

Feature Extraction

InfoGAN

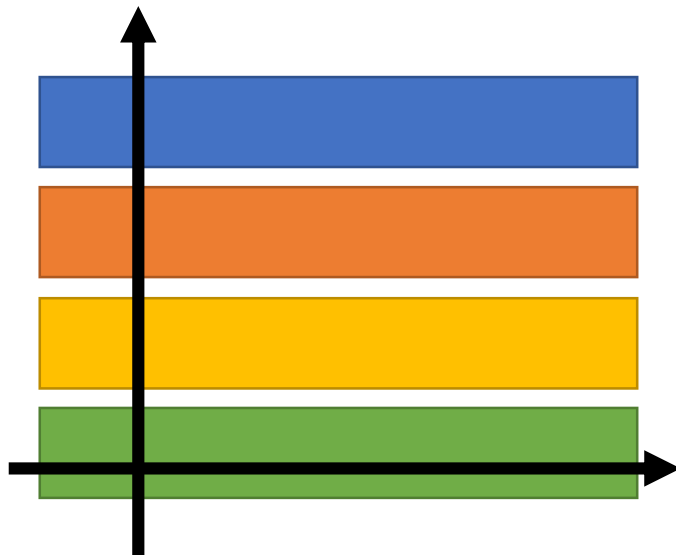
(The colors
represents the
characteristics.)

Regular
GAN

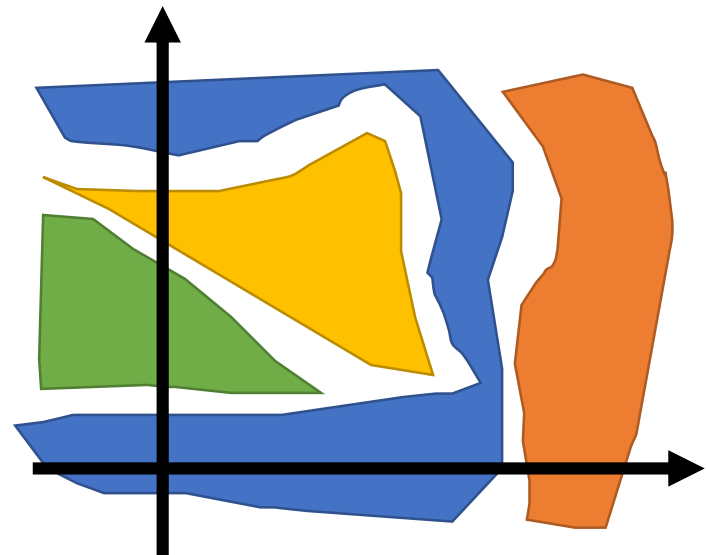


Modifying a specific dimension,
no clear meaning

What we expect



Actually ...



input vector characteristics

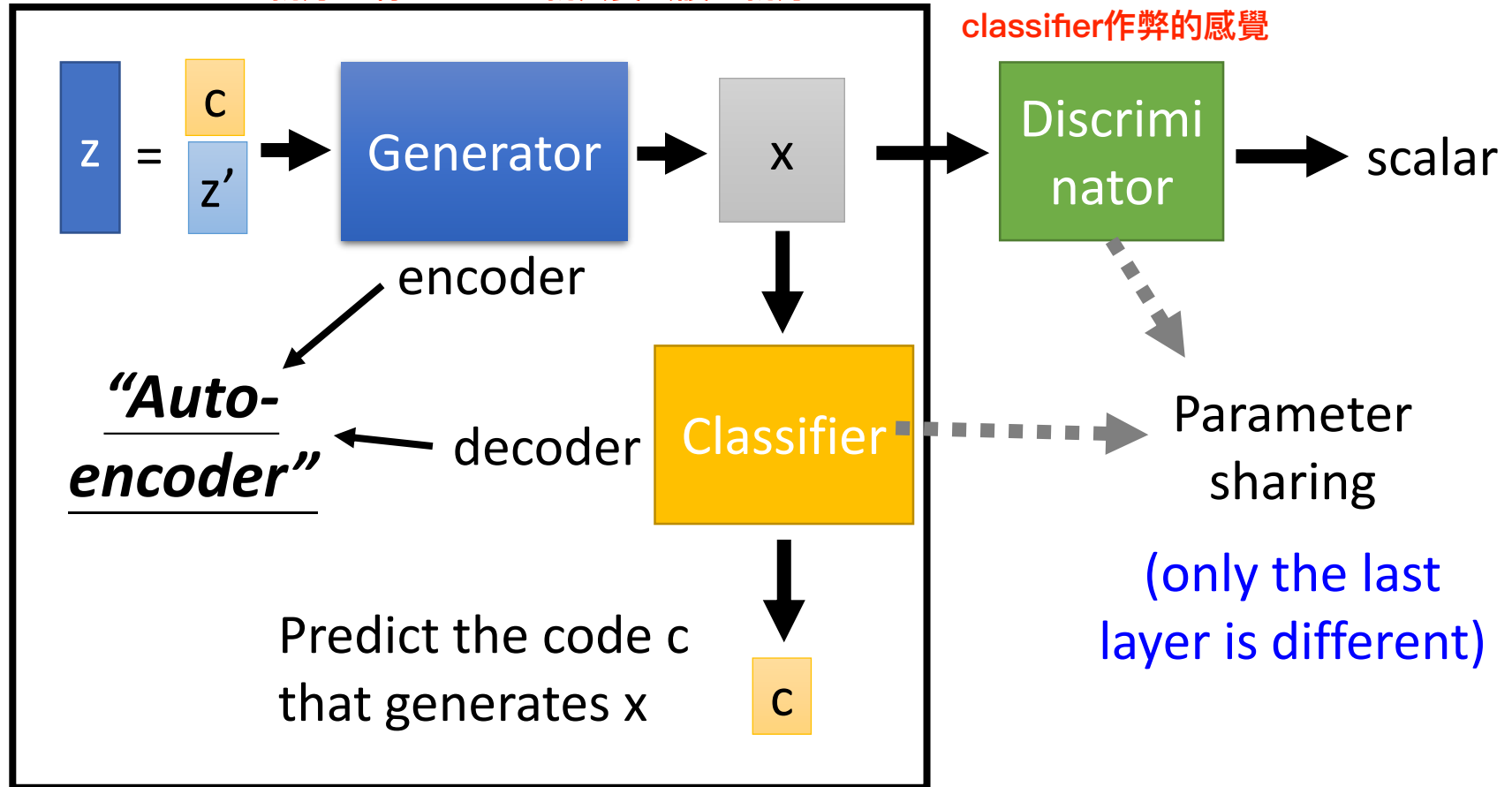
What is InfoGAN?

