

Evaluation

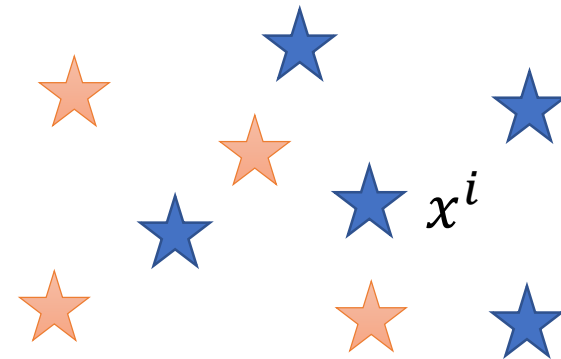
Ref: Lucas Theis, Aäron van den Oord, Matthias Bethge, “A note on the evaluation of generative models”, arXiv preprint, 2015

Likelihood

★ : real data (not observed during training)

★ : generated data

Prior
Distribution



傳統的衡量方法就是算generative data的likelihood

但是我們沒有辦法計算 $P_G(x^i)$ ，因為無法計算指定產生某張圖片的機率

$$\text{Log Likelihood: } L = \frac{1}{N} \sum_i \log P_G(x^i)$$

We cannot compute $P_G(x^i)$. We can only sample from P_G .

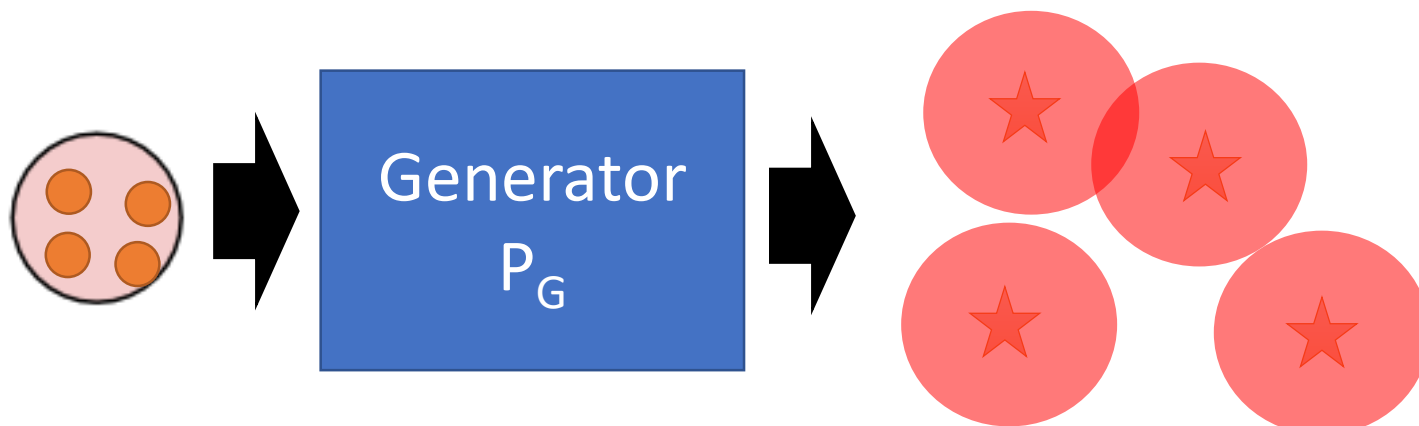
Likelihood

但是我們他媽的要用幾個gaussian model??
而且我們他媽的要generate幾個data才夠去fit??

- Kernel Density Estimation

先讓generator產生一堆圖片，再用gaussian mixture model去fit 他們

- Estimate the distribution of $P_G(x)$ from sampling



Each sample is the mean of a Gaussian with the same covariance.

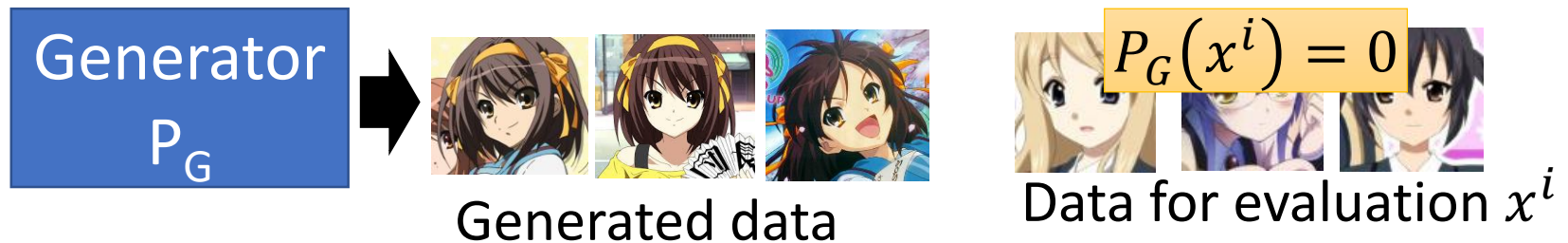
Now we have an approximation of P_G , so we can compute $P_G(x^i)$ for each real data x^i

Then we can compute the likelihood.

