature of request

**Type** string

**Required** False

**JSON Path** # ['*sign*']

Example JSON:

```
{"sign": ""}
```

### time

time in seconds (pythons time.time())

**Type** number

**Required** False

**JSON Path** # ['time']

Example JSON:

```
{"time": 0}
```

## 5.4.5 Response Schema

The '\*' signifies a required Field.

Schema for requests from Saxs Leash to Saxs Server

**Type** object

**Contains** *result\**, *data\**

**Required** True

**JSON Path** #

Example JSON:

```
{"data": {}, "result": ""}
```

### result

**Type** string

**Required** True

**JSON Path** # ['result']

Example JSON:

```
{"result": ""}
```

### data

**Type** object

**Contains** *cal*, *Error*, *stat*, *filename*, *array*

**Required** True

**JSON Path** # ['data']

Example JSON:

```
{"data": {}}
```

## cal

**Type** object

**Required** False

**JSON Path** # ['data']['cal']

Example JSON:

```
{"cal": null}
```

## Error

**type** object

**Required** False

**JSON Path** # ['data']['Error']

Example JSON:

```
{"Error": {}}
```

## stat

**type** object

**Contains** *queue length, images processed, time interval, frames per sec, pics*

**Required** False

**JSON Path** # ['data']['stat']

Example JSON:

```
{"stat": {}}
```

## queue length

**Type** integer

**Required** False

**JSON Path** # ['data']['stat']['queue length']

Example JSON:

```
{"queue length": 0}
```

## images processed

**Type** integer

**Required** False

**JSON Path** # ['data']['stat']['images processed']

Example JSON:

```
{"images processed": 0}
```

**time interval**

**Type** number

**Required** False

**JSON Path** # ['data']['stat']['time interval']

Example JSON:

```
{"time interval": 0}
```

**frames per sec**

**Type** number

**Required** False

**JSON Path** # ['data']['stat']['frames per sec']

Example JSON:

```
{"frames per sec": 0}
```

**pics**

**Type** integer

**Required** False

**JSON Path** # ['data']['stat']['pics']

Example JSON:

```
{"pics": 0}
```

**filename**

**Type** string

**Required** False

**JSON Path** # ['data']['filename']

Example JSON:

```
{"filename": ""}
```

**array**

**Type** array() items: array

**Required** False

**JSON Path** # ['data']['array']

Example JSON:

```
{"array": null}
```



## SAXS MODULE API

**class** `SAXS.calibration` (*config*)

This class represents a calibration for SAXS diffraction. After initialization, the `integrate()` method can compute the radial intensity very fast.

**Parameters** `config` (*string*) – is the path to the *root*:

**integrate** (*image*)

Integrate a picture.

**Parameters** `image` (*numpy.array(dim=2)*) – Sensor image to integrate as 2d *NumPy* array

**Returns** Returns Angle and intensity vector as a tuple (angle,intensity)

**integratechi** (*image, path*)

Integrate and save to file in “chi” format.

**Parameters**

- **image** (*np.array()*) – Image to integrate as numpy array
- **path** (*string*) – Path to save the file to

**Returns** Scattering curve data as numpy array

**integrateerror** (*image*)

Integrates an image and computes error estimates.

**Parameters** `image` (*np.array()*) – Image to integrate as numpy array

**Returns** The intensity the standard deviation and the Poisson statistics error in a numpy array.

**plot** (*image, outputfile='', startplotat=0, fig=None*)

Plot integrated function for image in argument.

**Parameters**

- **image** (*numpy.array(dim=2)*) – Sensor image to integrate as 2d *NumPy* array
- **outputfile** (*string*) – File to write plot to. Might be any image format supported by matplotlib.
- **startplotat** (*integer*) – radial point from which to start the plot

`SAXS.calc_theta` (*r, phi, d, tilt, tilt\_dir*)

Calculates the diffraction angle from pixel coordinates. It does work when called with arrays. See [The Geometry](#)

**Parameters**

- **r** (*float*) – Distance to beamcenter.
- **phi** (*float*) – Angle[rad] from polar sensor plane coordinates.
- **d** (*float*) – distance to diffraction center.
- **tilt** (*float*) – Angle[rad] of sensor plane tilt.

- **tiltdir** (*float*) – Angle[rad] of direction of tilt.

**Returns** theta

SAXS.**scalemat** (*Xsize, Ysize, ov*)

Computes a scaling projection for use in computing the pixel weights for integration

**Parameters**

- **Xsize** (*int*) – Picture size in X direction.
- **Ysize** (*int*) – Picture size in Ydirection.
- **ov** (*int*) – Number of oversampling ticks in x ynd y direction
- **corr** (*array*) – Polarizationn an other correction factors

**Returns** sparce matrix toing the scaling

SAXS.**openmask** (*config*)

Open the mask file especially the \*.msk file. Unfortunately there is no library module for msk files available also no documentation. So, for the msk file, we have a very brittle hack it works for our sensor. Nevermind any other resolution or size.

**Parameters** **config** (*object*) – Calibration config object.

**Returns** Mask as logical numpy array.

SAXS.**convert** ()

This implements the functionality oft *The Converter*. It parses the commandline options and converts the Fit2d info file to the JSON data used by the SAXS.calibration class.

SAXS.**saxsdog** ()

This implements the functionality of *The Saxsdog*

**class** SAXS.**imagequeue** (*Cal, options, args*)

This class keeps a queue of images which may be worked on in threads.

**Parameters**

- **Cal** (*SAXS.calibration*) – The SAXS Calibration to use for the processing
- **options** (*optparser*) – The object with the comandline options of the saxsdog
- **args** (*list*) – List of command line options

**fillqueuewithexistingfiles** ()

Fill the queue with the list of images that is already there.

**start** ()

Start threads and directory observer.

**class** SAXS.**Server** (*conf*)

class to manage a saxsdog server

SAXS.**initcommand** (*options, arg, conf*)

Interface for issuing leash commands

SAXS.**validateResponse** (*message*)

Validate response from saxsdog server against the schema.



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