

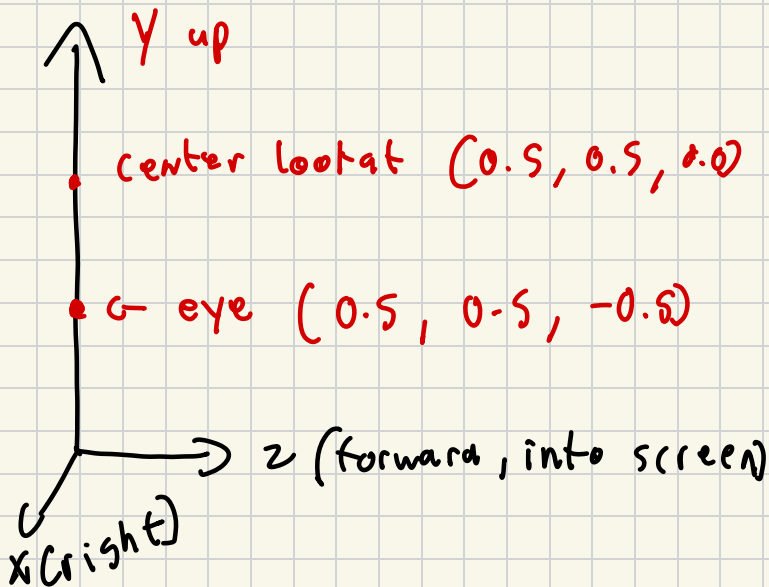
Part 1

1.1) The vector is calculated by subing in eye position from center point. (normalize it)

$$\begin{aligned}\text{center} - \text{eye} &= (0.5, 0.5, 0.0) - (0.5, 0.5, -0.5) \\ &= (0.0, 0.0, 0.5) \rightarrow \text{normalize}\end{aligned}$$

→ $(0.0, 0.0, 1.0)$

1.2)



1.3) X camera → comes to the right $(1, 0, 0)$
Y camera perpendicular to X and Z $(0, 1, 0)$

z camera forward into screen (0, 0, 1)

1.4) $V = \begin{bmatrix} 1 & 0 & 0 & 0.5 \\ 0 & 1 & 0 & -0.5 \\ 0 & 0 & -1 & -0.5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$ \rightarrow we rotate with camera
 \rightarrow and move origin to camera position

only thing we change is the x position/view to the right in this case

$$\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} -1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

2) $model = T(position) \cdot T(center) \cdot R \cdot S \cdot T(center)$

part 2) We store it in a model matrix to hold the transformation \rightarrow if parent we use parent's stored model matrix and ~~*~~ by Child's

With parent $= model(parent) \cdot T(pos) \cdot T(center)$
 $* T(center) \cdot R$

no parent $= T(pos) \cdot T(center) \cdot R \cdot T$