Likelihood v.s. Quality

- Low likelihood, high quality?

Considering a model generating good images (small variance)



- High likelihood, low quality?

好一百倍的model，但是在likelihood只差了...4.6 (感覺不出差別)



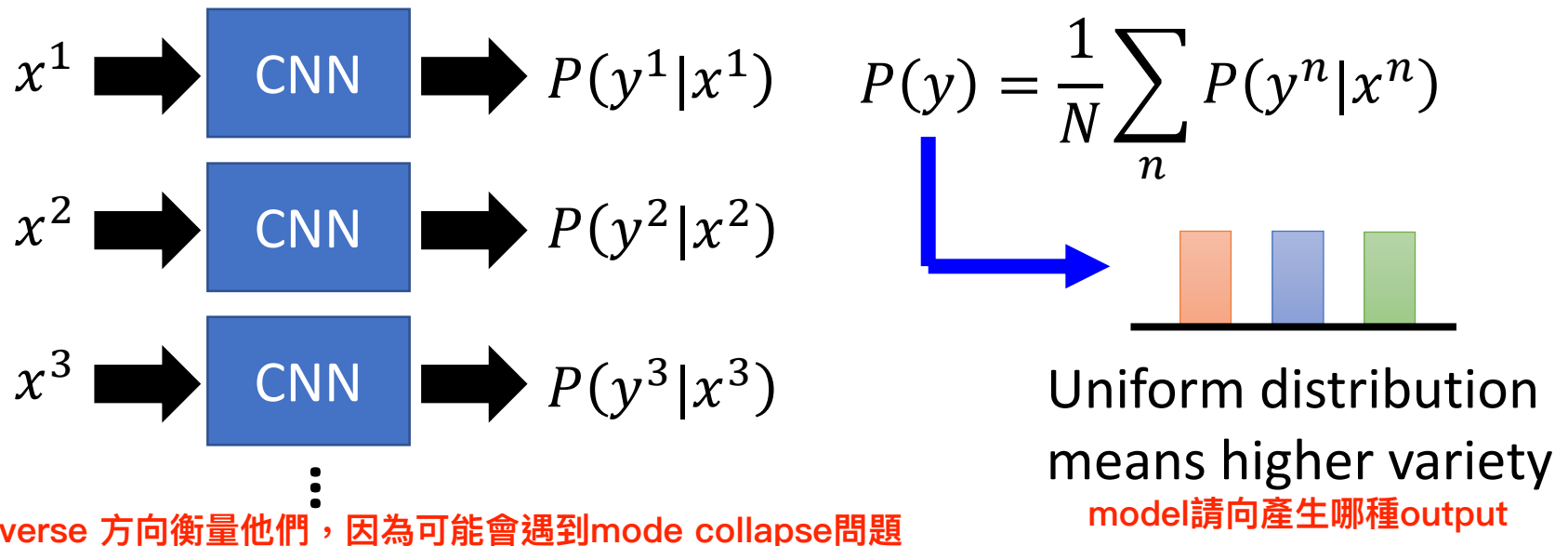
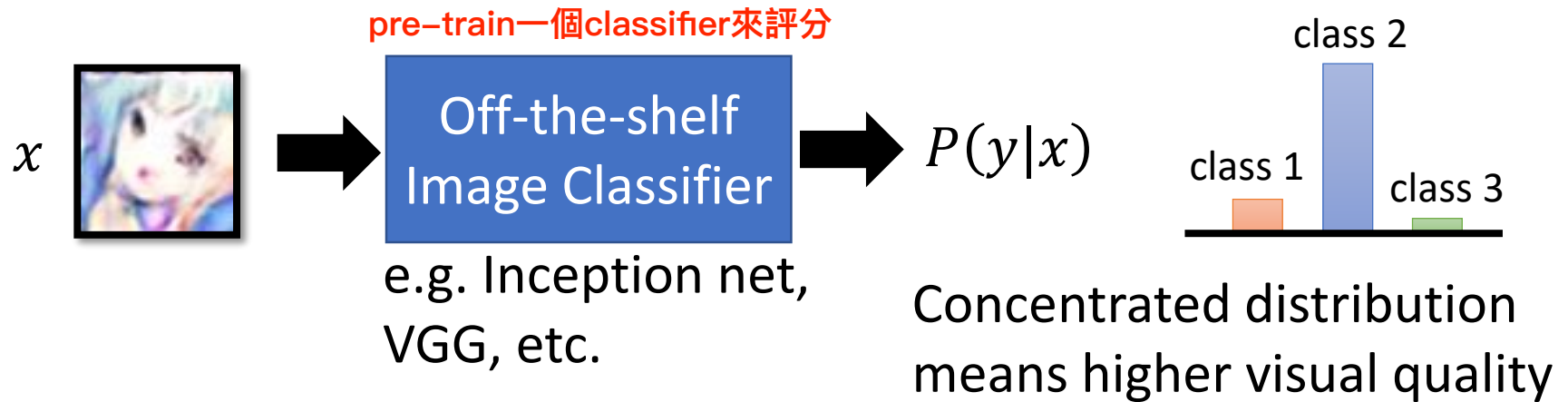
$$L = \frac{1}{N} \sum_i \log \frac{P_G(x^i)}{100} = -\log 100 + \frac{1}{N} \sum_i \log P_G(x^i)$$

