

# Statistical Machine Learning 2016

## Exercises and answers, week 1

### Exercise 1

In analyzing problems in which a sigma-summation symbol is involved, it is sometimes helpful to write out the sum. By writing out the sum, I mean e.g.,

$$\sum_{i=1}^5 x_i = x_1 + x_2 + x_3 + x_4 + x_5$$

or more general

$$\sum_{i=1}^n x_i = x_1 + x_2 + \dots + x_n .$$

- Show, by explicitly writing out the sums, rearranging terms, and using brackets where needed, that the following four equations hold:

$$\sum_{i=1}^3 (ax_i) = a \left( \sum_{i=1}^3 x_i \right) \tag{1}$$

$$\sum_{i=1}^3 \left( \sum_{j=1}^2 a_{ij} \right) = \sum_{j=1}^2 \left( \sum_{i=1}^3 a_{ij} \right) \tag{2}$$

$$\sum_{i=1}^3 \left( \sum_{j=1}^2 x_i y_j \right) = \left( \sum_{i=1}^3 x_i \right) \left( \sum_{j=1}^2 y_j \right) \tag{3}$$

$$\sum_{i=1}^3 a = 3a \tag{4}$$

ANSWER:

Show (1):

$$\begin{aligned} \sum_{i=1}^3 (ax_i) &= ax_1 + ax_2 + ax_3 \\ &= a(x_1 + x_2 + x_3) \\ &= a \left( \sum_{i=1}^3 x_i \right) \end{aligned}$$

Show (2):

$$\begin{aligned}
 \sum_{i=1}^3 \left( \sum_{j=1}^2 a_{ij} \right) &= \sum_{i=1}^3 (a_{i1} + a_{i2}) \\
 &= (a_{11} + a_{12}) + (a_{21} + a_{22}) + (a_{31} + a_{32}) \\
 &= (a_{11} + a_{21} + a_{31}) + (a_{12} + a_{22} + a_{32}) \\
 &= \sum_{j=1}^2 (a_{1j} + a_{2j} + a_{3j}) \\
 &= \sum_{j=1}^2 \left( \sum_{i=1}^3 a_{ij} \right)
 \end{aligned}$$

Show (3):

$$\begin{aligned}
 \sum_{i=1}^3 \left( \sum_{j=1}^2 x_i y_j \right) &= (x_1 y_1 + x_1 y_2) + (x_2 y_1 + x_2 y_2) + (x_3 y_1 + x_3 y_2) \\
 &= x_1(y_1 + y_2) + x_2(y_1 + y_2) + x_3(y_1 + y_2) \\
 &= (x_1 + x_2 + x_3)(y_1 + y_2) \\
 &= \left( \sum_{i=1}^3 x_i \right) \left( \sum_{j=1}^2 y_j \right)
 \end{aligned}$$

Show (4):

$$\begin{aligned}
 \sum_{i=1}^3 a &= a + a + a \\
 &= 3a
 \end{aligned}$$

## Exercise 2

Calculate the gradient  $\nabla f$  of the following functions  $f(\mathbf{x})$ . In the left column,  $\mathbf{x} = (x_1, x_2, x_3)$ . In the right column,  $\mathbf{x} = (x_1, \dots, x_n)$ .

- |   |  |
|---|--|
| a) $f(x_1, x_2, x_3) = a_1 x_1 + a_2 x_2 + a_3 x_3$   | e) $f(\mathbf{x}) = \sum_{i=1}^n a_i x_i$    |
| b) $f(x_1, x_2, x_3) = x_2$                           | f) $f(\mathbf{x}) = x_i$                     |
| c) $f(x_1, x_2, x_3) = x_1 x_2 x_3$                   | g) $f(\mathbf{x}) = \prod_{i=1}^n x_i$       |
| d) $f(x_1, x_2, x_3) = x_1^{k_1} x_2^{k_2} x_3^{k_3}$ | h) $f(\mathbf{x}) = \prod_{i=1}^n x_i^{k_i}$ |

Note: often it suffices to write down the partial derivative  $\partial f / \partial x_j$  (Can you tell why?).