一定要discriminator，不然的話最簡單的方法G只

要在imageX中間貼一個

'c'就好，啊classifier就只要去讀它就好

有點像防止G跟
classifier作弊的感覺



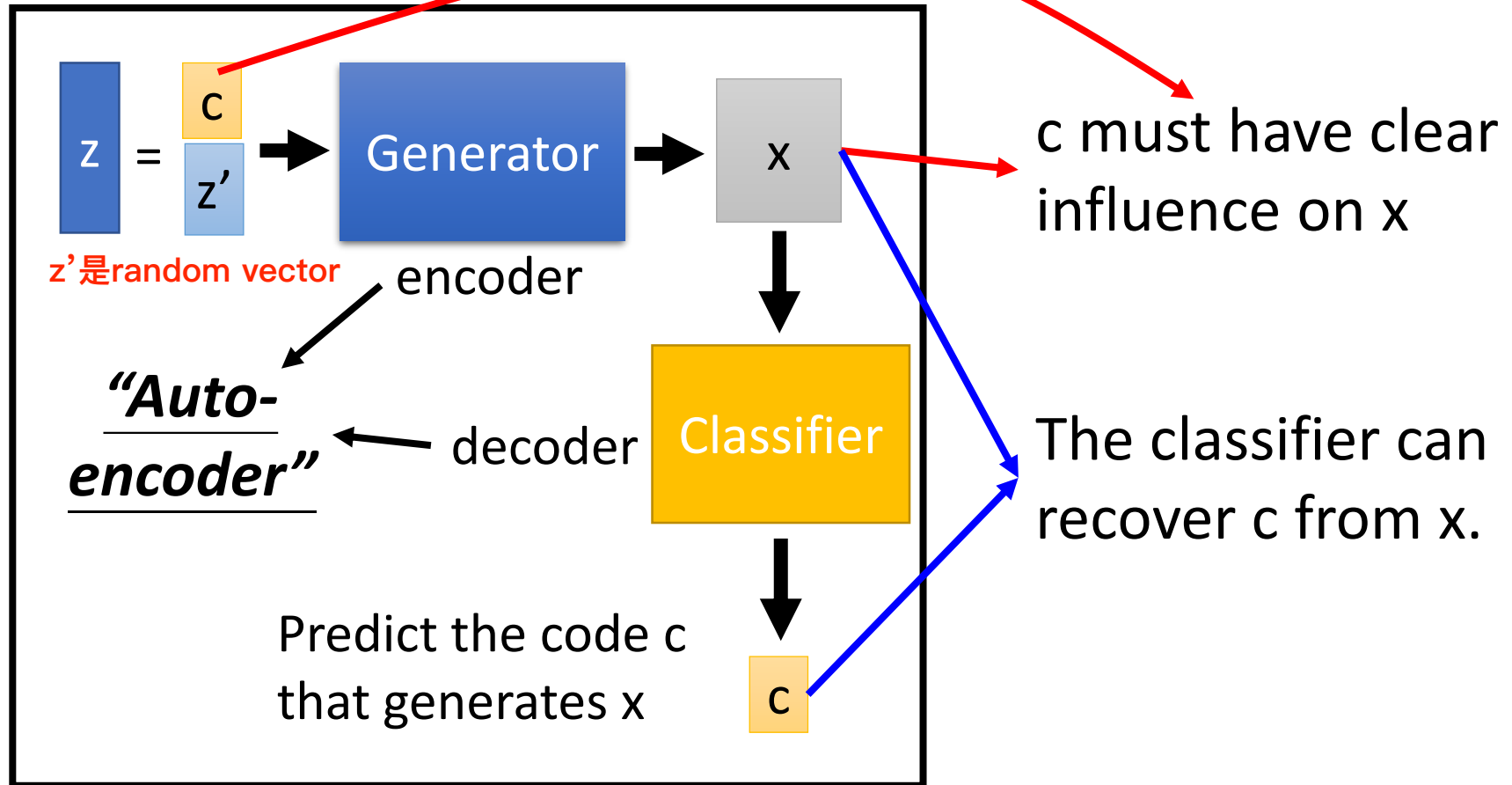
Predict the code c
that generates x

(only the last
layer is different)

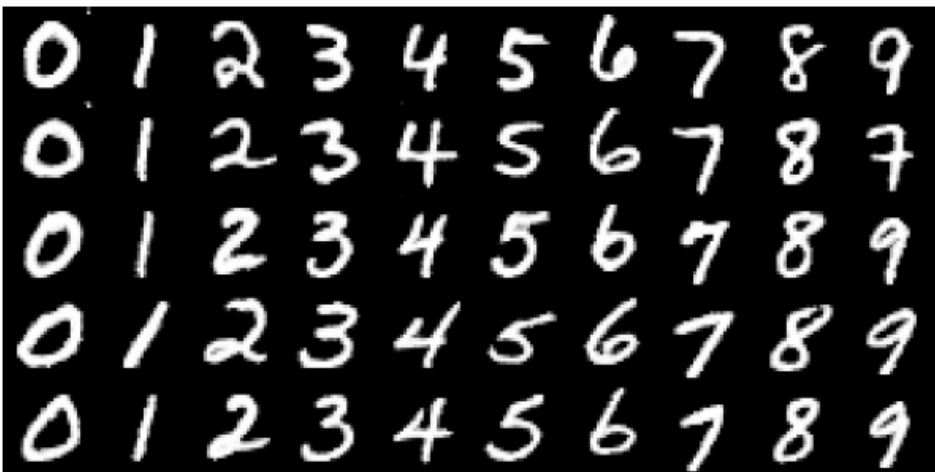
根據image x 判斷他的類別 c

What is InfoGAN?