100
4.6

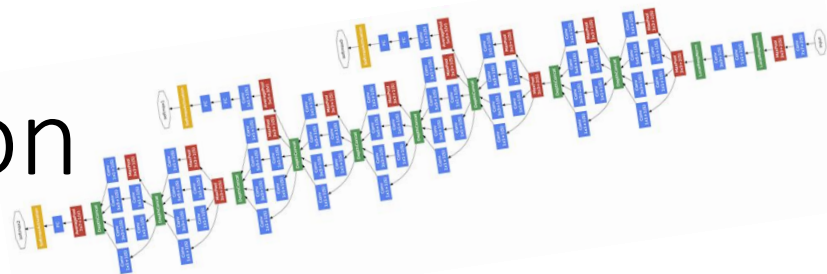
Objective Evaluation

x : image

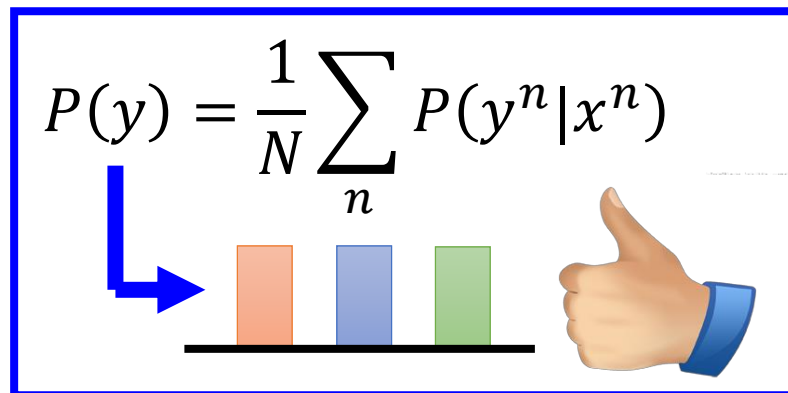
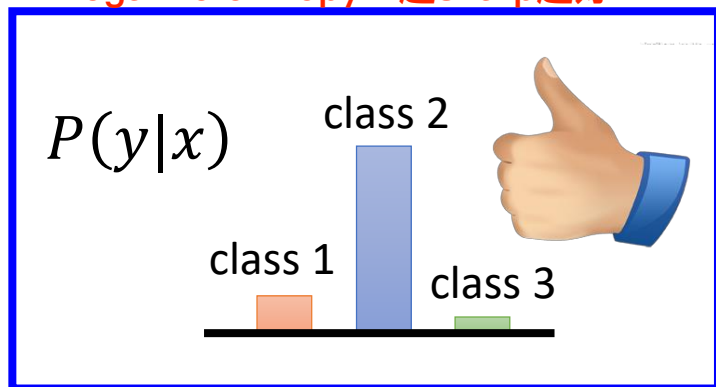
y : class (output of CNN)



Objective Evaluation



classifier裡算distribution算
negative entropy，越sharp越好



因為他用inception network
Inception Score

平均的結果entropy越大越好 (?)

$$= \sum_x \sum_y \underline{P(y|x) \log P(y|x)} - \underline{\sum_y P(y) \log P(y)}$$