ANSWER: a)  $(a_1, a_2, a_3)$ , in other words  $\partial f / \partial x_i = a_i$ ,  $i = 1 \dots 3$

b)  $(0, 1, 0)$ , in other words  $\partial f / \partial x_j = \delta_{2j}$ ,  $j = 1 \dots 3$  (Kronecker delta, see slides)

c)  $(x_2 x_3, x_1 x_3, x_1 x_2)$

d)  $(k_1 x_1^{k_1-1} x_2^{k_2} x_3^{k_3}, k_2 x_1^{k_1} x_2^{k_2-1} x_3^{k_3}, k_3 x_1^{k_1} x_2^{k_2} x_3^{k_3-1})$  (where the  $k_i x_i^{k_i-1}$  is understood as 0 if  $k_i = 0$ )

e)  $(a_1, \dots, a_n)$  in other words  $\partial f / \partial x_j = a_j$

f)  $(\delta_{i1}, \dots, \delta_{in})$  in other words  $\partial f / \partial x_j = \delta_{ij}$

g) Note that  $\prod_{i=1}^n x_i = (\prod_{i=1, i \neq j}^n x_i) x_j$ , so  $\partial f / \partial x_j = \prod_{i=1, i \neq j}^n x_i$

h)  $\partial f / \partial x_j = k_j x_j^{k_j-1} \prod_{i=1, i \neq j}^n x_i^{k_i}$

To describe a vector say  $\vec{u} = (u_1, u_2, \dots, u_j, \dots, u_n)$ , it suffices to give the expression of an arbitrary component  $u_j$ . So  $u_j$  is some expression that contains  $j$ 's. All components and so the complete vector can then be reconstructed by filling in the appropriate component number for  $j$ . E.g. if you look for  $u_2$ , take the general expression for  $u_j$  and substitute all the  $j$ 's by a 2. Now the gradient  $\nabla f$  is also a vector. Its  $j$ -th component is just  $\partial f / \partial x_j$ , which is therefore sufficient to describe the vector  $\nabla f$ .

In many cases, it is convenient to only write down the abstract  $j$  component. However, it should be remembered that the gradient is an object with  $n$  components, and that it is sometimes more convenient to write down all the components. I think this could be argued for e.g. the gradient in b),  $\nabla f = (0, 1, 0)$ .

### Exercise 3

The function

$$f(x, y) = 2x^2 - xy + y^2 - x + y + 5.5 \quad (5)$$

has a unique minimum  $(x^*, y^*)$ . Calculate this point.

ANSWER: Partial derivatives of  $f$  are given by

$$\begin{aligned} \frac{\partial f}{\partial x} &= 4x - y - 1 \\ \frac{\partial f}{\partial y} &= 2y - x + 1 \end{aligned}$$

Setting equal to zero yields two equations for  $x$  and  $y$ . Solve the first to get:  $y = 4x - 1$ . Substituting in the second then gives:  $8x - 2 - x + 1 = 7x - 1 = 0 \Rightarrow x^* = 1/7$ , and so  $y^* = -3/7$ .

(As a side remark: it is indeed a *minimum* since the Hessian, the matrix of second order partial derivatives, is positive definite, meaning that  $x^T M x > 0$  for all vectors  $x$ . An equivalent statement is that the eigenvalues  $\lambda_i$  of the matrix  $M$  are all positive.)

### Exercise 4

Calculate the minimum  $x^*$  of the following two functions.

$$f(x) = \sum_{i=1}^n (x - a_i)^2 \quad (6)$$

ANSWER:

$$\begin{aligned} \frac{df(x)}{dx} &= 2 \sum_{i=1}^n (x - a_i) = 0 \\ \Rightarrow \sum_{i=1}^n x &= \sum_{i=1}^n a_i \\ \Rightarrow nx &= \sum_{i=1}^n a_i \\ \Rightarrow x &= \frac{1}{n} \sum_{i=1}^n a_i \end{aligned}$$

so  $x$  is the mean of the  $a_i$ 's.

There are several things to note:

- 1) derivative of a sum is a sum of derivatives
- 2)  $x$  has no subindex  $i$ . Therefore

$$\sum_{i=1}^n x = \underbrace{x + x + \dots + x}_{n \text{ times}} = nx$$

As a side remark: this minimization can be seen as a least square problem: given data  $a_i$ , which  $x$  gives the best fit such that the sum of the squares of the errors  $(x - a_i)$  is minimal. The solution is the data mean.

$$f(x) = \sum_{i=1}^n \alpha_i (x - a_i)^2 \quad (\text{with } \alpha_i > 0) \quad (7)$$