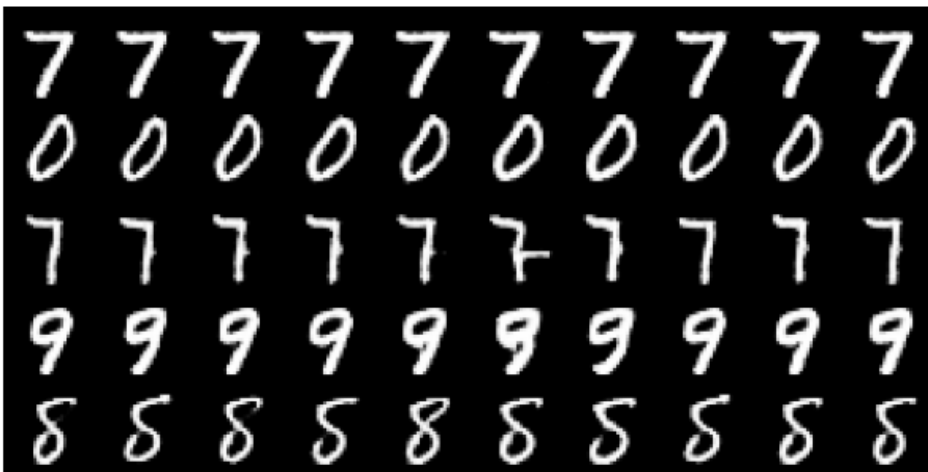
G要學會對c的每一個維度變化造成x的影響



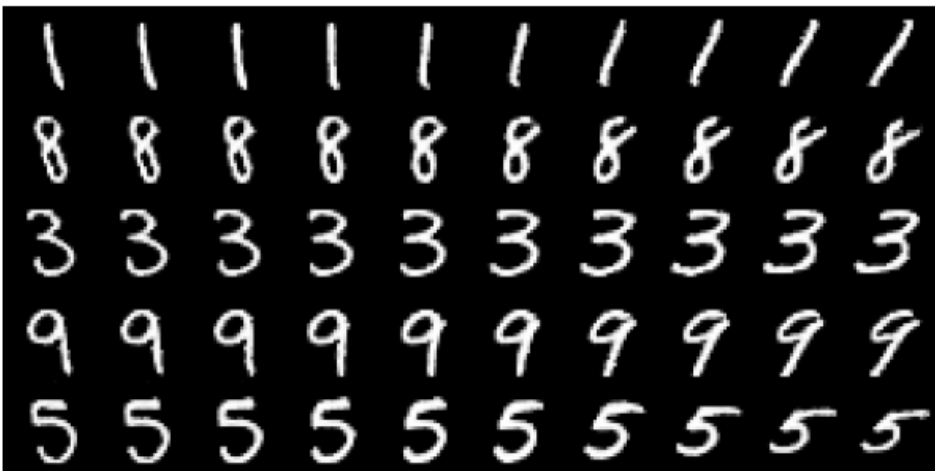
因為他被設為' c '，經過infoGAN的訓練後使得這些 c 被代表某些意義



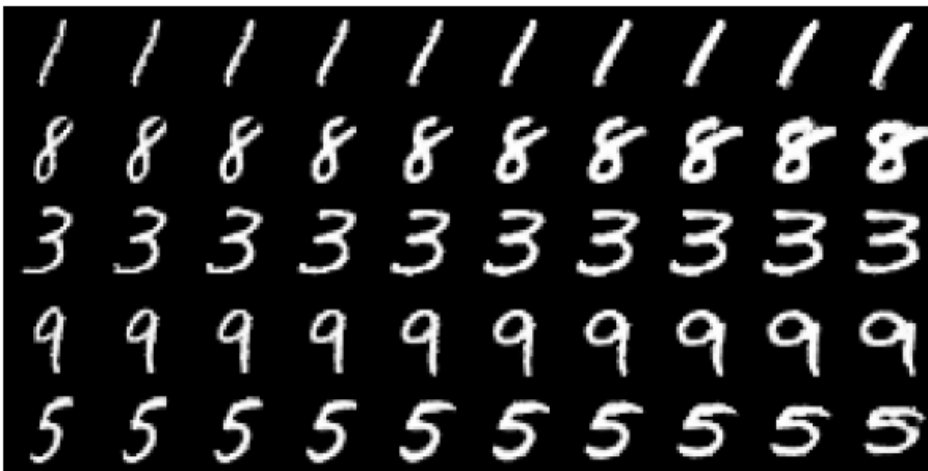
(a) Varying c_1 on InfoGAN (Digit type)



(b) Varying c_1 on regular GAN (No clear meaning)



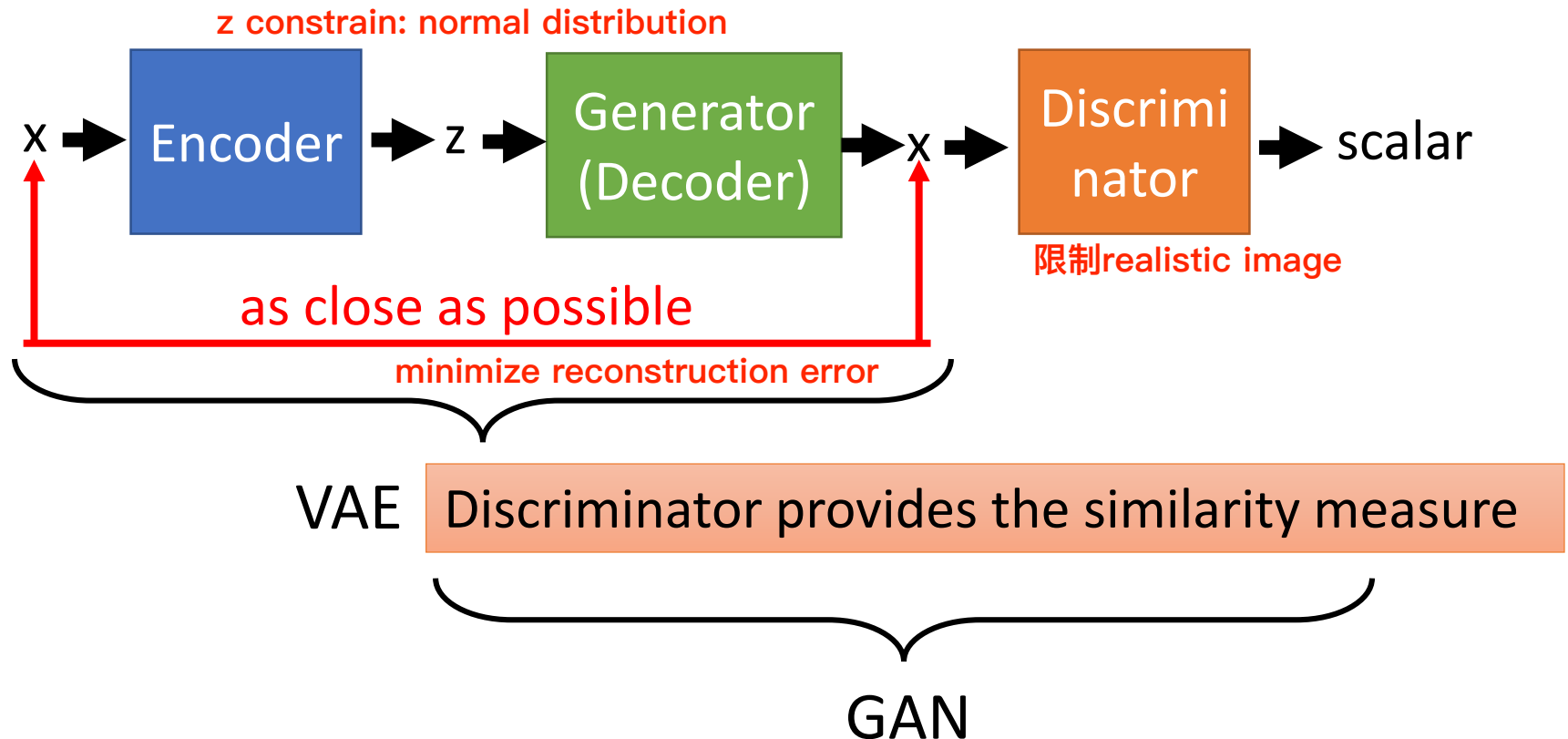
(c) Varying c_2 from -2 to 2 on InfoGAN (Rotation)



