

A GRASP-based search technique for scheduling travel-optimized warehouses in a logistics company

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Overview

Introduction

Problem specification

Solving techniques

- Ordering heuristics

- Improvements

Evaluation

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Introduction

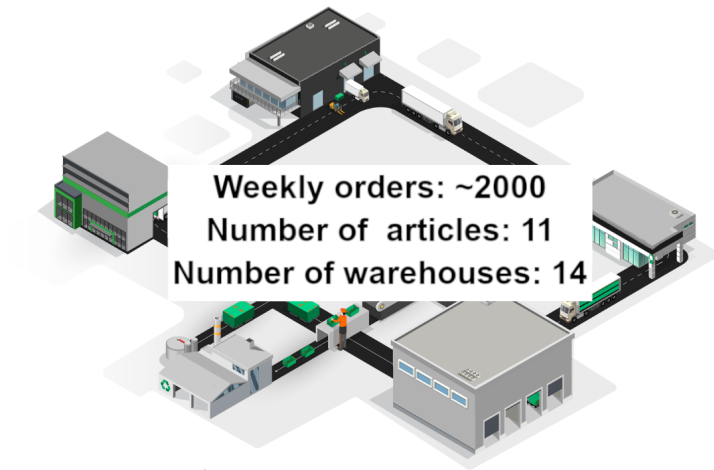


Figure: Weekly data management by the company.

Introduction

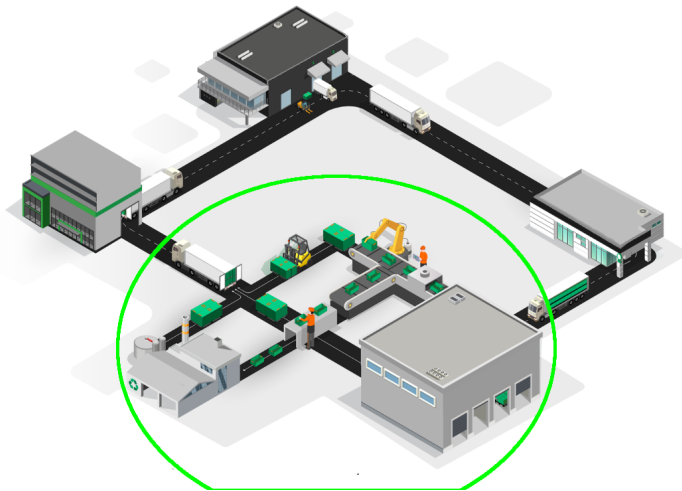


Figure: Diagram of the inner operation of the company.

Introduction

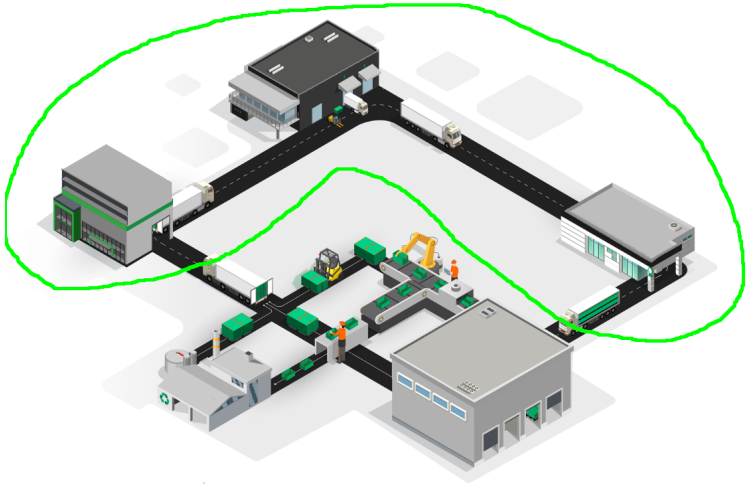


Figure: Diagram of the outer operation of the company.