ANSWER:

$$\begin{aligned} \frac{df(x)}{dx} &= 2 \sum_{i=1}^n \alpha_i (x - a_i) = 0 \\ \Rightarrow \sum_{i=1}^n \alpha_i x &= \sum_{i=1}^n \alpha_i a_i \\ \Rightarrow x &= \frac{\sum_{i=1}^n \alpha_i a_i}{\sum_{i=1}^n \alpha_i} \end{aligned}$$

Side remark: This minimization can be seen as a weighted least square problem: given data  $a_i$ , which  $x$  gives the best fit such that the weighted sum of the squares of the errors  $(x - a_i)$  is minimal. The solution is the weighted average so here  $x$  is the weighted average of  $a_i$  with weights  $\alpha_i$ . The factor in the denominator (noemer) is for normalization (just as the  $n$  is in the previous case).

## Exercise 5

Calculate the gradient  $\nabla f$  of

$$f(\vec{h}) = \sum_{i=1}^n p_i h_i - \ln \left( \sum_{i=1}^n \exp(h_i) \right) \quad (8)$$

ANSWER:

$\vec{h}$  is a vector of  $n$  components  $(h_1, \dots, h_n)$ . The function  $f(\vec{h})$  is a scalar function of these  $n$  components; the  $p_i$  are constants. The gradient  $\nabla f$  is then the vector of partial derivatives of  $f$  w.r.t. each component  $h_j$ . Since

$$\frac{\partial}{\partial h_j} \left[ \sum_{i=1}^n p_i h_i \right] = p_j$$

and

$$\frac{\partial}{\partial h_j} \left[ \sum_{i=1}^n \exp(h_i) \right] = \exp(h_j)$$

application of the chain rule to (8) gives

$$\frac{\partial f}{\partial h_j} = p_j - \frac{\exp(h_j)}{\sum_{i=1}^n \exp(h_i)}$$

Side remark: this  $f$  is related to a so-called likelihood function (will be treated later in the course).

## Exercise 6

Compute the minimum  $x^*$  of

$$f(x) = a \ln(x) + \frac{b}{2x^2} \quad (9)$$

with  $a > 0$ ,  $b > 0$  en  $x > 0$ . Express your answer in terms of  $a$  en  $b$ . (Note:  $\ln(x)' = 1/x$ ).

ANSWER: Calculate gradient (slope) of  $f$ , set equal to zero and solve for  $x^*$

$$\begin{aligned} \frac{a}{x} - bx^{-3} = 0 &\Rightarrow a - bx^{-2} = 0 \\ &\Rightarrow ax^2 - b = 0 \\ &\Rightarrow x = \sqrt{b/a} \end{aligned}$$

Side remark: this  $f$  is also related to (another) likelihood function (will also be treated later in the course).

## Exercise 7

(see Bishop, appendix C, eq.C.1) An  $N \times M$  matrix  $\mathbf{A}$  has elements  $A_{ij}$  (with  $i$  the row- and  $j$  the columnindex). The transposed matrix  $\mathbf{A}^T$  has elements  $(\mathbf{A}^T)_{ij} = A_{ji}$ . By writing out the matrix product using index notation show that

$$(\mathbf{AB})^T = \mathbf{B}^T \mathbf{A}^T \quad (10)$$

Hint:  $\mathbf{C} = \mathbf{AB}$  corresponds to  $C_{ij} = \sum_{k=1}^M A_{ik} B_{kj}$

ANSWER:  $(\mathbf{A})_{ij} = A_{ij}$ ,  $(\mathbf{A}^T)_{ij} = A_{ji}$ ,  $(\mathbf{AB})_{ij} = \sum_k A_{ik} B_{kj}$  so

$$\begin{aligned} ((\mathbf{AB})^T)_{ij} &= (\mathbf{AB})_{ji} = \sum_k A_{jk} B_{ki} = \sum_k B_{ki} A_{jk} \\ &= \sum_k (\mathbf{B}^T)_{ik} (\mathbf{A}^T)_{kj} = (\mathbf{B}^T \mathbf{A}^T)_{ij} \end{aligned}$$

## Exercise 8

( Exercise 1.1 from the Bishop book.) Consider the M-th order polynomial

$$y(x; \mathbf{w}) = w_0 + w_1 x + \dots + w_M x^M = \sum_{j=0}^M w_j x^j \quad (11)$$

and the error function

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \{y(x_n; \mathbf{w}) - t_n\}^2 \quad (12)$$

with  $x_n, t_n$  the input/output pairs from the data set. Define the error per data point as

$$E_n(\mathbf{w}) = \frac{1}{2} \{y(x_n; \mathbf{w}) - t_n\}^2 \quad (13)$$

(so  $E = \sum_{n=1}^N E_n$ ). Note that  $x$  is 1-dimensional, and that in this exercise the super-indices  $i, j$  represent ‘power’.