(d) Varying c_3 from -2 to 2 on InfoGAN (Width)

VAE-GAN

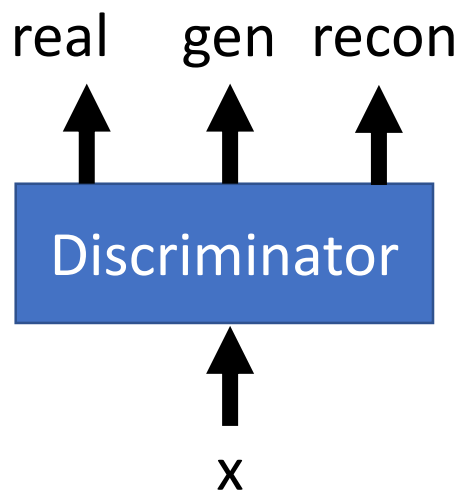
- Minimize reconstruction error
- z close to normal
- Minimize reconstruction error
- Cheat discriminator
- Discriminate real, generated and reconstructed images



Algorithm

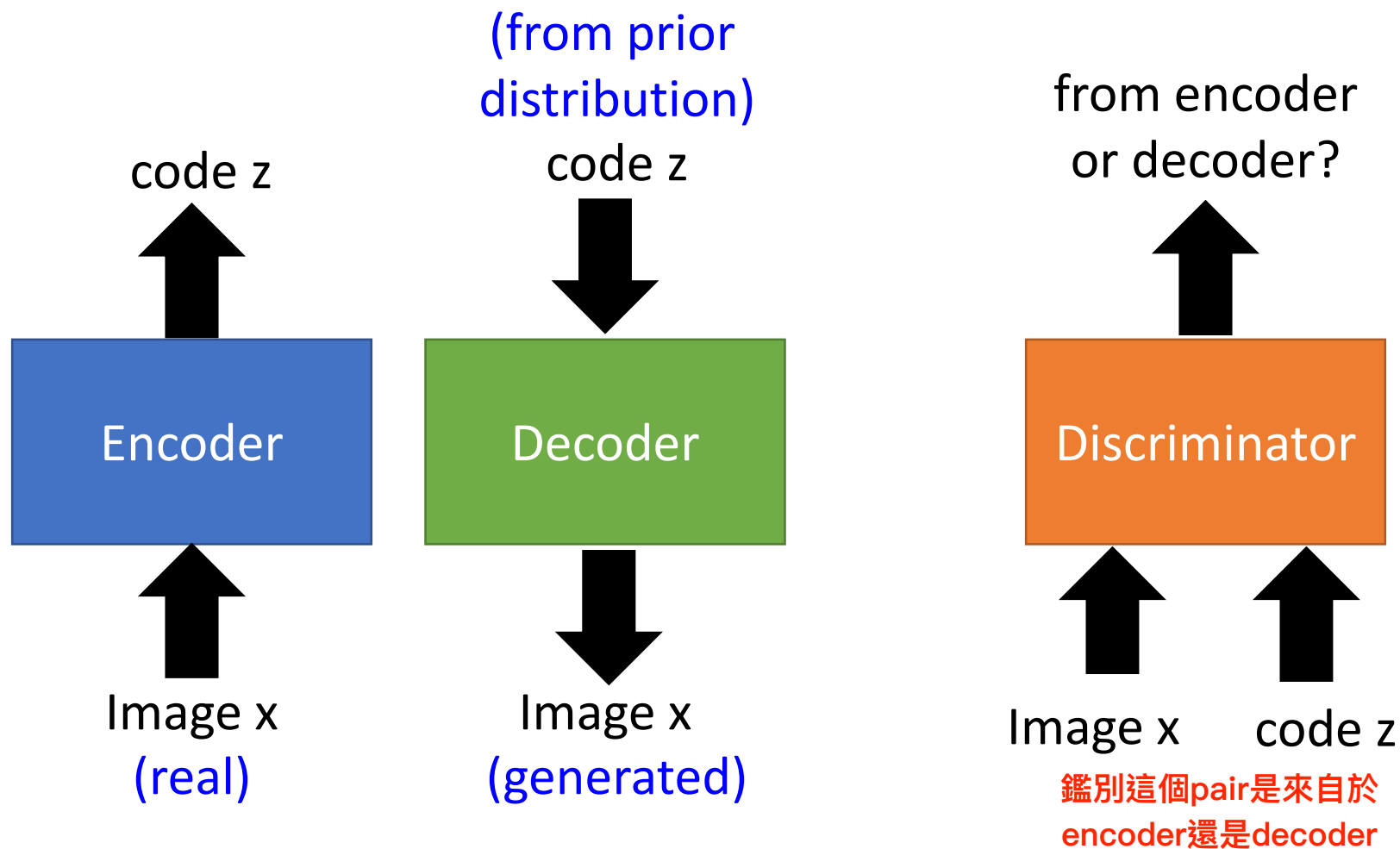
- Initialize En, De, Dis
- In each iteration:
 - Sample M images x^1, x^2, \dots, x^M from database
 - Generate M codes $\tilde{z}^1, \tilde{z}^2, \dots, \tilde{z}^M$ from encoder
 - $\tilde{z}^i = En(x^i)$
 - Generate M images $\tilde{x}^1, \tilde{x}^2, \dots, \tilde{x}^M$ from decoder
 - $\tilde{x}^i = De(\tilde{z}^i)$
 - Sample M codes z^1, z^2, \dots, z^M from prior $P(z)$ sample from normal distribution
 - Generate M images $\hat{x}^1, \hat{x}^2, \dots, \hat{x}^M$ from decoder
 - $\hat{x}^i = De(z^i)$
 - Update En to decrease $\|\tilde{x}^i - x^i\|$, decrease $KL(P(\tilde{z}^i | x^i) || P(z))$ 希望code z越接近normal distribution越好
 - Update De to decrease $\|\tilde{x}^i - x^i\|$, increase $Dis(\tilde{x}^i)$ and $Dis(\hat{x}^i)$
reconstruct image real image
 - Update Dis to increase $Dis(x^i)$, decrease $Dis(\tilde{x}^i)$ and $Dis(\hat{x}^i)$