Problem specification

- ▶ $DS = \{O, W, P\}$ is a triple with the weekly data of the company.
- ▶ $O = \{o_1, o_2, \dots, o_N\}$ is a set of orders.
 - ▶ Each o_i is composed by $(D_{o_i}, Ir_{o_i}, Ware_{o_i})$
 - ▶ D_{o_i} is the delivery date.
 - ▶ Ir_{o_i} is a set of articles to be loaded.
 - ▶ $Ware_{o_i}$ is a set of possible warehouses.
 - ▶ Each $Ware_{o_{ij}}$ is composed by $(ava_{o_{ij}}, pr_{o_{ij}}, dl_{o_{ij}})$.

Problem specification

- ▶ $W = \{w_1, w_2, w_3, \dots, w_M\}$ is a set of warehouses
 - ▶ Each warehouse w_i is a bidirection matrix.
 - ▶ The rows refers to an article.
 - ▶ The column refers to a day of week.
 - ▶ $w_{ijk} \in \mathbb{N}$
- ▶ $P = \{p_1, p_2, p_3, \dots, p_P\}$ is a set of prices

Objective function

- ▶ $f \longleftarrow \alpha * Ct + (1 - \alpha) * \sum Cs$
- ▶ Ct : Variable that contains the transport cost of a warehouse order tuple.
- ▶ Cs : List containing the stock cost of each of the items in the order for a specific warehouse.
- ▶ $\alpha : [0 - 1]$

Solving techniques

The Greedy algorithm provided by the company

- ▶ Control of the distance from the warehouse to the customer and other convenient factors.
- ▶ The zone of influence or geographical area is a higher priority in the assignment.
- ▶ Restrict the warehouses loading by the type of articles contained in the order.
- ▶ The quantity of articles is not constant throughout the year.

Solving techniques

GRASP

- 1: **input:** Orders O , Stocks matrix W , Article price vector P , Size of LCR list n
- 2: **output:** Optimized solution s^*
- 3: $s \leftarrow []$
- 4: $LCR \leftarrow \mathbf{LCRordening}(O, n)$
- 5: **while** $|s| \neq |LCR|$ **do:**
- 6: $j \leftarrow 0$
- 7: $lcr \leftarrow []$
- 8: **while** $j < |LCR|$ **do:**
- 9: $lcr \leftarrow lcr \cup \mathbf{LocalSearch}(LCR_j, \alpha, |LCR|)$
- 10: $j \leftarrow j + 1$
- 11: **end while**
- 12: $s \leftarrow s \cup lcr^*$
- 13: $LCR \leftarrow (LCR \setminus lcr^*) \cup LCR_{n+1}$
- 14: **end while**
- 15: **return** s

Solving techniques

Local Search

- 1: **input:** A order o , List of item price P , Alpha value for objective function α , Length of LCR list $nLCR$
- 2: **output:** Index of warehouse chosen j , Minimum cost of warehouse chosen Q^*
- 3: $Q \leftarrow []$
- 4: $I \leftarrow Ir_o, M \leftarrow W_o$
- 5: **For** j **in** $\{0, \dots, |M|\}$:
- 6: $Cs \leftarrow []$
- 7: $Ct \leftarrow \text{getTransportCost}(M_j)$
- 8: **For** i **in** $\{0, \dots, |I|\}$:
- 9: $Cs \leftarrow Cs \cup P_i * \sum_{k=D_o}^{|wst_{ij}|} wst_{ijk} \mid wst_{ijk} < 0$
- 10: **end for**
- 11: $Q_j \leftarrow \alpha * Ct + (1 - \alpha) * \sum Cs$
- 12: $Q \leftarrow Q \cup Q_j$
- 13: $\alpha \leftarrow \text{AlphaScheduler}(Cs)$
- 14: **end for**
- 15: **return** $(\min(Q), Q_{\min(Q)})$