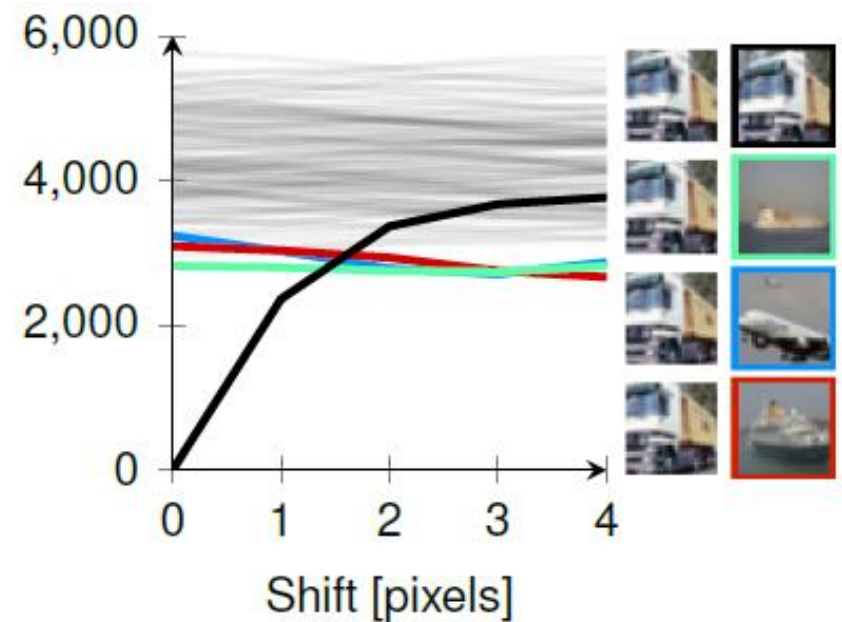
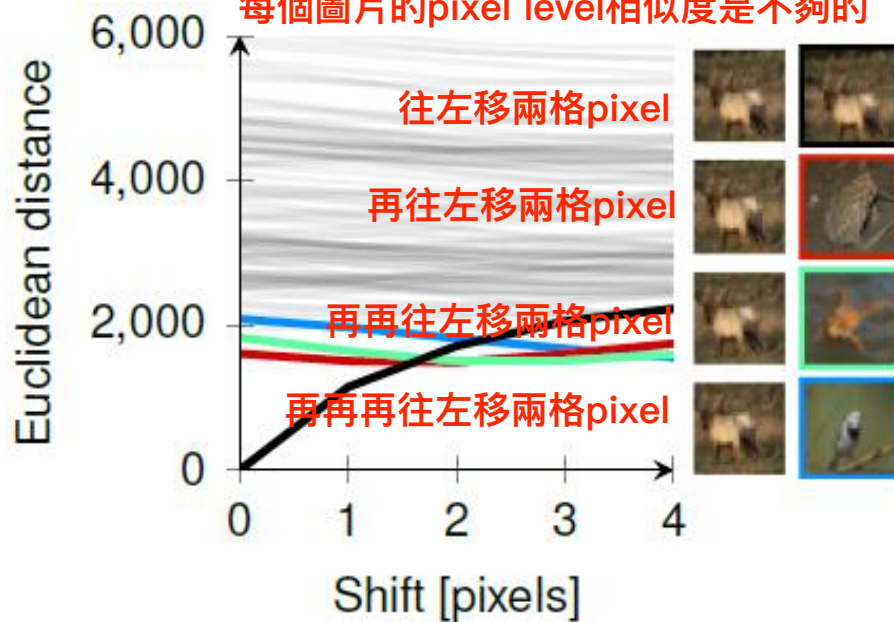
Negative entropy of $P(y|x)$