Another kind of discriminator:



BiGAN

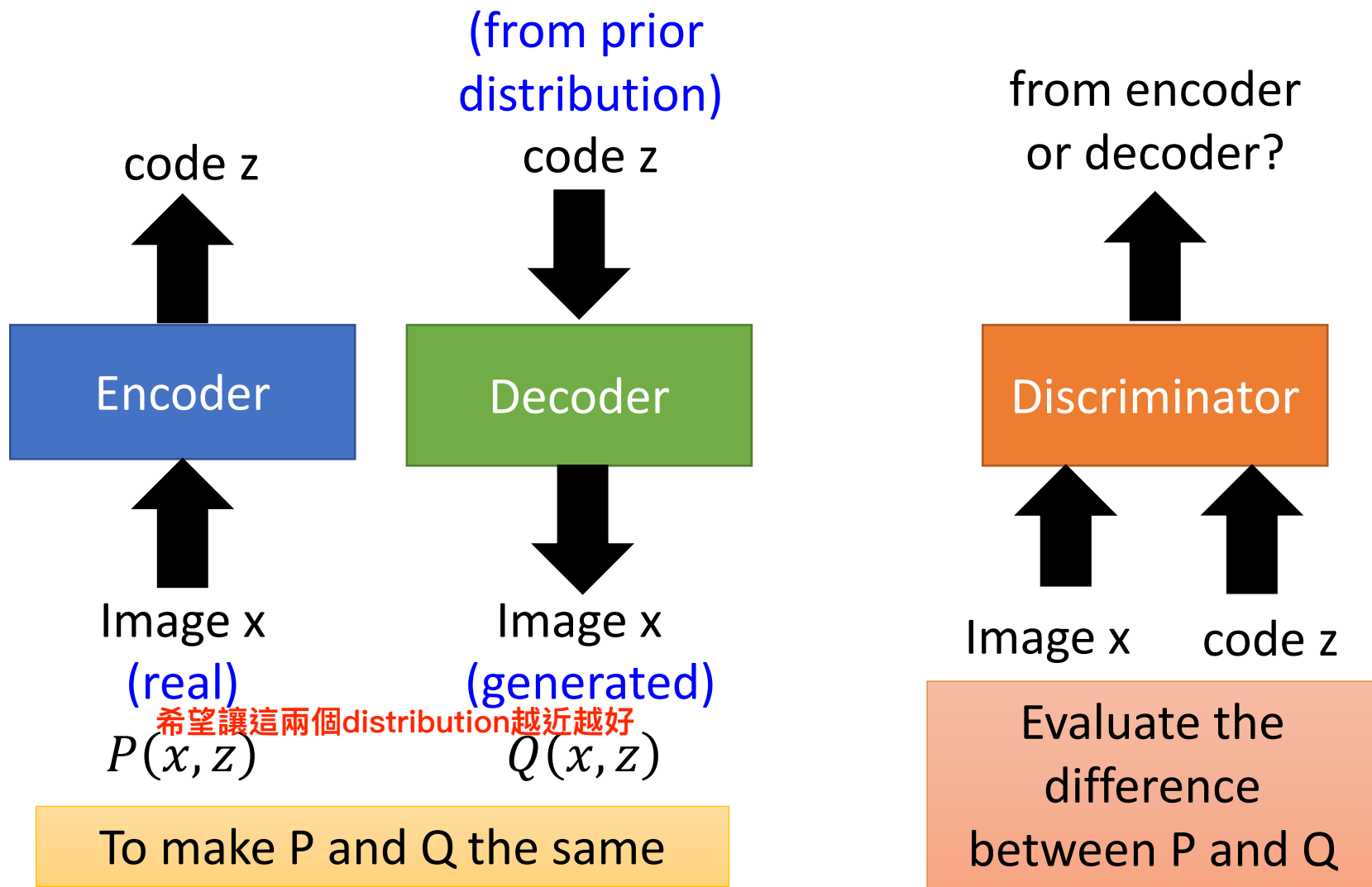
input/output並沒有接在一起



Algorithm

迫使encoder跟decoder合作一起騙過discriminator

- Initialize encoder En, decoder De, discriminator Dis
- In each iteration:
 - Sample M images x^1, x^2, \dots, x^M from database
 - Generate M codes $\tilde{z}^1, \tilde{z}^2, \dots, \tilde{z}^M$ from encoder
 - $\tilde{z}^i = En(x^i)$ encoder
 - Sample M codes z^1, z^2, \dots, z^M from prior $P(z)$
 - Generate M codes $\tilde{x}^1, \tilde{x}^2, \dots, \tilde{x}^M$ from decoder
 - $\tilde{x}^i = De(z^i)$ decoder
 - Update Dis to increase $Dis(x^i, \tilde{z}^i)$, decrease $Dis(\tilde{x}^i, z^i)$
不管給誰高分給誰低分都是一樣的意思 encoder decoder
 - Update En and De to decrease $Dis(x^i, \tilde{z}^i)$, increase $Dis(\tilde{x}^i, z^i)$