Ordering heuristics

GRASP

- 1: **input:** Orders O , Stocks matrix W , Article price vector P , Size of LCR list n
- 2: **output:** Optimized solution s^*
- 3: $s \leftarrow []$
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- 5: **while** $|s| \neq |LCR|$ **do:**
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- 8: **while** $j < |LCR|$ **do:**
- 9: $lcr \leftarrow lcr \cup \text{LocalSearch}(LCR_j, \alpha, |LCR|)$
- 10: $j \leftarrow j + 1$
- 11: **end while**
- 12: $s \leftarrow s \cup lcr^*$
- 13: $LCR \leftarrow (LCR \setminus lcr^*) \cup o_{n+1}$
- 14: **end while**
- 15: **return** s

Ordering heuristics

LCR ordering

The ordering of the LCR list depending on a number of characteristics of the orders:

- ▶ Number of available warehouses (Model 1)
- ▶ Number of warehouses and articles (Model 2)
- ▶ Number of warehouses and delay (Model 3)
- ▶ Number of warehouses and standardized delay and articles (Model 4)
- ▶ Number of weight warehouses and delay (Model 5)
- ▶ Early delay and number of articles (Model 6)

Improvements

Shuffle

This method randomize the LCR list from the criteria used in LCR ordering.

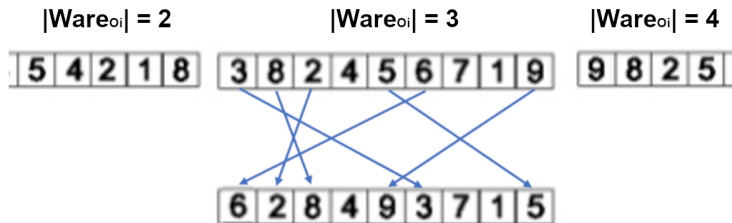


Figure: Example of randomize shuffle method

Improvements

Local Search

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Improvements

Alpha scheduler

It is observed that alpha value polarize fitness function during the execution tests.

Increases or decreases the alpha variable regardless of whether or not the assigned order is in a warehouse with negative stock.

$$F_{\alpha} \leftarrow (1 - \alpha)/nLCR$$

if $\sum C_s \leq 0$ **then:**

$$\alpha \leftarrow \alpha + F_{\alpha}$$

else:

$$\alpha \leftarrow \alpha - F_{\alpha}$$

end if

Evaluation

Study cases

We manage three cases provided by the company:

- ▶ **Test case:** dataset prepared by the company to test the algorithm. This data set is used to tune the parameters of the GRASP algorithm.
- ▶ **Study cases:** dataset with orders for the first and second week of July

Complexity

- ▶ **Orders:** $\simeq 2000$
- ▶ **Possible warehouses in** o_i : $[1 - 14]$
- ▶ **Articles in** o_i : $[1 - 11]$

Evaluation

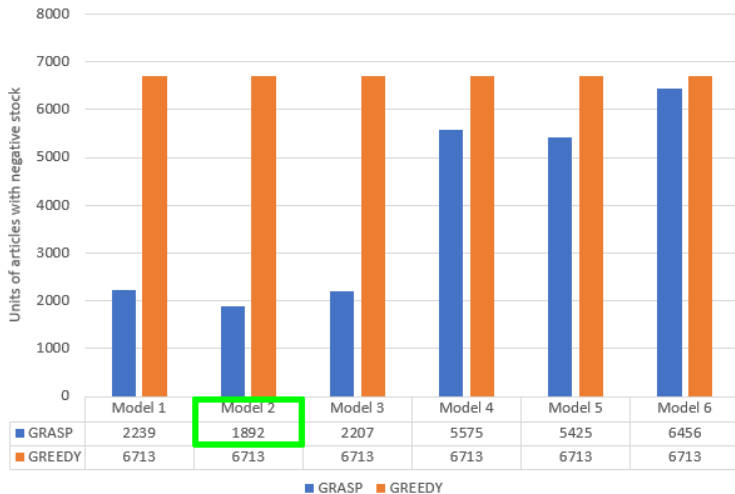


Figure: Dispersion of negative stock for each model.

Evaluation



Figure: Cost comparison for each model.

