

## Problem Set 2 Solutions

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**1. Probability integral transform**

Since  $F : \mathbb{R} \rightarrow [0, 1]$  is continuous and strictly increasing, its inverse,  $F^{-1} : (0, 1) \rightarrow \mathbb{R}$ , exists and is also strictly increasing. This implies  $x \leq y \Leftrightarrow F^{-1}(x) \leq F^{-1}(y)$ . For any  $y \in (0, 1)$ ,

$$\begin{aligned} F_Y(y) &= P(Y \leq y) = P(F(X) \leq y) = P\left(F^{-1}(F(X)) \leq F^{-1}(y)\right) \\ &= P\left(X \leq F^{-1}(y)\right) \\ &= F\left(F^{-1}(y)\right) \\ &= y. \end{aligned}$$

This shows

$$F_Y(y) = \begin{cases} 0 & x \leq 0 \\ y & 0 < y < 1 \\ 1 & y \geq 1 \end{cases}.$$

Hence,  $Y \sim U[0, 1]$ .

**2. Inverse transform sampling**

Since  $F : \mathbb{R} \rightarrow [0, 1]$  is continuous and strictly increasing, its inverse,  $F^{-1} : (0, 1) \rightarrow \mathbb{R}$ , is well defined. Also notice  $x \leq y \Leftrightarrow F(x) \leq F(y)$ . For any  $x \in \mathbb{R}$ ,

$$\begin{aligned} F_X(x) &= P(X \leq x) = P\left(F^{-1}(Y) \leq x\right) = P\left(F\left(F^{-1}(Y)\right) \leq F(x)\right) \\ &= P(Y \leq F(x)) \\ &= F(x). \end{aligned}$$

Hence,  $X \sim F$ .

**3. Moments and moment generating functions****(a) Method 1**

For any  $0 < l < r$ ,  $|x|^l \leq |x|^r$ , if  $|x| \geq 1$ ;  $|x|^l < 1$ , if  $|x| < 1$ . This suggests for any  $x \in \mathbb{R}$ ,

$$|x|^l \leq \mathbf{1}(|x| < 1) \cdot 1 + \mathbf{1}(|x| \geq 1)|x|^r < 1 + |x|^r.$$

Hence,  $|X|^l < 1 + |X|^r$ . Take expectation on both sides.

$$\mathbb{E}(|X|^l) < 1 + \mathbb{E}(|X|^r).$$

If the RHS is finite, the LHS must be finite.

## Method 2

For any  $0 < l < r$ , the function  $g : [0, \infty) \rightarrow \mathbb{R}$ ,  $g(x) = x^{\frac{l}{r}}$ , is a concave function on  $[0, \infty)$ . Use Jensen's inequality for r.v.  $Y := |X|^r$  and function  $g$ .

$$\mathbb{E}(|X|^l) = \mathbb{E}\left(|X|^r\right)^{\frac{l}{r}} = \mathbb{E}(g(Y)) \leq g(\mathbb{E}(Y)) = (\mathbb{E}(|X|^r))^{\frac{l}{r}}.$$

If the RHS is finite, the LHS must be finite.

(b)  $X \sim N(0, 1)$ .

$$\begin{aligned} M_X(t) &= \mathbb{E}(e^{tX}) \\ &= \int e^{tx} \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx \\ &= \int \frac{1}{\sqrt{2\pi}} e^{-\frac{(x-t)^2}{2}} dx \cdot e^{\frac{t^2}{2}} \\ &= e^{\frac{t^2}{2}} \\ \mathbb{E}(X) &= \frac{d}{dt} M_X(t)|_{t=0} = te^{\frac{t^2}{2}}|_{t=0} = 0 \\ \mathbb{E}(X^2) &= \frac{d^2}{dt^2} M_X(t)|_{t=0} = (t^2 + 1)e^{\frac{t^2}{2}}|_{t=0} = 1 \\ \mathbb{E}(X^3) &= \frac{d^3}{dt^3} M_X(t)|_{t=0} = (t^3 + 3t)e^{\frac{t^2}{2}}|_{t=0} = 0 \\ \mathbb{E}(X^4) &= \frac{d^4}{dt^4} M_X(t)|_{t=0} = (t^4 + 6t^2 + 3)e^{\frac{t^2}{2}}|_{t=0} = 3. \end{aligned}$$