Optimal encoder
and decoder:

$$\text{En}(x') = z'$$



$$\text{De}(z') = x'$$

For all x'

$$\text{De}(z'') = x''$$



$$\text{En}(x'') = z''$$

For all z''

BiGAN

auto encoder產生的圖會模糊

biGAN可以產生較清晰的圖片，但是可能input是一隻鳥，output是另外一隻鳥（清晰的圖片）

optimal solution是一樣的，但是兩個都無法達到optimal，且兩個的error surface是不一樣的

Optimal encoder
and decoder:

$$\text{En}(x') = z'$$



$$\text{De}(z') = x'$$

For all x'

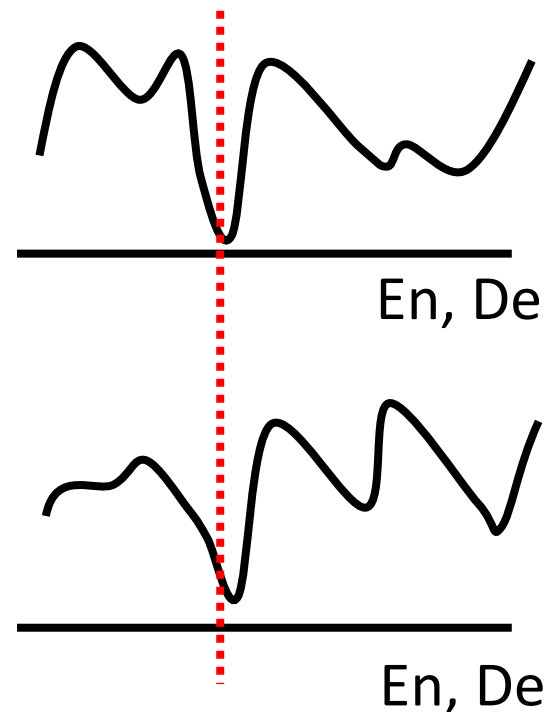
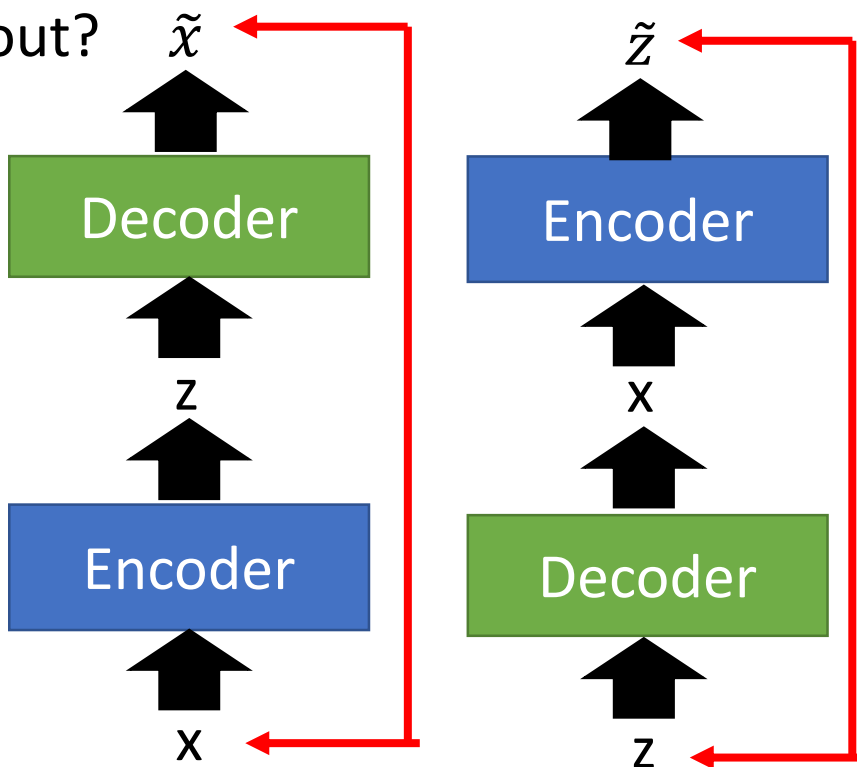
$$\text{De}(z'') = x''$$



$$\text{En}(x'') = z''$$

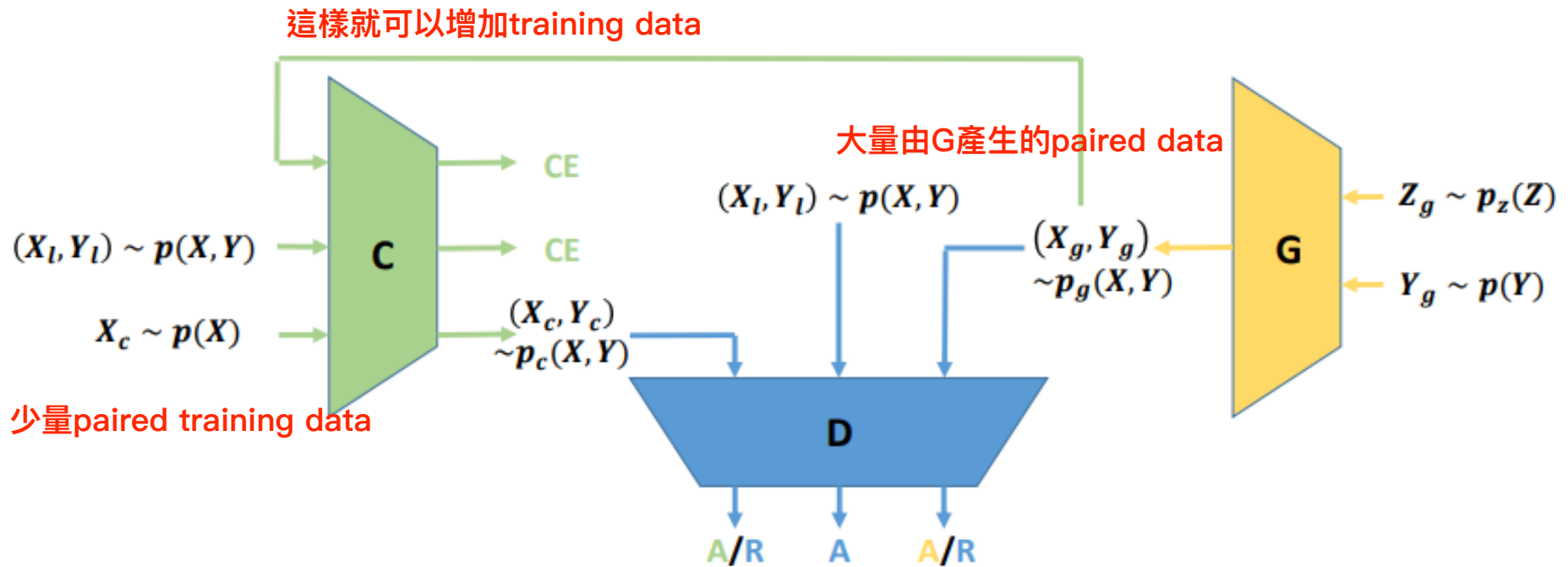
For all z''