Entropy of $P(y)$

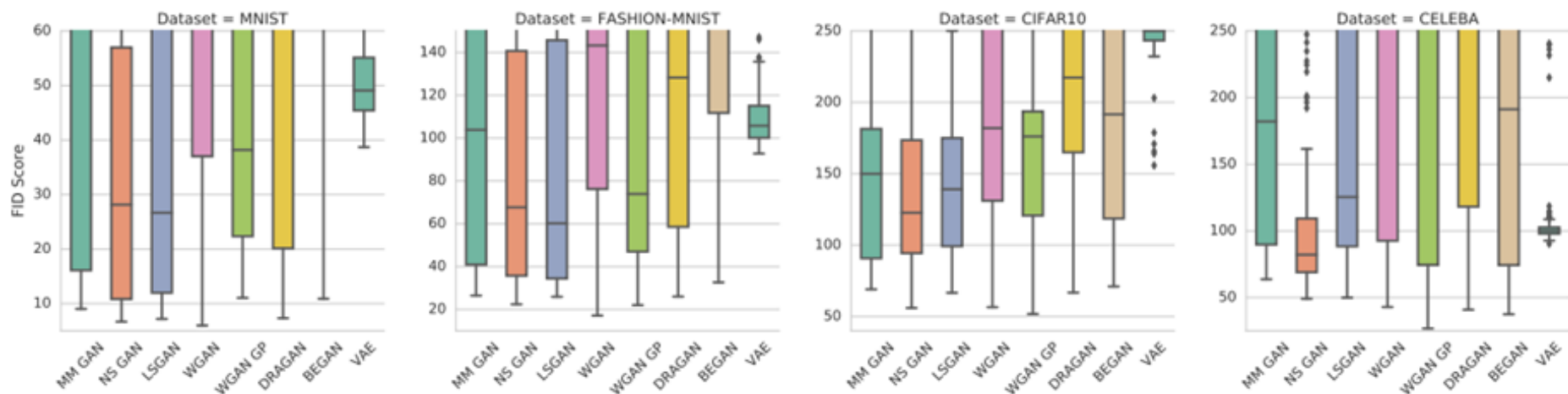
We don't want memory GAN.

- Using k-nearest neighbor to check whether the generator generates new objects

如果只算generative data與dataset中
每個圖片的pixel level相似度是不夠的



| GAN | DISCRIMINATOR LOSS | GENERATOR LOSS |
|---------|--|---|
| MM GAN | $\mathcal{L}_D^{\text{GAN}} = -\mathbb{E}_{x \sim p_d} [\log(D(x))] + \mathbb{E}_{\hat{x} \sim p_g} [\log(1 - D(\hat{x}))]$ | $\mathcal{L}_G^{\text{GAN}} = -\mathcal{L}_D^{\text{GAN}}$ |
| NS GAN | $\mathcal{L}_D^{\text{NSGAN}} = \mathcal{L}_D^{\text{GAN}}$ | $\mathcal{L}_G^{\text{NSGAN}} = \mathbb{E}_{\hat{x} \sim p_g} [\log(D(\hat{x}))]$ |
| WGAN | $\mathcal{L}_D^{\text{WGAN}} = -\mathbb{E}_{x \sim p_d} [D(x)] + \mathbb{E}_{\hat{x} \sim p_g} [D(\hat{x})]$ | $\mathcal{L}_G^{\text{WGAN}} = -\mathcal{L}_D^{\text{WGAN}}$ |
| WGAN GP | $\mathcal{L}_D^{\text{WGAN}} = \mathcal{L}_D^{\text{WGAN}} + \lambda \mathbb{E}_{\hat{x} \sim p_g} [(\nabla D(\alpha x + (1 - \alpha)\hat{x}) _2 - 1)^2]$ | $\mathcal{L}_G^{\text{WGAN}} = -\mathbb{E}_{\hat{x} \sim p_g} [D(\hat{x})]$ |
| LS GAN | $\mathcal{L}_D^{\text{LSGAN}} = -\mathbb{E}_{x \sim p_d} [(D(x) - 1)^2] + \mathbb{E}_{\hat{x} \sim p_g} [D(\hat{x})^2]$ | $\mathcal{L}_G^{\text{LSGAN}} = -\mathbb{E}_{\hat{x} \sim p_g} [(D(\hat{x}) - 1)^2]$ |
| DRAGAN | $\mathcal{L}_D^{\text{DRAGAN}} = \mathcal{L}_D^{\text{GAN}} + \lambda \mathbb{E}_{\hat{x} \sim p_d + \mathcal{N}(0, c)} [(\nabla D(\hat{x}) _2 - 1)^2]$ | $\mathcal{L}_G^{\text{DRAGAN}} = -\mathcal{L}_D^{\text{NSGAN}}$ |
| BEGAN | $\mathcal{L}_D^{\text{BEGAN}} = \mathbb{E}_{x \sim p_d} [x - \text{AE}(x) _1] - k_t \mathbb{E}_{\hat{x} \sim p_g} [\hat{x} - \text{AE}(\hat{x}) _1]$ | $\mathcal{L}_G^{\text{BEGAN}} = \mathbb{E}_{\hat{x} \sim p_g} [\hat{x} - \text{AE}(\hat{x}) _1]$ |



Smaller is better

FIT:

<https://arxiv.org/pdf/1706.08500.pdf>

Mario Lucic, Karol Kurach, Marcin Michalski, Sylvain Gelly, Olivier Bousquet, "Are GANs Created Equal? A Large-Scale Study", arXiv, 2017

Missing Mode ?

Mode collapse is easy to detect.



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