## 4. Covariance

(a)  $(X, Y)' \sim U((-1, 1) \times (-1, 1))$  means

$$f_{X,Y}(x, y) = \begin{cases} \frac{1}{4} & (x, y)' \in (-1, 1) \times (-1, 1) \\ 0 & \text{otherwise} \end{cases}.$$

$$\begin{aligned} \text{Cov}(X, Y) &= \mathbb{E}(XY) - \mathbb{E}(X)\mathbb{E}(Y) \\ &= \int \int xy \cdot f_{X,Y}(x, y) dx dy - \int \int x \cdot f_{X,Y}(x, y) dx dy \cdot \int \int y \cdot f_{X,Y}(x, y) dx dy \\ &= 0 - 0 \cdot 0 = 0 \quad \text{by symmetry.} \end{aligned}$$

$X$  and  $Y$  are uncorrelated. Moreover, since

$$f_X(x) = \begin{cases} \frac{1}{2} & -1 < x < 1 \\ 0 & \text{otherwise} \end{cases} \quad f_Y(y) = \begin{cases} \frac{1}{2} & -1 < y < 1 \\ 0 & \text{otherwise} \end{cases},$$

$f_{X,Y}(x, y) = f_X(x) \cdot f_Y(y)$  for any  $(x, y)' \in \mathbb{R}^2$ . This implies  $X$  and  $Y$  are independent.

(b) Denote the ball  $\{(x, y)' \in \mathbb{R}^2 : x^2 + y^2 \leq 1\}$  by  $B((0, 0)', 1)$ .  $(X, Y)' \sim U(B((0, 0)', 1))$

means

$$f_{X,Y}(x,y) = \begin{cases} \frac{1}{\pi} & (x,y)' \in B((0,0)', 1) \\ 0 & \text{otherwise} \end{cases}.$$

$$\begin{aligned} \text{Cov}(X,Y) &= \mathbb{E}(XY) - \mathbb{E}(X)\mathbb{E}(Y) \\ &= \int \int xy \cdot f_{X,Y}(x,y) dx dy - \int \int x \cdot f_{X,Y}(x,y) dx dy \cdot \int \int y \cdot f_{X,Y}(x,y) dx dy \\ &= 0 - 0 \cdot 0 = 0 \quad \text{by symmetry.} \end{aligned}$$

$X$  and  $Y$  are uncorrelated. However, since

$$f_X(x) = \begin{cases} \frac{2\sqrt{1-x^2}}{\pi} & -1 < x < 1 \\ 0 & \text{otherwise} \end{cases} \quad f_Y(y) = \begin{cases} \frac{2\sqrt{1-y^2}}{\pi} & -1 < y < 1 \\ 0 & \text{otherwise} \end{cases},$$

$f_{X,Y}(x,y) \neq f_X(x) \cdot f_Y(y)$  for a set in  $\mathbb{R}^2$  with positive measure. This implies  $X$  and  $Y$  are not independent.