How about?



Triple GAN

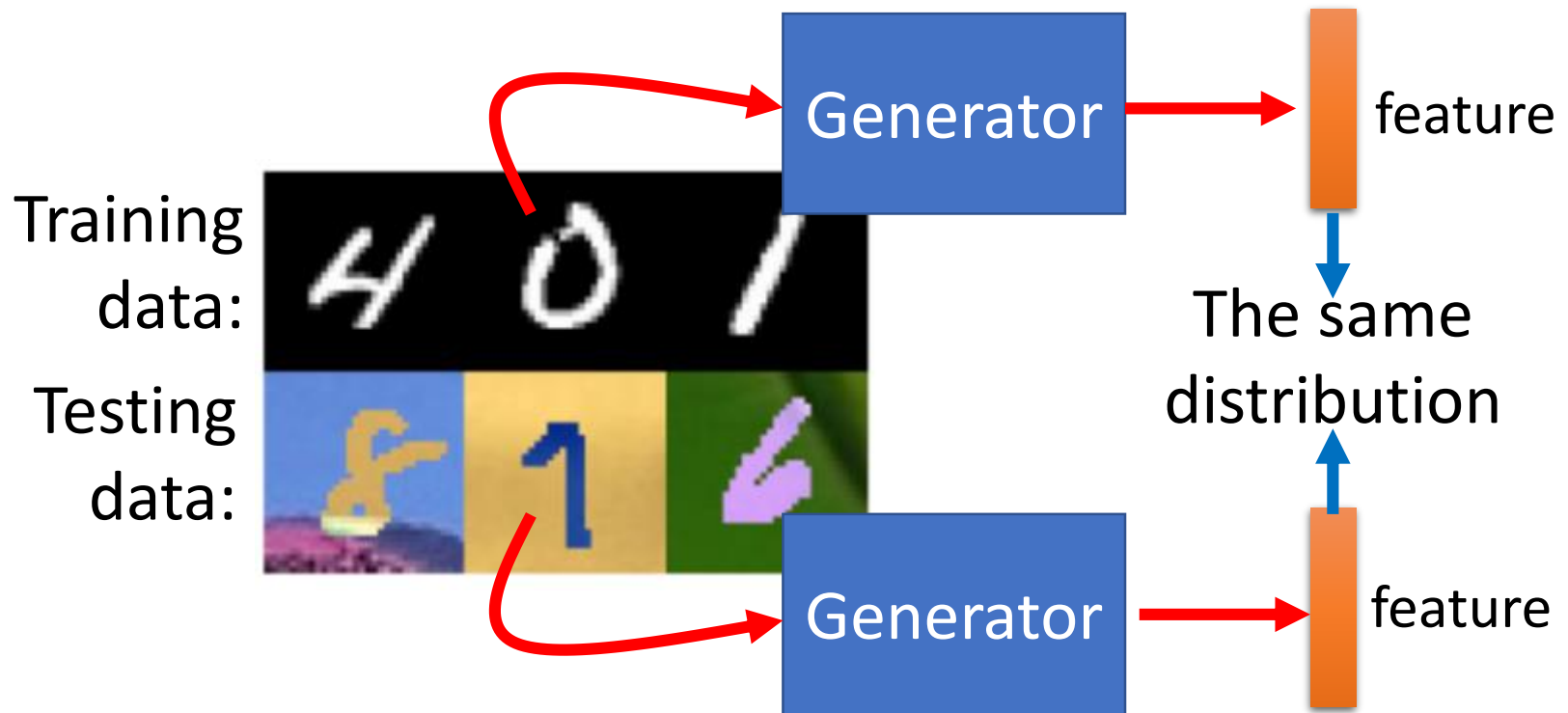
semi-supervised learning



Chongxuan Li, Kun Xu, Jun Zhu, Bo Zhang, "Triple Generative Adversarial Nets", arXiv 2017

