



Goal

Running time estimates for sampling from high dimensional probability distributions using Hamiltonian Monte Carlo (HMC).

Hamiltonian Monte Carlo

Bayesian posterior distribution:

$$\pi(q \mid \text{data}) = \frac{1}{Z} \mathcal{L}(\text{data} \mid q) \pi(q)$$

parameter $q \in \mathbb{R}^d$, $d \gg$ observations, and unknown normalizing constant Z .

Expectation of $f : \mathbb{R}^d \rightarrow \mathbb{R}$

$$I := \mathbb{E}_\pi(f) = \int f(q) \pi(q \mid \text{data}) dq$$

Empirical mean:

$$\hat{I} := \frac{1}{T} \sum_{t=1}^T Q_t, \quad Q_1, \dots, Q_T \sim \pi(q \mid \text{data})$$

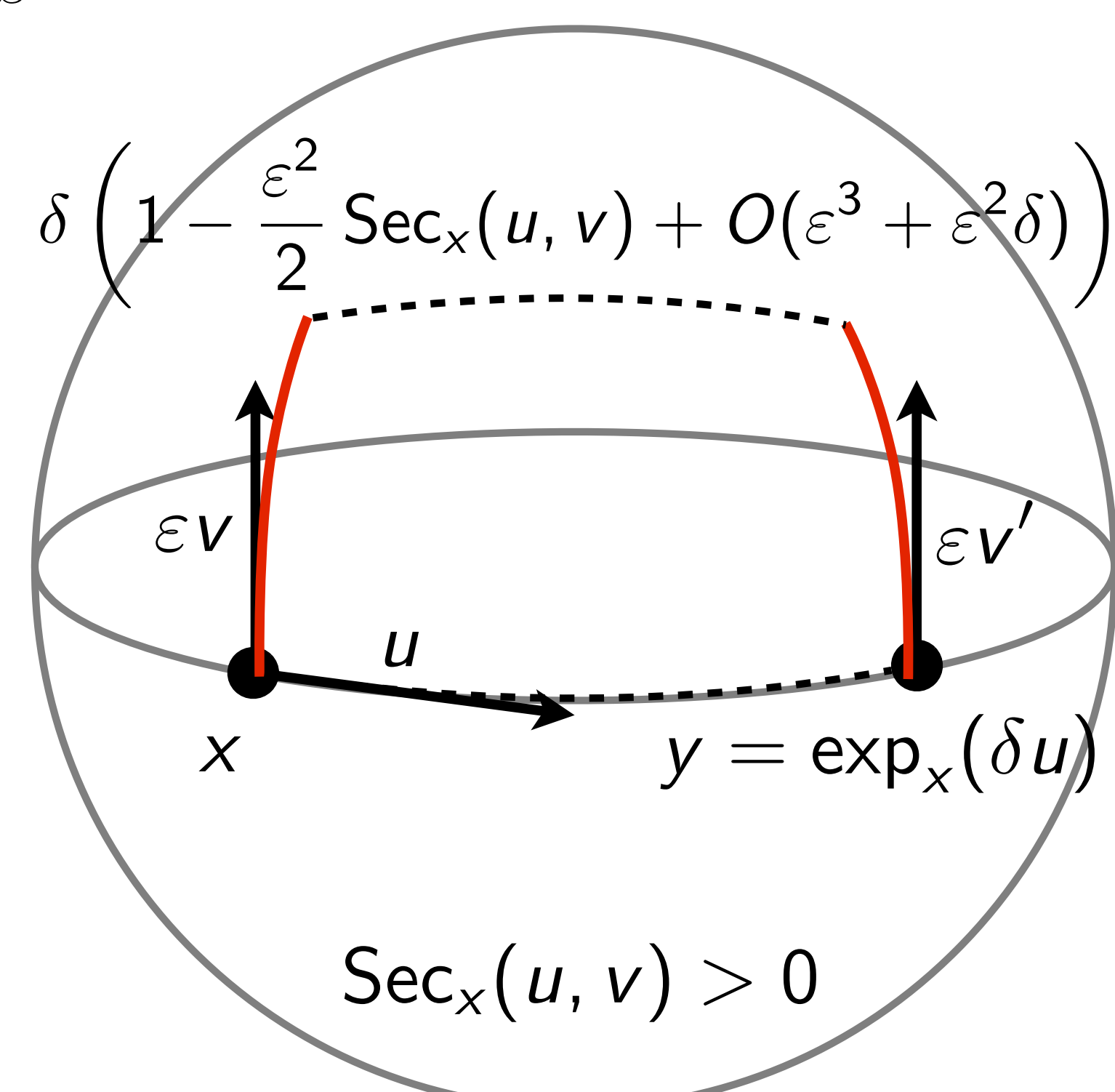
simulated using HMC for running time T

HMC algorithm: Metropolis-Hastings with proposal step following Hamiltonian trajectories

Error and running time: Bound the error $|\hat{I} - I|$ as a function of the running time T

Sectional Curvature

Sectional curvature Sec describes the nature of geodesics



Positive curvature: geodesics meet

Flat and negative curvature: geodesics deviate

Probability Meets Geometry