**Remark.** *Other arguments also work. For example, the conditional distribution of  $Y|X = x$  clearly depends on  $x$ . This implies  $X$  and  $Y$  are not independent. Or the cdf of the joint isn't equal to the product of the marginals'.*

(c) Since  $g(\cdot)$  and  $h(\cdot)$  are non-decreasing functions on  $\mathbb{R}$ ,

$$(g(x) - g(y))(h(x) - h(y)) \geq 0, \quad \forall x, y \in \mathbb{R}.$$

Consider random variables  $X_1, X_2 \stackrel{\text{iid}}{\sim} F$ . We have

$$\begin{aligned} &(g(X_1) - g(X_2))(h(X_1) - h(X_2)) \geq 0 \\ \implies &\mathbb{E}[(g(X_1) - g(X_2))(h(X_1) - h(X_2))] \geq 0. \end{aligned}$$

Notice

$$\begin{aligned} 0 &\leq \mathbb{E}[(g(X_1) - g(X_2))(h(X_1) - h(X_2))] \\ &= \mathbb{E}[g(X_1)h(X_1)] - \mathbb{E}[g(X_1)h(X_2)] - \mathbb{E}[g(X_2)h(X_1)] + \mathbb{E}[g(X_2)h(X_2)] \\ &= \mathbb{E}[g(X)h(X)] - \mathbb{E}[g(X)]\mathbb{E}[h(X)] - \mathbb{E}[g(X)]\mathbb{E}[h(X)] + \mathbb{E}[g(X)h(X)] \\ &= 2\left(\mathbb{E}[g(X)h(X)] - \mathbb{E}[g(X)]\mathbb{E}[h(X)]\right) \\ &= 2 \text{Cov}(g(X), h(X)) \\ \implies &\text{Cov}(g(X), h(X)) \geq 0. \end{aligned}$$

## 5. The gamma distribution

(a)

$$\begin{aligned}\Gamma(x+1) &= \int_0^\infty t^x e^{-t} dt \\ &= - \int_0^\infty t^x d e^{-t} \\ &= -(t^x e^{-t}|_0^\infty - \int_0^\infty e^{-t} dt^x) \\ &= x \int_0^\infty t^{x-1} e^{-t} dt \\ &= x \Gamma(x).\end{aligned}$$

Since  $\Gamma(1) = \int_0^\infty e^{-t} dt = -e^{-t}|_0^\infty = 1 = 0!$ ,

$$\begin{aligned}\Gamma(n+1) &= n \Gamma(n) \\ &= n \cdot (n-1) \Gamma(n-1) \\ &\dots \\ &= n \cdot (n-1) \dots 2 \cdot 1 \Gamma(1) \\ &= n!\end{aligned}\quad \text{for any } n = 1, 2, \dots$$

(b) \*

(c) First,  $p(x) \geq 0$  for any  $x \in \mathbb{R}$ . Second,

$$\begin{aligned}\int p(x) dx &= \int_0^\infty \frac{1}{\Gamma(\alpha) \beta^\alpha} x^{\alpha-1} e^{-x/\beta} dx \\ &= \int_0^\infty \frac{1}{\Gamma(\alpha)} t^{\alpha-1} e^{-t} dt && \text{by change of variable } t = x/\beta \\ &= \frac{\Gamma(\alpha)}{\Gamma(\alpha)} \\ &= 1.\end{aligned}$$

This shows  $p(\cdot)$  is a pdf.

(d) \*

(e) \*

(f) \*

## 6. Best linear predictor

To get the minimizer  $(\alpha^*, \beta^*)$  of the criteria function  $h(\alpha, \beta) := \mathbb{E}[(Y - (\beta X + \alpha))^2]$ , we look at the derivatives of  $h$ .

$$\begin{aligned}\frac{\partial}{\partial \alpha} h(\alpha, \beta) &= -2[\mathbb{E}(Y) - \beta \mathbb{E}(X) - \alpha] \\ \frac{\partial}{\partial \beta} h(\alpha, \beta) &= -2\mathbb{E}[(Y - \beta X - \alpha)X]\end{aligned}$$

The first-order condition says the two partial derivatives are 0 at the minimizer.

$$\begin{aligned} -2[\mathbb{E}(Y) - \beta^* \mathbb{E}(X) - \alpha^*] &= 0 \\ -2\mathbb{E}[(Y - \beta^* X - \alpha^*)X] &= 0. \end{aligned}$$