Domain-adversarial training

- Training and testing data are in different domains

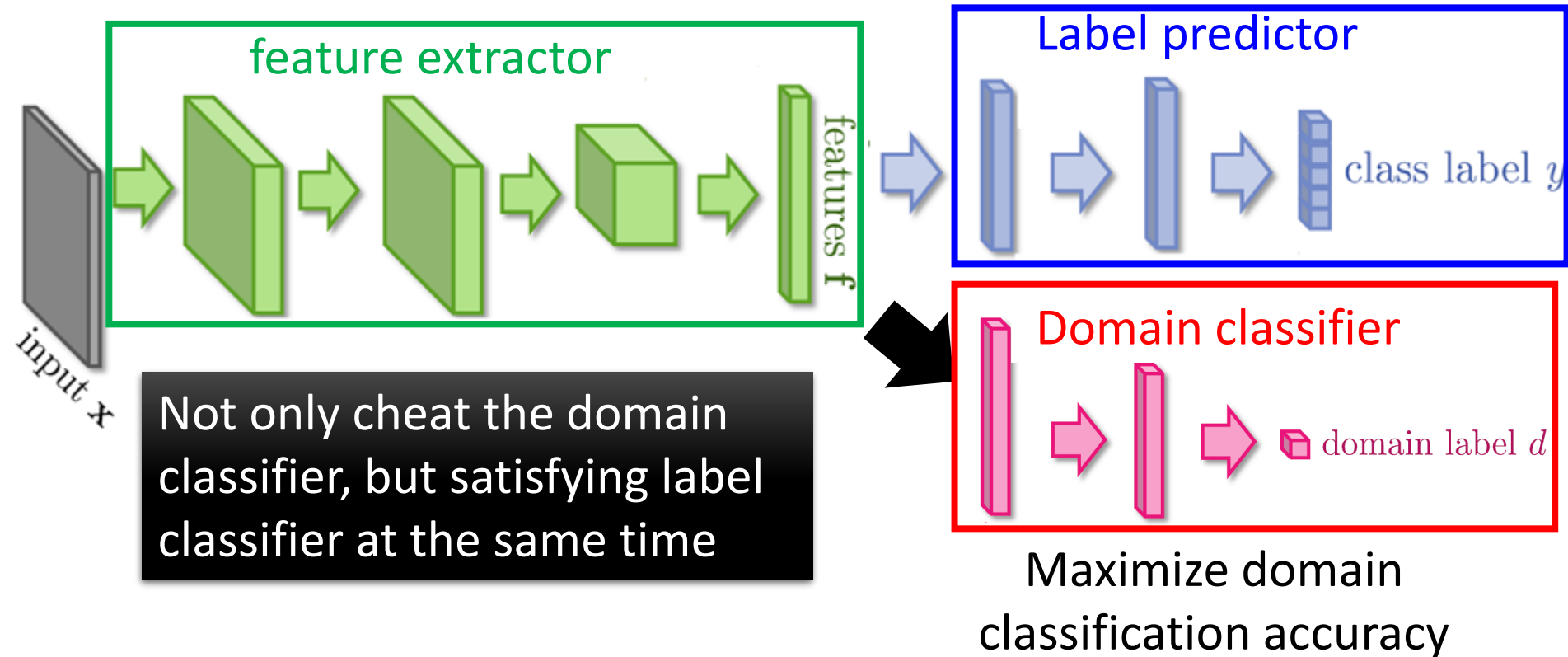


Domain-adversarial training

原始是一起learn的

Maximize label classification accuracy +
minimize domain classification accuracy

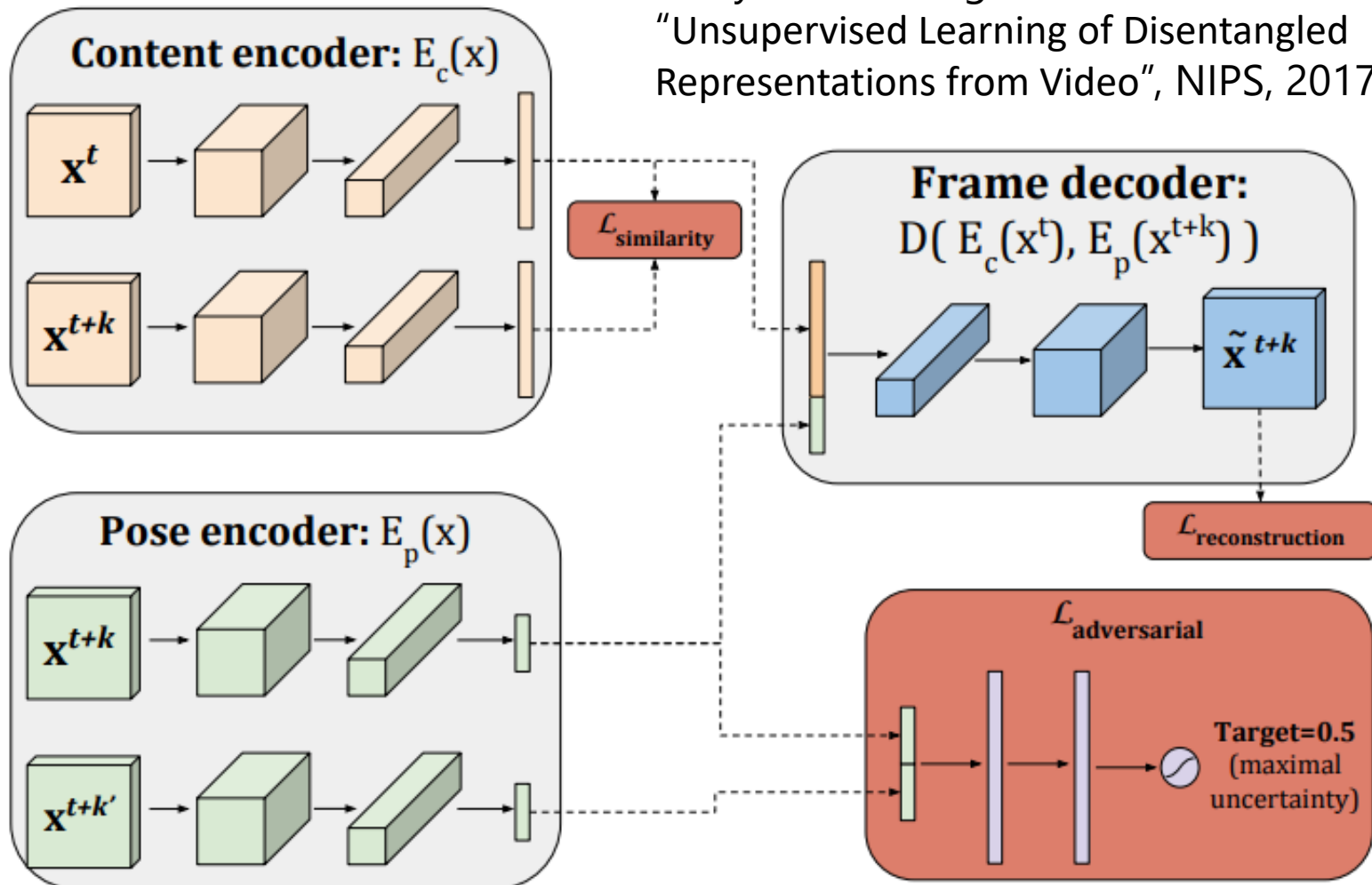
Maximize label
classification accuracy



This is a big network, but different parts have different goals.

Feature Disentangle

Emily Denton, Vighnesh Birodkar,
"Unsupervised Learning of Disentangled
Representations from Video", NIPS, 2017



Experimental

Results

<https://arxiv.org/pdf/1705.10915.pdf>