Coarse Ricci curvature κ describes the deviation from independence of subsequent draws from Markov chain Monte Carlo

- The larger κ the more independent
- The larger κ the smaller T for the same error
- We calculate the κ of HMC

Concentration inequality (JO10)

$$\mathbb{P}(|\hat{I} - I| \geq r \|f\|_{\text{Lip}}) \leq 2e^{-r^2/(16V^2(\kappa, T))}$$

Jacobi Metric

Jacobi metric g_h links Hamiltonians to Riemannian geometry

Hamiltonian function:

$$h = V(q) + K(p)$$

Potential energy:

$$V(q) = -\log \pi(q \mid \text{data}) + C$$

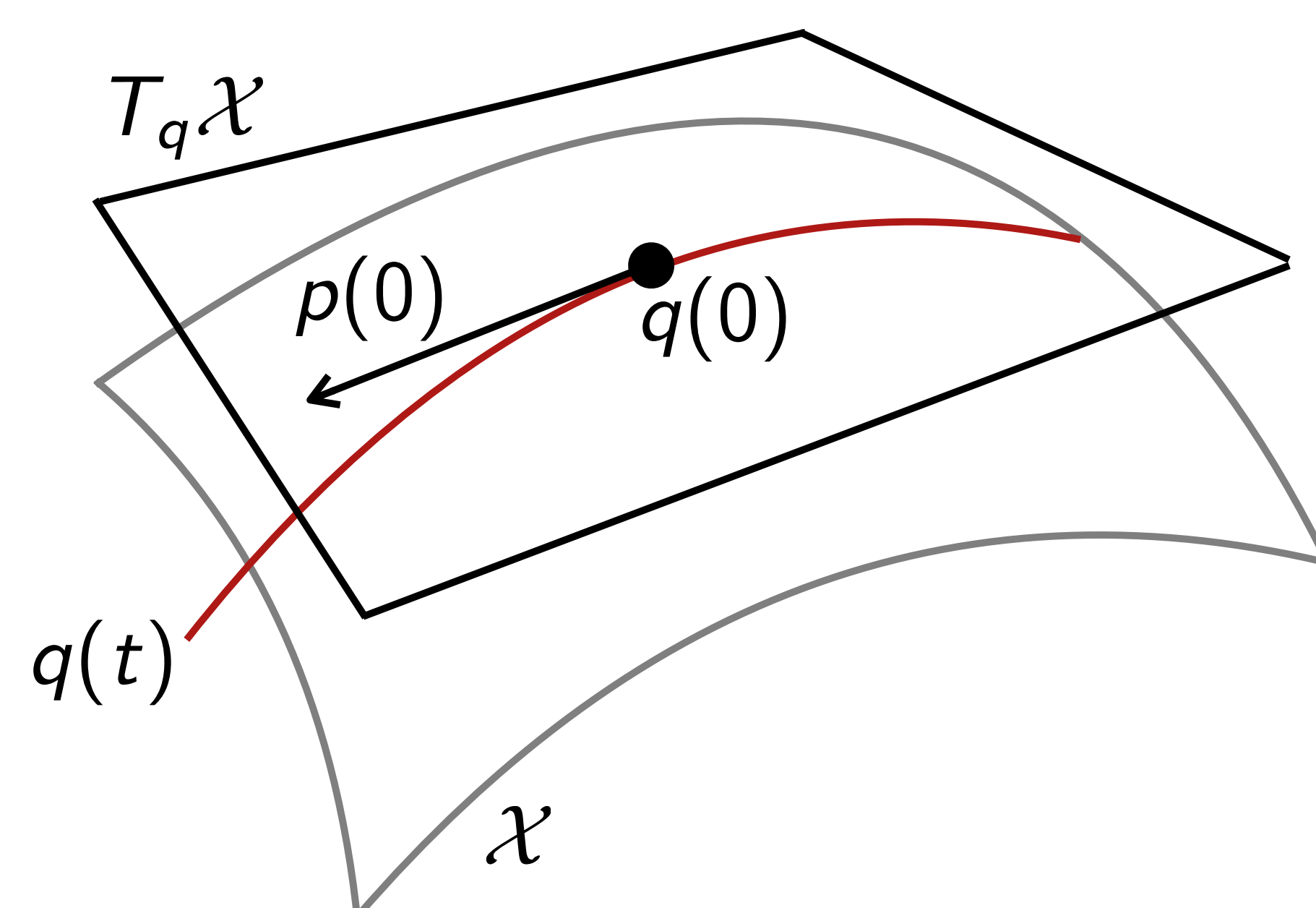
Kinetic energy:

$$K(p) = \frac{1}{2} \langle p, p \rangle$$

Hamiltonian equations:

$$\frac{dq}{dt} = \frac{\partial H}{\partial p} \quad \text{and} \quad \frac{dp}{dt} = -\frac{\partial H}{\partial q}$$

Jacobi-Maupertuis Principle:



Hamiltonian trajectories $q(t)$ with fixed h are geodesics on Riemannian manifolds \mathcal{X} with the Jacobi metric:

$$g_h(p, p) = 2(h - V) \langle p, p \rangle.$$

HMC Meets Geometry

Reference metric $\langle \cdot, \cdot \rangle$

Conformal scaling of a metric $2(h - V)$

Equivalence table:

HMC	Riemannian geometry
posterior distribution	scaling of reference metric
covariance of proposal	reference metric
pick from proposal	geodesics

Gaussian Example

- HMC sampling from a Gaussian in \mathbb{R}^d with zero mean and covariance matrix Λ^{-1}
- Calculate sectional curvature of Jacobi metric
- Sec is random because p is random
- Calculate coarse Ricci curvature from Sec

Our Lemma on positive curvature of HMC:

$$\mathbb{P}(d^2 \text{Sec} \geq K_1) \geq 1 - K_2 e^{-K_3 \sqrt{d}}$$

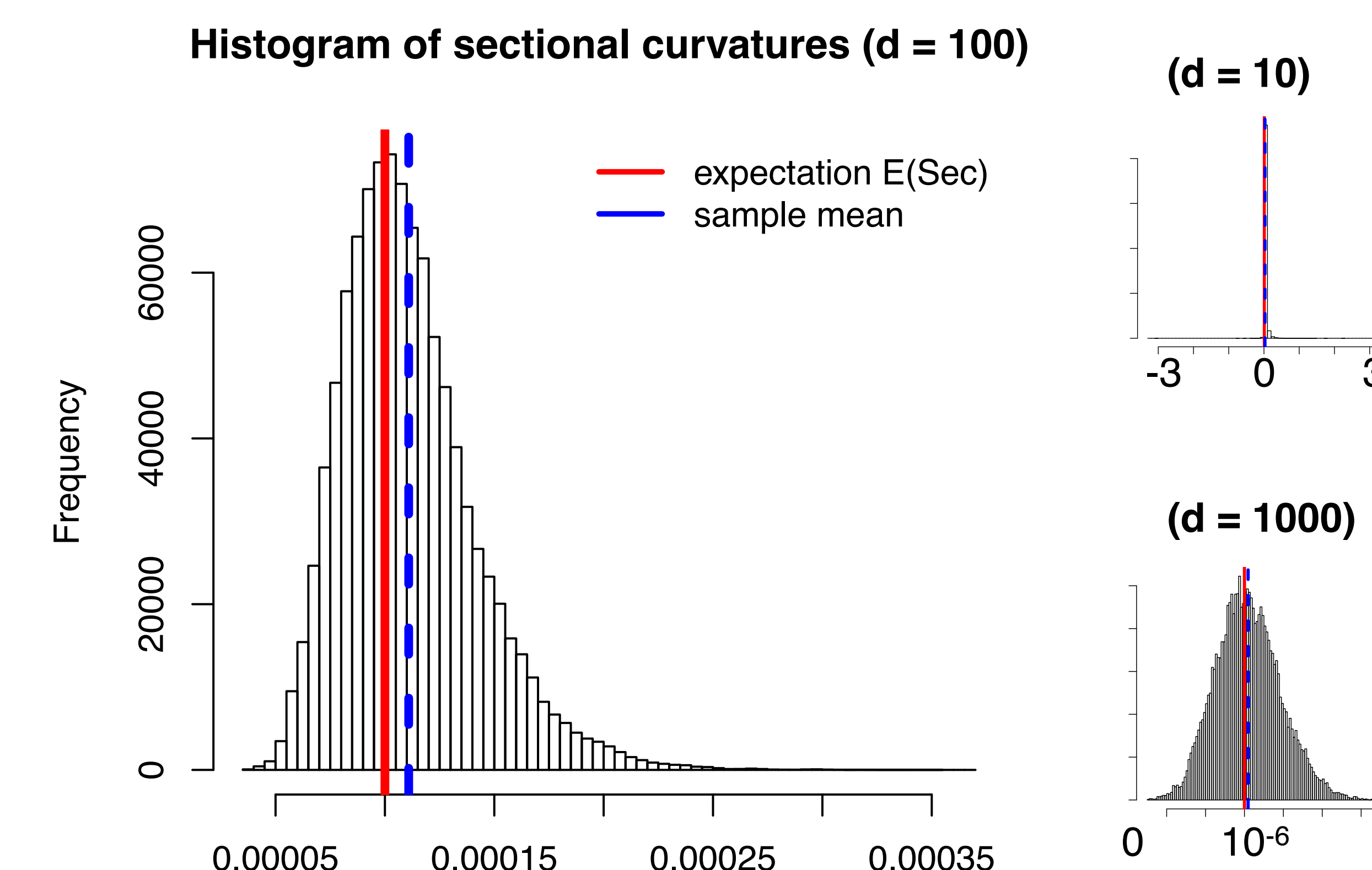
Our Corollary in high dimensions:

$$\text{Sec} \geq \frac{\text{Tr}(\Lambda)}{d^3} \quad \text{as } d \rightarrow \infty$$