1. Calculate the gradient of the error per data point  $E_n$ :

$$\nabla E_n = \left( \frac{\partial E_n}{\partial w_0}, \dots, \frac{\partial E_n}{\partial w_M} \right)^T. \quad (14)$$

ANSWER: Use the chain rule on  $E_n(\mathbf{w}) = \frac{1}{2} \{u(\mathbf{w})\}^2$  with  $u(\mathbf{w}) = y(x_n; \mathbf{w}) - t_n$ . Then for the components of the gradient

$$\begin{aligned} \frac{\partial E_n}{\partial w_i} &= \frac{\partial E_n}{\partial u} \frac{\partial u}{\partial w_i} \\ &= u(\mathbf{w}) \frac{\partial u(\mathbf{w})}{\partial w_i} \\ &= (y(x_n; \mathbf{w}) - t_n) \frac{\partial y(x_n; \mathbf{w}) - t_n}{\partial w_i} \\ &= \left( \sum_{j=0}^M w_j (x_n)^j - t_n \right) \frac{\partial}{\partial w_i} \left[ \sum_{k=0}^M w_k x_n^k - t_n \right] \\ &= \left( \sum_{j=0}^M w_j x_n^j - t_n \right) x_n^i \\ &= \sum_{j=0}^M w_j x_n^{i+j} - t_n x_n^i \end{aligned}$$

Note that  $x_n^i$  means:  $x_n$  to-the-power-of  $i$ . Note that in general  $x^a x^b = x^{a+b}$ , e.g.  $2^3 2^4 = 2^7$

If you got this answer by direct differentiation e.g. by writing out the  $y$ 's in terms of  $w$ 's, without the use of an  $u$ , that is of course also ok.

2. Calculate the gradient of the total error  $E$ .

ANSWER: The total error  $E$  is the sum of the errors per datapoint  $E_n$ . Since the gradient is a linear function of its operands:  $\nabla(f + g) = \nabla f + \nabla g$ , the gradient of the total error is the sum of the gradients of the error per datapoint:

$$\nabla E = \sum_{n=1}^N \nabla E_n$$

with  $\nabla E_n$  as above. So,

$$\frac{\partial E}{\partial w_i} = \sum_{n=1}^N \left( \sum_{j=0}^M w_j x_n^{i+j} - t_n x_n^i \right)$$

3. Show that the partial derivatives can be written as

$$\frac{\partial E}{\partial w_i} = \sum_{j=0}^M A_{ij} w_j - T_i \quad (15)$$

with  $A_{ij}$  and  $T_i$  defined as

$$A_{ij} = \sum_{n=1}^N x_n^{i+j} \quad T_i = \sum_{n=1}^N t_n x_n^i. \quad (16)$$

ANSWER: Substituting the result for the components of  $\nabla E_n$  into (2) we have

$$\begin{aligned} \frac{\partial E}{\partial w_i} &= \sum_{n=1}^N \left( \sum_{j=0}^M w_j x_n^{i+j} - t_n x_n^i \right) \\ &= \sum_{n=1}^N \sum_{j=0}^M w_j x_n^{i+j} - \sum_{n=1}^N t_n x_n^i \\ &= \sum_{j=0}^M \sum_{n=1}^N x_n^{i+j} w_j - \sum_{n=1}^N t_n x_n^i \\ &= \sum_{j=0}^M A_{ij} w_j - T_i \end{aligned}$$

4. When  $E$  is minimal it holds that  $\nabla E = 0$  (i.e., all partial derivatives are zero). Using this, show that in the minimum of  $E$  the parameters  $\mathbf{w}$  satisfy

$$\sum_{j=0}^M A_{ij} w_j = T_i. \quad (17)$$

ANSWER: In the last result, setting all partial derivatives equal to zero implies that when the error is minimal then

$$\sum_{j=0}^M A_{ij} w_j - T_i = 0 \Rightarrow \sum_{j=0}^M A_{ij} w_j = T_i.$$