Solve this system of linear equations. The first equation implies  $\alpha^* = \mathbb{E}(Y) - \beta^* \mathbb{E}(X)$ . Plug it into the second equation. When  $\mathbb{E}(X^2) - (\mathbb{E}X)^2 = \text{Var}(X) > 0$  (the following discussion assume  $\text{Var}(X) > 0$ ),

$$\begin{aligned} \beta^* &= \frac{\mathbb{E}[(Y - \mathbb{E}Y)X]}{\mathbb{E}[(X - \mathbb{E}X)X]} \\ &= \frac{\text{Cov}(X, Y)}{\text{Var}(X)}. \end{aligned}$$

Next, let's check the second-order condition.

$$H(\alpha, \beta) = \begin{pmatrix} \frac{\partial^2}{\partial \alpha^2} h(\alpha, \beta) & \frac{\partial^2}{\partial \beta \partial \alpha} h(\alpha, \beta) \\ \frac{\partial^2}{\partial \alpha \partial \beta} h(\alpha, \beta) & \frac{\partial^2}{\partial \beta^2} h(\alpha, \beta) \end{pmatrix} = 2 \begin{pmatrix} 1 & \mathbb{E}(X) \\ \mathbb{E}(X) & \mathbb{E}(X^2) \end{pmatrix}.$$

The Hessian doesn't depend on  $(\alpha, \beta)$  and is positive definite; because for any  $(a, b)' \in \mathbb{R}^2$ ,  $(a, b)' \neq (0, 0)'$ , the quadratic form

$$\begin{pmatrix} a & b \end{pmatrix} \begin{pmatrix} 1 & \mathbb{E}(X) \\ \mathbb{E}(X) & \mathbb{E}(X^2) \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = a^2 + 2ab\mathbb{E}(X) + b^2\mathbb{E}(X^2) = \mathbb{E}[(a + bX)^2] > 0.$$

This implies the function  $h$  is strictly convex on  $\mathbb{R}^2$  and the solution of the first-order condition,  $(\hat{\alpha}, \hat{\beta})$ , is the unique global minimizer. Our derivation shows  $\frac{\text{Cov}(X, Y)}{\text{Var}(X)}(X - \mathbb{E}(X)) + \mathbb{E}(Y)$  is the unique best linear predictor of  $Y$  using  $X$  when  $\text{Var}(X) > 0$ . When  $\text{Var}(X) = 0$ ,  $X$  is a constant.  $h$  is weakly convex and the minimizer is not unique. Any  $(\alpha, \beta)$  s.t.  $\alpha + \beta\mathbb{E}(X) - \mathbb{E}(Y) = 0$  is a minimizer.

## 7. Kullback-Leibler divergence

Consider a random variable  $X$  with density  $p$ . Define random variable  $Y := \frac{q(X)}{p(X)}$ .  $Y$  is always positive. To apply Jensen's inequality, consider the convex function  $g : (0, \infty) \rightarrow \mathbb{R}$ ,  $g(x) = -\log(x)$ .

$$\begin{aligned} -\int \log\left(\frac{q(x)}{p(x)}\right)p(x)dx &= \mathbb{E}(g(Y)) \\ &\geq g(\mathbb{E}(Y)) && \text{(by Jensen's inequality)} \\ &= -\log\left(\int \frac{q(x)}{p(x)} \cdot p(x)dx\right) \\ &= -\log\left(\int q(x)dx\right) \\ &= -\log(1) \\ &= 0. \end{aligned}$$

Since  $g$  is strictly convex, Jensen's inequality achieves equality if and only if  $Y$  is a constant a.s.. Suppose  $Y = c$  a.s.. Notice  $c = \mathbb{E}(Y) = \int \frac{q(x)}{p(x)} \cdot p(x)dx = 1$ . Hence  $Y = 1$  a.s., which

means  $p(X) = q(X)$  a.s.. This is just saying  $p(x) = q(x)$  almost surely with respect to  $p$ .