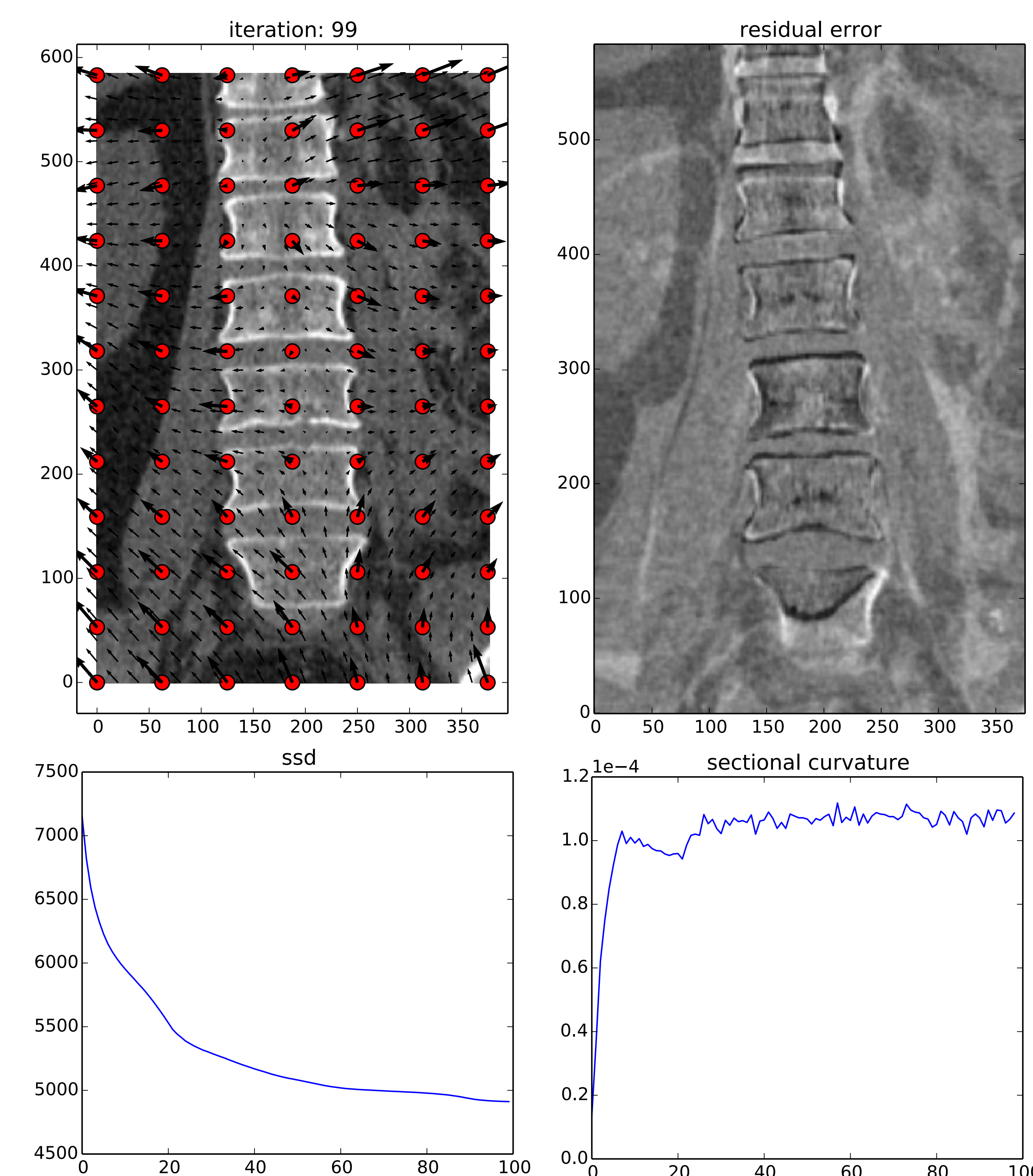
Our Proposal on coarse Ricci curvature of HMC:

$$\kappa \geq \frac{\text{Tr}(\Lambda)}{6d^2} + O\left(\frac{1}{d^2}\right) \quad \text{as } d \rightarrow \infty$$

Numerical simulations: Sample Sec's uniformly at each step, $q(0), \dots, q(T-1)$



Computational Anatomy



Conclusion

Linking HMC to geodesics of the Jacobi metric enables us to analyze HMC through the rich mathematical framework of Riemannian geometry.

References

- (JO10) A. Joulin and Y. Ollivier. Curvature, Concentration and Error Estimates for Markov Chain Monte Carlo. Ann. Probab., 2010.
- (Pin75) O. C. Pin. Curvature and Mechanics. Advances in Math., 1975.

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