

## Matrix & vector differentiation

Let  $y = f(x)$

$y \in \mathbb{R}^m$  and  $x \in \mathbb{R}^n$   
both are vectors

The Jacobian matrix is

$$J = \frac{\partial y}{\partial x} = \begin{bmatrix} \frac{\partial y_1}{\partial x_1} & \frac{\partial y_1}{\partial x_2} & \dots & \frac{\partial y_1}{\partial x_n} \\ \frac{\partial y_2}{\partial x_1} & | & & | \\ \vdots & | & & | \\ \frac{\partial y_m}{\partial x_1} & & & \frac{\partial y_m}{\partial x_n} \end{bmatrix}$$

if  $x$  is a scalar, then the resulting Jacobian  $J \in \mathbb{R}^{m \times 1}$

Define

$$y \in Ax$$

$$y \in \mathbb{R}^m \quad x \in \mathbb{R}^n$$

$$A \in \mathbb{R}^{m \times n}$$

$$\frac{\partial y}{\partial x} = A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & & & \\ \vdots & & & \\ a_{m1} & \dots & \dots & a_{mn} \end{bmatrix}$$

To see this write  $i$ th element of  $y$  as

$$y_i = \sum_{k=1}^n a_{ik} x_k$$

$$\frac{\partial y_i}{\partial x_j} = a_{ij} \quad \text{for all } i=1,2,\dots,m \quad j=1,2,\dots,n$$

$$\Rightarrow \frac{\partial y}{\partial x} = A$$

Define

$y = Ax$  as before with respect to  $\dim$ .

$A$  does not depend on  $x$   
 $x$  depends on  $z$  (vector)

$$\frac{\partial y}{\partial z} = A \frac{\partial x}{\partial z}$$

$$y_i = \sum_{k=1}^n a_{ik} x_k$$

$$\frac{\partial y_i}{\partial z_j} = \underbrace{\sum_{k=1}^n a_{ik} \frac{\partial x_k}{\partial z_j}}_{\text{element } (i,j) \text{ of } A \frac{\partial x}{\partial z}}$$

Hence

$$\frac{\partial y}{\partial z} = \frac{\partial y}{\partial x} \frac{\partial x}{\partial z} = A \frac{\partial x}{\partial z}$$

Define a scalar  $\alpha$

$$\alpha = y^T A x$$

$$y \in \mathbb{R}^m \quad x \in \mathbb{R}^n$$

$$A \in \mathbb{R}^{m \times n}$$

$A$  is independent of  $y$  and  $x$

$$\frac{\partial \alpha}{\partial y} = x^T A^T \quad \wedge \quad \frac{\partial \alpha}{\partial x} = y^T A$$

Proof : Define  $w^T = g^T A$

$$\alpha = w^T x$$

$$\frac{\partial \alpha}{\partial x} = w^T = g^T A$$

$\alpha$  is a scalar :

$$\alpha = \alpha^T = x^T A^T g$$

$$\frac{\partial \alpha}{\partial g} = x^T A^T$$

Define

$$\alpha = x^T A x$$

$A$  is a quadratic matrix  $A \in \mathbb{R}^{n \times n}$

$$\frac{\partial \alpha}{\partial x} = x^T (A + A^T)$$

Proof

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$$\alpha = \sum_{j=1}^n \sum_{i=1}^n a_{ij} x_i x_j$$

$$\frac{\partial \alpha}{\partial x_k} = \sum_{j=1}^n a_{kj} x_j + \sum_{i=1}^n a_{ik} x_i$$

for all  $k=1, 2, \dots, n$ , this leads to

$$\begin{aligned} \frac{\partial \alpha}{\partial x} &= x^T A^T + x^T A \\ &= x^T (A^T + A) \end{aligned}$$

if  $A$  is symmetric

$$\frac{\partial \alpha}{\partial x} = 2x^T A$$

Define

$$\alpha = y^T x = \text{scalar}$$

$$y, x \in \mathbb{R}^n$$

Both are function of a vector  $z$

$$\frac{\partial \alpha}{\partial z} = x^T \frac{\partial y}{\partial z} + y^T \frac{\partial x}{\partial z}$$

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$\frac{\partial \alpha}{\partial \mathbf{z}}$

Proof

$$\alpha = \sum_{j=1}^n x_j' y_j'$$

$$\frac{\partial \alpha}{\partial z_k} = \sum_{j=1}^n \left( x_j' \frac{\partial y_j'}{\partial z_k} + y_j' \frac{\partial x_j'}{\partial z_k} \right)$$

for all  $k=1, 2, \dots, n \Rightarrow$

$$\begin{aligned} \frac{\partial \alpha}{\partial \mathbf{z}} &= \frac{\partial \alpha}{\partial \mathbf{y}} \frac{\partial \mathbf{y}}{\partial \mathbf{z}} + \frac{\partial \alpha}{\partial \mathbf{x}} \frac{\partial \mathbf{x}}{\partial \mathbf{z}} \\ &= \mathbf{x}'^T \frac{\partial \mathbf{y}}{\partial \mathbf{z}} + \mathbf{y}'^T \frac{\partial \mathbf{x}}{\partial \mathbf{z}} \end{aligned}$$

Define

$$\mathbf{x}'^T \mathbf{x} = \alpha \quad (\text{scalar})$$

$$\frac{\partial \alpha}{\partial \mathbf{z}} = 2 \mathbf{x}'^T \frac{\partial \mathbf{x}}{\partial \mathbf{z}}$$

Define scalar  $\alpha$

$$\alpha = \mathbf{y}'^T \mathbf{A} \mathbf{x} \quad \begin{array}{l} \text{no dependence} \\ \text{on } \mathbf{z} \end{array}$$

↑ Depend on  $z$

$$\frac{\partial \alpha}{\partial z} = x^T A^T \frac{\partial y}{\partial z} + y^T A \frac{\partial x}{\partial z}$$

Proof  $w^T = y^T A$   
 $\alpha = w^T x$

$$\frac{\partial \alpha}{\partial z} = x^T \frac{\partial w}{\partial z} + w^T \frac{\partial x}{\partial z}$$

Substitute back  $w$

$$\begin{aligned} \frac{\partial \alpha}{\partial z} &= \frac{\partial \alpha}{\partial y} \frac{\partial y}{\partial z} + \frac{\partial \alpha}{\partial x} \frac{\partial x}{\partial z} \\ &= x^T A^T \frac{\partial y}{\partial z} + y^T A \frac{\partial x}{\partial z} \end{aligned}$$

Finally :

$$\alpha = (y - Ax)^T (y - Ax)$$

(used in MSE definition)

Define  $w = y - Ax$

$w$  depends on  $x$

$$\alpha = w^T w$$

$$\frac{\partial \alpha}{\partial x} = 2w^T \frac{\partial w}{\partial x}$$

$$\frac{\partial w}{\partial x} = -A \Rightarrow$$

$$\frac{\partial \alpha}{\partial x} = -2(y - Ax)^T A$$

$$= -2y^T A + 2x^T A^T A$$

↑  
does  
not  
depend  
on  $x$

$$\frac{\partial^2 \alpha}{\partial x^T \partial x} = 2A^T A$$