Evaluation

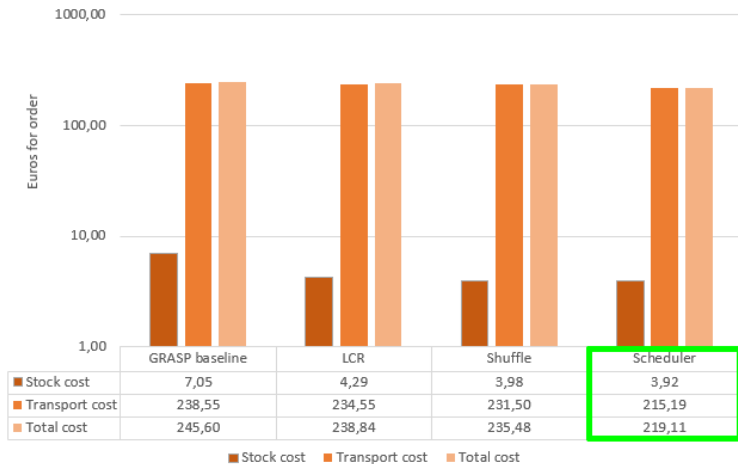


Figure: Different costs for each improvement.

Evaluation

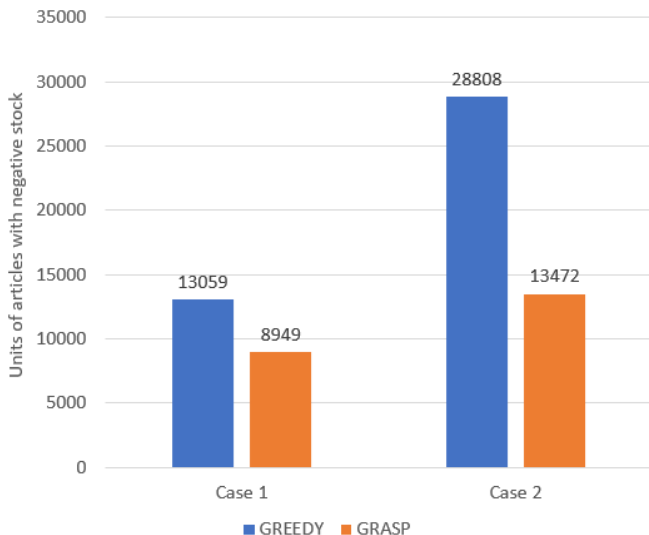


Figure: Dispersion of negative stock for case study.

Evaluation

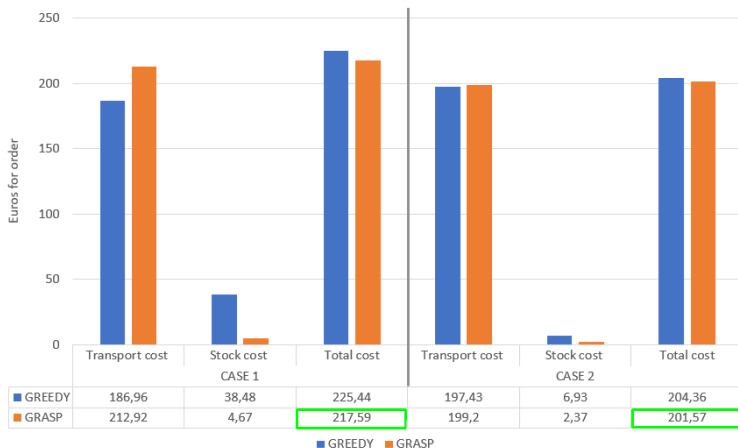


Figure: Different costs for each case study.

Conclusions and future work

Conclusions

- ▶ Logistic companies need to optimize their strategies to be more efficient.
- ▶ This paper shows that two problems can be combined: the warehouse stock management and routing problem.
- ▶ GRASP-based metaheuristic improve the negative average stock by up to 82%.
- ▶ Current tools cannot find a solution in a reasonable time.
- ▶ The proposed developed algorithm obtains a optimized solution in less than 1.5 minutes.

Future work

- ▶ Create a data pool from the grasp-based metaheuristic solutions.
- ▶ Develop a genetic algorithm where the initial population is fed with solutions obtained by GRASP.

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