Game Theory

## Problem Set 2

1. Consider the following coordination game. There are two players i = 1, 2, who can choose actions  $a_i \in \{0, 1\}$ . Let  $\theta$  be a parameter drawn from a uniform distribution on  $\{0, 1, 2, ..., 10\}$  before the game is played. Payoffs are given by:

$$u_i(a_i, a_j, \theta) = \begin{cases} a_j + \frac{1}{10}\theta - c & \text{if } a_i = 1\\ 0 & \text{if } a_i = 0 \end{cases}$$

where c is known with  $\frac{3}{2} < c < 2$ .

- a. Describe the Nash equilibria of this game given that the realization of  $\theta$  is commonly known.
- b. Now suppose that instead of observing  $\theta$ , players' information is given by the following partitions:

Player 1 : 
$$(\{0\}, \{1, 2\}, \{3, 4\}, ..., \{9, 10\})$$
  
Player 2 :  $(\{0, 1\}, \{2, 3\}, ..., \{8, 9\}, \{10\})$ 

That is, if  $\theta = 3$ , then player 1 learns that  $\theta \in \{3,4\}$  for sure (he then assigns equal probability to both of these values due to the uniform prior), while player 2 learns that  $\theta \in \{2,3\}$  (and similarly assigns equal probability to each of these values). Show that in this game, neither player will ever play a = 1.

- c. Connect this model to the global game model discussed in class (no need to write anything).
- 2. (Only for PhDs!!!) Consider the following global game with continuum of players. Each player chooses an action in  $\{0,1\}$ . Let  $u(a,l,\theta)$  be the utility function of each player, where  $a \in \{0,1\}$  is his action,  $l \in [0,1]$  is the proportion of players that choose action 1 and  $\theta$  is the state of the world. Now, each player observes only  $x = \theta + \varepsilon_i$ , where  $\theta$  is drown from an improper uniform prior over the real line, and  $\varepsilon_i$  are distributed independently across players with some cdf F (with pdf f). Let  $\pi(l,\theta) = u(1,l,\theta) u(0,l,\theta)$ .

Below you can take the following results for granted: conditional on  $\theta$ , x has a distribution function  $F_{x|\Theta}(x|\theta)$  equal to  $F_{\varepsilon}(x-\theta)$  and a density function  $f_{x|\Theta}(x|\theta)$  equal to  $f_{\varepsilon}(x-\theta)$ . Also conditional on observing x,  $\theta$  has a distribution function  $f_{\Theta|x}(\theta|x)$  equal to  $f_{\varepsilon}(x-\theta)$ .

a. Let  $\Psi(l, x, k)$  be the probability that a player assigns to a proportion less than l observing signal greater than k, if he himself observed signal x. Show that

$$\Psi\left(l, x, x\right) = l,$$

independently of F.

b. Let  $\pi^*(x,k)$  be the expected gain to choosing action 1 if the player got signal x and knows others choose 1 if their signal is greater than k. Show that the result in a. implies that

$$\pi^*(x,x) = \int_{l=0}^{1} \pi(l,x) \, dl.$$

In the solution you will see how to apply the results from exercise 4 to the following model of currency crises. The current value of a currency is e. If the currency is attacked and not defended by the central bank, the value of the currency drops to  $\zeta(\theta) < e$ . The CB will not defend the currency and the devaluation occurs if a proportion  $a(\theta)$  of speculators attacks, where a is increasing (this is a reduced model of costs of defending that depend on  $\theta$ ). The cost of attacking to the speculators is t. Thus, if a = 1 stands for "not attack" we have:

$$u(1, l, \theta) = 0,$$
  

$$u(0, l, \theta) = \varepsilon - \zeta(\theta) - t \text{ if } l < 1 - a(\theta),$$
  

$$u(0, l, \theta) = -t \text{ if } l > 1 - a(\theta).$$

Basically, we will be able to write down an equation that implicitly defines a  $\theta^*$  such that there is an equilibrium with the devaluation occurring if the realized  $\theta$  is below  $\theta^*$ .